

Design and Analysis of Algorithm (DAA)

Dynamic Programming (Multi-Stage Graphs)

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What is Multi-Stage Graph Problem?



A multi-stage graph is a directed, weighted graph that can be divided into stages, where each stage contains multiple nodes and edges connecting nodes between consecutive stages.

Multi-stage graph is a technique used to solve optimization problems involving a multi-stage decision process.

Multi-stage Graph

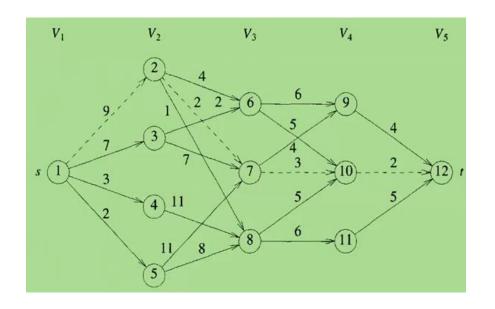


A multi-stage graph G(V, E) is a directed graph in which the vertices are partitioned into $k \ge 2$ disjoint sets V_i $1 \le i < k$ (k : no of stages)

If (u, v) is an edge in E, then

 $u \in V_i$ and $v \in V_{i+1}$

(Vertices on the same stage are not connected by edges)



Multi-Stage Graph Problem

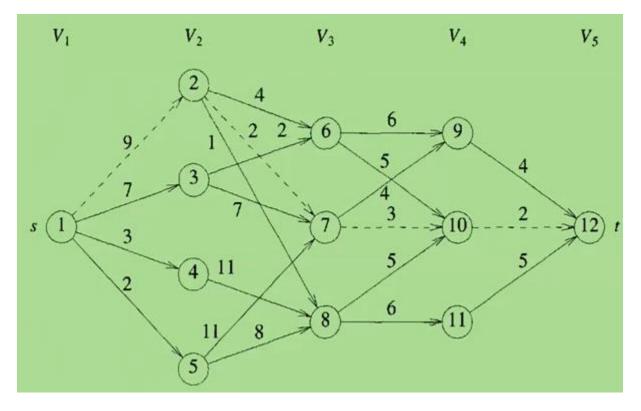


Given: A multi-stage graph with stages and weighted edges between consecutive stages.

Goal: find the minimum-cost path from the starting node to the destination node.

Five-stage Graph





Vertex s is the source, and t is the destination/sink.

A minimum-cost path from s to t is indicated by the broken edges.

Approaches



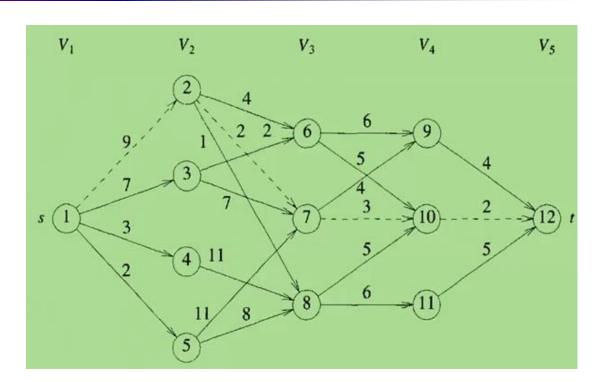
Forward Approach (Backward Reasoning)

Backward Approach (Forward Reasoning)



Note# Every s to t path is the result of sequence of k-2 decisions.

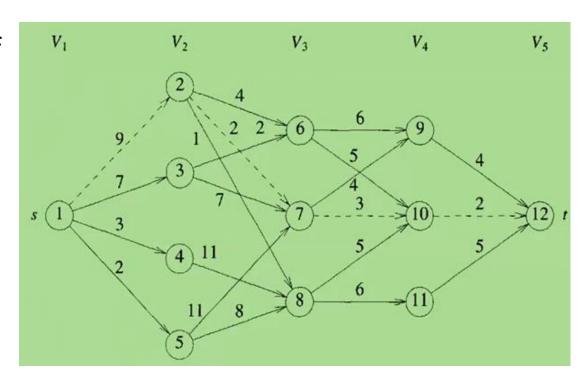
The i^{th} decision determines which vertex in V_{i+1} to be on the path.





