
AUTOMATION TEAM RESEARCH REVIEW

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Abstract

The automation team has already made the majority of the decisions it needs to make through research and some experimentation. This is a summary of progress, research, and decisions made... annd.. i'll fill this in as i get to it.



1 Introduction

Sustainability comes in many forms, some easier than others. In most instances, people want to be sustainable, they just also don't want to be inconvenienced. It is the automation team's goal to provide sustainability in a feasible fashion by providing it "cloaked" in convenience through HyveOS.

HyveOS is a software that implements a platform to receive and send data from a house. Data is collected by cameras and microphones placed in public rooms, to which the occupants can issue commands, and received through already owned phones or speakers in the house.

The primary goals for HyveOS are:

Safety making houses capable of detecting dangers such as a burglary or an occupant falling down and not getting back up

Cooperativity allowing houses to balance each other's energy loads and resources

Sustainability letting neighbours to connect with each other and share their own resources, such as tools and food, more easily (and with encouragement from their houses)

Hands-Free Operation enabling people to connect fluidly to the world of data around them through motion tracking systems more accurate than Microsoft's Kinect

Community gently encouraging neighbours to make connections and share with each other

1.1 Decisions Made

The following decisions have been somewhat firmly made:

1.2 Requested Feedback

In our case most of the technological decisions have been fairly firmly made. We were able to do this through extensive research and with the knowledge that what we do can be done fairly independently of the other Solar Decathlon teams.

What feedback we do request is where you see automation fitting in with your part of the house. Also I would like to know whether or not you think HyveOS should increase or decrease the scope of its goals or if you think our goals are misguided.

Aspect	Decision	Firmness (0-5)
Satellites Hardware	Raspberry Pi	5
Server Hardware	Custom PC Rig	4
Automation Satellites	Arduino	2
Satellite Operating System	Ubuntu Server	4
Satellite Peripherals	Audio, Visual	2
Primary Interface	Website (with mobile)	4
Primary Language	NodeJS	4
Analytical Language	Python	4

Table 1: A tabular description of some of the decisions already made.

2 Research

2.1 Hardware

Most of hardware concern comes down to Arduino vs Raspberry Pi vs TI Launchpad vs Beaglebone, some of which are depicted in Figure 1. For now, TI Launchpad and Beaglebone will be discounted, though the TI Launchpad is perhaps interesting in that it has the backing of a very large company and is desperate to gain market share.

This distinction is more made at what Hyvdev aims to do. The following quote from James Bruce clarifies the intended purposes of each of these machines.

The Arduino runs the Arduino firmware, a basic bit of core software which allows it to communicate with a computer over USB and gives access to all the features. You generally wouldn't replace this firmware, but it is possible. Once your application has been loaded, you can just plug it in anywhere and it'll start working immediately, you don't need to reboot, plug in a keyboard, or choose an application to run. It does the one job it's been programmed to do, and it does it immediately.

The Raspberry Pi on the other is a complete, functional, mini-computer. It requires an operating system - the first thing you need to choose that will dramatically affect your experience - and has all the bits and pieces you might expect a full computer to have (just in a smaller scale). Storage is provided from a micro-SD card, while built-in Ethernet allows for networking (you can get networking on Arduino too, but it requires an add-on "shield").

If the Arduino is chosen, then the team chooses its focus is more on typical home automation, such as controlling windows and doors and doing basic home monitoring; alternatively, the Raspberry Pi signifies a much more involved automation process.

The Raspberry Pi was chosen to empower the team to provide a full automation experience, attempting to make the "smart home." As it turns out, a few other groups are also attempting to make the smart home, Nest not the least of them. It is thus our job to also distinguish ourselves from these competitors.

But really, why choose? We can use both, using the Arduino (or TI Launchpad) to control much of the typical home automation and the Raspberry Pi for controlling satellites.

2.2 Software

It is in the software that Hyve is distinguishable. First, let's look at the competitors.

