# Neural Machine Translation

Knowledge and Language Engineering Lab 이 원 기 (wklee@postech.ac.kr)



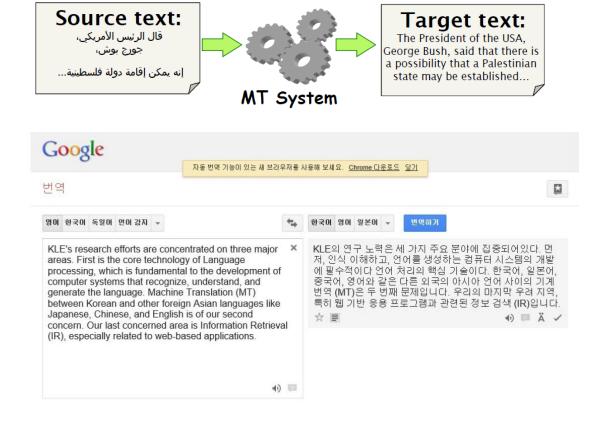
#### Goal

- 신경망 기계번역 모델에 대한 이해 및 구현
  - RNN 기반의 Sequence-to-Sequence 모델
  - Attention 메커니즘
- Torchtext
  - 효율적인 텍스트 데이터 (전) 처리를 위한 라이브러리

# NEURAL MACHINE TRANSLATION

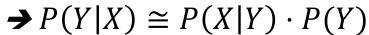
#### 기계 번역

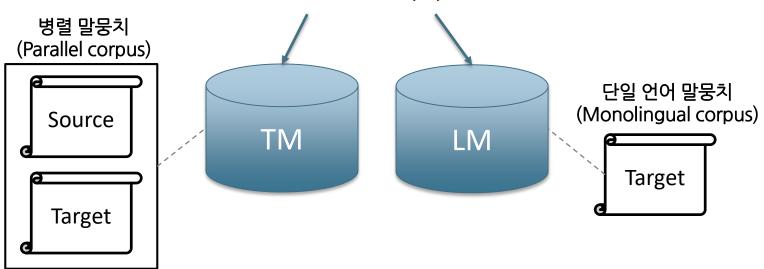
- 기계번역이란?
  - 원시문 (Source text) 를 다른 언어로 된 대상문장 (Target text)
     로 자동 번역하는 기술



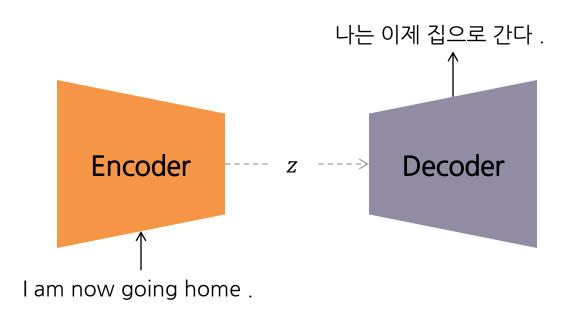
#### 기존의 방법론

- 통계 기반 기계 번역 (Statistical Machine Translation: SMT)
  - 원시문과 대상문에 대한 확률식 정의
    - 원시문(ex. 영어) :  $X = \{x_1, x_2, ..., x_n\}$
    - 대상문(ex. 한국어):  $Y = \{y_1, y_2, ..., y_n\}$





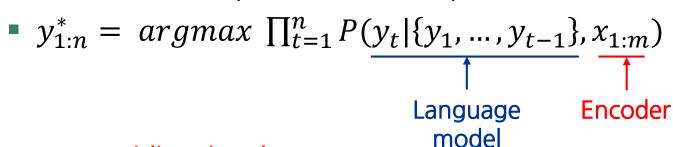
- Sequence-to-Sequence 모델
  - Encoder
    - : 무작위 길이의 Source 문장을 고정된 길이의 Vector로 변환
  - Decoder
    - : Encoder 의 Vector 정보와 입력(Input) 를 이용하여 가변 길이의 문장 생성



