Chapter 4: Compilers and Interpreters

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4. Compilers and Interpreters

- Aspects of compilation
- Static and dynamic memory allocation
- Memory allocation in block structured languages
- Compilation of expressions
- Code Optimization
- Interpreters

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Aspects of Compilation

- A compiler bridges the semantic gap between a PL domain and an execution domain.
- Two aspects of compilations are
 - Generate code to implement meaning of a source program in the execution domain.
 - Provide diagnostics for violations of PL semantics in a source program.

Aspects of Compilation

- PL Features
 - Data Types
 - Data Structures
 - Scope Rules
 - Control Structure

Data Types

- A data is a specification of
 - i. Legal values for variables of the type and
 - ii. Legal operations on the legal values of the type.
- The following tasks are involved
 - Checking legality of an operation for types of operands.
 - ii. Use type conversion operations.
 - iii. Use appropriate instruction sequence of the target machine.

Data Types

Example: Consider program segment

i: integer;

a, b: real

a := b + 1

Instruction generated for program segment:

CONV_R AREG, I

ADD R AREG, B

MOVEM AREG, A

Data Structure

- A PL permits the declaration and use of data structure like arrays, stacks, records, lists etc.
- To compile a reference to an element of a data structure, compiler must develop a memory mappings to access memory word(s) allocated to the element.
- A user defined type requires mapping of a different kind.

Data Structure Example:

```
program example (input, output);
  type
          employee = record
                    name: array [1..10] of character;
                    sex : character;
                    id: integer;
          end
          weekday = (mon, tue, wed, thu, fri, sat);
  var
          info: array [1..500] of employee;
          today: weekday;
          i, j: integer;
  begin
          today := mon;
          info[i].id := j;
          if today = tue then...
end
```

Scope Rule

- It determines the accessibility of variables declared in different block of a program.
- Example:

```
x, y : real;
y, z: integer;
B x := y
```

Control structure

 The control structure of a language is the collection of language features for altering the flow of control during the execution of a program.

```
– Example:
```

```
for i := 1 to 100 do
begin
lab1: if i = 10 then..
end;
```

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Memory Allocation

- Memory allocation involves three important task.
 - Determine the amount of memory required to represent the values of a data item.
 - Use an appropriate memory allocation model to implement the lifetimes and scope of data items.
 - Determine appropriate memory mappings to access the values in a non-scalar data item.

- Memory Binding is an association between the 'memory address' attribute of a data item and the address of a memory area.
 - In static memory allocation, memory is allocated to a variable before the execution of program begins.
 - In dynamic memory allocation, memory bindings are established and destroyed during the execution of a program.

Example:

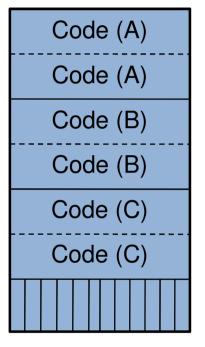


Fig a: Static memory allocation

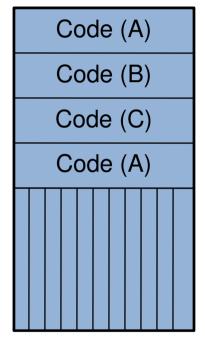


Fig b: Dynamic memory allocation when only program unit A

is active Mrs, Sunita M Dol, CSE Dept

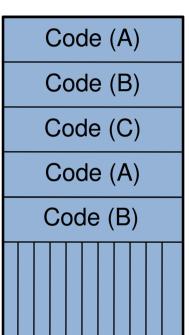


Fig c: the situation after A calls B

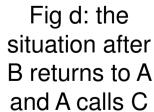
Code (A)

Code (B)

Code (C)

Code (A)

Code (B)



- Dynamic memory allocation has two flavours:
 - Automatic allocation: memory is allocated to the variables in a program unit when the program unit is entered during execution and is deallocated when the program is exited.
 - Program controlled allocation: a program can allocate or deallocate memory at arbitrary points during its execution.

- Dynamic memory allocation can be implemented using stack and heaps.
 - Automatic dynamic allocation is implemented using stack.
 - Program controlled allocation is implemented using heap.

- Dynamic memory allocation advantages
 - Recursion can be implemented easily.
 - Dynamic allocation can support data structure whose sizes are determined dynamically e.g. Array.

