

Improvements in short-term forecasting of geomagnetic activity

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[1] We have improved our space weather forecasting algorithms to now predict *Dst* and *AE* in addition to *Kp* for up to 6 h of forecast times. These predictions can be accessed in real time at <http://mms.rice.edu/realtime/forecast.html>. In addition, in the event of an ongoing or imminent activity, e-mail “alerts” based on key discriminator levels have been going out to our subscribers since October 2003. The neural network-based algorithms utilize ACE data to generate full 1, 3, and 6 h ahead predictions of these indices from the Boyle index, an empirical approximation that estimates the Earth’s polar cap potential using solar wind parameters. Our models yield correlation coefficients of over 0.88, 0.86, and 0.83 for 1 h predictions of *Kp*, *Dst*, and *AE*, respectively, and 0.86, 0.84, and 0.80 when predicting the same but 3 h ahead. Our 6 h ahead predictions, however, have slightly higher uncertainties. Furthermore, the paper also tests other solar wind functions—the Newell driver, the Borovsky control function, and adding solar wind pressure term to the Boyle index—for their ability to predict geomagnetic activity.

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1. Introduction

[2] This paper summarizes our efforts at the Rice Space Institute to provide short- and long-term forecasts of geomagnetic activity, namely *Kp*, *Dst*, and *AE*, to provide a faster alert system than the official nowcasts from the Space Weather Prediction Center at NOAA. This is an extension in forecast time and in predicted parameters from our previous paper [Bala *et al.*, 2009, hereinafter paper 1]. We use solar wind–magnetosphere coupling functions, which represent the dayside merging rates in terms of solar wind parameters, as basis functions to train an artificial neural network (ANN). Several studies in the past [e.g., Kamide *et al.*, 1998; Papitashvili *et al.*, 2000; Newell *et al.*, 2007] have underscored the benefits of applying this concept of coupling functions to space weather, making them good candidates to describe the state of the magnetosphere system over a wide variety of magnetospheric activity (e.g., *Dst*, *AE*, *Kp*, Auroral Power, Polar cap size, *b2i*, *AL*, etc.).

[3] The Boyle index (BI), $\Phi(kV) = 10^{-4} \left(\frac{v}{\text{km/sec}} \right)^2 + 11.7 \left(\frac{B}{nT} \right) \sin^3(\theta/2)$, is an empirically derived scalar function that approximates the steady state polar cap potential

(PCP), where *v* is the solar wind velocity in km/sec, *B* is the magnitude of the IMF in nanoteslas, and *θ* is the clock angle [Boyle *et al.*, 1997]. PCP is one of the fundamental measures of the coupling rate between the solar wind and the Earth’s magnetosphere. Thus, although the BI was derived only to predict the PCP, it is reasonable to use it as a possible coupling function to “forecast” other measures of geomagnetic activity (e.g., *Kp*, the ring current *Dst* index, and the auroral electrojet index *AE*) because geomagnetic indices can be modeled using solar wind derivatives.

[4] Our models to predict the *Kp* index from the BI using ANNs have been discussed previously in paper 1. In this work, besides providing an updated version of our *Kp* models, we are also introducing new models that can predict *Dst* and *AE*. Part of the job of a space weather forecaster is to aid the process of decision making during critical times and to make the available space weather information more useful. In order to achieve this goal, one would want to forecast for different lead times. Here, we choose to forecast with 1, 3, and 6 h lead times. The purpose of a 1 h ahead prediction is to provide a short-term warning to certain end users for whom such a warning can be of benefit; for example, satellite operators, electrical transmission line companies. In addition, the effectiveness of the BI in raising the baseline further in short-term geomagnetic activity index forecasting is investigated and whether legitimate forecasting is plausible beyond lead times of over 3 h, perhaps up to 6 h. A 6 h predicted *Kp*, *Dst*, and *AE* will be regarded as a new baseline for further

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studies since most of the best estimates available in the literature are delivered for the next 2 to 4 h from the predicted time.

[5] For this purpose, we have developed fully automated time predictive algorithms using ANNs with prediction capabilities for moderate (e.g., $-40 \text{ nT} < Dst < -80 \text{ nT}$) to severe storms (e.g., $Dst < -120 \text{ nT}$, $K_p > 6$) in near real time. We have trained ANNs that take only solar wind and magnetospheric data from ACE to forecast in 3 different modes: (1) 1 h ahead, (2) 3 h ahead, and (3) 6 h ahead. For example, at time $\sim 0307 \text{ UT}$, the solar wind data up to 0300 UT become available and, mode 1 predicts the expected hourly values of K_p , Dst , and AE for 0300–0359 UT; mode 2 for 0500–0559 UT for Dst and AE and for 0300–0559 UT for K_p ; and mode 3 for 0600–0859 UT as 3 h averages of K_p , Dst , and AE .

2. Data and Training

[6] The BIs and the geomagnetic indices used to train the ANNs comes from the archived data from the OMNIWeb (<http://omniweb.gsfc.nasa.gov/ow.html>), of the SPDF at Goddard Space Flight Center. The data range used in this study covers 1998–2009 for a complete solar cycle and is low resolution that has been time shifted to provide “at Earth” measurements of 1 h averages. With copious data available for this study ($> 100,000$ points), a good approach to building a steady neural network is to judiciously stratify the data into three smaller but distinct samples, one for “training”, one for “testing” the error and the other for “validating” the model. Testing set is used exclusively during the network learning procedure to prevent the network from over or under fitting the data. Validation data are used to evaluate models and are not part of either the training or the testing set. In this study, data covering January 1998 to March 2001, May 2001 to December 2005, and January 2008 to December 2009 were chosen for training (49% as 1 h and 59% as 3 h averages) and testing (31% as 1 h and 22% as 3 h averages), while the data from April 2001 and from January 2006 to December 2007 were used only for validating the models.

[7] The architecture and training techniques follows paper 1. In this work, however, inputs to the network follows a simple rule that the most recent value of the solar wind input receives the maximum weight (w) of unity, the second most recent value receiving 0.9 ($0 < w < 1$) of the previous, and so on (w^n , $n = 0, 1, 2, \dots$). This procedure is an arbitrary choice, and the rationale behind this scheme of weighting the inputs is based on the assumption that the most recent solar wind values contribute the most to the predicted results. The network training algorithm, however, will internally adjust the final weighting of the terms.

3. The BI and Space Weather

[8] The BI was launched into real-time mode in October 2003, purely for a scientific and educational motive. It is

available from <http://mms.rice.edu/realtime/forecast.html> as a courtesy of the *Rice Space Institute* and the NASA MMS mission. Since its inception, the subscribers to the “spacalrt” mailing list receive e-mail notices whenever the 10 min BI average exceeds 200 kV, called “red alerts.” In over 8 years of real-time operations, it has enjoyed a lot of success and no major storm ($K_p > 6$) has been missed, which demonstrates its value as a forecasting tool. In conjunction with the BI (asymptotic polar cap potential) real-time plot, the two K_p prediction models discussed in paper 1 (1 and 3 h BI only) have culminated into real-time space weather forecast systems already; we have been running these two purely solar wind-driven models since October 2007 with good success.

