

CP-3.

The weak form of the isotropic linear elasticity problem can be given as:

Given the domain  $\Omega$  and the following spaces:

$$W = \{ \vec{w} : \Omega \rightarrow \mathbb{R}^2 \mid \vec{w} \text{ is smooth vector field} \}$$

$$S = \{ \vec{w} \in W \mid \vec{w} = \vec{g} \text{ on } \partial\Omega_D \}$$

$$V = \{ \vec{v} \in W \mid \vec{v} = 0 \text{ on } \partial\Omega_D \}$$

Find  $\vec{w} \in S$  such that

$$a(\vec{w}, \vec{v}) = l(\vec{v}) \quad \forall \vec{v} \in V$$

where

$$a(\vec{w}, \vec{v}) = \int_{\Omega} \frac{E}{1+\nu} (e(\nabla \vec{w}) : e(\nabla \vec{v})) + \frac{\nu}{1-2\nu} \operatorname{div} \vec{w} \operatorname{div} \vec{v}$$

$$l(\vec{v}) = \int_{\Omega} \vec{b} \cdot \vec{v} d\Omega + \int_{\partial\Omega_N} \vec{H} \cdot \vec{v} d\Omega.$$



$$\frac{dN_1}{dx_1} = \sum_{i=1}^3 \frac{\partial N_1}{\partial \lambda_i} \frac{\partial \lambda_i}{\partial x_1}$$

$$\frac{d\lambda_i}{dx_j} = \begin{bmatrix} \frac{\partial \lambda_1}{\partial x_1} & \frac{\partial \lambda_2}{\partial x_1} & \frac{\partial \lambda_3}{\partial x_1} \\ \frac{\partial \lambda_1}{\partial x_2} & \frac{\partial \lambda_2}{\partial x_2} & \frac{\partial \lambda_3}{\partial x_2} \end{bmatrix}$$

$$\begin{aligned} dN_1 &= \begin{bmatrix} \frac{\partial N_1}{\partial \lambda_1} & \frac{\partial N_1}{\partial \lambda_2} & \frac{\partial N_1}{\partial \lambda_3} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \frac{\partial \lambda_1}{\partial x_1} & \frac{\partial \lambda_1}{\partial x_2} \\ \frac{\partial \lambda_2}{\partial x_1} & \frac{\partial \lambda_2}{\partial x_2} \\ \frac{\partial \lambda_3}{\partial x_1} & \frac{\partial \lambda_3}{\partial x_2} \end{bmatrix} \\ &= \begin{bmatrix} \frac{\partial N_1}{\partial x_1} + \frac{\partial N_1}{\partial x_1} + \frac{\partial N_1}{\partial x_1} & \frac{\partial N_1}{\partial x_2} + \frac{\partial N_1}{\partial x_2} + \frac{\partial N_1}{\partial x_2} \\ 0 & 0 \end{bmatrix} \\ &\quad N_1 \quad \dots \quad N_6 \\ &\quad \begin{bmatrix} \frac{\partial N_1}{\partial x_1} & \frac{\partial N_1}{\partial x_2} & \frac{\partial N_6}{\partial x_1} & \frac{\partial N_6}{\partial x_2} \\ 0 & 0 & 0 & 0 \end{bmatrix} \end{aligned}$$

$$E(\nabla u) = \frac{1}{2} (\nabla u + \nabla u^T)$$

$$= \begin{bmatrix} \frac{\partial N_1}{\partial x_1} & \frac{1}{2} \frac{\partial N_1}{\partial x_2} & \frac{\partial N_2}{\partial x_1} & \frac{1}{2} \frac{\partial N_2}{\partial x_2} & \dots \\ 0 & 0 & 0 & 0 & \dots \end{bmatrix}$$

$\mathcal{E}_{11}$























