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Scope Rules

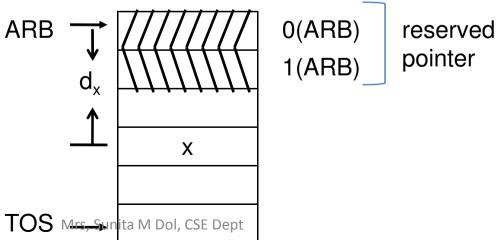
- A data declaration using a name name; creates a variable var; (name; var;)
- Variable var_i is visible at a place in the program if some binding $(name_i, var_i)$ is effective at that place.
- It is possible for data declaration in many blocks of a program to use a same name say name;
- Scope rules determine which of these bindings is effective at a specific place in the program.

- Scope of a variable
 - If a variable var_i is created with the name name_i in a block b,
 - var_i can be accessed in any statement situated in block b
 - var_i can be accessed in any statement situated in a block b' which is enclosed in b unless b' contains a declaration using the same name.
 - A variable declared in block b is called a local variable of block b.
 - A variable of enclosing block that is accessible within block b is called a nonlocal variable.

- Scope of a variable
 - Example

Block	Accessible variables	
	local	nonlocal
А	X_A, Y_A, Z_A	
В	g_{B}	x_A, y_A, z_A
С	h _C , z _C	x_A, y_A, g_B
D	i _D , j _D	x_A, y_A, z_A

- Memory allocation and access
 - Automatic memory allocation can be implemented using the extended stack model.
 - Each record in the stack has two reserved pointers.
 - Each stack record accommodates the variables for one activation of a block, hence called an activation record.



Memory allocation and access

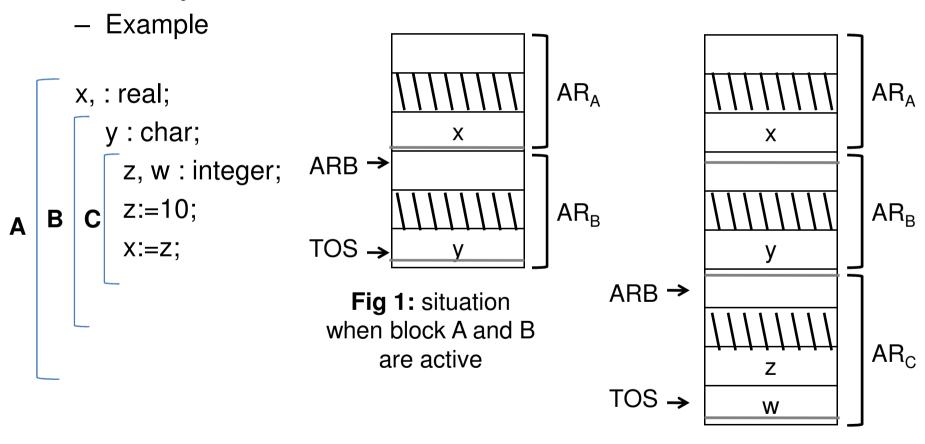


Fig 2: situation after entry to c₂₄

- Memory allocation and access
 - Action at entry of block C

Sr. No.	Statement
1	TOS := TOS + 1;
2	TOS* := ARB; {set the dynamic pointer}
3	ARB := TOS;
4	TOS := TOS + 1;
5	TOS* :=; {set the dynamic pointer 2}
6	TOS := TOS + n;

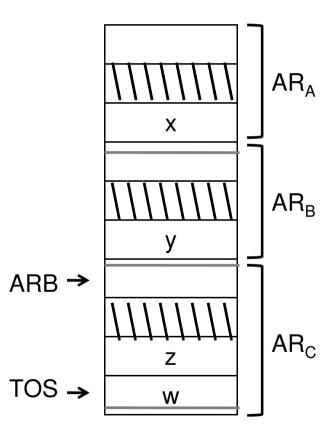


Fig 2: situation after entry to c₂₅

- Memory allocation and access
 - Action at exit of block C

Sr. No.	Statement		ППППП	
1	TOS := ARB - 1;		X	, <i>p</i>
2	$ARB := ARB^*;$	ARB →		
				AR _E
		TOS →	У	

Fig 1: situation when block A and B are active

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Compilation of expressions

- A Toy Code Generator for Expression
- Intermediate Codes for Expression

A Toy Code Generator for Expression

The major issues in code generation for expression are:

- Determination of an evaluation order for the operators in an expression
 - Top down and bottom up parse
- Selection of instruction to be used in the target code.
 - Operand Descriptor
- Use of registers and handling of partial result.
 - Register Descriptor

Operand Descriptor

An operand descriptor has the following fields:

- Attributes : contains subfields type, length and miscellaneous information
- Addressability
 - Addressability Code- M, R, AM, AR
 - Address

Example:

MOVER AREG, A MULT AREG, B

(int, 1)	M, addr(a)
(int, 1)	M, addr(b)
(int, 1)	R, addr(AREG)