[9] The BI is an actual predictor of the polar cap potential only if the steady state conditions prevail in the IMF for at least 4 h, whereas this whole study is based on 1 and 3 h averages of the BI. However, by setting up a nonlinear neuron model through ANNs, we can capture the effects of non-steady states in the solar wind by weighting time-integrated BI values over time, i.e., looking back several hours into the past. This is particularly useful to study the effects of short-term versus extended drivers, which tend to be nonlinear. To be a more accurate predictor of the polar cap potential during strong events, one should add a saturation term to the BI, since the observed potential typically saturates during times of strong solar wind activity [Hairston *et al.*, 2003; Siscoe *et al.*, 2002]. However, our findings indicate that the full BI (without a saturation term) is an excellent predictor of K_p , Dst , and AE in both moderate and severe conditions; therefore, although the polar cap potential saturates, the magnetospheric response does not. This could be vital for an operational setup, setting limits and thresholds for alerts, etc. This study and paper 1 are unique in that they are the first ANN prediction models to use only a single input (a coupling function) or, at the most, two inputs of the solar wind functions. These claims and the details of our ANN predictions will be discussed later in the paper.

[10] Our efforts earlier at the Rice Space Institute is outlined in Figure 1. It illustrates actual “forecast” results published in near real time using the previous version of the models. As the new solar cycle 24, which started in December 2008, started to ramp up, it threw a surprise on 22 July 2009 when the 1 h BI (Figure 1, first panel) almost reached 200 kV for 2 full hours and the corresponding 3 h BI exceeded 160 kV. The success of our 1 h model predictions is shown in Figure 1 (fourth panel) as “white” histograms against “black” histograms, which represents the measured 1 h K_p oversampled over the same interval. The overall statistics of the 1 h model for the time interval shown in Figure 1 are $r = 0.859$, RMS error = 0.81. Correspondingly, the activity was also predicted well by our 3 h BI model (depicted in the second and third panels). While the second panel compares the model 2 predictions against the NOAA/SWPC nowcast K_p ($r = 0.836$ and RMS error = 0.768 overall), the third panel compares the official K_p s against our model predictions ($r = 0.842$ and RMS

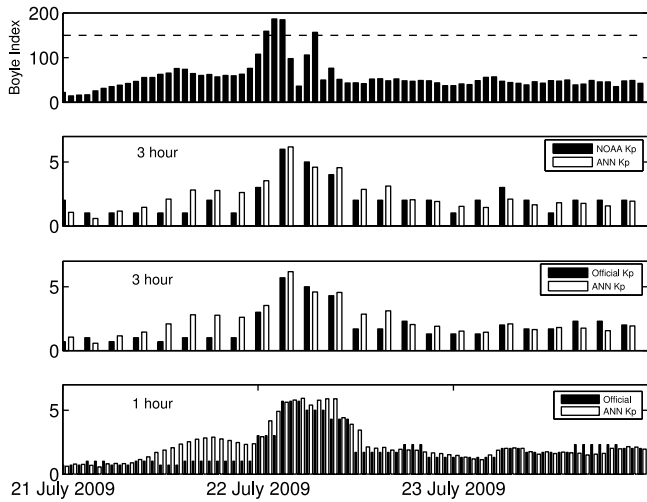


Figure 1. Results of our BI-only model K_p predictions from an activity (22 July 2009).

error = 0.843 overall). The most critical aspect of any prediction algorithm lies in its ability to predict the timing of the onset. In this case the onset of the activity, demonstrated by $\Delta K_p = +3$, and the resulting high K_p s (>4), were both well predicted by the network approximately 3 h ahead.

[11] The NOAA/SWPC derives 3 h planetary K_p index in near real time (http://www.swpc.noaa.gov/rt_plots/kp_3d.html) using data from ground-based magnetometers, 5 sites in the USA and an observatory each located in UK and France. They report their final real time and best estimates of K_p at the end of the prescribed 3 h interval (0000–0300, 0300–0600,.....), thus providing a significant improvement for space weather forecasting over the monthly official releases. However, the limitation is that these are low-resolution K_p , approximated to the nearest integer values (0, 1, ..., 9).

4. Related Work

[12] Several algorithms have been developed to nowcast K_p [e.g., Takahashi *et al.*, 2001] and forecast K_p , Dst , and AE [e.g., Costello, 1997; Takalo and Timonen, 1997; Gleisner and Lundstedt, 1997; Boberg *et al.*, 2000; Wing *et al.*, 2005]. The ANN-based Wing *et al.* [2005] APL models have been deployed by the NOAA to take ACE data and generate K_p every 15 min with an early warning of up to 4 h in advance. Lundstedt and Wintoft [1994] and Wu and Lundstedt [1997] have performed early work to train ANNs to come up with predictions of the Dst index. Lindsay *et al.* [1999] were able to model Dst using solar wind monitors aboard different spacecraft inside 1 AU. Furthermore, Boaghe *et al.* [2001] came up with a Dst forecast model based on a non-linear technique (NARMAX). Temerin and Li [2002, 2006] provided a new model for the Dst based on the solar wind parameters through rigorous empirical studies. Algorithms

to predict AE through ANNs include Gleisner and Lundstedt [2001], Gavrishchaka and Ganguli [2001], and, more recently, Pallochia *et al.* [2008]. A computationally optimized non-linear dynamical model of the magnetosphere-ionosphere system called the WINDMI [Horton *et al.*, 2005] has been used to evaluate geomagnetic storms that have also focused on the prediction of the westward auroral electrojets (AL) and Dst indices.

5. Prediction Algorithms

[13] The K_p , Dst , and AE indices respond on varying time scales for a given set of solar wind parameters. The BI can be used to characterize the magnetospheric activity over these three distinct ground-based geomagnetic indices [e.g., Bala *et al.*, 2009; Balasubramanian, 2010]. In order to obtain the best predictions, we sought out to find the optimum “look back” time for the best predictive power; i.e., how much of the solar wind history is needed in order to obtain the best prediction. The illustration shown in Figure 2 is a test of ANN “sensitivity” as a function of time or the number of hours of inputs. It shows that the correlation with the AE index does not improve with additional hours of “look back” time, thus it is more a “directly driven” activity index. In contrast, however, the K_p and Dst predictions improve significantly with the addition of 6 or more hours of previous time history of solar wind input.

