



Modal cut-on ratio in ducts with realistic flow profiles and its application to acoustic mode detection

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ABSTRACT

This paper considers the modal cut-on ratio and its use in acoustic mode detection in ducts for a radially varying flow with swirl. These concepts have previously only been considered for the idealised case of uniform axial mean flow and no swirl, and thus in this paper they are generalised and extended to account for radial variations in axial and swirl Mach numbers. The cut-on ratio is shown to no longer satisfy a simple relation with the axial wavenumber, showing that while the cut-on ratio in arbitrary flow is defined its usefulness significantly decreases. Mode distribution functions are also investigated for radially varying flows, both in terms of cut-on ratio and axial wavenumber. In view of the deficiencies of the cut-on ratio highlighted in the paper a recent method for mode detection in ducts that uses just two microphones is generalised to deduce the mode amplitudes in radially varying flows, based on modal axial wavenumber rather than cut-on ratio. This method is shown to perform better than the existing method in radially varying and/or swirling flow in simple test configurations with an idealised source distribution.

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1. Introduction

This paper deals with the definition of modal cut-on (or cut-off) ratio in ducts with realistic mean flow profiles and its application to mode detection in high-frequency broadband sound fields. The concept of cut-on ratio was proposed in the early 1970's by Rice [1] as a non-dimensional measure of the extent to which an acoustic mode (indexed by (m, n)) in a duct is cut-on. In approximate terms it is related to how high in frequency ω an acoustic mode is excited above its cut-on, or resonance, frequency ω_{mn} . A mode excited at a single frequency well above its cut-on frequency, $\omega \gg \omega_{mn}$, is said to be well cut-on and its wavefront normal vector propagates at a shallow angle to the duct axis. At frequencies close to the cut-on frequency, the mode is said to be close to cut-off, whose modal wavefront normal vector propagates at a large angle to the duct axis. These modes transport comparatively little sound power along the duct, tending to zero at cut-off. The usefulness of this concept is that in a hard-walled duct containing a uniform mean axial flow, different modes with different values of mode indices (m, n) , but with the same cut-on ratio, have similar transmission characteristics along the duct and similar radiation characteristics to the far field, as indicated in Section 1.2 below.

The concept of modal cut-on (or cut-off ratio) is now in common usage in duct acoustics [2–5] as a single index of the degree to which a single mode is cut-on. It is a well-defined quantity in the idealised case of a hard-walled duct containing a uniform mean axial flow and can be used to deduce the modal propagation angle within the duct [6] and also the angle of the

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main lobe upon radiation to the far field [7,8]. However, its definition in realistic mean flow profiles, and more importantly its interpretation, is less clear. These issues are addressed in this paper.

We start by reviewing the basic relations between cut-on ratio and modal wavenumbers for the idealised case of uniform mean axial flow. These are generalised to arbitrary mean flow profiles including the effects of swirl, whose usefulness and limitations are then explored. Finally, its application to the new two-microphone method recently proposed by Joseph [9] is investigated in which the concept of cut-on ratio and its simple relationship to the modal axial wavenumber is central. Here we show that this method, which aims to determine the distribution of mode amplitudes versus cut-on ratio, breaks down. An alternative formulation is proposed that overcomes these issues.

1.1. Modal cut-on ratio

The usefulness of the cut-on ratio was first proposed by Rice [10,11]. Rice's innovation was to recognise that in a hard-walled duct containing a uniform mean axial flow, different modes with different values of mode indices (m, n), but with the same cut-on ratio α_{mn} , had similar transmission characteristics along the duct and similar radiation characteristics to the far field. In particular, Rice showed that for this idealised case, in which the flow speed was everywhere the same, the cut-on ratio was uniquely and simply related to the angle φ_x at which the modal wavefront normal vector makes with the duct axis, and also the angle ψ_p of the main far-field radiation lobe. Rice [1] used this concept to derive mode amplitude distributions that vary smoothly with cut-on ratio for some idealised source distributions, such as when each mode is assumed to contain identical sound power. Joseph et al. [12] later extended this concept to express the amplitude distribution of a broader family of physically important source distributions in terms of α .

We start by reviewing the basic relations between modal cut-on ratio α and the modal wavenumber components in a cylindrical hard-walled hollow or annular duct (with hub-to-tip ratio h) containing a uniform axial flow. The outer duct wall has been non-dimensionalised (see Appendix A for the details of how we non-dimensionalise all the variables) so that $r = 1$. At a single non dimensional frequency ω the acoustic pressure propagating along the duct is of the form

$$p(r, \theta, x) = \exp(-i\omega t) \sum_{m=-\infty}^{\infty} \sum_{n=0}^{\infty} A_{mn}^{\pm} P_{mn}^{\pm}(r) \exp(im\theta) \exp\left(i\omega k_{mn}^{\pm} x\right), \quad (1)$$

where A_{mn}^{\pm} is the pressure mode amplitude, m is the azimuthal mode order, $P_{mn}^{\pm}(r)$ is the normalised, non-dimensional mode shape over the duct cross section and k_{mn}^{\pm} is the non-dimensional axial wavenumber, which specifies the rate of change of phase with axial distance x along the duct for each mode. The superscripts \pm correspond to downstream modes (+) and upstream modes (−). The time dependence of p is kept implicit throughout. We note that the exponent ω in the final term is an unusual choice, but this saves having to non-dimensionalise k_{mn} by ω later on. (Work by Heaton and Peake [13] has shown that for certain flow parameters, there are instabilities associated with the nearly-convected modes and the critical layer that grow exponentially, which means that the Fourier transforms are not strictly valid. However, even in these cases Eq. (1) is still applicable unless we go far too downstream, since the contribution from the critical layer and nearly-convected modes are initially of a very small magnitude.)

Substituting Eq. (1) into the convected wave equation with the axial Mach number M_x assumed to be constant over the duct cross section yields the expression for k_{mn} of the form,

$$k_{mn} = \frac{\alpha_{mn} - M_x}{\beta^2}, \quad (2)$$

where $\beta^2 = 1 - M_x^2$. This simple relationship between k and α is central to the usefulness of the cut-on ratio as an index of modal behaviour. The relation in Eq. (2) makes explicit that the cut-on ratio α is simply the axial wavenumber k scaled by β^2 and shifted by M_x , which explains the usefulness of α . Any departure from this linear relationship leads to a loss in the usefulness of the cut-on ratio and ambiguity in its interpretation.

We have non-dimensionalised velocities by the sound speed in the quiescent medium c_0 , and hence for a uniform mean flow c_0 is identically unity and therefore the usual $1/c_0$ term on the right hand side of Eq. (2) doesn't explicitly appear. The quantity α_{mn} may be expressed in terms of the transverse modal wavenumber κ_{mn} [14]:

$$\alpha_{mn} = \pm \sqrt{1 - \beta^2 \frac{\kappa_{mn}^2}{\omega^2}}. \quad (3)$$

For the case of uniform axial flow in a hollow duct, κ_{mn} satisfies $J'_m(\kappa_{mn}) = 0$ and hence may be determined from tables of the stationary values of the Bessel function J_m , as given in Abramowitz and Stegun [15]. We can also determine the axial wavenumbers k_{mn} for uniform axial flow by solving the eigenvalue problem given in A (which also applies for an arbitrary swirling flow).

Eqs (1) and (2) make explicit the existence of a frequency $\omega = \omega_{mn}$ at which $\alpha_{mn} = 0$, below which the mode decays exponentially along the duct away from the source and may be said to be cut-off. Setting $\alpha_{mn} = 0$ in Eq. (3) gives the cut-on frequency as $\omega_{mn} = \beta \kappa_{mn}$. At any arbitrary frequency ω therefore α_{mn} may be written as,

$$\alpha = \pm \sqrt{1 - \frac{\omega_{mn}^2}{\omega^2}}. \quad (4)$$

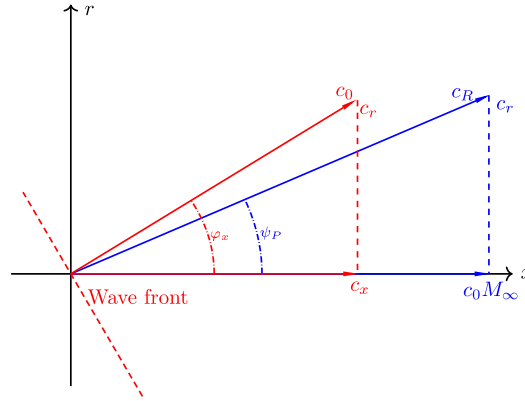


Fig. 1. Modal wavefront propagating in the r - x plane.

