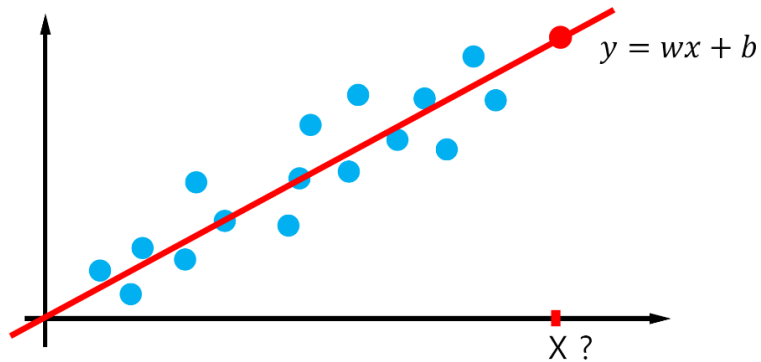


# NeuralNet 101

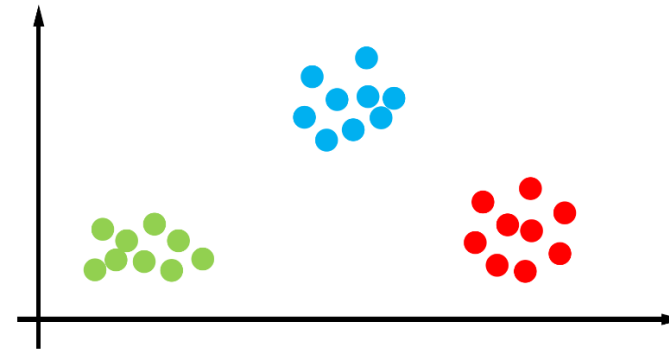
## 6. CNN

# We have a problem.. (again)

Linear Function



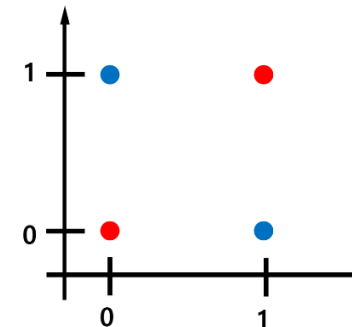
We have a problem..



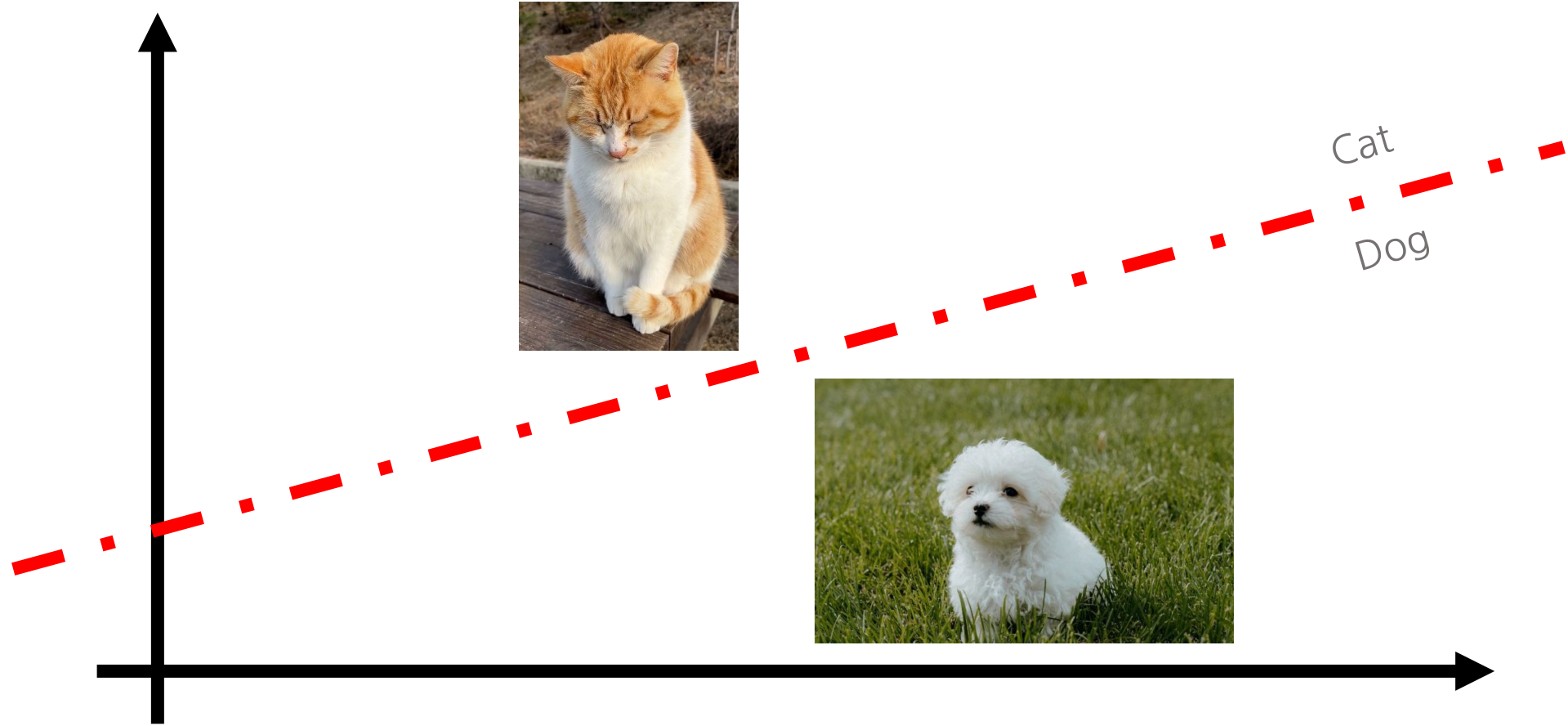
We have a problem..