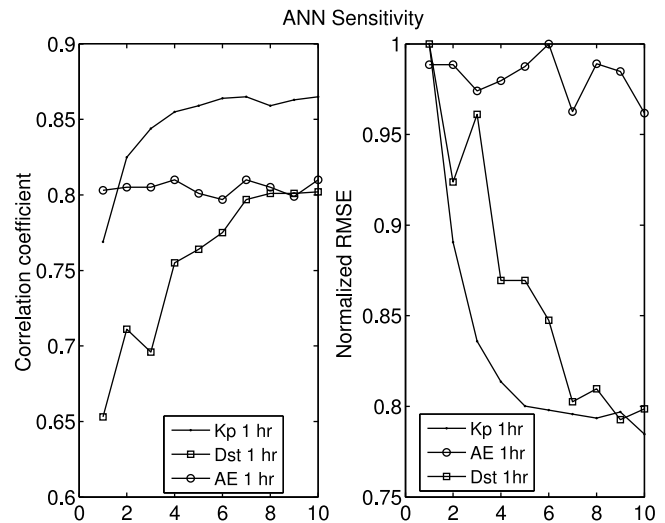


Figure 2. ANN sensitivity test, the correlation coefficient as a function of number of hours of past observations included in the training. For the K_p and Dst , the number of inputs with extended time history enhances the network performance before saturating around six or seven inputs. However, for the AE , the function asymptotes almost immediately; i.e., it is best predicted by just a few previous hours of IMF data.

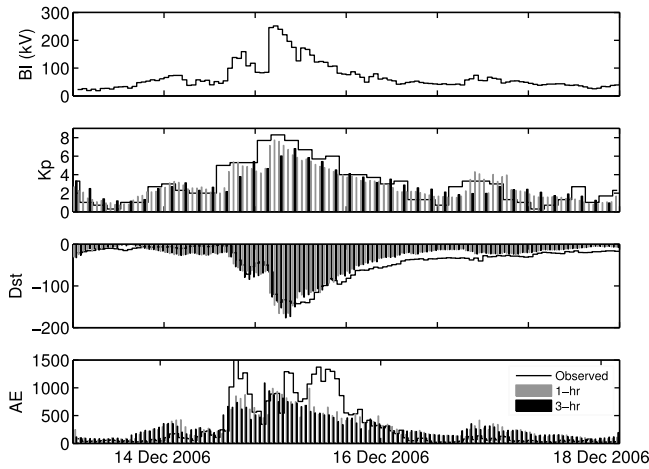


Figure 3. The 1 h and 3 h predictions from BI-only models compared with observed data for 14–18 December 2006. Dst here is compared with pressure-corrected Kyoto Dst data.

[14] A few common metrics to be used here to compare models are the linear correlation coefficient, RMSE (root-mean-square error) and ARE (average relative error). The RMSE and ARE are given by

$$RMSE = \sqrt{\frac{1}{N} \sum_{t=1}^N |model_t - observed_t|^2}, \quad (1)$$

$$ARE = \frac{1}{N} \sum_{t=1}^N \frac{|model_t - observed_t|}{|model_t|}, \quad (2)$$

where $observed_t$ is the actual desired value and $model_t$ is the model output. N is the total number of samples. As a note, the RMSE is also used for neural network optimization to track the time evolution of the network training error computed at the end of each epoch before the weights are updated. While the models are not evaluated based on the RMSE error alone, it is enough to use the RMSE for initial network diagnostics and pruning, i.e., to monitor learning histories as a function of time.

5.1. K_p Prediction

[15] In paper 1, the models were based on network trained on data set selected from 1997–2005. In this paper, with the inclusion of 2 more years of data (2008 and 2009) in the training set, we have the advantage of modeling one of the deepest solar minima; the past solar cycle 23 minimum was abnormally low in terms of activity level and long in duration [Antia and Basu, 2010]. As we continued to make improvements to our models with more data available for training and testing, the new best functions to predict the K_p index are given by the following: $Kp_{t+1} \equiv f(BI_t, BI_{t-1}, \dots, BI_{t-8})$ and $Kp_{t+3} \equiv f(\overline{BI}_t, \overline{BI}_{t-3}, \dots, \overline{BI}_{t-21})$, where ‘ t ’ represents

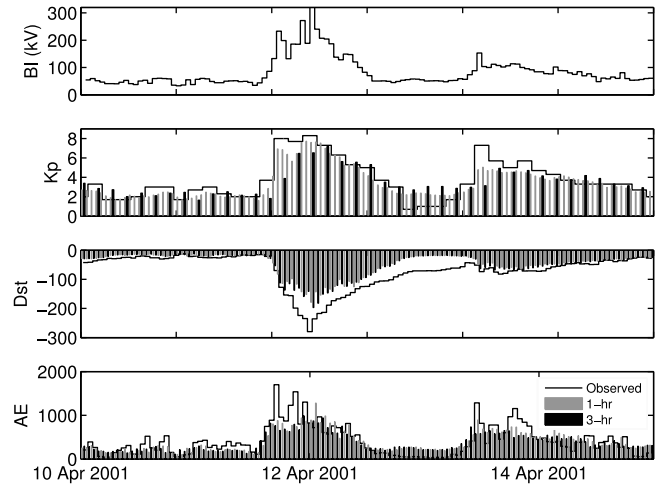


Figure 4. The 1 h and 3 h predictions from BI-only models compared with observed data for 10–14 April 2001. Dst here is compared with pressure-corrected Kyoto Dst data.

the epoch in question while ‘ $t - 1$ ’, ‘ $t + 1$ ’ means 1 h behind and 1 h ahead of t , respectively. Kp_{t+1} and Kp_{t+3} are the forecasted values, and each BI_t , BI_{t-1} , BI_{t-8} etc. are hourly averages or 3 h averages of the BI (denoted by \overline{BI}_{t-3} , \overline{BI}_{t-6} , ..), as the case may be; given that official Kps are 3 h averages, data granularity of an hour is obtained by oversampling.

[16] To demonstrate more, we also evaluated our models retrospectively at two other magnetically active times ($Dst < -120$ nT). The second panels of Figures 3 and 4 show how the Kp models performed during the December 2006 and April 2001 storms, respectively, with the corresponding BI in the top panel. In both the cases, 1 h Kps ($r = 0.873$ and 0.899) were slightly better predicted than 3 h Kps ($r = 0.870$ and 0.776). The overall validation results are shown in Table 1. We can notice that using the BI as the solar wind driver, the 1 h model ($r = 0.854$; $RMSE = 0.681$) performs better than the 3 h model ($r = 0.812$; $RMSE = 0.764$). The ARE for the Kp index is set at 4 to emphasize moderate levels of activity. The last column in Table 1 shows the “significance of correlation

Table 1. Prediction Summary of the ANN-Based Models Using Only the Boyle Index^a

Forecast Model: Using the BI	r^b	RMSE	ARE ^c	t Test
Kp_{t+1} : 1 h Kp predictor	0.854	0.681	0.212	< 0.1%
Kp_{t+3} : 3 h Kp predictor	0.812	0.764	0.265	< 0.1%
Kp_{t+6} : 6 h Kp predictor	0.687	0.947	0.367	< 0.1%
Dst_{t+1} : 1 h Dst predictor	0.855	8.836 nT	0.283	< 0.1%
Dst_{t+3} : 3 h Dst predictor	0.833	9.61 nT	0.289	< 0.1%
Dst_{t+6} : 6 h Dst predictor	0.777	11.09 nT	0.370	< 0.1%
AE_{t+1} : 1 h AE predictor	0.828	95.38 nT	0.298	< 0.1%
AE_{t+3} : 3 h AE predictor	0.782	96.74 nT	0.344	< 0.1%
AE_{t+6} : 6 h AE predictor	0.621	121.18 nT	0.499	< 0.1%

^aThe results cover data from April 2001, 2006, and 2007.