It therefore takes purely imaginary values for cut-off modes, is zero at cut-off and ranges between zero and unity as the frequency increases above cut-off. Other variants of this quantity are often used, such as the cut-off ratio ξ_{mn} introduced by Rice et al. [6],

$$\xi_{mn}^2 = \frac{1}{1 - \alpha_{mn}^2} = \frac{\omega^2}{\omega_{mn}^2}, \quad (5)$$

which has the advantage of being real for both cut-on and cut-off modes.

The relationship in Eq. (2) has recently been used in a new measurement method by which the mode amplitude distribution versus α_{mn} can be determined from the cross spectrum of acoustic pressures between two closely spaced microphones at the duct wall. This method will be considered again in Sections 3 and 4 and shown to be inaccurate for realistic mean flow profiles due to the deficiencies of cut-on ratio in these cases.

1.2. Modal propagation angles

Before proceeding to investigate the meaning and interpretation of cut-on ratio for realistic mean flow profiles we first discuss its usefulness in determining the main modal propagation angles in uniform axial flow. Fig. 1 show the modal wavefront, approximated as a plane wave, in the r - x plane of the duct.

The normal to the modal wavefront propagates at the speed of sound c_0 at an angle φ_x to the duct axis with components (c_x, c_r) , whose wavenumber components are in the same direction with magnitudes $k = \omega/c_0$, $k_x = \omega/c_x$ and $k_r = \omega/c_r$. However, in the presence of a uniform axial flow the resultant direction of propagation is c_R with components $(c_x + c_0 M_x, c_r)$ at an angle ψ_P to the duct axis since the axial propagation speed includes an additional drift correction $c_0 M_x$ corresponding to the axial flow speed. Making use of Eq. (2) and the geometry sketched in Fig. 1, the two modal propagation angles φ_x and ψ_P may be expressed solely in terms of cut-on ratio or axial wavenumber as follows [6],

$$\cos \varphi_x = \frac{k_{mn}}{1 - k_{mn} M_x} = \frac{\alpha_{mn} - M_x}{1 - \alpha_{mn} M_x}, \quad (6a)$$

$$\cos \psi_P = \frac{M_x + k_{mn} \beta^2}{[(1 - k_{mn} M_x)(1 + M_x(M_x + k_{mn} \beta^2))]^{1/2}} = \frac{\alpha_{mn} \beta}{(1 - \alpha_{mn}^2 M_x^2)^{1/2}}. \quad (6b)$$

The two angles φ_x and ψ_P define the behaviour of modal propagation in the duct and to the far field. The first angle relates to the angle of the wavefront within the duct, and is linked to the phase speed of the mode, which is $\cos^{-1}(M_x)$ at cut-on, tending to 0° as the frequency is increased. The second angle ψ_P quantifies the resultant propagation angle and is identical to the angle of the main far-field radiation lobe as it radiates from the duct open end. At the cut-on frequency it takes the value of 90° , and tends towards 0° as the frequency is increased above the cut-on frequency. Clearly, therefore, different modes with the same cut-on ratios have similar transmission and radiation characteristics for this idealised flow profile. It is also clear that the expression for the radiation angles are much simpler in terms of cut-on ratio than axial wavenumber.

2. Defining the cut-on ratio for swirling flow in an annular duct

As discussed in Section 1 above, the concept of cut-on ratio is well defined for a duct containing a uniform axial mean flow. Moreover, its relationship to the modal wavenumber components, and hence propagation angles, is straightforward. In the more realistic case of an arbitrary swirling flow, its definition, and usefulness, is less obvious. In this section we generalise the definition of the cut-on ratio α_{mn} to include these general profiles and investigate its relationship to the axial wavenumber

component k_{mn} , which as we saw in Eq. (6) is inextricably linked to the modal propagation angles φ_x and ψ_p . Throughout this paper we will generally drop the indices notation (m, n) (except where needed) and just refer to the cut-on ratio as α and axial wavenumber or mode k .

We now consider modal propagation in a hard-walled annular duct $h < r < 1$ containing radially varying axial and circumferential velocity components $M_x(r)$ and $M_\theta(r)$, respectively. As soon as we consider swirling flow, we have a number of difficulties. For example, the formulation in Eq. (1) is no longer true, since the modes are no longer orthogonal and a complete basis. However, if the nearly-convected modes are assumed to have a very small contribution then it approximately holds as a sum over the acoustic modes, as shown in Posson and Peake [16].

2.1. Defining the cut-on ratio for arbitrary swirling flow

In this paper we define the cut-on ratio for arbitrary swirling flows to be

$$\alpha_{mn} = \pm \sqrt{1 - \frac{\omega_{mn}^2}{\omega^2}}, \quad (7)$$

where ω_{mn} is the cut-on frequency of the (m, n) -th mode (i.e. the frequency at which k_{mn} goes from propagating ($\Im(k_{mn}) = 0$) to evanescent ($\Im(k_{mn}) \neq 0$)). Note that this definition was chosen to have the desired property of spanning the range $[-1, 1]$ for the range of propagating duct modes. We emphasise, however, that the choice of definition is essentially arbitrary. In choosing it to be defined by Eq. (7) it has the advantages of being entirely consistent with the case of uniform mean axial flow and, as we shall show below in Section 2.3, has an identical distribution to that of a uniform axial flow even for large radial variations in axial and circumferential flow speeds.

Another advantage of choosing the definition in Eq. (7) is that it allows for the easy determination of propagating (or cut-on) and evanescent (or cut-off) modes. In term of the axial wavenumber k_{mn} , a mode is propagating if $\Im(k_{mn}) = 0$ and evanescent otherwise. In term of the cut-on ratio α_{mn} , a for a propagating mode we have $\alpha_{mn} \in [-1, 1]$, while for an evanescent mode α_{mn} is purely imaginary since $\omega_{mn} > \omega$. Thus, it performs in the same way as for uniform flow.

In general, the cut-off frequencies ω_{mn} are required to be calculated numerically, and a procedure for doing this is described in B.

2.2. Relating the cut-on ratio and axial wavenumber

In this section, the computed values of α deduced from the numerical procedure outlined in B are plotted against their corresponding values of k (also calculated using the method described in A) for the three representative cases of: uniform axial flow, radially varying axial flow and radially varying swirling flow. In what follows we are only interested in the acoustic modes k , with all the nearly-convected modes or hydrodynamic modes ignored. Furthermore, we will limit our discussions to cut-on or propagating acoustic modes. Comparing the numerical values of α and k will be shown to be key in establishing the validity of the theoretical linear relationship expressed in Eq. (2) in these cases, and hence establish the usefulness of cut-on ratio as a parameter for uniquely determining modal propagation.

We will see that the relationship between α and k becomes significantly more complicated and non-linear when radial variations to the flow are present. In these more realistic cases, therefore, cut-on ratio may not be as useful as a parameter for predicting modal propagation and an alternative parameter must be considered, as discussed in Section 3.

2.2.1. Uniform axial flow

Before discussing more realistic flow profiles, we first consider the idealised case of a uniform axial flow with Mach number $M_x = 0.5$ in an annular duct with hub-to-tip ratio $h = 0.5$ at a non-dimensional frequency of $\omega = 20$. This case allows the validation of the numerical procedure aimed at reproducing the theoretical relation of Eq. (2). Fig. 2 is a plot of k against α (calculated using the cut-on frequency in Eq. (7)) for all the cut-on radial modes associated with representative values of m ($m = 0, 5, 10, 15, 20$). Also shown is the dashed line of Eq. (2). Extremely good agreement is observed, thereby validating the numerical procedure.

