

# Zero-Renderer

0.1

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## Chapter 1

# README



## Chapter 2

## Todo List

Member [BoundingBoxUnionIntersect](#) (const BoundingBox3< BaseType > &b1, const BoundingBox3< BaseType > &b2)

The function name "BoundingBoxOverlap" might better

Class [CoordConvertor](#)

A namespace contains function might better?

Class [RGBSpectrum](#)

To be finished



## Chapter 3

# Module Index

### 3.1 Modules

Here is a list of all modules:

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## Chapter 4

# Hierarchical Index

### 4.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

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## Chapter 5

# Class Index

### 5.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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Axis-aligned bounding box 3D base type, the box edges are mutually perpendicular and aligned to axes . . . . .	17
<a href="#">CoefficientSpectrum&lt; nSamples &gt;</a>	
Spectrum of nSamples sample points . . . . .	18
<a href="#">CoordConvertor</a>	
Provides transformations between different coordinate systems . . . . .	21
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Base class for pixel sampler, which generate specific samples before rendering each pixel need the dimensions and samplesPerPixels when construct . . . . .	22
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<a href="#">RandomNumberGenerator</a> , using pcg to generate random number . . . . .	22
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### 6.1 File List

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## Chapter 7

# Module Documentation

### 7.1 Geometry

#### Classes

- class [BoundingBox3< BaseType >](#)  
*Axis-aligned bounding box 3D base type, the box edges are mutually perpendicular and aligned to axes.*
- class [CoordConvertor](#)  
*Provides transformations between different coordinate systems.*

#### 7.1.1 Detailed Description



## Chapter 8

# Class Documentation

### 8.1 BoundingBox3< BaseType > Class Template Reference

Axis-aligned bounding box 3D base type, the box edges are mutually perpendicular and aligned to axes.

```
#include <BoundingBox.h>
```

#### Public Member Functions

- `std::optional< Point2d > Intersection` (const Ray &r)  
*Intersect of ray and bounding box.*
- `double SurfaceArea` ()  
*The surface area of the bounding box.*

#### 8.1.1 Detailed Description

```
template<typename BaseType>  
class BoundingBox3< BaseType >
```

Axis-aligned bounding box 3D base type, the box edges are mutually perpendicular and aligned to axes.

##### Parameters

<i>BaseType</i>	the type of the bounding box, int/float/double.
-----------------	---

#### 8.1.2 Member Function Documentation

### 8.1.2.1 Intersection()

```
template<typename BaseType >
std::optional< Point2d > BoundingBox3< BaseType >::Intersection (
    const Ray & r ) [inline]
```

Intersect of ray and bounding box.

#### Returns

A pointer to the pair (t0, t1)

### 8.1.2.2 SurfaceArea()

```
template<typename BaseType >
double BoundingBox3< BaseType >::SurfaceArea ( ) [inline]
```

The surface area of the bounding box.

#### Returns

A double represents the bounding box's surface area

The documentation for this class was generated from the following file:

- /mnt/renderer/Zero/src/CoreLayer/Geometry/[BoundingBox.h](#)

## 8.2 CoefficientSpectrum< nSamples > Class Template Reference

Spectrum of nSamples sample points.

```
#include <Color.h>
```

### Public Member Functions

- **CoefficientSpectrum ()**  
*All coefficients initialized as 0.0f.*
- **CoefficientSpectrum (double val)**  
*All coefficients initialized as val.*
- double [operator\[\]](#) (int i) const
- double & [operator\[\]](#) (int i)
- [CoefficientSpectrum operator/](#) (const [CoefficientSpectrum](#) &s) const
- [CoefficientSpectrum & operator/=](#) (const [CoefficientSpectrum](#) &s)
- [CoefficientSpectrum operator/](#) (double v) const
- [CoefficientSpectrum & operator/=](#) (double v)
- virtual XYZ3 [toXYZ3](#) () const

## Friends

- [CoefficientSpectrum sqrt](#) (const [CoefficientSpectrum](#) &s)

## 8.2.1 Detailed Description

```
template<int nSamples>
class CoefficientSpectrum< nSamples >
```

Spectrum of nSamples sample points.

## 8.2.2 Member Function Documentation

### 8.2.2.1 operator/() [1/2]

```
template<int nSamples>
CoefficientSpectrum CoefficientSpectrum< nSamples >::operator/ (
    const CoefficientSpectrum< nSamples > & s ) const [inline]
```

#### Attention

There may be NaNs in result

### 8.2.2.2 operator/() [2/2]

```
template<int nSamples>
CoefficientSpectrum CoefficientSpectrum< nSamples >::operator/ (
    double v ) const [inline]
```

#### Attention

There may be NaNs in result

### 8.2.2.3 operator/=( ) [1/2]

```
template<int nSamples>
CoefficientSpectrum & CoefficientSpectrum< nSamples >::operator/= (
    const CoefficientSpectrum< nSamples > & s ) [inline]
```

#### Attention

There may be NaNs in result

**8.2.2.4 operator/=( ) [2/2]**

```
template<int nSamples>
CoefficientSpectrum & CoefficientSpectrum< nSamples >::operator/= (
    double v ) [inline]
```

**Attention**

There may be NaNs in result

**8.2.2.5 operator[]( ) [1/2]**

```
template<int nSamples>
double & CoefficientSpectrum< nSamples >::operator[] (
    int i ) [inline]
```

**Attention**

No bounding check

**8.2.2.6 operator[]() [2/2]**

```
template<int nSamples>
double CoefficientSpectrum< nSamples >::operator[] (
    int i ) const [inline]
```

**Attention**

No bounding check

**8.2.2.7 toXYZ3()**

```
template<int nSamples>
virtual XYZ3 CoefficientSpectrum< nSamples >::toXYZ3 ( ) const [inline], [virtual]
```

**Attention**

This function is just used for debugging

Reimplemented in [SampledSpectrum](#).

## 8.2.3 Friends And Related Function Documentation

### 8.2.3.1 sqrt

```
template<int nSamples>
CoefficientSpectrum sqrt (
    const CoefficientSpectrum< nSamples > & s ) [friend]
```

#### Attention

Does not check if each component is greater than 0

The documentation for this class was generated from the following file:

- /mnt/renderer/Zero/src/CoreLayer/ColorSpace/Color.h

## 8.3 CoordConvertor Class Reference

Provides transformations between different coordinate systems.

```
#include <CoordConvertor.h>
```

### Static Public Member Functions

- static Point3d [cartesian2Spherical](#) (const Point2d &p)  
*Convert a spherical coordinate  $(\phi, \theta)$  to cartesian coordinate.*
- static Vec3d [cartesian2SphericalVec](#) (const Point2d &p)  
*Convert  $[0, 1]^2$  to a point on unit sphere..*

### 8.3.1 Detailed Description

Provides transformations between different coordinate systems.

**Todo** A namespace contains function might better?

### 8.3.2 Member Function Documentation

#### 8.3.2.1 cartesian2Spherical()

```
Point3d CoordConvertor::cartesian2Spherical (
    const Point2d & p ) [static]
```

Convert a spherical coordinate  $(\phi, \theta)$  to cartesian coordinate.

#### Attention

Sperical2cartesian? The function name doesn't match

**Parameters**

$p$	$(\phi, \theta)$
-----	------------------

**Returns**

The corresponding coordinate in cartesian

The documentation for this class was generated from the following files:

- /mnt/renderer/Zero/src/CoreLayer/Geometry/[CoordConvertor.h](#)
- /mnt/renderer/Zero/src/CoreLayer/Geometry/[CoordConvertor.cpp](#)

## 8.4 PixelSampler Class Reference

Base class for pixel sampler, which generate specific samples before rendering each pixel need the dimensions and samplesPerPixels when construct.

```
#include <Sampler.h>
```

Inherits Sampler.

Inherited by StratifiedSampler.

### 8.4.1 Detailed Description

Base class for pixel sampler, which generate specific samples before rendering each pixel need the dimensions and samplesPerPixels when construct.

The documentation for this class was generated from the following file:

- /mnt/renderer/Zero/src/FunctionLayer/Sampler/[Sampler.h](#)

## 8.5 RandomNumberGenerator Class Reference

[RandomNumberGenerator](#), using pcg to generate random number.

```
#include <Random.h>
```

**Public Member Functions**

- double **operator()** ()  
*Generate uniformly distributed random double in [0, 1)*
- int **operator()** (int begin, int end)  
*Generate uniformly distributed random int in [begin, end)*



### 8.5.1 Detailed Description

[RandomNumberGenerator](#), using `pcg` to generate random number.

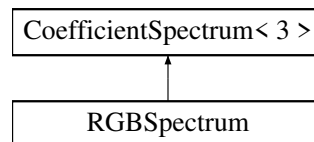
The documentation for this class was generated from the following file:

- `/mnt/renderers/Zero/src/CoreLayer/Adapter/Random.h`

## 8.6 RGBSpectrum Class Reference

```
#include <Color.h>
```

Inheritance diagram for RGBSpectrum:



### Additional Inherited Members

#### 8.6.1 Detailed Description

**Todo** To be finished

The documentation for this class was generated from the following file:

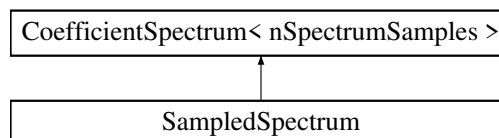
- `/mnt/renderers/Zero/src/CoreLayer/ColorSpace/Color.h`

## 8.7 SampledSpectrum Class Reference

The spectrum samples uniformly. Actually used in program.

```
#include <Color.h>
```

Inheritance diagram for SampledSpectrum:



### Public Member Functions

- virtual XYZ3 [toXYZ3](#) () const override

## Static Public Member Functions

- static void **init** ()  
*Global init of static values. should be called before any constructor of [SampledSpectrum](#).*
- static [SampledSpectrum](#) **fromSampled** (std::vector< [SpectrumSample](#) > v)  
*generate [SampledSpectrum](#) from a set of [SpectrumSample](#).*

### 8.7.1 Detailed Description

The specturm samples uniformly. Actually used in program.

### 8.7.2 Member Function Documentation

#### 8.7.2.1 toXYZ3()

```
XYZ3 SampledSpectrum::toXYZ3 ( ) const [override], [virtual]
```

#### Attention

This function is just used for debugging

Reimplemented from [CoefficientSpectrum< nSpectrumSamples >](#).

The documentation for this class was generated from the following files:

- /mnt/renderer/Zero/src/CoreLayer/ColorSpace/[Color.h](#)
- /mnt/renderer/Zero/src/CoreLayer/ColorSpace/Spectrum.cpp

## 8.8 SpectrumSample Struct Reference

One sample point from a spectrum.

```
#include <Color.h>
```

### Public Member Functions

- bool **operator**> (const [SpectrumSample](#) &s) const  
*Sorted by lambda.*
- bool **operator**< (const [SpectrumSample](#) &s) const  
*Sorted by lambda.*

#### 8.8.1 Detailed Description

One sample point from a spectrum.

The documentation for this struct was generated from the following file:

- /mnt/renderer/Zero/src/CoreLayer/ColorSpace/[Color.h](#)

## Chapter 9

# File Documentation

### 9.1 Attribute.h

```
1
11 #pragma once
12 #include "rapidjson/document.h"
13 #include <vector>
14 #include <string>
15 #include <unordered_map>
16 #include <iostream>
17 #include <memory>
18
19 struct Value {
20     Value() = default;
21     virtual ~Value() = default;
22
23     virtual void print() const = 0;
24 };
25
26 class Attribute {
27 public:
28     Attribute() : m_type(EValueType::EInvalid), m_value(nullptr) { }
29
30     Attribute(const rapidjson::Document &document);
31
32     Attribute(const std::string &key, bool b);
33
34     Attribute(const std::string &key, int i);
35
36     Attribute(const std::string &key, double d);
37
38     Attribute(const std::string &key, const std::string &str);
39
40     Attribute(const std::string &key,
41               const rapidjson::GenericValue<rapidjson::UTF8<>::ConstArray &array);
42
43     Attribute(const std::string &key,
44               const rapidjson::GenericValue<rapidjson::UTF8<>::ConstObject &object);
45
46
47     void print() const {
48         std::cout << "Key = " << m_key << ", ";
49         m_value->print();
50     }
51
52     Attribute operator[](const std::string &key) const;
53
54     Attribute operator[](int i) const;
55
56     bool getBool() const;
57
58     int getInt() const;
59
60     double getDouble() const;
61
62     std::string getString() const;
63 private:
64
65     enum class EValueType {
66         EInvalid = 0,
```

```

68         EBool,
69         EInt,
70         EDouble,
71         EString,
72         EArray,
73         EObject
74     } m_type;
75
76     std::string m_key;
77
78     std::shared_ptr<Value> m_value;
79
80 };
81
82
83 struct BoolValue : public Value {
84     BoolValue() = default;
85
86     BoolValue(bool b) : data(b) { };
87
88     virtual ~BoolValue() = default;
89
90     virtual void print() const override {
91         std::cout << "BoolValue : " << (data ? "true" : "false") << std::endl;
92     }
93
94     bool data;
95
96 };
97
98 struct IntValue : public Value {
99     IntValue() = default;
100
101     IntValue(int i) : data(i) { }
102
103     virtual ~IntValue() = default;
104
105     int data;
106
107     virtual void print() const override {
108         std::cout << "IntValue : " << data << std::endl;
109     }
110 };
111
112
113 struct DoubleValue : public Value {
114     DoubleValue() = default;
115
116     DoubleValue(double d) : data(d) { }
117
118     virtual ~DoubleValue() = default;
119
120     double data;
121
122     virtual void print() const override {
123         std::cout << "DoubleValue : " << data << std::endl;
124     }
125 };
126
127
128 struct ArrayValue : public Value {
129     ArrayValue() = default;
130
131     virtual ~ArrayValue() {
132         for (int i = 0; i < data.size(); ++i) {
133             delete data[i];
134         }
135     }
136
137     std::vector<Attribute*> data;
138
139     virtual void print() const override {
140         std::cout << "ArrayValue : \n";
141         for (int i = 0; i < data.size(); ++i) {
142             std::cout << "\t";
143             data[i]->print();
144         }
145     }
146 };
147
148 struct StringValue : public Value {
149     StringValue() = default;
150
151     StringValue(const std::string &str) : data(str) { }
152
153     virtual ~StringValue() = default;
154

```

```

155     virtual void print() const override {
156         std::cout << "StringValue : " << data << std::endl;
157     }
158
159     std::string data;
160
161 };
162
163 struct ObjectValue : public Value {
164     ObjectValue() = default;
165
166     virtual ~ObjectValue() {
167         for (auto itr = data.begin(); itr != data.end(); ++itr) {
168             delete itr->second;
169         }
170     }
171
172     virtual void print() const override {
173         std::cout << "ObjectValue : {\n";
174         for (auto itr = data.begin(); itr != data.end(); ++itr) {
175             std::cout << "\t";
176             itr->second->print();
177         }
178         std::cout << "}" << std::endl;
179     }
180
181     std::unordered_map<std::string, Attribute *> data;
182 };
183
184
185 inline Attribute::Attribute(const rapidjson::Document &document) {
186     m_type = EValueType::EObject;
187     m_key = "root";
188     m_value = std::make_shared<ObjectValue>();
189
190     ObjectValue* object_value = static_cast<ObjectValue *>(m_value.get());
191
192     for (auto itr = document.MemberBegin(); itr != document.MemberEnd(); ++itr) {
193         Attribute *attribute = nullptr;
194         const std::string &member_key = itr->name.GetString();
195         const auto &member_value = itr->value;
196         if (member_value.IsBool()) {
197             attribute = new Attribute(member_key, member_value.GetBool());
198         } else if (member_value.IsInt()) {
199             attribute = new Attribute(member_key, member_value.GetInt());
200         } else if (member_value.IsDouble()) {
201             attribute = new Attribute(member_key, member_value.GetDouble());
202         } else if (member_value.IsString()) {
203             attribute = new Attribute(member_key, std::string(member_value.GetString()));
204         } else if (member_value.IsArray()) {
205             attribute = new Attribute(member_key, member_value.GetArray());
206         } else if (member_value.IsObject()) {
207             attribute = new Attribute(member_key, member_value.GetObject());
208         }
209         if (attribute == nullptr) {
210             std::cout << "Error type\n";
211             std::exit(1);
212         }
213         object_value->data[member_key] = attribute;
214     }
215 }
216
217 inline Attribute::Attribute(const std::string &key, bool b) :
218     m_type(EValueType::EBool),
219     m_key(key),
220     m_value(new BoolValue {b}) { }
221
222
223 inline Attribute::Attribute(const std::string &key, int i) :
224     m_type(EValueType::EInt),
225     m_key(key),
226     m_value(new IntValue {i}) { }
227
228 inline Attribute::Attribute(const std::string &key, double d) :
229     m_type(EValueType::EDouble),
230     m_key(key),
231     m_value(new DoubleValue {d}) { }
232
233 inline Attribute::Attribute(const std::string &key, const std::string &str) :
234     m_type(EValueType::EString),
235     m_key(key),
236     m_value(new StringValue {str}) { }
237
238
239 inline Attribute::Attribute(
240     const std::string &key,
241     const rapidjson::GenericValue<rapidjson::UTF8<>::ConstArray &array) :

```

```

242     m_type(EValueType::EArray),
243     m_key(key) {
244
245     m_value = std::make_shared<ArrayValue>();
246     ArrayValue *array_value = static_cast<ArrayValue *>(m_value.get());
247     for (auto itr = array.Begin(); itr != array.End(); ++itr) {
248         Attribute *attribute = nullptr;
249         if (itr->IsBool()) {
250             attribute = new Attribute("", itr->GetBool());
251         } else if (itr->IsInt()) {
252             attribute = new Attribute("", itr->GetInt());
253         } else if (itr->IsDouble()) {
254             attribute = new Attribute("", itr->GetDouble());
255         } else if (itr->IsString()) {
256             attribute = new Attribute("", std::string(itr->GetString()));
257         } else if (itr->IsArray()) {
258             attribute = new Attribute("", itr->GetArray());
259         } else if (itr->IsObject()) {
260             attribute = new Attribute("", itr->GetObject());
261         }
262         if (attribute == nullptr) {
263             std::cout << "Error Type\n";
264             std::exit(1);
265         }
266         array_value->data.emplace_back(attribute);
267     }
268 }
269
270 inline Attribute::Attribute(
271     const std::string &key,
272     const rapidjson::GenericValue<rapidjson::UTF8<>::ConstObject &object> :
273     m_type(EValueType::EObject),
274     m_key(key) {
275
276     m_value = std::make_shared<ObjectValue>();
277     ObjectValue *object_value = static_cast<ObjectValue *>(m_value.get());
278     for (auto itr = object.MemberBegin(); itr != object.MemberEnd(); ++itr) {
279         Attribute *attribute = nullptr;
280         const std::string &member_key = itr->name.GetString();
281         const auto &member_value = itr->value;
282         if (member_value.IsBool()) {
283             attribute = new Attribute(member_key, member_value.GetBool());
284         } else if (member_value.IsInt()) {
285             attribute = new Attribute(member_key, member_value.GetInt());
286         } else if (member_value.IsDouble()) {
287             attribute = new Attribute(member_key, member_value.GetDouble());
288         } else if (member_value.IsString()) {
289             attribute = new Attribute(member_key, std::string(member_value.GetString()));
290         } else if (member_value.IsArray()) {
291             attribute = new Attribute(member_key, member_value.GetArray());
292         } else if (member_value.IsObject()) {
293             attribute = new Attribute(member_key, member_value.GetObject());
294         }
295         if (attribute == nullptr) {
296             std::cout << "Error type\n";
297             std::exit(1);
298         }
299         object_value->data[member_key] = attribute;
300     }
301 }
302
303 inline Attribute Attribute::operator[](const std::string &key) const {
304     assert(m_type == EValueType::EObject);
305     ObjectValue *object_value = static_cast<ObjectValue *>(m_value.get());
306     const auto attributes = object_value->data;
307     if (auto itr = attributes.find(key); itr == attributes.end()) {
308         std::cout << "No such a key \"" << key << "\"\n";
309         std::exit(1);
310     } else {
311         return *(itr->second);
312     }
313 }
314
315 inline Attribute Attribute::operator[](int i) const {
316     assert(m_type == EValueType::EArray);
317     ArrayValue *array_value = static_cast<ArrayValue *>(m_value.get());
318     const auto attribute_list = array_value->data;
319     assert(i < attribute_list.size());
320     return *attribute_list[i];
321 }
322
323 inline bool Attribute::getBool() const {
324     assert(m_type == EValueType::EBool);
325     BoolValue *bool_value = static_cast<BoolValue *>(m_value.get());
326     return bool_value->data;
327 }
328

```

```
329 inline int Attribute::getInt() const {
330     assert(m_type == EValueType::EInt);
331     IntValue *int_value = static_cast<IntValue *>(m_value.get());
332     return int_value->data;
333 }
334
335 inline double Attribute::getDouble() const {
336     assert(m_type == EValueType::EDouble);
337     DoubleValue *double_value = static_cast<DoubleValue *>(m_value.get());
338     return double_value->data;
339 }
340
341 inline std::string Attribute::getString() const {
342     assert(m_type == EValueType::EString);
343     StringValue *string_value = static_cast<StringValue *>(m_value.get());
344     return string_value->data;
345 }
346
```

## 9.2 /mnt/renderer/Zero/src/CoreLayer/Adapter/Random.h File Reference

The class used to generate random numbers.

```
#include <random>
#include "pcg/pcg_random.hpp"
#include "CoreLayer/Math/Common.h"
```

### Classes

- class [RandomNumberGenerator](#)  
*[RandomNumberGenerator](#), using `pcg` to generate random number.*

### 9.2.1 Detailed Description

The class used to generate random numbers.

