

ESE 519 - Lab 0

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Hardware connections

For this lab we have used the following hardware,

1. mbed (LPC1768)
2. Keypad
3. Buzzer
4. Breadboard and connecting wires
5. Seven Segment Display

The following is the schematic we used to interconnect the hardware using Fritzing,

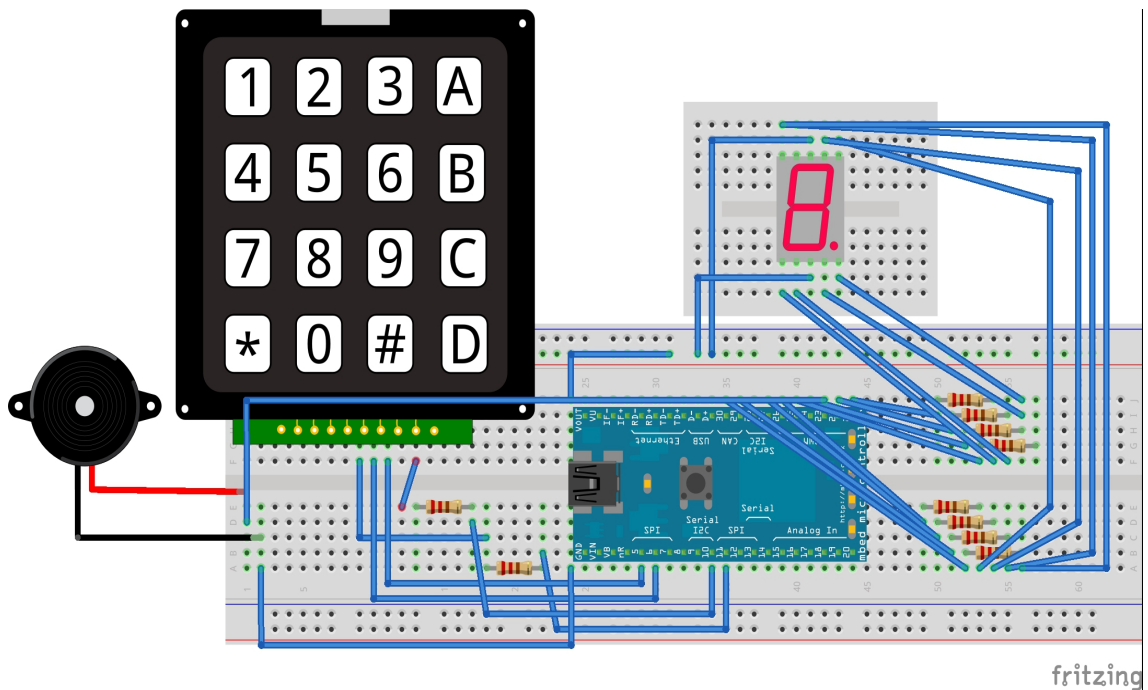


Figure 1: Hardware Connections

Part 0

In part0 of the assignment, we decided to use the value from the ADC to change the frequency of an LED blinky.

We implemented the following code,

```
1  /*
2  ese519-lab1-part0
3      Vaibhav N. Bhat (vaibhavn@seas)
4      Shanjit S. Jajmann (sjajmann@seas)
5
6  Idea : Vary the frequency of the led blink by reading
          randomness from the universe using onboard ADC
7
8  */
9
10 #include "mbed.h"
11
12 // define leds
13 DigitalOut myled1(LED1);
14 DigitalOut myled2(LED2);
15 DigitalOut myled3(LED3);
16 DigitalOut myled4(LED4);
17
18 // analog pins to read randomness from the universe
19 AnalogIn ain(p19);
20 int a[4];
21
22 // serial interface - for debug
23 Serial pc(USBTX, USBRX);
24
25 // ticker timer for 18 second window
26 Ticker ticker_period_18;
27
28 // read the adc and assign digits to array 'a'
29 void get_adc()
30 {
31     // This gets called every 18 seconds and updates the
        'a' array
32     int temp;
33     temp = ain.read_u16();
34     a[0] = temp%10;
35     temp = temp/10;
36     a[1] = temp%10;
37     temp = temp/10;
38     a[2] = temp%10;
39     temp = temp/10;
40     a[3] = temp%10;
41
42     // for debug - to see randomness on terminal
```

```

43     pc.printf("Bits are %d %d %d %d\n", a[0], a[1], a[2], a
44               [3]);
45 }
46
47 int main() {
48
49     // serial speed
50     pc.baud(9600);
51
52
53     // 18 second timer period
54     ticker_period_18.attach(&get_adc, 18.0);
55     get_adc();
56     while(1) {
57
58         // led1
59         myled1 = 1;
60         wait(0.1*a[0]);
61         myled1 = 0;
62
63         //led2
64         myled2 = 1;
65         wait(0.1*a[1]);
66         myled2 = 0;
67
68         //led3
69         myled3 = 1;
70         wait(0.1*a[2]);
71         myled3 = 0;
72
73         //led4
74         myled4 = 1;
75         wait(0.1*a[3]);
76         myled4 = 0;
77
78     }
79
80 }

```

Part 1

In part1 of the assignment, we have integrated the keypad with the mbed using polling. This involved checking in a while loop if a particular key of the keypad was pressed and light up corresponding leds.

When both the buttons are pressed simulataneously, any of the two leds can glow depending on which instruction the microcontroller is executing and that moment. The rate at which we are polling is the twice the amount of time to required to blink the leds and the associate wait.

Yes, it is possible to simulataneously type faster than a poll generally, in our case it depends on when the button is pressed. This is not the case when interrupts are used instead.

We implemented the following code,

```
1  /*
2  ese519-lab1-part0
3      Vaibhav N. Bhat (vaibhavn@seas)
4      Shanjit S. Jajmann (sjajmann@seas)
5
6  Idea : Vary the frequency of the led blink by reading
          randomness from the universe using onboard ADC
7
8  */
9
10 #include "mbed.h"
11
12 // define leds
13 DigitalOut myled1(LED1);
14 DigitalOut myled2(LED2);
15 DigitalOut myled3(LED3);
16 DigitalOut myled4(LED4);
17
18 // analog pins to read randomness from the universe
19 AnalogIn ain(p19);
20 int a[4];
21
22 // serial interface - for debug
23 Serial pc(USBTX, USBRX);
24
25 // ticker timer for 18 second window
26 Ticker ticker_period_18;
27
28 // read the adc and assign digits to array 'a'
29 void get_adc()
30 {
31     // This gets called every 18 seconds and updates the
        'a' array
32     int temp;
33     temp = ain.read_u16();
34     a[0] = temp%10;
35     temp = temp/10;
36     a[1] = temp%10;
37     temp = temp/10;
38     a[2] = temp%10;
39     temp = temp/10;
40     a[3] = temp%10;
41
42     // for debug - to see randomness on terminal
43     pc.printf("Bits are %d %d %d %d\n", a[0], a[1], a[2], a
```

```

        [3]);
44
45 }
46
47 int main() {
48
49     // serial speed
50     pc.baud(9600);
51
52
53     // 18 second timer period
54     ticker_period_18.attach(&get_adc,18.0);
55     get_adc();
56     while(1) {
57
58         // led1
59         myled1 = 1;
60         wait(0.1*a[0]);
61         myled1 = 0;
62
63         //led2
64         myled2 = 1;
65         wait(0.1*a[1]);
66         myled2 = 0;
67
68         //led3
69         myled3 = 1;
70         wait(0.1*a[2]);
71         myled3 = 0;
72
73         //led4
74         myled4 = 1;
75         wait(0.1*a[3]);
76         myled4 = 0;
77
78     }
79
80 }

```

Part 2

In part2 of the assignment, instead of polling as in part1 we used interrupts on the keys to check if a key was pressed.

We implemented the following code,

```

1  /*
2  ese519-lab1-part2
3      Vaibhav N. Bhat (vaibhavn@seas)
4      Shanjit S. Jajmann (sjajmann@seas)

```

```

5
6 Idea : Using the keypad, interrupt when the key is
   pressed.
7
8 */
9
10 #include "mbed.h"
11
12
13 // Connections on the mbed
14 // Mbed - Keypad
15 // p5 - 7
16 // p6 - 6
17 // p7 - 5
18 // p8 - 3
19 // p10 - 8
20 // p11 - 4
21
22
23 //define the leds
24 DigitalOut myled1(LED1);
25 DigitalOut myled2(LED2);
26 DigitalOut myled3(LED3);
27 DigitalOut myled4(LED4);
28
29 //define the pins for # and 2
30 DigitalOut pin1(p10);
31 DigitalOut pin2(p11);
32
33
34 // keypad association
35 DigitalIn col4(p5);
36 InterruptIn col3(p6);
37 InterruptIn col2(p7);
38 DigitalIn col1(p8);
39
40 // ISR when button pressed - lights up led1
41 void light0(){
42     myled1 = 1;
43     wait(0.2);
44     myled1 = 0;
45     wait(0.2);
46 }
47
48 // ISR when button pressed - lights up led2
49 void light1(){
50     myled2 = 1;
51     wait(0.2);
52     myled2 = 0;
53     wait(0.2);

```

```

54 }
55
56 int main() {
57
58     pin1 = 1 ;
59     pin2 = 1 ;
60
61     // associate interrupts with functions light1 and
        light0
62     col3.rise(&light1);
63     col2.rise(&light0);
64     while(1) {
65     }
66 }

```

Part 3

In part3 of the assignment, we extended the part2 of the lab and used timer alongside interrupts to implement a dot and dash when the hash (#) key is pressed.

