


# Oswin Rodrigues

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## TOOLS

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- C · C++ · Python · Ladder Logic · JavaScript · MATLAB · Assembly · VHDL
- Circuit Design · Arduino · Soldering Iron · Upverter · EAGLE · Oscilloscope · Multimeter

## EDUCATION

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**Mechatronics Engineering, Honors**, Candidate for BSc 2013 – Present  
University of Waterloo, Waterloo, ON Class of 2018

## EXPERIENCE

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**EDA/CAD Engineer Intern** May – Aug 2015  
**Upverter Inc.** Toronto, ON

*Enhancing PCB CAD tool features in software (JavaScript, Python) and hardware avenues.*

- Created and verified symbols and footprints for 150+ electronic components.
- Implemented component-tagging feature, using pin names to deduce functionality.
- Adjusted prioritization of design rules in layout constraint manager.
- Fixed incorrect drawing and positioning of constraint violation layout bodies.
- Refactored click event-listening logic in schematic net-drawing tool.
- Corrected book-keeping errors in pin manager for tracking connection mappings.
- Facilitated BGA footprint generator's omitting specific letters during row enumeration.

**Neuro-Robotics Lab Research Assistant** Feb – Apr 2014  
**University of Waterloo** Waterloo, ON

*Using ROS-run Turtlebot for social navigation research purposes.*

- Wrote C++ and Python nodes to implement basic navigation stack on Turtlebot.
- Published sensor, odometry and transform messages to mobile base.
- Tweaked existing open-source code for advanced algorithms: person-detection, SLAM navigation.

**Mechanical Design Co-op** Sep – Dec 2014  
**Prodomax Automation Inc.** Barrie, ON

*Designing jigs and fixtures in Solidworks for automotive part-assembly stations.*

- Modeled custom tooling in two stations for assembling a vehicle's seat track mechanism.
- One station inserted an anti-collapse spacer and the other stamp-pressed a bushing.
- Detailed and ballooned numerous part and assembly drawings extensively.

## PROJECTS

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**UW Robotics Team & WAVE<sup>1</sup> Lab** Jan – Apr 2015, Sep 2015 – Present

<sup>1</sup> *Waterloo Autonomous Vehicles*

- Modified EAGLE schematics and layouts for Arduino motor shield.
- Soldered different SMT and THT components onto multiple bare shields.
- Currently designing and implementing a wireless (RF) e-stop mechanism for racing robot.
- Currently revamping and parts-sourcing a Mars Rover's electrical box.

## Tilt-Sensitive LED Matrix Panel

Personal Project, Ongoing

*'Moving' a single lit LED on the panel by physically tilting it. This uses:*

- Arduino microcontroller for handling the 'smarts and magic'.
- ADXL335 accelerometer for controlling the tilt functionality.
- 74HC595N shift register (SIPO) for I/O expansion on the Arduino board.

## Hackathons

Various

- Pebble-facilitated dosage notification service - *SmartMeds*; used C. Hack the North, 2015
- IMU-based instructor - *Yoga Yoda*; developed business case. PCH Hardware Hackathon, 2015
- Myo-controlled air drum kit - *DruMyo*; used C++. hackWaterloo, 2014
- Myo-enabled Solidworks controller; used Lua. Hack the North, 2014

## COURSES

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|---|-----|
| • Circuits                                | 93% |
| • Sensors & Instrumentation               | —   |
| • Data Structures & Algorithms            | 94% |
| • Microprocessors & Digital Logic         | 78% |
| • Computer Structures & Real-Time Systems | —   |

## NON-TECHNICAL

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- East Coast Swing
  - Guitar & Drums
  - Rap & Poetry
  - Basketball
  - Outdoors (Camping, Discovery Walks, etc.)