#### Author

Chenxi Zhou

#### Version

0.1

#### Date

2022-06-24

#### Copyright

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## 9.3 Random.h

[Go to the documentation of this file.](#)

```

1
13 #pragma once
14 #include <random>
15 #include "pcg/pcg_random.hpp"
16 #include "CoreLayer/Math/Common.h"
17
22 class RandomNumberGenerator {
23     std::uniform_real_distribution<> dist;
24     pcg_extras::seed_seq_from<std::random_device> seedSource;
25     pcg32 rng;
26 public:
27     RandomNumberGenerator():dist(0, ONEMINUSEPSILON), rng(seedSource) { }
28
29     double operator()() {
30         return dist(rng);
31     }
32
33     int operator()(int begin, int end) {
34         int sample = begin + (end - begin) * dist(rng);
35         return std::min(end - 1, sample);
36     }
37
38 };
39
40 };

```

## 9.4 /mnt/renderer/Zero/src/CoreLayer/ColorSpace/Color.h File Reference

Color representation, including rgb, xyz and spectrum.

```

#include <vector>
#include <cmath>
#include <cfloat>

```

### Classes

- class [CoefficientSpectrum< nSamples >](#)  
*Spectrum of nSamples sample points.*
- struct [SpectrumSample](#)  
*One sample point from a spectrum.*
- class [SampledSpectrum](#)  
*The spectrum samples uniformly. Actually used in program.*
- class [RGBSpectrum](#)

### Enumerations

- enum class [SpectrumType](#)  
*types of spectrum. different strategies will be applied.*

### Functions

- double **mathClamp** (double source, double low=0.0, double high=DBL\_MAX)  
*Mathematical clamp.*
- double **mathLerp** (double ratio, double source0, double source1)  
*Mathematical lerp.*



## Variables

- static const int **nSpectrumSamples** = 60  
The number of uniform samples for *SampledSpectrum*.

### 9.4.1 Detailed Description

Color representation, including rgb, xyz and spectrum.

XYZ3 implementation.

Spectrum implementation and preset Spectrums.

RGB3 implementation.

#### Author

orbitchen

#### Version

0.1

#### Date

2022-04-30

#### Copyright

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## 9.5 Color.h

[Go to the documentation of this file.](#)

```
1
12 #pragma once
13
14 #include <vector>
15 #include <cmath>
16 #include <cfloat>
17
18 class RGB3;
19 class XYZ3;
20 class SampledSpectrum;
21
22 // TODO: should be defined by cmake marco.
23 using Spectrum = SampledSpectrum;
24
25 //using Spectrum = RGB3;
26
27 static const double sampledLambdaStart = 400.0;
28 static const double sampledLambdaEnd = 700.0;
29
31 static const int nSpectrumSamples = 60;
32
34 double mathClamp(double source, double low=0.0, double high=DBL_MAX);
35
37 double mathLerp(double ratio, double source0, double source1);
38
40 enum class SpectrumType { REFLECTANCE, ILLUMINANT };
41
```

```

42 class RGB3
43 {
44     double rgbData[3];
45
46 public:
47     RGB3();
48
49     RGB3(double r, double g, double b);
50
51     // @brief initialize all rgb value as val.
52     RGB3(double val);
53
54     double operator[](int i) const;
55     double &operator[](int i);
56
57     RGB3 operator+(const RGB3 &rgb);
58     RGB3 operator-(const RGB3 &rgb);
59     RGB3 operator*(const RGB3 &rgb);
60     RGB3 operator/(const RGB3 &rgb);
61
62     RGB3 &operator+=(const RGB3 &rgb);
63     RGB3 &operator-=(const RGB3 &rgb);
64     RGB3 &operator*=(const RGB3 &rgb);
65     RGB3 &operator/=(const RGB3 &rgb);
66
67     RGB3 operator*(double v);
68     RGB3 operator/(double v);
69
70     RGB3 &operator*=(double v);
71     RGB3 &operator/=(double v);
72
73     friend RGB3 operator*(double v, const RGB3 &rgb);
74
75     XYZ3 toXYZ3() const;
76
77     // @brief convert RGB3 to SampledSpectrum.
78     Spectrum toSpectrum(SpectrumType type=SpectrumType::REFLECTANCE) const;
79 };
80
81 class XYZ3
82 {
83     double xyzData[3];
84
85 public:
86     XYZ3();
87
88     XYZ3(double x, double y, double z);
89
90     // @brief initialize all xyz value as val.
91     XYZ3(double val);
92
93     double operator[](int i) const;
94     double &operator[](int i);
95
96     XYZ3 operator+(const XYZ3 &xyz);
97     XYZ3 operator-(const XYZ3 &xyz);
98     XYZ3 operator*(const XYZ3 &xyz);
99     XYZ3 operator/(const XYZ3 &xyz);
100
101     XYZ3 &operator+=(const XYZ3 &xyz);
102     XYZ3 &operator-=(const XYZ3 &xyz);
103     XYZ3 &operator*=(const XYZ3 &xyz);
104     XYZ3 &operator/=(const XYZ3 &xyz);
105
106     XYZ3 operator*(double v);
107     XYZ3 operator/(double v);
108
109     XYZ3 &operator*=(double v);
110     XYZ3 &operator/=(double v);
111
112     friend XYZ3 operator*(double v, const XYZ3 &xyz);
113
114     RGB3 toRGB3() const;
115 };
116
117 template <int nSamples>
118 class CoefficientSpectrum
119 {
120 protected:
121     double coefficients[nSamples];
122
123 public:
124     CoefficientSpectrum() {
125         for (int i = 0; i < nSamples; i++) {
126             coefficients[i] = 0.0;
127         }
128     }
129 }
130

```

```

131
132
133     CoefficientSpectrum(double val) {
134         for (int i = 0; i < nSamples; i++) {
135             coefficients[i] = val;
136         }
137     }
138
139     double operator[](int i) const {
140         return coefficients[i];
141     }
142 }
143
144 double &operator[](int i) {
145     return coefficients[i];
146 }
147
148
149 CoefficientSpectrum operator+(const CoefficientSpectrum&s) const {
150     CoefficientSpectrum retVal = *this;
151     for (int i = 0; i < nSamples; i++) {
152         retVal.coefficients[i] += s.coefficients[i];
153     }
154     return retVal;
155 }
156
157 CoefficientSpectrum operator-(const CoefficientSpectrum&s) const {
158     CoefficientSpectrum retVal = *this;
159     for (int i = 0; i < nSamples; i++) {
160         retVal.coefficients[i] -= s.coefficients[i];
161     }
162     return retVal;
163 }
164
165 CoefficientSpectrum operator*(const CoefficientSpectrum&s) const {
166     CoefficientSpectrum retVal = *this;
167     for (int i = 0; i < nSamples; i++) {
168         retVal.coefficients[i] *= s.coefficients[i];
169     }
170     return retVal;
171 }
172
173 CoefficientSpectrum operator/(const CoefficientSpectrum&s) const {
174     CoefficientSpectrum retVal = *this;
175     for (int i = 0; i < nSamples; i++) {
176         retVal.coefficients[i] /= s.coefficients[i];    // NaN
177     }
178     return retVal;
179 }
180
181
182 CoefficientSpectrum& operator+=(const CoefficientSpectrum&s) {
183     for (int i = 0; i < nSamples; i++) {
184         this->coefficients[i] += s.coefficients[i];
185     }
186     return *this;
187 }
188
189 CoefficientSpectrum& operator-=(const CoefficientSpectrum&s) {
190     for (int i = 0; i < nSamples; i++) {
191         this->coefficients[i] -= s.coefficients[i];
192     }
193     return *this;
194 }
195
196 CoefficientSpectrum& operator*=(const CoefficientSpectrum&s) {
197     for (int i = 0; i < nSamples; i++) {
198         this->coefficients[i] *= s.coefficients[i];
199     }
200     return *this;
201 }
202
203 CoefficientSpectrum& operator/=(const CoefficientSpectrum&s) {
204     for (int i = 0; i < nSamples; i++) {
205         this->coefficients[i] /= s.coefficients[i];    // NaN
206     }
207     return *this;
208 }
209
210
211 CoefficientSpectrum operator*(double v) const {
212     CoefficientSpectrum retVal = *this;
213     for (int i = 0; i < nSamples; i++) {
214         retVal.coefficients[i] *= v;
215     }
216     return retVal;
217 }
218
219 CoefficientSpectrum operator/(double v) const {
220     CoefficientSpectrum retVal = *this;
221     for (int i = 0; i < nSamples; i++) {
222         retVal.coefficients[i] /= v;    // NaN
223     }

```

```

224     }
225     return retVal;
226 }
227
228 CoefficientSpectrum& operator*=(double v) {
229     for (int i = 0; i < nSamples; i++) {
230         this->coefficients[i] *= v;
231     }
232     return *this;
233 }
234
235 CoefficientSpectrum& operator/=(double v) {
236     for (int i = 0; i < nSamples; i++) {
237         this->coefficients[i] /= v; // NaN
238     }
239     return *this;
240 }
241
242 friend CoefficientSpectrum operator*(double v, const CoefficientSpectrum& s) {
243     return s * v;
244 }
245
246 friend CoefficientSpectrum sqrt(const CoefficientSpectrum& s) {
247     CoefficientSpectrum ret;
248     for (int i = 0; i < nSamples; i++)
249         ret[i] = std::sqrt(s[i]);
250     return ret;
251 }
252
253 friend CoefficientSpectrum pow(const CoefficientSpectrum& s, double e) {
254     CoefficientSpectrum ret;
255     for (int i = 0; i < nSamples; i++)
256         ret[i] = std::pow(s[i], e);
257     return ret;
258 }
259
260 friend CoefficientSpectrum exp(const CoefficientSpectrum& s) {
261     CoefficientSpectrum ret;
262     for (int i = 0; i < nSamples; i++)
263         ret[i] = std::exp(s[i]);
264     return ret;
265 }
266
267 bool isBlack() const {
268     for (int i = 0; i < nSamples; i++) {
269         if (coefficients[i] != 0.0)
270             return false;
271     }
272     return true;
273 }
274
275 bool hasNaN() const {
276     for (int i = 0; i < nSamples; i++)
277         if (std::isnan(coefficients[i]))
278             return true;
279     return false;
280 }
281
282 inline CoefficientSpectrum clamp(double low = 0.0, double high = DBL_MAX) const {
283     CoefficientSpectrum retVal;
284     for (int i = 0; i < nSamples; i++) {
285         retVal[i] = mathClamp(coefficients[i], low, high);
286     }
287     return retVal;
288 }
289
290 double sum() const {
291     double sum = 0;
292     for (int i = 0; i < nSamples; i++) {
293         sum += coefficients[i];
294     }
295     return sum;
296 }
297
298 double average() const {
299     return sum() / nSamples;
300 }
301
302 virtual XYZ3 toXYZ3() const {
303     //DEBUG this function should never be called.
304     return XYZ3(0.0);
305 }
306
307 };
308
309 struct SpectrumSample
310 {
311     double lambda;
312     double value;

```

```

315
316     SpectrumSample(double _lambda, double _value) {
317         lambda = _lambda;
318         value = _value;
319     }
320
322     bool operator>(const SpectrumSample& s) const {
323         return lambda > s.lambda;
324     }
325
327     bool operator<(const SpectrumSample& s) const {
328         return lambda < s.lambda;
329     }
330 };
331
333 class SampledSpectrum
334     : public CoefficientSpectrum<nSpectrumSamples>
335 {
336     // these spectrums should be calculated at compile time.
337     static SampledSpectrum X;
338     static SampledSpectrum Y;
339     static SampledSpectrum Z;
340
341     static SampledSpectrum rgbRef12SpectWhite;
342     static SampledSpectrum rgbRef12SpectCyan;
343     static SampledSpectrum rgbRef12SpectMagenta;
344     static SampledSpectrum rgbRef12SpectYellow;
345     static SampledSpectrum rgbRef12SpectRed;
346     static SampledSpectrum rgbRef12SpectGreen;
347     static SampledSpectrum rgbRef12SpectBlue;
348
349     static SampledSpectrum rgbIllum2SpectWhite;
350     static SampledSpectrum rgbIllum2SpectCyan;
351     static SampledSpectrum rgbIllum2SpectMagenta;
352     static SampledSpectrum rgbIllum2SpectYellow;
353     static SampledSpectrum rgbIllum2SpectRed;
354     static SampledSpectrum rgbIllum2SpectGreen;
355     static SampledSpectrum rgbIllum2SpectBlue;
356
357 public:
358     friend class RGB3;
359     friend class XYZ3;
360
362     static void init();
363
364     SampledSpectrum();
365
366     SampledSpectrum(double val);
367
368     SampledSpectrum(const CoefficientSpectrum& s);
369
371     static SampledSpectrum fromSampled(std::vector<SpectrumSample> v);
372
373     virtual XYZ3 toXYZ3() const override;
374 };
375
377 class RGBSpectrum : public CoefficientSpectrum<3>
378 {
379     // TODO RGBSpectrum
380 };

```

## 9.6 /mnt/renderer/Zero/src/CoreLayer/Geometry/BoundingBox.cpp File Reference

Bounding box impl.

```
#include "BoundingBox.h"
```

### 9.6.1 Detailed Description

Bounding box impl.

**Author**

orbitchen

**Version**

0.1

**Date**

2022-05-07

**Copyright**

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## 9.7 /mnt/renderer/Zero/src/CoreLayer/Geometry/BoundingBox.h File Reference

Bounding box declaration.

```
#include "Geometry.h"
#include "CoreLayer/Ray/Ray.h"
#include <optional>
#include <algorithm>
#include <limits>
```

### Classes

- class [BoundingBox3< BaseType >](#)  
*Axis-aligned bounding box 3D base type, the box edges are mutually perpendicular and aligned to axes.*

### Functions

- `template<typename BaseType >`  
static [BoundingBox3< BaseType >](#) [BoundingBoxUnion](#) (const [BoundingBox3< BaseType >](#) &b1, const [BoundingBox3< BaseType >](#) &b2)  
*Union of two bounding boxes.*
- `template<typename BaseType >`  
static [BoundingBox3< BaseType >](#) [BoundingBoxUnionIntersect](#) (const [BoundingBox3< BaseType >](#) &b1, const [BoundingBox3< BaseType >](#) &b2)  
*Overlap of two bounding boxes.*

### 9.7.1 Detailed Description

Bounding box declaration.

#### Author

orbitchen

#### Version

0.1

#### Date

2022-04-30

#### Copyright

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### 9.7.2 Function Documentation

#### 9.7.2.1 BoundingBoxUnion()

```
template<typename BaseType >
static BoundingBox3< BaseType > BoundingBoxUnion (
    const BoundingBox3< BaseType > & b1,
    const BoundingBox3< BaseType > & b2 ) [static]
```

Union of two bounding boxes.

#### Returns

The smallest bounding box that bounds both b1 and b2.

#### 9.7.2.2 BoundingBoxUnionIntersect()

```
template<typename BaseType >
static BoundingBox3< BaseType > BoundingBoxUnionIntersect (
    const BoundingBox3< BaseType > & b1,
    const BoundingBox3< BaseType > & b2 ) [static]
```

Overlap of two bounding boxes.

#### Returns

The largest bounding box that bounded by both b1 and b2.

**Todo** The function name "BoundingBoxOverlap" might better

## 9.8 BoundingBox.h

[Go to the documentation of this file.](#)

```

1
12 #pragma once
13
14 #include "Geometry.h"
15 #include "CoreLayer/Ray/Ray.h"
16 #include <optional>
17 #include <algorithm>
18 #include <limits>
19
25 template <typename BaseType>
26 class BoundingBox3
27 {
28 public:
29     TPoint3<BaseType> pMin;
30     TPoint3<BaseType> pMax;
31
32     BoundingBox3() {
33         pMin[0] = pMin[1] = pMin[2] = std::numeric_limits<BaseType>::max();
34         pMax[0] = pMax[1] = pMax[2] = std::numeric_limits<BaseType>::min();
35     };
36
37     BoundingBox3(TPoint3<BaseType> _p)
38     {
39         pMin = pMax = _p;
40     }
41     BoundingBox3(TPoint3<BaseType> _pMin, TPoint3<BaseType> _pMax)
42     {
43         pMin = _pMin;
44         pMax = _pMax;
45     }
46
47     std::optional<Point2d> Intersection(const Ray& r) {
48         double t0 = 0, t1 = DBL_MAX;
49         for (int i = 0; i < 3; i++) {
50             double inv = 1.0 / r.direction[i];
51             double tNear = (pMin[i] - r.origin[i]) * inv;
52             double tFar = (pMax[i] - r.origin[i]) * inv;
53             if (tNear > tFar) std::swap(tNear, tFar);
54             if (t0 < tNear) t0 = tNear;
55             if (t1 > tFar) t1 = tFar;
56         }
57         if (t0 > t1) return std::nullopt;
58         return std::make_optional(Point2d(t0, t1));
59     }
60
61     double SurfaceArea() {
62         double x = pMax[0] - pMin[0];
63         double y = pMax[1] - pMin[1];
64         double z = pMax[2] - pMin[2];
65         return 2 * (x * y + x * z + y * z);
66     }
67 };
68
69 template <typename BaseType>
70 static BoundingBox3<BaseType> BoundingBoxUnion(const BoundingBox3<BaseType>& b1,
71                                                const BoundingBox3<BaseType>& b2)
72 {
73     TPoint3<BaseType> _pMin(std::min(b1.pMin[0], b2.pMin[0]), std::min(b1.pMin[1], b2.pMin[1]),
74                             std::min(b1.pMin[2], b2.pMin[2]));
75     TPoint3<BaseType> _pMax(std::max(b1.pMax[0], b2.pMax[0]), std::max(b1.pMax[1], b2.pMax[1]),
76                             std::max(b1.pMax[2], b2.pMax[2]));
77     return BoundingBox3(_pMin, _pMax);
78 }
79
80 template <typename BaseType>
81 static BoundingBox3<BaseType> BoundingBoxUnionIntersect(const BoundingBox3<BaseType>& b1,
82                                                         const BoundingBox3<BaseType>& b2)
83 {
84     TPoint3<BaseType> _pMin(std::max(b1.pMin[0], b2.pMin[0]), std::max(b1.pMin[1], b2.pMin[1]),
85                             std::max(b1.pMin[2], b2.pMin[2]));
86     TPoint3<BaseType> _pMax(std::min(b1.pMax[0], b2.pMax[0]), std::min(b1.pMax[1], b2.pMax[1]),
87                             std::min(b1.pMax[2], b2.pMax[2]));
88     return BoundingBox3(_pMin, _pMax);
89 }
90
91 using BoundingBox3f = BoundingBox3<double>;

```



## 9.9 /mnt/enderer/Zero/src/CoreLayer/Geometry/CoordConvertor.cpp File Reference

Provide convertor between standard coordinates.

```
#include "CoordConvertor.h"  
#include <cmath>
```

### 9.9.1 Detailed Description

Provide convertor between standard coordinates.

#### Author

Zhimin Fan

#### Version

0.1

#### Date

2022-05-27

#### Copyright

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## 9.10 /mnt/enderer/Zero/src/CoreLayer/Geometry/CoordConvertor.h File Reference

Provide convertor between standard coordinates.

```
#include "Geometry.h"
```

### Classes

- class [CoordConvertor](#)  
*Provides transformations between different coordinate systems.*

### 9.10.1 Detailed Description

Provide convertor between standard coordinates.

