Data Structures and Algorithms for competitive programming

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1 Graphs

Traversal

```
\mathbf{BFS}
```

```
int dist[MXN];
   vector < int > adjList [MX.N];
3
   int main(){
 5
        for(int i = 0; i < MX_N; i++)
 6
            dist[i]=INF;
        queue<int> q;
 8
        q.push(0);
9
        dist[0] = 0;
10
        while (!q.empty()) {
            int u = q.front(); q.pop();
11
12
            int d = dist[u];
            for(int i : adjList[u]){
13
                 if (dist [i]==INF) {
14
                     dist[i]=d+1;
15
16
                     q.push(i);
17
18
19
20
        return 0;
   Dijkstras
   struct path {
2
        int u,d;
3
        bool operator < (const path& p) const {
 4
            return d > p.d;
 5
 6
    };
    for (int i =0; i < N; ++i)
        dist[i] = INF;
    dist[S] = 0;
   priority_queue < path > q;
   q.push(path(S,0));
12
   while (!q.empty()) {
13
        path p = q.top(); q.pop();
14
        u = p.u, d = p.d;
15
        if(dist[u] < d)
16
            continue;
17
        for (auto v : adjList[u]) {
            nd = d + v.second;
18
19
            if(nd < dist[v.first]){</pre>
20
                 dist[v.first] = nd;
21
                q.push(path{v.first,nd});
22
23
24
```

Trees

MST

```
struct edge {
2
        int x, y, w;
3
        bool operator < (edge e) const {
4
            return w < e.w;
5
6
    };
8
   int main(){
9
        vector<edge> eList; //Input
10
        for (int i = 0; i < N; i++)// Set up UFDS
11
            p[i]=i;
12
        vector<ii> treeList;
13
        sort (eList.begin(), eList.end());
14
        int cost = 0;
15
        int sz=N;
16
        int u, v, w;
17
        for (const auto &i : eList) {
18
            v=i.x; u=i.y; w=i.w;
19
            if (!connected(u,v)){
20
                join (u,v);
21
                treeList.push\_back(\{min(u,v),max(u,v)\});
22
                sz --;
23
                 cost+=w;
24
25
26
        if (sz!=1)
27
            puts("Impossible");
28
   LCA
    *H/u is first visit of u
    *E[x] is vertex at time x
4
    *L[x] is depth at time x
5
    */
    void vis(int u, int d){
6
        H[u] = vind;
8
        E[vind] = u;
9
        L[vind++] = d;
10
        for (auto i : adjList[u]) {
11
            if(H[i]!=-1)
12
                continue;
13
            vis(i,d+1);
14
            E[vind] = u;
15
            L[vind++] = d;
16
17
18
19
    int LCA(int u, int v){
20
        if(H[u] > H[v])
```

```
21
            int t = u:
22
            u = v;
23
            v = t;
24
25
        //run some range min query on L
26
        //between H/u/ and H/v/
27
        int ind = rmq(H[u], H[v]);
28
        return E[ind];
29
30
31
   int dist(int u, int v){
32
        int a = H[u];
33
        int b = H[v];
34
        int ind = LCA(u, v);
35
        return abs(L[H[ind]]-L[a])
36
            + abs(L[H[ind]]-L[b]);
37
   Centroid Decomposition
   void fill_sz(int u, int p){
2
        sz[u] = 1;
3
        for(int v : adjList[u]) {
            if (v==p || mkd[v])
4
                continue;
            fill_sz(v,u);
            sz[u]+=sz[v];
8
9
10
   int get_centroid(int u, int n, int p){
11
        for(int v : adjList[u]){
12
13
            if (v==p || mkd[v])
14
                continue;
15
            if(sz[v] > n/2)
                return get_centroid(v, n, u);
16
17
18
        return u;
19
20
21
   int decomp(int u){
22
        fill_sz(u, -1);
23
        int cent = get_centroid(u, sz[u], -1);
24
        mkd[cent] = true;
25
        for(int v : adjList[cent]){
26
            if (mkd [v])
27
                continue:
28
            int r = decomp(v);
29
            centP[r] = cent;
30
31
        return cent;
32
```