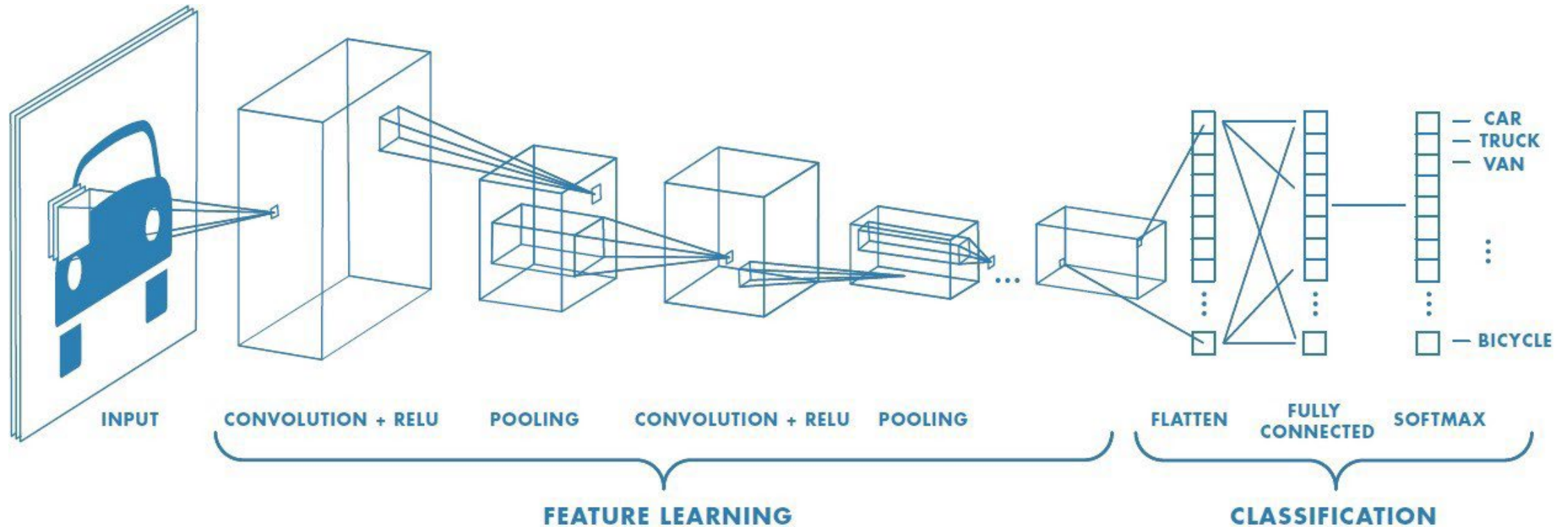
We have a problem..