**Author**

Zhimin Fan

**Version**

0.1

**Date**

2022-05-27

**Copyright**

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## 9.11 CoordConvertor.h

[Go to the documentation of this file.](#)

```
1
13 #include "Geometry.h"
14
18 class CoordConvertor
19 {
20 public:
25     static Point3d cartesian2Spherical(const Point2d &p);
26
28     static Vec3d cartesian2SphericalVec(const Point2d &p);
29
30     static Vec3d world2TBN(const Vec3d &v, const Vec3d &t, const Vec3d &b, const Vec3d &n);
31
32     static Vec3d TBN2World(const Vec3d &v, const Vec3d &t, const Vec3d &b, const Vec3d &n);
33 };
```

## 9.12 /mnt/renderer/Zero/src/CoreLayer/Geometry/Frame.h File Reference

```
#include "Geometry.h"
#include "CoreLayer/Math/Common.h"
```

### 9.12.1 Detailed Description

**Author**

Junping Yuan

**Version**

0.1

**Date**

2022/06/06

**Copyright**

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## 9.13 Frame.h

[Go to the documentation of this file.](#)

```

1 //
2 // Created by yjp on 2022/6/6.
3 //
4
16 #pragma once
17
18 #include "Geometry.h"
19 #include "CoreLayer/Math/Common.h"
20
21
22 static void coordinateSystem(const Normal3d &a, Vec3d &b, Vec3d &c) {
23     if (std::abs(a.x) > std::abs(a.y)) {
24         float invLen = 1.0f / std::sqrt(a.x * a.x + a.z * a.z);
25         c = Vec3d(a.z * invLen, 0.0f, -a.x * invLen);
26     } else {
27         float invLen = 1.0f / std::sqrt(a.y * a.y + a.z * a.z);
28         c = Vec3d(0.0f, a.z * invLen, -a.y * invLen);
29     }
30     Vec3d _a(a.x, a.y, a.z);
31     b = cross(_a, c);
32 }
33
34 struct Frame {
35     Vec3d s, t;
36     Normal3d n;
37
38     Frame() { }
39
40     Frame(const Vec3d &s, const Vec3d &t, const Normal3d &n)
41         : s(s), t(t), n(n) { }
42
43     Frame(const Vec3d &x, const Vec3d &y, const Vec3d &z)
44         : s(x), t(y), n(z.x, z.y, z.z) { }
45
46     Frame(const Normal3d n) : n(n) {
47         coordinateSystem(n, s, t);
48     }
49
50     Vec3d toLocal(const Vec3d &v) const {
51         return Vec3d(
52             dot(v, s), dot(v, t), dot(v, n)
53         );
54     }
55
56     Vec3d toWorld(const Vec3d &v) const {
57         return s * v.x + t * v.y + n * v.z;
58     }
59
60     static float cosTheta(const Vec3d &v) {
61         return v.z;
62     }
63
64     static float sinTheta(const Vec3d &v) {
65         float temp = sinTheta2(v);
66         if (temp <= 0.0f)
67             return 0.0f;
68         return std::sqrt(temp);
69     }
70
71     static float tanTheta(const Vec3d &v) {
72         float temp = 1 - v.z * v.z;
73         if (temp <= 0.0f)
74             return 0.0f;
75         return std::sqrt(temp) / v.z;
76     }
77
78     static float sinTheta2(const Vec3d &v) {
79         return 1.0f - v.z * v.z;
80     }
81
82     static float sinPhi(const Vec3d &v) {
83         float sinTheta = Frame::sinTheta(v);
84         if (sinTheta == 0.0f)
85             return 1.0f;
86         return clamp(v.y / sinTheta, -1.0f, 1.0f);
87     }
88
89     static float cosPhi(const Vec3d &v) {
90         float sinTheta = Frame::sinTheta(v);
91         if (sinTheta == 0.0f)
92             return 1.0f;
93         return clamp(v.x / sinTheta, -1.0f, 1.0f);
94     }
95
96
97
98
99
100
101
102
103
104
105
106
107
108
109
110
111

```

```
112     }
113
114     static float sinPhi2(const Vec3d &v) {
115         return clamp(v.y * v.y / sinTheta2(v), 0.0f, 1.0f);
116     }
117
118     static float cosPhi2(const Vec3d &v) {
119         return clamp(v.x * v.x / sinTheta2(v), 0.0f, 1.0f);
120     }
121
122     bool operator==(const Frame &frame) const {
123         return frame.s == s && frame.t == t && frame.n == n;
124     }
125
126     bool operator!=(const Frame &frame) const {
127         return !operator==(frame);
128     }
129 };
```

## 9.14 /mnt/renderer/Zero/src/CoreLayer/Geometry/Geometry.h File Reference

The geometry part of whole program, including vector, point and normal.

```
#include "normal.h"
#include "point.h"
#include "vector.h"
```

### 9.14.1 Detailed Description

The geometry part of whole program, including vector, point and normal.

#### Author

ZCX

#### Version

0.1

#### Date

2022-04-22

#### Copyright

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## 9.15 Geometry.h

[Go to the documentation of this file.](#)

```
1
12 #pragma once
13
14 #include "normal.h"
15 #include "point.h"
16 #include "vector.h"
17
18
19
20 // vector.h
21 template <typename T>
22 struct TVector2;
23 template <typename T>
24 struct TVector3;
25 using Vec2f = TVector2<float>;
26 using Vec2d = TVector2<double>;
27 using Vec2i = TVector2<int>;
28 using Vec3f = TVector3<float>;
29 using Vec3d = TVector3<double>;
30 using Vec3i = TVector3<int>;
31 // point.h
32 template <typename T>
33 struct TPoint2;
34 template <typename T>
35 struct TPoint3;
36 using Point2f = TPoint2<float>;
37 using Point2d = TPoint2<double>;
38 using Point2i = TPoint2<int>;
39 using Point3f = TPoint3<float>;
40 using Point3d = TPoint3<double>;
41 using Point3i = TPoint3<int>;
42 // normal.h
43 struct Normal3d;
```

## 9.16 /mnt/renderer/Zero/src/CoreLayer/Geometry/Matrix.cpp File Reference

Matrix impl.

```
#include "Matrix.h"
```

### 9.16.1 Detailed Description

Matrix impl.

**Author**

orbitchen

**Version**

0.1

**Date**

2022-05-10

**Copyright**

NJUMeta (c) 2022 www.njumeta.com

## 9.17 /mnt/renderer/Zero/src/CoreLayer/Geometry/Matrix.h File Reference

Matrix4x4 (Eigen backend) and TransformMatrix3D.

```
#include "Geometry.h"
#include "Eigen/Dense"
```

### 9.17.1 Detailed Description

Matrix4x4 (Eigen backend) and TransformMatrix3D.

#### Author

orbitchen

#### Version

0.2

#### Date

2022-05-10

#### Copyright

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## 9.18 Matrix.h

[Go to the documentation of this file.](#)

```
1
12 #pragma once
13
14 #include "Geometry.h"
15
16 #include "Eigen/Dense"
17
18 /*
19  * @brief Angle type. Providing convenient angle transformation between deg and rad.
20  */
21 class Angle
22 {
23     double deg;
24     double rad;
25
26 public:
27     enum class AngleType
28     {
29         ANGLE_DEG,
30         ANGLE_RAD
31     };
32     /*
33     * @brief init an angle.
34     * @param v value of angle, deg or rad.
35     * @param type the type of v.
36     */
37     Angle(double v, AngleType type);
38
39     double getDeg() const;
40
```

```

41     double getRad() const;
42 };
43
44 enum class EulerType
45 {
46     EULER_XYZ,
47     EULER_ZYX
48 };
49
50 // @brief a simple wrap of Eigen Matrix 4x4.
51 class Matrix4x4
52 {
53 private:
54
55     // @brief Eigen data. inaccessible from outside.
56     Eigen::Matrix4d matrix=Eigen::Matrix4d::Identity();
57
58     // @brief init from Eigen data. inaccessible from outside.
59     Matrix4x4(const Eigen::Matrix4d& _matrix);
60
61 public:
62
63     Matrix4x4();
64
65     Matrix4x4 operator*(const Matrix4x4& mat) const;
66
67     Vec3d operator*(const Vec3d& v) const;
68     Point3d operator*(const Point3d& p) const;
69     Normal3d operator*(const Normal3d& n) const;
70
71     // model
72     static Matrix4x4 translate(double x, double y, double z);
73     static Matrix4x4 scale(double x, double y, double z);
74     static Matrix4x4 scale(double ratio);
75     static Matrix4x4 rotateEuler(const Angle& x, const Angle& y, const Angle& z, EulerType type =
EulerType::EULER_XYZ);
76     static Matrix4x4 rotateQuaternion(double w, double x, double y, double z);
77     static Matrix4x4 rotateAxis(const Vec3d& axis, const Angle& angle);
78
79     // view & projection
80     static Matrix4x4 lookAt(const Point3d& lookFrom, const Vec3d& vecLookAt, const Vec3d& up);
81     static Matrix4x4 orthographic(double left,double right,double up,double down,double near,double far);
82     static Matrix4x4 perspective(const Angle& fov,double aspect, double near, double far);
83
84     Matrix4x4 inverse();
85     Matrix4x4 transpose();
86
87     friend void printMatrix(const Matrix4x4 &mat);
88 };
89
90 /*
91 * @brief Encapsulated transform matrix. By default, it will be initialized as identity matrix.
92 */
93 class TransformMatrix3D
94 {
95     // @brief the matrix that applies rotate, scale and translate.
96     Matrix4x4 matrixAll;
97
98     Matrix4x4 matrixRotate;
99     Matrix4x4 matrixScale;
100     Matrix4x4 matrixTranslate;
101
102     // @brief true iff matrixAll!=matrixTranslate*matrixScale*matrixRotate.
103     bool dirty;
104
105     void update();
106
107 public:
108     TransformMatrix3D();
109
110     void setTranslate(double x, double y, double z);
111
112     void setScale(double x, double y, double z);
113     void setScale(double ratio);
114
115     void setRotateEuler(const Angle& x, const Angle& y, const Angle& z, EulerType type =
EulerType::EULER_XYZ);
116
117     void setRotateQuaternion(double w, double x, double y, double z);
118
119     // @brief Rotate by axis. Counterclockwise rotate.
120     void setRotateAxis(const Vec3d& axis, const Angle& angle);
121
122     Vec3d operator*(const Vec3d &v);
123     Point3d operator*(const Point3d &p);
124     Normal3d operator*(const Normal3d &n);
125 };

```

```
126
127 // TODO TransformMatrix2D
```

## 9.19 /mnt/renderer/Zero/src/CoreLayer/Geometry/normal.h File Reference

```
#include "vector.h"
```

### 9.19.1 Detailed Description

#### Author

ZCX

#### Version

0.1

#### Date

2022-04-22

#### Copyright

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## 9.20 normal.h

[Go to the documentation of this file.](#)

```
1
13 #pragma once
14 #include "vector.h"
15
16 struct Normal3d : public TVector3<double> {
17
18     Normal3d() { }
19
20     Normal3d (const TVector3<double> &v) : TVector3<double>(normalize(v)) { }
21
22     Normal3d (double _x, double _y, double _z) : Normal3d(TVector3<double> {_x, _y, _z}) { }
23
24
25 };
```

## 9.21 /mnt/renderer/Zero/src/CoreLayer/Geometry/point.h File Reference

```
#include "vector.h"
```



### 9.21.1 Detailed Description

#### Author

ZCX

#### Version

0.1

#### Date

2022-04-22

#### Copyright

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## 9.22 point.h

[Go to the documentation of this file.](#)

```

1
12 #pragma once
13 #include "vector.h"
14
15 template <typename T>
16 struct TPoint2 {
17     /*--- data field ---*/
18     T x, y;
19
20     /*--- constructor ---*/
21     TPoint2() { }
22
23     TPoint2(T _x, T _y) : x(_x), y(_y) { }
24
25     explicit TPoint2(T t) : x(t), y(t) { }
26
27     /*--- operator overloading ---*/
28     TPoint2 operator+(const TVector2<T> &rhs) const {
29         return TPoint2(x+rhs.x, y+rhs.y);
30     }
31
32     TPoint2 operator+(const TPoint2<T> &rhs) const {
33         return TPoint2(x + rhs.x, y + rhs.y);
34     }
35
36     TPoint2& operator+=(const TVector2<T> &rhs) {
37         x += rhs.x, y += rhs.y;
38         return *this;
39     }
40
41     TPoint2 operator-(const TVector2<T> &rhs) const {
42         return TPoint2(x-rhs.x, y-rhs.y);
43     }
44
45     TVector2<T> operator-(const TPoint2<T> &rhs) const {
46         return TVector2(x - rhs.x, y - rhs.y);
47     }
48
49     TPoint2& operator-=(const TVector2<T> &rhs) {
50         x -= rhs.x, y -= rhs.y;
51         return *this;
52     }
53
54     TPoint2 operator*(T t) const {
55         return TPoint2(x*t, y*t);
56     }
57
58     TPoint2& operator*=(T t) {
59         x *= t, y *= t;

```

```

60         return *this;
61     }
62
63     TPoint2 operator/(T t) const {
64         assert(t != 0);
65         T recip = (T) 1 / t;
66         return TPoint2(x*recip, y*recip);
67     }
68
69     TPoint2& operator/=(T t) {
70         assert(t != 0);
71         T recip = (T) 1 / t;
72         x *= recip, y *= recip;
73         return *this;
74     }
75
76     TPoint2 operator-() const {
77         return TPoint2(-x, -y);
78     }
79
80     bool operator==(const TPoint2 &rhs) const {
81         return x==rhs.x && y==rhs.y;
82     }
83
84     bool operator!=(const TPoint2 &rhs) const {
85         return x!=rhs.x || y!=rhs.y;
86     }
87
88     T operator[] (int i) const {
89         return (&x)[i];
90     }
91
92     T& operator[] (int i) {
93         return (&x)[i];
94     }
95
96     bool isZero() const {
97         return x==0 && y==0;
98     }
99 };
100
101 template <typename T>
102 std::ostream& operator<<(std::ostream &os, const TPoint2<T> &p) {
103     os << p.x << " " << p.y;
104     return os;
105 }
106
107 template <typename T>
108 TPoint2<T> operator*(T t, const TPoint2<T> &v) {
109     return TPoint2(t*v.x, t*v.y);
110 }
111
112 template<>
113 inline TPoint2<int> TPoint2<int>::operator/(int i) const {
114     assert(i!=0);
115     return TPoint2<int>(x/i, y/i);
116 }
117
118 template<>
119 inline TPoint2<int>& TPoint2<int>::operator/=(int i) {
120     assert(i!=0);
121     x/=i, y/=i;
122     return *this;
123 }
124
125
126 template <typename T>
127 struct TPoint3 {
128     /*--- data field ---*/
129     T x, y, z;
130
131     /*--- constructor ---*/
132     TPoint3() { }
133
134     TPoint3(T _x, T _y, T _z) : x(_x), y(_y), z(_z) { }
135
136     explicit TPoint3(T t) : x(t), y(t), z(t) { }
137
138     /*--- operator overloading ---*/
139     TPoint3 operator+(const TVector3<T> &rhs) const {
140         return TPoint3(x+rhs.x, y+rhs.y, z+rhs.z);
141     }
142
143     TPoint3 operator+(const TPoint3<T>& rhs) const {
144         return TPoint3(x + rhs.x, y + rhs.y, z + rhs.z);
145     }
146

```

```

147     TPoint3& operator+=(const TVector3<T> &rhs) {
148         x += rhs.x, y += rhs.y, z += rhs.z;
149         return *this;
150     }
151
152     TPoint3 operator-(const TVector3<T> &rhs) const {
153         return TPoint3(x-rhs.x, y-rhs.y, z-rhs.z);
154     }
155
156     TVector3<T> operator-(const TPoint3<T> &rhs) const {
157         return TVector3<T>(x-rhs.x, y-rhs.y, z-rhs.z);
158     }
159
160     TPoint3& operator-=(const TVector3<T> &rhs) {
161         x -= rhs.x, y -= rhs.y, z -= rhs.z;
162         return *this;
163     }
164
165     TPoint3 operator*(T t) const {
166         return TPoint3(x*t, y*t, z*t);
167     }
168
169     TPoint3& operator*=(T t) {
170         x *= t, y *= t, z *= t;
171         return *this;
172     }
173
174     TPoint3 operator/(T t) const {
175         assert(t != 0);
176         T recip = (T) 1 / t;
177         return TPoint3(x*recip, y*recip, z*recip);
178     }
179
180     TPoint3& operator/=(T t) {
181         assert(t != 0);
182         T recip = (T) 1 / t;
183         x *= recip, y *= recip, z *= recip;
184         return *this;
185     }
186
187     TPoint3 operator-() const {
188         return TPoint3(-x, -y, -z);
189     }
190
191     bool operator==(const TPoint3 &rhs) const {
192         return x==rhs.x && y==rhs.y && z==rhs.z;
193     }
194
195     bool operator!=(const TPoint3 &rhs) const {
196         return x!=rhs.x || y!=rhs.y || z!=rhs.z;
197     }
198
199     T operator[] (int i) const {
200         return (&x)[i];
201     }
202
203     T& operator[] (int i) {
204         return (&x)[i];
205     }
206
207     bool isZero() const {
208         return x==0 && y==0 && z==0;
209     }
210 };
211
212 template <typename T>
213 std::ostream& operator<<(std::ostream &os, const TPoint3<T> &p) {
214     os << p.x << " " << p.y << " " << p.z;
215     return os;
216 }
217
218 template <typename T>
219 TPoint3<T> operator*(T t, const TPoint3<T> &v) {
220     return TPoint3(t*v.x, t*v.y, t*v.z);
221 }
222
223 template<>
224 inline TPoint3<int> TPoint3<int>::operator/(int i) const {
225     assert(i!=0);
226     return TPoint3<int>(x/i, y/i, z/i);
227 }
228
229 template<>
230 inline TPoint3<int>& TPoint3<int>::operator/=(int i) {
231     assert(i!=0);
232     x/=i, y/=i, z/=i;
233     return *this;

```

```
234 }
```

## 9.23 /mnt/renderzer/Zero/src/CoreLayer/Geometry/Transform3d.cpp File Reference

3d transformation representation impl.

```
#include "Transform3d.h"
```

### 9.23.1 Detailed Description

3d transformation representation impl.

#### Author

Zhimin Fan

#### Version

0.1

#### Date

2022-05-20

#### Copyright

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## 9.24 /mnt/renderzer/Zero/src/CoreLayer/Geometry/Transform3d.h File Reference

3d transformation representation. More like an interface: be inherited means that the inheriting class supports 3d transformation.

```
#include "Geometry.h"  
#include "Matrix.h"  
#include <memory>
```

### 9.24.1 Detailed Description

3d transformation representation. More like an interface: be inherited means that the inheriting class supports 3d transformation.

#### Author

orbitchen

#### Version

0.1

#### Date

2022-04-30

#### Copyright

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## 9.25 Transform3d.h

[Go to the documentation of this file.](#)

```

1
2 #pragma once
3
4 #include "Geometry.h"
5 #include "Matrix.h"
6
7 #include <memory>
8
9 class Transform3D
10 {
11
12     std::shared_ptr<TransformMatrix3D> matrix;
13
14     bool isDone = false;
15
16 protected:
17     // apply matrix to this object. Cache should be managed locally.
18     virtual void apply() = 0;
19
20 public:
21     Transform3D();
22
23     Transform3D(std::shared_ptr<Transform3D> _matrix);
24
25     void setTranslate(double x, double y, double z);
26
27     void setScale(double x, double y, double z);
28     void setScale(double ratio);
29
30     void setRotateEuler(Angle x, Angle y, Angle z, EulerType type = EulerType::EULER_XYZ);
31
32     void setRotateQuaternion(double w, double x, double y, double z);
33
34     // @brief Rotate by axis. Counterclockwise rotate.
35     void setRotateAxis(Angle angle, Vec3d axis);
36
37     // @brief inform this object that transform setting is DONE and 'you' can apply all transformation
38     // without redundant calculation. apply() should be called within.
39     void done();
40
41     Point3d getTranslate();
42 };

```

## 9.26 /mnt/renderer/Zero/src/CoreLayer/Geometry/vector.h File Reference

Template class for vector.

```
#include <assert.h>
#include <cmath>
#include <iostream>
```

### Functions

- `template<typename T >`  
`TVector3< T > cross (const TVector3< T > &v1, const TVector3< T > &v2)`  
*Only 3 deminsion vector can do this operation.*

### 9.26.1 Detailed Description

Template class for vector.

#### Author

ZCX

#### Version

0.1

#### Date

2022-04-22

#### Copyright

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### 9.26.2 Function Documentation

#### 9.26.2.1 cross()

```
template<typename T >
TVector3< T > cross (
    const TVector3< T > & v1,
    const TVector3< T > & v2 )
```

Only 3 deminsion vector can do this operation.