Descriptor for a

Descriptor for b

Descriptor for a*b

Register Descriptor

An register descriptor has the following fields:

- Status: occupied or free
- Operand Descriptor#

Example:

MOVER AREG, A MULT AREG, B

Operand Descriptor

(int, 1)	M, addr(a)	Descriptor for a
(int, 1)	M, addr(b)	Descriptor for b
(int, 1)	R, addr(AREG)	Descriptor for a*b

Register Descriptor

Occupied	#3
----------	----

Generating Instruction

- Single instruction can be generated to evaluate op_i if the descriptor indicate that one operand is in a register and the other is in memory.
- If both operands are in memory, an instruction is generated to move one of them into a register. This is followed by an instruction to evaluate op;

Saving Partial Result

 If all registers are occupied when operator op_i is to be evaluated, a register r is freed by copying its contents into a temporary location in the memory.

Example: Consider the expression a*b + c*d. After generating code for a*b, the operand and register descriptor would be as shown below.

Operand [Descriptor
-----------	------------

(int, 1)	M, addr(a)	Descriptor for a
(int, 1)	M, addr(b)	Descriptor for b
(int, 1)	R, addr(AREG)	Descriptor for a*b

Register Descriptor

Occupied	#3

After the partial result a*b moved to a temporary location, the operand descriptor must become:

(int, 1)	M, addr(a)	Descriptor for a
(int, 1)	M, addr(b)	Descriptor for b
(int, 1)	M, addr(temp[1])	Descriptor for a*b

Code Generation Routine

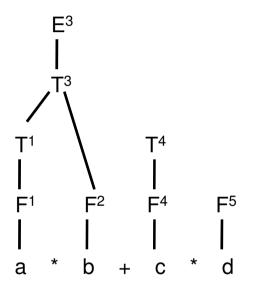
```
codegen(operator, opd1, opd2)
          if opd1.addressability code = 'R'
                    if operator = '+' generate 'ADD AREG, opd2';
          else if opd2.addressability_code = 'R'
                    if operator = '+' generate 'ADD AREG, opd1';
          else
                    if Register descr.status = 'occupied'
                              generate ('MOVEM AREG, Temp[j]');
                              i = i + 1;
                              Operand_descr [Register_descr.Operand_descriptor#] =
                                 (<key>, (M, Addr(Temp[j])));
                              generate 'MOVEM AREG, opd1'
                    if operator = '+' generate 'ADD AREG, opd2';
          i = i + 1;
          Operand descr[i] = (<key>, (R, Addr(AREG)));
          Register descr[i] = ('Occupied', i);
          return I:
```

Code Generation actions for a*b + c*d

Step No.	Parsing action	Code generation action
1	$< id>_a \rightarrow F^1$	Build descriptor # 1
2	$F^1 \to T^1$	-
3	$< id>_b \rightarrow F^2$	Build descriptor # 2
4	$T^1 * F^2 \rightarrow T^3$	Generate MOVER AREG, A MULT AREG, B
		Build descriptor # 3
5	$T^3 \rightarrow E^3$	-
6	$<$ id $>_c \rightarrow F^4$	Build descriptor # 4
7	$F^4 \rightarrow T^4$	-
8	$< id>_d \rightarrow F^5$	Build descriptor # 5
9	$T^4 * F^5 \rightarrow T^6$	Generate MOVEM AREG, TEMP_I MOVER AREG, C MULT AREG, D Build descriptor # 6
10	$E^3 + T^6 \rightarrow E^7_{Mrs, Si}$	Generate ADD AREG, TEMP_I

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Code Generation actions for a*b + c*d



Operand Descriptor

(int, 1)	M, addr(a)
,	, ,
(int, 1)	M, addr(b)
(int, 1)	R, addr(AREG)
(int, 1)	M, addr(c)
(int, 1)	M, addr(d)

Descriptor for a

Descriptor for b

Descriptor for a*b

Descriptor for c

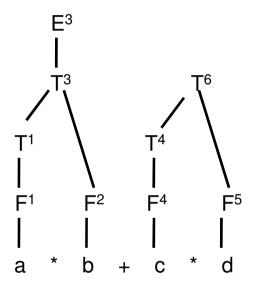
Descriptor for d

Register Descriptor

Occupied #3

5

Code Generation actions for a*b + c*d



Operand Descriptor

(int, 1)	M, addr(a)
(int, 1)	M, addr(b)
(int, 1)	M, addr(temp[1])
(int, 1)	M, addr(c)
(int, 1)	M, addr(d)
(int, 1)	R, addr(AREG)

