

# DIRAS: Distributed Image Reconstruction in Adversarial Scenario

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# Motivation

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# Motivation - CPS

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- ▶ Analysis of image plays a key role in agriculture [Vibhute and Bodhe, 2012], medical systems [Dougherty, 2009], remote sensing [Chen, 2012], robotics [Kurka and Salazar, 2019]
- ▶ Image data holds great value in numerous fields

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- ▶ **These issues need to be addressed**

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- ▶ Uses Robust Principal Component Analysis and Matrix Completion for cleaning the tampered image
- ▶ Incorporates other mechanisms to mitigate the effect of other security attacks

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DIRAS combines the concept of security in CPS, distributed optimization and image reconstruction for secure and scalable reconstruction of images.

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- ▶ However, in case of gross errors - performance of PCA degrades
- ▶ Need for making PCA robust
- ▶ RPCA helps in extracting the low-rank matrix and the sparse matrix from the data matrix in case of gross errors

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# Background - Matrix Completion

- ▶ Matrix Completion [Keshavan et al., 2010] will be used when RPCA won't be capable to reconstruct the image
- ▶ Occurs when the node reconstructing the image does not receive chunks of the image - parts of an image are missing
- ▶ Matrix Completion is used to obtain those parts of the images that have been lost by the framework

# System Design

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- ▶ Monitors have enough computation power to run RPCA and matrix completion algorithms
- ▶ Sensors have enough computation power to split images into chunks



# System Design - System Architecture

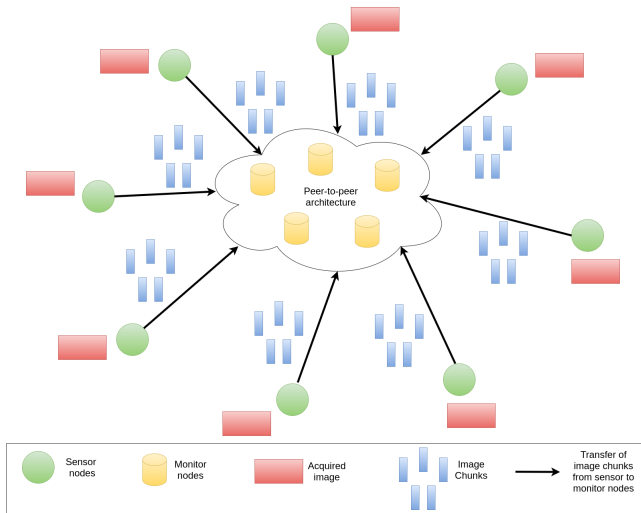


Figure: High level architecture of DIRAS

# System Design - System Architecture

- ▶ Sensor nodes
- ▶ Monitor nodes
- ▶ Peer-to-peer network

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- ▶ **Sensor nodes**
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  - ▶ Acquire images from surroundings
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# System Design - System Architecture

- ▶ **Sensor nodes**

- ▶ Acquire images from surroundings
- ▶ Send the images to the monitor nodes for further analysis

- ▶ Monitor nodes

- ▶ Peer-to-peer network

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- ▶ Sensor nodes
- ▶ **Monitor nodes**
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# System Design - System Architecture

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- ▶ **Monitor nodes**
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- ▶ Sensor nodes
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# System Design - System Architecture

- ▶ Sensor nodes
- ▶ **Monitor nodes**
  - ▶ Obtain images from the sensors
  - ▶ Reconstruct the whole image which is used for further analysis
  - ▶ Remove the noise added to the image by an attacker
- ▶ Peer-to-peer network

# System Design - System Architecture

- ▶ Sensor nodes
- ▶ Monitor nodes
- ▶ **Peer-to-peer network**

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# System Design - System Architecture

- ▶ Sensor nodes
- ▶ Monitor nodes
- ▶ **Peer-to-peer network**
  - ▶ Monitors are connected over a peer-to-peer network (p2p network)
  - ▶ Ensures that a monitor can share packet with any other monitor
  - ▶ Reasonable assumption considering the advent of IoT

# System Design - Functionality

- ▶ Monitor Position Assignment
- ▶ Image acquisition and splitting
- ▶ Lightweight Leader Selection Algorithm
- ▶ Image Reconstruction
- ▶ Improvement in DIRAS: Load Balancing

We explain each of these steps in the next few slides.