# How to train for image data?



# CNN (step-by-step)



# Convolution

Stride(step) ->

1	2	3	0	1
0	1	5	1	0
1	0	2	2	1
1	1	2	0	0
1	0	1	1	1

input

1	0	1
0	1	0
1	0	1

filter

8	9	8
8	5	9
6	5	5

output

# Convolution Filter (Kernel)

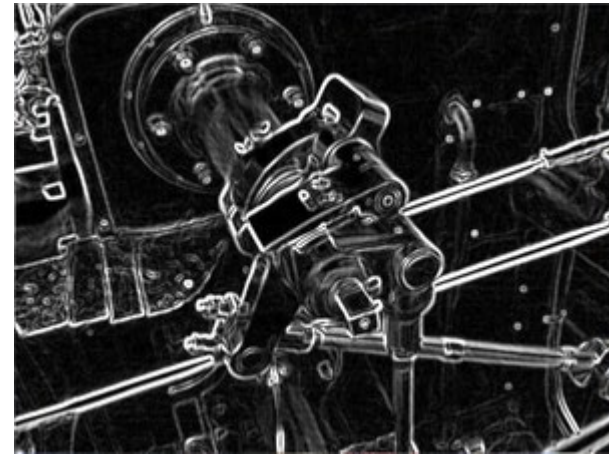
ex) Sobel X/Y: Edge Filter

-1	0	+1
-2	0	+2
-1	0	+1

x filter

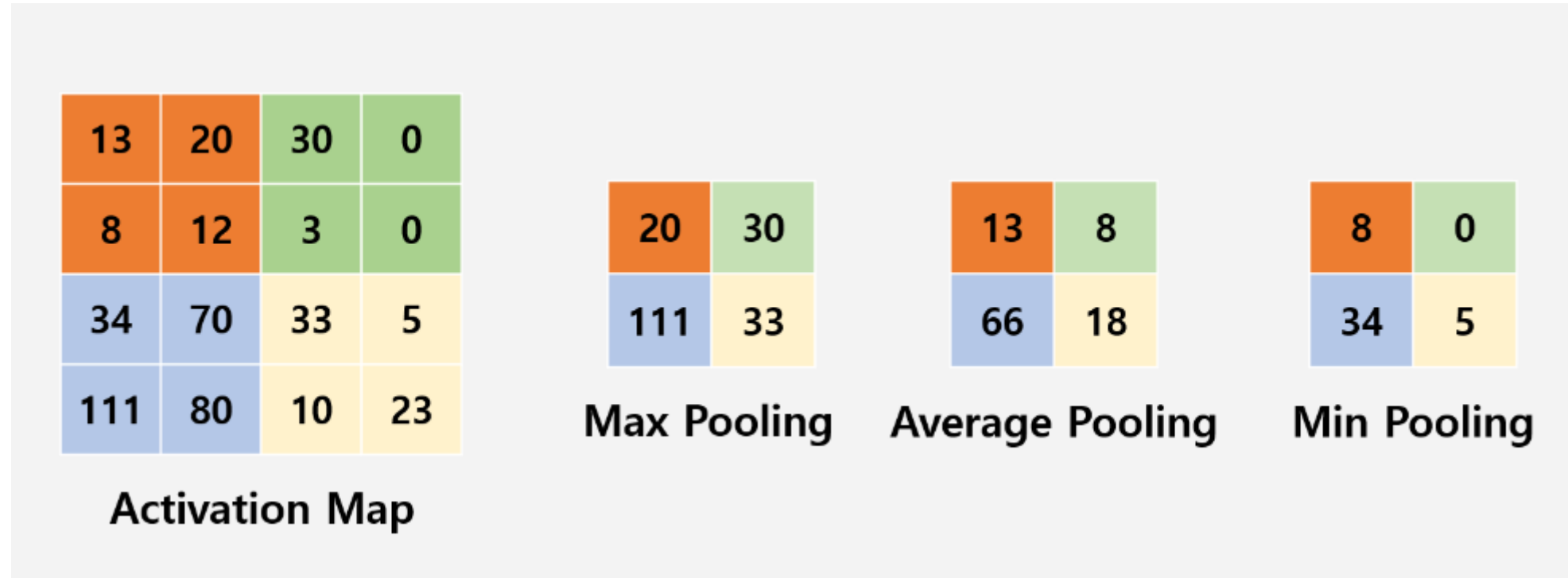
+1	+2	+1
0	0	0
-1	-2	-1

y filter



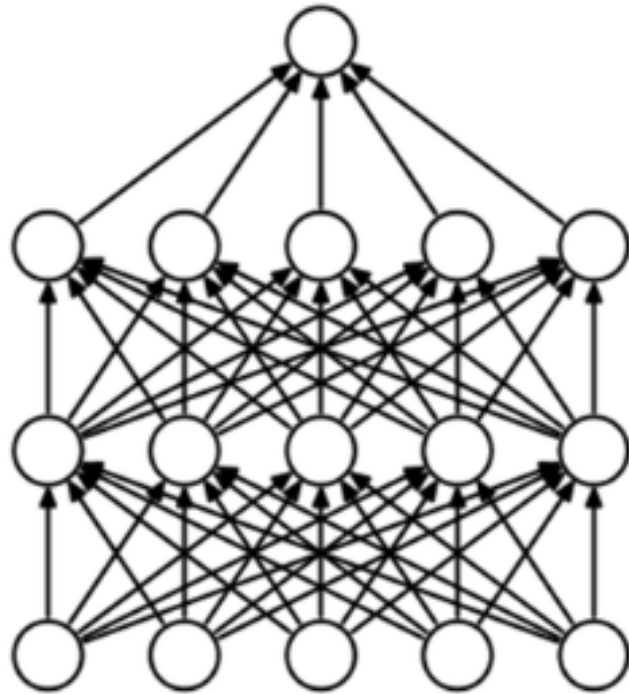
Appropriate filters automatically trained in CNN,  
to extract **feature**

