

6-Axis **F/T**Sensor

Benefits:

- Multi axis force measurement
- High resolution
- Highly adaptable product design
- Dust and water proof (IP65)
- High overload range
- Mechanical shock resistant
- Cost efficient solution
- Easy integration

10

HEX-70-XE-1000N

Description:

OptoForce 6 axis F/T sensors provide 6 degrees of freedom force and torque measurement. Our sensors are designed to fit most of the currently used industrial robot arms. Integration with the various available interfaces is simple. Common applications are **force control** devices, **teach in activities**, and **crash detection**, but the sensors can be used next to **end effectors** in case of **grinding**, **polishing** or **deburring** tools. High durability and an unlimited number of custom opportunities resemble all of our sensor types.

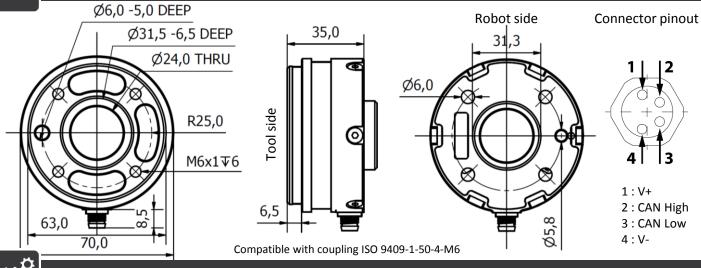
We offer these sensors mostly for **system integrator** companies, **robot arm manufacturers** and **contract manufacturing** companies.

	Nominal Capacity	Deformation (Deflection)		
Fxy	± 200 N	± 1.7 mm		
Fz – compression	1000 N	1 mm		
Fz – tension	450 N	0.7 mm		
Тху	± 10 Nm	(± 2 °)		
Tz	± 6.5 Nm	(± 5 °)		

Accuracy	3% FS

CAD DR

DRAWINGS HEX-70-XE



SPECIFICATIONS

Sensor Type	6 Axis Force Sensor				
Dimensions	Height x diameter			35 x 70 mm	
Weight	(With built-in adapter plates)			200g	
	Fz Compression	Fz Tension	Fxy	Тху	Tz
Nominal Capacity (N.C)	1000 N	450 N	200 N	10 Nm	6.5 Nm
Single axis overload	200 %	200 %	200 %	200 %	200 %
Full scale nonlinearity	2 %	2 %	2 %	2 %	2 %
Resolution (typical)	125 mN	125 mN	± 22.22 mN	± 1 mNm	± 0.65 mNm
Single axis deformation at N.C	1 mm	0.7 mm	± 1.7 mm	± 2.5 °	±5°
Crosstalk (typical)	< 5 %		 		
Hysteresis (measured on Fz axis , typical)	< 2 %				
Working temperature range			-40 °C - +80 °C		
Temperature compensation	All axes		-10 °C - +40 °C		
Power requirement	DC input range 7-48V			0.8 W	
Robot mounting screw	4 x M6 x 8 mm		DIN7984-A20-0130		
Sensor mounting screw	6 x M4 x 8 mm			DIN7984-A20-050	



INTERFACE TYPES



USB	CAN	Ethernet - UDP	Ethernet - TCP			
Maximum sampling frequency 1000 Hz						
Supported systems Windows; Linux; ROS; UR						