# System Design - Functionality

- ▶ **Monitor Position Assignment** - Occurs every epoch time ( $\Delta$ )
- ▶ Image acquisition and splitting
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- ▶ Improvement in DIRAS: Load Balancing

# System Design - Functionality

## Monitor Position Assignment

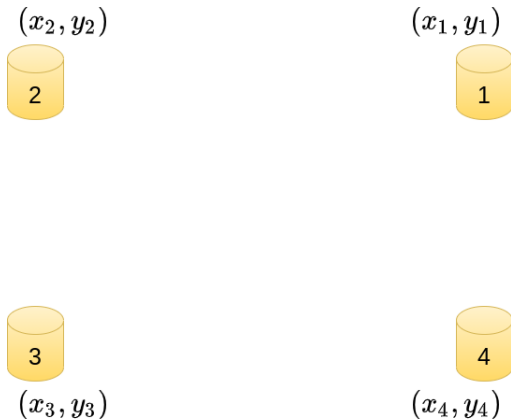


Figure: Monitors generate (pseudo)random coordinates



# System Design - Functionality

## Monitor Position Assignment

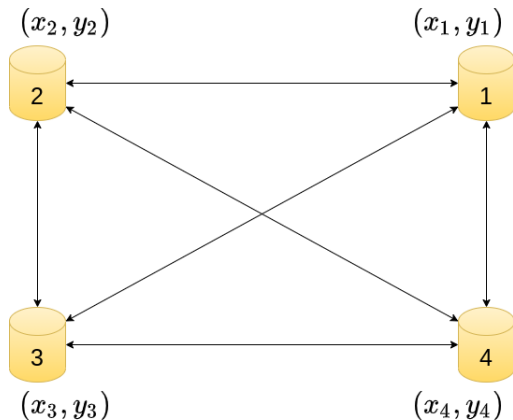


Figure: Monitors broadcast the random coordinates to each other

# System Design - Functionality

## Monitor Position Assignment

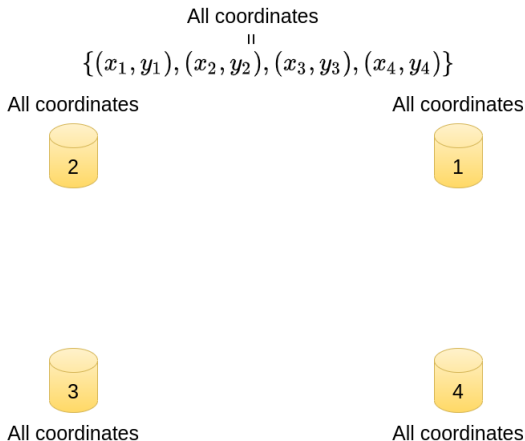


Figure: Monitors acquire and store the coordinates of all other monitors

# System Design - Functionality

- ▶ Monitor Position Assignment
- ▶ **Image acquisition and splitting**
- ▶ Lightweight Leader Selection Algorithm
- ▶ Image Reconstruction
- ▶ Improvement in DIRAS: Load Balancing

# System Design - Functionality

## Image acquisition and splitting

All coordinates



All coordinates



Image = 3D Matrix



All coordinates



All coordinates

**Figure:** Sensor acquires image

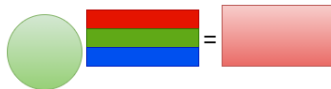
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## Image acquisition and splitting

All coordinates



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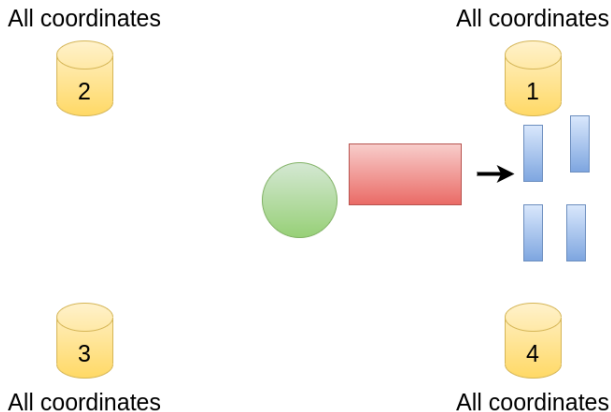