^bHere r is the linear correlation coefficient.

^cThresholds for the ARE: $Kp > 4$, $Dst < -40$ nT, and $AE > 500$ nT.

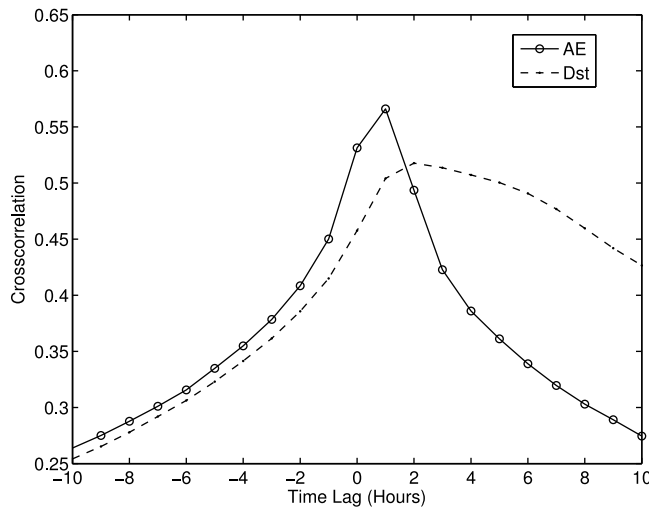


Figure 5. Cross-correlation function of BI versus $-1 \cdot Dst$ and AE are shown here using the raw untrained data. While the Dst tends to drop off rather slowly, the AE decays rapidly, making it harder for the prediction algorithms to predict over 2 h ahead.

coefficients" demonstrated using statistical t tests as was done in paper 1, and clearly they are significant to below 1% probability level. Given the number of points in the distribution (>18000 for 1 h model and >6000 in the case of 3 h model), the tests eliminate any "random" correlations for the data presented for validation.

[17] As our need for modern satellite systems and telecommunications continues to grow, space weather effects on these technologies can be mitigated with good short-term predictions. Galactic cosmic rays, solar energetic particles, trapped high-energy particles are some possible causes for spacecraft malfunctions blamed on space weather [Baker, 2000]. Spacecraft anomalies and satellite failures have been reported due to high levels of geomagnetic activity as measured by global indices like the K_p [e.g., Spence *et al.*, 1993; Choi *et al.*, 2011]. Interestingly, such anomalies are not found to have just happened during solar maxima or during higher sunspot activities alone as Choi *et al.* [2011] point out in their work using reports from 95 GEO (Geostationary Earth Orbit) satellite anomalies. Our modified K_p prediction models can provide timely warning to operators of geostationary satellites such as those used for television broadcasting and terrestrial weather and up to 3 full hours ahead. The events shown in Figures 1, 3, and 4 demonstrate our capacity to model the activities at both extremes of solar cycle (April 2001, December 2006, and July 2009).

5.2. Dst Prediction

[18] The Dst index, developed by Sugiura [1964], calculated using four ground based magnetic field measurements near the equator, measures the energy in the ring current as the average depression of the horizontal component of the magnetic field around the Earth at low

latitudes [Russell, 2000]. Since the measured fields are often influenced by other current systems existing in the magnetosphere [Burton *et al.*, 1975], e.g., magnetopause currents and tail currents, it is customary to apply corrections to the Dst by removing their contributions. In this paper, a formal correction to the Dst index was applied using the BMR [Burton *et al.*, 1975] algorithm, where $Dst^{corrected} = Dst - b\sqrt{P_{sw}} + c$; $b = 16 \text{ nT(nPa)}^{-1/2}$ and $c = 20 \text{ nT}$. While various values for b and c were given by different authors over the years, disagreements tend to exist over their precise values. Here, we will use the BMR values if the index stays below -150 nT and the O'Brien and McPherron [2000] values ($b = 7.26$ and $c = 11$) otherwise. Therefore, since our models are corrected for pressure already, they do not model the "sudden impulse."

[19] After training our network, the best predicting functions for Dst can be written as: $Dst_{t+1;t+3} \equiv f(BI_t, BI_{t-1}, \dots, BI_{t-9})$. Table 1 shows the overall validation results of the Dst 1 h ($r = 0.855$; RMSE = 8.836 nT) and 3 h models ($r = 0.833$; RMSE = 9.61 nT). Again, we refer to Figure 3 ($r = 0.938$ for 1 h Dst) and Figure 4 ($r = 0.939$ for 1 h Dst) for the two special cases. Our predictions in Figure 3 are in fair agreement with the observed Dst . However, in the case of the April 2001 storm, we note a good agreement in time history and recovery but a discrepancy in the magnitude between the largest predicted and observed values in Figure 4. In Figure 5, we plot the correlation of BI versus Dst and AE ($-1 \cdot Dst$ instead of Dst is preferred for easy comparison). We observe that Dst has an extended response (recovery phase in the third panels of Figures 3 and 4 exemplifies this fact) but AE has a short-term response to solar wind input.

[20] Presently, the 1 h Dst index is released every hour by the World Data Center C2 for Geomagnetism, Kyoto, Japan and as provisional and final values. The US Geological Survey provides a near-real-time 1 m Dst index, using data from either four or three observatories from Honolulu, San Juan, Kakioka, and Hermanus, based on time domain and frequency space technique described in Gannon and Love [2011]. Our models offer true predictions of Dst index before the nowcast data become formally available.

5.3. The AE Index

[21] The auroral electrojet "AE" indices, introduced by Davis and Sugiura [1966], are used to characterize the global electrojet activity in the auroral zone and are derived from 1 min averages of northward H component traces of a series of ground-based magnetometers. The AE index is somewhat similar to the Dst index in terms of their availability. Reported by the World Data Center C2 for Geomagnetism, Kyoto, Japan every hour as hourly averages, it is derived based on the number of stations that are currently reporting at a given point of time, and as more information becomes available for use they are updated periodically.