By using the dots and dash, we implemented the Morse Code. We implemented the following code,

```

1  /*
2  ese519-lab1-part3
3      Vaibhav N. Bhat (vaibhavn@seas)
4      Shanjit S. Jajmann (sjajmann@seas)
5
6  Idea : Using the keypad and timers , implement dot and
        dash functionality
7  Timer 1 is used to measure the duration of the key press
8  Timer 2 is used independently to generate spaces
9
10 */
11
12 #include "mbed.h"
13
14
15 // Connections on the mbed
16 // Mbed - Keypad
17 // p5 - 7
18 // p6 - 6
19 // p7 - 5
20 // p8 - 3
21 // p10 - 8
22 // p11 - 4
23
24 bool flag = false;
25

```

```

26 // Interrupt whenever pin is pressed (#) – keypad
27 InterruptIn key(p6);
28 DigitalOut row(p11);
29
30 // led interface – visual feedback
31 DigitalOut myled1(LED1);
32 DigitalOut myled2(LED2);
33 DigitalOut myled3(LED3);
34 DigitalOut myled4(LED4);
35
36 /*
37 *   Dot represented by led1
38 *   Dash represented by led2
39 *   Space represented by led3
40 */
41
42 // serial interface – for debugging
43 Serial pc(USBTX, USBRX);
44
45 // timers to ensure dot and dash
46 Timer timer_400;
47 Timer timer_key;
48
49 // ISR when the key is just pressed on the keypad (for
   debugging)
50 void key_rise_int1()
51 {
52     // debouncing code – wait and check
53     wait(0.01);
54     if(key)
55     {
56         // serial debug
57         pc.printf("pressed");
58     }
59 }
60
61
62 // ISR when the key is just pressed on the keypad (for
   debugging)
63 void key_fall_int1()
64 {
65     // debouncing code – wait and check
66     wait(0.01);
67     if(!key)
68     {
69         // serial debug
70         pc.printf("released");
71     }
72 }
73 }

```



```

74
75
76 // ISR when the key is just pressed on the keypad
77 void key_rise_int()
78 {
79     // debouncing code – wait and check
80     //read the value of the key after 10ms and set the
        flag
81     wait(0.01);
82
83     if(key)
84     {
85         timer_400.stop(); // Stop the space timer
86         flag = true;
87         //start a timer
88         timer_key.start(); // Start counting the
            duration of the key press
89         pc.printf("key pressed"); // For debugging
90     }
91
92     else
93     {
94         flag = false;
95     }
96 }
97
98
99 // ISR when the key is just pressed on the keypad
100 void key_fall_int()
101 {
102     wait(0.01);
103
104     if(!key)
105     {
106         pc.printf("key released"); // For debugging
107         //timer_400.reset();
108         // stop the timer
109         timer_key.stop(); // Stop the first timer which
            measures the key press
110
111         // read the timer value and decide if dot, dash
112         int timer_key_val = timer_key.read_ms();
113
114         if((timer_key_val>40)&&(timer_key_val<220)&&(flag
            ==true) ) // Dot has been pressed
115         {
116             myled1 = 1;
117             wait(0.05);
118             myled1 = 0;
119         }

```

```

120
121         else if (timer_key_val>220){      // Dash has been
122             pressed
123             myled2 = 1;
124             wait(0.05);
125             myled2 = 0;
126         }
127
128         // Reset and stop the measurement timer
129         timer_key.stop();
130         timer_key.reset();
131         flag=0;
132         timer_400.reset(); // Reset and restart the
133                             timer for space
134         timer_400.start();
135     }
136 }
137
138 int main() {
139
140     myled1 = 0;      // blink the leds once to indicate
141                       start of the program
142     myled2 = 1;
143     myled3 = 1;
144     myled4 = 1;
145
146     wait(0.5);
147     myled1 = 0;
148     myled2 = 0;
149     myled3 = 0;
150     myled4 = 0;
151
152     pc.baud(9600);
153     row = 1;
154
155     // start the timer for 400ms to check the occurrence
156       of space
157     timer_400.start();
158
159     key.rise(&key_rise_int);    // Set up the button
160                                interrupt handlers
161     key.fall(&key_fall_int);
162
163     while(1) {
164         // if timer value hits 400 ms, then reset the
165           timer and read as space.

```

```

164         if (timer_400.read_ms() >= 400)
165         {
166             timer_400.reset();
167             if (!flag)
168             {
169                 //pc.printf("Got a space\n");
170                 myled3 = 1; //Indicate the presence of space
                             by blinking led
171                 wait(0.05);
172                 myled3 = 0;
173             }
174         }
175     }
176 }

```

Part 4

In part4 of the assignment, we again extended part3 of the lab and integrated a common anode based seven segment display with our existing hardware connections for part3.

We integrated this with our existing Morse Code hardware in part3, to show different patterns on the seven segment.

We implemented the seven segment by individually switching on/off the required leds.

Code:

```

1  #include "mbed.h"
2  /*
3  ese519-lab1-part4
4      Vaibhav N. Bhat (vaibhavn@seas)
5      Shanjit S. Jajmann (sjajmann@seas)
6
7  Idea : Using the keypad and timers , implement dot and
          dash functionality
8  Timer 1 is used to measure the duration of the key press
9  Timer 2 is used independently to generate spaces
10
11  7 segment display is interfaced to display dot, space and
          dash
12
13  Dot - Segment D
14  Dash - Segment G
15  Space - Segment A
16  */
17
18  // Connections on the mbed
19  // Mbed - Keypad
20  // p5 - 7
21  // p6 - 6

```

```

22 // p7 - 5
23 // p8 - 3
24 // p10 - 8
25 // p11 - 4
26
27
28 bool flag = false;
29
30 // Define the row and column for keypad
31 InterruptIn key(p6);
32 DigitalOut row(p11);
33
34 DigitalOut myled1(LED1);
35 DigitalOut myled2(LED2);
36 DigitalOut myled3(LED3);
37 DigitalOut myled4(LED4);
38 Serial pc(USBTX, USBRX); // tx, rx
39
40 // 2 timers used for space and dot/dash measurement
41 Timer timer_400;
42 Timer timer_key;
43
44 // seven segment display interface
45 // Mbed - Seven Segment (common anode)
46 // p21 - 1
47 // p22 - 2
48 // gnd - 3
49 // p24 - 4
50 // p25 - 5
51 // p26 - 6
52 // p27 - 7
53 // gnd - 8
54 // p29 - 9
55 // p30 - 10
56
57 DigitalOut ss_a(p27);
58 DigitalOut ss_b(p26);
59 DigitalOut ss_c(p24);
60 DigitalOut ss_d(p22);
61 DigitalOut ss_e(p21);
62 DigitalOut ss_f(p29);
63 DigitalOut ss_g(p30);
64 DigitalOut ss_dot(p25);
65
66 // Function for handling dot behavior
67 inline void dot()
68 {
69     ss_d = 0;
70     wait(0.05);
71     ss_d = 1;

```

```

72 }
73 }
74
75 // Function for handling dash behavior
76 inline void dash()
77 {
78     ss_g = 0;
79     wait(0.05);
80     ss_g = 1;
81
82 }
83
84 // Function for handling space behavior
85 inline void space()
86 {
87     ss_a = 0;
88     wait(0.05);
89     ss_a = 1;
90
91 }
92 // Function for turning of the 7 segment display
93
94 void segment_off()
95 {
96     ss_a = 1;
97     ss_b = 1;
98     ss_c = 1;
99     ss_d = 1;
100    ss_e = 1;
101    ss_f = 1;
102    ss_g = 1;
103    ss_dot = 1;
104
105 }
106
107 // Function for turning on all leds in the 7 segment
    display
108 // Used for debugging
109 void segment_on()
110 {
111     ss_a = 0;
112     ss_b = 0;
113     ss_c = 0;
114     ss_d = 0;
115     ss_e = 0;
116     ss_f = 0;
117     ss_g = 0;
118     ss_dot = 0;
119 }
120

