## 多媒体智能课程汇报

2024.7.1





- ➤ 论文: EmbodiedGPT: Vision-Language Pre-Training via Embodied Chain of Thought
- ➤ 作者: Yao Mu、Qinglong Zhang、Mengkang Hu、Wenhai Wang、Mingyu Ding、Jun Jin、Bin Wang、Jifeng Dai、Yu Qiao、Ping Luo
- ▶ 单位: 香港大学、上海人工智能实验室、诺亚方舟实验室
- ➤ 录用: NeurIPS 2023 (CCF-A)
- ▶ 领域: 多媒体智能、具身智能



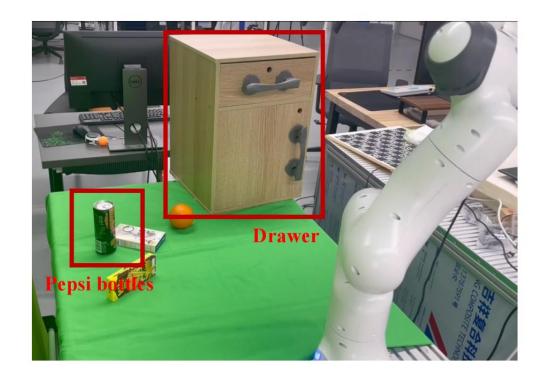
汇报 内容 研究背景

**一** 研究方法

三 实验评估



#### **Perception: Classification & Grounding**



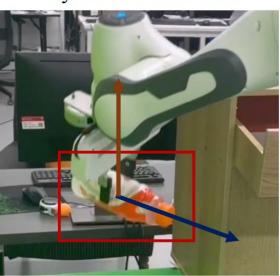
### **Embodied Cognition**

Where to interact? How to interact?



Interactive preferences
Physical Constrains





I know it

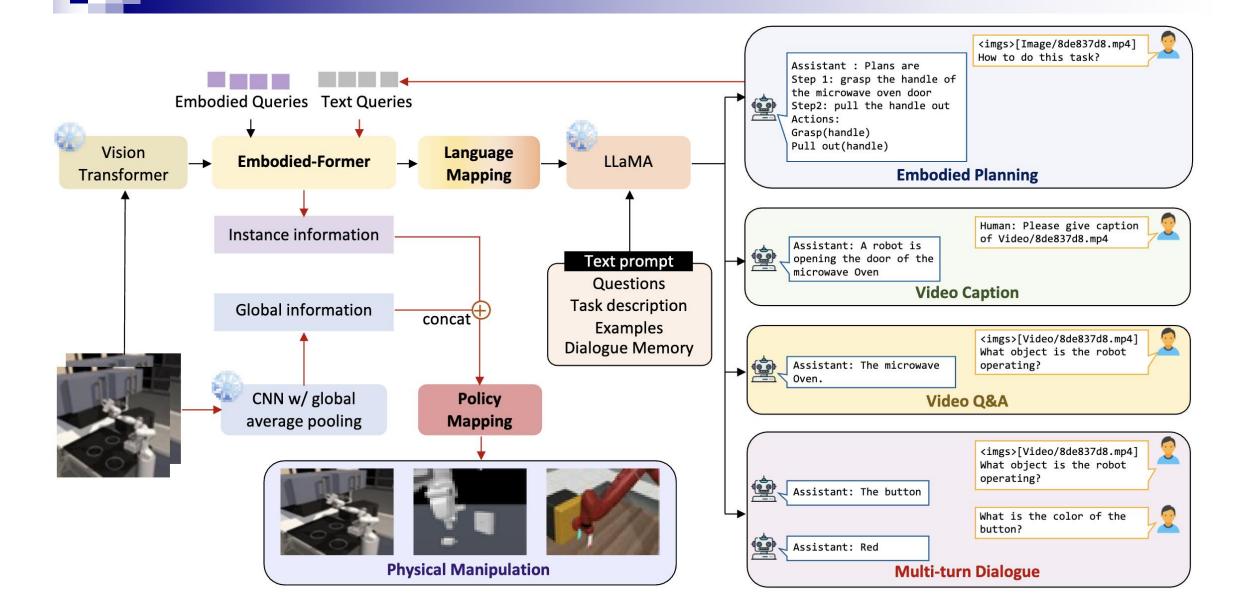
I know how to deal with it



- ▶ LLM的进步: LLM具备在语言理解、推理和建立逻辑链的能力
- ➤ **大规模数据集**: EAI任务需要以自我为中心的机器人领域的数据、精确规划的 结构化语言指令
- ▶ 现有数据集的局限性:成本高、规模较小且特定于特定领域,Sim2Real