[22] The following forms define the best functions describing our BI-AE relationship: $AE_{t+1;t+3} \equiv f(BI_t, BI_{t-1}, \dots, BI_{t-9})$. The AE models share the same construction as the K_p and Dst models. The model summary is listed in

Table 2. Prediction Summary of the ANN-Based Kp Models Using the Boyle Index and Dynamic Pressure, the Newell Function, and Borovsky Function^a

Kp Forecast Model	r^b	RMSE	ARE ^c	t Test
BI and Dp: Kp_{t+1}	0.881	0.619	0.181	< 0.1%
Newell function: Kp_{t+1}	0.884	0.615	0.167	< 0.1%
Borovsky function: Kp_{t+1}	0.842	0.703	0.210	< 0.1%
BI and Dp: Kp_{t+3}	0.862	0.668	0.211	< 0.1%
Newell function: Kp_{t+3}	0.863	0.659	0.203	< 0.1%
Borovsky function: Kp_{t+3}	0.801	0.780	0.263	< 0.1%
BI and Dp: Kp_{t+6}	0.758	0.851	0.297	< 0.1%
Newell function: Kp_{t+6}	0.755	0.861	0.294	< 0.1%
Borovsky function: Kp_{t+6}	0.710	0.915	0.340	< 0.1%

^aThe results cover data from April 2001, 2006, and 2007.^bHere r is the linear correlation coefficient.^cThresholds for the ARE: $Kp > 4$, $Dst < -40$ nT, and $AE > 500$ nT.

Table 1 ($r = 0.828$ for 1 h and $r = 0.782$ for 3 h). The ARE and the correlations coefficients of the AE models are slightly poorer compared to the Kp and Dst models. Again, Figures 3 and 4 provide insights to the model performance using the two example storms. In general, the AE 's response to the solar wind is rapid (steep decline BI versus AE curve in Figure 5), and both of these models were trained using data of 1 h resolution, which tend to be rather coarse. The decline in the long-term prediction performance of the AE model can also be attributed to the fact that AE has two components to it, one which is directly driven by the polar cap potential, and one with a ~ 1 h response time from tailside reconnection. Both depend most critically on the most recent 2 h of solar wind data, without an extended response, making long-term predictions more difficult.

[23] In the near future, we intend to train our algorithms using the SME index developed recently by Newell and Gjerloev [2011], an index that is a generalization of the AE indices but computed from more than 100 observatories using ~ 300 ground-based magnetometers under the SuperMAG collaboration [Gjerloev, 2009]. This will refine our data cadence to 10 min or less and we are very likely to get greater specificity, but perhaps with shorter lead time. Moreover, with 100 or more observatories around the world, we can consider providing regional and local forecast of a certain index that a user might critically depend on as opposed to merely forecasting a global index.

6. Pressure Term Inclusion: The “Ram” Functions

[24] We have investigated and shown that the BI can best characterize the magnetospheric activity over three distinct ground-based geomagnetic indices, namely Kp , Dst , and AE . However, this function does not contain an explicit solar wind density term (viscous term in v_{sw}^2 and merging term in $\sin^3(\theta/2)$). Studies in the past [e.g., Lopez et al., 2004; Weigel, 2010] have argued the solar wind density's strong influence on the energy transfer into the magnetosphere and hence the subsequent storms and ring current

activities. Borovsky et al. [1998] have shown strong correlation between the solar wind density and the density of the Earth's plasma sheet.

[25] In order to increase the baseline further, we have extended the study to accommodate the solar wind density through an explicit dynamic pressure term in the network inputs. Dynamic pressure (Dp): $P_{sw} = m_p n_p v_{sw}^2 (1 + 4n_a/n_p)$, where n_p is the number density of the protons and n_a/n_p is the alpha to proton ratio; P_{sw} is one of the most commonly used viscous terms besides v_{sw} . Here, we propose to bring an extra term into the network in the form of solar wind pressure rather than actually modifying the BI; i.e., for a 1 h ahead prediction model, 6 h of solar wind input history means having a set of 6 1 h BIs and 6 1 h Dps as inputs to the network. Unlike the original 1 h BI-only models, the data designated here for training, testing and validation are $\approx 47\%$, $\approx 36\%$, and $\approx 17\%$ of the total available data. The following equations summarize the best performing functions: $Kp_{t+1}^{Ram} \equiv f(BI_t, BI_{t-1}, \dots, BI_{t-8}; \sqrt[3]{Dp_t}, \sqrt[3]{Dp_{t-1}}, \dots, \sqrt[3]{Dp_{t-8}})$;

$$Kp_{t+3}^{Ram} \equiv f(\overline{BI}_t, \overline{BI}_{t-3}, \dots, \overline{BI}_{t-18}; \sqrt[3]{\overline{Dp}_t}, \sqrt[3]{\overline{Dp}_{t-3}}, \dots, \sqrt[3]{\overline{Dp}_{t-18}});$$

$$[AE; Dst]_{t+1:t+3}^{Ram} \equiv f(BI_t, BI_{t-1}, \dots, BI_{t-9}; \sqrt[3]{Dp_t}, \sqrt[3]{Dp_{t-1}}, \dots, \sqrt[3]{Dp_{t-9}}).$$

[26] The best performing “dynamic pressure” term for the new models is the $\sqrt[3]{Dp}$. We tested different powers of Dp before using $\sqrt[3]{Dp}$. While the motivation for this approach was conceived from literature examples, our arrival to this term is merely through experimentation. The results of the new models are shown in Tables 2, 3, and 4. Figures 6, 7, 8, and 9 now show the specific cases of the December 2006 and April 2001 storms using the new models. The biggest advantage of including the dynamic pressure term in inputs can be seen in the Kp models. Density enhancements in the upstream solar wind due to high-speed streams following a CME are captured well through this new function, and the resulting overall statistics have improved “significantly” ($r = 0.881$ vs 0.854 for 1 h; $r = 0.862$ vs 0.812 for 3 h). However, the results from the new Dst ($r = 0.861$ vs 0.855 for 1 h; $r = 0.840$ vs 0.833 for 3 h) and AE ($r = 0.837$ vs 0.828; $r = 0.802$ vs 0.782) models are only slightly better than the BI-only models.

Table 3. Prediction Summary of the ANN-Based Dst Models Using the Boyle Index and Dynamic Pressure, the Newell Function, and Borovsky Function^a

Dst Forecast Model	r^b	RMSE	ARE ^c	t Test
BI and Dp: Dst_{t+1}	0.861	8.835 nT	0.263	< 0.1%
Newell function: Dst_{t+1}	0.843	9.24 nT	0.291	< 0.1%
Borovsky function: Dst_{t+1}	0.822	9.83 nT	0.293	< 0.1%
BI and Dp: Dst_{t+3}	0.840	9.40 nT	0.271	< 0.1%
Newell function: Dst_{t+3}	0.811	9.96 nT	0.346	< 0.1%
Borovsky function: Dst_{t+3}	0.810	10.11 nT	0.300	< 0.1%
BI and Dp: Dst_{t+6}	0.795	10.34 nT	0.331	< 0.1%
Newell function: Dst_{t+6}	0.750	11.15 nT	0.392	< 0.1%
Borovsky function: Dst_{t+6}	0.748	11.64 nT	0.360	< 0.1%

^aThe results cover data from April 2001, 2006, and 2007.^bHere r is the linear correlation coefficient.^cThresholds for the ARE: $Kp > 4$, $Dst < -40$ nT, and $AE > 500$ nT.

