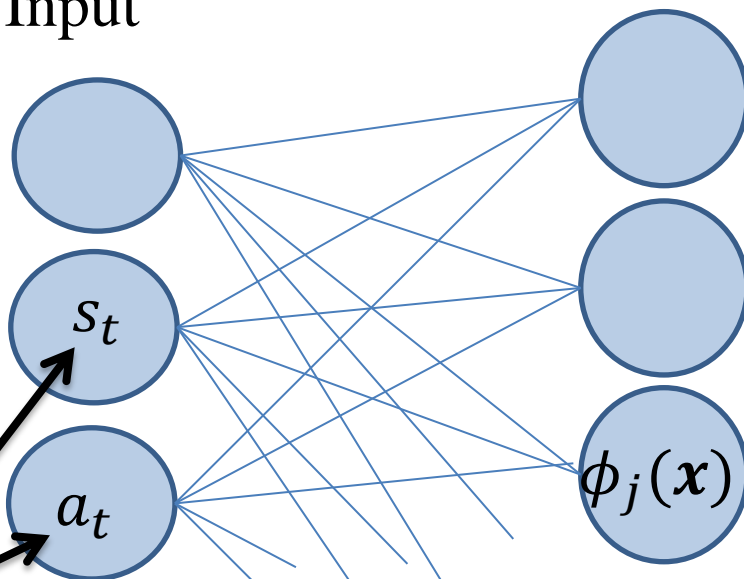
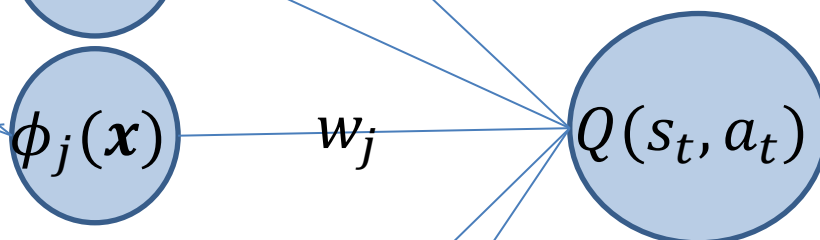


Radial Basis Function $\phi_j(\mathbf{x})$

Input



Output



State s_t Action a_t

Action-Value
Function Q