All coordinates

**Figure:** Sensor stacks the R, G and B components vertically to create a 2-D matrix

# System Design - Functionality

## Image acquisition and splitting



**Figure:** Sensor splits the image into chunks

# System Design - Functionality

## Image acquisition and splitting

All coordinates



All coordinates



$(x_i, y_i)$



All coordinates



All coordinates

**Figure:** Sensor generates a random coordinate

# System Design - Functionality

## Image acquisition and splitting

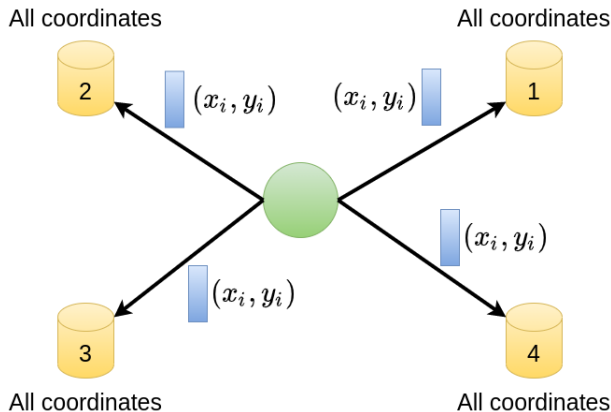


Figure: Sensor sends coordinates and chunks to the monitors

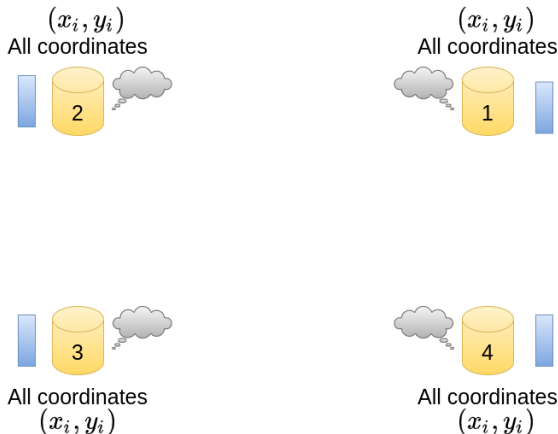


# System Design - Functionality

- ▶ Monitor Position Assignment
- ▶ Image acquisition and splitting
- ▶ **Lightweight Leader Selection Algorithm**
- ▶ Image Reconstruction
- ▶ Improvement in DIRAS: Load Balancing

# System Design - Functionality

## Lightweight Leader Selection Algorithm



**Figure:** Monitors find the distance between  $(x_i, y_i)$  and all  $(x_j, y_j)$  using  $D_{ij} = \sqrt{(x_i - x_j)^2 + (y_i - y_j)^2}$ , where  $j = \{1, 2, 3, 4\}$

# System Design - Functionality

## Lightweight Leader Selection Algorithm

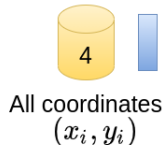
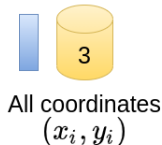
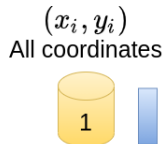
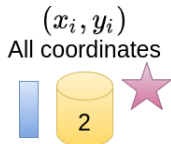


Figure: Monitor with the shortest distance from  $(x_i, y_i)$  is the leader

# System Design - Functionality

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# System Design - Functionality

