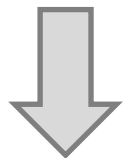
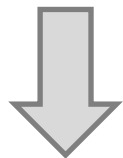


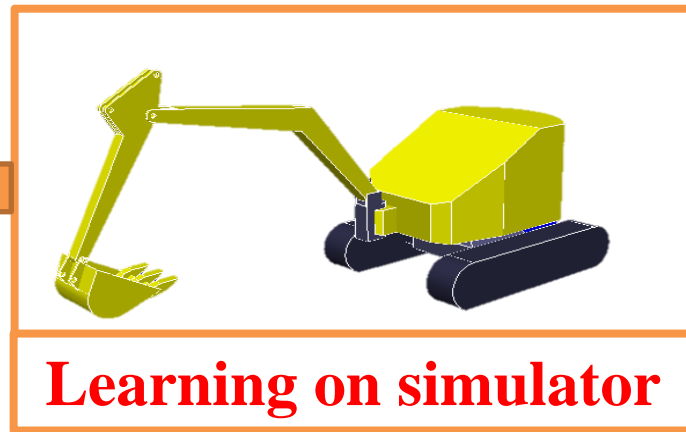
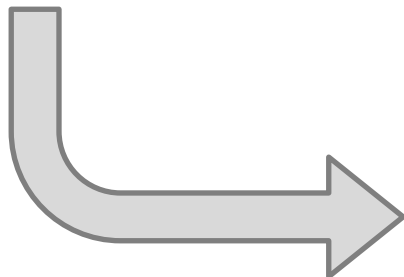
Robot in failure



Detect the failure



Start recovery motion



Learned recovery motion

②

Input state

③

Output recovery motion



① Controller input { Straight
Turn