Let cost(i,j) be the cost of minimum-cost path from vertex j to destination t.

cost(ith stage, jth vertex)







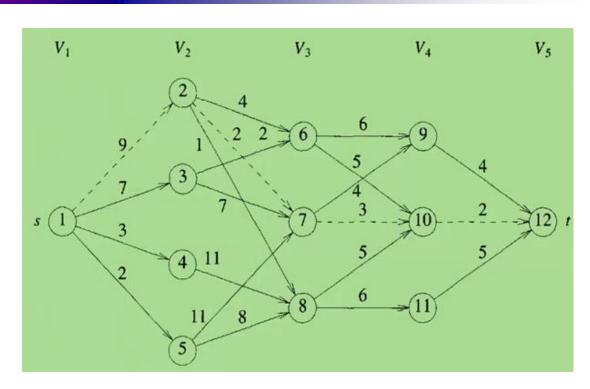
cost(ith stage, jth vertex)

$$cost(5,12) = 0$$

$$cost(4,11) = 5$$

$$cost(4,10) = 2$$

$$cost(4,9) = 4$$

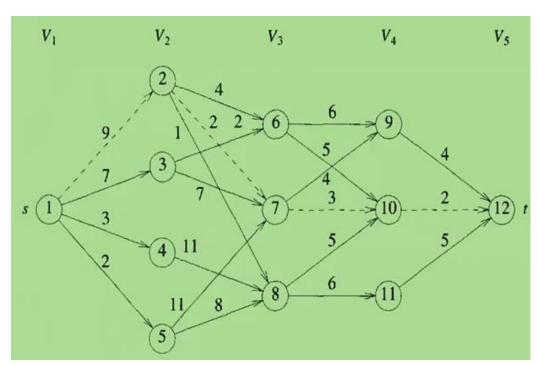


Vertex	1	2	3	4	5	6	7	8	9	10	11	12
cost									4	2	5	0
d									12	12	12	12



cost(ith stage, jth vertex)

```
cost(3,8)
= min(6 + 5, 5 + 2)
= min(6 + cost(4,11), 5 + cost(4,10))
= min(11, 7)
= 7
```



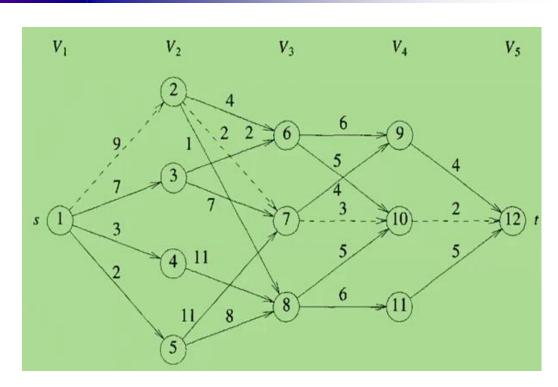
Vertex	1	2	3	4	5	6	7	8	9	10	11	12
cost								7	4	2	5	0
d								10	12	12	12	12

OSGN - OSPN [10]



cost(ith stage, jth vertex)

```
cost(3,7)
= min(3 + cost(4,10), 4 + cost(4,9))
= min(3 + 2, 4 + 4)
= min(5, 8)
= 5
```

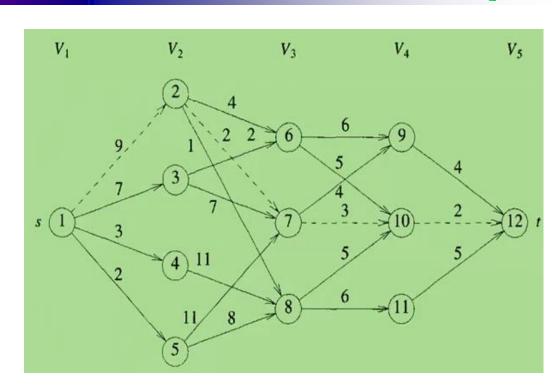


Vertex	1	2	3	4	5	6	7	8	9	10	11	12
cost							5	7	4	2	5	0
d							10	10	12	12	12	12



cost(ith stage, jth vertex)

```
cost(3,6)
= min(6 + cost(4,9), 5 + cost(4,10))
= min(6 + 4, 5 + 2)
= min(10, 7)
= 7
```