```

```

121 // Interrupt handler for key press – Debugging purpose
122 void key_rise_int1()
123 {
124     wait(0.01); // Debounce period
125     if(key)
126     {
127         pc.printf("pressed");
128     }
129 }
130 }
131
132 // Interrupt handler for key release – Debugging purpose
133 void key_fall_int1()
134 {
135     wait(0.01);
136     if(!key)
137     {
138         pc.printf("released");
139     }
140 }
141 }
142
143 // Interrupt handler for key press
144 void key_rise_int()
145 {
146
147     wait(0.01);
148     //read the value of the key after 10ms and set the
149     //flag
150     if(key)
151     {
152         timer_400.stop(); // Stop the space timer
153         flag = true;
154         //start a timer for measuring the duration of the
155         //key press
156         timer_key.start();
157         pc.printf("key pressed");
158     }
159     else
160     {
161         flag = false; // Debouncing failed – key wasn't
162         //pressed
163     }
164 }
165
166 // Interrupt handler for key release
167 void key_fall_int()
168 {

```

```

168     wait(0.01);
169
170     if(!key)
171     {
172         pc.printf("key released");
173         //timer_400.reset();
174         // stop the timer used for measuring key press
175         timer_key.stop();
176
177         // read the timer value and decide if dot, dash
178         int timer_key_val = timer_key.read_ms();
179
180         if((timer_key_val>40)&&(timer_key_val<220)&&(flag
            ==true) )
181         {
182             /*myled1 = 1;
183             wait(0.05);
184             myled1 = 0;*/
185             dot(); // Dot pressed
186         }
187
188         else if (timer_key_val>220){
189             /*myled2 = 1;
190             wait(0.05);
191             myled2 = 0;*/
192             dash(); //Dash pressed
193         }
194
195         // reset the measurement timer
196         timer_key.stop();
197         timer_key.reset();
198         flag=0;
199         timer_400.reset(); // Restart the space timer
200         after reset
201         timer_400.start();
202     }
203 }
204
205
206 int main() {
207
208
209     // Check the leds
210     myled1 = 0;
211     myled2 = 1;
212     myled3 = 1;
213     myled4 = 1;
214
215     wait(0.5);

```

```

216     myled1 = 0;
217     myled2 = 0;
218     myled3 = 0;
219     myled4 = 0;
220
221     // Check the seven segment
222     segment_off();
223     wait(0.5);
224     segment_on();
225     wait(0.5);
226     segment_off();
227
228     pc.baud(9600);
229     row = 1;
230
231
232     // start the timer for 400ms
233     timer_400.start();
234
235     key.rise(&key_rise_int);
236     key.fall(&key_fall_int);    // Set up the interrupt
                                // handlers
237
238
239     while(1) {
240         // if timer value hits 400 ms, then reset the
                // timer and read as space.
241         if(timer_400.read_ms() >= 400)
242         {
243             timer_400.reset();
244
245             if(!flag)
246             {
247                 //pc.printf("Got a space\n");
248                 /*myled3 = 1;
249                 wait(0.05);
250                 myled3 = 0;*/
251                 space();    // Space occurred
252             }
253         }
254     }
255 }

```

Part 5

In part5 of the assignment, we used the seven segment to display ASCII digits on the seven segment, we implemented this by hard coding in what leds need to glow for what characters.

With this integrated, we were able to show different ASCII characters for corresponding dots and dashes on the seven segment display.

Code:

```
1  #include "mbed.h"
2
3  #define DOT 1
4  #define DASH 2
5  /*
6  ese519-lab1-part5
7      Vaibhav N. Bhat (vaibhavn@seas)
8      Shanjit S. Jajmann (sjajmann@seas)
9
10 Idea : Using the keypad and timers , implement dot and
        dash functionality
11 Timer 1 is used to measure the duration of the key press
12 Timer 2 is used independently to generate spaces
13
14 7 segment display is interfaced to display dot , space and
        dash
15 The ASCII characters are interpreted and printed on the
        serial terminal
16
17 */
18
19 // Connections on the mbed
20 // Mbed - Keypad
21 // p5 - 7
22 // p6 - 6
23 // p7 - 5
24 // p8 - 3
25 // p10 - 8
26 // p11 - 4
27
28 // array for saving the received dot / dash pattern
29 int ch[5];
30 int count_ch = 0;    // stores count of the number of dots
        /dashes received
31
32 // Flag for detecting key
33 bool flag = false;
34
35 // Set up the row and column for the keypad
36 // p6 senses active high and p11 activates the row
37 InterruptIn key(p6);
38 DigitalOut row(p11);
39
40 // leds
41 DigitalOut myled1(LED1);
42 DigitalOut myled2(LED2);
```

```

43 DigitalOut myled3(LED3);
44 DigitalOut myled4(LED4);
45 Serial pc(USBTX, USBRX); // tx, rx
46
47 // Timers used for detecting dot/dash and space
48 Timer timer_400; // Timer for space
49 Timer timer_key;
50
51 // seven segment display
52 // Mbed - Seven Segment (common anode)
53 // p21 - 1
54 // p22 - 2
55 // gnd - 3
56 // p24 - 4
57 // p25 - 5
58 // p26 - 6
59 // p27 - 7
60 // gnd - 8
61 // p29 - 9
62 // p30 - 10
63 DigitalOut ss_a(p27);
64 DigitalOut ss_b(p26);
65 DigitalOut ss_c(p24);
66 DigitalOut ss_d(p22);
67 DigitalOut ss_e(p21);
68 DigitalOut ss_f(p29);
69 DigitalOut ss_g(p30);
70 DigitalOut ss_dot(p25);
71
72 // Function for determining the character after storing the
    dot/dash pattern received
73 inline void find_char()
74 {
75
76     if(count_ch==0)
77     {
78         return;
79     }
80
81     else if(count_ch==1) // If the no of characters
        received is 1
82     { // the letter can be either E
83         or T
84         if(ch[0]==DOT)
85         {
86             pc.printf("E"); // Print the interpreted
                character on the terminal
87         }
88         else if (ch[0]==DASH)

```

```

89         {
90             pc.printf("T");
91         }
92     }
93
94     else if (count_ch==2)
95     {
96         if ((ch[0]==DOT)&&(ch[1]==DASH))
97         {
98             pc.printf("A");
99         }
100
101         else if ((ch[0]==DOT)&&(ch[1]==DOT))
102         {
103             pc.printf("I");
104         }
105
106         else if ((ch[0]==DASH)&&(ch[1]==DOT))
107         {
108             pc.printf("N");
109         }
110
111         else if ((ch[0]==DASH)&&(ch[1]==DASH))
112         {
113             pc.printf("M");
114         }
115     }
116
117     else if (count_ch==3)
118     {
119         if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DOT))
120         {
121             pc.printf("S");
122         }
123
124         else if ((ch[0]==DOT)&&(ch[1]==DASH)&&(ch[2]==DOT))
125         {
126             pc.printf("R");
127         }
128
129         else if ((ch[0]==DOT)&&(ch[1]==DASH)&&(ch[2]==DASH))
130         {
131             pc.printf("W");
132         }
133
134         else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DOT))
135         {

```

```

136         pc.printf("D");
137     }
138
139     else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==DOT
140         ))
141     {
142         pc.printf("G");
143     }
144
145     else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DASH
146         ))
147     {
148         pc.printf("K");
149     }
150
151     else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==
152         DASH))
153     {
154         pc.printf("O");
155     }
156
157     else if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DASH)
158         )
159     {
160         pc.printf("U");
161     }
162
163     }
164
165     else if (count_ch==4)
166     {
167         if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DOT)&&(ch
168             [3]==DOT))
169         {
170             pc.printf("H");
171         }
172
173         else if ((ch[0]==DOT)&&(ch[1]==DASH)&&(ch[2]==DOT)
174             &&(ch[3]==DOT))
175         {
176             pc.printf("L");
177         }
178
179         else if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DASH)
180             &&(ch[3]==DOT))
181         {
182             pc.printf("F");
183         }
184     }

```

```

179     else if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DOT)
180             &&(ch[3]==DASH))
181     {
182         pc.printf("V");
183     }
184     else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==DOT)
185             &&(ch[3]==DOT))
186     {
187         pc.printf("Z");
188     }
189     else if ((ch[0]==DOT)&&(ch[1]==DASH)&&(ch[2]==DASH)
190             &&(ch[3]==DOT))
191     {
192         pc.printf("P");
193     }
194     else if ((ch[0]==DOT)&&(ch[1]==DASH)&&(ch[2]==DASH)
195             &&(ch[3]==DASH))
196     {
197         pc.printf("J");
198     }
199     else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DASH)
200             &&(ch[3]==DASH))
201     {
202         pc.printf("Y");
203     }
204     else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DOT)
205             &&(ch[3]==DASH))
206     {
207         pc.printf("X");
208     }
209     else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==DOT)
210             &&(ch[3]==DASH))
211     {
212         pc.printf("Q");
213     }
214     else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DASH)
215             &&(ch[3]==DOT))
216     {
217         pc.printf("C");
218     }
219     else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DOT)
220             &&(ch[3]==DOT))

