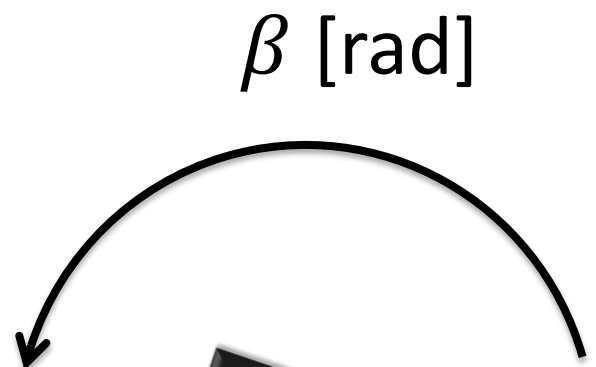
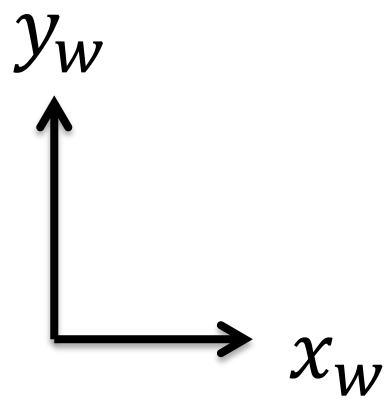
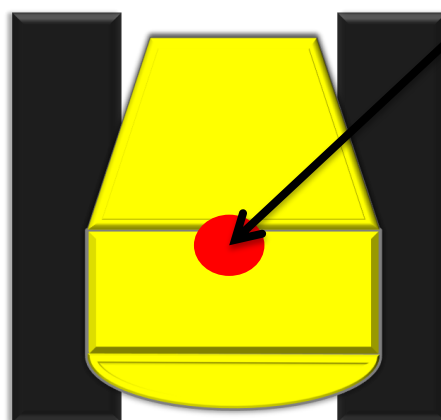


Top view



$t = 0$   
 $(x_0, y_0)$



Robot

$d_4$

$t = T$   
 $(x_T, y_T)$