Vertex	1	2	3	4	5	6	7	8	9	10	11	12
cost						7	5	7	4	2	5	0
d						10	10	10	12	12	12	12

OSGN - OSPN [12]

DP Formula: Forward Approach



```
Vertex Cost:
```

cost(ith stage, jth vertex)

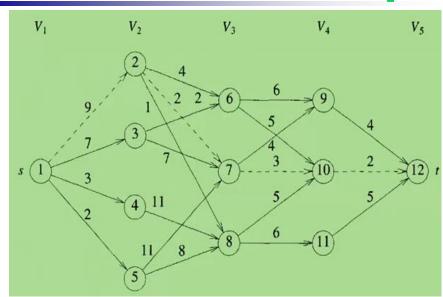
Edge Cost:

c(j, r): cost of edge (j,r)

cost(3,6)

- $= min\{6 + cost(4,9), 5 + cost(4,10)\}$
- = $\min \{c(6, 9) + \cos t(4, 9), c(6, 10) + \cos t(4, 10)\}$
- $= \min(6 + 4, 5 + 2)$
- = min(10, 7)
- = 7

Vertex	1	2	3	4	5	6	7	8	9	10	11	12
cost						7	5	7	4	2	5	0
d						10	10	10	12	12	12	12



DP Formula: Forward Approach



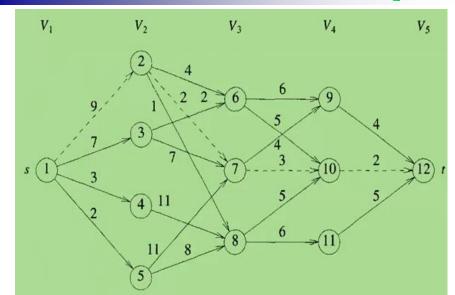
```
Vertex Cost:
cost(i<sup>th</sup> stage, j<sup>th</sup> vertex)
```

Edge Cost:

```
c(j, r): cost of edge (j,r)

i j

cost(3,6)
```

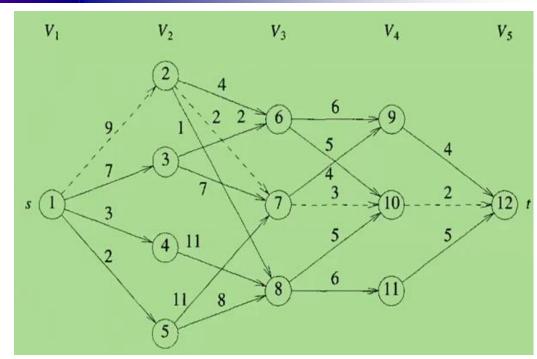


```
\int_{i+1}^{j} r \quad i+1 \quad r \quad j \quad r \quad i+1 \quad r \\
= \min \{c(6, 9) + \cos t (4, 9), c(6, 10) + \cos t (4, 10)\}

= \min \{c(j, r) + \cos t (i+1, r)\}

cost(i, j) = \min_{\substack{r \in V_{i+1} \\ < j, r > \in E}} \{c(j, r) + \cos t (i+1, r)\}
```





cost(ith stage, jth vertex)

cost(2,2)

= min(4 + cost(3,6), 2 + cost(3,7), 1 + cost(3,8))

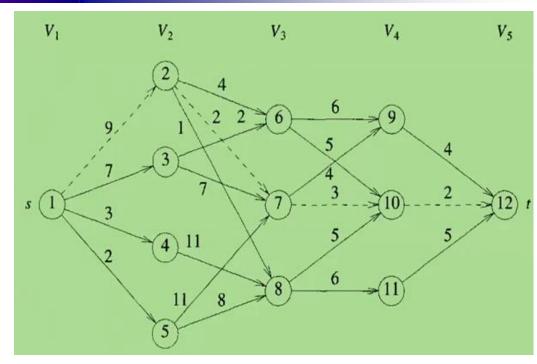
= min(6 + 7, 2 + 5, 1+7)