## Template Parameters

$T$	
-----	--

## Parameters

$v1$	
$v2$	

## Returns

$\text{TVector3}<T>$

## 9.27 vector.h

[Go to the documentation of this file.](#)

```

1
12 #pragma once
13 #include <assert.h>
14 #include <cmath>
15 #include <iostream>
16
17 template <typename T>
18 struct TVector2 {
19
20     /*---data field---*/
21     T x, y;
22
23     /*---constructor---*/
24     TVector2() { }
25
26     TVector2(T _x, T _y) : x(_x), y(_y) { }
27
28     explicit TVector2(T t) : x(t), y(t) { }
29
30     /*---operator overloading---*/
31     TVector2 operator+(const TVector2 &rhs) const {
32         return TVector2(x + rhs.x, y + rhs.y);
33     }
34
35     TVector2& operator+=(const TVector2 &rhs) {
36         x += rhs.x, y += rhs.y;
37         return *this;
38     }
39
40     TVector2 operator-(const TVector2 &rhs) const {
41         return TVector2(x - rhs.x, y - rhs.y);
42     }
43
44     TVector2& operator-=(const TVector2 &rhs) {
45         x -= rhs.x, y -= rhs.y;
46         return *this;
47     }
48
49     TVector2 operator*(const T t) const {
50         return TVector2(x * t, y * t);
51     }
52
53     TVector2& operator*=(const T t) {
54         x *= t, y *= t;
55         return *this;
56     }
57
58     TVector2 operator/(T t) const {
59         assert(t != 0);
60         T recip = (T) 1 / t;
61         return TVector2(x * recip, y * recip);
62     }
63
64     TVector2& operator/=(T t) {
65         assert(t != 0);
66         T recip = (T) 1/t;

```

```

67         x *= recip, y *= recip;
68         return *this;
69     }
70
71     TVector2 operator-() const {
72         return TVector2(-x, -y);
73     }
74
75     T operator[](int i) const {
76         return (&x)[i];
77     }
78
79     T& operator[](int i) {
80         return (&x)[i];
81     }
82
83     decltype(auto) length2() const {
84         return x * x + y * y;
85     }
86
87     decltype(auto) length() const {
88         return std::sqrt(x*x + y*y);
89     }
90
91     bool operator==(const TVector2 &rhs) const {
92         return x==rhs.x && y==rhs.y;
93     }
94
95     bool operator!=(const TVector2 &rhs) const {
96         return x!=rhs.x || y!=rhs.y;
97     }
98
99     bool isZero() const {
100         return x==0 && y==0;
101     }
102
103 };
104
105 template <typename T>
106 std::ostream& operator<<(std::ostream& os, const TVector2<T> &v) {
107     os << v.x << " " << v.y ;
108     return os;
109 }
110
111 template <typename T>
112 TVector2<T> operator*(T t, const TVector2<T> &v) {
113     return TVector2<T>(v.x * t, v.y * t);
114 }
115
116 template <typename T>
117 decltype(auto) dot(const TVector2<T> &v1, const TVector2<T> &v2) {
118     return v1.x*v2.x + v1.y * v2.y;
119 }
120
121 template <typename T>
122 decltype(auto) absDot(const TVector2<T> &v1, const TVector2<T> &v2) {
123     return std::abs(v1.x*v2.x + v1.y * v2.y);
124 }
125
126 template <typename T>
127 TVector2<double> normalize(const TVector2<T> &v) {
128     double recip = 1.0f / v.length();
129     return TVector2<double> (v.x * recip, v.y * recip);
130 }
131
132 template<>
133 inline TVector2<int> TVector2<int>::operator/(int i) const {
134     assert(i != 0);
135     return TVector2<int>(x/i, y/i);
136 }
137
138 template<>
139 inline TVector2<int>& TVector2<int>::operator/=(int i) {
140     assert(i != 0);
141     x/=i, y/=i;
142     return *this;
143 }
144
145
146
147 template <typename T>
148 struct TVector3 {
149     /*--- data field ---*/
150     T x, y, z;
151
152     /*--- constructor ---*/
153     TVector3 () { }

```



```

154
155     TVector3 (T _x, T _y, T _z) : x(_x), y(_y), z(_z) { }
156
157     explicit TVector3 (T t) : x(t), y(t), z(t) { }
158
159     /*--- operator overloading ---*/
160     TVector3 operator+(const TVector3 &rhs) const {
161         return TVector3(x + rhs.x, y + rhs.y, z + rhs.z);
162     }
163
164     TVector3& operator+=(const TVector3 &rhs) {
165         x += rhs.x, y += rhs.y, z += rhs.z;
166         return *this;
167     }
168
169     TVector3 operator-(const TVector3 &rhs) const {
170         return TVector3(x-rhs.x, y-rhs.y, z-rhs.z);
171     }
172
173     TVector3& operator-=(const TVector3 &rhs) {
174         x -= rhs.x, y -= rhs.y, z -= rhs.z;
175         return *this;
176     }
177
178     TVector3 operator*(const T t) const {
179         return TVector3(x*t, y*t, z*t);
180     }
181
182     TVector3& operator*=(const T t) {
183         x*=t, y*=t, z*=t;
184         return *this;
185     }
186
187     TVector3 operator/(const T t) const {
188         assert(t != 0);
189         T recip = (T) 1/t;
190         return TVector3(x*recip, y*recip, z*recip);
191     }
192
193     TVector3& operator/=(const T t) {
194         assert(t != 0);
195         T recip = (T) 1/t;
196         x*=recip, y*=recip, z*=recip;
197         return *this;
198     }
199
200     TVector3 operator-() const {
201         return TVector3(-x, -y, -z);
202     }
203
204     T operator[](const int i) const {
205         return (&x)[i];
206     }
207
208     T& operator[](const int i) {
209         return (&x)[i];
210     }
211
212     decltype(auto) length2() const {
213         return x*x + y*y + z*z;
214     }
215
216     decltype(auto) length() const {
217         return std::sqrt(x*x + y*y + z*z);
218     }
219
220     bool operator==(const TVector3 &rhs) const {
221         return x==rhs.x && y==rhs.y && z==rhs.z;
222     }
223
224     bool operator!=(const TVector3 &rhs) const {
225         return x!=rhs.x || y!=rhs.y || z!=rhs.z;
226     }
227
228     bool isZero() const {
229         return x==0 && y==0 && z==0;
230     }
231 };
232
233 template <typename T>
234 std::ostream& operator<<(std::ostream &os, const TVector3<T> &v) {
235     os << v.x << " " << v.y << " " << v.z;
236     return os;
237 }
238
239 template <typename T>
240 TVector3<T> operator*(T t, const TVector3<T> &v) {

```

```

241     return TVector3<T>(v.x*t, v.y*t, v.z*t);
242 }
243
244 template <typename T>
245 decltype(auto) dot(const TVector3<T> &v1, const TVector3<T> &v2) {
246     return v1.x * v2.x + v1.y * v2.y + v1.z * v2.z;
247 }
248
249 template <typename T>
250 decltype(auto) absDot(const TVector3<T> &v1, const TVector3<T> &v2) {
251     return std::abs(v1.x * v2.x + v1.y * v2.y + v1.z * v2.z);
252 }
253
254 template <typename T>
255 TVector3<double> normalize(const TVector3<T> &v) {
256     double recip = 1.0f / v.length();
257     return TVector3<double>(v.x * recip, v.y * recip, v.z * recip);
258 }
259
260 template <typename T>
261 TVector3<T> cross(const TVector3<T> &v1, const TVector3<T> &v2) {
262     return TVector3<T> (
263         v1.y * v2.z - v1.z * v2.y,
264         v1.z * v2.x - v1.x * v2.z,
265         v1.x * v2.y - v1.y * v2.x
266     );
267 }
268
269
270
271
272
273
274
275
276
277
278
279

```

## 9.28 /mnt/renderer/Zero/src/CoreLayer/Math/Common.h File Reference

some common but useful functions

```

#include <cmath>
#include <limits>
#include <utility>

```

### Functions

- float **clamp** (float value, float min, float max)  
*Simple floating point clamping function.*
- int **clamp** (int value, int min, int max)  
*Simple integer clamping function.*
- float **lerp** (float t, float v1, float v2)  
*Linearly interpolate between two values.*
- int **mod** (int a, int b)  
*Always-positive modulo operation.*

### 9.28.1 Detailed Description

some common but useful functions

Author

Junping Yuan

## Version

0.1

## Date

2022/06/06

## Copyright

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## 9.29 Common.h

[Go to the documentation of this file.](#)

```

1
13 #pragma once
14 #include <cmath>
15 #include <limits>
16 #include <utility>
17 // some constant values
18 #define M_PI      3.14159265358979323846f
19 #define INV_PI    0.31830988618379067154f
20 #define INV_TWOPI 0.15915494309189533577f
21
22 constexpr double ONEMINUSEPSILON = 1 - std::numeric_limits<double>::epsilon();
23
24 inline float clamp(float value, float min, float max) {
25     if (value < min)
26         return min;
27     else if (value > max)
28         return max;
29     else return value;
30 }
31
32 inline int clamp(int value, int min, int max) {
33     if (value < min)
34         return min;
35     else if (value > max)
36         return max;
37     else return value;
38 }
39
40 inline float lerp(float t, float v1, float v2) {
41     return ((float) 1 - t) * v1 + t * v2;
42 }
43
44 inline int mod(int a, int b) {
45     int r = a % b;
46     return (r < 0) ? r+b : r;
47 }
48
49 inline float fresnel(float cosThetaI, float extIOR, float intIOR) {
50     float etaI = extIOR, etaT = intIOR;
51
52     if (extIOR == intIOR)
53         return 0.0f;
54
55     /* Swap the indices of refraction if the interaction starts
56        at the inside of the object */
57     if (cosThetaI < 0.0f) {
58         std::swap(etaI, etaT);
59         cosThetaI = -cosThetaI;
60     }
61
62     /* Using Snell's law, calculate the squared sine of the
63        angle between the normal and the transmitted ray */
64     float eta = etaI / etaT,
65           sinThetaTSqr = eta*eta * (1-cosThetaI*cosThetaI);
66
67     if (sinThetaTSqr > 1.0f)
68         return 1.0f; /* Total internal reflection! */
69
70     float cosThetaT = std::sqrt(1.0f - sinThetaTSqr);
71

```

```

76     float Rs = (etaI * cosThetaI - etaT * cosThetaT)
77               / (etaI * cosThetaI + etaT * cosThetaT);
78     float Rp = (etaT * cosThetaI - etaI * cosThetaT)
79               / (etaT * cosThetaI + etaI * cosThetaT);
80
81     return (Rs * Rs + Rp * Rp) / 2.0f;
82 }
83
84 inline double fresnel(double cosThetaI, double extIOR, double intIOR) {
85     double etaI = extIOR, etaT = intIOR;
86
87     if (extIOR == intIOR)
88         return 0.0;
89
90     /* Swap the indices of refraction if the interaction starts
91        at the inside of the object */
92     if (cosThetaI < 0.0f) {
93         std::swap(etaI, etaT);
94         cosThetaI = -cosThetaI;
95     }
96
97     /* Using Snell's law, calculate the squared sine of the
98        angle between the normal and the transmitted ray */
99     double eta = etaI / etaT,
100        sinThetaTSqr = eta*eta * (1-cosThetaI*cosThetaI);
101
102     if (sinThetaTSqr > 1.0f)
103         return 1.0f; /* Total internal reflection! */
104
105     double cosThetaT = std::sqrt(1.0f - sinThetaTSqr);
106
107     double Rs = (etaI * cosThetaI - etaT * cosThetaT)
108               / (etaI * cosThetaI + etaT * cosThetaT);
109     double Rp = (etaT * cosThetaI - etaI * cosThetaT)
110               / (etaT * cosThetaI + etaI * cosThetaT);
111
112     return (Rs * Rs + Rp * Rp) / 2.0;
113 }
114
115
116
117
118
119
120

```

## 9.30 Warp.h

```

1  #include "CoreLayer/Geometry/Geometry.h"
2  #include "Common.h"
3
4  static double TentInverse(double x){
5      if(x<=.5f)
6          return std::sqrt(2*x)-1;
7      return 1- std::sqrt(2-2*x);
8  }
9  inline Point2d SquareToTent(const Point2d &sample) {
10     Point2d res(TentInverse(sample[0]), TentInverse(sample[1]));
11     return res;
12     // throw NoriException("SquareToTent() is not yet implemented!");
13 }
14
15 inline float SquareToTentPdf(const Point2d &p) {
16     return (1.0-abs(p[0])) * (1.0-abs(p[1]));
17 }
18
19
20 //Point2d SquareToUniformDisk(const Point2d &sample) {
21 //     auto phi=2*sample.x()*M_PI;
22 //     auto r=sqrt(sample.y());
23 //     return {r*cos(phi),r*sin(phi)};
24 //}
25 //
26 //float SquareToUniformDiskPdf(const Point2d &p) {
27 //     return < 1.f ? INV_PI : .0f;}
28
29 inline Vec3d SquareToUniformSphere(const Point2d &sample) {
30     float z = 1 - 2 * sample[0];
31     float r = std::sqrt(std::max((float)0, (float)1 - z * z));
32     float phi = 2 * M_PI * sample[1];
33     return {r * std::cos(phi), r * std::sin(phi), z};
34 }
35

```

```

36 inline float SquareToUniformSpherePdf(const Vec3d &v) {
37     return 0.25f*INV_PI;
38 }
39
40 inline Vec3d SquareToUniformHemisphere(const Point2d &sample) {
41     float z = 1 - 2 * sample[0];
42     float r = std::sqrt(std::max((float)0, (float)1 - z * z));
43     float phi = 2 * M_PI * sample[1];
44     return {r * std::cos(phi), r * std::sin(phi), abs(z)};
45 }
46
47 inline float SquareToUniformHemispherePdf(const Vec3d &v) {
48     return v[2] >=0 ? 0.5f * INV_PI : .0f;
49 }
50
51 inline Vec3d SquareToCosineHemisphere(const Point2d &sample) {
52     float z=sqrt(1-sample.x);
53     float phi=sample.y*2*M_PI;
54
55     return {sqrt(sample.x) * cos(phi), sqrt(sample.x)*sin(phi), z};
56 }
57
58 inline float SquareToCosineHemispherePdf(const Vec3d &v) {
59     return v[2] >=0 ? v.z * INV_PI : .0f;
60 }
61 //
62 inline Vec3d SquareToBeckmann(const Point2d &sample, double alpha) {
63     auto tan2theta= -alpha*alpha*log( sample.x );
64     auto cosTheta=sqrt(1/(1+tan2theta));
65     auto sinTheta= sqrt(1-cosTheta*cosTheta);
66     auto phi=sample.y * 2 * M_PI;
67     Vec3d t1= Vec3d(sinTheta*cos(phi), sinTheta*sin(phi), cosTheta);
68     return t1;
69 }
70 //
71 inline float SquareToBeckmannPdf(const Vec3d &m, double alpha) {
72     if(m.z<=0)
73         return 0.0f;
74     auto cosTheta=m.z;
75     auto sinTheta=sqrt(1-cosTheta*cosTheta);
76     auto tan2Theta=(sinTheta* sinTheta)/(cosTheta*cosTheta);
77     float azimuthal = INV_PI;
78     float longitudinal = exp(-tan2Theta/(alpha*alpha)) / (alpha*alpha*pow(cosTheta,3));
79     return azimuthal * longitudinal;
80 }

```

## 9.31 /mnt/renderer/Zero/src/CoreLayer/Ray/Ray.cpp File Reference

Ray implementation.

```
#include "Ray.h"
```

### 9.31.1 Detailed Description

Ray implementation.

#### Author

Zhimin Fan

#### Version

0.1

#### Date

2022-05-09

#### Copyright

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## 9.32 /mnt/renderer/Zero/src/CoreLayer/Ray/Ray.h File Reference

Ray representation.

```
#include <memory>
#include "CoreLayer/Geometry/Geometry.h"
#include "FunctionLayer/Medium/Medium.h"
#include <cfloat>
```

### 9.32.1 Detailed Description

Ray representation.

#### Author

orbitchen

#### Version

0.1

#### Date

2022-04-30

#### Copyright

NJUMeta (c) 2022 www.njumeta.com

## 9.33 Ray.h

[Go to the documentation of this file.](#)

```
1
12 #pragma once
13
14 // #include "../core.h"
15 #include <memory>
16 #include "CoreLayer/Geometry/Geometry.h"
17 #include "FunctionLayer/Medium/Medium.h"
18 #include <cfloat>
19 struct Ray
20 {
21     Point3d origin;
22     Vec3d direction;
23
24     double timeMin;
25     double timeMax;
26
27     std::shared_ptr<Medium> medium;
28
29     Point3d at(double t);
30
31     bool withinTime(double time);
32
33     Ray(const Point3d &_origin, const Vec3d &_direction, double _timeMin = .0f, double _timeMax =
        DBL_MAX);
34 };
35
36 struct RayDifferential : public Ray
37 {
38     Point3d origin_x, origin_y;
39     Vec3d direction_x, direction_y;
40 };
```

## 9.34 /mnt/enderer/Zero/src/CoreLayer/Scene/Scene.cpp File Reference

Scene implementation.

```
#include "Scene.h"
```

### 9.34.1 Detailed Description

Scene implementation.

**Author**

Zhimin Fan

**Version**

0.1

**Date**

2022-05-31

**Copyright**

NJUMeta (c) 2022 www.njumeta.com

## 9.35 /mnt/enderer/Zero/src/CoreLayer/Scene/Scene.h File Reference

Scene representation. Handle ray intersection.

```
#include "CoreLayer/Ray/Ray.h"  
#include "FunctionLayer/Shape/Entity.h"  
#include "FunctionLayer/Aggregate/Bvh.h"  
#include "FunctionLayer/Intersection.h"  
#include "FunctionLayer/Light/Light.h"  
#include <optional>
```

### 9.35.1 Detailed Description

Scene representation. Handle ray intersection.

**Author**

orbitchen

**Version**

0.1

**Date**

2022-04-30

**Copyright**

NJUMeta (c) 2022 www.njumeta.com

## 9.36 Scene.h

[Go to the documentation of this file.](#)

```

1
12 #pragma once
13
14 #include "CoreLayer/Ray/Ray.h"
15 #include "FunctionLayer/Shape/Entity.h"
16 #include "FunctionLayer/Aggregate/Bvh.h"
17 #include "FunctionLayer/Intersection.h"
18 #include "FunctionLayer/Light/Light.h"
19
20 #include <optional>
21
22 class Scene
23 {
24     std::shared_ptr<Bvh> BVH;
25     std::shared_ptr<std::vector<std::shared_ptr<Light>>> lights;
26     std::shared_ptr<std::vector<std::shared_ptr<Entity>>> entities;
27
28 public:
29     Scene();
30     void addEntity(std::shared_ptr<Entity> object);
31     void addLight(std::shared_ptr<Light> light);
32
33     void build();
34     std::optional<Intersection> intersect(const Ray &r) const;
35
36     // @return true if r hits object first (closest), false otherwise.
37     bool intersectionTest(const Ray &r, std::shared_ptr<Entity> object) const;
38
39     std::shared_ptr<std::vector<std::shared_ptr<Light>>> getLights() const;
40 };

```

## 9.37 /mnt/renderrer/Zero/src/FunctionLayer/Aggregate/Bvh.h File Reference

BVH implementation.

```

#include "CoreLayer/Geometry/BoundingBox.h"
#include "FunctionLayer/Shape/Entity.h"
#include "FunctionLayer/Intersection.h"

```

### 9.37.1 Detailed Description

BVH implementation.

BVH declaration.

**Author**

Pengpei Hong

**Version**

0.1

**Date**

2022-06-30

**Copyright**

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## 9.38 Bvh.h

[Go to the documentation of this file.](#)

```

1
12 #pragma once
13
14 #include "CoreLayer/Geometry/BoundingBox.h"
15 #include "FunctionLayer/Shape/Entity.h"
16 #include "FunctionLayer/Intersection.h"
17
18 //@brief Entity information declaration for building BVH
19 struct EntityInfo {
20     EntityInfo(){}
21     EntityInfo(int _EntityId, const BoundingBox3f& _bounds): EntityId(_EntityId), bounds(_bounds),
        center(0.5 * (_bounds.pMin + _bounds.pMax)){}
22     int EntityId;
23     BoundingBox3f bounds;
24     Point3d center;
25 };
26
27 struct BvhTreeNode {
28     BoundingBox3f bounds;
29     std::shared_ptr<BvhTreeNode> children[2] = {nullptr, nullptr}; //0: left, 1: right
30     int splitAxis;
31     int nEntites = 0; //0: interior nodes, otherwise: leaf nodes
32     int entityOffset;
33 };
34
35 //@brief Bvh Nodes in Dfs-Order
36 struct LinearBvhNode {
37     BoundingBox3f bounds;
38     union
39     {
40         int firstdEntityOffset; //for leaves to enumerate
41         int secondChildOrder; //for interior nodes to traverse
42     };
43     int nEntites = 0;
44     int splitAxis;
45 };
46
47 struct Bvh {
48 public:
49     enum class SplitMethod{
50         SAH,
51         Middle,
52         EqualCounts
53     }; //not support LBBVH yet
54     const SplitMethod splitMethod;
55     std::vector<std::shared_ptr<Entity>> entites;
56     std::vector<LinearBvhNode> linearBvhNodes;
57
58     /*
59     * @brief Bvh constructor
60     * @param <_entites>
61     * @param <_SplitMeshod>
62     */
63     Bvh(std::vector<std::shared_ptr<Entity>>& _entites, SplitMethod _splitMethod = SplitMethod::SAH);
64
65     /*
66     * @brief recursively build BVH
67     * @return the root of BVH
68     */
69     std::shared_ptr<BvhTreeNode> RecursiveBuild(std::vector<EntityInfo>& entityInfo, int start, int end,
        int& nodeNumber, std::vector<std::shared_ptr<Entity>>& orderedEntites);
70
71     //@brief flatten the BVH to Dfs-Order
72     void Flatten(std::shared_ptr<BvhTreeNode> node, int& dfsOrder);
73
74     //@brief return the scene intersection
75     std::optional<Intersection> Intersect(const Ray& r);
76 };

```

## 9.39 /mnt/renderer/Zero/src/FunctionLayer/Camera/Camera.h File Reference

Different cameras. Need to be investigated.

```
#include "CoreLayer/Geometry/Geometry.h"
#include "CoreLayer/Ray/Ray.h"
```

### 9.39.1 Detailed Description

Different cameras. Need to be investigated.

