

## Data Codebook of movement measures across activities of daily living (Walking (level, up or downstairs), sitting, standing, laying)

Legacy definition of the variable or measure

More descriptive name of variable or measure		Description of the variable or measurement					
		Measurement		Movement type		Data transformations	
original	modified	form of movement: [b]ody or [g]ravity	signal source: [g]yroscope or [a]ccelerometer* *	directional: direction of movement (axis X, Y or Z)	omnidirectional: derived from linear acceleration & linear velocity [Jerk]	raw[t*] or [f***]ourier transformed signal	signal nitude calculated using Euclidean norm []

Subject ID, values range from 1 to 30

Activity of Daily Living (ADL) (1 value recorded): 1=Walking, 2=Walking.Upstairs, 3=Walking.Downstairs, 4=Sitting, 5= Standing

### tBodyAcc-XYZ

XYZ		body	Accelerometer	directional	raw
BodyAcc-mean-X	Bodymotion.mean.along.Xaxis	mean of body movement along the X axis for an ADL based on raw data			
BodyAcc-mean-Y	Bodymotion.mean.along.Yaxis	mean of body movement along the Y axis for an ADL based on raw data			
BodyAcc-mean-Z	Bodymotion.mean.along.Zaxis	mean of body movement along the Z axis for an ADL based on raw data			
BodyAcc-std-X	Bodymotion.sd.along.Xaxis	standard deviation of body movement along the X axis for an ADL based on raw data			
BodyAcc-std-Y	Bodymotion.sd.along.Yaxis	standard deviation of body movement along the Y axis for an ADL based on raw data			
BodyAcc-std-Z	Bodymotion.sd.along.Zaxis	standard deviation of body movement along the Z axis for an ADL based on raw data			

**tGravityAcc**

**-XYZ** gravity Accelerometer directional raw

GravityAcc-mean-X UpDownmotion.mean.along.Xaxis mean of body (up/down) movement along the X axis for an ADL based on raw data

GravityAcc-mean-Y UpDownmotion.mean.along.Yaxis mean of body (up/down) movement along the Y axis for an ADL based on raw data

GravityAcc-mean-Z UpDownmotion.mean.along.Zaxis mean of body (up/down) movement along the Z axis for an ADL based on raw data

GravityAcc-std-X UpDownmotion.sd.along.Xaxis standard deviation of body (up/down) movement along the X axis for an ADL based on raw data

GravityAcc-std-Y UpDownmotion.sd.along.Yaxis standard deviation of body (up/down) movement along the Y axis for an ADL based on raw data

GravityAcc-std-Z UpDownmotion.sd.along.Zaxis standard deviation of body (up/down) movement along the Z axis for an ADL based on raw data

**tBodyAccJer**

**rk-XYZ** body Accelerometer directional omnidirectional raw

BodyAccJer-mean-X Bodymotion.multiplefoci.mean.along.Xaxis mean of body (up/down) movement along the X axis and omnidirectional axis for an ADL based on raw data

BodyAccJer-mean-Y Bodymotion.multiplefoci.mean.along.Yaxis mean of body (up/down) movement along the Y axis and omnidirectional axis for an ADL based on raw data

BodyAccJer-mean-Z Bodymotion.multiplefoci.mean.along.Zaxis mean of body (up/down) movement along the Z axis and omnidirectional axis for an ADL based on raw data

BodyAccJer-k-std-X Bodymotion.multiplefoci.sd.along.Xaxis standard deviation of body (up/down) movement along the X and omnidirectional axis for an ADL based on raw data

BodyAccJer-k-std-Y Bodymotion.multiplefoci.sd.along.Yaxis standard deviation of body (up/down) movement along the Y and omnidirectional axis for an ADL based on raw data