= 7

Vertex	1	2	3	4	5	6	7	8	9	10	11	12
cost		7				7	5	7	4	2	5	0
d		7				10	10	10	12	12	12	12



cost(ith stage, jth vertex)



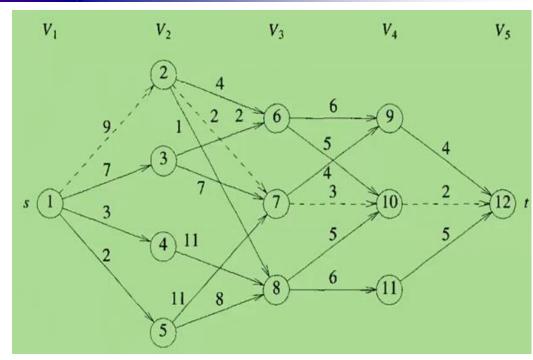
Vertex	1	2	3	4	5	6	7	8	9	10	11	12
cost		7	9			7	5	7	4	2	5	0
d		7	6			10	10	10	12	12	12	12

OSGN - OSPN [16]



cost(ith stage, jth vertex)

cost(2,4) = 18



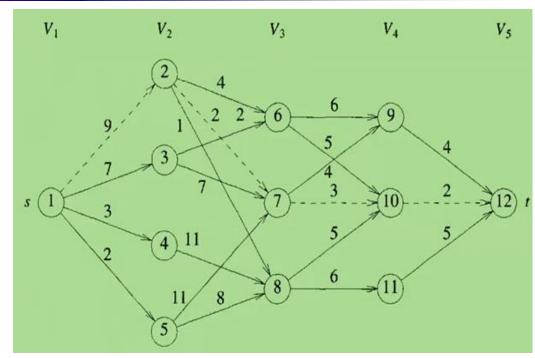
Vertex	1	2	3	4	5	6	7	8	9	10	11	12
cost		7	9	18		7	5	7	4	2	5	0
d		7	6	8		10	10	10	12	12	12	12

OSGN - OSPN [17]



cost(ith stage, jth vertex)

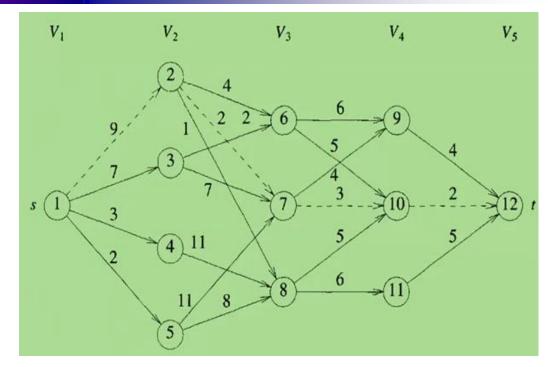
cost(2,5) = 15



Vertex	1	2	3	4	5	6	7	8	9	10	11	12
cost		7	9	18	15	7	5	7	4	2	5	0
d		7	6	8	8	10	10	10	12	12	12	12

OSGN - OSPN [18]





cost(ith stage, jth vertex)

cost(1,1)

 $= min\{9 + cost(2,2), 7 + cost(2,3), 3 + cost(2,4), 2 + cost(2,5)\}$

 $= \min\{9+7, 7+9, 3+18, 2+15\}$

= 16

Vertex	1	2	3	4	5	6	7	8	9	10	11	12
cost	16	7	9	18	15	7	5	7	4	2	5	0
d	2/3	7	6	8	8	10	10	10	12	12	12	12



```
Algorithm FGraph(G, k, n, p)
    // The input is a k-stage graph G = (V, E) with n vertices
    // indexed in order of stages. E is a set of edges and c[i,j]
    // is the cost of (i, j). p[1:k] is a minimum-cost path.
5
\frac{6}{7}
         cost[n] := 0.0;
         for j := n - 1 to 1 step -1 do
8
         \{ // \text{ Compute } cost[j]. 
              Let r be a vertex such that \langle j, r \rangle is an edge
10
              of G and c[j,r] + cost[r] is minimum;
              cost[j] := c[j,r] + cost[r];
11
12
              d[j] := r;
13
         // Find a minimum-cost path.
14
                                                                  Stage
                                                                                  2
                                                                                         3
                                                                                                      5
         p[1] := 1; p[k] := n;
15
                                                                            1
                                                                                                      12
                                                                  P
         for j := 2 to k-1 do p[j] := d[p[j-1]];
16
17
```