SCC Tarjans

```
stack<int> scc;
   int dfsCounter=1;
    int sccIdx=1;
    map<int, int> sccMap;
6
    void tarjans(int u){
        scc.push(u);
8
        vis [u]=true;
9
10
        dfs_low[u] = dfs_num[u] = dfsCounter++;
11
12
        for (int i = 0; i < adjList[u].size(); i++)
13
            int v = adjList[u][i];
            if(dfs_num[v]==0)
14
15
                 tarjans(v);
16
                 dfs_low[u] = min(dfs_low[u], dfs_low[v]);
17
            } else if (vis [v]) {
                 dfs_low[u]=min(dfs_low[u],dfs_num[v]);
18
19
20
21
        if(dfs_low[u]==dfs_num[u])
            while (1) {
22
23
                 int v = scc.top(); scc.pop();
24
                 \operatorname{sccMap}[v] = \operatorname{sccId}x;
25
                 vis[v] = false;
26
                 if (v==u)
27
                     break;
28
29
            sccIdx++;
30
31
    AP & Bridges
1
    int dfs(int u,int p){
2
        dfs_num[u] = dfs_low[u] = ++dfs_counter;
3
        for(auto v : adjList[u]){
4
            if(dfs_num[v]==0)
5
                 dfs(v,u);
6
                 if(dfs_low[v] >= dfs_num[u])
                     articulation [u]=true;
8
9
                 if(dfs_low[v] > dfs_num[u])
10
                     bridge = true;
11
                 dfs_low[u] = min(dfs_low[u], dfs_low[v]);
12
            } else if(v!=p)
                 dfs_low[u] = min(dfs_low[u], dfs_num[v]);
13
14
15
```

Network Flow

Edmond Karp Max Flow

```
1 void aug(int u, int minE){
2
        if(u==S){ f=minE; return; }
3
        if(p[u]!=u){
             aug(p[u], min(minE, res[p[u]][u]));
4
 5
             res[p[u]][u]-=f;
6
             res[u][p[u]]+=f;
 8
9
10 int main(){
11
        int mf=0;
12
        for (;;) {
13
             f=0;//Global
             for (int i = 0; i < N; i++)
14
15
                 dist[i]=INF, p[i]==i;
16
             dist[S]=0;
17
             queue < int > q; q.push(S);
18
             while (!q.empty()) {
                 int u = q. front(); q.pop();
19
20
                 if(u==T) break;
21
                 for (int i = 0; i < N; i++)
22
                      if (res [u] [i] > 0 && dist [i]==INF)
23
                          \operatorname{dist}[i] = \operatorname{dist}[u] + 1, p[i] = u, q.\operatorname{push}(i);
24
25
             aug(T, INF);
26
             if(f==0) break;
27
             mf+=f;
28
29
        vector<ii> used;
30
        for(int i = 0; i < N; i++)
31
             for (int j = 0; j < N; j++)
                 if (graph [i][j] > 0 && res[i][j] < graph [i][j])
32
33
                     used.push_back(make_pair(i,j));
34 }
   Ford Fulkerson Max Flow
1 int ff(int u, int minE){
2
        i f ( u==T)
3
             return minE;
4
        vis [u]=true;
5
        for(auto i : adjList[u]){
6
             if (! vis [i] && res [u] [i] > 0) {
                 if(int f = ff(i, min(minE, res[u][i])))
7
                     res[u][i] -= f;
9
                     res[i][u] += f;
10
                     return f;
11
12
13
14
        return 0;
15
16
17 int main(){
        int mf = 0;
18
```

```
19
        while (1) {
20
            memset(vis,0,sizeof(vis));
21
            int f = ff(S, INF);
22
            if(f==0)
23
                break;
24
            mf+=f;
25
26
        printf("%d\n",mf);
27 }
```

2 Data Structures

13 for (int j = 1; (1 << j) <= N; j++)