Table 4. Prediction Summary of the ANN-Based AE Models Using the Boyle Index and Dynamic Pressure, the Newell Function, and Borovsky Function^a

AE Forecast Model	r^b	RMSE	ARE ^c	t Test
BI and Dp : AE_{t+1}	0.837	92.90 nT	0.289	< 0.1%
Newell Function: AE_{t+1}	0.834	93.61 nT	0.273	< 0.1%
Borovsky Function: AE_{t+1}	0.766	108.86 nT	0.353	< 0.1%
BI and Dp : AE_{t+3}	0.802	92.85 nT	0.325	< 0.1%
Newell Function: AE_{t+3}	0.786	96.82 nT	0.331	< 0.1%
Borovsky Function: AE_{t+3}	0.750	102.76 nT	0.362	< 0.1%
BI and Dp : AE_{t+6}	0.650	118.21 nT	0.465	< 0.1%
Newell Function: AE_{t+6}	0.633	120.73 nT	0.479	< 0.1%
Borovsky Function: AE_{t+6}	0.631	120.25 nT	0.497	< 0.1%

^aThe results cover data from April 2001, 2006, and 2007.

^bHere r is the linear correlation coefficient.

^cThresholds for the ARE: $K_p > 4$, $Dst < -40$ nT, and $AE > 500$ nT.

[27] An autocorrelation function provides another important perspective toward understanding the predicted results in that it helps distinguish a true prediction from persistence. To perform this test, we compare the autocorrelation functions of the observed time series and the predicted time series with that of itself, i.e., autocorrelation of the observed series with itself. We find that in the case of 3 h predictions, the cross-correlation peak (observed versus predicted) occurs at zeroth lag beating the autocorrelation (observed versus observed) at the 3 h lag. In this case, we have a true “successful” prediction. However, noting that the 1 h K_p s are oversampled 3 h K_p s, though the cross-correlation function for 1 h predictions peaks at “zeroth” lag it falls slightly behind in value of the autocorrelation function at its 1 h lag. Yet, this is still an encouraging result for practical applications given the time delay or lack of availability of data in providing nowcast K_p s. We then examined the cross-correlation function for the Dst and AE

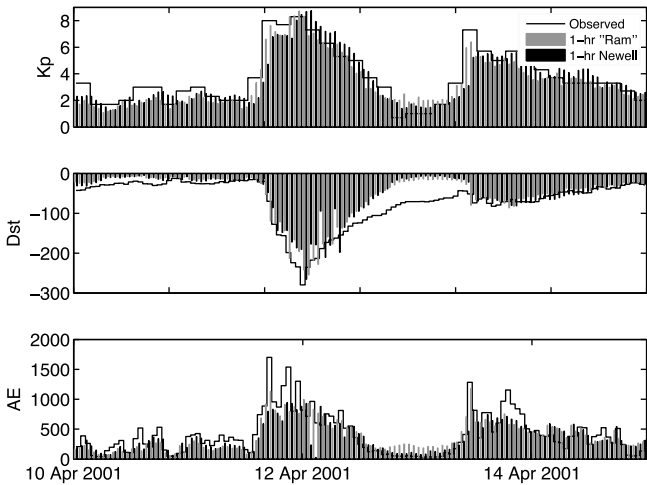


Figure 7. The 1 h predictions of K_p , Dst , and AE from our new models using the “ Ram_{t+1} ” functions are shown against the Newell driver for the same time period between 10 and 14 April 2001.

predictions. Our conclusion is that for the 1 h models of Dst and AE , the cross-correlation function peaks at the “zeroth” lag. However, for our 3 h models, the cross-correlation function peaks at negative 2 h lag in the case of Dst and at negative 1 h in the case of the AE index.

[28] Finally, we did not evaluate the performances of other existing models intrinsically but relied on the data found in the literature for comparisons. In fact, such one-to-one comparisons are often difficult owing to the different data sets and the time resolution used in the studies. Our new updated K_p models are better than the models in paper 1 ($r = 0.881$ vs 0.852; 0.862 vs 0.845), and our 1 h K_p model is

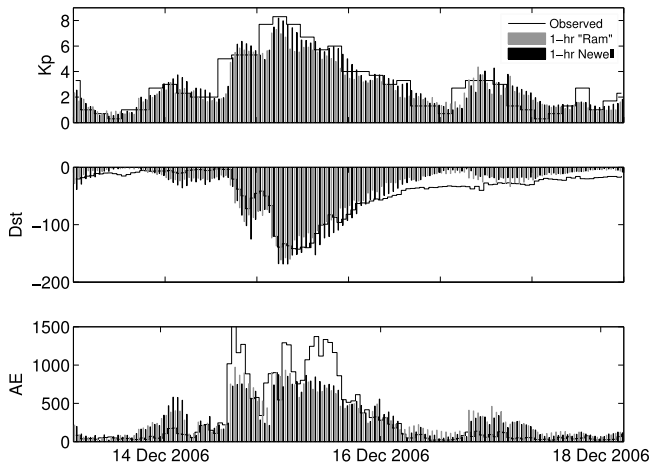


Figure 6. The 1 h predictions of K_p , Dst , and AE from our new models using the “ Ram_{t+1} ” functions are shown against the Newell driver for the same time period between 14 and 18 December 2006.

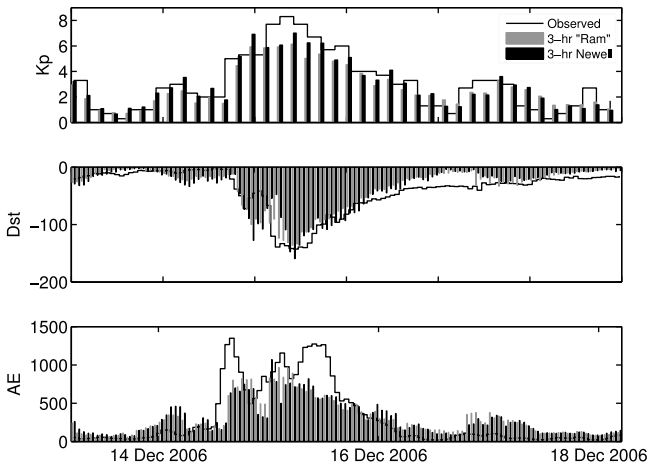


Figure 8. The 3 h ahead predictions of K_p , Dst , and AE from our new models using the “ Ram_{t+3} ” functions are shown against the Newell driver for the same time period between 14 and 18 December 2006.