Descriptor for a

Descriptor for b

Descriptor for a*b

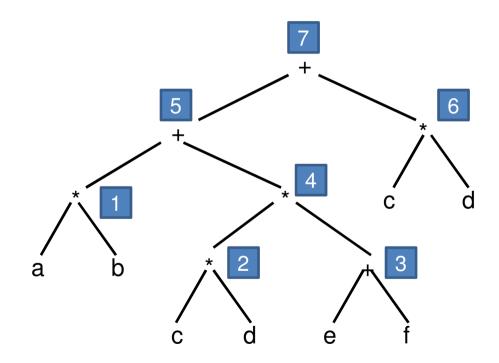
Descriptor for c

Descriptor for d

Register Descriptor

Occupied	#6

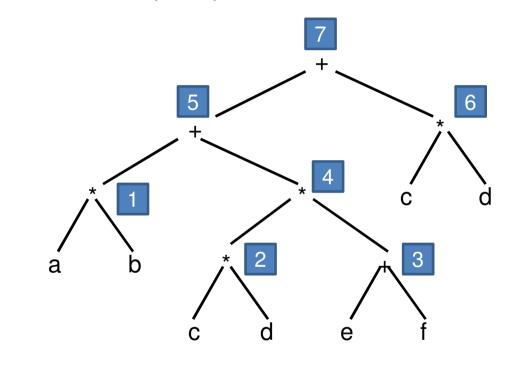
Expression tree for a*b+c*d*(e+f)+c*d



Expression tree for a*b+c*d*(e+f)+c*d

MOVER	AREG,	Α
MULT	AREG,	В
MOVEM	AREG,	TEMP_1
MOVER	AREG,	С
MULT	AREG,	D
MOVEM	AREG,	TEMP_2
MOVER	AREG,	E
ADD	AREG,	F
MULT	AREG,	TEMP_2
ADD	AREG,	TEMP_1
MOVEM	AREG,	TEMP_3
MOVER	AREG,	С
MULT	AREG,	D
ADD	AREG,	TEMP_3
- 10 - 10 0		

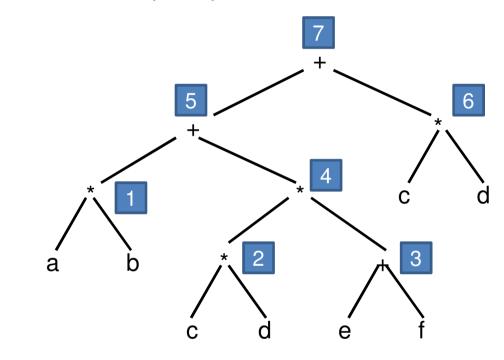
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Temporary	Contents	Used in
temp[1]	Value of node 1	Evaluating node 5
temp[2]	Value of node 2	Evaluating node 4
temp[3] Mrs, Sunita M Dol, CSE	Value of node 5	Evaluating node 7

Expression tree for a*b+c*d*(e+f)+c*d

MOVER	AREG,	Α
MULT	AREG,	В
MOVEM	AREG,	TEMP_1
MOVER	AREG,	С
MULT	AREG,	D
MOVEM	AREG,	TEMP_2
MOVER	AREG,	Е
ADD	AREG,	F
MULT	AREG,	TEMP_2
ADD	AREG,	TEMP_1
MOVEM	AREG,	TEMP_1
MOVER	AREG,	С
MULT	AREG,	D
ADD	AREG,	TEMP_1
5/25/2015		



	Temporary	Contents	Used in
	temp[1]	Value of node 1	Evaluating node 5
	temp[2]	Value of node 2	Evaluating node 4
Irs	Temp[1] , Sunita M Dol, CSE D	Value of node 5	Evaluating node 7

Compilation of expressions

- A Toy Code Generator for Expression
- Intermediate Codes for Expression

Compilation of expressions

- Intermediate Codes for Expression
 - a. Postfix strings
 - b. Triples and quadruples
 - c. Expression trees

- Postfix Strings
 - Each operator appears immediately after its last operand.

Postfix Strings

- Stack of operand descriptor can be used to perform code generation.
 - Operand descriptors are pushed on the stack as operands appear in the string.
 - When a operand with arity k appears in the string, k descriptors are popped off the stack.
 - A descriptor for the partial result generated by the operator is now pushed on the stack.

- Triples and quadruples
 - Triple is a representation of an elementary operation in the form of a pseudo-machine instruction.