## Image Reconstruction

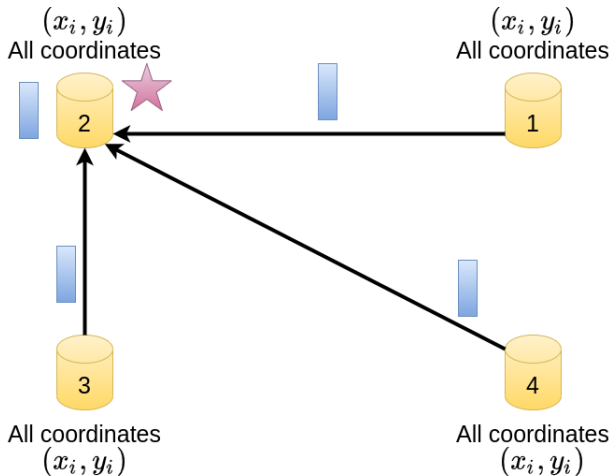


Figure: Monitors send chunks of image to the leader

# System Design - Functionality

## Image Reconstruction

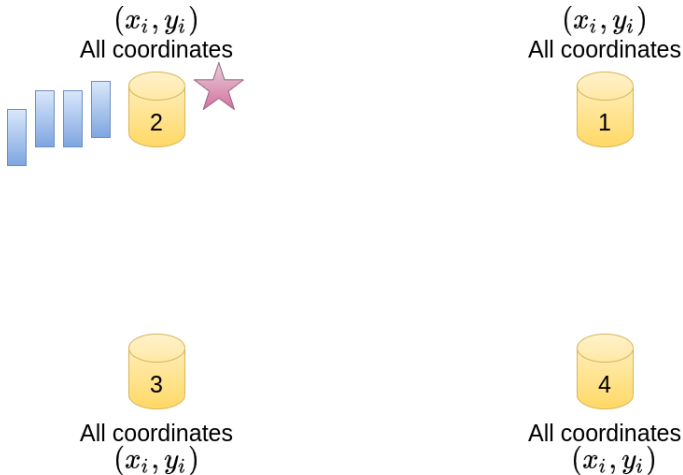
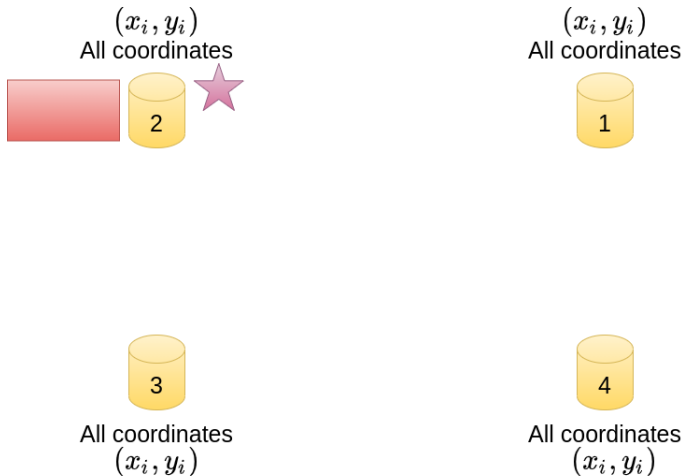


Figure: Leader gets all the chunks from the monitors

# System Design - Functionality

## Image Reconstruction



**Figure:** Leader combines all the chunks to form a single 2D matrix

# System Design - Functionality

## Image Reconstruction

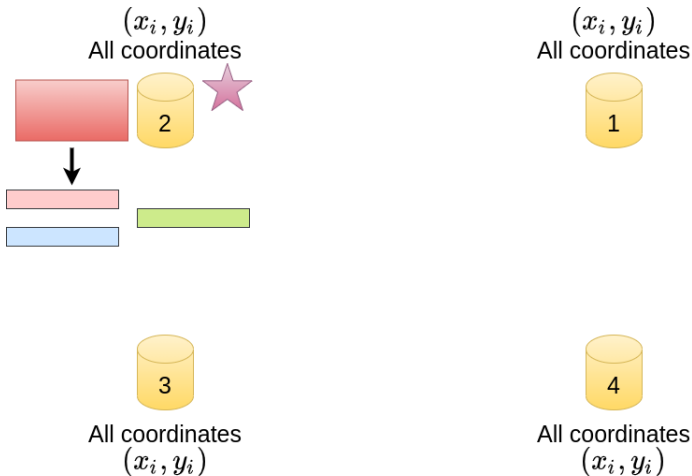
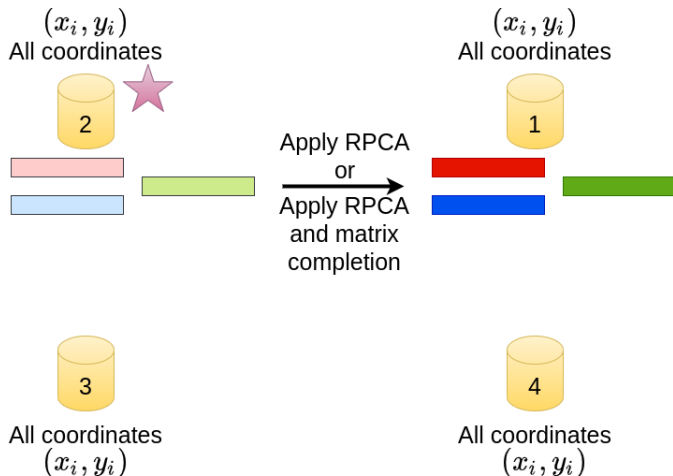


