# Oswin Rodrigues

### Mechatronics Engineering, 3rd Year

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#### **P** Goals

- To excel and grow in the design and development of hardware and embedded software systems.
- To meaningfully contribute to teams with high-quality engineering poured towards real-world problems.

### F Tools

- Schematics & Layouts · Soldering & Rework · Multimeter & Oscilloscope · Arduino & Raspberry Pi
- $C \cdot C++\cdot Python \cdot MATLAB \cdot FPGA Programming \cdot Ladder Logic \cdot ROS \cdot JavaScript$

# **4** </>

#### **EXPERIENCE**

#### **Mechatronics Engineer**

Fall 2016 (Present)

KitchenMate Inc.

Toronto, ON

(In progress). Building components of electrical, software and mechanical sub-systems.

- Detecting stall on DC motors with current sensors or speed encoders.
- Sensing heat modes on cooker PCB with opto-isolator and ADC.

#### AI & Robotics Engineer

Winter 2016

#### Stealth-mode AI & Robotics Startup

Toronto, ON

Robot-wrangling with Python over distributed communication architecture.

- Sourced, tested and integrated components into system via custom-coded drivers.
- Soldered robots' power boards and executed safety bringup.

#### EDA & CAD Engineer

Summer 2015

#### Upverter Inc.

Toronto, ON

Enhancing PCB CAD features in hardware and software avenues.

- Created and verified symbols and footprints for 150+ electronic components.
- Used JavaScript to re-factor features and fire-fight bugs extensively.

#### Junior Mechanical Designer

Fall 2014

#### Prodomax Automation Inc.

Barrie, ON

CAD-ing custom jigs and fixtures in Solidworks for automotive part-assembly stations.

#### Neuro-Robotics Lab Research Assistant

Winter 2014

#### University of Waterloo

Waterloo, ON

Implementing C++ and  $Python\ nodes\ on\ ROS$ -run  $Turtlebot\ for\ navigation\ research.$ 

#### **A** Projects

#### UW Robotics Team & Waterloo Autonomous Vehicles Lab

Various

- Verified and modified EAGLE schematics and layouts for Arduino motor shield.
- Soldered SMT and THT components onto three bare PCBs and probed subsequently.

#### Tilt-Sensitive LED Matrix Panel

Winter 2016

- Wrote LED driver that uses two 74HC595N shift registers for I/O expansion.
- Wrote IMU driver for ADXL335 and MPU6050, with filter to integrate gyro and accelerometer.

## **E**DUCATION

#### **₽** Courses

$\mathbf{M}$	echa	tron	i	cs	Eng	inee	ring,	$\mathbf{H}$	onors,	BASc.
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University of Waterloo, Waterloo, ON Class of 2018

Microprocessor Systems & Interfacing	95%
Sensors & Instrumentation	80%

Circuits 93%