2.2.2. Radially varying axial flow

In this section the relationship between α and k is investigated for the case of radially varying axial flow in which swirl is absent. Fig. 3a, b and c are plots of α versus k for the three idealised profiles of $M_x(r) = 0.4 + 0.4(r - h)$, $M_x(r) = 0.33 + 0.66(r - h)$ and $M_x(r) = 0.25 + (r - h)$ at a non-dimensional frequency of $\omega = 20$ in a duct with a hub-to-tip ratio of $h = 0.5$. These shear flows profiles are designed to have increasing gradient but have an identical radially-averaged mean flow speed of $\bar{M}_x = 0.5$. Whilst not being completely realistic, these profiles were chosen to allow a systematic investigation to be carried out into the sensitivity of cut-on ratio to variations in the axial shear flow profiles. Such profiles could be representative of those typical of the inlet and bypass ducts in aeroengines. For each flow we consider all the cut-on radial modes, with the largest value of m corresponding to a propagating mode different in each figure and is highlighted in red circles.

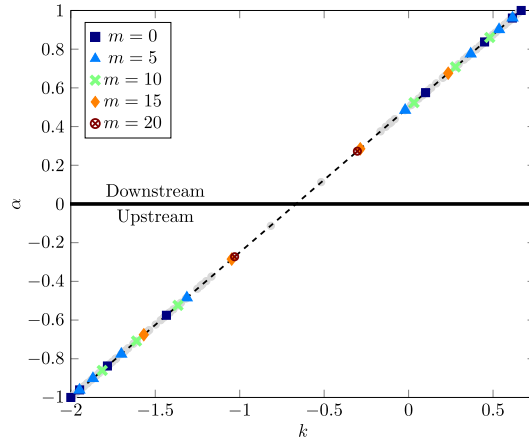


Fig. 2. Plot of k versus α in grey circles for $M_x = 0.5$, $\omega = 20$, $h = 0.5$ and all values of m . Selected values of m are highlighted with coloured shapes. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

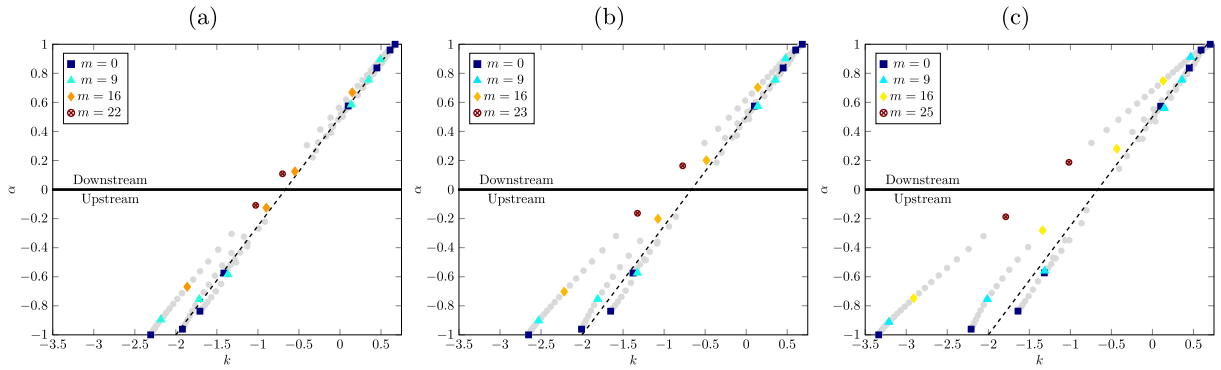


Fig. 3. Plot of k versus α for three different axial flows (grey circles), (a): $M_x(r) = 0.4 + 0.4(r-h)$, (b): $M_x(r) = 0.33 + 0.66(r-h)$ and (c): $M_x(r) = 0.25 + (r-h)$. The other parameters are $h = 0.5$ and $\omega = 20$. Selected values of m have been highlighted with coloured shapes. In black (dashed) is the relationship between k and α for uniform flow $\overline{M_x} = 0.5$. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

Also shown in these figures, as a dashed line, is the theoretical line of Eq. (2) showing the relationship for the case of uniform axial mean flow.

These figures demonstrate that the relationship $k(\alpha)$ is no longer linear and whose deviation from the uniform flow case (the black dashed line) increases as the shear flow gradient increases. In these figures the modal behaviour associated with some representative circumferential mode orders m are indicated as coloured shapes. It is clear from the figure that in these systematically chosen flow profiles, the behaviour of $k(\alpha)$ for individual modes is complicated and may be summarised as follows:

1. The relationship $k(\alpha)$ is monotonic for modes at a fixed value of m .
2. Modes of the same radial index n (with $n = 1$ corresponding to the most cut-on mode) but different m values follow the same trajectory, which in this case appears to be approximately linear.
3. The variation of α for a given value of k increases as α decreases from 1 to -1 . Greater variations in α are predicted for upstream-going modes than downstream-going modes.
4. As a consequence of the second observation the relationship $k(\alpha)$ is no longer one-to-one, in the sense that a single value of k can correspond to multiple values of α . In particular, in Fig. 3c, $k \approx -1$, for example, could correspond to an upstream or a downstream mode, with this distinction marked in each figure.

We can therefore conclude from Fig. 3 that for small variations in the mean flow profile (such as in Fig. 3a), the cut-on ratio remains a useful concept in determining the modal axial wavenumber k and hence modal propagation, as sketched in Fig. 1. However, for larger variations in flow profile (such as Fig. 3b and c), α no longer accurately quantifies the behaviour of k and hence modal propagation.

We now consider the relationship between k and α for a more realistic axial flow profile. This profile was measured in the by-pass section of a scale-model aero-engine with hub-to-tip ratio of $h = 0.6558$ in the Anecom test facility in Germany [17].

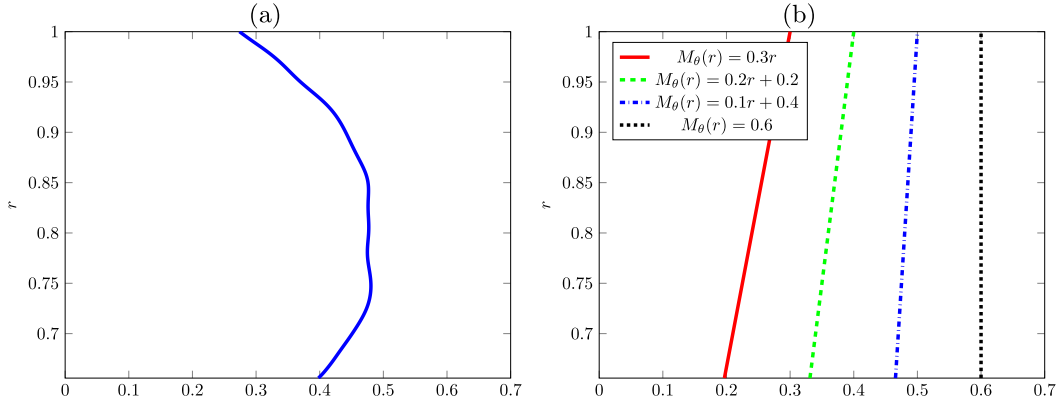


Fig. 4. Plot of (a) axial flow $M_x(r)$ based on Tester and Murray [17]. The hub-to-tip ratio is $h = 0.6558$. In (b) we give the idealised swirling flows $M_\theta(r)$ that are considered later in Section 2.2.3. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

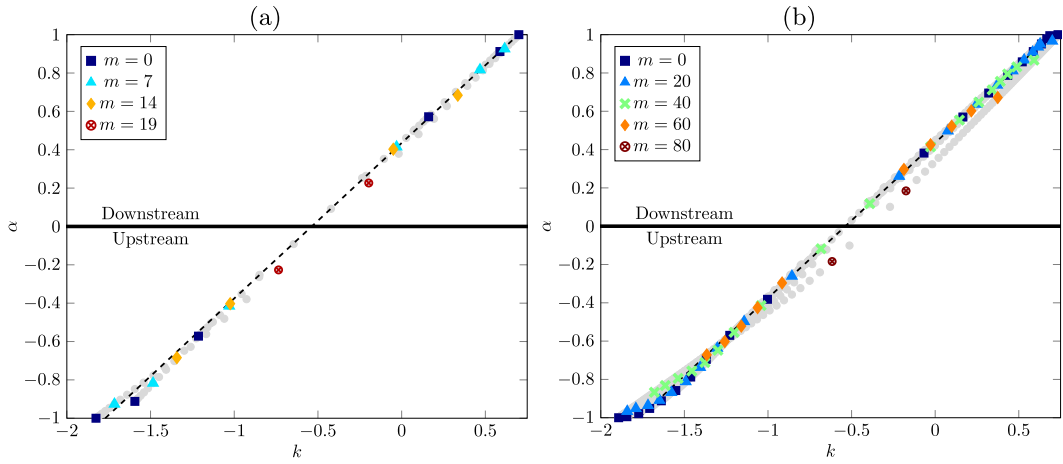


Fig. 5. Plot of k versus α for the realistic axial flow $M_x(r)$ from Fig. 4a. The other parameters are $h = 0.6558$ and (a) $\omega = 20$ and (b) $\omega = 80$. Selected values of m have been highlighted with coloured shapes. In black (dashed) is the relationship between k and α for uniform flow $\overline{M_x} = 0.445$, corresponding to the radial average. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

This profile is plotted in Fig. 4a. The relationship between α and k is plotted in Fig. 5 at the two frequencies of $\omega = 20$ and $\omega = 80$. While all four features above are present in the plots, for this more realistic case the variation $k(\alpha)$ is much closer to the uniform profile case. The definition of cut-on ratio remains valid and useful for this more realistic non-swirling profile.