Figure: Leader separates the R, G, and B components of the image



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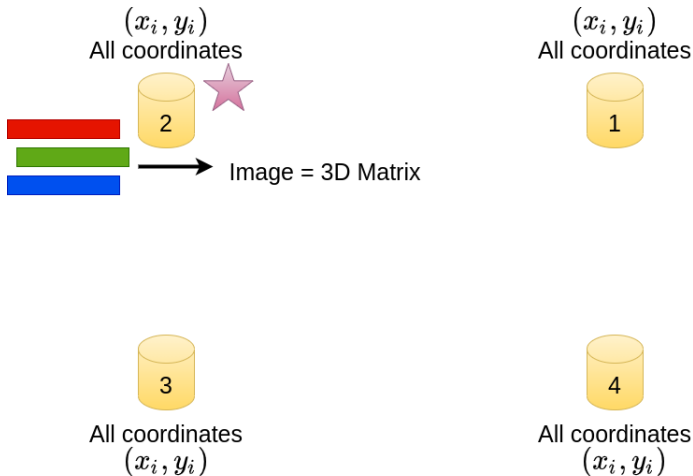
## Image Reconstruction



**Figure:** Leader applies RPCA or RPCA along with matrix completion to remove noise and reconstruct the matrix

# System Design - Functionality

## Image Reconstruction



**Figure:** Leader combines the R, G, and B components of the image to obtain the entire image

# System Design - Functionality

## When and why do we need RPCA?

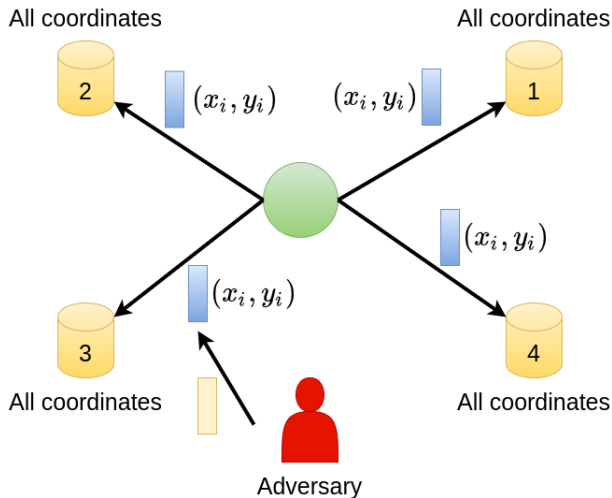


Figure: Attacker adds injects false data to the chunk

## System Design - Functionality

**When and why do we need RPCA with matrix completion?**

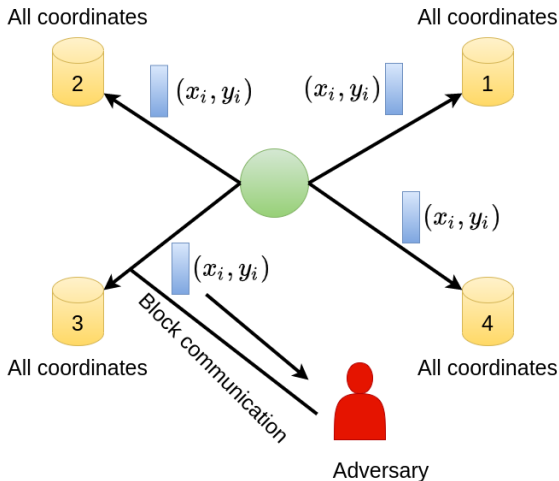


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- ▶ **Improvement in DIRAS: Load Balancing**

## Improvement in DIRAS: Load Balancing

- ▶ Leader selection algorithm in DIRAS:

$$L(l_i) = j, \quad \text{s.t.} \quad \min_j D_{ij}$$

where  $D_{ij} = \sqrt{(x_i - x_j)^2 + (y_i - y_j)^2}, \quad j = 1, \dots, \mathbf{MN}$

# System Design - Functionality

## Improvement in DIRAS: Load Balancing

- ▶ Leader selection algorithm in DIRAS:

$$Leader = j, \quad \text{s.t.} \quad \min_j D_{ij}$$

$$\text{where } D_{ij} = \sqrt{(x_i - x_j)^2 + (y_i - y_j)^2}, \quad j = 1, \dots, \mathbf{MN}$$