#### Author

orbitchen

#### Version

0.1

#### Date

2022-04-30

#### Copyright

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## 9.40 Camera.h

[Go to the documentation of this file.](#)

```
1
12 #pragma once
13
14 #include "CoreLayer/Geometry/Geometry.h"
15 #include "CoreLayer/Ray/Ray.h"
16
17 struct CameraSample {
18     Point2d xy;
19     double time;
20     Point2d lens;
21 };
22
23 class Camera
24 {
25 public:
26
27     virtual Ray generateRay(const Point2i &filmResolution,
28                             const Point2i &pixelPosition,
29                             const CameraSample &sample) const = 0;
30 };
```

## 9.41 /mnt/renderer/Zero/src/FunctionLayer/Camera/Perspective.h File Reference

Abstract base class for all perspective camera.

```
#include "CoreLayer/Geometry/Matrix.h"
#include "Camera.h"
```

### 9.41.1 Detailed Description

Abstract base class for all perspective camera.

#### Author

Chenxi Zhou

#### Version

0.1

#### Date

2022-06-10

#### Copyright

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## 9.42 Perspective.h

[Go to the documentation of this file.](#)

```

1
12 #pragma once
13 #include "CoreLayer/Geometry/Matrix.h"
14 #include "Camera.h"
15
16 class PerspectiveCamera : public Camera {
17 protected:
18 public:
19     // TODO replace martrix with transform3d
20
21     //
22     //      [0, 0]-----> x
23     //      |           |
24     //      |-----+ [x, y]
25     //      |
26     //      y
27     Matrix4x4 cameraToWorld, sampleToFilm;
28
29 public:
30     PerspectiveCamera() = default;
31
32     PerspectiveCamera(
33         const Point3d &lookFrom,
34         const Point3d &lookAt,
35         const Vec3d &up,
36         double xFov,
37         double aspectRatio,
38         double distToFilm
39     )
40     {
41         cameraToWorld =
42             Matrix4x4::lookAt(lookFrom, lookAt - lookFrom, up).inverse();
43         // ! near is the distToFilm and far set to MAX_FLOAT
44         // ! if far set to MAX_DOUBLE, it will crash when computing the matrix
45         Matrix4x4 filmToSample = Matrix4x4::perspective(
46             Angle(xFov, Angle::AngleType::ANGLE_DEG),
47             aspectRatio,
48             distToFilm,
49             std::numeric_limits<float>::max()
50         );
51         sampleToFilm =
52             Matrix4x4::scale(0.5, -0.5, 1.0)
53             * Matrix4x4::translate(1, -1, 0)
54             * filmToSample;
55         sampleToFilm = sampleToFilm.inverse();
56     }
57 };

```

## 9.43 Pinhole.h

```

1 #pragma once
2
3 #include "Perspective.h"
4
5 class PinholeCamera : public PerspectiveCamera {
6 public:
7     PinholeCamera() = default;
8     PinholeCamera(
9         const Point3d &lookFrom,
10        const Point3d &lookAt,
11        const Vec3d &up,
12        double xFov,
13        double aspectRatio,
14        double distToFilm
15    ) : PerspectiveCamera(lookFrom, lookAt, up, xFov, aspectRatio, distToFilm) { }
16
17     virtual Ray generateRay(const Point2i &filmResolution,
18                            const Point2i &pixelPosition,
19                            const CameraSample &sample) const override;
20 };

```

## 9.44 Thinlens.h

```

1 #pragma once
2
3 #include "Perspective.h"
4
5 class ThinlensCamera : public PerspectiveCamera {
6 protected:
7     double apertureRadius, focalLen, focalDistance;
8 public:
9     ThinlensCamera() = default;
10    ThinlensCamera(
11        const Point3d &lookFrom,
12        const Point3d &lookAt,
13        const Vec3d &up,
14        double xFov,
15        double aspectRatio,
16        double _focaDistance,
17        double _apertureRadius = 0.1,
18        double _focallLen = 0.05
19    ) : apertureRadius(_apertureRadius), focalLen(_focallLen), focalDistance(_focaDistance) {
20        double distToFilm =
21            (_focallLen * _focaDistance) / (_focaDistance - _focallLen);
22
23        cameraToWorld =
24            Matrix4x4::lookAt(lookFrom, lookAt - lookFrom, up).inverse();
25        // ! near is the distToFilm and far set to MAX_FLOAT
26        // ! if far set to MAX_DOUBLE, it will crash when computing the matrix
27        Matrix4x4 filmToSample = Matrix4x4::perspective(
28            Angle(xFov, Angle::AngleType::ANGLE_DEG),
29            aspectRatio,
30            distToFilm,
31            std::numeric_limits<float>::max()
32        );
33        sampleToFilm =
34            Matrix4x4::scale(0.5, -0.5, 1.0)
35            * Matrix4x4::translate(1, -1, 0)
36            * filmToSample;
37        sampleToFilm = sampleToFilm.inverse();
38    }
39
40
41
42    virtual Ray generateRay(const Point2i &filmResolution,
43                           const Point2i &pixelPosition,
44                           const CameraSample &sample) const override;
45 };

```

## 9.45 /mnt/renderer/Zero/src/FunctionLayer/Film/Film.cpp File Reference

The class that records ray sampling results. Just like old camera exposures!

```

#include <fstream>
#include "Film.h"

```

### 9.45.1 Detailed Description

The class that records ray sampling results. Just like old camera exposures!

**Author**

Zhimin Fan

**Version**

0.1

**Date**

2022-05-31

**Copyright**

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## 9.46 /mnt/renderer/Zero/src/FunctionLayer/Film/Film.h File Reference

The class that records ray sampling results. Just like old camera exposures!

```
#include "FunctionLayer/Filter/Filter.h"
#include "ResourceLayer/ResourceManager.h"
#include <memory>
```

### 9.46.1 Detailed Description

The class that records ray sampling results. Just like old camera exposures!

**Author**

orbitchen

**Version**

0.1

**Date**

2022-04-30

**Copyright**

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## 9.47 Film.h

[Go to the documentation of this file.](#)

```

1
12 #pragma once
13
14 #include "FunctionLayer/Filter/Filter.h"
15 #include "ResourceLayer/ResourceManager.h"
16 #include <memory>
17
18 class Film
19 {
20 protected:
21     std::unique_ptr<Image> image;
22     std::shared_ptr<Filter> filter;
23     Point2i resolution;
24     int channels;
25     std::vector<double> sumWeights; // a temp impl
26     std::vector<Spectrum> sumValues; // a temp impl
27
28     void syncWithGui();
29
30 public:
31     Film(Point2i resolution, int channels);
32     Film(Point3i shape);
33
34     Spectrum getSpectrum(const Point2i &p);
35     RGB3 getRGB(const Point2i &p);
36
37     void setGamma(double gamma = 2.2);
38     void setFilter(std::shared_ptr<Filter> filter);
39     Point2i getResolution() const;
40
41     // @brief: 'deposit' a spectrum at p. all deposit will be averaged when get(p).
42     void deposit(const Point2i &p, const Spectrum &s);
43     void save(const std::string &path);
44
45     int getDepositCount(const Point2i &p);
46 };

```

## 9.48 /mnt/renderer/Zero/src/FunctionLayer/Filter/Filter.h File Reference

Linear filters.

```
#include "CoreLayer/Geometry/Geometry.h"
```

### 9.48.1 Detailed Description

Linear filters.

#### Author

Zhimin Fan

#### Version

0.1

#### Date

2022-05-01

#### Copyright

NJUMeta (c) 2022 www.njumeta.com

## 9.49 Filter.h

[Go to the documentation of this file.](#)

```
1
12 #pragma once
13
14 #include "CoreLayer/Geometry/Geometry.h"
15
16 // ! Note that we cannot use any non-linear "filter" here, such as bilateral and etc
17
18 // @brief: Base class for linear filter used for film
19 class Filter
20 {
21 public:
22     virtual float eval(const Point2d &pos) = 0;
23
24     // @brief: also known as Kernel Size
25     virtual Point2d support() = 0;
26 };
27
```

## 9.50 /mnt/renderer/Zero/src/FunctionLayer/Integrator/AbstractPath↵ Integrator.cpp File Reference

Path Integrator Abstraction.

```
#include "AbstractPathIntegrator.h"
```

### 9.50.1 Detailed Description

Path Integrator Abstraction.

#### Author

Zhimin Fan

#### Version

0.1

#### Date

2022-05-16

#### Copyright

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## 9.51 /mnt/renderer/Zero/src/FunctionLayer/Integrator/AbstractPath↵ Integrator.h File Reference

Path Integrator Abstraction.

```
#include <cmath>
#include "CoreLayer/Ray/Ray.h"
#include "MonteCarloIntegrator.h"
```

### 9.51.1 Detailed Description

Path Integrator Abstraction.

#### Author

Zhimin Fan

#### Version

0.1

#### Date

2022-05-16

#### Copyright

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## 9.52 AbstractPathIntegrator.h

[Go to the documentation of this file.](#)

```

1
12 #pragma once
13
14 #include <cmath>
15 #include "CoreLayer/Ray/Ray.h"
16 #include "MonteCarloIntegrator.h"
17
18 struct PathIntegratorLocalRecord
19 {
20     Vec3d wi;
21     Spectrum f;
22     double pdf;
23     bool isDelta = false;
24 };
25
26 class AbstractPathIntegrator : public MonteCarloIntegrator
27 {
28 protected:
29     const int nDirectLightSamples = 1;
30     const double misWeightPower = 1.0f;
31
32 public:
33     AbstractPathIntegrator(
34         std::shared_ptr<Camera> _camera,
35         std::unique_ptr<Film> _film,
36         std::unique_ptr<TileGenerator> _tileGenerator,
37         std::shared_ptr<Sampler> _sampler,
38         int _spp,
39         int _renderThreadNum=4);
40
41     virtual Spectrum Li(const Ray &ray, std::shared_ptr<Scene> scene);
42     virtual double MISWeight(double x, double y);
43
44     /*****
45     Functions below need to be implemented in derived classes
46     *****/
47
48     // @brief Return the radiance along given ray, emitted from given intersection.
49     // @param scene      Ptr to scene.
50     // @param its         Intersection hit by ray.
51     // @param ray         Ray to evaluate.
52     // @return            Direction of given ray, incident radiance at origin of ray, pdf of direct light
53     //                    sampling.
54     virtual PathIntegratorLocalRecord evalEmittance(std::shared_ptr<Scene> scene,
55                                                     std::optional<Intersection> its,
```



```

55                                     const Ray &ray) = 0;
56
57 // @brief Sample incident direction of direct lighting.
58 // @param scene      Ptr to scene.
59 // @param its        Reference point.
60 // @param ray        Ray, used to specify wo (out direction).
61 // @return           Sampled incident direction, incident radiance and pdf per solid angle.
62 virtual PathIntegratorLocalRecord sampleDirectLighting(std::shared_ptr<Scene> scene,
63                                                         const Intersection &its,
64                                                         const Ray &ray) = 0;
65
66 // @brief Return scatter value of BSDF or phase function.
67 // @param scene      Ptr to scene.
68 // @param its        Reference point.
69 // @param ray        Ray, used to specify wo (out direction).
70 // @param wi         Incident direction wi.
71 // @return           Incident direction, scatter throughput f, pdf per solid angle.
72 //                 For surface, f is the product of BSDF value and cosine term.
73 //                 For medium, f is the value of phase function.
74 virtual PathIntegratorLocalRecord evalScatter(std::shared_ptr<Scene> scene,
75                                               const Intersection &its,
76                                               const Ray &ray,
77                                               const Vec3d &wi) = 0;
78
79 // @brief Sample incident direction by scatter value of BSDF or phase function.
80 // @param scene      Ptr to scene.
81 // @param its        Reference point.
82 // @param ray        Ray, used to specify wo (out direction).
83 // @return           Sampled incident direction, scatter throughput f, pdf per solid angle.
84 //                 For surface, f is the product of BSDF value and cosine term.
85 //                 For medium, f is the value of phase function.
86 virtual PathIntegratorLocalRecord sampleScatter(std::shared_ptr<Scene> scene,
87                                                 const Intersection &its,
88                                                 const Ray &ray) = 0;
89
90 // @brief Return probability of Russian roulette.
91 virtual double russianRoulette(std::shared_ptr<Scene> scene,
92                               const Intersection &its,
93                               const Spectrum &T,
94                               int nBounce) = 0;
95 };

```

## 9.53 /mnt/renderer/Zero/src/FunctionLayer/Integrator/Integrator.cpp File Reference

Integrator.

```
#include "Integrator.h"
```

### 9.53.1 Detailed Description

Integrator.

#### Author

Zhimin Fan

#### Version

0.1

#### Date

2022-05-31

#### Copyright

NJUMeta (c) 2022 www.njumeta.com

## 9.54 /mnt/renderer/Zero/src/FunctionLayer/Integrator/Integrator.h File Reference

Renderer. The start of everything.

```
#include "CoreLayer/Scene/Scene.h"
#include "FunctionLayer/Camera/Camera.h"
#include "FunctionLayer/Film/Film.h"
#include "FunctionLayer/Sampler/Sampler.h"
#include "FunctionLayer/TileGenerator/TileGenerator.h"
#include <memory>
```

### 9.54.1 Detailed Description

Renderer. The start of everything.

#### Author

orbitchen

#### Version

0.1

#### Date

2022-04-30

#### Copyright

NJUMeta (c) 2022 www.njumeta.com

## 9.55 Integrator.h

[Go to the documentation of this file.](#)

```
1
12 #pragma once
13
14 #include "CoreLayer/Scene/Scene.h"
15 #include "FunctionLayer/Camera/Camera.h"
16 #include "FunctionLayer/Film/Film.h"
17 #include "FunctionLayer/Sampler/Sampler.h"
18 #include "FunctionLayer/TileGenerator/TileGenerator.h"
19
20 #include <memory>
21
22 class Integrator
23 {
24 protected:
25     std::shared_ptr<Camera> camera;
26     std::unique_ptr<Film> film;
27
28 public:
29     Integrator(std::shared_ptr<Camera> _camera, std::unique_ptr<Film> _film);
30     virtual void render(std::shared_ptr<Scene> scene) = 0;
31     virtual void save(const std::string& path);
32
33 };
```

## 9.56 /mnt/renderer/Zero/src/FunctionLayer/Integrator/MonteCarloIntegrator.h File Reference

Integrators.

```
#include <cmath>
#include "Integrator.h"
```

### 9.56.1 Detailed Description

Integrators.

#### Author

Zhimin Fan edited by orbitchen at 2022-7-7: apply multithread acceleration and tile generator.

#### Version

0.1

#### Date

2022-05-06

#### Copyright

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## 9.57 MonteCarloIntegrator.h

[Go to the documentation of this file.](#)

```
1
13 #pragma once
14
15 #include <cmath>
16 #include "Integrator.h"
17
18 class MonteCarloIntegrator : public Integrator
19 {
20 protected:
21     std::shared_ptr<Sampler> sampler;
22     int spp = 4;
23
24     std::shared_ptr<TileGenerator> tileGenerator;
25
26     // @brief: render process per thread. Should be called in render().
27     void renderPerThread(std::shared_ptr<Scene> scene);
28
29     int renderThreadNum=4;
30
31 public:
32     MonteCarloIntegrator(
33         std::shared_ptr<Camera> _camera,
34         std::unique_ptr<Film> _film,
35         std::unique_ptr<TileGenerator> _tileGenerator,
36         std::shared_ptr<Sampler> _sampler,
37         int _spp,
38         int _renderThreadNum=4
39     );
40
41     virtual void render(std::shared_ptr<Scene> scene);
42
43     // @brief Estimate radiance along a given ray
44     virtual Spectrum Li(const Ray &ray, std::shared_ptr<Scene> scene) = 0;
45     // @brief Get a random number WITHOUT using MonteCarloIntegrator::sampler
46     virtual double randFloat();
47 };
```

## 9.58 /mnt/enderer/Zero/src/FunctionLayer/Integrator/PathIntegrator.cpp

### File Reference

Path Integrator.

```
#include "CoreLayer/Geometry/CoordConvertor.h"  
#include "PathIntegrator.h"
```

#### 9.58.1 Detailed Description

Path Integrator.

Author

Zhimin Fan

Version

0.1

Date

2022-05-06

Copyright

NJUMeta (c) 2022 www.njumeta.com

## 9.59 /mnt/enderer/Zero/src/FunctionLayer/Integrator/PathIntegrator.h

### File Reference

Path Integrator.

```
#include <cmath>  
#include "CoreLayer/Ray/Ray.h"  
#include "AbstractPathIntegrator.h"
```

#### 9.59.1 Detailed Description

Path Integrator.

Author

Zhimin Fan

Version

0.1

Date

2022-05-06

Copyright

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## 9.60 PathIntegrator.h

[Go to the documentation of this file.](#)

```

1
12 #pragma once
13
14 #include <cmath>
15 #include "CoreLayer/Ray/Ray.h"
16 #include "AbstractPathIntegrator.h"
17
18 class PathIntegrator : public AbstractPathIntegrator
19 {
20 protected:
21     const int nPathLengthLimit = 20;
22     const double pRussianRoulette = 0.95;
23
24 public:
25     PathIntegrator(
26         std::shared_ptr<Camera> _camera,
27         std::unique_ptr<Film> _film,
28         std::unique_ptr<TileGenerator> _tileGenerator,
29         std::shared_ptr<Sampler> _sampler,
30         int _spp,
31         int _renderThreadNum=4);
32
33     // @brief Return the radiance along given ray, emitted from given intersection.
34     // @param scene      Ptr to scene.
35     // @param its        Intersection hit by ray.
36     // @param ray        Ray to evaluate.
37     // @return           Direction of given ray, incident radiance at origin of ray, pdf of direct light
38     virtual PathIntegratorLocalRecord evalEmittance(std::shared_ptr<Scene> scene,
39                                                     std::optional<Intersection> its,
40                                                     const Ray &ray) override;
41
42     // @brief Sample incident direction of direct lighting.
43     // @param scene      Ptr to scene.
44     // @param its        Reference point.
45     // @param ray        Ray, used to specify wo (out direction).
46     // @return           Sampled incident direction, incident radiance and pdf per solid angle.
47     virtual PathIntegratorLocalRecord sampleDirectLighting(std::shared_ptr<Scene> scene,
48                                                            const Intersection &its,
49                                                            const Ray &ray) override;
50
51     // @brief Return scatter value of BSDF or phase function.
52     // @param scene      Ptr to scene.
53     // @param its        Reference point.
54     // @param ray        Ray, used to specify wo (out direction).
55     // @param wi        Incident direction wi.
56     // @return           Incident direction, scatter throughput f, pdf per solid angle.
57     // For surface, f is the product of BSDF value and cosine term.
58     // For medium, f is the value of phase function.
59     virtual PathIntegratorLocalRecord evalScatter(std::shared_ptr<Scene> scene,
60                                                  const Intersection &its,
61                                                  const Ray &ray,
62                                                  const Vec3d &wi) override;
63
64     // @brief Sample incident direction by scatter value of BSDF or phase function.
65     // @param scene      Ptr to scene.
66     // @param its        Reference point.
67     // @param ray        Ray, used to specify wo (out direction).
68     // @return           Sampled incident direction, scatter throughput f, pdf per solid angle.
69     // For surface, f is the product of BSDF value and cosine term.
70     // For medium, f is the value of phase function.
71     virtual PathIntegratorLocalRecord sampleScatter(std::shared_ptr<Scene> scene,
72                                                    const Intersection &its,
73                                                    const Ray &ray);
74
75     // @brief Return survive probability of Russian roulette.
76     virtual double russianRoulette(std::shared_ptr<Scene> scene,
77                                   const Intersection &its,
78                                   const Spectrum &T,
79                                   int nBounce) override;
80
81     // todo: move light sampling into a new class (called LightDistribution?)
82     // @brief Sample a light, by some weight distribution
83     virtual std::pair<std::shared_ptr<Light>, double> chooseOneLight(std::shared_ptr<Scene> scene,
84                                                                      const Intersection &its,
85                                                                      const Ray &ray,
86                                                                      double lightSample);
87
88     // @brief Probability of choosing a specified light source
89     virtual double chooseOneLightPdf(std::shared_ptr<Scene> scene,
90                                      const Intersection &its,
91                                      const Ray &ray,

```

```

92                                     std::shared_ptr<Light> light);
93
94     // @brief Evaluate radiance of env lights
95     virtual PathIntegratorLocalRecord evalEnvLights(std::shared_ptr<Scene> scene,
96                                                    const Ray &ray);
97 };

```

## 9.61 /mnt/renderer/Zero/src/FunctionLayer/Intersection.h File Reference

Intersection information on an object.

```

#include "CoreLayer/Geometry/Geometry.h"
#include "CoreLayer/Geometry/Frame.h"
#include "FunctionLayer/Material/Material.h"
#include "FunctionLayer/Medium/Medium.h"
#include "FunctionLayer/Shape/Entity.h"
#include <memory>

```

### 9.61.1 Detailed Description

Intersection information on an object.