```

```

220         {
221             pc.printf("B");
222         }
223     }
224
225     else if (count_ch==5)
226     {
227         if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DOT)&&(ch
228             [3]==DOT)&&(ch[4]==DOT))
229         {
230             pc.printf("5");
231         }
232
233         else if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DOT)
234             &&(ch[3]==DOT)&&(ch[4]==DASH))
235         {
236             pc.printf("4");
237         }
238
239         else if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DOT)
240             &&(ch[3]==DASH)&&(ch[4]==DASH))
241         {
242             pc.printf("3");
243         }
244
245         else if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DASH)
246             &&(ch[3]==DASH)&&(ch[4]==DASH))
247         {
248             pc.printf("2");
249         }
250
251         else if ((ch[0]==DOT)&&(ch[1]==DASH)&&(ch[2]==DASH
252             )&&(ch[3]==DASH)&&(ch[4]==DASH))
253         {
254             pc.printf("1");
255         }
256
257         else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DOT)
258             &&(ch[3]==DOT)&&(ch[4]==DOT))
259         {
260             pc.printf("6");
261         }
262
263         else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==DOT

```

```

263         DASH)&&(ch[3]==DOT)&&(ch[4]==DOT) )
264     {
265         pc.printf("8");
266     }
267     else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==
268         DASH)&&(ch[3]==DASH)&&(ch[4]==DOT) )
269     {
270         pc.printf("9");
271     }
272     else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==
273         DASH)&&(ch[3]==DASH)&&(ch[4]==DASH) )
274     {
275         pc.printf("0");
276     }
277 }
278
279 }
280
281 // Function for space behavior
282 inline void space()
283 {
284     ss_a = 0;
285     wait(0.05);
286     ss_a = 1;
287
288     // depending on count, determine the character
289     find_char();
290
291     count_ch = 0;    // Reset the number of characters
292     count
293     ch[0] = 0;        // Clear the array
294     ch[1] = 0;
295     ch[2] = 0;
296     ch[3] = 0;
297     ch[4] = 0;
298 }
299
300 inline void dot()
301 {
302     ss_d = 0;
303     wait(0.05);
304     ss_d = 1;
305     if (count_ch >= 5)
306     {
307         space();    // When count >= 5 the array must be
308 
```

```

        checked for the ascii character
309     }
310     else
311     {
312         ch[count_ch] = DOT;
313         count_ch++;
314     }
315 }
316
317 inline void dash()
318 {
319     ss_g = 0;
320     wait(0.05);
321     ss_g = 1;
322
323     if(count_ch>=5) // When count >= 5 the array must be
        checked for the ascii character
324     {
325         space();
326     }
327     else
328     {
329         ch[count_ch] = DASH;
330         count_ch++;
331     }}
332
333 // function to turn off the 7 segment
334 void segment_off()
335 {
336     ss_a = 1;
337     ss_b = 1;
338     ss_c = 1;
339     ss_d = 1;
340     ss_e = 1;
341     ss_f = 1;
342     ss_g = 1;
343     ss_dot = 1;
344 }
345
346 // function to turn on the 7 segment
347 void segment_on()
348 {
349     ss_a = 0;
350     ss_b = 0;
351     ss_c = 0;
352     ss_d = 0;
353     ss_e = 0;
354     ss_f = 0;
355     ss_g = 0;
356     ss_dot = 0;

```



```

357 }
358
359 // debugging function
360 void key_rise_int1()
361 {
362     wait(0.01);
363     if(key)
364     {
365         pc.printf("pressed");
366     }
367 }
368 }
369
370 // debugging function
371 void key_fall_int1()
372 {
373     wait(0.01);
374     if(!key)
375     {
376         pc.printf("released");
377     }
378 }
379 }
380
381 // Interrupt handler for key press
382 void key_rise_int()
383 {
384
385     wait(0.01);
386     //read the value of the key after 10ms and set the
387     //flag
388     if(key)
389     {
390         timer_400.stop();
391         flag = true;
392         //start a timer
393         timer_key.start();
394         // pc.printf("key pressed");
395     }
396
397     else
398     {
399         flag = false;
400     }
401 }
402 // Interrupt handler for key press
403 void key_fall_int()
404 {
405     wait(0.01);

```

```

406
407     if (!key)
408     {
409         //pc.printf("key released");
410         //timer_400.reset();
411         // stop the timer
412         timer_key.stop();
413
414         // read the timer value and decide if dot, dash
415         int timer_key_val = timer_key.read_ms();
416
417         if ((timer_key_val > 40) && (timer_key_val < 220) && (flag
418             == true) )
419         {
420             /*myled1 = 1;
421             wait(0.05);
422             myled1 = 0;*/
423             dot();
424         }
425
426         else if (timer_key_val > 220){
427             /*myled2 = 1;
428             wait(0.05);
429             myled2 = 0;*/
430             dash();
431         }
432
433         // reset the timer
434         timer_key.stop(); // Stop and reset the dot/
435                             dash timer
436         timer_key.reset();
437         flag=0;
438         timer_400.reset(); // Reset the space timer
439         timer_400.start();
440     }
441 }
442
443 int main() {
444
445     // Check the leds
446     myled1 = 0;
447     myled2 = 1;
448     myled3 = 1;
449     myled4 = 1;
450
451     wait(0.5);
452     myled1 = 0;

```

```

454     myled2 = 0;
455     myled3 = 0;
456     myled4 = 0;
457
458     // Check the seven segment
459     segment_off();
460     wait(0.5);
461     segment_on();
462     wait(0.5);
463     segment_off();
464
465     pc.baud(9600);
466     row = 1;
467
468
469     // start the timer for 400ms
470     timer_400.start();
471
472     key.rise(&key_rise_int);    // Setup the interrupt
                                handlers
473     key.fall(&key_fall_int);
474
475
476     while(1) {
477         // if timer value hits 400 ms, then reset the
                                timer and read as space.
478         if(timer_400.read_ms() >= 400)
479         {
480             timer_400.reset();
481
482             if(!flag)
483             {
484                 //pc.printf("Got a space\n");
485                 /*myled3 = 1;
486                 wait(0.05);
487                 myled3 = 0;*/
488                 space();
489             }
490         }
491     }
492 }

```

Extra Credit 1

For this extra credit, we integrated the buzzer on a particular pin of the mbed and changed the frequency for which it beeps to distinguish between a dot and a dash.

We used the following code,
Code:

```

1  #include "mbed.h"
2
3  #define DOT 1
4  #define DASH 2
5  /*
6  ese519-lab1-Extra Credit Part 1
7      Vaibhav N. Bhat (vaibhavn@seas)
8      Shanjit S. Jajmann (sjajmann@seas)
9
10 Idea : Using the keypad and timers , implement dot and
        dash functionality
11 Timer 1 is used to measure the duration of the key press
12 Timer 2 is used independently to generate spaces
13
14 7 segment display is interfaced to display dot , space and
        dash
15 The ASCII characters are interpreted and printed on the
        serial terminal
16 Buzzer is interfaced to beep when a dot is pressed and a
        longer beep
17 when a dash is pressed
18
19 */
20
21 // Connections on the mbed
22 // Mbed - Keypad
23 // p5 - 7
24 // p6 - 6
25 // p7 - 5
26 // p8 - 3
27 // p10 - 8
28 // p11 - 4
29
30 // array for saving the received dot / dash pattern
31 int ch[5];
32 int count_ch = 0; // stores count of the number of dots
        /dashes received
33
34 // Flag for detecting key
35 bool flag = false;
36
37 // Set up the row and column for the keypad
38 // p6 senses active high and p11 activates the row
39 InterruptIn key(p6);
40 DigitalOut row(p11);
41
42 // leds
43 DigitalOut myled1(LED1);
44 DigitalOut myled2(LED2);
45 DigitalOut myled3(LED3);

```

```

46 DigitalOut myled4(LED4);
47 Serial pc(USBTX, USBRX); // tx, rx
48
49 // Timers used for detecting dot/dash and space
50 Timer timer_400; // Timer for space
51 Timer timer_key;
52
53 // seven segment display
54 // Mbed - Seven Segment (common anode)
55 // p21 - 1
56 // p22 - 2
57 // gnd - 3
58 // p24 - 4
59 // p25 - 5
60 // p26 - 6
61 // p27 - 7
62 // gnd - 8
63 // p29 - 9
64 // p30 - 10
65 DigitalOut ss_a(p27);
66 DigitalOut ss_b(p26);
67 DigitalOut ss_c(p24);
68 DigitalOut ss_d(p22);
69 DigitalOut ss_e(p21);
70 DigitalOut ss_f(p29);
71 DigitalOut ss_g(p30);
72 DigitalOut ss_dot(p25);
73
74 //buzzer
75 DigitalOut buzz(p23);
76
77 // Function for determing the character after storing the
    dot/dash pattern received
78 inline void find_char()
79 {
80
81     if(count_ch==0)
82     {
83         return;
84     }
85
86     else if(count_ch==1) // If the no of characters
        received is 1
87     { // the letter can be either E
        or T
88         if(ch[0]==DOT)
89         {
90             pc.printf("E"); // Print the interpreted
                character on the terminal
91         }