Fenwick Tree

```
1 int tree [MX_N];
2 int N;
  int lsOne(int i) \{ return i \& (-i); \}
   void update(int k,int v){
        for (; k<MX_N; k+=lsOne(k))
6
            tree[k]+=v;
7
   int query(int k){
8
        int cnt=0;
10
        for (; k; k-=lsOne(k)) {
11
            cnt+=tree[k];
12
13
        return cnt;
14 }
   UFDS
1 int find(int u) { return p[u] = (p[u] = u ? u : find(p[u])); }
3
   inline void join (int a, int b) {
        pa = find(a);
        pb = find(b);
6
        if (pa!=pb) {
            if(rank[pa] < rank[pb])
8
                ni = pb;
9
                pb = pa;
10
                pa = ni;
11
12
            p[pb] = pa;
            if (rank [pa]==rank [pb])
13
14
                rank[pa]++;
15
16
   Sparse Table
   inline int rmq(int u, int v){
2
        if(u > v)
3
            return -20000000000;
4
        int k=(int) floor(log2((double)(v-u+1)));
5
        if (r [mtable [u] [k]] >
6
                r [ mtable [ v-(1 << k) + 1 ] [k] ] )
            return mtable[u][k];
8
        return mtable [v-(1 << k) + 1][k];
9
10
   for (int i = 0; i < N; i++)
11
        mtable[i][0] = i;
```

```
14
        for (int i = 0; i + (1 << j) - 1 < N; ++i)
15
             if (r [mtable [i] [j−1]]
16
                     >r [ mtable [ i+(1<<(j-1)) ] [ j-1] ])
17
                 mtable[i][j] = mtable[i][j-1];
18
             else
19
                 mtable[i][j]=mtable[i+(1<<(j-1))][j-1];
    Segment Tree
1 int tree [MX_N*4];
   int a [MX.N];
3
   int N;
    void construct (int p, int L, int R) {
6
        if (L=R) {
7
             tree[p] = a[L];
8
             return:
9
        if (R<L)
10
11
             return;
12
        int md = (L+R)/2;
13
        construct (2*p,L,md);
14
        construct(2*p+1,md+1,R);
15
        tree[p] = min(tree[2*p], tree[2*p+1]);
16
17
18
    void update(int p, int L, int R, int ind, int v){
19
        if (L=R) {
20
             a[ind] = v;
21
             tree[p] = v;
22
             return:
23
24
        int md = (L+R)/2;
25
        if (ind \ll md)
26
             update(2*p,L,md,ind,v);
27
28
             update(2*p+1,md+1,R,ind,v);
        tree[p] = min(tree[2*p], tree[2*p+1]);
29
30
31
32
    int rmq(int p, int L, int R, int l, int r){
        if(r < L \mid \mid l > R)
33
34
             return INF;
35
        if(l>=L && r<=R)
36
             return tree[p];
37
        int md = (l+r)/2;
38
        return \min(\text{rmq}(2*p, L, R, l, md), \text{rmq}(2*p+1, L, R, md+1, r));
39 }
```

3 Geometry

Convex Hull

```
int main() {
2
        for (int i = 0; i < N; i++){
3
            perm[i]=i;
4
5
        sort (perm, perm+N,
6
                 [](int a, int b){
                     const point &pa = V[a];
                     const point &pb = V[b];
9
                     if (real (pa)!=real (pb))
                         return real(pa) < real(pb);
10
11
                     return imag(pa) < imag(pb);
12
13
        vector<int> L; vector<int> U;
14
        for (int i = 0; i < N;) {
15
            int t = L. size();
16
            if(t \ge 2 \&\& ! ccw(V[L[t-2]],V[L[t-1]],V[perm[i]]))
17
                 L. pop_back();
18
            else
19
                 L. push_back(perm[i++]);
20
21
        for (int i = N-1; i >=0;) {
22
            int t = U. size();
23
            if(t \ge 2 \&\& ! ccw(V[U[t-2]],V[U[t-1]],V[perm[i]]))
24
                 U.pop_back();
25
            else
26
                 U. push_back (perm [i --]);
27
28
        vector<int> hull;
29
        for (int i = 0; i < L. size() -1; ++i)
            hull.push_back(L[i]);
30
31
        for (int i = 0; i < U. size() -1; ++i)
32
             hull.push_back(U[i]);
33
        return 0;
34
```

Geometry Axioms

```
typedef complex<double> pt;
   typedef complex<double> vec;
   typedef vector <pt> pgon;
   typedef struct { pt p,q; } lseg;
   double cross (const vec& a, const vec &b) {
6
        return x(a)*y(b)-y(a)*x(b);
7
    //cross\ product\ of\ (b-a)\ and\ (c-b), 0 is collinear
   int orientation (const pt& a,
10
            const pt& b, const pt& c){
        double v = cross(b-a, c-b);
11
12
        if (abs (v-0.0) < EPS)
13
            return 0;
```

```
14
        return v > 0 ? 1 : 2;
15 }
16
    //Line segment intersection
17
    bool intersects (const lseg& a, const lseg& b) {
18
        if(a.q = b.p | | b.q = a.p)
19
            return false;
20
        if (orientation (a.p,a.q,b.p)
21
                != orientation (a.p, a.q, b.q)
22
                && orientation(b.p,b.q,a.p)
23
                 != orientation(b.p,b.q,a.q))
24
            return true;
25
        return false;
26
27
    //Area of polygon
28
    double area (const pgon& p) {
29
        double area = 0.0;
30
        for(int i = 1; i < p.size(); ++i)
31
            area+=cross(p[i-1],p[i]);
32
        return abs(area)/2.0;
33
    //If a \rightarrow b \rightarrow c is a counterclockwise turn
34
35
    double ccw(const point& a, const point& b,
36
            const point& c){
37
        if (a==b | b==c | a==c)
38
            return false;
39
        point relA = b-a:
40
        point relC = b-c;
41
        return cross(relA, relC) >= 0.0:
42
43
    //Returns if point p is in the polygon poly
    bool in Poly (const pgon& poly, const pt& p) {
45
        for (int i = 0; i < poly.size()-1; i++){
46
             if (! ccw ( poly [ i ] , p , poly [ i +1]) )
47
                 return false;
48
49
        return true;
50
    //Distance from p to line (a,b)
51
    double distToLine(const pt& p, const pt& a,
53
            const pt &b){
54
        vec ap = p-a;
55
        vec ab = b-a;
56
        double u = dot(ap, ab)/dot(ab, ab);
57
        //Ignore for non-line segment
58
        if (u < 0.0) //Closer to a
59
            return abs(a-p);
60
        if(u > 1.0) //Closer to b
61
            return abs(b-p);
62
        pt c = a+ab*u; // This is the point
63
        return abs(c-p);
64 }
```