#### Author

orbitchen

#### Version

0.1

#### Date

2022-04-30

#### Copyright

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## 9.62 Intersection.h

[Go to the documentation of this file.](#)

```

1
12 #pragma once
13
14 #include "CoreLayer/Geometry/Geometry.h"
15 #include "CoreLayer/Geometry/Frame.h"
16 #include "FunctionLayer/Material/Material.h"
17 #include "FunctionLayer/Medium/Medium.h"
18 #include "FunctionLayer/Shape/Entity.h"
19
20 #include <memory>
21
22 struct Intersection
23 {

```

```

24     Point3d position;
25     Normal3d geometryNormal;
26     Normal3d geometryTangent;
27     Normal3d geometryBitangent;
28     Point2d uv;
29
30     // shadingFrame
31     Frame shFrame;
32
33     Vec3d dpdu, dpdv;
34     Normal3d dndu, dndv;
35
36     // std::shared_ptr<Entity> object;
37     const Entity *object;
38
39     std::shared_ptr<Material> material;
40     std::shared_ptr<Medium> mediumInside;
41     std::shared_ptr<Medium> mediumOutside;
42
43     Vec3d toLocal(const Vec3d &d) const
44     {
45         return shFrame.toLocal(d);
46     }
47
48     Vec3d toWorld(const Vec3d &d) const
49     {
50         return shFrame.toWorld(d);
51     }
52 };

```

## 9.63 /mnt/renderer/Zero/src/FunctionLayer/Shape/Intersection.h File Reference

Intersection information on an object.

```

#include "CoreLayer/Geometry/Frame.h"
#include "CoreLayer/Geometry/Geometry.h"
#include "FunctionLayer/Material/Material.h"
#include "FunctionLayer/Medium/Medium.h"
#include "Entity.h"
#include <memory>

```

### 9.63.1 Detailed Description

Intersection information on an object.

#### Author

orbitchen

#### Version

0.1

#### Date

2022-04-30

#### Copyright

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## 9.64 Intersection.h

[Go to the documentation of this file.](#)

```

1
12 #pragma once
13
14 #include "CoreLayer/Geometry/Frame.h"
15 #include "CoreLayer/Geometry/Geometry.h"
16 #include "FunctionLayer/Material/Material.h"
17 #include "FunctionLayer/Medium/Medium.h"
18 #include "Entity.h"
19
20 #include <memory>
21
22 struct Intersection
23 {
24     Point3d position;
25     Normal3d geometryNormal;
26     Normal3d geometryTangent;
27     Normal3d geometryBitangent;
28     Point2d uv;
29
30     // shadingFrame
31     Frame shFrame;
32
33     Point3d dpdu, dpdv;
34     Normal3d dndu, dndv;
35
36     // std::shared_ptr<Entity> object;
37     const Entity *object;
38
39     std::shared_ptr<Material> material;
40     std::shared_ptr<Medium> mediumInside;
41     std::shared_ptr<Medium> mediumOutside;
42
43     Vec3d toLocal(const Vec3d &d) const
44     {
45         return shFrame.toLocal(d);
46     }
47
48     Vec3d toWorld(const Vec3d &d) const
49     {
50         return shFrame.toWorld(d);
51     }
52 };

```

## 9.65 /mnt/renderer/Zero/src/FunctionLayer/Light/AreaLight.cpp File Reference

Area light (abstract)

```
#include "AreaLight.h"
```

### 9.65.1 Detailed Description

Area light (abstract)

**Author**

Zhimin Fan

**Version**

0.1



**Date**

2022-05-20

**Copyright**

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## 9.66 /mnt/renderer/Zero/src/FunctionLayer/Light/AreaLight.h File Reference

Area light (abstract).

```
#include "CoreLayer/Geometry/Transform3d.h"  
#include "Light.h"
```

### 9.66.1 Detailed Description

Area light (abstract).

**Author**

Zhimin Fan

**Version**

0.1

**Date**

2022-05-20

**Copyright**

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## 9.67 AreaLight.h

[Go to the documentation of this file.](#)

```
1  
13 #include "CoreLayer/Geometry/Transform3d.h"  
14 #include "Light.h"  
15  
16 class AreaLight : public Light  
17 {  
18 protected:  
19     std::shared_ptr<Transform3D> transform;  
20  
21 public:  
22     AreaLight (std::shared_ptr<Transform3D> transform3D);  
23 };
```

## 9.68 /mnt/renderer/Zero/src/FunctionLayer/Light/DiffuseAreaLight.cpp File Reference

Diffuse Area light impl.

```
#include "DiffuseAreaLight.h"  
#include "CoreLayer/Geometry/CoordConvertor.h"
```

### 9.68.1 Detailed Description

Diffuse Area light impl.

#### Author

Zhimin Fan

#### Version

0.1

#### Date

2022-05-20

#### Copyright

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## 9.69 /mnt/renderer/Zero/src/FunctionLayer/Light/DiffuseAreaLight.h File Reference

Diffuse Area light.

```
#include "AreaLight.h"  
#include "CoreLayer/Geometry/Transform3d.h"  
#include "FunctionLayer/Shape/Entity.h"
```

### 9.69.1 Detailed Description

Diffuse Area light.

#### Author

Zhimin Fan

#### Version

0.1

#### Date

2022-05-20

#### Copyright

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## 9.70 DiffuseAreaLight.h

[Go to the documentation of this file.](#)

```

1
13 #include "AreaLight.h"
14 #include "CoreLayer/Geometry/Transform3d.h"
15 #include "FunctionLayer/Shape/Entity.h"
16
17 class DiffuseAreaLight : public AreaLight
18 {
19     std::shared_ptr<Entity> shape;
20     Spectrum radiance;
21
22 public:
23     DiffuseAreaLight(std::shared_ptr<Entity> shape,
24                     Spectrum radiance);
25     virtual LightSampleResult evalEnvironment(const Ray &ray) override;
26     virtual LightSampleResult eval(const Ray& ray, const Intersection &its, const Vec3d &d) override;
27     virtual LightSampleResult sampleEmit(const Point2d &positionSample, const Point2d &directionSample,
28     float time) override;
29     virtual LightSampleResult sampleDirect(const Intersection &its, const Point2d &sample, float time)
30     override;
31 };

```

## 9.71 Light.h

```

1
12 #pragma once
13 #include "CoreLayer/Geometry/Geometry.h"
14 #include "CoreLayer/ColorSpace/Color.h"
15 #include "CoreLayer/Ray/Ray.h"
16 #include "FunctionLayer/Intersection.h"
17
18 struct LightSampleResult
19 {
20     // @brief Spectrum from light.
21     Spectrum s;
22
23     // @brief Point on an object where receives light if exists.
24     Point3d src;
25
26     // @brief Point on a light where emits light if exists.
27     Point3d dst;
28
29     // @brief Direction from src to dst.
30     Vec3d wi;
31
32     Normal3d dstNormal;
33     Point2d uv;
34
35     // @brief PDF of direct light sampling.
36     double pdfDirect;
37     // @brief Positional emission PDF if exists.
38     double pdfEmitPos;
39     // @brief Directional emission PDF if exists.
40     double pdfEmitDir;
41
42     // @brief FALSE for area and volume light, TRUE for point and etc
43     bool isDeltaPos;
44     // @brief TRUE for distant light
45     bool isDeltaDir;
46 };
47
48 class Light
49 {
50 public:
51     // @brief Assume that the given ray hits nothing in the scene.
52     // Note that this function will not return a direct light sampling PDF.
53     virtual LightSampleResult evalEnvironment(const Ray &ray) = 0;
54     // @brief Assume that the given intersection is on the emitter.
55     // Note that param ray is only used to fill 'src' field.
56     virtual LightSampleResult eval(const Ray& ray, const Intersection &its, const Vec3d &d) = 0;
57     // @brief Note that this function will not return a direct light sampling PDF.
58     virtual LightSampleResult sampleEmit(const Point2d &positionSample, const Point2d &directionSample,
59     float time) = 0;
60     virtual LightSampleResult sampleDirect(const Intersection &its, const Point2d &sample, float time) =
61     0;
62 };

```

## 9.72 /mnt/renderer/Zero/src/FunctionLayer/Light/PointLight.cpp File Reference

Point light.

```
#include "CoreLayer/Geometry/CoordConvertor.h"  
#include "PointLight.h"
```

### 9.72.1 Detailed Description

Point light.

Author

Zhimin Fan

Version

0.1

Date

2022-05-15

Copyright

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## 9.73 /mnt/renderer/Zero/src/FunctionLayer/Light/PointLight.h File Reference

Point light.

```
#include "Light.h"  
#include "CoreLayer/Geometry/Transform3d.h"
```

### 9.73.1 Detailed Description

Point light.

Author

Zhimin Fan

Version

0.1

Date

2022-05-15

Copyright

NJUMeta (c) 2022 www.njumeta.com

## 9.74 PointLight.h

[Go to the documentation of this file.](#)

```

1
13 #pragma once
14
15 #include "Light.h"
16 #include "CoreLayer/Geometry/Transform3d.h"
17
18 #pragma once
19
20 class PointLight : public Light, public Transform3D
21 {
22 protected:
23     Spectrum intensity;
24
25 public:
26     PointLight(const Spectrum &intensity, const Point3d &center);
27     virtual void apply() override;
28     virtual LightSampleResult evalEnvironment(const Ray &ray) override;
29     virtual LightSampleResult eval(const Ray &ray, const Intersection &its, const Vec3d &d) override;
30     virtual LightSampleResult sampleEmit(const Point2d &positionSample, const Point2d &directionSample,
31     float time) override;
32     virtual LightSampleResult sampleDirect(const Intersection &its, const Point2d &sample, float time)
33     override;
34 };

```

## 9.75 /mnt/renderer/Zero/src/FunctionLayer/Material/BSSRDF/BSSRDF.h

### File Reference

BSSRDF.

### 9.75.1 Detailed Description

BSSRDF.

**Author**

orbitchen

**Version**

0.1

**Date**

2022-04-30

**Copyright**

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## 9.76 BSSRDF.h

[Go to the documentation of this file.](#)

```

1
12 #pragma once
13
14 class BSSRDF
15 {
16     // TODO
17 };

```

## 9.77 /mnt/renderer/Zero/src/FunctionLayer/Material/BxDF/BxDF.h File Reference

BxDF, including BRDF and BTDF.

```
#include "CoreLayer/ColorSpace/Color.h"
#include "CoreLayer/Geometry/Geometry.h"
#include "CoreLayer/Math/Warp.h"
```

### 9.77.1 Detailed Description

BxDF, including BRDF and BTDF.

#### Author

orbitchen

#### Version

0.1

#### Date

2022-04-30

#### Copyright

NJUMeta (c) 2022 www.njumeta.com

## 9.78 BxDF.h

[Go to the documentation of this file.](#)

```
1
12 #pragma once
13
14 #include "CoreLayer/ColorSpace/Color.h"
15 #include "CoreLayer/Geometry/Geometry.h"
16 #include "CoreLayer/Math/Warp.h"
17 struct BxDFSampleResult
18 {
19     Spectrum s;
20     Vec3d directionIn;
21     double pdf;
22     bool isSpecular;
23 };
24
25 // @brief BxDF. out == rays from/to camera, in == rays from/to objects/lights.
26 class BxDF
27 {
28
29 public:
30     virtual Spectrum f(const Vec3d &out, const Vec3d &in) const = 0;
31
32     virtual Vec3d sampleWi(const Vec3d &out, const Point2d& sample) const = 0;
33
34     virtual double pdf(const Vec3d &out, const Vec3d &in) const = 0;
35
36     virtual BxDFSampleResult sample(const Vec3d &out, const Point2d& sample) const = 0;
37
38     virtual bool isSpecular() const = 0;
39 };
```

## 9.79 /mnt/renderer/Zero/src/FunctionLayer/Material/BxDF/Dielectric.h File Reference

Dielectric Bxdf.

```
#include "CoreLayer/Geometry/Frame.h"
#include "BxDF.h"
```

### 9.79.1 Detailed Description

Dielectric Bxdf.

#### Author

Junping Yuan

#### Version

0.1

#### Date

#### Copyright

NJUMeta (c) 2022 www.njumeta.com

## 9.80 Dielectric.h

[Go to the documentation of this file.](#)

```
1
2 #pragma once
3 #include "CoreLayer/Geometry/Frame.h"
4 #include "BxDF.h"
5 class Dielectric : public BxDF{
6 public:
7     Dielectric(float m_intIOR =1.5046f,float m_extIOR = 1.00277f) : m_intIOR(m_intIOR),
8         m_extIOR(m_extIOR){
9
10     }
11
12     virtual Spectrum f(const Vec3d &wo, const Vec3d &wi) const ;
13
14     virtual Vec3d sampleWi(const Vec3d &wo, const Point2d &sample) const ;
15
16     virtual double pdf(const Vec3d &wo, const Vec3d &wi) const ;
17
18     virtual BxDFSampleResult sample(const Vec3d &wo, const Point2d &sample) const ;
19
20     virtual bool isSpecular() const ;
21
22 private:
23     float m_intIOR;
24     float m_extIOR;
25
26     static Vec3d reflect(const Vec3d &wi) {
```

```

38         return Vec3d {
39             -wi[0], -wi[1], wi[2]
40         };
41     }
42
43     Vec3d refract(const Vec3d &wi) const {
44         float cosThetaI = Frame::cosTheta(wi),
45             eta = cosThetaI > 0 ? m_extIOR / m_intIOR : m_intIOR / m_extIOR,
46             cosThetaT = std::sqrt(
47                 1 - eta*eta*(1-cosThetaI*cosThetaI)
48             );
49         return Vec3d {
50             - wi[0] * eta,
51             - wi[1] * eta,
52             cosThetaI > 0 ? -cosThetaT : cosThetaT
53         };
54     }
55
56
57 };
58
59

```

## 9.81 /mnt/renderer/Zero/src/FunctionLayer/Material/BxDF/Diffuse.cpp

### File Reference

```
#include "Diffuse.h"
```

#### 9.81.1 Detailed Description

##### Author

Junping Yuan

##### Version

0.1

##### Date

##### Copyright

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## 9.82 /mnt/renderer/Zero/src/FunctionLayer/Material/BxDF/Diffuse.h File Reference

diffuse bxdf

```

#include "CoreLayer/Geometry/Frame.h"
#include "BxDF.h"

```



### 9.82.1 Detailed Description

diffuse bxdf

#### Author

Junping Yuan

#### Version

0.1

#### Date

2022/06/06

#### Copyright

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## 9.83 Diffuse.h

[Go to the documentation of this file.](#)

```
1
12 #pragma once
13 #include "CoreLayer/Geometry/Frame.h"
14 #include "BxDF.h"
15
16
17
18 class Diffuse : public BxDF{
19 private:
20
21     Spectrum albedo;
22
23 public:
24
25     Diffuse(Spectrum albedo);
26
27     virtual Spectrum f(const Vec3d &wo, const Vec3d &wi) const;
28
29     virtual Vec3d sampleWi(const Vec3d &wo, const Point2d &sample) const;
30
31     virtual double pdf(const Vec3d &wo, const Vec3d &wi) const;
32
33     virtual BxDFSampleResult sample(const Vec3d &wo, const Point2d &sample) const;
34
35     virtual bool isSpecular() const;
36
37 };
38
39
40
```

## 9.84 Microfacet.h

```

1
13 #pragma once
14
15 #include "BxDF.h"
16 #include "CoreLayer/Geometry/Frame.h"
17
18 class Mircofacet : public BxDF {
19
20
21 public:
22     Mircofacet(Spectrum kd, double intIOR, double extIOR, double alpha);
23
24     virtual Spectrum f(const Vec3d &wo, const Vec3d &wi) const;
25
26     virtual Vec3d sampleWi(const Vec3d &wo, const Point2d &sample) const;
27
28     virtual double pdf(const Vec3d &wo, const Vec3d &wi) const;
29
30     virtual BxDFSampleResult sample(const Vec3d &wo, const Point2d &sample) const;
31
32     virtual bool isSpecular() const;
33 private:
34     Spectrum kd;
35     double ks;
36     double intIOR, extIOR, alpha;
37 };
38
39

```

## 9.85 /mnt/renderer/Zero/src/FunctionLayer/Material/BxDF/Mirror.h File Reference

Mirror Material.

```

#include "CoreLayer/Geometry/Frame.h"
#include "BxDF.h"

```

### 9.85.1 Detailed Description

Mirror Material.

#### Author

Junping Yuan

#### Version

0.1

#### Date

2022/6/8

#### Copyright

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## 9.86 Mirror.h

[Go to the documentation of this file.](#)

```

1
13 #include "CoreLayer/Geometry/Frame.h"
14 #include "BxDF.h"
15
16 #pragma once
17
18 class Mirror : public BxDF {
19
20     virtual Spectrum f(const Vec3d &wo, const Vec3d &wi) const;
21
22     virtual Vec3d sampleWi(const Vec3d &wo, const Point2d &sample) const;
23
24     virtual double pdf(const Vec3d &wo, const Vec3d &wi) const;
25
26     virtual BxDFSampleResult sample(const Vec3d &wo, const Point2d &sample) const;
27
28     virtual bool isSpecular() const;
29 };
30

```

## 9.87 TestMirrorBxdf.h

```

1 #pragma once
2
3 #include "BxDF.h"
4 #include "FunctionLayer/Intersection.h"
5
6 class TestMirrorBxdf : public BxDF
7 {
8 public:
9     virtual Spectrum f(const Vec3d &wo, const Vec3d &wi) const;
10
11     virtual Vec3d sampleWi(const Vec3d &wo, const Point2d &sample) const;
12
13     virtual double pdf(const Vec3d &wo, const Vec3d &wi) const;
14
15     virtual BxDFSampleResult sample(const Vec3d &wo, const Point2d &sample) const;
16
17     virtual bool isSpecular() const;
18 };

```

## 9.88 /mnt/renderer/Zero/src/FunctionLayer/Material/DelectricMaterial.h

### File Reference

```

#include "Material.h"
#include "FunctionLayer/Material/BxDF/Dielectric.h"
#include "FunctionLayer/Intersection.h"
#include "FunctionLayer/Texture/Texture.h"

```

### 9.88.1 Detailed Description

#### Author

Junping Yuan

#### Version

0.1

**Date**

2022/6/11

**Copyright**

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## 9.89 DelectricMaterial.h

[Go to the documentation of this file.](#)

```

1
13 #pragma once
14 #include "Material.h"
15 #include "FunctionLayer/Material/BxDF/Dielectric.h"
16 #include "FunctionLayer/Intersection.h"
17 #include "FunctionLayer/Texture/Texture.h"
18
19 class DelectricMaterial : public Material{
20
21 public:
22     virtual std::shared_ptr<BxDF> getBxDF(Intersection intersect) const;
23
24     virtual std::shared_ptr<BSSRDF> getBSSRDF(Intersection intersect) const;
25
26     DelectricMaterial(const std::shared_ptr<Texture<float>> & m_intIDR, const
std::shared_ptr<Texture<float>> & m_extIDR) : m_intIDR(m_intIDR)
27     {
28
29     }
30
31     DelectricMaterial(){
32
33     }
34 private:
35     std::shared_ptr<Texture<float>> m_intIDR;
36     std::shared_ptr<Texture<float>> m_extIDR;
37
38 };
39
40

```

## 9.90 /mnt/renderer/Zero/src/FunctionLayer/Material/Material.h File Reference

Material of an object. Generate BxDF and/or BSSRDF.

```

#include "FunctionLayer/Material/BxDF/BxDF.h"
#include "FunctionLayer/Material/BSSRDF/BSSRDF.h"
#include <memory>

```

### 9.90.1 Detailed Description

Material of an object. Generate BxDF and/or BSSRDF.