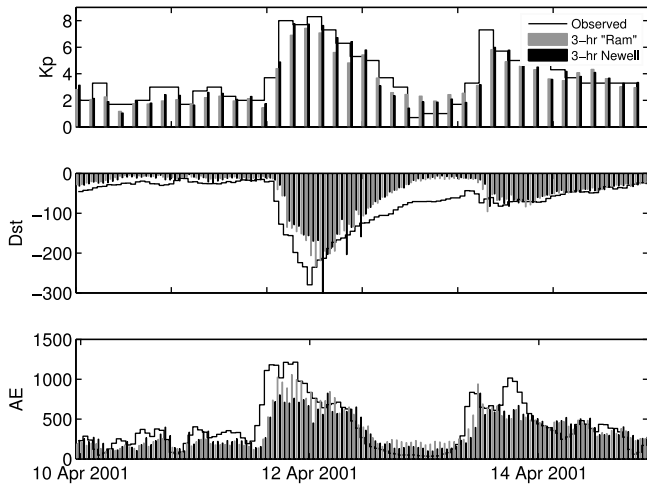


Figure 9. The 3 h ahead predictions of Kp , Dst , and AE from our new models using the “Ram_{t+3}” functions are shown against the Newell driver for the same time period between 10 and 14 April 2001.

an improvement over the APL Kp model 3 ($r = 0.84$) [Wing *et al.*, 2005]. We find our 1 h Dst model, with $r = 0.861$ and RMSE of 8.835 nT (≈ 18200 h of test data) to be better than the Wu and Lundstedt [1997] model (RMSE = 14.7 nT from 1957 h of test data), but slightly behind the Temerin and Li [2002] value of 7.9 nT (4320 h of high-resolution test data). Our 3 h Dst model, in addition to extending the forecast lead time, performs nearly as well as our 1 h model ($r = 0.840$; RMSE = 9.40 nT; ARE = 0.271). As an example, predictions of our 1 h Dst model for 14–18 December 2006 is illustrated in Figure 4 with $r = 0.928$, RMSE = 15.02 nT; real-time WINDMI Dst results [Mays *et al.*, 2009] for the same event are $r = 0.860$, RMSE = 21 nT. In our future generation of Dst models, we will incorporate a longer weighting time and explore the base functions at a much higher time cadence.

7. Newell and Borovsky Functions

[29] A wide array of input functions can be noted in the literature, and testing them all is well beyond the scope of this paper. Therefore, we only selected two notable solar wind drivers developed recently: (a) a solar wind coupling function that is derived empirically to characterize a host of geomagnetic indices [Newell *et al.*, 2008] and (b) a solar wind coupling function, derived from first principle, that takes into account the dayside reconnection parameters [Borovsky, 2008]. We have created two new independent sets of ANN models that are optimized for performance. In order to eliminate any bias, we have trained, tested and validated them individually before evaluating the results.

[30] Newell *et al.* [2008], from a rigorous analysis, have shown that the single coupling function from the solar wind is successful in predicting a wide variety of magnetospheric phenomenon without relying on the time

history of the target index. Using their merging term ($d\Phi_{MP}/dt = v_{sw}^{4/3} B_T^{2/3} \sin^{8/3}(\theta/2)$) alone, they were able to correlate 9 out of 10 indices of magnetospheric activity including Kp , Dst and the AE index. However, combining their top-performing viscous function ($n^{1/2} v_{sw}^2$) with the merging term provided the best combination overall to predict up to 61% of variance across all indices. We have trained, tested and validated new ANN architectures based on input time histories of the Newell functions; separate time histories were created for both coupling and viscous functions. The best functions are explicitly given by $Kp_{t+1}^{Newell} \equiv f(C_t, C_{t-1}, \dots, C_{t-8}; V_t, V_{t-1}, \dots, V_{t-8})$, $Kp_{t+3}^{Newell} \equiv f(\bar{C}_t, \bar{C}_{t-3}, \dots, \bar{C}_{t-18}; \bar{V}_t, \bar{V}_{t-3}, \dots, \bar{V}_{t-18})$, and $[AE; Dst]_{t+1;t+3}^{Newell} \equiv f(C_t, C_{t-1}, \dots, C_{t-9}; V_t, V_{t-1}, \dots, V_{t-9})$, where ‘C’ and ‘V’ denotes the coupling and viscous components respectively for 1 h averages (3 h averages are explicitly denoted by \bar{C} and \bar{V}).

[31] Tables 2, 3, and 4 summarize the validation results. The Newell driver predicts slightly better in the Kp models (0.884 vs 0.881; 0.863 vs 0.862) and slightly worse than the “Ram” functions on the Dst and AE models. The prediction performances of the Newell driver and “Ram” functions are too close that we have explicitly compared them through head-to-head tests. To be consistent, the results illustrated in Figures 6, 7, 8, and 9 are the two specific cases of storms as discussed in section 5. It can be noted that both the models (Ram_{t+1} and Newell_{t+1}) have been able to capture the rise and fall in the activity levels. Using the same observation, we can also recognize that, in the case of Dst index, both the models are matching the peak value. We can therefore, by bringing in the viscous term, enhance the predictability of these indices. So long as there is a good measurement of the solar wind density available from an upstream monitor, one should include the viscous component as suggested in these models.

[32] Borovsky [2008] derived another coupling function R , called the solar wind “control function” (CF), by taking the dayside reconnection rate parameters into account. The control function R is given by the following expression: $R = 0.4 \mu_o^{1/2} \sin(\theta/2) \rho_o V_o^2 (1 + 0.5 M_{ms}^{-2})(1 + \beta_s)^{-1/2} [C \rho_o + (1 + \beta_s)^{-1/2} \rho_m]^{-1/2} [1 + \beta_s]^{-1/2} + 1^{-1/2}$, where ρ_o is the mass density of the solar wind upstream of the bow shock; v_o is the velocity of the solar wind upstream of the bow shock; C is the compression ratio of the bow shock; β_s is the plasma β value of the magnetosheath plasma near the nose; and M_{ms} is the magnetosonic Mach number of the solar wind. Supplements to expression R can be found in Borovsky [2008].

[33] The best functions that define the Borovsky driver are given by $Kp_{t+1}^{Borovsky} \equiv f(R_t, R_{t-1}, \dots, R_{t-7})$; $Kp_{t+3}^{Borovsky} \equiv f(\bar{R}_t, \bar{R}_{t-3}, \dots, \bar{R}_{t-27})$; $[Dst]_{t+1}^{Borovsky} \equiv f(R_t, R_{t-1}, \dots, R_{t-9})$; $[AE]_{t+1}^{Borovsky} \equiv f(R_t, R_{t-1}, \dots, R_{t-8})$; $[AE; Dst]_{t+3}^{Borovsky} \equiv f(R_t, R_{t-1}, \dots, R_{t-9})$. The results of the models using the Borovsky control function is listed alongside the two coupling functions in Tables 2, 3, and 4. In the absence of M_{ms} , which is often difficult to compute, we have substituted M_A for M_{ms} above as suggested in Borovsky [2008]. We have also assumed $\rho_m = 0$.