```

```

92         else if (ch[0]==DASH)
93         {
94             pc.printf("T");
95         }
96     }
97
98
99     else if (count_ch==2)
100     {
101         if ((ch[0]==DOT)&&(ch[1]==DASH))
102         {
103             pc.printf("A");
104         }
105
106         else if ((ch[0]==DOT)&&(ch[1]==DOT))
107         {
108             pc.printf("I");
109         }
110
111         else if ((ch[0]==DASH)&&(ch[1]==DOT))
112         {
113             pc.printf("N");
114         }
115
116         else if ((ch[0]==DASH)&&(ch[1]==DASH))
117         {
118             pc.printf("M");
119         }
120     }
121
122     else if (count_ch==3)
123     {
124         if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DOT))
125         {
126             pc.printf("S");
127         }
128
129         else if ((ch[0]==DOT)&&(ch[1]==DASH)&&(ch[2]==DOT))
130         {
131             pc.printf("R");
132         }
133
134         else if ((ch[0]==DOT)&&(ch[1]==DASH)&&(ch[2]==DASH))
135         {
136             pc.printf("W");
137         }
138
139         else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DOT))

```

```

    )
140 {
141     pc.printf("D");
142 }
143
144 else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==DOT))
145 {
146     pc.printf("G");
147 }
148
149 else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DASH))
150 {
151     pc.printf("K");
152 }
153
154 else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==DASH))
155 {
156     pc.printf("O");
157 }
158
159 else if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DASH))
160 {
161     pc.printf("U");
162 }
163
164 }
165
166
167 else if (count_ch==4)
168 {
169     if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DOT)&&(ch[3]==DOT))
170     {
171         pc.printf("H");
172     }
173
174     else if ((ch[0]==DOT)&&(ch[1]==DASH)&&(ch[2]==DOT)&&(ch[3]==DOT))
175     {
176         pc.printf("L");
177     }
178
179     else if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DASH)&&(ch[3]==DOT))
180     {
181         pc.printf("F");

```

```

182     }
183
184     else if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DOT)
185             &&(ch[3]==DASH))
186     {
187         pc.printf("V");
188     }
189
190     else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==DOT)
191             &&(ch[3]==DOT))
192     {
193         pc.printf("Z");
194     }
195
196     else if ((ch[0]==DOT)&&(ch[1]==DASH)&&(ch[2]==DASH)
197             &&(ch[3]==DOT))
198     {
199         pc.printf("P");
200     }
201
202     else if ((ch[0]==DOT)&&(ch[1]==DASH)&&(ch[2]==DASH)
203             &&(ch[3]==DASH))
204     {
205         pc.printf("J");
206     }
207
208     else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DASH)
209             &&(ch[3]==DASH))
210     {
211         pc.printf("Y");
212     }
213
214     else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DOT)
215             &&(ch[3]==DASH))
216     {
217         pc.printf("X");
218     }
219
220     else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==DOT)
221             &&(ch[3]==DASH))
222     {
223         pc.printf("Q");
224     }
225
226     else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DASH)
227             &&(ch[3]==DOT))
228     {
229         pc.printf("C");
230     }
231

```



```

224         else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DOT)
225                 &&(ch[3]==DOT))
226         {
227             pc.printf("B");
228         }
229     }
230     else if (count_ch==5)
231     {
232         if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DOT)&&(ch
233             [3]==DOT)&&(ch[4]==DOT))
234         {
235             pc.printf("5");
236         }
237         else if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DOT)
238                 &&(ch[3]==DOT)&&(ch[4]==DASH))
239         {
240             pc.printf("4");
241         }
242         else if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DOT)
243                 &&(ch[3]==DASH)&&(ch[4]==DASH))
244         {
245             pc.printf("3");
246         }
247         else if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DASH)
248                 &&(ch[3]==DASH)&&(ch[4]==DASH))
249         {
250             pc.printf("2");
251         }
252         else if ((ch[0]==DOT)&&(ch[1]==DASH)&&(ch[2]==DASH)
253                 &&(ch[3]==DASH)&&(ch[4]==DASH))
254         {
255             pc.printf("1");
256         }
257         else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DOT)
258                 &&(ch[3]==DOT)&&(ch[4]==DOT))
259         {
260             pc.printf("6");
261         }
262         else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==DOT)
263                 &&(ch[3]==DOT)&&(ch[4]==DOT))
264         {
265             pc.printf("7");
266         }

```

```

266
267     else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==
268         DASH)&&(ch[3]==DOT)&&(ch[4]==DOT))
269     {
270         pc.printf("8");
271     }
272     else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==
273         DASH)&&(ch[3]==DASH)&&(ch[4]==DOT))
274     {
275         pc.printf("9");
276     }
277     else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==
278         DASH)&&(ch[3]==DASH)&&(ch[4]==DASH))
279     {
280         pc.printf("0");
281     }
282 }
283
284
285 }
286
287
288 inline void space()
289 {
290     ss_a = 0;
291     wait(0.05);
292     ss_a = 1;
293
294
295     // depending on count, determine the character
296     find_char();
297
298     count_ch = 0;
299     ch[0] = 0;
300     ch[1] = 0;
301     ch[2] = 0;
302     ch[3] = 0;
303     ch[4] = 0;
304
305 }
306
307 inline void dot()
308 {
309     ss_d = 0;
310     wait(0.05);
311     ss_d = 1;
312

```

```

313
314     buzz = 1;
315     wait(0.05);
316     buzz = 0;
317
318     if(count_ch>=5)
319     {
320         space(); // When count >= 5 the array must be
                    checked for the ascii character
321     }
322     else
323     {
324         ch[count_ch] = DOT;
325         count_ch++;
326     }
327 }
328
329 inline void dash()
330 {
331     ss_g = 0;
332     wait(0.05);
333     ss_g = 1;
334
335     buzz = 1;
336     wait(0.15);
337     buzz = 0;
338
339     if(count_ch>=5) // When count >= 5 the array must be
                    checked for the ascii character
340     {
341         space();
342     }
343     else
344     {
345         ch[count_ch] = DASH;
346         count_ch++;
347     }}
348
349 // function to turn off the 7 segment
350 void segment_off()
351 {
352     ss_a = 1;
353     ss_b = 1;
354     ss_c = 1;
355     ss_d = 1;
356     ss_e = 1;
357     ss_f = 1;
358     ss_g = 1;
359     ss_dot = 1;
360

```

```

361 }
362
363 // function to turn on the 7 segment
364 void segment_on()
365 {
366     ss_a = 0;
367     ss_b = 0;
368     ss_c = 0;
369     ss_d = 0;
370     ss_e = 0;
371     ss_f = 0;
372     ss_g = 0;
373     ss_dot = 0;
374 }
375
376 // debugging function
377 void key_rise_int1()
378 {
379     wait(0.01);
380     if(key)
381     {
382         pc.printf("pressed");
383     }
384 }
385
386 // debugging function
387 void key_fall_int1()
388 {
389     wait(0.01);
390     if(!key)
391     {
392         pc.printf("released");
393     }
394 }
395
396 }
397
398 // Interrupt handler for key press
399 void key_rise_int()
400 {
401
402     wait(0.01);
403     //read the value of the key after 10ms and set the
404     //flag
405     if(key)
406     {
407         timer_400.stop();
408         flag = true;
409         //start a timer
410         timer_key.start();

```

```

410         // pc.printf("key pressed");
411     }
412
413     else
414     {
415         flag = false;
416     }
417
418 }
419 // Interrupt handler for key release
420 void key_fall_int ()
421 {
422     wait(0.01);
423
424     if (!key)
425     {
426         //pc.printf("key released");
427         //timer_400.reset();
428         // stop the timer
429         timer_key.stop();
430
431         // read the timer value and decide if dot, dash
432         int timer_key_val = timer_key.read_ms();
433
434         if ((timer_key_val > 40) && (timer_key_val < 220) && (flag
435             == true) )
436         {
437             /*myled1 = 1;
438             wait(0.05);
439             myled1 = 0;*/
440             dot();
441         }
442
443         else if (timer_key_val > 220){
444             /*myled2 = 1;
445             wait(0.05);
446             myled2 = 0;*/
447             dash();
448         }
449
450         // reset the timer
451         timer_key.stop();
452         timer_key.reset();
453         flag = 0;
454         timer_400.reset(); // Reset the space timer
455         timer_400.start();
456     }
457 }
458

```

```

459
460 int main() {
461
462
463     // Check the leds
464     myled1 = 0;
465     myled2 = 1;
466     myled3 = 1;
467     myled4 = 1;
468
469     wait(0.5);
470     myled1 = 0;
471     myled2 = 0;
472     myled3 = 0;
473     myled4 = 0;
474
475     // Check the seven segment
476     segment_off();
477     wait(0.5);
478     segment_on();
479     wait(0.5);
480     segment_off();
481
482     pc.baud(9600);
483     row = 1;
484
485
486     // start the timer for 400ms
487     timer_400.start();
488
489     key.rise(&key_rise_int); // Setup the interrupt
490                             // handlers
491     key.fall(&key_fall_int);
492
493     while(1) {
494         // if timer value hits 400 ms, then reset the
495         // timer and read as space.
496         if(timer_400.read_ms() >= 400)
497         {
498             timer_400.reset();
499
500             if(!flag)
501             {
502                 //pc.printf("Got a space\n");
503
504                 space();
505             }
506         }
507     }

```

507 }

Extra Credit 2

For this extra credit, we implemented the space functionality to distinguish between two words when typed in the morse code. 5 or more spaces are interpreted as a single space, while a 2-3 spaces can be allowed when pressing the key. This configuration can be changed depending on the final end user.