**Author**

orbitchen

**Version**

0.1

**Date**

2022-04-30

**Copyright**

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## 9.91 Material.h

[Go to the documentation of this file.](#)

```
1
12 #pragma once
13
14 #include "FunctionLayer/Material/BxDF/BxDF.h"
15 #include "FunctionLayer/Material/BSSRDF/BSSRDF.h"
16 #include <memory>
17 // #include "Intersection.h"
18
19
20
21 struct Intersection;
22
23 class Material
24 {
25 public:
26
27     virtual std::shared_ptr<BxDF> getBxDF(Intersection intersect) const = 0;
28     virtual std::shared_ptr<BSSRDF> getBSSRDF(Intersection intersect) const = 0;
29 };
```

## 9.92 /mnt/renderer/Zero/src/FunctionLayer/Material/MatteMaterial.h File Reference

```
#include "Material.h"
#include "FunctionLayer/Intersection.h"
#include "FunctionLayer/Texture/Texture.h"
```

### 9.92.1 Detailed Description

**Author**

Junping Yuan

**Version**

0.1

**Date**

2022/6/7

**Copyright**

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## 9.93 MatteMaterial.h

[Go to the documentation of this file.](#)

```

1
12 #pragma once
13 #include "Material.h"
14 #include "FunctionLayer/Intersection.h"
15 #include "FunctionLayer/Texture/Texture.h"
16
17 class MatteMaterial : public Material{
18 private:
19     std::shared_ptr<Texture<Spectrum>> kd ;
20 public:
21     MatteMaterial(const std::shared_ptr<Texture<Spectrum>> & kd );
22
23     virtual std::shared_ptr<BxDF> getBxDF(Intersection intersect) const;
24
25     virtual std::shared_ptr<BSSRDF> getBSSRDF(Intersection intersect) const;
26
27 };
28
29

```

## 9.94 /mnt/renderer/Zero/src/FunctionLayer/Material/MirrorMaterial.h File Reference

```

#include "Material.h"
#include "FunctionLayer/Material/BxDF/Mirror.h"
#include "FunctionLayer/Intersection.h"

```

### 9.94.1 Detailed Description

#### Author

Junping Yuan

#### Version

0.1

#### Date

2022/6/9

#### Copyright

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## 9.95 MirrorMaterial.h

[Go to the documentation of this file.](#)

```

1
13 #include "Material.h"
14 #include "FunctionLayer/Material/BxDF/Mirror.h"
15 #include "FunctionLayer/Intersection.h"
16
17 #pragma once
18 class MirrorMaterial : public Material{
19
20
21 public:
22     virtual std::shared_ptr<BxDF> getBxDF(Intersection intersect) const;
23     virtual std::shared_ptr<BSSRDF> getBSSRDF(Intersection intersect) const;
24 };

```

## 9.96 TestMirror.h

```
1
2 #pragma once
3 #include "Material.h"
4 #include "FunctionLayer/Material/BxDF/TestMirrorBxdf.h"
5
6 class TestMirror : public Material
7 {
8 private:
9 public:
10     TestMirror();
11     virtual std::shared_ptr<BxDF> getBxDF(Intersection intersect) const;
12     virtual std::shared_ptr<BSSRDF> getBSSRDF(Intersection intersect) const;
13 };
```

## 9.97 /mnt/renderer/Zero/src/FunctionLayer/Medium/Medium.h File Reference

Medium.

### 9.97.1 Detailed Description

Medium.

#### Author

orbitchen

#### Version

0.1

#### Date

2022-04-30

#### Copyright

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## 9.98 Medium.h

[Go to the documentation of this file.](#)

```
1
12 #pragma once
13
14 class Medium
15 {
16     // TODO
17 };
```

## 9.99 DirectSampler.h

```

1 #pragma once
2
3 #include "Sampler.h"
4
5 #pragma once
6 class DirectSampler : public Sampler
7 {
8 public:
9     virtual double sample() const;
10    virtual std::vector<double> sample(int num) const;
11 };

```

## 9.100 Independent.h

```

1 #pragma once
2 #include "Sampler.h"
3
4 class IndependentSampler : public Sampler {
5 public:
6     IndependentSampler() = default;
7
8     virtual ~IndependentSampler() = default;
9
10    virtual void startPixel(const Point2i &pixelPosition) override {
11        // do nothing
12    }
13
14    virtual void nextSample() override {
15        // do nothing
16    }
17
18    virtual double sample1D() override {
19        return rng();
20    }
21
22    virtual Point2d sample2D() override {
23        return Point2d{rng(), rng()};
24    }
25 };

```

## 9.101 /mnt/renderer/Zero/src/FunctionLayer/Sampler/Sampler.h File Reference

generate random numbers between (0,1).

```

#include <vector>
#include "CoreLayer/Adapter/random.h"
#include "CoreLayer/Geometry/Geometry.h"
#include "CoreLayer/Math/Common.h"

```

### Classes

- class [PixelSampler](#)

*Base class for pixel sampler, which generate specific samples before rendering each pixel need the dimensions and samplesPerPixels when construct.*

### Functions

- `template<typename T>`  
`void shuffle (std::vector< T > &samples, RandomNumberGenerator &rng)`  
*Shuffle the vector samples.*



### 9.101.1 Detailed Description

generate random numbers between (0,1).

#### Author

orbitchen

#### Version

0.1

#### Date

2022-04-30

#### Copyright

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### 9.101.2 Function Documentation

#### 9.101.2.1 shuffle()

```
template<typename T >
void shuffle (
    std::vector< T > & samples,
    RandomNumberGenerator & rng )
```

Shuffle the vector samples.

#### Template Parameters

<i>T</i>	
----------	--

#### Parameters

<i>samples</i>	
----------------	--

## 9.102 Sampler.h

[Go to the documentation of this file.](#)

```
1
12 #pragma once
```

```

13
14 #include <vector>
15 #include "CoreLayer/Adapter/random.h"
16 #include "CoreLayer/Geometry/Geometry.h"
17 #include "CoreLayer/Math/Common.h"
18
23 struct CameraSample;
24
25 class Sampler
26 {
27 protected:
28     RandomNumberGenerator rng;
29 public:
30     Sampler() = default;
31
32     virtual ~Sampler() = default;
33
34     virtual void startPixel(const Point2i &pixelPosition) = 0;
35
36     virtual void nextSample() = 0;
37
38     virtual double sample1D() = 0;
39
40     virtual Point2d sample2D() = 0;
41
42     CameraSample getCameraSample();
43
44 };
45
46 template<typename T>
47 void shuffle(std::vector<T> &samples, RandomNumberGenerator &rng) {
48     int count = samples.size();
49     for (int i = 0; i < count; ++i) {
50         int other = rng(i, count);
51         std::swap(samples[i], samples[other]);
52     }
53 }
54
55 class PixelSampler : public Sampler {
56 protected:
57     Point2i pixelPosition;
58     std::vector<std::vector<double>> samples1D;
59     std::vector<std::vector<Point2d>> samples2D;
60     int sppSqrt;
61     int samplesPerPixel;
62     int nDimensions;
63     int curSamplePixelIndex;
64     int curDimensionIndex1D;
65     int curDimensionIndex2D;
66
67     virtual void generateSamples1D(std::vector<double> &samples) = 0;
68     virtual void generateSamples2D(std::vector<Point2d> &samples) = 0;
69
70 public:
71     PixelSampler() = delete;
72
73     PixelSampler(int _sppSqrt)
74         : sppSqrt(_sppSqrt), samplesPerPixel(_sppSqrt * _sppSqrt), nDimensions(4),
75         curSamplePixelIndex(0), curDimensionIndex1D(0), curDimensionIndex2D(0) {
76         for (int i = 0; i < nDimensions; ++i) {
77             samples1D.emplace_back(std::vector<double>(samplesPerPixel));
78             samples2D.emplace_back(std::vector<Point2d>(samplesPerPixel));
79         }
80     }
81
82     PixelSampler(int _sppSqrt, int _nDimensions)
83         : sppSqrt(_sppSqrt), samplesPerPixel(_sppSqrt * _sppSqrt), nDimensions(_nDimensions),
84         curSamplePixelIndex(0), curDimensionIndex1D(0), curDimensionIndex2D(0) {
85         for (int i = 0; i < nDimensions; ++i) {
86             samples1D.emplace_back(std::vector<double>(samplesPerPixel));
87             samples2D.emplace_back(std::vector<Point2d>(samplesPerPixel));
88         }
89     }
90
91     virtual ~PixelSampler() = default;
92
93     // @brief The sampler may change the sampling strategy at different pixel location ,record the
94     // current pixel location
95     // @param _pixelPositon location of current pixel
96     virtual void startPixel(const Point2i &_pixelPositon) override {
97         // record the position
98         pixelPosition = _pixelPositon;
99         // reset the sample index
100         curDimensionIndex1D = curDimensionIndex2D = curSamplePixelIndex = 0;
101         // generate the samples will be used in current pixel
102         for (int i = 0; i < nDimensions; ++i) {
103             generateSamples1D(samples1D[i]);
104         }
105     }

```

```

111         shuffle(samples1D[i], rng);
112         generateSamples2D(samples2D[i]);
113         shuffle(samples2D[i], rng);
114     }
115 }
116
117 // @brief Start the next sample at a specific pixel
118 virtual void nextSample() override {
119     ++curSamplePixelIndex;
120     curDimensionIndex1D = curDimensionIndex2D = 0;
121 }
122
123 // @brief Sample a double in [0, 1], if curDimension exceeds the nDimensions, just return rng()
124 // @return A double sample
125 virtual double sample1D() override {
126     if (curDimensionIndex1D < nDimensions)
127         return samples1D[curDimensionIndex1D++][curSamplePixelIndex];
128     else
129         return rng();
130 }
131
132 // @brief Sample a point2d in [0, 1]^2, if curDimension exceeds the nDimensions, just return {rng(),
133 rng()}
134 // @return A point2d sample
135 virtual Point2d sample2D() override {
136     if (curDimensionIndex2D < nDimensions)
137         return samples2D[curDimensionIndex2D++][curSamplePixelIndex];
138     else
139         return Point2d{rng(), rng()};
140 }

```

## 9.103 /mnt/renderer/Zero/src/FunctionLayer/Sampler/Stratified.h File Reference

Stratified sampler.

```
#include "Sampler.h"
```

### 9.103.1 Detailed Description

Stratified sampler.

#### Author

Chenxi Zhou

#### Version

0.1

#### Date

2022-06-24

#### Copyright

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## 9.104 Stratified.h

[Go to the documentation of this file.](#)

```
1
13 #pragma once
14 #include "Sampler.h"
15
16 class StratifiedSampler : public PixelSampler {
17     // fill the samples1D
18     virtual void generateSamples1D(std::vector<double> &samples) override;
19     // fill the samples2D
20     virtual void generateSamples2D(std::vector<Point2d> &samples) override;
21 public:
22     StratifiedSampler() = delete;
23
24     StratifiedSampler(int sppSqrt) : PixelSampler(sppSqrt) { }
25
26     StratifiedSampler(int sppSqrt, int _nDimensions) : PixelSampler(sppSqrt, _nDimensions) { }
27
28     ~StratifiedSampler() = default;
29
30 };
```

## 9.105 /mnt/renderer/Zero/src/FunctionLayer/Shape/Entity.h File Reference

Objects that can be intersected with ray.

```
#include "CoreLayer/Geometry/Transform3d.h"
#include "FunctionLayer/Material/Material.h"
#include "CoreLayer/Geometry/BoundingBox.h"
#include "CoreLayer/Ray/Ray.h"
#include <optional>
#include <memory>
```

### 9.105.1 Detailed Description

Objects that can be intersected with ray.

#### Author

orbitchen

#### Version

0.1

#### Date

2022-04-30

#### Copyright

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## 9.106 Entity.h

[Go to the documentation of this file.](#)

```

1
12 #pragma once
13
14 #include "CoreLayer/Geometry/Transform3d.h"
15 #include "FunctionLayer/Material/Material.h"
16 #include "CoreLayer/Geometry/BoundingBox.h"
17 #include "CoreLayer/Ray/Ray.h"
18
19 #include <optional>
20 #include <memory>
21
22 struct Intersection;
23 class Light;
24
25 class Entity : public Transform3D
26 {
27 public:
28     std::shared_ptr<Light> lightPtr;
29     std::shared_ptr<Material> material;
30     // @brief Returns the intersection of the entity and the ray
31     virtual std::optional<Intersection> intersect(const Ray &r) const = 0;
32     // @brief Return ptr to light when primitive is a emitter. Otherwise, return nullptr.
33     virtual std::shared_ptr<Light> getLight() const = 0;
34     virtual void setLight(std::shared_ptr<Light> light) = 0;
35     virtual double area() const = 0;
36     virtual Intersection sample(const Point2d &positionSample) const = 0;
37     // @brief Return the bounding box of the entity
38     virtual BoundingBox3f WorldBound() const = 0;
39 };

```

## 9.107 /mnt/renderer/Zero/src/FunctionLayer/Shape/Sphere.cpp File Reference

Sphere. Only for test. Ignore transform.

```

#include "Sphere.h"
#include "FunctionLayer/Intersection.h"
#include "CoreLayer/Geometry/CoordConvertor.h"

```

### 9.107.1 Detailed Description

Sphere. Only for test. Ignore transform.

#### Author

Zhimin Fan

#### Version

0.1

#### Date

2022-05-30

#### Copyright

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## 9.108 /mnt/renderer/Zero/src/FunctionLayer/Shape/Sphere.h File Reference

Sphere. Only for test. Ignore transform.

```
#include "Entity.h"
#include <optional>
```

### 9.108.1 Detailed Description

Sphere. Only for test. Ignore transform.

#### Author

Zhimin Fan

#### Version

0.1

#### Date

2022-05-30

#### Copyright

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## 9.109 Sphere.h

[Go to the documentation of this file.](#)

```
1
12 #pragma once
13
14 #include "Entity.h"
15 #include <optional>
16
17 class Sphere : public Entity
18 {
19 protected:
20     double radius;
21     Point3d center;
22     virtual void apply() override;
23
24 public:
25     Sphere(Point3d _center, double _radius, std::shared_ptr<Material> _material);
26     virtual std::optional<Intersection> intersect(const Ray &r) const;
27     virtual double area() const;
28     virtual Intersection sample(const Point2d &positionSample) const;
29     virtual std::shared_ptr<Light> getLight() const;
30     virtual void setLight(std::shared_ptr<Light> light);
31     virtual BoundingBox3f WorldBound() const;
32 };
```

## 9.110 /mnt/renderer/Zero/src/FunctionLayer/Shape/Triangle.cpp File Reference

Triangle implementation, transform not implemented yet.

```
#include "Triangle.h"  
#include "FunctionLayer/Intersection.h"
```

### 9.110.1 Detailed Description

Triangle implementation, transform not implemented yet.

#### Author

Pengpei Hong

#### Version

0.1

#### Date

2022-06-26

#### Copyright

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## 9.111 /mnt/renderer/Zero/src/FunctionLayer/Shape/Triangle.h File Reference

Triangle implementation, transform not implemented yet.

```
#include "Entity.h"  
#include <optional>
```

### 9.111.1 Detailed Description

Triangle implementation, transform not implemented yet.

#### Author

Pengpei Hong

#### Version

0.1

#### Date

2022-06-26

#### Copyright

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## 9.112 Triangle.h

[Go to the documentation of this file.](#)

```

1
13 #pragma once
14
15 #include "Entity.h"
16 #include <optional>
17
18 class TriangleMesh{
19 public:
20     const int nTriangles;
21     const int nVertices;
22     std::shared_ptr<std::vector<int> vertexIndices; //the i-th triangle maps vertex[i * 3], vertex[i * 3 +
23     1], vertex[i * 3 + 2]
24     std::shared_ptr<std::vector<Point3d> p; //geometry position
25     std::shared_ptr<std::vector<Normal3d> n; //shading normal
26     std::shared_ptr<std::vector<Vec3d> s; //shading tangent(optional)
27     std::shared_ptr<std::vector<Point2d> uv; //uv coordinates
28     std::shared_ptr<Material> material;
29     /*
30     @brief constructor of TriangleMesh, parameter pointers(except material) will point to nullptr after
31     construction
32     @param <_nTriangles> number of triangle
33     @param <_nVertices> number of vertices(equal to the sizeof of _p)
34     @param <_p> position of vertices
35     @param <_n> shading normal of vertices(optional)
36     @param <_s> shading tangent of vertices(optional)
37     @param <_uv> uv coordinates of vertices(optional)
38     @param <_material> material of triangle mesh
39     */
40     TriangleMesh(const int& _nTriangles, const int& _nVertices, const std::shared_ptr<std::vector<int>>&
41     _vertexIndices, const std::shared_ptr<std::vector<Point3d>& _p, const
42     std::shared_ptr<std::vector<Normal3d>& _n, const std::shared_ptr<std::vector<Vec3d>& _s, const
43     std::shared_ptr<std::vector<Point2d>& _uv, const std::shared_ptr<Material>& _material);
44 };
45
46 //vertices in counter-clockwise order
47 class Triangle: public Entity{
48 protected:
49     int vertexId[3];
50     int faceId;
51     std::shared_ptr<TriangleMesh> mesh;
52 public:
53     virtual void apply() override;
54     Triangle(const std::shared_ptr<TriangleMesh>& _mesh, const int& _faceId);
55     Triangle(const std::vector<Point3d>& points, const std::shared_ptr<Material>& _material);
56     virtual std::optional<Intersection> intersect(const Ray& r) const;
57     virtual double area() const;
58     virtual Intersection sample(const Point2d& positionSample) const;
59     virtual std::shared_ptr<Light> getLight() const;
60     virtual void setLight(std::shared_ptr<Light> light);
61     virtual BoundingBox3f WorldBound() const;
62 };

```

## 9.113 /mnt/renderer/Zero/src/FunctionLayer/Texture/ImageTexture.cpp

### File Reference

Image texture.

```
#include "ImageTexture.h"
```

### 9.113.1 Detailed Description

Image texture.

Author

Zhimin Fan



**Version**

0.1

**Date**

2022-05-10

**Copyright**

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## 9.114 /mnt/renderer/Zero/src/FunctionLayer/Texture/ImageTexture.h File Reference

Image texture.

```
#include <cmath>
#include "CoreLayer/ColorSpace/Color.h"
#include "ResourceLayer/File/Image.h"
#include "FunctionLayer/Intersection.h"
#include "Texture.h"
#include "TextureMapping.h"
```

### 9.114.1 Detailed Description

Image texture.