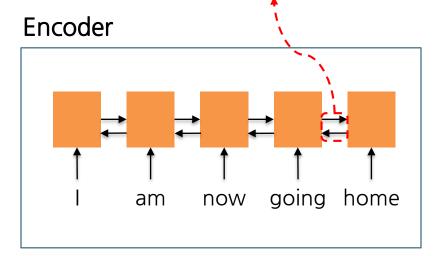
#### ■ 문제 정의

```
 y_{1:n}^* = argmax P(y_{1:n}|x_{1:m}) 
= argmax P(y_1|x_{1:m}) \cdot P(y_2|y_1, x_{1:m}) \cdot P(y_3|y_2, y_1, x_{1:m}) \cdots P(y_n|y_{1:n-1}, x_{1:m}) 
= argmax \prod_{t=1}^n P(y_t|\{y_1, \dots, y_{t-1}\}, x_{1:m})
```

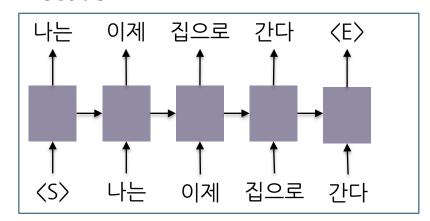
RNN 기반의 Sequence-to-Sequence 모델







#### Decoder

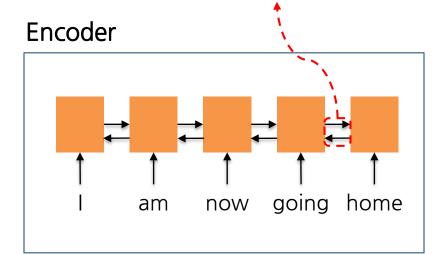


RNN 기반의 Sequence-to-Sequence 모델

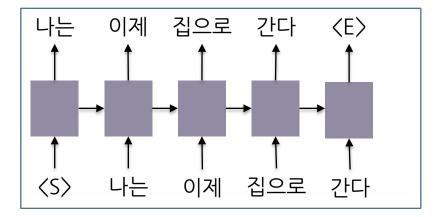
• 
$$y_{1:n}^* = argmax \prod_{t=1}^n P(y_t | \{y_1, ..., y_{t-1}\}, x_{1:m})$$

Conditional Language model

#### **Bidirectional RNN**

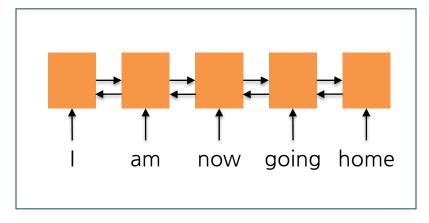


#### Decoder

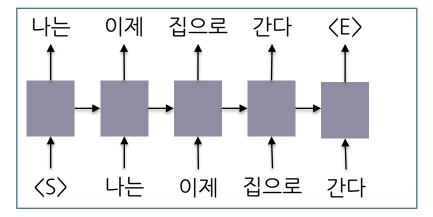


- RNN 기반의 Sequence-to-Sequence 모델
  - Encoder로 부터 입력열에 대한 고정 길이 벡터 생성 방법 ?