# Pooling (sub sampling)

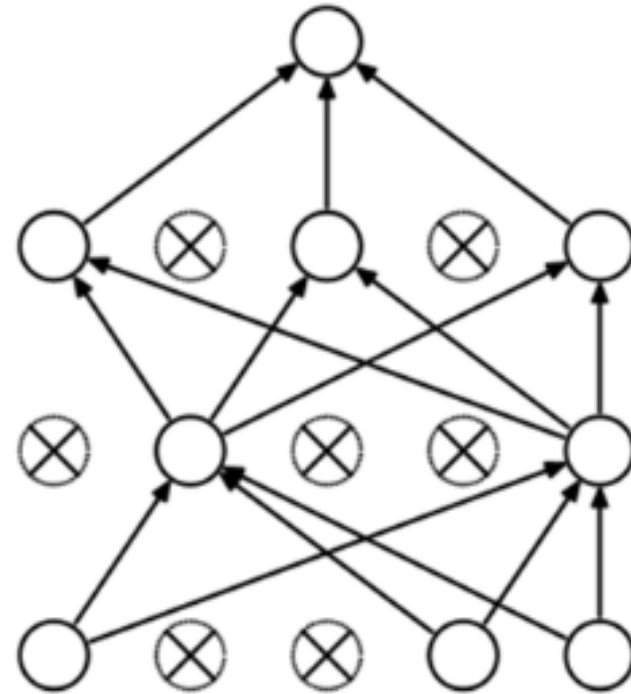


**Reduce** data size for less calculation and less overfitting

# Dropout



(a) Standard Neural Net

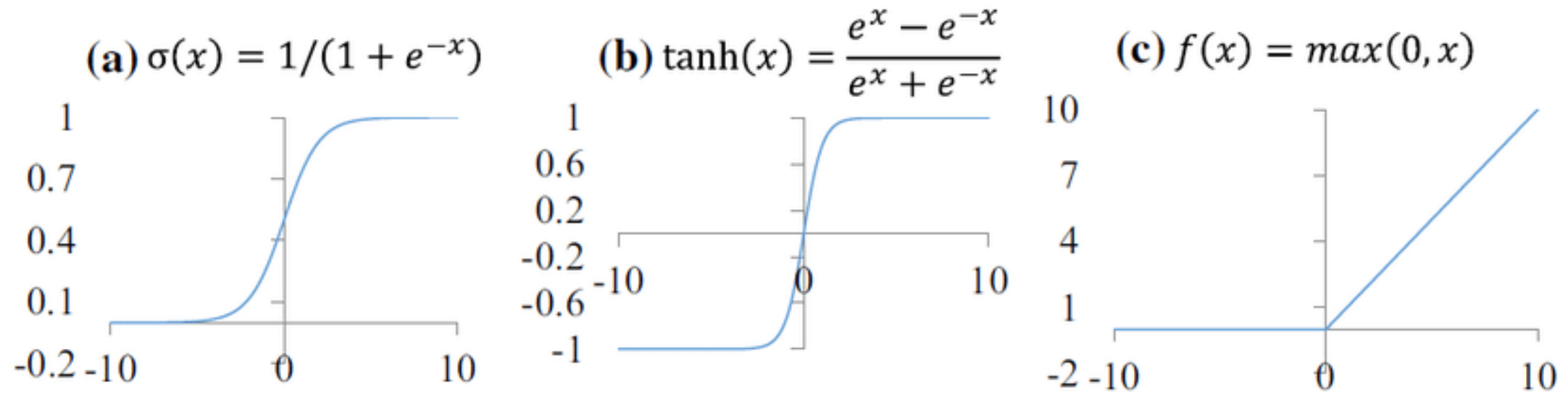


(b) After applying dropout.