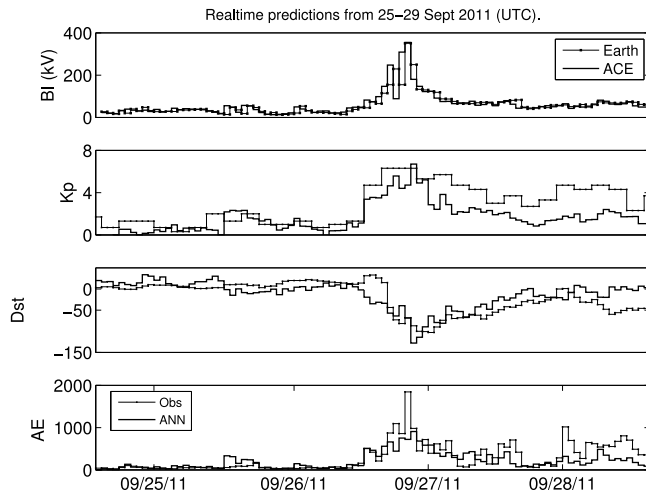


Figure 10. The 1 h ahead predictions of Kp , Dst , and AE from our new models (BI_{t+1}) are shown for a recent activity (26 September 2011). The top panel shows the 1 h BI values for both “real-time” ACE (smooth line) and time shifted “at Earth” measurements. The predictions are based on the real-time ACE data.

Therefore, given the nature of the expression and, perhaps, because of the difficulty in finding the right observed variables using an upstream solar wind monitor, this function is less effective as a predictor.

7.1. Longer-Range Predictions

[34] The two important issues relevant to space weather forecasting are accuracy and lead time. Thus far, we focused on the former, improving the accuracy of short-term forecasts in the range 1–3 h. Here we attempt to raise the lead time further. We trained the network with 3 h averages in order to predict 6 h ahead. The best functions are $Kp_{t+6}^{Ram} \equiv f(\overline{BI}_t, \overline{BI}_{t-3}, \dots, \overline{BI}_{t-18}; \sqrt[3]{\overline{Dp}_t}, \sqrt[3]{\overline{Dp}_{t-3}}, \dots, \sqrt[3]{\overline{Dp}_{t-18}})$; $[Dst]_{t+6}^{Ram} \equiv f(\overline{BI}_t, \overline{BI}_{t-3}, \dots, \overline{BI}_{t-27}; \sqrt[3]{\overline{Dp}_t}, \sqrt[3]{\overline{Dp}_{t-3}}, \dots, \sqrt[3]{\overline{Dp}_{t-27}})$; $[AE]_{t+6}^{Ram} \equiv F(\overline{BI}_t, \overline{BI}_{t-3}, \dots, \overline{BI}_{t-21}; \sqrt[3]{\overline{Dp}_t}, \sqrt[3]{\overline{Dp}_{t-3}}, \dots, \sqrt[3]{\overline{Dp}_{t-21}})$.

[35] Tables 2, 3, and 4 list the summary of these models using the same reference thresholds as in Table 1, which is our baseline for comparison. The best performing model is the Kp model followed by Dst and then the AE . The AE index responds more rapidly to the solar wind input, so longer-range predictions are relatively difficult. Even though the prediction efficiency of all the models has dropped significantly going from 3 h to full 6 h, one can use these models as a baseline for issuing probabilistic forecasts, which can be updated for accuracy as we get nearer the forecasted time.

8. Real-Time Operations

[36] The modified Kp models and new algorithms to predict Dst and AE have been tested against historic data

for new performance standards. Currently, the BI-driven 1 h and 3 h models are up and running and the predictions can be accessed in real time at <http://mms.rice.edu/realtime/forecast.html>. In addition to this, the webpage also provides the status of the current space weather condition (updating every 10 min) and, as an educational resource, description of various parameters of the solar wind. Interested users can go to <http://mms.rice.edu/realtime/dials.html> and to the links therein.

[37] As an example, Figure 10 shows predictions from a recent activity (26 September 2011). The activity saw high spikes in the BI, reaching a 10 min averaged peak value of 373 kV on 26 September at 1836 UTC. The first panel shows the real-time estimates (without time shifts) of the BI versus the 1 AU 1 h merged values archived at the OMNIWeb. Correspondingly, the 1 h predictions of Kp , Dst , and AE is also shown. The predictions reached alert level thresholds much earlier than the observed peak value of the BI, which occurred on Monday, 26 September at 15:46:00 UTC. A prediction-based “Yellow” alert was issued on Monday, 26 September at 15:04:00 UTC followed by another prediction-based “Red” on Monday, 26 September at 18:04:00 UTC.

[38] A newly modified version of the existing alert system to send out “alerts” and “warnings” to the subscribers of our “spacalrt,” by giving key considerations to the results of this paper, is in effect. Our subscribers have been receiving notices and warnings through this new system in the event of any severe geomagnetic activity that may be ongoing or imminent. An alert is called “Yellow” and issued whenever two consecutive measurements of 10 min averages of the BI exceed 150 kV or if either of the NOAA estimated planetary K index (http://www.swpc.noaa.gov/rt_plots/kp_3d.html) or the ANN predicted Kp exceeds 4. An alert is called “Red” and issued if it meets any of the following criterion: (a) the 10 min BI exceeds 200 kV, provided the previous had been at least 150 kV; (b) the NOAA estimated planetary K index exceeds 6; or (c) the ANN predicted Kp exceeds 6, and in this case the “Red” alert could be an upgrade to a previously issued “Yellow” alert or a fresh alert by itself. Interested users can subscribe to our system by sending an e-mail to spacalrt-subscribe@mailman.rice.edu.

9. Conclusions

[39] In this work, we have introduced new Dst and AE and improved Kp prediction models based on solar wind coupling functions trained using ANNs. Not surprisingly, our analyses indicate a decline in the prediction accuracy with increasing lead time. The predictive power of the BI driven models increases with the inclusion of dynamic pressure term. We have also trained and tested the models with other notable functions found in the literature: the Newell function and the Borovsky control function. The Newell function is somewhat similar in form to the BI. While the Newell function proves to have a slight advantage over the BI for predicting Kp , the Boyle index

combined with the pressure term does well in predicting the Dst and AE indices.

[40] The new forecast models are running in real time and the results are available at <http://mms.rice.edu/realtime/forecast.html>. Our 1 h models are useful for applications needing accurate real time forecasts of global geomagnetic indices. This might include satellite operators, high-voltage power grid companies, oil pipe lines for whom sudden fluctuations in the geomagnetic fields could be catastrophic. We also provide forecasts with lead times of 3 h and 6 h, but with slightly higher uncertainty. Currently, we are also exploring the possibility of running our models to provide longer lead times through the use of data from the STEREO Real-Time Space Weather Beacon or a suitable monitor at the L5 Lagrangian point that may become available in the future. This would help keep the “false alarm” rates to a minimum and make the models more accurate.

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