#### Encoder

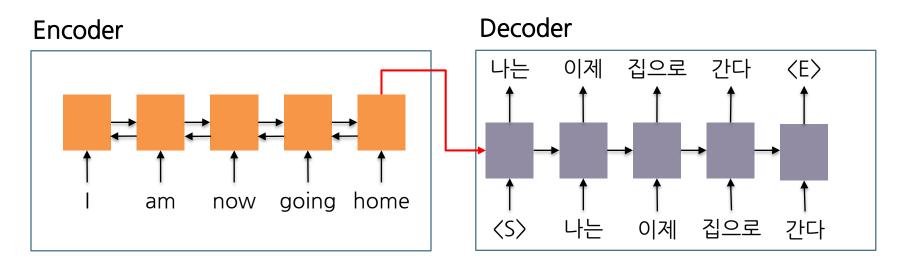


#### Decoder

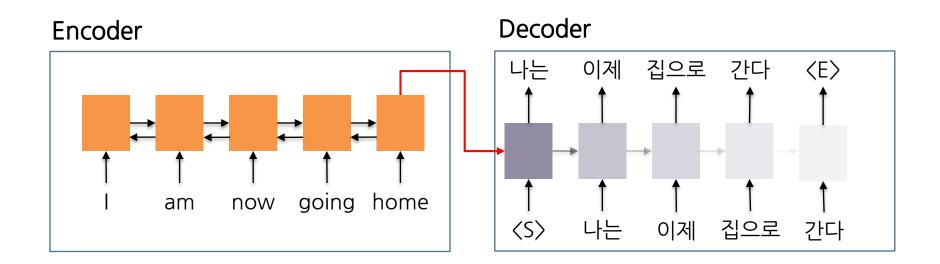


- RNN 기반의 Sequence-to-Sequence 모델
  - Encoder로 부터 입력열에 대한 고정 길이 벡터 생성 방법 ?
  - 가장 쉬운 방법
    - Encoder의 마지막 Hidden으로 Decoder의 Hidden을 초기화

$$h_t^{Enc} = f(x_1, x_2, \dots, x_n)$$



- 장기 의존성 학습 어려움: Long-term dependency
  - Decoder의 time-step이 증가할 수록 Encoder의 정보 전달이 약해짐.
    - → Encoder의 정보 활용이 부족.



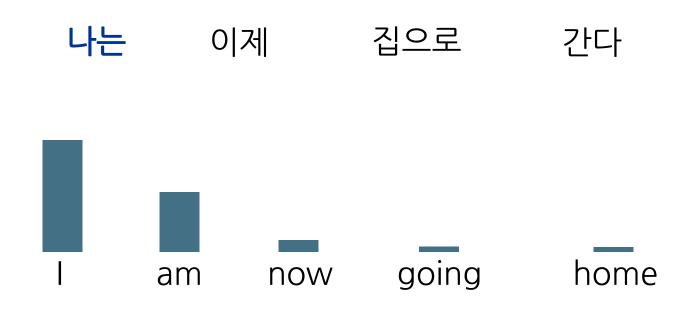
#### 신경망 기계번역

- Attention
  - Concept  $y_t$ 를 번역(생성) 할 때 Encoder의 전체 입력열을 중요도에 따른 비율로 참조하는 것.
  - 중요도 (가중치) 에 따라 Encoder의 전체 입력열을 **압축된 Vector**로 변환 (a.k.a. 'Context vector')