Nest is a home automation company that designs and manufactures sensor-driven, Wi-Fi-enabled, self-learning, programmable thermostats and smoke detectors.

Insteon is a home automation networking technology that enables light switches, lights, thermostats, motion sensors, and other devices to interoperate through power lines, radio frequency (RF) communications, or both.

Pointgrab aims to control all household appliances with natural gestures. Pretty damn cool, but not exactly competing with us yet.

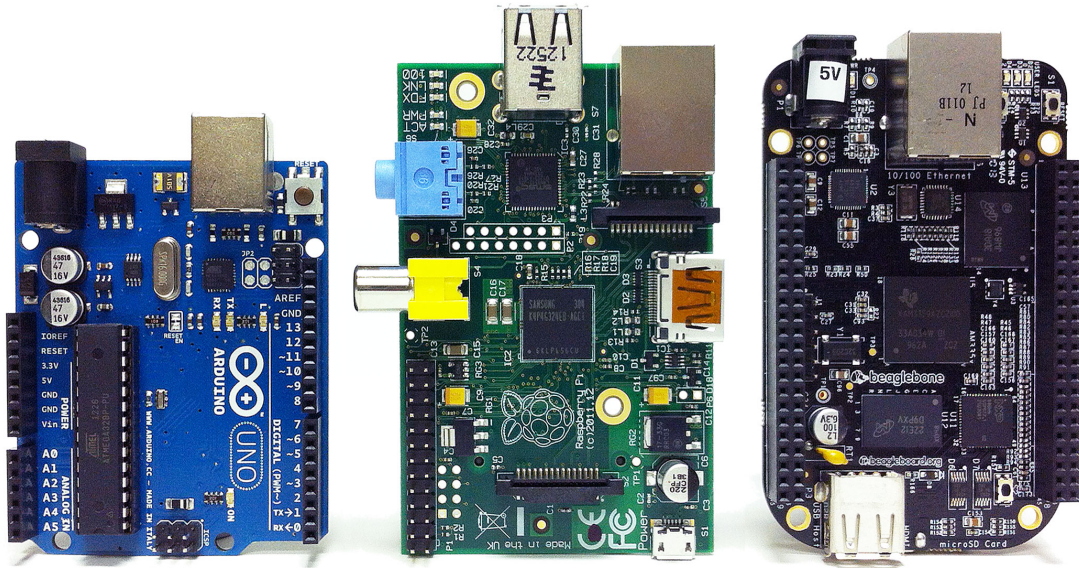
Revolv \$299 device that connects existing smart devices, unifying them to make a full smart home.

Nest gets a lot of hype, but is underwhelming from a home automation perspective. It is likely that they will make an aggressive shift into home automation since their purchase by Google.

There are some other competitors, but most follow this tune. It is thus not difficult to see where Hyve can differ.

These other approaches are largely cautious, timid, and realistic. Hyve is a student group, part of the Solar Decathlon competition. We do not need to be realistic at first. We do not need to be cautious. Fortunately, it is the sign of many great adventures (and successful companies) to not be overly concerned about what is considered normal today and instead be prepared for what is normal in the future.

Figure 1: An Arduino, Raspberry Pi, and Beaglebone from left to right, demonstrating their relative size. Their absolute size should be inferred by the size of their ports.



This brings us to Hyve’s primary endeavour, which is behaviour modification and true integration of technology and home life, but this topic is saved for the conclusion.

2.3 Available Software

This is the most important section of the paper! Here is what’s already out there. More importantly, this is what is available to use.

2.3.1 WiTrack: Through-wall 3D Tracking Using Body Radio Reflections

A technology from CSAIL at MIT.

WiTrack is a device that tracks the 3D motion of a user from the radio signals reflected off her body. It works even if the person is occluded from the WiTrack device or in a different room. WiTrack does not require the user to carry any wireless device, yet its accuracy exceeds current RF localization systems, which require the user to hold a transceiver. It transmits wireless signals whose power is 100 times smaller than Wi-Fi and 1000 times smaller than cellphone transmissions.