Example: Triples for a + b * c + d * e ↑ f

Operator	Operand1	Operand2
*	b	С
+	1	а
↑	е	f
*	d	3
+	2	4

- Triples and quadruples
 - In indirect triple, a table is built to contain all distinct triples in the program. A program statement is represented as a list of triple numbers.
 - Example: Triples for $x = a + b * c + d * e \uparrow f$ & y = x + b * c

	Operator	Operand1	Operand2
1	*	b	С
2	+	1	a
3	↑	е	f
4	*	d	3
5	+	2	4
6	+	X Mrs, Su	nita M Do ¹ , CSE Dept

Statement no.	Triple no.
1	1, 2, 3, 4, 5
2	1, 6

- Triples and quadruples
 - Quadruple represents an elementary evaluation in the following format

Operator	Operand1	Operand2	Result name
----------	----------	----------	-------------

Example: Triples for a + b * c + d * e ↑ f

	Operator	Operand1	Operand2	Result name
1	*	Ь	С	t1
2	+	1	а	t2
3	↑	е	f	t3
4	*	d	3	t4
5	+	2	4	t5

Expression Trees

- It is an abstract syntax tree which depicts the structure of an expression.
- It is used to determine the best evaluation order.
- Example (a + b) / (c + d)

MOVER	AREG,	Α	MOVER	AREG,	С
ADD	AREG,	В	ADD	AREG,	D
MOVEM	AREG,	TEMP_1	MOVEM	AREG,	TEMP_1
MOVER	AREG,	С	MOVER	AREG,	Α
ADD	AREG,	D	ADD	AREG,	В
MOVEM	AREG,	TEMP_2	DIV	AREG,	TEMP_1
MOVER	AREG,	TEMP_1			
DIV	AREG,	TEMP_2			

Expression Trees

- Two step procedure is used to determine the best evaluation order for the operation in an expression.
- The first step associates a register requirement label with each node in the expression.
- The second step analyses the RR labels of the child nodes of s node to determine the order in which they should be evaluated.

Expression Trees

Algorithm – Evaluation order for operators

1. Visit all nodes in an expression tree in post order.

```
For each node n_i
(a) if n_i is a leaf node then
if n_i is the left operand of its parent then
RR(n_i) := 1;
else RR(n_i) := 0;
(b) if n_i is not a leaf node then
if RR(I\_child_{n_i}) NE RR(r\_child_{n_i}) then
RR(n_i) := max(RR(r\_child_{n_i}), RR(I\_child_{n_i});
else RR(n_i) := RR(I\_child_{n_i}) + 1;
```

Expression Trees

Algorithm – Evaluation order for operators

2. Perform the procedure call evaluation_order (root) which prints a postfix form of the source string in which operators appear in the desired evaluation order.

```
Procedure evaluation_order (node);

if node is not a leaf node then

if RR(I_child_node) ≤ RR(r_child_node))

evaluation_order(r_child_node));

evaluation_order(I_child_node));

else

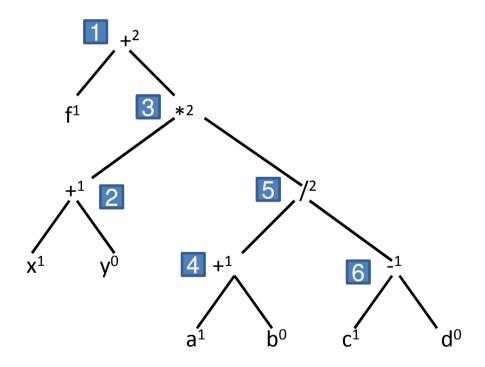
evaluation_order(I_child_node));

evaluation_order(r_child_node));

print node;

end evaluation_order;
```

- Expression Trees Example:
 - Expression tree for f + (x + y) * ((a + b) / (c d))



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- Code optimization aims at improving the execution efficiency of a program.
- This is achieved in two ways:
 - Redundancies in a program are eliminated.
 - Computations in a program are rearranged to make it executes efficiently.

Code optimization

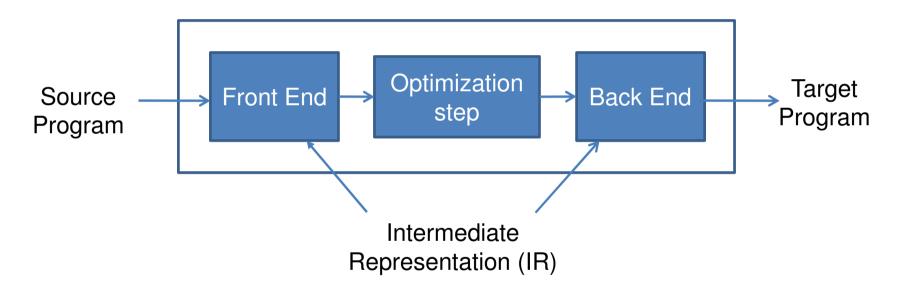


Figure: Schematic of an optimizing compiler

- Optimizing Transformation
 - An optimizing transformation is a rule for rewriting a segment of a program to improve its execution efficiency without affecting its meaning.
 - Optimizing transformations used in compilers
 - Compile time evaluation
 - Elimination of common subexpression
 - Dead code elimination
 - Frequency reduction
 - Strength reduction