From Fig. 5, it is clear that the relationship between k and α is broadly similar at the low and high frequencies under consideration. This applies generally for other flows, such as those in Fig. 3 and throughout the rest of this paper. Since calculating the wavenumbers k and cut-on ratio α is more expensive at higher frequencies, we can thus examine the behaviour $k(\alpha)$ at low frequencies to determine the relationship between k and α , and the usefulness of the cut-on ratio.

At the present time we are unable to predict the extent of deviation of $k(\alpha)$ for any arbitrary flow profile from the uniform axial flow case and hence establish the usefulness of cut-on ratio. However, the deviation is clearly linked to the degree of variation in the flow profile with radius. More work is needed to understand the sensitivity of $k(\alpha)$ to flow profile.

2.2.3. Radially varying axial and swirling flow

We now consider the most general case of radially varying axial flow and swirling flow representative of, for example, the interstage region of an aeroengine. To understand the general effects of swirl on the behaviour of $k(\alpha)$ it is instructive to first consider the idealised case of solid body swirl of $M_\theta(r) = \Omega r$ with uniform axial flow. We initially use an idealised swirl model where the effect of swirl is simply to shift the frequency in Eq. (2) by a Doppler factor $-m\Omega$, as in Morfey [14] (so ignoring the effect of the mean swirl on the mean flow speed of sound and density in Eq. (A.2) and Eq. (A.3) briefly for this example only). The $k(\alpha)$ relationship from Eq. (2) therefore becomes

$$k_{mn} = \frac{\alpha_{mn} - M_x}{1 - M_x^2} \frac{\omega - m\Omega}{\omega}. \quad (8)$$

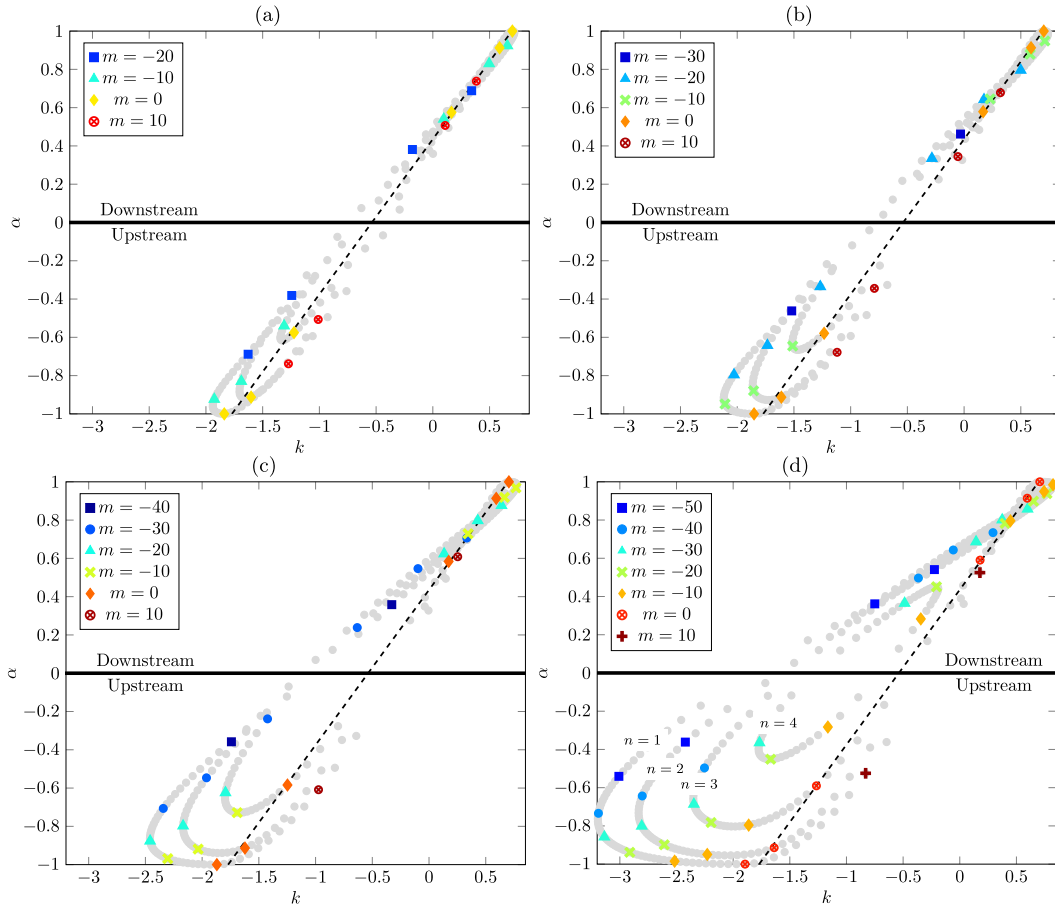


Fig. 6. Plot of k versus α (grey circles) for the axial flow from Fig. 4a and different swirling flows (a) $M_\theta(r) = 0.3r$; (b) $M_\theta(r) = 0.2r + 0.2$; (c) $M_\theta(r) = 0.1r + 0.4$ and (d) $M_\theta(r) = 0.6$. The other parameters are $h = 0.6558$ and $\omega = 20$. Selected values of m have been highlighted with coloured shapes. In black (dashed) is the relationship between k and α for uniform axial flow $\bar{M}_x = 0.445$ and no swirl. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

Thus, there is no longer a relation involving only k and α since now we have an additional dependence on m .

We now investigate the precise dependence of k on α for a flow profile comprising the realistic axial flow profile $M_x(r)$ plotted in Fig. 4a, combined with four different idealised swirling flow profiles with increasing levels of swirl. These are given by $M_\theta(r) = 0.3r$ (solid body swirl), $M_\theta(r) = 0.2r + 0.2$, $M_\theta(r) = 0.1r + 0.4$ and $M_\theta(r) = 0.6$, and are plotted in Fig. 4b. We have assumed both the axial and swirling flow have an infinitely thin boundary layer, and therefore used the Myers boundary condition to account for the boundary layer. Otherwise, fully resolving the boundary layer is challenging and computationally expensive.

The computed variation of k with α is plotted in Fig. 6 at a frequency of $\omega = 20$. Note that the effects on the mean sound speed and density by the swirling flow is accounted for in these computations and throughout the rest of the paper.

The variation of k with α in these figures show similar features as described in Section 2.2.2 for the non-swirling flow but with some important differences. The most notable difference is that the relationship is no longer symmetric in $\pm m$. As a result, for a fixed radial mode order n , the trajectories that were approximately lines in Fig. 3 now become loops. Each loop corresponds to a particular radial mode order, as explicitly labelled in Fig. 6d (with $n = 1$ corresponding to the most cut-on mode).

Finally we note that the modes associated with circumferential mode order $m = 0$ lie very close to the black (dashed) line denoting the relationship between k and α in uniform flow. This behaviour is readily understood from Eq. (8) for the case of solid body swirl with the idealised swirl model which predicts that swirl has no effect for these axisymmetric modes. Therefore, the behaviour at $m = 0$ closely mirrors Fig. 5a which has the same axial flow profile but no swirl.

