IVIALITOTTIALIO	aı və. i iiyəlcai i	vioucia
■ Mathematical Model: is the model. The symbolism used	can be a language or a	mathematical notation.
 A simulation model is land is an abstract mode Physical Model: Physical m 	el.	and mathematical equations ger physical copy of an
object. The object being mod (for example, the Solar Syste	leled may be small (for em).	example, an atom) or large
 A model of an airplane (map, a globe, a model ca 		of the atom (scaled up), a sical (iconic) models.
Static Vs. Dynamic (Al	ostract /Physical/	Computer) Models
☐ Static Model: is the one wh respect to time.	ich describes relationsl	hips that do not change with
 An architectural model An equation relating the playground variation is 	e lengths and weights	on each side of a
 Static computer model Dynamic Model: is the one 	which means fixed.	
relationships. • A wind tunnel is a dyn		
 The equations of motion dynamic mathematics 		
 Dynamic computer usu 	ally means capable of	action and/or change.
	×	×
		□
	imerical Mathema	
mathematical theory.	•	sing the deductive reasoning of er Linear Programming
model, a nonlinear opti models.	imization model are ex	amples of analytical
 Numerical Model: is the on computational procedures. Finding the roots of a result of the control of		pplying $ation, f(x) = 0, using the$
numerical model.	J J J J J J J J J J J J J J J J J J J	
Linear Vs. No	nlinear Mathemat	tical Models
☐ Linear Model: is the on form.	e which describes re	lationships in linear
☐ Nonlinear Model: is the	4z + 1=0 is a linear e one which describe	
nonlinear form. • The equation $2x^2$	+ y ³ —2=0 is a nonl	inear model.
	×	×
Stable Or Unsta	ble Mathematical	Models
☐ Stable Model: is the one was after being disturbed.	hich tends to return	to its initial condition
■ Like a simple pendulu ☐ Unstable Model: is the or		not come back to its
initial condition after being	g disturbed.	
Steady-state Or Tra	nsient Mathemati	cal Models
☐ Steady-State Model: is the of the same nature as any o		r in one time period is
☐ Transient Model: is the on time.	•	anges with respect to
state		
Transient Behav	/ior	Steady-State Behavior
		time
	×	×
Descriptive Vs. Pre	escriptive (Normat	rive) Models
☐ Descriptive Model: a system		
indicate any course of action. ☐ The equation F (force) = I model.	M (mass) x A (accelera	ation) is a descriptive
☐ All simulation models ar ☐ Prescriptive or Normative M of action that the decision ma	lodel: a system in that	•
of action that the decision ma		ieve a defined objective.
	MODELS	III
SIMPLE		COMPLEX
StaticDeterministic	versus	Dynamic Stochastic
LinearContinuous	versus	Nonlinear Discrete
Steady State	01003	
The same of the sa	versus	Transient
AggregateStable	versus versus	Transient Detail Unstable

디

Distributed-lag Model

(the X's) it is called a distributed-lag model.

dynamic model.

■ If the regression model includes not only the current but

If the model includes one or more lagged values of the

also the lagged (past) values of the explanatory variables

dependent variable among its explanatory variables, it is

called an autoregressive model. This model is know as a