Code:

```
1  #include "mbed.h"
2
3  #define DOT 1
4  #define DASH 2
5  /*
6  ese519-lab1-Extra Credit Seven segment
7      Vaibhav N. Bhat (vaibhavn@seas)
8      Shanjit S. Jajmann (sjajmann@seas)
9
10 Idea : Using the keypad and timers , implement dot and
        dash functionality
11 Timer 1 is used to measure the duration of the key press
12 Timer 2 is used independently to generate spaces
13
14 7 segment display is interfaced to display dot , space and
        dash
15 The ASCII characters are interpreted and printed on the
        serial terminal
16
17 Buzzer is interfaced to beep when a dot is pressed and a
        longer beep
18 when a dash is pressed
19
20 ASCII characters are display on the 7 segment display
21
22 2 spaces are allowed between letters .
23 5 or more spaces is considered as one space
24
25 */
26
27 // Connections on the mbed
28 // Mbed - Keypad
29 // p5 - 7
30 // p6 - 6
31 // p7 - 5
32 // p8 - 3
33 // p10 - 8
34 // p11 - 4
35
```

```

36 // array for saving the received dot / dash pattern
37 int ch[5];
38 int count_ch = 0; // stores count of the number of dots
    /dashes received
39
40 bool flag = false;
41
42 // Set up the row and column for the keypad
43 // p6 senses active high and p11 activates the row
44 InterruptIn key(p6);
45 DigitalOut row(p11);
46
47 DigitalOut myled1(LED1);
48 DigitalOut myled2(LED2);
49 DigitalOut myled3(LED3);
50 DigitalOut myled4(LED4);
51 Serial pc(USBTX, USBRX); // tx, rx
52
53 // Timers used for detecting dot/dash and space
54 Timer timer_400; // Timer for space
55 Timer timer_key;
56
57 DigitalOut buzz(p23);
58
59 // seven segment display
60 // Mbed – Seven Segment (common cathode)
61 // p21 – 1
62 // p22 – 2
63 // gnd – 3
64 // p24 – 4
65 // p25 – 5
66 // p26 – 6
67 // p27 – 7
68 // gnd – 8
69 // p29 – 9
70 // p30 – 10
71 DigitalOut ss_a(p27);
72 DigitalOut ss_b(p26);
73 DigitalOut ss_c(p24);
74 DigitalOut ss_d(p22);
75 DigitalOut ss_e(p21);
76 DigitalOut ss_f(p29);
77 DigitalOut ss_g(p30);
78 DigitalOut ss_dot(p25);
79
80 // Function which displays ASCII character on the 7
    segment display given a character
81 void seven_seg_disp(char sev_ch)
82 {
83     if(sev_ch == '0'){

```



```

84         ss_a = 0;
85         ss_b = 0;
86         ss_c = 0;
87         ss_d = 0;
88         ss_e = 0;
89         ss_f = 0;
90         ss_g = 1;
91         ss_dot = 1;
92         wait(0.30);
93
94     }
95
96     else if(sev_ch == '1'){
97         ss_a = 1;
98         ss_b = 0;
99         ss_c = 0;
100        ss_d = 1;
101        ss_e = 1;
102        ss_f = 1;
103        ss_g = 1;
104        ss_dot = 1;
105        wait(0.30);
106
107    }
108
109    else if(sev_ch == '2'){
110        ss_a = 0;
111        ss_b = 0;
112        ss_c = 1;
113        ss_d = 0;
114        ss_e = 0;
115        ss_f = 1;
116        ss_g = 0;
117        ss_dot = 1;
118        wait(0.30);
119
120    }
121
122    else if(sev_ch == '3'){
123        ss_a = 0;
124        ss_b = 0;
125        ss_c = 0;
126        ss_d = 0;
127        ss_e = 1;
128        ss_f = 1;
129        ss_g = 0;
130        ss_dot = 1;
131        wait(0.30);
132
133    }

```

```

134     else if(sev_ch == '4'){
135         ss_a = 1;
136         ss_b = 1;
137         ss_c = 0;
138         ss_d = 1;
139         ss_e = 1;
140         ss_f = 0;
141         ss_g = 0;
142         ss_dot = 1;
143         wait(0.30);
144
145     }
146
147     else if(sev_ch == '5'){
148         ss_a = 0;
149         ss_b = 1;
150         ss_c = 0;
151         ss_d = 0;
152         ss_e = 1;
153         ss_f = 0;
154         ss_g = 0;
155         ss_dot = 1;
156         wait(0.30);
157
158     }
159
160     else if(sev_ch == '6'){
161         ss_a = 0;
162         ss_b = 1;
163         ss_c = 0;
164         ss_d = 0;
165         ss_e = 0;
166         ss_f = 0;
167         ss_g = 0;
168         ss_dot = 1;
169         wait(0.30);
170
171     }
172
173     else if(sev_ch == '7'){
174         ss_a = 0;
175         ss_b = 0;
176         ss_c = 0;
177         ss_d = 1;
178         ss_e = 1;
179         ss_f = 1;
180         ss_g = 1;
181         ss_dot = 1;
182         wait(0.30);
183

```

```

184     }
185
186     else if (sev_ch == '8'){
187         ss_a = 0;
188         ss_b = 0;
189         ss_c = 0;
190         ss_d = 0;
191         ss_e = 0;
192         ss_f = 0;
193         ss_g = 0;
194         ss_dot = 1;
195         wait(0.30);
196
197     }
198
199     else if (sev_ch == '9'){
200         ss_a = 0;
201         ss_b = 0;
202         ss_c = 0;
203         ss_d = 0;
204         ss_e = 1;
205         ss_f = 0;
206         ss_g = 0;
207         ss_dot = 1;
208         wait(0.30);
209
210     }
211
212     else if (sev_ch == 'A'){
213         ss_a = 0;
214         ss_b = 0;
215         ss_c = 0;
216         ss_d = 1;
217         ss_e = 0;
218         ss_f = 0;
219         ss_g = 0;
220         ss_dot = 1;
221         wait(0.30);
222
223     }
224
225     else if (sev_ch == 'B'){
226         ss_a = 0;
227         ss_b = 0;
228         ss_c = 0;
229         ss_d = 0;
230         ss_e = 0;
231         ss_f = 0;
232         ss_g = 0;
233         ss_dot = 1;

```

```

234         wait(0.30);
235
236     }
237
238     else if(sev_ch == 'C'){
239         ss_a = 0;
240         ss_b = 1;
241         ss_c = 1;
242         ss_d = 0;
243         ss_e = 0;
244         ss_f = 0;
245         ss_g = 1;
246         ss_dot = 1;
247         wait(0.30);
248
249     }
250
251     else if(sev_ch == 'D'){
252         ss_a = 0;
253         ss_b = 0;
254         ss_c = 0;
255         ss_d = 0;
256         ss_e = 0;
257         ss_f = 0;
258         ss_g = 1;
259         ss_dot = 1;
260         wait(0.30);
261
262     }
263
264     else if(sev_ch == 'E'){
265         ss_a = 0;
266         ss_b = 1;
267         ss_c = 1;
268         ss_d = 0;
269         ss_e = 0;
270         ss_f = 0;
271         ss_g = 0;
272         ss_dot = 0;
273         wait(0.30);
274
275     }
276
277     else if(sev_ch == 'F'){
278         ss_a = 0;
279         ss_b = 1;
280         ss_c = 1;
281         ss_d = 1;
282         ss_e = 0;
283         ss_f = 0;

```

```

284         ss_g = 0;
285         ss_dot = 1;
286         wait(0.30);
287
288     }
289
290     else if(sev_ch == 'G'){
291         ss_a = 0;
292         ss_b = 1;
293         ss_c = 0;
294         ss_d = 0;
295         ss_e = 0;
296         ss_f = 0;
297         ss_g = 0;
298         ss_dot = 1;
299         wait(0.30);
300
301     }
302
303     else if(sev_ch == 'H'){
304         ss_a = 1;
305         ss_b = 0;
306         ss_c = 0;
307         ss_d = 1;
308         ss_e = 0;
309         ss_f = 0;
310         ss_g = 0;
311         ss_dot = 1;
312         wait(0.30);
313
314     }
315
316     else if(sev_ch == 'I'){
317         ss_a = 1;
318         ss_b = 1;
319         ss_c = 1;
320         ss_d = 1;
321         ss_e = 0;
322         ss_f = 0;
323         ss_g = 1;
324         ss_dot = 1;
325         wait(0.30);
326
327     }
328
329
330     else if(sev_ch == 'J'){
331         ss_a = 1;
332         ss_b = 0;
333         ss_c = 0;