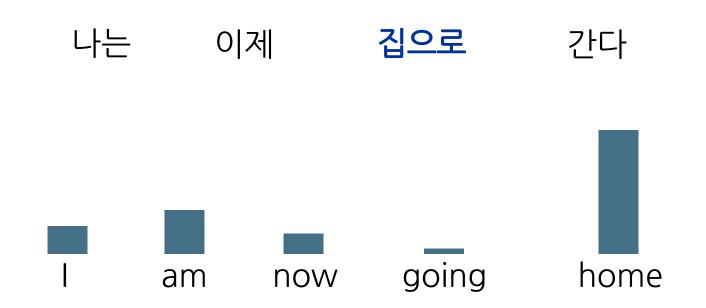
Concept

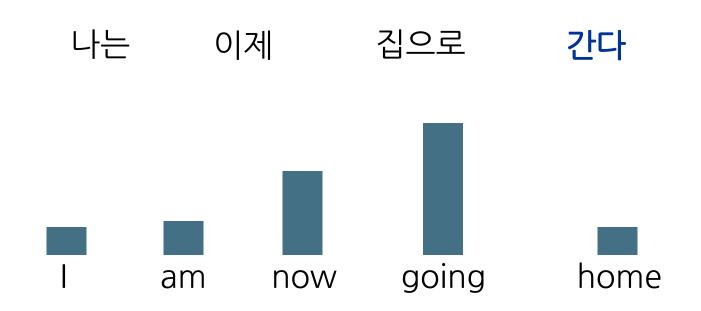
나는 이제 집으로 간다

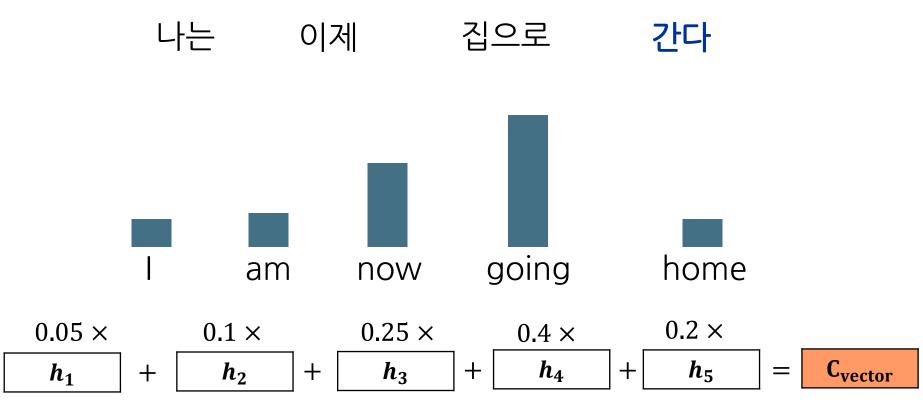
I am now going home











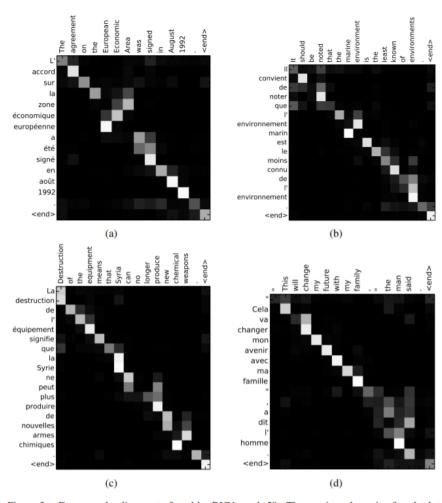
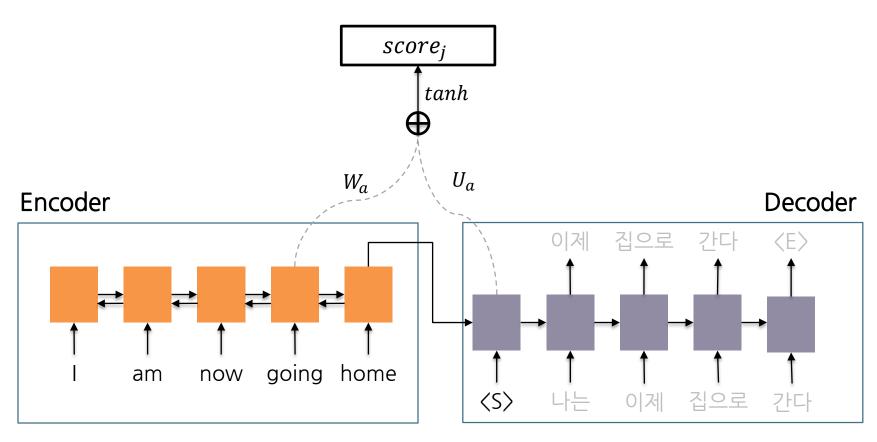


Figure 3: Four sample alignments found by RNNsearch-50. The x-axis and y-axis of each plot correspond to the words in the source sentence (English) and the generated translation (French), respectively. Each pixel shows the weight  $\alpha_{ij}$  of the annotation of the j-th source word for the i-th target word (see Eq. (6)), in grayscale (0: black, 1: white). (a) an arbitrary sentence. (b–d) three randomly selected samples among the sentences without any unknown words and of length between 10 and 20 words from the test set.