4 Strings

Suffix Array

```
void countingSort(int k){
2
        int i, sum, maxi=\max(300,N);
 3
        memset(c, 0, sizeof(c));
 4
        for (i = 0; i < N; i++)
 5
            c[i+k < N ? RA[i+k] : 0]++;
 6
        for (i=sum=0; i < maxi; i++)
            int t = c[i];
 8
            c[i]=sum;
9
            sum+=t;
10
11
        for (i = 0; i < N; i++)
            tempSA [c [SA [i]+k < N
12
                 ? RA[SA[i]+k]: 0]++] = SA[i];
13
14
        for (i=0; i < N; i++)
15
            SA[i] = tempSA[i];
16
17
18
    int main(){
19
        for (int i = 0; i < N; i++)
20
            SA[i]=i,RA[i]=input[i];
21
22
        for (int k = 1; k < N; k <<= 1) {
23
            countingSort(k);
24
            countingSort(0);
25
            tempRA[SA[0]] = r = 0;
            for (int i = 1; i < N; i++){
26
27
                 tempRA [SA [i]]
28
                     =(RA[SA[i]])==RA[SA[i-1]]
29
                     && RA[SA[i]+k] = RA[SA[i-1]+k]
30
                     ? r:++r);
31
32
            for (int i = 0; i < N; i++)
33
                 RA[i] = tempRA[i];
34
35
        return 0;
36
    Trie
   struct node {
2
        node * children [26];
3
        int count;
 4
        node(){
 5
            memset(children, 0, sizeof(children));
 6
            count=0;
 7
 8
    };
   void insert(node* nd, char *s){
11
        if (*s) {
```

```
12
             if (!nd->children [*s-'a'])
13
                  nd \rightarrow children [*s-'a'] = new node();
14
             insert (nd \rightarrow children [*s-'a'], s+1);
15
16
         nd \rightarrow count ++;
17
18
19
    int count(node* nd, char *s){
20
         if(*s){
21
             if (!nd->children[*s-'a'])
22
                  return 0:
23
             return count (nd\rightarrowchildren [*s-'a'], s+1);
24
         } else {
25
             return nd->count;
26
27
    KMP
    vector < int > build Failure (string s) {
2
         vector < int > T(n+1,0);
3
         T[0] = -1;
4
         int j = 0;
5
         for (int i = 1; i < s.size();++i){
6
             if (s[i]==s[j]) {
                  T[i]=T[j];
                  j++;
9
             } else{
10
                  T[i] = j;
11
                  j = T[j];
12
                  while (j >= 0 \&\& s[i]! = s[j])
13
                      j = T[j];
14
                  j++;
15
16
        \hat{T}[s.size()] = j;
17
18
         return T;
19
20
    vector < int > search (string W, string S) {
21
         auto T=buildFailure(W);
22
         vector < int > p;
23
         int k = 0;
24
         int j = 0;
25
         \mathbf{while}(j < S.size())
26
             if(W[k]==S[j])
27
                  k++; j++;
28
                  if (k=-W. size ()) {
29
                       p.push_back(j-k);
30
                       k = T[k];
31
32
             }else{
33
                  k = T[k];
34
                  if(k < 0)
35
                       j+=1, k+=1;
36
```

```
37 }
38 return p;
39 }
```