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- ▶  $x_i, y_i, x_j, y_j$  are all random numbers
- ▶ Therefore, some monitors will have to reconstruct more images, while some will have to regenerate less images
- ▶ Hence, latency will be induced

# System Design - Functionality

## **Improvement in DIRAS: Load Balancing**

- ▶ Incorporation of load balancing

# System Design - Functionality

## Improvement in DIRAS: Load Balancing

- ▶ Incorporation of load balancing
- ▶ After incorporating load balancing, leader selection algorithm becomes:

$$Leader = j, \quad \text{s.t.} \quad \min_j F_{ij}$$

$$F_{ij} = D_{ij} + \beta_j \times \max_j D_{ij}$$

where  $D_{ij} = \sqrt{(x_i(l_i) - x_j)^2 + (y_i(l_i) - y_j)^2}$ ,  $j = 1, \dots, \mathbf{MN}$

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- ▶ The term  $\beta_j \times \max_j D_{ij}$  ensures that the computation burden is distributed evenly in the monitor node network

# Implementation

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# Implementation - Communication Network

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- ▶ **For studying the performance of image reconstruction**

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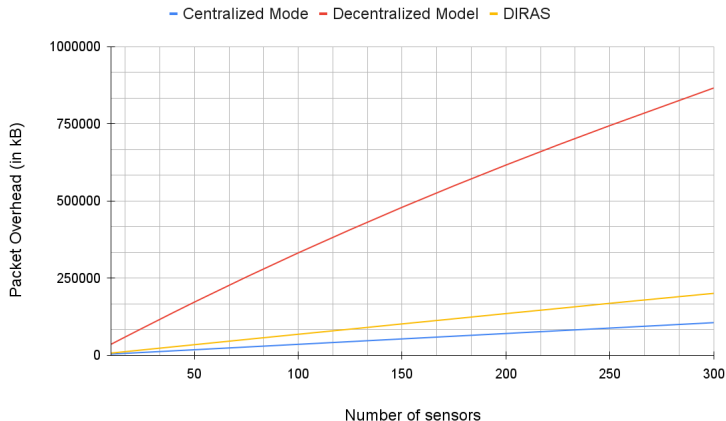
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- ▶ **For studying the amount of information revealed by a given number of rows of a matrix**



# Evaluation

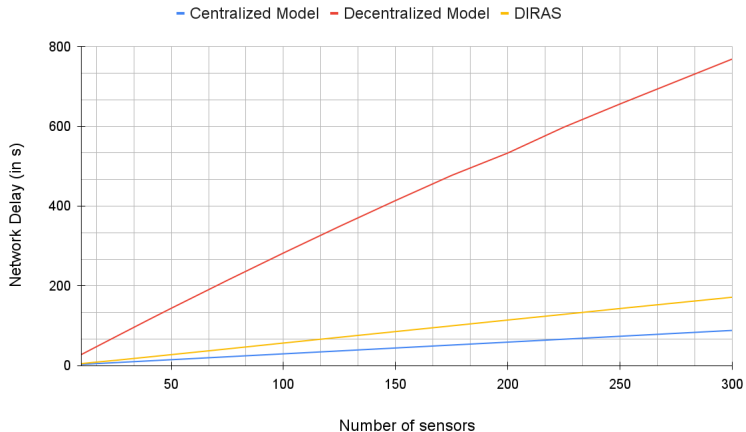
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# Evaluation - Communication Network



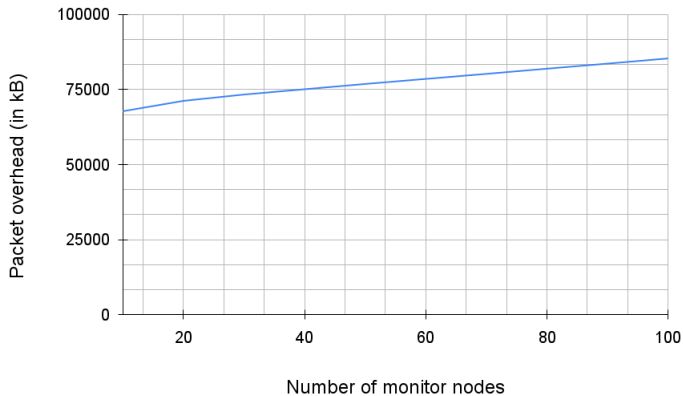
**Figure:** Variation in packet overhead with change in number of sensor nodes and comparison with centralized and decentralized models