- Optimizing Transformation
 - Compile time evaluation:
 - Execution efficiency can be improved by performing certain actions specified in a program during compilation itself.
 - Constant folding is the main optimization of this kind.
 - e.g. an assignment a:= 3.14157/2 can be replaced by a:= 1.570785

- Optimizing Transformation
 - Elimination of common subexpression
 - Common subexpressions are occurrences of expression yielding the same value.

e.g.

```
a := b * c;
----

After eliminating t := b * c;
the common a := t;
x := b * c + 5.2;
subexpression -----
x := t + 5.2;
```

- Optimizing Transformation
 - Dead code elimination
 - Code which can be omitted from a program without affecting its result is called dead code.
 - e.g. an assignment x := <exp> constitute dead code if the value assigned to it is not used in the program, no matter how control flows after executing this assignment.

- Optimizing Transformation
 - Frequency reduction
 - Execution time of a program can be reduced by moving code from a part of a program which is executed very frequently to another part of the program which is executed fewer times.

```
for I := 1 to 100 do x := 25 * a; for I := 1 to 100 do begin z := i; z := 25 * a; end; z := x + z; end;
```

- Optimizing Transformation
 - Strength reduction
 - Strength reduction optimization replaces the occurrences of a time consuming operation by an occurrence of a faster operation.
 - e.g. replacement of a multiplication by an addition.

```
for I := 1 to 10 do
begin

-----

k := i * 5;
-----

end;

itemp := 5;
for I := 1 to 10 do
begin

k := i temp

-----

itemp := itemp + 5;
end;
```

- Optimizing Transformation
 - Strength reduction
 - Strength reduction is very important for array access within program loops.
 - Strength reduction optimization is not performed on operations involving floating point operands.

- Local and global optimization
 - Optimization of a program is structured into the following two phases
 - Local optimization: this optimization are applied over small segments of a program consisting of a few statements.
 - Global optimization: this optimization are applied over a program unit i.e. over a function or procedure.

- Local optimization
 - Scope of local optimization is a basic block.
 - A basic block is a sequence of program statements (S₁, S₂,, S_n) such that only S_n can be a transfer of control statement and only S₁ can be the destination of a transfer of control statement.

Local optimization

- Local optimization identifies two basic blocks in the program
 - The first block extends up to the statement b := x * y.
 - The second basic contains the statement

$$lab_i$$
: $c := x * y$;

- Local optimization
 - Value number
 - Value numbers are used to determine if two occurrences of an expression in a basic block are equivalent.
 - The value number vn_{alpha} is associated with variable alpha
 - If statement n, the current statement being processed, is an assignment to *alpha*.

- Local optimization
 - Value number
 - A new field is added to each symbol table entry to hold the value number of a variable.
 - The IC for a basic block is a list of quadruples stored in a tabular form
 - A boolean flag save is associated with each quadruple to indicate whether its value should be saved for use elsewhere in the program.

- Local optimization
 - Value number example

Stmt no.	<u>Statement</u>
14	g := 25.2;
15	x := z + 2;
16	h := x * y + d;
••	
34	W := X * y

Symbol table

Symbol	 Value number
у	0
X	15
g	14
Z	0
d	5
W	0

- Local optimization
 - Value number example

Quadruple table

	operator	Operand 1		Operand2		Result	Use flag
		operand	Value no.	Operand	Value no.	name	
20	:=	g		25.2		t20	f
21	+	Z	0	2		t21	f
22	:=	Х	0	t21		t22	f
23	*	Х	15	у	0	t23	f t
24	+	t23		d	5	t24	f
	••						
57	:=	W	W	t23		t57	f

Global optimization

- Global optimization requires more analysis effort .
- Global common subexpression elimination: if some expression x * y occurs in a set of basic block SB of program P, its occurrence in a block b_j can eliminated if following two conditions are satisfied for ever execution of P:
 - x * y is evaluated before execution reaches block b_i and
 - The evaluated value is equivalent to value of x * y in block b_i

- Global optimization
 - Program representation: a program flow graph for a program P is a directed graph $G_P = (N, E, n_0)$

where N: set of basic block in P

E : set of directed edges (b_i, b_j) indicating the possibility of control flow from the last statement b_i to the first statement of b_i

n₀: start node of P

- Global optimization
 - Control flow analysis
 - control flow analysis analyses a program to collect information concerning its structure e.g. presence and nesting of loops in the program.