2.3. Mode distribution function for cut-on ratio

One of the advantages of representing modes by their cut-on ratio rather than mode indices (m, n) is in the calculation of multi-mode sound field in the high frequency limit [1,12]. In these calculations the double summation over m and n is replaced

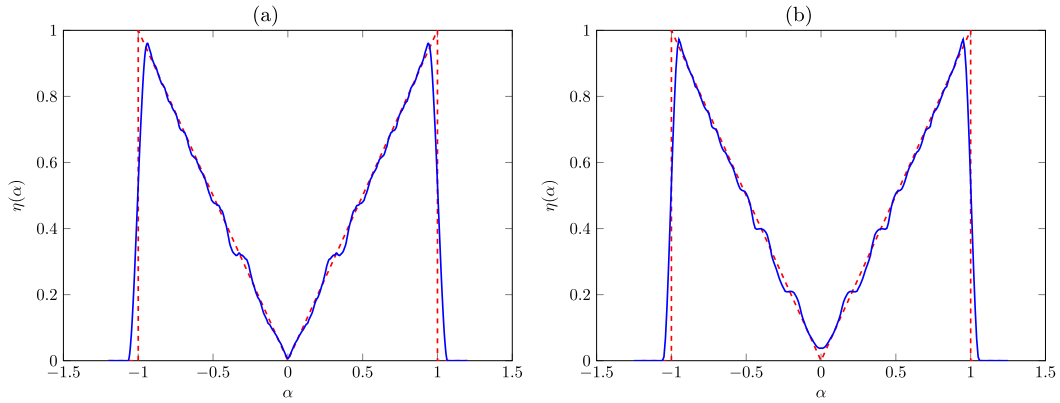


Fig. 7. Plot of $\eta(\alpha)$ (in blue, solid) after calculating α for all cut-on modes for two different flows in an annular duct with $0.5 < r < 1$. We have plotted $|\alpha|$ in red (dashed). The flow parameters are (a) $M_x = 0.5, M_\theta = 0, \omega = 80$; (b) $M_x(r) = 0.3 + 0.2r^2, M_\theta(r) = 0.2r + 0.3, \omega = 80$. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

by a single integration over cut-on ratio α , where α is treated as a continuous variable on the domain $[-1, 1]$. Central to these calculations is therefore knowledge of how the values of α are distributed, which is expressed as a probability density function $\eta(\alpha)$.

One such example of this approach is in a new measurement procedure, referred to here as the two-microphone method [9], which allows the mode amplitude distribution to be deduced as a function of α from measurements of the coherence function between two acoustic measurements made at the duct wall. However, this method based on α is restricted to a uniform axial mean flow. This procedure will be discussed in some detail in Section 3 and a revised formulation based on wavenumber k is presented subsequently that is valid for any arbitrary flow profile.

In a hollow duct with uniform axial flow, in the high-frequency limit, work by Joseph [9], Joseph et al. [12], Rice [1] have shown analytically that α has the following distribution

$$\eta(\alpha) = |\alpha|, \quad -1 \leq \alpha \leq 1. \quad (9)$$

This result predicts that there are comparatively very few modes close to $\alpha = 0$ near cut-off, and most of the modes are clustered near the end points at $\alpha = \pm 1$, corresponding to well cut-on modes.

The density function $\eta(\alpha)$ is now computed numerically for the case of uniform axial flow in an annular duct with $h = 0.5$ and also the more general swirling flow $M_x(r) = 0.3 + 0.2r^2, M_\theta(r) = 0.2r + 0.3$, also with $h = 0.5$. These density functions are plotted in Fig. 7a and Fig. 7b respectively, in blue (solid). The dashed red curve in this figure corresponds to the distribution of Eq. (9). Even for swirling flow, the distribution $\eta(\alpha)$ is observed to closely follow $|\alpha|$. These results clearly suggest that the definition of α in Eq. (7) appears to preserve the essential density function derived for uniform flow, irrespective of flow profile. The reasons for this unexpected result are currently not clear.

In order for the density functions to be reasonably smooth, we have to compute $\eta(\alpha)$ at a large frequency, which has been done in Fig. 7 ($\omega = 80$). If we instead considered lower frequencies, then we would get a distribution which oscillates significantly and would not be useful in estimating $\eta(\alpha)$ accurately.

2.4. Mode distribution for wavenumber

So far in this section we have considered the relationship between wavenumber k and cut-on ratio α , and also the probability density function of α . We therefore now turn our attention to the probability density function (or modal density function) $\eta(k)$, which will be of use in Section 3 in a revised two-microphone method based on k . Note that unlike the $\eta(\alpha)$ distribution in Fig. 7, the mode distribution is expected to differ for each flow profile.

2.4.1. Uniform axial flow

In the case of uniform axial flow, Eq. (2) indicates a linear relationship between k and α from which k takes values in the range

$$-\frac{1}{1-M_x} < k < \frac{1}{1+M_x}, \quad (10)$$

for propagating modes, so, unlike α is not symmetric unless $M_x = 0$. Substituting for k in the probability density function for α in Eq. (9) and normalising $\eta(k)$ such that

$$\int_{-1/(1-M_x)}^{1/(1+M_x)} \eta(k) dk = 1, \quad (11)$$

Table 1

Calculation of k_{\min} and k_{\max} for the swirling flow $M_x(r) = 0.4 + 0.4(r - h)$, $M_\theta = 0$ in a duct $0.5 < r < 1$ at different frequencies, showing the weak frequency dependency.

ω	10	20	40	80	160
k_{\min}	-1.7896	-1.8382	-1.8788	-1.9060	-1.9188
k_{\max}	0.6987	0.7013	0.7135	0.7351	0.7523

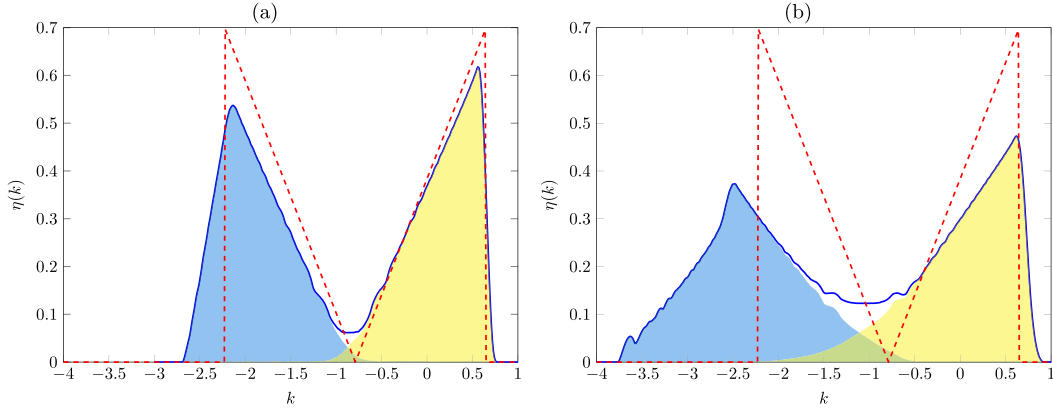


Fig. 8. Plot of $\eta(k)$ (in blue, solid) after calculating k for all cut-on modes for axial flow $M_x(r) = 0.4 + 0.2r$ in a duct $0.5 < r < 1$ at a frequency $\omega = 150$. The swirl is (a) $M_\theta(r) = 0.1r + 0.1/r$ and (b) $M_\theta(r) = 0.3r + 0.2/r$. In blue is the distribution of upstream cut-on modes, while in yellow is the distribution of downstream modes. In red (dashed) we have plotted the density function $\eta(k)$ for the uniform axial flow \bar{M}_x , given by Eq. (12). (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

gives

$$\eta(k) = (1 - M_x^2)^2 \left| k + \frac{M_x}{1 - M_x^2} \right|. \quad (12)$$

It is clear that $k = -M_x/(1 - M_x^2)$ corresponds to $\alpha = 0$ for modes at cut-off, with both having probability zero. The maximum value of the modal density function occurs for the most upstream and downstream cut-on modes, $k = -1/(1 - M_x)$ and $k = 1/(1 + M_x)$ respectively, where $\eta(k) = 1 - M_x^2$.

2.4.2. Radially varying axial and swirling flow

One of the advantages of expressing the distribution of modes according to their α values is that across the range of propagating modes α varies between -1 and 1 . In the case of uniform axial mean flow, the corresponding range of k is readily determined from Eq. (10). However, in the general case of arbitrary radially varying swirling flow, the range of k must be determined numerically, which we now show varies with frequency.