# Evaluation - Communication Network



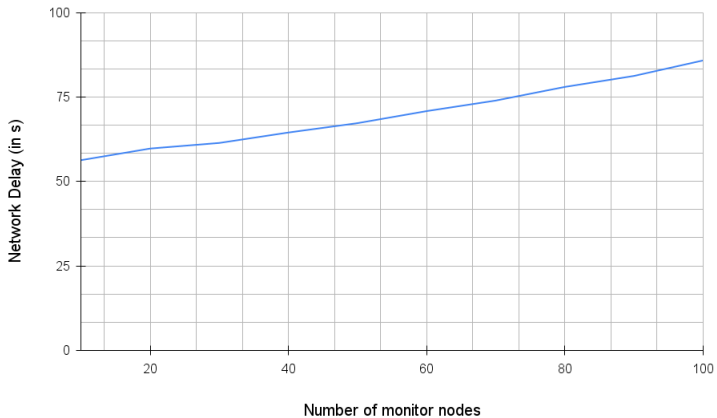
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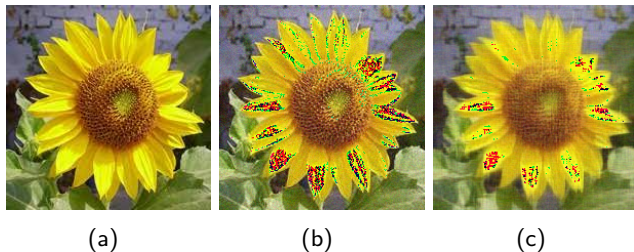
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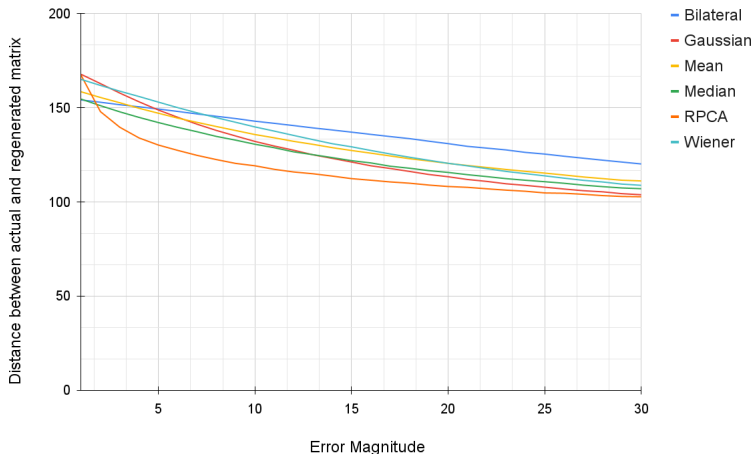
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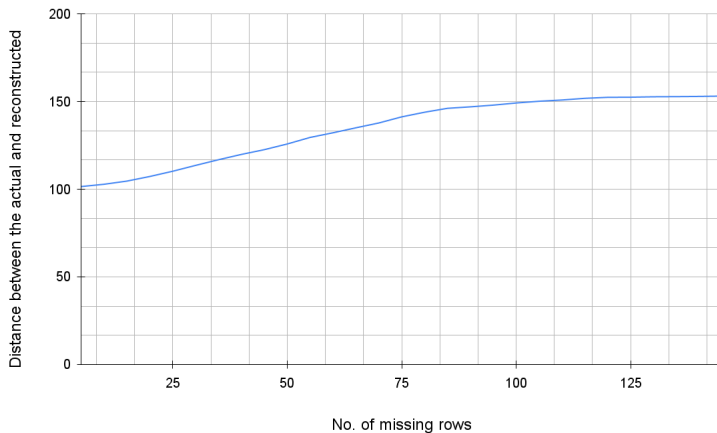
**Figure:** Denoising by RPCA - (a) Actual Image (b) Image with noise (c) Reconstructed image