5 Algorithms

NlogN LIS

```
1 int ls [MX_N];
2 int L[MX.N];
   int I[MX.N];
5
   void nlogn(){
        for (int i = 1; i < N+1; ++i)
            I[i]=INF;
8
        I[0] = -INF;
9
        int mx = 1;
        for(int i = 0; i < N; ++i){
10
11
            int ind = lower_bound(I, I+N+1, ls[i]) - I;
12
            I[ind] = ls[i];
13
           L[i] = ind;
14
            mx = max(mx, ind);
15
16
        int prv = INF;
17
        vector < int > out;
18
        for (int i = N-1; i >= 0; —i) {
19
            if(ls[i] < prv && L[i]==mx){
                out.push_back(ls[i]);
20
21
                prv = ls[i];
22
                mx--;
23
24
25 }
```

RectInHist

```
1 int R,C;
   char board [MX_RC] [MX_RC];
   int h[MX_RC][MX_RC];
5
   int perim(int 1, int w){
6
        if ( l==0 || w==0)
            return 0;
        return 2*1 + 2*w;
8
9
10
11
   int main(){
12
        for (int i = 0; i < R; i++){
13
            int run=0;
14
            for (int j = 0; j < C; j++){
15
                run = (board[i][j] == '. '?run + 1:0);
16
                h[i][j] = run;
17
18
19
        int mx = 0;
20
        for (int j = 0; j < C; j++){
            stack<int> s;
21
22
            for (int i = 0; i < R; i++){
```

```
if(s.empty()
                           | | h [ i ] [ j ] > h [ s.top() ] [ j ])
24
25
                      s.push(i);
26
                  else if (h[i][j]<h[s.top()][j]) {
27
                      while (!s.empty()
                      &&h[i][j]<h[s.top()][j]){
28
                           int l = h[s.top()][j];
29
30
                          s.pop();
31
                           int pm = perim(1,
32
                               (s.empty()?
33
                                i : i - s \cdot top() - 1);
34
                          mx = max(mx,pm);
35
36
                      s.push(i);
37
                 \} else if (h[i][j]==h[s.top()][j])
38
                      s.pop();
39
                      s.push(i);
40
41
42
             while (! s . empty()) {
                 int l = h[s.top()][j]; s.pop();
43
44
                 int pm = perim(1, s.empty() ? R : R - s.top()-1);
45
                 mx = max(mx,pm);
46
47
48
        printf("%d\n",mx-1);
49
```

6 Maths

Miller Rabin

```
void factor(ll x, ll& e, ll& k){
2
        while (x%2LL==0LL) {
3
            x/=2LL;
4
            ++e;
6
        k = x;
7
8
    //increase x for higher certainty, 5 works well
    bool is_prime(ll n, int x){
10
11
        if (n&2LL==0 | | n==1LL)
12
            return false;
13
        if (n==2 || n==3 || n==5 || n==7)
14
            return true;
        ll e, k;
15
16
        factor(n-1,e,k);
17
        while (x-->0){
18
             11 a = (rand())\%(n-5LL) + 2LL;
19
             ll p = mod_exp(a,k,n);
             if (p==1LL || p==n-1LL)
20
21
                 continue;
22
             bool all_fail = true;
23
             for (int i = 0; i < e-1; ++i){
24
                 p = mod_exp(p, 2, n);
25
                 \mathbf{i} \mathbf{f} (p = n-1LL) 
26
                      all_fail = false;
27
                     break;
28
29
30
             if (all_fail)
31
                 return false;
32
33
        return true;
34 }
```

Binomial Coefficients

```
ll ncrmem [MX_N] [MX_N];
2
    ll ncr(int n, int r){
4
             if (n==0)
5
                       return r==0;
6
             if(r==0)
                       return 1;
8
             \mathbf{if} (\operatorname{ncrmem} [n] [r] != -1)
9
                      return ncrmem[n][r];
             return ncrmem[n][r] = ncr(n-1, r-1) + ncr(n-1, r);
10
11 }
```

```
1 void factor(ll x, ll& e, ll& k){
2
       while (x%2LL==0LL) {
3
            x/=2LL;
4
           ++e;
5
6
       k = x;
7
   //increase x for higher certainty, 5 works well
   bool is_prime(ll n, int x){
11
       if (n&2LL==0 | | n==1LL)
12
            return false;
13
       if (n==2 || n==3 || n==5 || n==7)
14
            return true;
15
       ll e, k;
16
       factor (n-1,e,k);
17
       while (x-->0){
            11 a = (rand())\%(n-5LL) + 2LL;
18
19
            ll p = mod_exp(a,k,n);
20
            if (p==1LL | | p==n-1LL)
21
                continue;
22
            bool all_fail = true;
23
            for (int i = 0; i < e-1; ++i) {
24
               p = mod_exp(p, 2, n);
25
                if(p=n-1LL)
                    all_fail = false;
26
27
                    break;
28
29
30
            if (all_fail)
31
               return false;
32
33
       return true;
34 }
```