Table 1 lists the calculated values of the minimum and maximum values of k for the range of propagating modes at different frequencies for the radially varying non-swirl case, $M_x(r) = 0.4 + 0.4(r - h)$, $M_\theta = 0$ considered previously in Section 2.2.2. Table 1 makes clear the frequency dependence of the minimum and maximum values of k needed to quantify the range of propagating modes. However, as we let $\omega \rightarrow \infty$ then k_{\min} and k_{\max} appears to converge to well defined limits. A similar study in swirling flow suggests that the observation is also valid in this case, but the maximum and minimum values of k no longer occur at $m = 0$, so it much more expensive to compute k_{\min} and k_{\max} .

We now investigate the behaviour of the modal density function for an arbitrary swirling flow, obtained after numerically computing k for all the propagating modes. In practice $\omega \gtrsim 100$ was found to be sufficiently high to obtain a smooth estimate for the density function $\eta(k)$.

The modal density functions $\eta(k)$ are compared in Fig. 8 for two cases of identical axial flow profile $M_x(r) = 0.4 + 0.2r$ but with low (Fig. 8a) and high (Fig. 8b) levels of swirl, gives by the profiles $M_\theta(r) = 0.1r + 0.1/r$ and $M_\theta(r) = 0.3r + 0.2/r$. The radially averaged levels of swirl for the two cases are $\bar{M}_\theta = 0.2136$ and $\bar{M}_\theta = 0.5023$ respectively. The distributions were calculated at the non-dimensional frequency of $\omega = 150$. The distribution of upstream propagating modes is depicted in yellow and the downstream modes in blue. For comparison, the density function of Eq. (12) for the uniform axial mean flow is plotted as a red dashed line.

The density functions $\eta(k)$ for swirling flow in Fig. 8 exhibit several features distinct from the α distributions plotted in Fig. 7. The most striking observation is that $\eta(k)$ differs significantly from the case of the uniform axial flow in terms of shape, height and end points k_{\min} and k_{\max} . As we increase the swirl velocity, these differences becomes more exaggerated, as seen in Fig. 8b. One particularly noticeable feature in Fig. 8 is the presence of an overlap region (in green) of k in which upstream and downstream propagating modes share the same value of k . This phenomenon is also observed in flow profiles in which swirl

is absent. For higher values of swirl, this effect is more pronounced, as seen in Fig. 8b. However, this non-uniqueness is not a problem when either the upstream or downstream going modes are dominant, such as in an aeroengine duct inlet or bypass section.

By way of summary, therefore, a simple distribution for α with $\eta(\alpha) = |\alpha|$ for $-1 \leq \alpha \leq 1$ is observed for all swirling flows considered. However, due to the complex inter-relationship between the wavenumber and cut-on ratio, as shown in Section 2.2, the resulting density function in k is complicated, depends on the flow profile and must be numerically determined.

3. A new two-microphone method

In this section we investigate a relatively new method for determining the mode amplitude distribution in which the concept of cut-on ratio was central. It is based on previous work by Joseph [9] in which the mode amplitude distribution may be determined as a function of cut-on ratio α from measurements of the coherence function between the acoustic pressures at two closely spaced microphones at the duct wall. Central to the formulation of the method is Eq. (2) linking k to α for a uniform mean axial flow. The formulation in Joseph [9] is therefore restricted to the idealised case of uniform mean flow.

In this section we provide an alternative formulation in terms of the axial mode wavenumber k which circumvents the need to invoke the relationship of Eq. (2) for uniform mean flow. The new formulation in terms of k is therefore completely general, and therefore allows the mode amplitude distribution to be determined as a function of k for any arbitrary flow profile, including swirl. This new formulation also highlights the deficiency of the cut-on ratio in arbitrary flows. We will show in the next section that the α -based and k -based formulations give essentially equivalent mode amplitude distribution results for the flow profiles for which $k(\alpha)$ matches most closely the theoretical relationship of Eq. (2) for a uniform mean axial flow.

3.1. Outline of method

In this section the basic steps involved in the derivation of the expression for the mode amplitude distribution in terms of the pressure coherence function are presented for radially varying swirling flow. However, unlike in Joseph [9] we avoid the use of Eq. (2) linking k and α which is valid only for uniform mean flow.

We begin by calculating the pressure cross spectrum (density) between two points separated by a distance Δx at the same circumferential location on the outer duct wall. Making the assumption of uncorrelated mode amplitudes, the cross spectrum between the acoustic pressures at the outer wall of the duct with arbitrary θ and an axial separation distance of Δx is given by

$$S_{12}(\omega) = \mathbb{E} \left[\frac{p(1, \theta, x_1) p^*(1, \theta, x_1 + \Delta x)}{T} \right]. \quad (13)$$

In this expression, T is the time interval over which the Fast Fourier Transform of p is taken, and p is given in Eq. (1). Substituting Eq. (1) in Eq. (13) (which approximately holds even for swirling flow as discussed at the start of Section 2) then gives the cross spectrum as

$$S_{12}(\omega) = \sum_{m,n} \left[\mathbb{E} \left(|A_{mn}^+(\omega)|^2 \right) e^{i\omega k_{mn}^+ \Delta x} |P_{mn}^+(1)|^2 + \mathbb{E} \left(|A_{mn}^-(\omega)|^2 \right) e^{i\omega k_{mn}^- \Delta x} |P_{mn}^-(1)|^2 \right], \quad (14)$$

where we have separated the cross spectrum into downstream (+) and upstream contributions (−). The eigenfunctions (or mode shapes) $P_{mn}^\pm(r)$ have been normalised such that

$$\frac{2}{(1-h^2)} \int_h^1 |P_{mn}^\pm(r)|^2 r dr = 1. \quad (15)$$

The main assumption underlying the technique is that the relative mode amplitude distribution is only a function of the non-dimensional axial wavenumber k_{mn} . The mode amplitude distribution has been demonstrated to be solely a function of α in uniform flow for a broad range of physically realistic source distributions as seen in Rice [1], Joseph et al. [12]. It must therefore be solely a function of k in a uniform mean axial flow since k and α are linearly related through Eq. (2). In this new formulation we will assume that the relative mode amplitude distribution only depends on k for all flow profiles. The mode amplitudes may therefore be written in the form

$$\mathbb{E} \left(|A_{mn}^\pm(\omega)|^2 \right) = S(\omega) \overline{a_\pm^2(k_{mn}^\pm)}. \quad (16)$$

where $S(\omega)$ is a frequency-dependent source term whose interpretation will be made clear below and $\overline{a_\pm^2}$ describes the non-dimensional mode amplitude function of modal axial wavenumbers k_{mn}^\pm , which is to be determined.

In the high-frequency limit (non-dimensional frequency $\omega \gtrsim 10$) we can treat $\overline{a_\pm^2}(k)$ as a continuous variable. The discrete summation in Eq. (14) can therefore be replaced by an integration over k that includes the density function $\eta(k)$ to account for the distribution of modes across their k -values, as plotted in Fig. 8 and discussed in Section 2.4. Finally, we replace the square of the radial eigenfunctions $P_{mn}^\pm(1)$ by their value at the duct wall (see Joseph et al. [12]) averaged over all indices m and n , given by

$$\langle |P_{mn}^\pm(1)|^2 \rangle = 2. \quad (17)$$

This approximation gives the largest error for modes with large m values [9], but since there are relatively few of these modes the approximation should produce “negligible error” [12] compared to the exact calculation.