Bahdanau, Dzmitry, Kyunghyun Cho, and Yoshua Bengio.

"Neural machine translation by jointly learning to align and translate."

- In practice: MLP approach
  - $\operatorname{score}(h_i^{Enc}, h_t^{Dec}) = v_a^T \tanh(W_a h_j^{Enc} + U_a h_t^{Dec}) \rightarrow \operatorname{scalar}$



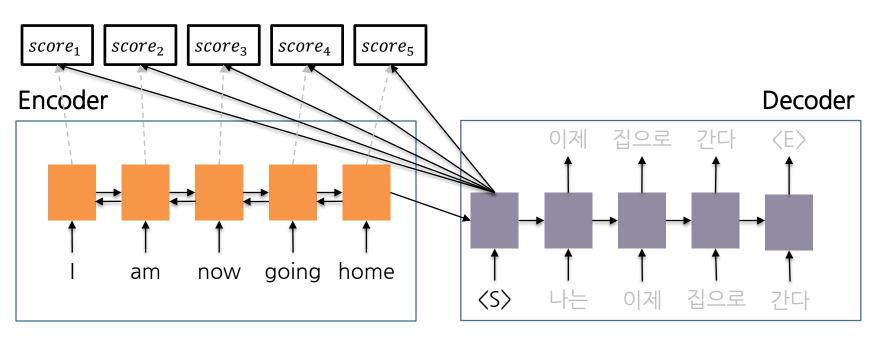
- In practice: MLP approach
  - $\operatorname{score}(h_i^{Enc}, h_t^{Dec}) = v_a^T \tanh(W_a h_i^{Enc} + U_a h_t^{Dec})$