- Global optimization
 - Control flow analysis
 - The control flow concepts of interest are:
 - Predecessor and successor
 - Paths
 - Ancestors and predecessor
 - Dominators and post-dominators

- Global optimization
 - Data flow analysis

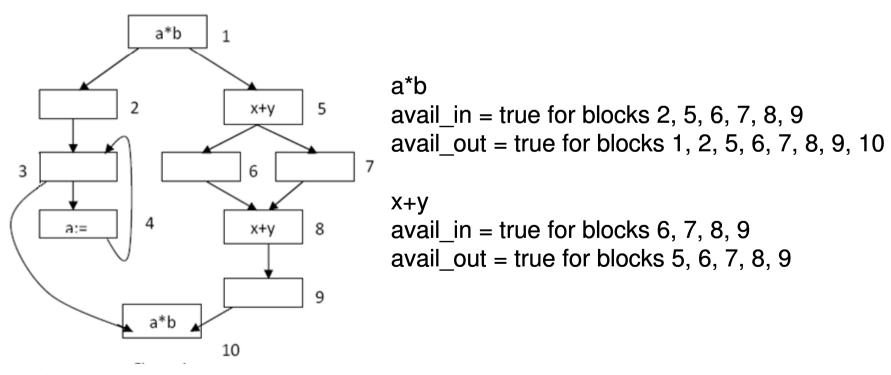
Data flow concept	Optimization in which used	
Available expression	Common subexpression elimination	
Live variable	Dead code elimination	
Reaching definition	Constants and variable propagation	

- Global optimization
 - Data flow analysis:
 - This technique analyses the use of data in a program to collect information for the purpose of optimization.
 - This information is computed at entry and exit of each basic block.

- Global optimization
 - Data flow analysis:
 - Available information: the availability of information at entry or exit of basic block b_i is computed using following rules
 - 1. Expression e is available at the exit of b_i if
 - i. b_i contains an evaluation of e which is not followed by assignment to any operands of e or
 - ii. The value of e is available at the entry to b_i and b_i does not contain assignment to any operands of e.
 - 2. Expression e is available at entry to b_i if it is available at the exit of each predecessor of b_i in program flow graph

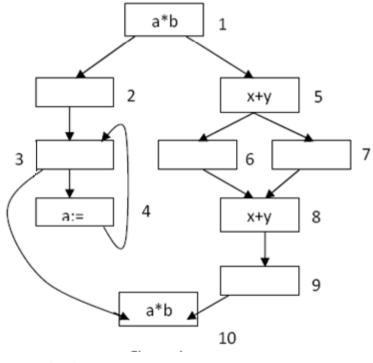
- Global optimization
 - Data flow analysis:
 - Available information
 - The boolean variables avail_in and avail_out are used to represent the availability of expression e at entry and exit of basic block b_i respectively.

- Global optimization
 - Data flow analysis:
 - Available information



- Global optimization
 - Data flow analysis:
 - Live variable: the liveness property of a variable can be determined as follows:
 - 1. Variable v is available at the entry of b_i if
 - i. b_i contains a use of e which is not preceded by assignment to v or
 - ii. v is live at the exit of b_i and b_i does not contain assignment to v.
 - 2. v is is available at exit to b_i if it is live at the entry of some successor of b_i in program flow graph

- Global optimization
 - Data flow analysis:
 - Live variable



Variable b is live at the entry of all blocks, a is live at the entry of all blocks excepting block 4 and variables x, y are live at the entry of blocks 1, 5, 6, 7 and 8.

- Interpretation avoids the overheads of compilation.
- Interpretation is expensive in terms of CPU time.
- For comparison of compilers and interpreters, consider the following notations:
 - tc : average compilation time per statement
 - te : average execution time per statement
 - ti : average interpretation time per statement

- Both compiler and interpreter analyze a source statement to determine its meaning.
- During compilation, analysis of a statement is followed by code generation and during interpretation, it is followed by actions which implements its meaning.
- tc = ti*te
- Let's assume that tc = 20 te.
- Consider a program P.
- Let size_P: number of statement in P stmts_executed_P: number of statement executed in some execution of P

Example

Let size_P = 200. For a specific set of data, let program P execute as follows:

- 20 statements are executed for initialization purpose.
- This is followed by 10 iterations of a loop containing statement followed by
- the execution of 20 statements for printing result.
- ✓ stmts_executedP = 20 + 10 * 8 + 20
 = 120
- ✓ Total execution time using the compilation model = 200.tc + 120.te $\approx 206.\text{tc}$
- ✓ Total execution time using interpretation model = 120.ti

- Use of interpreters
 - Use of interpreters are motivated by two reasons:
 - Efficiency in certain environments
 - simplicity
 - It is simpler to develop an interpreter than to develop a compiler.
 - Interpreter is used in situations where programs or commands are not executed repeatedly.