BodyAccJerk-std-Z	Bodymotion.multiplefoci.sd.along.Zaxis	standard deviation of body (up/down) movement along the Z and omnidirectional axis for an ADL based on raw data
<b>tBodyGyro-XYZ</b>		
	body	Gyroscope
		directional
		raw
BodyGyro-mean-X	BodyShift.mean.along.Xaxis	mean of body positional change along the X axis for an ADL based on raw data
BodyGyro-mean-Y	BodyShift.mean.along.Yaxis	mean of body positional change along the Y axis for an ADL based on raw data
BodyGyro-mean-Z	BodyShift.mean.along.Zaxis	mean of body positional change along the Z axis for an ADL based on raw data
BodyGyro-std-X	BodyShift.sd.along.Xaxis	standard deviation of body positional change along the X axis for an ADL based on raw data
BodyGyro-std-Y	BodyShift.sd.along.Yaxis	standard deviation of body positional change along the Y axis for an ADL based on raw data
BodyGyro-std-Z	BodyShift.sd.along.Zaxis	standard deviation of body positional change along the Z axis for an ADL based on raw data

## Data Codebook of movement measures across activities of daily living (Walking (level, up or downstairs), sitting, standing, laying)

General definition of the variable or measure

More descriptive name of variable or measure	Description of the variable or measurement		
	Measurement	Movement type	Data transformations
	form of movement: [b]ody or [g]ravity	directional: direction of movement (axis X, Y or Z)	omnidirectional: derived from linear acceleration & linear velocity [Jerk]
	signal source: [g]yroscope or [a]ccelerometer*		raw[t*] or [f***]ourier transformed signal
			signal nitude calculated using Euclidean norm []

**tBodyGyroJ  
erk-XYZ**

		body	Gyroscope	directional	omnidirectional	raw
BodyGyroJ erk-mean-X	BodyShift.multiplefo ci.mean.along.Xaxis	mean of body positional change along the X axis and	omnidirectional axis for an ADL	based on		
BodyGyroJ erk-mean-Y	BodyShift.multiplefo ci.mean.along.Yaxis	mean of body positional change along the Y axis and	omnidirectional axis for an ADL	based on		
BodyGyroJ erk-mean-Z	BodyShift.multiplefo ci.mean.along.Zaxis	mean of body positional change along the Z axis and	omnidirectional axis for an ADL	based on		
BodyGyroJ erk-std-X	BodyShift.multiplefo ci.sd.along.Xaxis	standard deviation of body positional change along the X axis and	omnidirectional axis for an	ADL based on raw data		
BodyGyroJ erk-std-Y	BodyShift.multiplefo ci.sd.along.Yaxis	standard deviation of body positional change along the Y axis and	omnidirectional axis for an	ADL based on raw data		
BodyGyroJ erk-std-Z	BodyShift.multiplefo ci.sd.along.Zaxis	standard deviation of body positional change along the Z axis and	omnidirectional axis for an ADL	based on raw data		

**Data Codebook of movement measures across activities of daily living (Walking (level, up or downstairs), sitting, standing, laying)**

General definition of the variable or measure

Revised descriptive name of measure					
Measurement		Movement type		Data transformations	
form of movement: [b]ody or [g]ravity	signal source: [g]yroscope or [a]ccelerometer* *	directional: direction of movement (axis X, Y or Z)	omnidirectional: derived from linear acceleration & linear velocity [Jerk]	raw[t*] or [f***]ourier transformed signal	signal nitude calculated using Euclidean norm []