Random dropout prevents overfitting and co-adaptation  
-> better feature!



# Activation Function

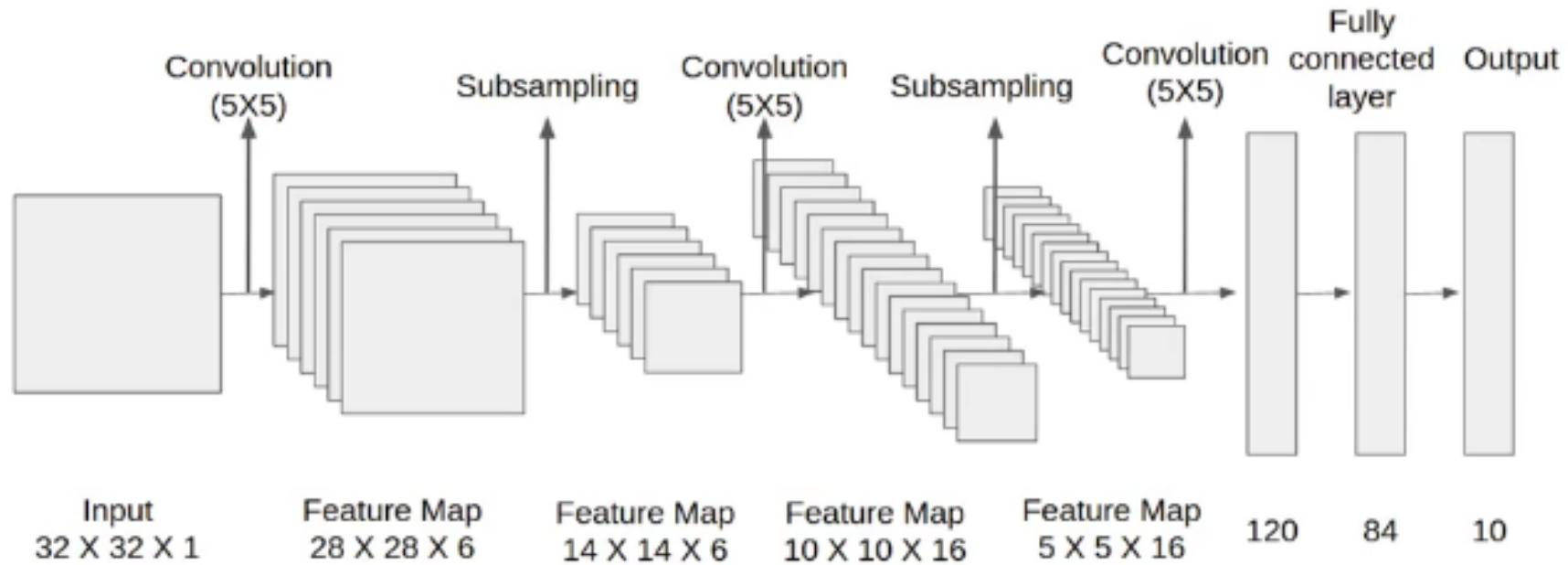


tanh: better slope, back-prop direction not biased  
ReLU: faster training, no saturation for extreme values