```

```

334         ss_d = 0;
335         ss_e = 1;
336         ss_f = 1;
337         ss_g = 1;
338         ss_dot = 1;
339         wait(0.30);
340
341     }
342
343     else if(sev_ch == 'K'){
344         ss_a = 1;
345         ss_b = 0;
346         ss_c = 0;
347         ss_d = 1;
348         ss_e = 0;
349         ss_f = 0;
350         ss_g = 0;
351         ss_dot = 1;
352         wait(0.30);
353
354     }
355
356     else if(sev_ch == 'L'){
357         ss_a = 1;
358         ss_b = 1;
359         ss_c = 1;
360         ss_d = 0;
361         ss_e = 0;
362         ss_f = 0;
363         ss_g = 1;
364         ss_dot = 1;
365         wait(0.30);
366
367     }
368
369
370     else if(sev_ch == 'M'){
371         ss_a = 1;
372         ss_b = 1;
373         ss_c = 1;
374         ss_d = 1;
375         ss_e = 1;
376         ss_f = 1;
377         ss_g = 1;
378         ss_dot = 1;
379         wait(0.30);
380
381     }
382
383     else if(sev_ch == 'N'){

```

```

384         ss_a = 1;
385         ss_b = 1;
386         ss_c = 1;
387         ss_d = 1;
388         ss_e = 1;
389         ss_f = 1;
390         ss_g = 1;
391         ss_dot = 1;
392         wait(0.30);
393
394     }
395
396     else if(sev_ch == 'O'){
397         ss_a = 0;
398         ss_b = 0;
399         ss_c = 0;
400         ss_d = 0;
401         ss_e = 0;
402         ss_f = 0;
403         ss_g = 1;
404         ss_dot = 1;
405         wait(0.30);
406
407     }
408
409     else if(sev_ch == 'P'){
410         ss_a = 0;
411         ss_b = 0;
412         ss_c = 1;
413         ss_d = 1;
414         ss_e = 0;
415         ss_f = 0;
416         ss_g = 0;
417         ss_dot = 1;
418         wait(0.30);
419
420     }
421
422     else if(sev_ch == 'Q'){
423         ss_a = 0;
424         ss_b = 0;
425         ss_c = 0;
426         ss_d = 0;
427         ss_e = 0;
428         ss_f = 0;
429         ss_g = 0;
430         ss_dot = 0;
431         wait(0.30);
432
433     }

```

```

434
435     else if(sev_ch == 'R'){
436         ss_a = 0;
437         ss_b = 0;
438         ss_c = 0;
439         ss_d = 1;
440         ss_e = 0;
441         ss_f = 0;
442         ss_g = 0;
443         ss_dot = 1;
444         wait(0.30);
445
446     }
447
448     else if(sev_ch == 'S'){
449         ss_a = 0;
450         ss_b = 1;
451         ss_c = 0;
452         ss_d = 0;
453         ss_e = 1;
454         ss_f = 0;
455         ss_g = 0;
456         ss_dot = 1;
457         wait(0.30);
458
459     }
460
461     else if(sev_ch == 'T'){
462         ss_a = 0;
463         ss_b = 0;
464         ss_c = 0;
465         ss_d = 1;
466         ss_e = 1;
467         ss_f = 1;
468         ss_g = 1;
469         ss_dot = 1;
470         wait(0.30);
471
472     }
473
474     else if(sev_ch == 'U'){
475         ss_a = 1;
476         ss_b = 0;
477         ss_c = 0;
478         ss_d = 0;
479         ss_e = 0;
480         ss_f = 0;
481         ss_g = 1;
482         ss_dot = 1;
483         wait(0.30);

```



```

484
485     }
486
487     else if(sev_ch == 'V'){
488         ss_a = 1;
489         ss_b = 0;
490         ss_c = 0;
491         ss_d = 0;
492         ss_e = 0;
493         ss_f = 0;
494         ss_g = 1;
495         ss_dot = 1;
496         wait(0.30);
497
498     }
499
500     else if(sev_ch == 'W'){
501         ss_a = 1;
502         ss_b = 0;
503         ss_c = 0;
504         ss_d = 0;
505         ss_e = 0;
506         ss_f = 0;
507         ss_g = 1;
508         ss_dot = 1;
509         wait(0.30);
510
511     }
512
513     else if(sev_ch == 'X'){
514         ss_a = 1;
515         ss_b = 0;
516         ss_c = 0;
517         ss_d = 1;
518         ss_e = 0;
519         ss_f = 0;
520         ss_g = 0;
521         ss_dot = 1;
522         wait(0.30);
523
524     }
525
526     else if(sev_ch == 'Y'){
527         ss_a = 1;
528         ss_b = 0;
529         ss_c = 0;
530         ss_d = 1;
531         ss_e = 1;
532         ss_f = 0;
533         ss_g = 0;

```

```

534         ss_dot = 1;
535         wait(0.30);
536
537     }
538
539     else if(sev_ch == 'Z'){
540         ss_a = 0;
541         ss_b = 0;
542         ss_c = 1;
543         ss_d = 0;
544         ss_e = 0;
545         ss_f = 1;
546         ss_g = 0;
547         ss_dot = 1;
548         wait(0.30);
549
550     }
551
552         ss_a = 1;
553         ss_b = 1;
554         ss_c = 1;
555         ss_d = 1;
556         ss_e = 1;
557         ss_f = 1;
558         ss_g = 1;
559         ss_dot = 1;
560     }
561
562     // Function for determining the character after storing the
563     // dot/dash pattern received
564     inline void find_char()
565     {
566         if(count_ch==0)
567         {
568
569             return;
570         }
571
572         else if(count_ch==1)    // If the no of characters
573             received is 1      // the letter can be either E
574             or T
575             if(ch[0]==DOT)
576             {
577                 pc.printf("E");    // Print the interpreted
578                                     character on the terminal
579                 seven_seg_disp('E');
580             }

```

```

580         else if (ch[0]==DASH)
581         {
582             pc.printf("T");
583             seven_seg_disp('T');
584         }
585     }
586
587     else if(count_ch==2)
588     {
589         if((ch[0]==DOT)&&(ch[1]==DASH))
590         {
591             pc.printf("A");
592             seven_seg_disp('A');
593         }
594
595         else if((ch[0]==DOT)&&(ch[1]==DOT))
596         {
597             pc.printf("I");
598             seven_seg_disp('I');
599         }
600
601         else if((ch[0]==DASH)&&(ch[1]==DOT))
602         {
603             pc.printf("N");
604             seven_seg_disp('N');
605         }
606
607         else if((ch[0]==DASH)&&(ch[1]==DASH))
608         {
609             pc.printf("M");
610             seven_seg_disp('M');
611         }
612     }
613
614     else if(count_ch==3)
615     {
616         if((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DOT))
617         {
618             pc.printf("S");
619             seven_seg_disp('S');
620         }
621
622         else if((ch[0]==DOT)&&(ch[1]==DASH)&&(ch[2]==DOT))
623         {
624             pc.printf("R");
625             seven_seg_disp('R');
626         }
627
628         else if((ch[0]==DOT)&&(ch[1]==DASH)&&(ch[2]==DASH

```

```

        ))
629     {
630         pc.printf("W");
631         seven_seg_disp('W');
632     }
633
634     else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DOT))
635     {
636         pc.printf("D");
637         seven_seg_disp('D');
638     }
639
640     else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==DOT))
641     {
642         pc.printf("G");
643         seven_seg_disp('G');
644     }
645
646     else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DASH))
647     {
648         pc.printf("K");
649         seven_seg_disp('K');
650     }
651
652     else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==DASH))
653     {
654         pc.printf("O");
655         seven_seg_disp('O');
656     }
657
658     else if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DASH))
659     {
660         pc.printf("U");
661         seven_seg_disp('U');
662     }
663
664 }
665
666 else if (count_ch==4)
667 {
668     if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DOT)&&(ch[3]==DOT))
669     {
670         pc.printf("H");
671     }

```

```

672     seven_seg_disp ( 'H' );
673 }
674
675     else if ( ( ch[0]==DOT)&&(ch[1]==DASH)&&(ch[2]==DOT)
676             &&(ch[3]==DOT) )
677     {
678         pc.printf ( "L" );
679         seven_seg_disp ( 'L' );
680     }
681
682     else if ( ( ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DASH)
683             &&(ch[3]==DOT) )
684     {
685         pc.printf ( "F" );
686         seven_seg_disp ( 'F' );
687     }
688
689     else if ( ( ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DOT)
690             &&(ch[3]==DASH) )
691     {
692         pc.printf ( "V" );
693         seven_seg_disp ( 'V' );
694     }
695
696     else if ( ( ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==DOT)
697             &&(ch[3]==DOT) )
698     {
699         pc.printf ( "Z" );
700         seven_seg_disp ( 'Z' );
701     }
702
703     else if ( ( ch[0]==DOT)&&(ch[1]==DASH)&&(ch[2]==DASH)
704             &&(ch[3]==DOT) )
705     {
706         pc.printf ( "P" );
707         seven_seg_disp ( 'P' );
708     }
709
710     else if ( ( ch[0]==DOT)&&(ch[1]==DASH)&&(ch[2]==DASH)
711             &&(ch[3]==DASH) )
712     {
713         pc.printf ( "J" );
714         seven_seg_disp ( 'J' );
715     }
716
717     else if ( ( ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DASH)
718             &&(ch[3]==DASH) )
719     {
720         pc.printf ( "Y" );
721         seven_seg_disp ( 'Y' );
722     }