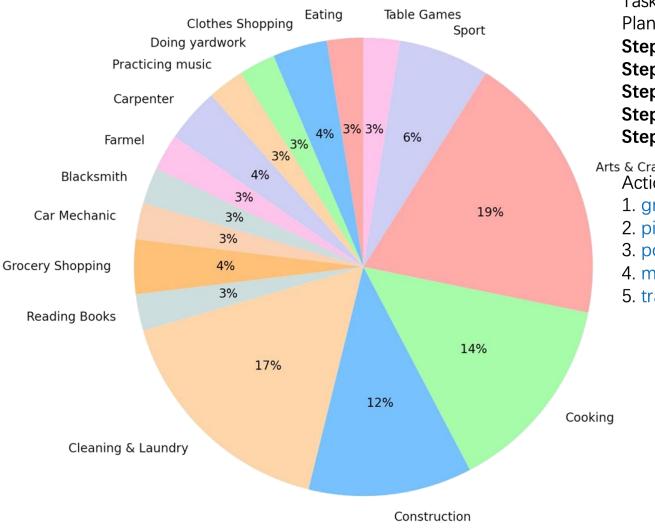


### 研究方法: Embodied GPT





## 研究方法: EgoCot Dataset



Task: Move sliced meat onto a plate

Plans:

**Step 1**: First, grasp the handle of the knife.

Step 2: Pick up the knife.

**Step 3**: Use your left hand to position the meat onto the knife.

**Step 4**: Then, move the knife to the position over the plate.

**Step 5**: Transfer the meat slices from the knife to the plate.

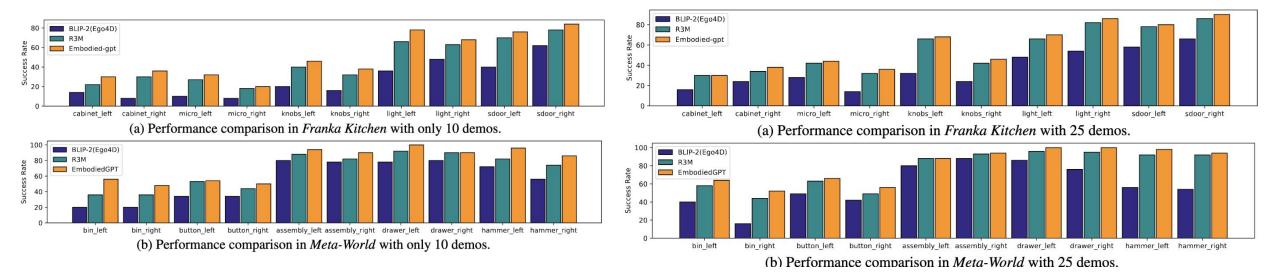
#### Arts & Crafts

#### Actions:

- 1. grasp(handle of the knife)
- 2. pick up(knife)
- 3. position(meat, onto the knife)
- 4. move(knife, position over the plate)
- 5. transfer(meat slices, plate)







Model	Object(†)	Spatial(↑)	Redundancy( $\downarrow$ )	Plan Reasonable(†)	Plan Executable(↑)
Minigpt4	5.6	4.8	4.4	4.5	4.8
LLaVA-7B	7.3	7.4	3.9	7.5	6.6
LLaVA-13B	8.5	8.6	3.4	8.4	7.6
EmbodiedGPT	8.4	8.8	2.6	8.8	8.4

Table 1: Generate Quality Evaluation on image input tasks.

Figure 6: Performance of EmbodiedGPT in low-level control tasks with 25 demonstration demos.

Model	Franka(10 demos)	Franka(25 demos)	Meta-World(10 demos)	Meta-World(25 demos)
EmbodiedGPT	50.8% $\pm 2.8$	58.5% $\pm 2.7$	<b>76.4</b> % $\pm 2.2$	<b>81.2</b> %±2.0
<ul> <li>Close-loop</li> </ul>	$38.6\% \pm 2.9$	$47.3\% \pm 2.5$	$62.7\% \pm 2.2$	$64.9\% \pm 2.0$
- COT	$26.2\% \pm 3.2$	$36.4\% \pm 2.7$	$55.2\% \pm 2.4$	$58.7\% \pm 2.0$

# 谢谢! 请各位批评指正!