**Author**

Zhimin Fan

**Version**

0.1

**Date**

2022-05-03

**Copyright**

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## 9.115 ImageTexture.h

[Go to the documentation of this file.](#)

```

1
12 #pragma once
13
14 #include <cmath>
15 #include "CoreLayer/ColorSpace/Color.h"
16 #include "ResourceLayer/File/Image.h"
17 #include "FunctionLayer/Intersection.h"
18 #include "Texture.h"
19 #include "TextureMapping.h"
20
21 enum class WrapMode
22 {
23     // todo
24 };
25
26 template <typename T>
27 class PrefilteredImage
28 {
29 protected:
30     WrapMode wrapMode;
31
32 public:
33     virtual void setWrapMode(enum WrapMode _wrapMode);
34     virtual WrapMode getWrapMode();
35     // todo: other common parameters
36
37     virtual T eval(const TextureCoord2D &coord) = 0;
38     virtual T texel(const Point2i &coord) = 0;
39     virtual void loadImage(const std::string &filename) = 0;
40 };
41
42 template <typename T>
43 class DirectImage : public PrefilteredImage<T>
44 {
45 protected:
46     std::shared_ptr<Image> image;
47
48 public:
49     virtual void loadImage(const std::string &filename);
50     virtual T eval(const TextureCoord2D &coord);
51     virtual T texel(const Point2i &coord);
52 };
53
54 template <typename T>
55 class LinearMIPMap : public PrefilteredImage<T>
56 {
57 protected:
58     std::shared_ptr<Image> image;
59
60 public:
61     virtual void loadImage(const std::string &filename);
62     virtual T eval(const TextureCoord2D &coord);
63     virtual T texel(const Point2i &coord);
64 };
65
66 template <typename Treturn, typename Tmemory>
67 class ImageTexture : public StdTexture<Treturn, TextureCoord2D>
68 {
69 protected:
70     std::shared_ptr<PrefilteredImage<Tmemory>> imageSampler;
71
72 public:
73     ImageTexture(const std::string &filename,
74                 std::shared_ptr<TextureMapping2D> mapping = std::make_shared<UVTextureMapping2D>()); //
75     using default_sampler
76     ImageTexture(const std::string &filename,
77                 std::shared_ptr<PrefilteredImage<Tmemory>> imageSampler,
78                 std::shared_ptr<TextureMapping2D> mapping = std::make_shared<UVTextureMapping2D>());
79     virtual Treturn eval(const TextureCoord2D &coord) const override;
80 };
81
82 // * Example: Creating a Image-based Color Texture using UV coordinates from mesh
83 // * > ImageTexture<RGB3>("1.jpg");
84 // * > ImageTexture<RGB3>("1.jpg", std::make_shared<DirectSampler>());
85 // * > ImageTexture<RGB3>("1.jpg", std::make_shared<UVTextureMapping2D>());
86 // * > ImageTexture<RGB3>("1.jpg", std::make_shared<DirectSampler>(),
87 // *                       std::make_shared<UVTextureMapping2D>());
88
89 // * Example: Create a Image-based Normal Map (wip)
90 // * since normal cannot be directly interpolated, you need to provide T with some compact NDF type
91 // * The NDF must provide convertor from RGB3 and some accessors for shadings (depends on implementation
92 // * of material)

```

```

90
91 template <typename T>
92 void PrefilteredImage<T>::setWrapMode(enum WrapMode _wrapMode)
93 {
94     wrapMode = _wrapMode;
95 }
96
97 template <typename T>
98 WrapMode PrefilteredImage<T>::getWrapMode()
99 {
100     return wrapMode;
101 }
102
103 template <typename T>
104 void DirectImage<T>::loadImage(const std::string &filename)
105 {
106     image = std::make_shared<Image>(filename);
107 }
108
109 template <typename T>
110 T DirectImage<T>::texel(const Point2i &coord)
111 {
112     // todo
113     return 0.0;
114 }
115
116 template <typename Treturn, typename Tmemory>
117 ImageTexture<Treturn, Tmemory>::ImageTexture(const std::string &filename,
118                                             std::shared_ptr<TextureMapping2D> mapping) :
119     StdTexture<Treturn, TextureCoord2D>(mapping)
120 {
121     imageSampler = std::make_shared<DirectImage<Tmemory>>();
122     imageSampler->loadImage(filename);
123 }
124
125
126 template <typename Treturn, typename Tmemory>
127 ImageTexture<Treturn, Tmemory>::ImageTexture(const std::string &filename,
128                                             std::shared_ptr<PrefilteredImage<Tmemory>> imageSampler,
129                                             std::shared_ptr<TextureMapping2D> mapping) :
130     imageSampler(imageSampler), StdTexture<Treturn, TextureCoord2D>(mapping)
131 {
132     this->imageSampler->loadImage(filename);
133 }

```

## 9.116 /mnt/renderer/Zero/src/FunctionLayer/Texture/ProceduralTexture.cpp File Reference ↩

Procedural texture.

```

#include "ProceduralTexture.h"
#include "TextureMapping.h"

```

### 9.116.1 Detailed Description

Procedural texture.

#### Author

Zhimin Fan

#### Version

0.1

**Date**

2022-05-13

**Copyright**

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## 9.117 /mnt/renderer/Zero/src/FunctionLayer/Texture/ProceduralTexture.h File Reference

Procedural texture.

```
#include "Texture.h"
```

### 9.117.1 Detailed Description

Procedural texture.

**Author**

Zhimin Fan

**Version**

0.1

**Date**

2022-05-13

**Copyright**

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## 9.118 ProceduralTexture.h

[Go to the documentation of this file.](#)

```
1
13 #include "Texture.h"
14
15 class Checkerboard2D : public StdTexture<double, TextureCoord2D>
16 {
17 protected:
18 public:
19     Checkerboard2D();
20     using StdTexture::eval;
21     virtual double eval(const TextureCoord2D &coord) const override;
22 };
23
24 class Checkerboard3D : public StdTexture<double, TextureCoord3D>
25 {
26 protected:
27 public:
28     Checkerboard3D();
29     using StdTexture::eval;
30     virtual double eval(const TextureCoord3D &coord) const override;
31 };
```

## 9.119 /mnt/renderer/Zero/src/FunctionLayer/Texture/Texture.h File Reference

Texture of different types.

```
#include <cmath>
#include "FunctionLayer/Intersection.h"
#include "CoreLayer/Geometry/Geometry.h"
```

### 9.119.1 Detailed Description

Texture of different types.

#### Author

Zhimin Fan

#### Version

0.1

#### Date

2022-05-03

#### Copyright

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## 9.120 Texture.h

[Go to the documentation of this file.](#)

```
1
12 #pragma once
13
14 #include <cmath>
15 #include "FunctionLayer/Intersection.h"
16 #include "CoreLayer/Geometry/Geometry.h"
17
18 // Tvalue can be float or any specturm type
19 template <typename Tvalue>
20 class Texture
21 {
22 public:
23     virtual Tvalue eval(const Intersection &intersection) const = 0;
24 };
25
26
27 // @brief Struct for texture coord C and dC/dx, dC/dy.
28 template <typename Tpos, typename Tvec>
29 struct TextureCoord
30 {
31     Tpos coord;
32     Tvec dcdx;
33     Tvec dcdy;
34 };
35
36 typedef TextureCoord<Point2d, Vec2d> TextureCoord2D;
```

```

37 typedef TextureCoord<Point3d, Vec3d> TextureCoord3D;
38
39 // @brief TextureMapping maps an intersection to texture coordinates of type Tcoord.
40 template <typename Tcoord>
41 class TextureMapping
42 {
43 protected:
44 public:
45     virtual Tcoord mapping(const Intersection &intersection) const = 0;
46 };
47
48 typedef TextureMapping<TextureCoord2D> TextureMapping2D;
49 typedef TextureMapping<TextureCoord3D> TextureMapping3D;
50
51 template <typename Tvalue>
52 class ConstantTexture : public Texture<Tvalue>
53 {
54 protected:
55     Tvalue value;
56
57 public:
58     ConstantTexture(const Tvalue &value);
59     virtual Tvalue eval(const Intersection &intersection) const;
60 };
61
62 template <typename Tvalue>
63 class MixTexture : public Texture<Tvalue>
64 {
65 protected:
66     std::shared_ptr<Texture<Tvalue>> srcA;
67     std::shared_ptr<Texture<Tvalue>> srcB;
68     std::shared_ptr<Texture<double>> factor;
69
70 public:
71     MixTexture(std::shared_ptr<Texture<Tvalue>> srcA,
72               std::shared_ptr<Texture<Tvalue>> srcB,
73               std::shared_ptr<Texture<double>> factor);
74
75     virtual Tvalue eval(const Intersection &intersection) const;
76 };
77
78 // @brief StdTexture refers to textures that needs a texture mapping to generate Tcoord from Intersection
79 template <typename Tvalue, typename Tcoord>
80 class StdTexture : public Texture<Tvalue>
81 {
82 protected:
83     std::shared_ptr<TextureMapping<Tcoord>> mapping;
84
85 public:
86     StdTexture();
87     StdTexture(std::shared_ptr<TextureMapping<Tcoord>> mapping);
88
89     // @brief This function just redirects the query to eval(coord) using member TextureMapping. Derived
90     // should NOT overwrite this.
91     virtual Tvalue eval(const Intersection &intersection) const final;
92
93     // @brief Eval texture value at given texture coord. (Derived needs to implement this)
94     virtual Tvalue eval(const Tcoord &coord) const = 0;
95 };
96
97 template <typename Tvalue>
98 ConstantTexture<Tvalue>::ConstantTexture(const Tvalue &value) : value(value)
99 {
100 }
101
102 template <typename Tvalue>
103 Tvalue ConstantTexture<Tvalue>::eval(const Intersection &intersection) const
104 {
105     return value;
106 }
107
108 template <typename Tvalue>
109 MixTexture<Tvalue>::MixTexture(std::shared_ptr<Texture<Tvalue>> srcA,
110                               std::shared_ptr<Texture<Tvalue>> srcB,
111                               std::shared_ptr<Texture<double>> factor) : srcA(srcA), srcB(srcB),
112                               factor(factor)
113 {
114 }
115
116 template <typename Tvalue>
117 Tvalue MixTexture<Tvalue>::eval(const Intersection &intersection) const
118 {
119     double alpha = factor->eval(intersection);
120     return srcA->eval(intersection) * alpha + srcB->eval(intersection) * (1 - alpha);
121 }
122
123 template <typename Tvalue, typename Tcoord>

```

```
122 StdTexture<Tvalue, Tcoord>::StdTexture(std::shared_ptr<TextureMapping<Tcoord> > mapping): mapping(mapping)
123 {
124 }
125
126 template <typename Tvalue, typename Tcoord>
127 Tvalue StdTexture<Tvalue, Tcoord>::eval(const Intersection &intersection) const
128 {
129     return eval(mapping->mapping(intersection));
130 }
```

## 9.121 /mnt/renderer/Zero/src/FunctionLayer/Texture/TextureMapping.cpp File Reference

Texture mapping.

```
#include "TextureMapping.h"
```

### 9.121.1 Detailed Description

Texture mapping.

#### Author

Zhimin Fan

#### Version

0.1

#### Date

2022-05-10

#### Copyright

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## 9.122 /mnt/renderer/Zero/src/FunctionLayer/Texture/TextureMapping.h File Reference

Texture mapping.

```
#include <cmath>
#include "CoreLayer/ColorSpace/Color.h"
#include "Texture.h"
#include "FunctionLayer/Intersection.h"
```

### 9.122.1 Detailed Description

Texture mapping.

#### Author

Zhimin Fan

#### Version

0.1

#### Date

2022-05-03

#### Copyright

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## 9.123 TextureMapping.h

[Go to the documentation of this file.](#)

```

1
12 #pragma once
13
14 #include <cmath>
15 #include "CoreLayer/ColorSpace/Color.h"
16 #include "Texture.h"
17 #include "FunctionLayer/Intersection.h"
18 // Various kinds of TextureMapping
19
20 class UVTextureMapping2D : public TextureMapping<TextureCoord2D>
21 {
22 protected:
23     // todo: add a affine transform
24 public:
25     virtual TextureCoord2D mapping(const Intersection &intersection) const override;
26 };
27
28 class NaturalTextureMapping3D : public TextureMapping<TextureCoord3D>
29 {
30 protected:
31     // todo: add a affine transform
32 public:
33     virtual TextureCoord3D mapping(const Intersection &intersection) const override;
34 };

```

## 9.124 /mnt/renderer/Zero/src/FunctionLayer/TileGenerator/SequenceTileGenerator.cpp File Reference

Implementation of SequenceTileGenerator.

```
#include "SequenceTileGenerator.h"
```



### 9.124.1 Detailed Description

Implementation of SequenceTileGenerator.

#### Author

orbitchen

#### Version

0.1

#### Date

2022-7-7

#### Copyright

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## 9.125 /mnt/renderer/Zero/src/FunctionLayer/TileGenerator/SequenceTileGenerator.h File Reference

TileGenerator thats generate tiles sequentially, from top-left to down-right.

```
#include "TileGenerator.h"
```

### 9.125.1 Detailed Description

TileGenerator thats generate tiles sequentially, from top-left to down-right.

#### Author

orbitchen

#### Version

0.1

#### Date

2022-7-7

#### Copyright

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## 9.126 SequenceTileGenerator.h

[Go to the documentation of this file.](#)

```

1
12 #pragma once
13
14 #include "TileGenerator.h"
15
16 class SequenceTileGenerator : public TileGenerator
17 {
18
19 private:
20
21     std::vector<int> xList;
22     std::vector<int> yList;
23
24     Point2i currentBeginIndex;
25     // currentEndIndex=[currentBeginIndex.x+1,currentBeginIndex.y+1]
26     bool reachedEnd=false;
27
28 protected:
29
30     //@brief the size of a tile. The default size of a tile is 16x16.
31     int size;
32
33 public:
34
35     SequenceTileGenerator(const Point2i& _resolution,int _size=16);
36
37     virtual std::vector<std::shared_ptr<Tile>> generateTiles();
38
39     virtual std::optional<std::shared_ptr<Tile>> generateNextTile();
40
41 };

```

## 9.127 /mnt/renderer/Zero/src/FunctionLayer/TileGenerator/TileGenerator.cpp File Reference

Implementation of SquareTile and pointIterator.

```
#include "TileGenerator.h"
```

### 9.127.1 Detailed Description

Implementation of SquareTile and pointIterator.

#### Author

orbitchen

#### Version

0.1

#### Date

2022-7-7

#### Copyright

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## 9.128 /mnt/renderer/Zero/src/FunctionLayer/TileGenerator/TileGenerator.h File Reference

Generate tiles for different threads in renderer.

```
#include "CoreLayer/Geometry/Geometry.h"
#include <vector>
#include <mutex>
#include <optional>
```

### 9.128.1 Detailed Description

Generate tiles for different threads in renderer.

#### Author

orbitchen

#### Version

0.1

#### Date

2022-04-30

#### Copyright

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## 9.129 TileGenerator.h

[Go to the documentation of this file.](#)

```
1
12 #pragma once
13
14 #include "CoreLayer/Geometry/Geometry.h"
15
16 #include <vector>
17 #include <mutex>
18 #include <optional>
19
20 /*@brief Iterator for Point2i.
21 * It will generate points between pBegin and pEnd but pEnd is not included.
22 * e.g, pBegin=[0,0], pEnd=[2,2], and the generated points will be
23 * [0,0], [1,0], [0,1] and [1,1].
24 * */
25 class PointIterator
26 {
27
28 protected:
29
30     // @brief the first point of a tile.
31     Point2i pBegin;
32
33     // @brief the last point of a tile.
34     Point2i pEnd;
35
```

```

36     // @brief current point in tile.
37     Point2i currentP;
38
39     int xMin, xMax;
40     int yMin, yMax;
41
42 public:
43
44     PointIterator(const Point2i& _pBegin, const Point2i& _pEnd, const Point2i& p);
45
46     Point2i operator*() const;
47
48     PointIterator& operator++();
49
50     bool operator!=(const PointIterator& anotherIt);
51
52 };
53
54 /*
55  * @brief Tile representation, and generate points within the tile.
56  * Check PointIterator for more information.
57  */
58 class Tile
59 {
60
61 protected:
62
63     Point2i pBegin;
64     Point2i pEnd;
65
66 public:
67
68     Tile(const Point2i& _pBegin, const Point2i& _pEnd);
69
70     virtual PointIterator begin() const=0;
71     virtual PointIterator end() const=0;
72 };
73
74 /*
75  * @brief Basic Tile implementation. Generate points in a square.
76  */
77 class SquareTile : public Tile
78 {
79 private:
80
81     PointIterator beginIte;
82     PointIterator endIte;
83 public:
84
85     SquareTile(const Point2i& _pBegin, const Point2i& _pEnd);
86
87     virtual PointIterator begin() const;
88     virtual PointIterator end() const;
89 };
90
91 class TileGenerator
92 {
93
94 protected:
95
96     // @brief the resolution of render image.
97     Point2i resolution;
98
99     // @brief lock for generateNextTile.
100     std::mutex mute;
101
102 public:
103
104     TileGenerator(const Point2i& _resolution);
105
106     // @brief generate all tiles. No mutex.
107     virtual std::vector<std::shared_ptr<Tile>> generateTiles() = 0;
108
109     /*
110     * @brief generate next tile.
111     * Use mutex to make sure that threads will have different tiles.
112     */
113     virtual std::optional<std::shared_ptr<Tile>> generateNextTile() = 0;
114
115 };

```

## 9.130 /mnt/renderer/Zero/src/ResourceLayer/File/Image.h File Reference

Simple Image representation.

```
#include "CoreLayer/Geometry/Geometry.h"
#include "CoreLayer/ColorSpace/Color.h"
#include <string>
```

### 9.130.1 Detailed Description

Simple Image representation.

#### Author

orbitchen

#### Version

0.1

#### Date

2022-04-30

#### Copyright

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## 9.131 Image.h

[Go to the documentation of this file.](#)

```
1
12 #pragma once
13
14 #include "CoreLayer/Geometry/Geometry.h"
15 #include "CoreLayer/ColorSpace/Color.h"
16
17 #include <string>
18
19 // todo: support various data type
20
21 class Image
22 {
23     unsigned char *imageRawData;
24     Point2i resolution;
25     int channels;
26
27 public:
28     Image();
29     ~Image();
30
31     enum class ImageLoadMode
32     {
33         IMAGE_LOAD_BW,
34         IMAGE_LOAD_COLOR
35     };
36     // todo: support alpha reading
37     // todo: do gamma correction
38     Image(const std::string &path, ImageLoadMode = ImageLoadMode::IMAGE_LOAD_COLOR);
```

```

39
40 // @brief generate one black image with resolution [width,height] and channels.
41 Image(const Point2i &resolution, int channels);
42 Image(const Point3i &shape);
43
44 friend class ImageManager;
45
46 Point2i getResolution() const;
47 int getChannels() const;
48 int getWidth() const;
49 int getHeight() const;
50
51 void setColorAt(const Point2i &p, const Spectrum &s);
52 void setColorAt(const Point2i &p, const RGB3 &rgb);
53 RGB3 getRGBColorAt(const Point2i &p);
54 Spectrum getSpectrumColorAt(const Point2i &p);
55
56 bool saveTo(const std::string &path);
57 };

```

## 9.132 /mnt/renderer/Zero/src/ResourceLayer/File/MeshData.h File Reference

Mesh data for both real time renderer and ray tracing renderer.

```

#include "CoreLayer/Geometry/Geometry.h"
#include <string>

```

### 9.132.1 Detailed Description

Mesh data for both real time renderer and ray tracing renderer.

#### Author

orbitchen

#### Version

0.1

#### Date

2022-04-30

#### Copyright

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## 9.133 MeshData.h

[Go to the documentation of this file.](#)

```

1
12 #pragma once
13
14 #include "CoreLayer/Geometry/Geometry.h"
15
16 #include <string>
17
18 class MeshData
19 {
20     double *vertexRaw;
21     double *normalRaw;
22     double *uvRaw;
23     double *tangentRaw;
24     double *bitangentRaw;
25     int *indiceRaw;
26
27     // @brief init MeshData from raw data pointer. MeshData can not be initialized from file path cause
28     // one single file may contain multiple MeshData.
29     MeshData(double *_v, double *_n, double *_uv, double *_tan, double *_bi, int *_indice);
30 public:
31     friend class MeshDataManager;
32
33     Point3d getVertexAt(int i) const;
34     Normal3d getNormalAt(int i) const;
35     Point2d getUvAt(int i) const;
36     Vec3d getTangentAt(int i) const;
37     Vec3d getBitangentAt(int i) const;
38
39     // @brief get 3 indices for ist triangle mesh. In order.
40     Point3i getTriangleIndiceAt(int i) const;
41
42     int getTriangleNum() const;
43 };

```

## 9.134 /mnt/renderer/Zero/src/ResourceLayer/ResourceManager.h File Reference

Simple Memory Allocator.

```

#include "ResourceLayer/File/Image.h"
#include "ResourceLayer/File/MeshData.h"
#include <map>
#include <string>
#include <memory>

```

### 9.134.1 Detailed Description

Simple Memory Allocator.

#### Author

orbitchen

#### Version

0.1

#### Date

2022-04-30

#### Copyright

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## 9.135 ResourceManager.h

[Go to the documentation of this file.](#)

```
1
12 #pragma once
13
14 #include "ResourceLayer/File/Image.h"
15 #include "ResourceLayer/File/MeshData.h"
16
17 #include <map>
18 #include <string>
19 #include <memory>
20
21 template <typename BaseType>
22 class ResourceManager
23 {
24 protected:
25     std::map<std::string, std::shared_ptr<BaseType>> hash;
26
27 public:
28     ResourceManager();
29 };
30
31 class ImageManager : public ResourceManager<Image>
32 {
33     ImageManager();
34     std::shared_ptr<ImageManager> instance;
35
36 public:
37     // @brief singleton pattern get.
38     static std::shared_ptr<ImageManager> getInstance();
39
40     std::shared_ptr<Image> getImage(const std::string &path, Image::ImageLoadMode mode);
41 };
42
43 class MeshDataManager : public ResourceManager<MeshData>
44 {
45     MeshDataManager();
46     std::shared_ptr<MeshDataManager> instance;
47
48 public:
49     // @brief singleton pattern get.
50     static std::shared_ptr<MeshDataManager> getInstance();
51
52     std::vector<std::shared_ptr<MeshData>> getMeshData(const std::string &path);
53 };
```