0.2

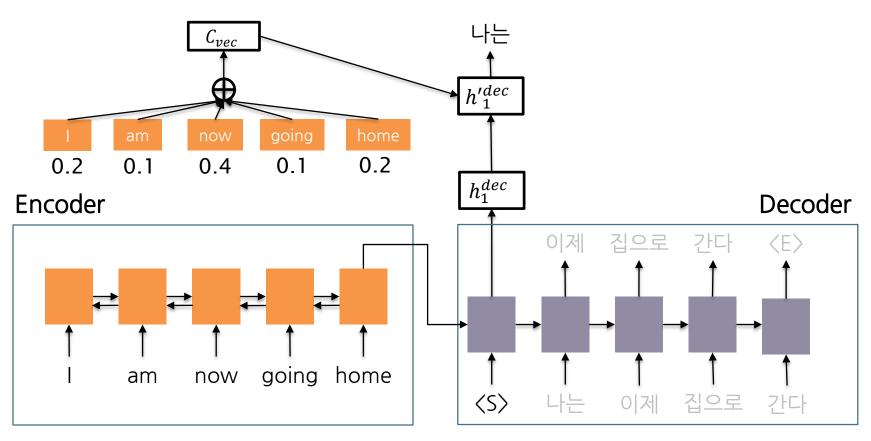
0.1 0.4 0.1

0.2

#### Softmax



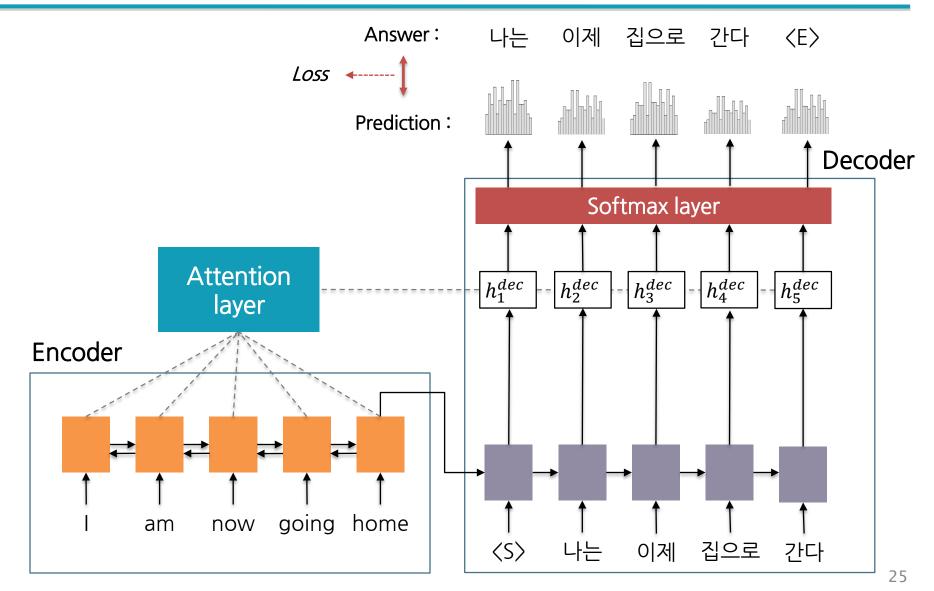
- In practice: MLP approach
  - $C_{vec} = \sum_{j=1}^{|x|} a_j \cdot h_j^{Enc}$



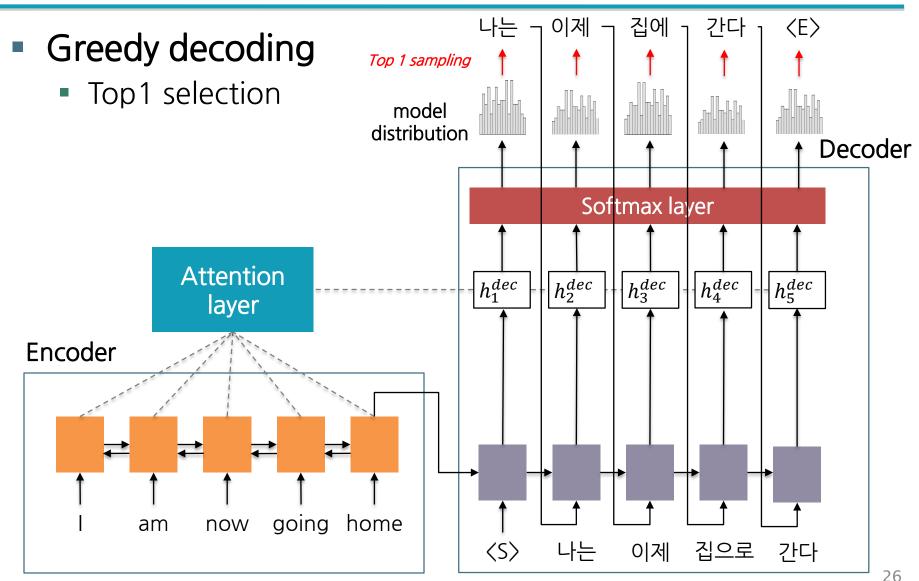
# 신경망 기계번역: Training

- Output probability:
  - $P(y_t|\{y_1,...,y_{t-1}\},x_{1:m}) \cong g(y_{t-1},h_t^{dec},c_t)$ 
    - where
      - $y_{t-1}$  = Current input (t-1) for the decoder
      - $h_t^{dec}$  = Hidden stage for time=t
      - $c_t$  = Context vector for time=t
      - g = Nonlinear function representing the decoder
- Training objective:
  - $\mathcal{L}(y) = -\frac{1}{T}\sum_{i=1}^{T} P(y_i) \log(P(\hat{y}_i))$ 
    - where
      - $y_i$  = true distribution &  $\hat{y}_i$  = model distribution