Vertex	1	2	3	4	5	6	7	8	9	10	11	12
cost	16	7	9	18	15	7	5	7	4	2	5	0
d	2/3	7	6	8	8	10	10	10	12	12	12	12



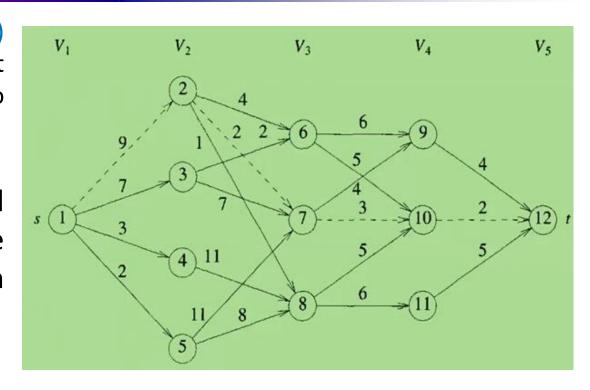
```
Algorithm FGraph(G, k, n, p)
    // The input is a k-stage graph G = (V, E) with n vertices
    // indexed in order of stages. E is a set of edges and c[i,j]
    // is the cost of (i, j). p[1:k] is a minimum-cost path.
                                                                                     Time complexity
5
                                                                                     proportional to the
\frac{6}{7}
         cost[n] := 0.0;
                                                                                    degree of vertex j
                                                                \Theta(|V|+|E|)
         for j := n - 1 to 1 step -1 do
8
         \{ // \text{ Compute } cost[j]. 
                                                                                    Overall:
              Let r be a vertex such that \langle j, r \rangle is an edge
                                                                                        \Theta(|V|+|E|)
10
              of G and c[j,r] + cost[r] is minimum;
              cost[j] := c[j,r] + cost[r];
11
12
              d[j] := r;
13
         // Find a minimum-cost path.
14
                                                                   Stage
                                                                                   2
                                                                                         3
                                                                                                       5
         p[1] := 1; p[k] := n;
15
                                                                                   2
                                                                                                10
                                                                                                       12
                                                                             1
         for j := 2 to k - 1 do p[j] := d[p[j - 1]]; \Theta(k)
16
17
```

Vertex	1	2	3	4	5	6	7	8	9	10	11	12
cost	16	7	9	18	15	7	5	7	4	2	5	0
d	2/3	7	6	8	8	10	10	10	12	12	12	12



In forward approach, cost(i,j) was the cost of minimum-cost path from vertex j to destination t.

Here in backward approach bcost(i,j) be the cost of minimum-cost path from source s to vertex j.



bcost(ith stage, jth vertex)





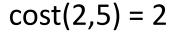
bcost(ith stage, jth vertex)