- Overview of Interpretation
 - Interpretation schematic implements the meaning of a statement without generating code for it.
 - The interpreter consist of three main components:
 - **Symbol table**: holds information concerning entities in the source program.
 - Data Store: contains values of the data items declared in the program being interpreted. It consist of a set of component {comp_i}
 - **Data Manipulation routines**: A set of data manipulation routines contains a routine for every legal data manipulation action in the source language

- Overview of Interpretation
 - Example: the meaning of the statement a:= b + c where a, b, c are of the same type can be implemented by executing the calls

```
add(b, c, result) assign(a, result)
```

- Overview of Interpretation
 - Advantages
 - The meaning of the source statement is implemented through execution of the interpreter routine rather than through code generation.
 - Avoiding generation of machine language instruction helps to make the interpreter portable.

- Toy Interpreter
 - Design and operation of an interpreter for Basic written in Pascal.
 - The data store of interpreter consist of two large array
 - rvar to store real
 - ivar to store integer
 - Last few locations in the rvar and ivar arrays are used as stacks for expression evaluation with the help of the pointers r_tos and i_tos respectively.

- Toy Interpreter
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Basic Interpreter written in Pascal

```
program interpreter (source, output)
   type
        symentry = record
                symbol: array [1..10] of character;
                type: character;
                address: integer;
        end
   var
        symtab: array [1..100] of symentry;
        rvar: array [1..100] of real;
        ivar: array [1..100] of integer;
        r tos = 1..100;
        i tos = 1..100;
```

Basic Interpreter written in Pascal

```
procedure assignint (addr1 : integer; value : integer);
     begin
             ivar [addr1] := value;
     end;
procedure add( sym1, sym2 : symentry)
     begin
             if( sym1.type = 'real' and sym2.type = 'integer') then
                      addrealint (sym1.address, sym2.address);
              . . . .
     end
```

Basic Interpreter written in Pascal

Example

Consider the Basic program

real a, b

integer c

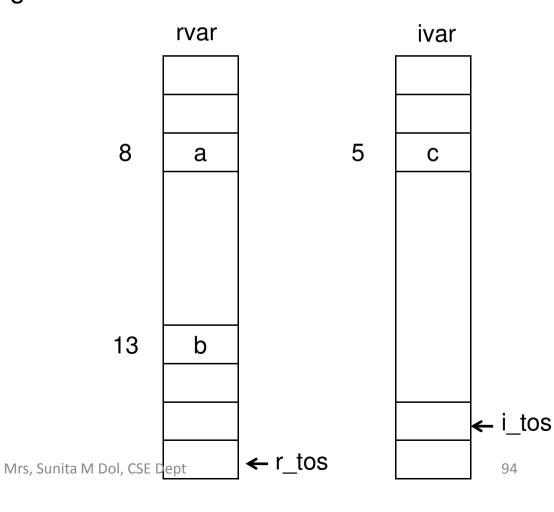
let c = 7

let b = 1.2

a = b + c

Symbol	Type	Address
а	real	8
b	real	13
С	int	5

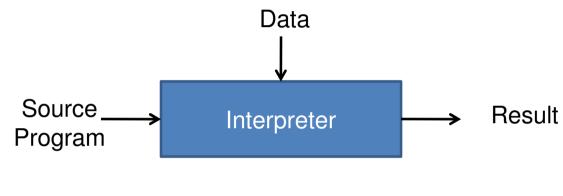
Symbol Table



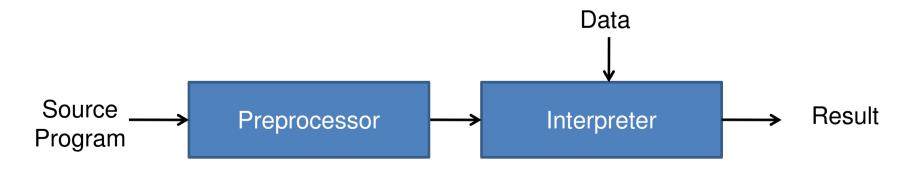
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Pure and Impure Interpreters



Pure Interpreter



- Pure and Impure Interpreters
 - Impure Interpreter
 - It performs some preliminary processing of the source program to reduce analysis overhead during interpretation.
 - The preprocessor converts the program to an intermediate representation (i.e. intermediate code IC).
 - IC can be analyzed more efficiently than the source form of the program
 - E.g. intermediate code for a + b * c using postfix notation look like the following

