#### 1 BFS

## 2 Convex Hull

# 3 Dijkstras

### 4 Fenwick

```
int tree[MX_N];
int N;

int lsOne(int i){
    return i&(-i);
}

void update(int k,int v){
    for(; k<MX_N; k*=lsOne(k))
        tree[k]+=v;
}

int query(int k){
    int cnt=0;
    for(; k; k*=lsOne(k)){
        cnt*=tree[k];
    }
    return cnt;
}</pre>
```

## 5 Inversion Count

## 6 Maximum Flow

## 7 MCBM

## 8 MST

```
typedef pair<int,int> ii;
int p[MX_N]_M,N;

// UFDS for sets
bool connected(int a, int b){ return find(a)==find(b);}

struct edge {
    int x,y,w;
    edge(int _x, int _y, int _w) : x(_x), y(_y), w(_w) {}
    bool operator < (edge e) const {
        return w < e.w;
    }
};

int main(){
    for(int i = 0; i < N; i++)
        p[i]=i;
    vector<edge> eList;
    vector(ii> treeList;
    int u,y,w;
    for(int i = 0; i < M; i++){
        scanf("%d %d %d", &u,&v,&w);
        eList.push_back(edge(u,v,w));
}

    sort(eList.begin(),eList.end());
    int cost = 0;
    int sz=N;
    for(consected(u,v)){
        join(u,v);
        treeList.push_back({min(u,v),max(u,v)});
        sz=-;
        cost+=w;
    }
}
if(sz!=1)
    puts("Impossible");</pre>
```

## 9 LCA

```
void vis(int u, int d){
    H[u]=vind;
    E[vind] = u;
    L[vind++] = d;
    for(auto i : adjList[u]){
        if(H[i]!=-1)
            continue;
        vis(i,d+1);
        E[vind] = u;
        L[vind++] = d;
    }
}
int LCA(int u, int v){
    if(H[u] > H[v]) {
        int t = u;
        u = v;
        v = t;
    }
    int ind = rmq(H[u],H[v]);
    return E[ind];
}
int dist(int u, int v){
    int a = H[u];
    int b = H[v];
    int ind = LCA(u,v);
    return abs(L[H[ind]] - L[a]) + abs(L[H[ind]] - L[b]);
}
```

## 10 Segment Tree

```
int tree[MX_N*4];
int a[MX_N];
int N;

void construct(int p, int L, int R){
    if(L==R){
        tree[p] = a[L];
        return;
    }
    if(R<L)
        return;
int md = (L+R)/2;
    construct(2*p+1,md+1,R);
    tree[p] = min(tree[2*p],tree[2*p+1]);
}

void update(int p, int L, int R, int ind,int v){
    if(L==R){
        a[ind] = v;
        tree[p] = v;
        return;
    }
    int md = (L+R)/2;
    if(ind <= md)
        update(2*p,L,md,ind,v);
    else
        update(2*p+1,md+1,R,ind,v);
    tree[p] = min(tree[2*p],tree[2*p+1]);
}

int rmq(int p, int L, int R, int 1, int r){
    if(r < L || 1 > R)
        return INF;
    if(1>=L && r<=R)
        return tree[p];
    int md = (1+r)/2;
    return min(rmq(2*p,L,R,1,md),rmq(2*p+1,L,R,md+1,r));
}</pre>
```

### 11 RectInHist

## 12 SCC Tarjans

## 13 NlogN LIS

## 14 AP & Bridges

# 15 Sparse Table

```
inline int rmq(int u, int v){
    if(u > v)
        return -2000000000;
    int k = (int) floor(log2((double) (v-u+1)));
    if(r[mtable[u][k]] > r[mtable[v-(1<<k) + 1][k]])
        return mtable[u][k];
    return mtable[v-(1<k) + 1][k];
}

for(int i = 0; i < N; i++)
    mtable[i][0] = i;
for(int j = 1; (1 << j) <= N; j++)
    for(int i = 0; i + (1<<j) -1 < N; ++i)
        if(r[mtable[i][j-1]] > r[mtable[i] + (1 << (j-1))][j-1]])
        mtable[i][j] = mtable[i][j-1];
    else
    mtable[i][j] = mtable[i+(1<<(j-1))][j-1];</pre>
```