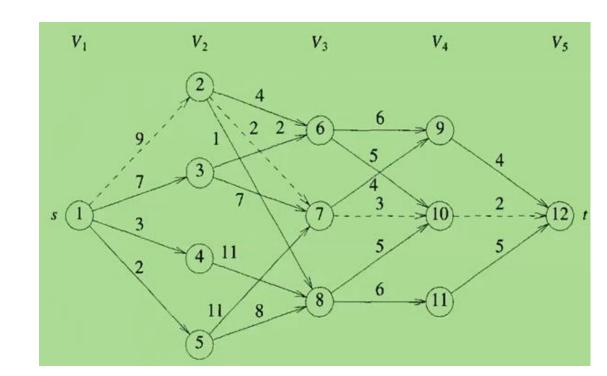
$$cost(1,1) = 0$$

$$cost(2,2) = 9$$

$$cost(2,3) = 7$$

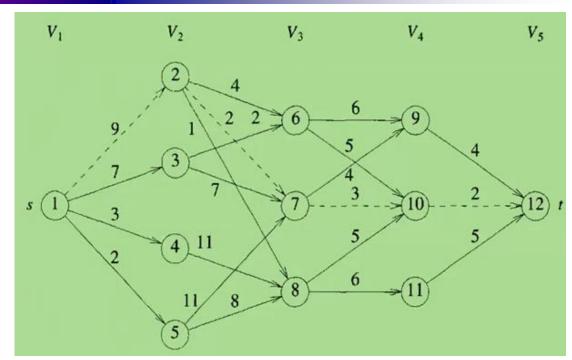
$$cost(2,4) = 3$$





Vertex	1	2	3	4	5	6	7	8	9	10	11	12
cost	0	9	7	3	2							
d	1	1	1	1	1							





bcost(ith stage, jth vertex)

cost(3,6)

= min(bcost(2,2) + 4, bcost(2,3) + 2)

= min(9+4, 7+2)

= 9

Vertex	1	2	3	4	5	6	7	8	9	10	11	12
cost	0	9	7	3	2	9						
d	1	1	1	1	1	3						

DP Formula: Backward Approach



```
Vertex Cost:
bcost(i<sup>th</sup> stage, j<sup>th</sup> vertex)
```

Edge Cost:

```
c(r, j): cost of edge (r,j)

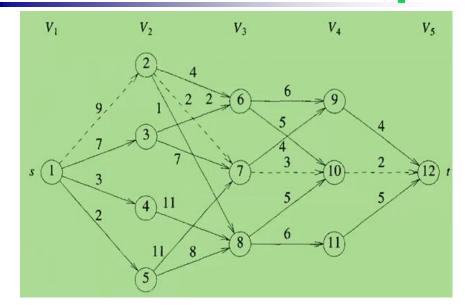
i j

cost(3,6)
```

$$i-1$$
 r r j $i-1$ r r j = min(bcost(2,2)+ c(2,6), bcost(2,3)+c(3,6))

= min {bcost(i-1, r)+ c(r, j)}

$$cost(i,j) = \min_{\substack{r \in V_{i-1} \\ \langle r,j \rangle \in E}} \{bcost(i-1,r) + c(r,j)\}$$



DP Formula: Backward Approach



```
bcost(3,7) = 11

bcost(3,8) = 10

bcost(4,9) = 15

bcost(4,10) = 14

bcost(4,11) = 16

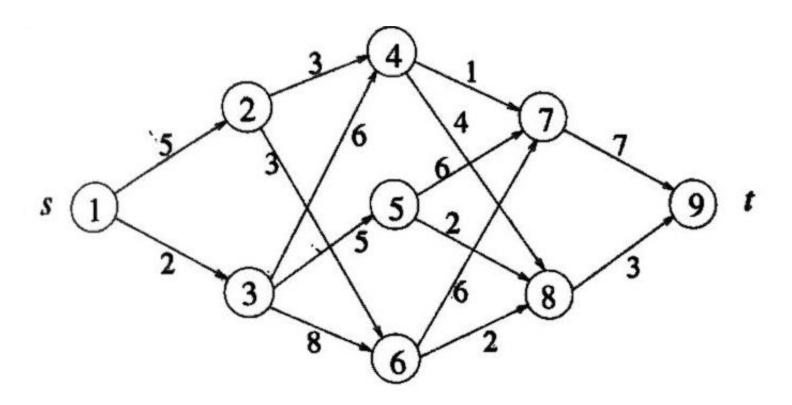
bcost(5,12) = 16
```



```
Algorithm BGraph(G, k, n, p)
2
3
4
5
6
7
8
9
         Same function as FGraph
          bcost[1] := 0.0;
          for j := 2 to n do
          { // Compute bcost[j].
               Let r be such that (r, j) is an edge of
               G and bcost[r] + c[r, j] is minimum;
               bcost[j] := bcost[r] + c[r, j];
               d[j] := r;
 11
 12
              Find a minimum-cost path.
 13
          p[1] := 1; p[k] := n;
 14
          for j := k - 1 to 2 do p[j] := d[p[j + 1]];
 15
```

Example 2







Each of your actions will have an impact on your future.

Once you know
who is walking
with you on your path.
you will never
be afraid.

Thank you