**tBodyAcc**

body Accelerometer raw yes

BodyAccMag-mean	Bodymotion.mean	mean of body movement along the Z axis for an ADL with Euclidean norm transformation of nitude				
BodyAccMag-std	Bodymotion.sd	standard deviation of body movement along the Z axis for an ADL with Euclidean norm transformation of nitude				
<b>tGravityAcc</b>		gravity	Accelerometer		raw	yes
GravityAccMag-mean	UpDownmotion.mean	mean of up/down movement for an ADLwith Euclidean norm transformation of nitude				
GravityAccMag-std	UpDownmotion.sd	standard deviation of up/down movement for an ADL with Euclidean norm transformation of nitude				
<b>tBodyAccJerk</b>		body	Accelerometer	omnidirectional	raw	yes
BodyAccJerkMag-mean	Bodymotion.multiplefoci.mean	mean of bodily movement for an ADL of omnidirectional change wit Euclidean norm transformation of nitude				
BodyAccJerkMag-std	Bodymotion.multiplefoci.sd	standard deviation of bodily movement for an ADL of omnidirectional change wit Euclidean norm transformation of nitude				
<b>tBodyGyro</b>		body	Gyroscope		raw	
BodyGyroMag-mean	BodyShift.mean	mean of body positional movement for an ADL based upon raw data				
BodyGyroMag-std	BodyShift.sd	standard deviation of body positional movement for an ADL based upon raw data				
<b>tBodyGyroJerk</b>		body	Gyroscope		raw	
BodyGyroJerkMag-mean	BodyShift.multiplefoci.mean	mean of bodily omnidirectional body shift movement movement for an ADL based upon raw data				
BodyGyroJerkMag-std	BodyShift.multiplefoci.sd	standard deviation of bodily omnidirectional body shift movement for an ADL based upon raw data				

## Data Codebook of movement measures across activities of daily living (Walking (level, up or downstairs), sitting, standing, laying)

General definition of the variable or measure

More descriptive name of variable or measure      Description of the variable or measurement

Measurement		Movement type		Data transformations	
form of movement: [b]ody or [g]ravity	signal source: [g]yroscope or [a]ccelerometer* *	directional: direction of movement (axis X, Y or Z)	omnidirectional: derived from linear acceleration & linear velocity [Jerk]	raw[t*] or [f***]ourier transformed signal	signal nitude calculated using Euclidean norm []

### BodyAcc-XYZ

body      Accelerometer      directional      fourier

BodyAcc-mean-X	Bodymotion.mean.along.Xaxis	mean of bodily movement along the X axis for an ADL based upon fourier transformed signal
BodyAcc-mean-Y	Bodymotion.mean.along.Yaxis	mean of bodily movement along the Y axis for an ADL based upon fourier transformed signal
BodyAcc-mean-Z	Bodymotion.mean.along.Zaxis	mean of bodily movement along the Z axis for an ADL based upon Fourier transformed signal
BodyAcc-std-X	Bodymotion.sd.along.Xaxis	standard deviation of bodily movement along the X axis for an ADL based upon Fourier transformed signal
BodyAcc-std-Y	Bodymotion.sd.along.Yaxis	standard deviation of bodily movement along the Y axis for an ADL based upon Fourier transformed signal
BodyAcc-std-Z	Bodymotion.sd.along.Zaxis	standard deviation of bodily movement along the Z axis for an ADL based upon Fourier transformed signal

### BodyAccJerk-XYZ

body      Accelerometer      directional      Fourier

BodyAccJerk-mean-X	Bodymotion.multiplefoci.mean.along.Xaxis	mean of omnidirectional bodily movement along the X axis for an ADL based upon Fourier transformed signal
BodyAccJerk-mean-Y	Bodymotion.multiplefoci.mean.along.Yaxis	mean of omnidirectional bodily movement along the Y axis for an ADL based upon Fourier transformed signal
BodyAccJerk-mean-Z	Bodymotion.multiplefoci.mean.along.Zaxis	mean of omnidirectional bodily movement along the Z axis for an ADL based upon Fourier transformed signal
BodyAccJerk-std-X	Bodymotion.multiplefoci.sd.along.Xaxis	standard deviation of omnidirectional bodily movement along the X axis for an ADL based upon Fourier transformed signal
BodyAccJerk-std-Y	Bodymotion.multiplefoci.sd.along.Yaxis	standard deviation of omnidirectional bodily movement along the Y axis for an ADL based upon Fourier transformed signal
BodyAccJerk-std-Z	Bodymotion.multiplefoci.sd.along.Zaxis	standard deviation of omnidirectional bodily movement along the Z axis for an ADL based upon Fourier transformed signal nitude