#### Suffix Array 16

```
int RA[MX_N], SA[MX_N], tempRA[MX_N], tempSA[MX_N], N, c[MX_N];
void countingSort(int k){
   int i,sum,maxi=max(300,N);
   memset(c,0,sizeof(c));
   for(i = 0; i < N; i++);
        c[i+k < N ? RA[i+k] : 0]++;
   for(i=sum=0; i < maxi; i++){
        int t = c[i];
        c[i] = sum:</pre>
                                                                                                                                                                         j++;
} else{
                                                                                                                                                                              alse(
  T[i] = j;
  j = T[j];
  while(j >= 0 && s[i]!=s[j])
  j = T[j];
  j++;
       for(i = 0; i < N; i++)
    tempSA[c[SA[i]+k < N ? RA[SA[i]+k]: 0]++] = SA[i];</pre>
       for(i=0; i < N;i++)
SA[i]=tempSA[i];
                                                                                                                                                                        }
                                                                                                                                                                  T[n] = j;
return T;
       main(){
buff = new char[100011];
char * doubled = new char[MX_N];
cin.getline(buff,MX_N);
                                                                                                                                                          vector<int> search(string W, string S){
  int N = S.size();
       auto T=buildFailure(W);
                                                                                                                                                                   vector<int> p;
                                                                                                                                                                  vector(int> p,
int k = 0;
int j = 0;
while(j < N){
    if(W[k]==S[j]){</pre>
      j++;
if(k==W.size()){
              for(int i = 1; i < N; i++){
    tempRa[SA[i]] = (RA[SA[i]]==RA[SA[i-1]] && RA[SA[i]+k]==RA[SA[i-1]+k] ? r:++r);</pre>
                                                                                                                                                                                      p.push_back(j-k);
k = T[k];
              for(int i = 0; i < N; i++)
    RA[i]=tempRA[i];</pre>
                                                                                                                                                                         }else{
    k = T[k];
    if(k < 0){
       delete buff;
       return 0:
                                                                                                                                                                                       j+=1;
k+=1;
                     Trie
```

#### 17

```
struct node {
   node * children[26];
         index = children[20];
int count;
node(){
   memset(children,0,sizeof(children));
   count=0;
};
 void insert(node* nd, char *s){
                **){
  if(!nd->children[*s-'a'])
    nd->children[*s-'a']=new node();
  insert(nd->children[*s-'a'],s+1);
        nd->count++;
 int count(node* nd, char *s){
         if(*s){
    if(!nd->children[*s-'a'])
                 return 0;
return count(nd->children[*s-'a'],s+1);
        } else {
return nd->count;
int main(){
  node * trie = new node();
  int N; scanf("%d",&N);
  char * buff = new char[40];
  for(int i = 0; i < N; i++){
      scanf("%a",buff);
      printf("%d",count(trie,buff));
      insert(trie,buff);
}</pre>
        }
return 0;
```

#### **UFDS** 18

```
int find(int u){ return p[u] = (p[u] == u ? u : find(p[u])); }
inline void join(int a, int b){
       ine void join(int a, int b){
pa = find(a);
pb = find(b);
if(pa!=pb){
    if(rank[pa] < rank[pb]){
        ni = pb;
        pb = pa;
        pa = ni;
    }
}</pre>
                p[pb] = pa;
if(rank[pa]==rank[pb])
    rank[pa]++;
```

#### **KMP** 19

```
vector<int> buildFailure(string s){
  int n = s.size();
  vector<int> T(n+1,0);
  T[0]=-1;
  int j = 0;
  for(int i = 1; i < n;++i){
    if(s[i]==s[j]){
        T[i]=T[j];
        i++;
    }
}</pre>
```

#### 20 Geometry

```
typedef complex<double> pt;
typedef complex<double> vec;
typedef vectortypedef vectortypedef vectortypedef vectortypedef struct { pt p, q; } lseg;
double cross(const vec& a, const vec &b){ return x(a)*y(b)-y(a)*x(b); }
//cross product of (b-a) and (c-b), 0 is collinear
int orientation(const pt& a, const pt& b, const pt& c){
    double v = cross(b-a,c-b);
    if(abs(v-0.0)<EPS)
    return 0;
             return 0;
return v > 0 ? 1 : 2;
 //Line segment intersection
 //Line segment intersection
bool intersects(const lseg& a, const lseg& b){
   if(a.q == b.p || b.q == a.p)
      return false;
   if(orientation(a.p.a.q,b.p)!=orientation(a.p,a.q,b.q)
      && orientation(b.p,b.q,a.p) != orientation(b.p,b.q,a.q))
      return true;
              return false;
return abs(area)/2.0;
}
//If a~b->c is a counterclockwise turn
double ccw(const point& a, const point& b, const point& c){
   if(a=b | | b=c | | a==c)
        return false;
   point relA = b-a;
   point relC = b-c;
   return cross(relA,relC) >= 0.0;
}
 }
//Returns if point p is in the polygon poly
bool inPoly(const pgon& poly, const pt& p){
  for(int i = 0; i < poly.size()-1; i++){
    if(!ccw(poly[i],p,poly[i+1]))</pre>
                                      return false;
              return true:
}
}
//Distance from p to line (a,b)
double distToLine(const pt& p, const pt& a, const pt &b){
    vec ap = p-a;
    vec ap = b-a;
    double u = dot(ap,ab)/dot(ab,ab);
    //Ignore for non-line segment
    if(u < 0.0) //Closer to a
        return abs(a-p);
    if(u > 1.0) //Closer to b
        return abs(b-p);
    pt c = a+ab*u; // This is the point
    return abs(c-p);
}
```

# 21 vimrc

```
set nocompatible
set autoindent " always set autoindenting on
set cindent
filetype indent on
filetype plugin on
set backup
set undofile
set history=50
set laststatus=2
imap jj <ESC'
nnoremap <CR'> inoh<CR><CR'>
set wildmenu
" Tabs"
set tabstop=8
set softtabstop=0
set expandtab
set sifftwidth=4
set smarttab
```