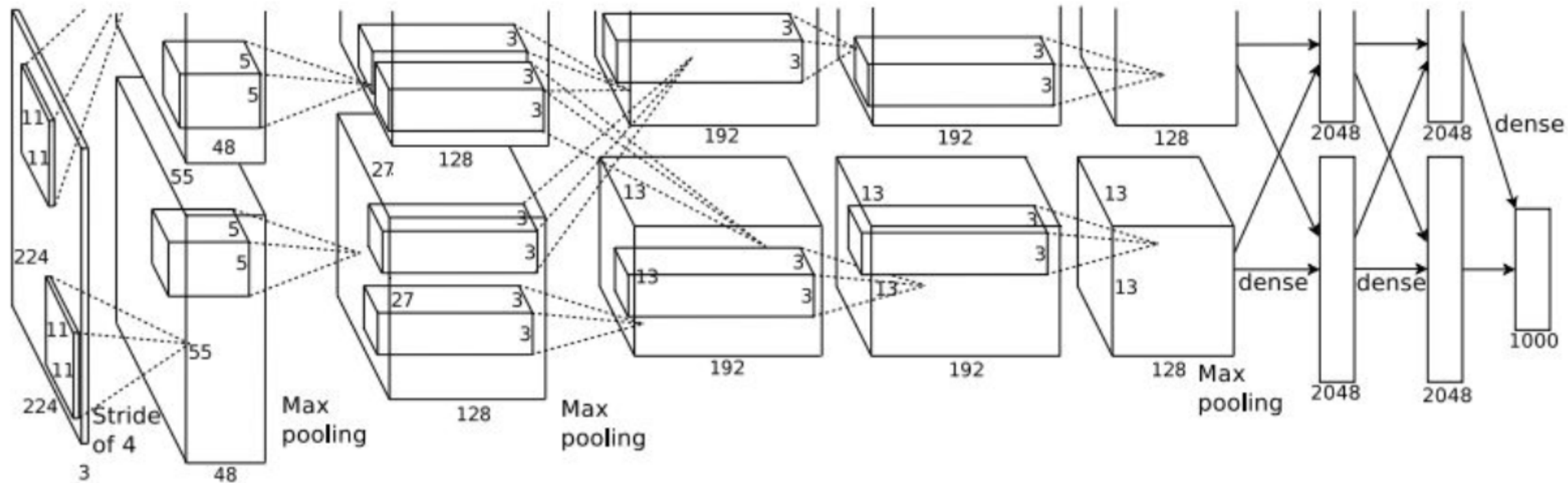
# CNN Architecture Overview

LeNet -> AlexNet/ZFNet ->  
VGG/GoogLeNet -> ResNet -> ...

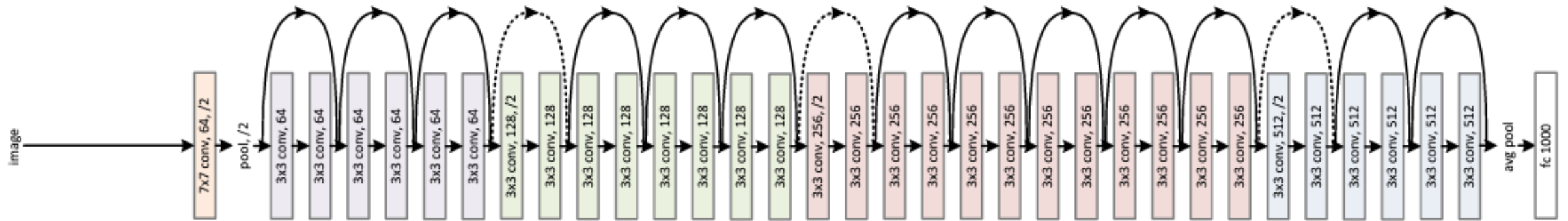
# LeNet-5



# AlexNet



# ResNet



skip connection:  
residual mapping  
-> deep layer performance!