WiTrack localizes the center of a human body to within 10 to 13 cm in the x and y dimensions (about the size of an adult hand), and 21 cm in the z dimension. It also provides coarse tracking of body parts, identifying the direction of a pointing hand with a median of 11.2 degrees. It can also detect falls with 96.9% accuracy. WiTrack can be

incorporated into consumer electronics and has a wide set of applications.

The paper for the technology is available [here](#).

2.3.2 Wit Speech

Wit speech is one of several online APIs for voice recognition. It’s a very attractive package, though perhaps not as good as Nuance’s offerings yet. In any case, they provide an excellent description of their service:

Wit.AI enables developers to add a natural language interface to their app or device in minutes. It’s faster and more accurate than Siri, and requires no upfront investment, expertise, or training dataset.

It’s very simple, really, and very powerful since their AI is constantly improving with hundreds of users.

2.3.3 Jasper: Control Anything with Your Voice, Connected to Raspberry-Pi

Jasper is an existing open source platform for developing fully voice controlled applications. Fortunately, it is already designed for the Raspberry Pi, and it is supposed to be very easy to set up on a single Raspberry Pi.

2.3.4 SpaceBrew

This is part technology and part resource.

Spacebrew is an open, dynamically re-routable software toolkit for choreographing interactive spaces. Or, in other words, a simple way to connect interactive things to one another. Every element you hook

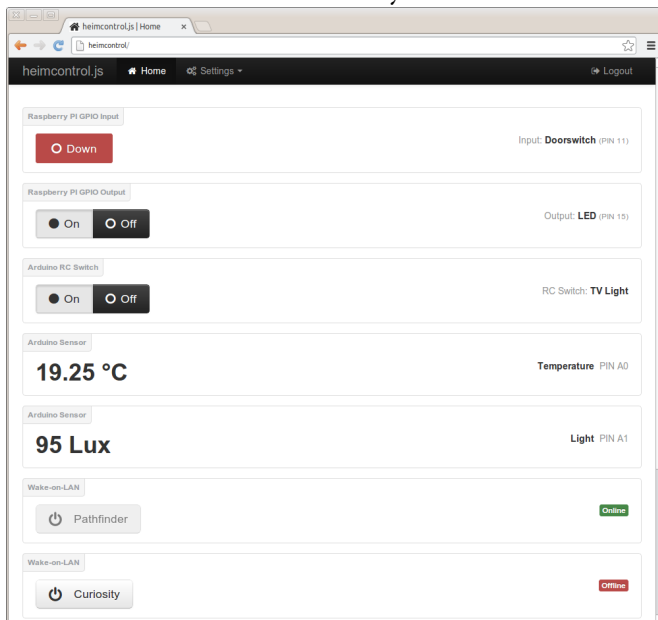
up to the system is identified as either a subscriber (reading data in) or a publisher (pushing data out). Data is in one of three standardized formats: a boolean (true/false), a number range (0-1023) or a string (text). Once these elements are set up, you can use a web based visual switch-board to connect or disconnect publishers and subscribers to each other.

2.3.5 HeimControlJS

An existing Home Automation suite with Raspberry Pi and Arduino with a control interface. Hell, it's so much like what we planned on doing it could practically be the result.

I'm seriously considering HyveOS being an expansion on this project and then using the extra time we save to rewrite the entire codebase once with the experience we gain from the first write.

This only covers home automation, and does not include more advanced features of HyveOS.



2.3.6 Quake

Not really a resource but you can play Quake on a Raspberry Pi. Damned cool.

3 Cost Analysis

3.1 Raspberry Pi Satellites

3.2 Server

3.3 Arduino Automation

4 Conclusion

Hyve's primary endeavour is behaviour modification and a bolder marriage of technology and the home. It is through true integration of and comfort with technology that communities can become closer together.

Hyve is designed to both protect the individual, his property, his person, and his privacy, and also to help connect him to his neighbours. While I expand this paper, this will be further detailed.