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		form of movement: [b]ody or [g]ravity	signal source: [g]yroscope or [a]ccelerometer* *	directional: direction of movement (axis X, Y or Z)	omnidirectional: derived from linear acceleration & linear velocity [Jerk]	raw[t*] or [f***]ourier transformed signal	signal nitude calculated using Euclidean norm []
BodyGyro-XYZ	body	Gyroscope		directional		Fourier	

BodyGyro-mean-X	BodyShift.mean.along.Xaxis	mean of body shift change along the X axis for an ADL based upon raw data				
BodyGyro-mean-Y	BodyShift.mean.along.Yaxis	mean of body shift change along the Y axis for an ADL based upon raw data				
BodyGyro-mean-Z	BodyShift.mean.along.Zaxis	mean of body shift change along the Z axis for an ADL based upon raw data				
BodyGyro-std-X	BodyShift.sd.along.Xaxis	standard deviation of body shift change along the X axis for an ADL based upon raw data				
BodyGyro-std-Y	BodyShift.sd.along.Yaxis	standard deviation of body shift change along the Y axis for an ADL based upon raw data				
BodyGyro-std-Z	BodyShift.sd.along.Zaxis	standard deviation of body shift change along the Z axis for an ADL based upon raw data				
<b>BodyAcc</b>		body	Accelerometer		Fourier	
BodyAccMag-mean	Bodymotion.mean	mean of unspecified bodily movement movement for an ADL based upon raw data				
BodyAccMag-std	Bodymotion.sd	standard deviation of unspecified bodily movement movement for an ADL based upon raw data				
<b>BodyAccJerk</b>		body	Accelerometer	omnidirectional	Fourier	yes
BodyBodyAccJerkMag-mean	BodyBodymotion.multiplefoci.mean	mean of bodily omnidirectional bodily movement movement for an ADL based upon Fourier transformed nitude signals				
BodyBodyAccJerkMag-std	BodyBodymotion.multiplefoci.sd	standard deviation of bodily omnidirectional bodily movement movement for an ADL based upon Fourier transformed nitude signals				
<b>BodyGyro</b>		body	Gyroscope		Fourier	yes
BodyBodyGyroMag-meanFreq	BodyBodyShift.meanFreq	mean frequency of reported frequencies of body shift change movement for an ADL based upon Fourier transformed nitude signals				



BodyGyroJerk

rk body Gyroscope omnidirectional Fourier yes

BodyBodyGyroJerkMag-mean BodyBodyShift.multiplefoci.mean mean of omnidirectional body shift change movement for an ADL based upon Fourier transformed nitude signals

BodyBodyGyroJerkMag-std BodyBodyShift.multiplefoci.sd standard deviation of omnidirectional body shift change movement for an ADL based upon Fourier transformed nitude signals

angle.BodyAccMean,gravity.

angle.BodyAccJerkMean.,gravityMean.

angle.BodyGyroMean,gravityMean.

angle.BodyGyroJerkMean,gravityMean.

angle.X,gravityMean.

angle.Y,gravityMean.

angle.Z,gravityMean.

Component variables modifying other variables used in the signal averaging process

mean() mean or average measurement movement for an ADL used to estimate from each signal

std() standard deviation movement for an ADL or square root of sum of squared differences from the mean from each signal

\* t stands for time domain signals captured at a constant rate of 50 Hz and filtered using a median filter and a 3rd order low pass Butterworth filter with a corner frequency of 20 Hz to remove noise

\*\* the acceleration signal was then separated into body and gravity acceleration signals (tBodyAcc-XYZ and tGravityAcc-XYZ) using another low pass Butterworth filter with a corner frequency of 0.3 Hz.

\*\*\*a Fast Fourier Transform (FFT) was applied to some of these signals producing BodyAcc-XYZ, BodyAccJerk-XYZ, BodyGyro-XYZ, BodyAccJerk, BodyGyro, BodyGyroJerk. (Note the 'f' to indicate frequency domain signals).