# Evaluation - Image Reconstruction



**Figure:** Performance of DIRAS in case of false data injection and its comparison with other filters

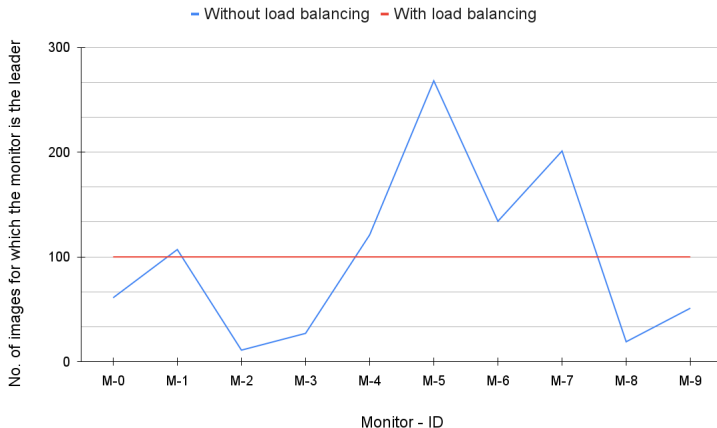
# Evaluation - Image Reconstruction



**Figure:** Performance of DIRAS in case of packet dropping and false data injection

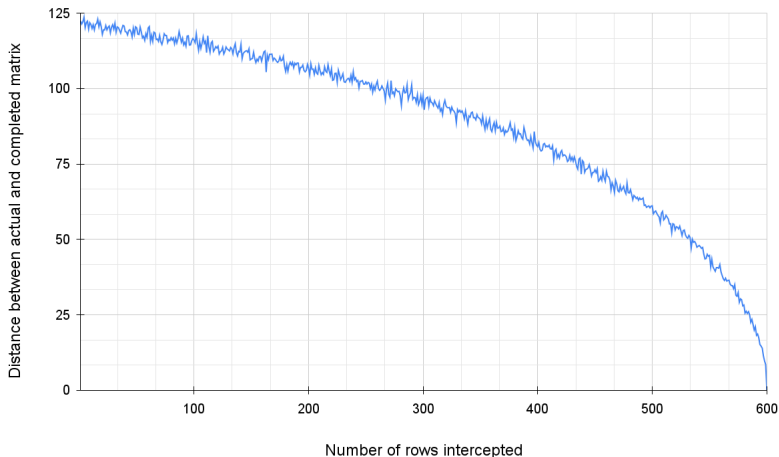


# Evaluation - Load Balancing Analysis



**Figure:** Improvement in performance because of load balancing based on the number of images for which each monitor node has been chosen as the leader

# Evaluation - Privacy Analysis



**Figure:** Privacy provided by DIRAS based on distance between the actual matrix and the matrix reconstructed after applying matrix completion

# Discussion

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- ▶ For successfully obtaining substantial information - attacker needs to control multiple channels, which is difficult - figure 28
- ▶ To reduce number of rows in a chunk - increase the number of monitor nodes - this increases the latency and bandwidth a little - trade-off between network performance and privacy

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  - ▶ Load balancing helps in resolving this issue

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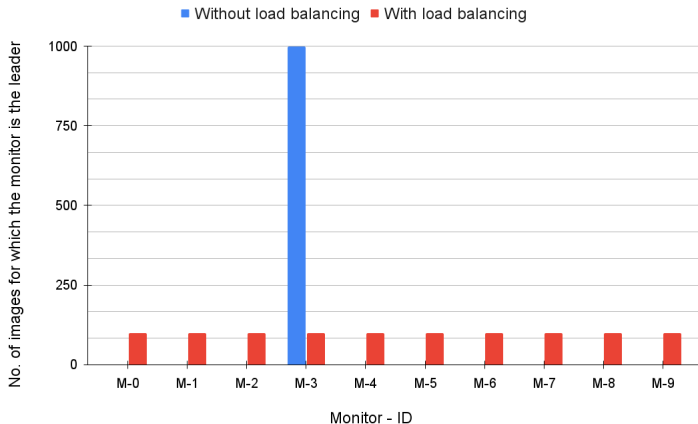


Figure: Mitigation of effect of DoS attacks by load balancing

# Future Work

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- ▶ Improving the privacy by integrating differential privacy [Dwork, 2008]

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- ▶ Distributed - which makes it scalable
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- ▶ Privacy-preserving
- ▶ Image reconstruction part is still not robust - needs improvements
- ▶ Can be integrated with any system that uses matrix for data storage and processing

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Thank You!