After making these three approximations and noting that the number of modes with k values between k and $k + dk$ is $N_\omega \eta(k)dk$, where N_ω is the total number of propagating modes at the frequency ω , we therefore arrive at the pressure cross spectrum at the duct wall:

$$S_{12}(\hat{\omega}) = 2N_\omega S(\hat{\omega}) \int_{k_{\min}}^{k_{\max}} \overline{a^2(k)} \eta(k) e^{i\hat{\omega}k} dk, \text{ where } \hat{\omega} = \omega \Delta x. \quad (18)$$

Finally, we choose the non-dimensional mode amplitude distribution to be normalised such that

$$\int_{k_{\min}}^{k_{\max}} \overline{a^2(k)} \eta(k) dk = 1. \quad (19)$$

Setting $\Delta x = 0$ in Eq. (18) gives the autospectrum $S_{11}(\hat{\omega})$ of pressure at the duct wall. Further noting the normalisation property of Eq. (19) defines the source term $S(\omega)$ in terms of the autospectrum of the pressure at the duct wall,

$$S_{11}(\hat{\omega}) = 2N_\omega S(\hat{\omega}). \quad (20)$$

We then approximate the pressure power spectral density at $x_2 = x_1 + \Delta x$, by $S_{22}(\hat{\omega}) \approx S_{11}(\hat{\omega})$ and introduce the complex coherence function $\psi_{12}(\hat{\omega})$, which is defined at the duct wall and is given by

$$\psi_{12}(\hat{\omega}) = \frac{S_{12}(\hat{\omega})}{\sqrt{S_{11}(\hat{\omega})S_{22}(\hat{\omega})}}. \quad (21)$$

Finally, we arrive at an integral relationship between the complex coherence function $\psi_{12}(\hat{\omega})$ and the mode amplitude distribution function $\overline{a^2(k)}$,

$$\psi_{12}(\hat{\omega}) = \int_{k_{\min}}^{k_{\max}} \overline{a^2(k)} \eta(k) e^{i\hat{\omega}k} dk. \quad (22)$$

This integral can be thought of as an integral over \mathbb{R} , since $\eta(k) = 0$ for $k < k_{\min}$ or $k > k_{\max}$. The result is a Fourier transform relationship between the coherence function $\psi_{12}(\hat{\omega})$ and the mode amplitude distribution $\overline{a^2(k)}$, which can be readily inverted to deduce $\overline{a^2(k)}$ in terms of the easily measurable quantity $\psi_{12}(\hat{\omega})$:

$$\overline{a^2(k)} = \frac{1}{2\pi\eta(k)} \int_{-\infty}^{\infty} \psi_{12}(\hat{\omega}) e^{-i\hat{\omega}k} d\hat{\omega} \quad \text{for } k_{\min} < k < k_{\max}. \quad (23)$$

In the original formulation of this method [9] the additional step was taken of expressing k in terms of α using Eq. (2) for the case of uniform mean flow to arrive at a Fourier Transform relationship between the mode amplitude distribution as a function of α and the coherence function. The original formulation in terms of α may be recovered from the general result of Eq. (23) by making the substitution $k = (\alpha - M_x)/(1 - M_x^2)$ to give

$$\overline{a^2(\alpha)} = \frac{1}{2\pi|\alpha|} \int_{-\infty}^{\infty} e^{iM_x\hat{\omega}} \psi_{12}(\hat{\omega}) e^{-i\hat{\omega}\alpha} d\hat{\omega} \quad \text{for } -1 < \alpha < 1, \text{ where } \hat{\omega} = \frac{\omega \Delta x}{1 - M_x^2}. \quad (24)$$

However, the current analysis demonstrates that this additional step is unnecessary in the case of uniform mean flow and incorrect for realistic flow profiles since there is no longer a linear relationship between k and α . The analysis above has demonstrated that the essential Fourier Transform relation between $\overline{a^2}$ and the coherence function is with the modal axial wavenumber k and that further expressing it in terms of α is unnecessary and potentially inaccurate, as demonstrated in the simulations presented below in Section 4.

3.2. Limitations of the new two-microphone method

The previous section has demonstrated how the two-microphone method may be completely generalised to any arbitrary flow profile to allow the mode amplitude distribution to be determined as a function of k based on pressure measurements at just two microphones at the duct wall. However, the formulation introduces a number of potential difficulties that must be considered that do not exist in the original formulation in terms of α for uniform mean flow.

One of the major difficulties with the use of the new formulation is that, whilst it can provide an accurate estimate for $\overline{a^2}$ in terms of k , the interpretation of k in terms of modal propagation and radiation angles, φ_x and φ_p respectively, is much less clear. This difficulty is an artefact of the radially varying flow and the difficulty in defining meaningful propagation and radiation angles in these flow profiles, rather than the new technique itself.

The second fundamental difficulty with the new formulation is the non-uniqueness of k in describing upstream and downstream propagating modes. A small range of k values have been shown to exist for each flow profile that correspond to both

upstream and downstream going modes for different values of m , as seen in Fig. 8. Clearly, this non-uniqueness issue only presents difficulties when upstream and downstream going modes of roughly the same amplitude are present simultaneously.

Lastly, the new method requires an estimate for the modal density function $\eta(k)$, which we have shown in Section 2.4 varies considerably depending upon the mean flow profile. By contrast, the density function for α , based on a limited number of simulations with different profiles, appears to be robust and given by $\eta(\alpha) = |\alpha|$. The new formulation therefore introduces extra computation time, but is not excessive if the range of flow profiles under consideration is limited.

4. Evaluation of the two-microphone methods

In this section, the accuracy of the original two-microphone method of Eq. (24) based on the cut-on ratio and the assumption of uniform mean flow is now compared against the new formulation of Eq. (23) based on k in which no assumption is made about the nature of the mean flow profile. Their relative ability to deduce the mode amplitude distribution from the acoustic pressure coherence function is now compared. An idealised source distribution is assumed in this study comprising incoherent point monopole sources uniformly distributed over the duct cross section.

Four different swirling flow profiles are investigated for numerical validation of the two methods. The first is the axial flow profile shown in Fig. 4a, which was measured in a scale-model test rig with hub-to-tip ratio of $h = 0.6558$, and the second is for the axial flow $M_x(r) = 0.25 + (r - h)$ with $h = 0.5$. Both flow profiles have no swirling component. The third and fourth cases involve swirling flow, with the third case corresponding to the solid body swirl profile $M_\theta = 0.3r$ and the fourth case the swirling flow profile $M_\theta = 0.1r + 0.4$, both shown in Fig. 4b. In the last two cases the hub-to-tip ratio was $h = 0.6558$ and the axial flow profile was assumed to be that of Fig. 4a.

The coherence function was deduced from the acoustic pressure cross spectrum of Eq. (14) with an assumed mode amplitude distribution function versus α corresponding to incoherent point monopole sources (in uniform axial flow with no swirl) uniformly distributed over the duct cross section. This is given by Ref. [12]

$$|A_{mn}(\alpha_{mn})|^2 \propto \frac{1}{\alpha_{mn}^2} \frac{(1 - \alpha_{mn} M_x)^2}{(1 - M_x^2)^2}, \quad (25)$$

where $|A_{mn}^+(\alpha_{mn})|^2 = |A_{mn}(\alpha_{mn})|^2$ for $\alpha_{mn} > 0$ and $|A_{mn}^-(\alpha_{mn})|^2 = |A_{mn}(\alpha_{mn})|^2$ for $\alpha_{mn} < 0$.

In order to validate the new two-microphone formulation in terms of k , the mode amplitude distribution function must be known as a function of k . Substituting $k_{mn} = (\alpha_{mn} - M_x)/\beta^2$ for the case of uniform flow into Eq. (25) provides a theoretical mode distribution function in terms of k that we wish to recover from the coherence function using Eq. (23), of the form

$$|A_{mn}(k_{mn})|^2 \propto \frac{(1 - k_{mn} M_x)^2}{(M_x + k_{mn}(1 - M_x^2))^2}. \quad (26)$$

The mode amplitude distributions in terms of α and k were used in Eq. (24) and Eq. (23) respectively to deduce the complex coherence function at 100 frequency points between $\omega = 1$ to $\omega = 101$ in equal increments of $\Delta\omega = 1$. The coherence function was computed *separately* for upstream and downstream going modes for the two mode amplitude distribution functions of Eqs. (25) and (26). The microphone non-dimensional axial separation distance was chosen to be $\Delta x = 0.2$ to ensure that the coherence function decays sufficiently to zero and hence achieve convergence of the integrals in Eqs. (23) and (24). The coherence functions based on the distributions of α and k were then used in Eqs. (23) and (24) to deduce the mean square mode amplitude distribution as a function of α and k . The amplitude distribution functions obtained from this procedure are plotted in subsequent figures and compared against their theoretical distribution functions of Eqs. (25) and (26).

4.1. Axial flow

Fig. 9 shows the comparison of the mode amplitude distribution deduced from the α -based and k -based two-microphone methods for the purely axial flow profile measured in the bypass section of a scale-model rig (plotted in Fig. 4a) with their corresponding theoretical distributions of Eqs. (25) and (26) respectively.