# 신경망 기계번역: Training

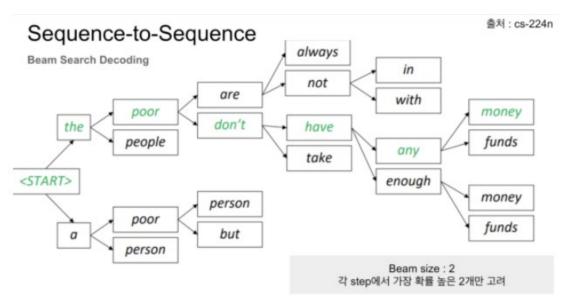


# 신경망 기계번역: Decoding (Inference)



# 신경망 기계번역: Decoding (Inference)

- Beam search decoding
  - 각 time step 에서 가장 좋은 결과만을 선택 ≠ 최적의 문장열 (=Greedy decoding)
  - 각 time step 에서 모든 출력 시퀸스 검색
     (Dynamic programming): Time complexity 로 인해 불가능
  - → Beam search: 탐색 영역을 각 time step 에서 top N (=beam size) 개로 제한하는 것.



# PRACTICE: NMT 모델 구현하기

## Requirement

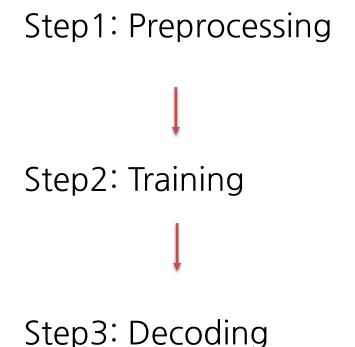
- pip install torchtext
- pip install mosestokenizer
- pip install torch

# PRACTICE#2: OPEN SOURCE TOOLKIT

#### Useful tools

- Fairseq (Pytorch): <a href="https://github.com/pytorch/fairseq">https://github.com/pytorch/fairseq</a>
- OpenNMT-py (Pytorch): <a href="https://github.com/OpenNMT/OpenNMT-py">https://github.com/OpenNMT/OpenNMT-py</a>
- HuggingFaice (Pytorch): https://github.com/huggingface/transformers
- Tensor2Tensor (Tensorflow): https://github.com/tensorflow/tensor2tensor

 Simple tutorial to training your own model with Fairseq.



clone repository

```
git clone <a href="https://github.com/pytorch/fairseq">https://github.com/pytorch/fairseq</a>
```

install fairseq

```
cd fairseq
pip install -e ./
```

Step1: Preprocessing

```
#!/bin/bash

dataPath=./dataSplit
fairseq-preprocess \
    --source-lang en --target-lang fr \
    --tokenizer moses \
    --trainpref $dataPath/train \
    --validpref $dataPath/dev \
    --destdir data-bin/tutorial-NMT
```

- source-lang: source 파일의 확장자 부분
- trainpref: train 데이터 파일의 확장자를 제외한 부분
- destdir: binary 파일이 저장될 디렉토리 경로 (없는 경우 생성)

(https://fairseg.readthedocs.io/en/latest/command\_line\_tools.html#fairseg-preprocess)

Step2: Training

```
#!/bin/bash
export CUDA_VISIBLE_DEVICES=0

savePath=./checkpoints/tutorial-NMT
binPath=./data-bin/tutorial-NMT
fairseq-train $binPath \
    --save-dir $savePath --keep-best-checkpoints 1 --max-epoch 20 \
    --no-progress-bar --lr 0.0005 --optimizer adam --clip-norm 0.1 \
    --dropout 0.1 --max-tokens 3000 --arch lstm \
    --encoder-embed-dim 128 --encoder-bidirectional \
    --decoder-embed-dim 128 --decoder-attention True
```

Step3: Decoding

```
> fairseq-interactive \
    ./data-bin/tutorial-NMT \
    --path ./checkpoints/tutorial/checkpoint_best.pt \
    --beam 5 --source-lang en --target-lang fr --tokenizer moses
```