```

```

715     }
716
717     else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DOT)
718             &&(ch[3]==DASH))
719     {
720         pc.printf("X");
721         seven_seg_disp('X');
722     }
723
724     else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==DOT)
725             &&(ch[3]==DASH))
726     {
727         pc.printf("Q");
728         seven_seg_disp('Q');
729     }
730
731     else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DASH)
732             &&(ch[3]==DOT))
733     {
734         pc.printf("C");
735         seven_seg_disp('C');
736     }
737
738     else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DOT)
739             &&(ch[3]==DOT))
740     {
741         pc.printf("B");
742         seven_seg_disp('B');
743     }
744 }
745
746 else if (count_ch==5)
747 {
748     if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DOT)&&(ch[3]==DOT)
749         &&(ch[4]==DOT))
750     {
751         pc.printf("5");
752         seven_seg_disp('5');
753     }
754
755     else if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DOT)
756             &&(ch[3]==DOT)&&(ch[4]==DASH))
757     {
758         pc.printf("4");
759         seven_seg_disp('4');
760     }
761
762     else if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DOT)

```

```

759         &&(ch[3]==DASH)&&(ch[4]==DASH) )
760     {
761         pc.printf("3");
762         seven_seg_disp('3');
763     }
764
765     else if ((ch[0]==DOT)&&(ch[1]==DOT)&&(ch[2]==DASH)
766             &&(ch[3]==DASH)&&(ch[4]==DASH) )
767     {
768         pc.printf("2");
769         seven_seg_disp('2');
770     }
771
772     else if ((ch[0]==DOT)&&(ch[1]==DASH)&&(ch[2]==DASH
773             &&(ch[3]==DASH)&&(ch[4]==DASH) )
774     {
775         pc.printf("1");
776         seven_seg_disp('1');
777     }
778
779     else if ((ch[0]==DASH)&&(ch[1]==DOT)&&(ch[2]==DOT)
780             &&(ch[3]==DOT)&&(ch[4]==DOT) )
781     {
782         pc.printf("6");
783     }
784
785     else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==DOT
786             &&(ch[3]==DOT)&&(ch[4]==DOT) )
787     {
788         pc.printf("7");
789     }
790
791     else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==
792             DASH)&&(ch[3]==DOT)&&(ch[4]==DOT) )
793     {
794         pc.printf("8");
795     }
796
797     else if ((ch[0]==DASH)&&(ch[1]==DASH)&&(ch[2]==
798             DASH)&&(ch[3]==DASH)&&(ch[4]==DOT) )
799     {
800         pc.printf("9");

```

```

801         seven_seg_disp('0');
802     }
803
804 }
805
806
807 }
808
809 // Counter for no of spaces
810 int count_space = 0;
811 bool bool_space = false;    // Flag for displaying space
812
813 // Function for handling space
814 inline void space()
815 {
816     ss_a = 0;
817     wait(0.05);
818     ss_a = 1;
819
820     count_space++; // Increment the no of spaces
821                   received
822
823     if(count_space<3){ // If there are two between
824                       letters then interpret the letter
825
826     // depending on count, determine the character
827     find_char();
828
829     count_ch = 0; // Reset the count and array
830     ch[0] = 0;
831     ch[1] = 0;
832     ch[2] = 0;
833     ch[3] = 0;
834     ch[4] = 0;
835     bool_space = false;
836 }
837
838 else if ((count_space>=5)&&(bool_space==false)) //
839         Display space
840 {
841     bool_space = true;
842
843     pc.printf("space");
844
845 }
846
847 // Function for handling dot

```



```

848 inline void dot()
849 {
850     count_space = 0;
851     ss_d = 0;
852     wait(0.05);
853     ss_d = 1;
854
855     buzz=1;
856     wait(0.05);
857     buzz = 0;
858     if(count_ch>=5)
859     {
860         space();
861     }
862     else
863     {
864         ch[count_ch] = DOT;
865         count_ch++;
866     }
867 }
868
869 // Function for handling dash
870 inline void dash()
871 {
872     count_space = 0;
873     ss_g = 0;
874     wait(0.05);
875     ss_g = 1;
876
877     buzz=1;
878     wait(0.15);
879     buzz = 0;
880
881     if(count_ch>=5)
882     {
883         space();
884     }
885     else
886     {
887         ch[count_ch] = DASH;
888         count_ch++;
889     }}
890
891 // Function for turning off the 7 segment display
892 void segment_off()
893 {
894     ss_a = 1;
895     ss_b = 1;
896     ss_c = 1;
897     ss_d = 1;

```

```

898     ss_e = 1;
899     ss_f = 1;
900     ss_g = 1;
901     ss_dot = 1;
902
903 }
904
905 // Function for turning on the 7 segment display
906 void segment_on()
907 {
908     ss_a = 0;
909     ss_b = 0;
910     ss_c = 0;
911     ss_d = 0;
912     ss_e = 0;
913     ss_f = 0;
914     ss_g = 0;
915     ss_dot = 0;
916 }
917
918 // Debugging function
919 void key_rise_int1()
920 {
921     wait(0.01);
922     if(key)
923     {
924         pc.printf("pressed");
925     }
926 }
927
928 // Debugging function
929 void key_fall_int1()
930 {
931     wait(0.01);
932     if(!key)
933     {
934         pc.printf("released");
935     }
936 }
937
938 }
939
940 // Interrupt handler for key press
941 void key_rise_int()
942 {
943
944     wait(0.01);
945     //read the value of the key after 10ms and set the
946     flag
947     if(key)

```

```

947     {
948         timer_400.stop();    // Stop the space timer
949         flag = true;
950         //start a timer
951         timer_key.start();   // Start the button press
                                timer
952         // pc.printf("key pressed");
953     }
954
955     else
956     {
957         flag = false;
958     }
959 }
960
961 // Interrupt handler for key release
962 void key_fall_int()
963 {
964     wait(0.01);
965
966     if(!key)
967     {
968         //pc.printf("key released");
969         //timer_400.reset();
970         // stop the timer
971         timer_key.stop();
972
973         // read the timer value and decide if dot, dash
974         int timer_key_val = timer_key.read_ms();
975
976         if((timer_key_val>40)&&(timer_key_val<220)&&(flag
977             ==true) )
978         { // dot received
979             /*myled1 = 1;
980             wait(0.05);
981             myled1 = 0;*/
982             dot();
983         }
984
985         // dash received
986         else if (timer_key_val>220){
987             /*myled2 = 1;
988             wait(0.05);
989             myled2 = 0;*/
990             dash();
991         }
992
993         // reset the timer
994         timer_key.stop();

```

```

995         timer_key.reset();
996         flag=0;
997         timer_400.reset(); // Reset and restart the
           space timer
998         timer_400.start();
999
1000     }
1001 }
1002
1003
1004
1005 int main() {
1006
1007
1008     // Check the leds
1009     myled1 = 0;
1010     myled2 = 1;
1011     myled3 = 1;
1012     myled4 = 1;
1013
1014     wait(0.5);
1015     myled1 = 0;
1016     myled2 = 0;
1017     myled3 = 0;
1018     myled4 = 0;
1019
1020     // Check the seven segment
1021     segment_off();
1022     wait(0.5);
1023     segment_on();
1024     wait(0.5);
1025     segment_off();
1026
1027     pc.baud(9600);
1028     row = 1;
1029
1030
1031     // start the timer for 400ms
1032     timer_400.start();
1033
1034     key.rise(&key_rise_int); // Set up the interrup
           handler
1035     key.fall(&key_fall_int);
1036
1037
1038     while(1) {
1039         // if timer value hits 400 ms, then reset the
           timer and read as space.
1040         if(timer_400.read_ms()>=400)
1041         {

```

```

1042         timer_400.reset();
1043
1044         if (!flag)
1045         {
1046             //pc.printf("Got a space\n");
1047             /*myled3 = 1;
1048             wait(0.05);
1049             myled3 = 0;*/
1050
1051             space();
1052
1053         }
1054     }
1055 }
1056

```

Difference between Polling and Interrupt driven programs

Polling and interrupts based detections are two common ways to check if a certain key has been pressed or if a certain pin has been either pulled up or pulled down. In a polling driven program, the CPU wastes cycles while waiting for the pin to go high or low, this happens because the code is put in an infinite while loop with an if statement reading the pin configuration. In an interrupt driven program, the CPU is generally interrupted when a certain pin reaches a particular condition and thus with this the micro-controller doesn't keep checking the status of a pin unnecessarily.