Generally good agreement between the predicted and actual mode distribution functions is observed in both cases, with levels of error being similar in both the α and k -based methods. The greatest error (of more than 5 dB) is found to occur for the extreme values of α and k . The upstream and downstream modes are represented by horizontal arrows in both figures. Note the small region of overlap in k between about -0.5 and -0.45 , which represents both upstream and downstream going modes. Modes represented by their k values in this region are therefore non-unique. This phenomenon represents one of the disadvantages of the k -based two-microphone method. We show below the region of overlap becomes greater when swirl is present, as we saw with the modal density function in Section 2.4. However, this non-uniqueness phenomenon is only an issue when both upstream and downstream propagation of similar amplitudes are present simultaneously. In situations where it is required to resolve upstream and downstream propagating modes, for example in the case of strong reflections, knowledge of the axial wavenumber is ambiguous in the small overlap region. In these cases, the use of the cut-on ratio has been shown to provide an unambiguous differentiator of upstream and downstream propagating modes.

We now consider the second case of a purely axial flow, $M_x(r) = 0.25 + (r - h)$. A comparison of the predicted and actual mode amplitude distribution functions for this profile are shown in Fig. 10a and b for the α -based and k -based two-microphone

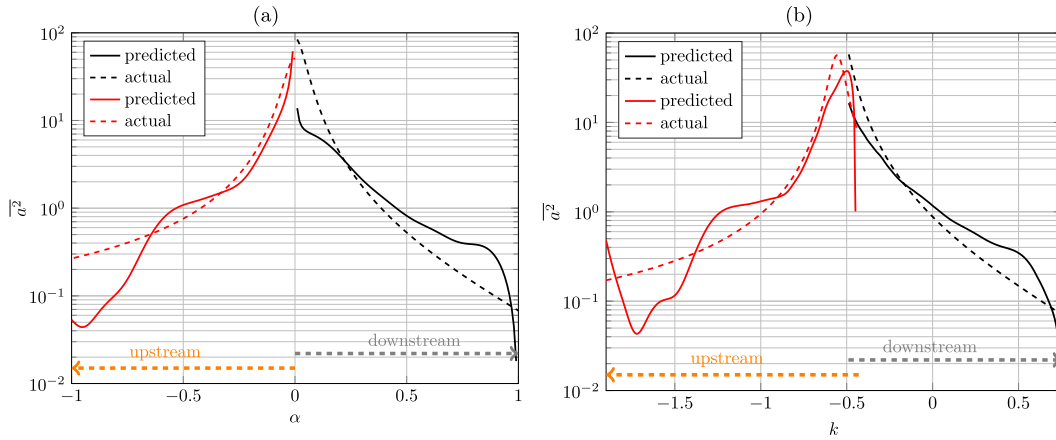


Fig. 9. Prediction results for $\overline{a^2}$ for the axial flow shown in Fig. 4a, from Tester and Murray [17]. (a): α -based method, (b): k -based method.

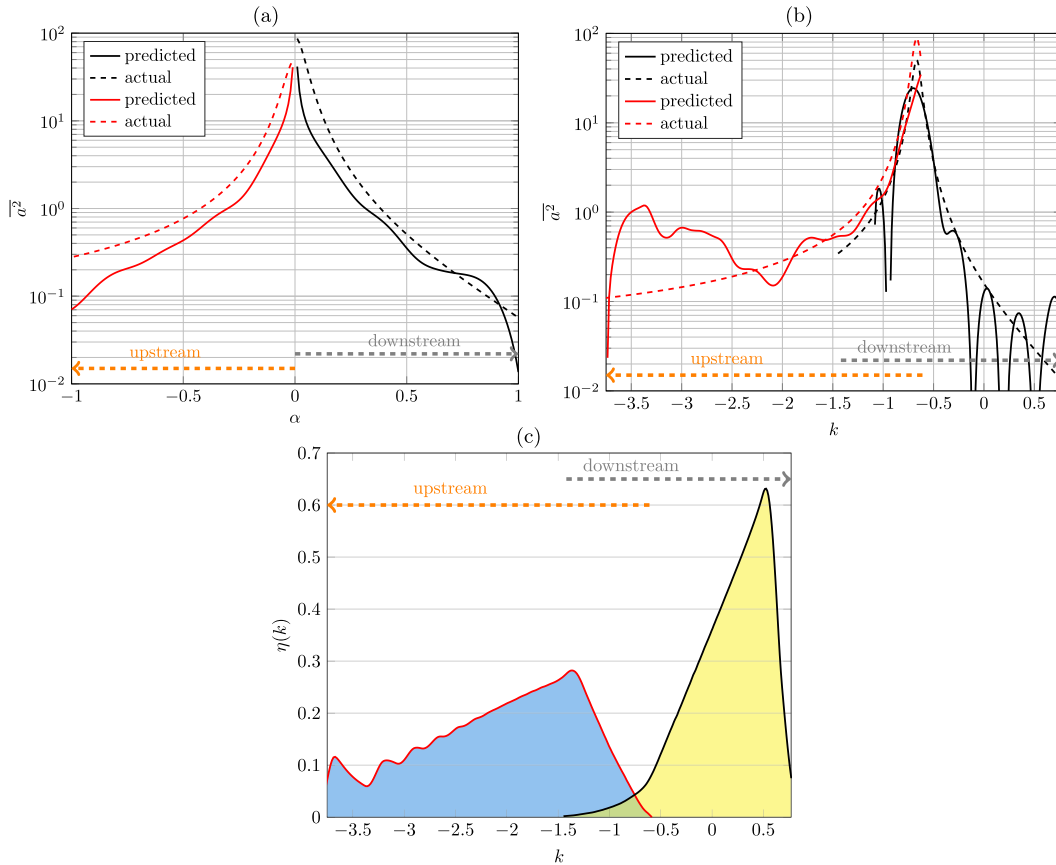


Fig. 10. Prediction results for $\overline{a^2}$ for the axial flow of $M_x(r) = 0.25 + (r-h)$. (a): α -based method, (b): k -based method. (c): mode density function $\eta(k)$.

methods respectively.

For this radial profile the k -based method provides consistently better agreement with the theoretical distribution, except at large negative k values, corresponding to well cut-on modes whose corresponding α values are close to -1 . The range of k for which upstream and downstream going modes overlap is also greater for this axial flow profile. The generally poor performance of the α -based method could have been predicted from the extent of deviation of $k(\alpha)$ from the uniform mean flow result of Eq. (2), as seen in Fig. 3c. For the previous realistic axial flow example, there was a much smaller deviation from Eq. (2), as seen in

Fig. 5b, which explains the better performance of the α -based method in that example.

One reason for the poor performance of the two-microphone method in this example at large negative k values is due to the poor estimate of the modal density function since there is a relative sparseness of modes in this k range, as shown in Fig. 10c.

The density function $\eta(k)$ exhibits non-physical oscillatory behaviour for values of $k \lesssim -2.5$ (with 13% of the total modes satisfying $k < -2.5$) corresponding to the range of k in Fig. 10b of poorest agreement with the theoretical distribution. To obtain a smoother, more accurate estimate for $\eta(k)$ in this example, the propagating modes from *all* frequencies in the range $1 \leq \omega \leq 101$ were used to compute the distribution plotted in Fig. 10c, but even this is not sufficiently smooth. This sparseness phenomenon is less of an issue for the α -based method, since the probability density function appears to follow $\eta(\alpha) = |\alpha|$ for all flow profiles.

4.2. Swirling flow

We now consider the effect of swirl on the α -based and k -based two-microphone methods. Fig. 11 shows a comparison of the predicted and actual mode amplitude distribution functions for the case in which the axial flow profile $M_x(r)$ corresponds to the measured data in Fig. 4a with a swirl component given by $M_\theta(r) = 0.3r$.

Both methods can be seen to provide satisfactory agreement with the actual distribution but with the k -based method providing marginally better agreement overall. In this case the overlap between upstream and downstream propagating modes is relatively small. Again, this level of agreement with the α -based method could have been anticipated from the generally good levels of agreement between the exact relationship $k(\alpha)$ and the uniform mean flow case, plotted in Fig. 6a.

Finally, we examine the effect of increasing the level of swirl. Fig. 12 shows a comparison of the mode amplitude distribution functions using the α and k -based methods when the swirl velocity profile is increased to $M_\theta(r) = 0.1r + 0.4$. The predicted mode amplitude distribution for the α -based method is generally over-estimated by more than 5 dB over the full range of

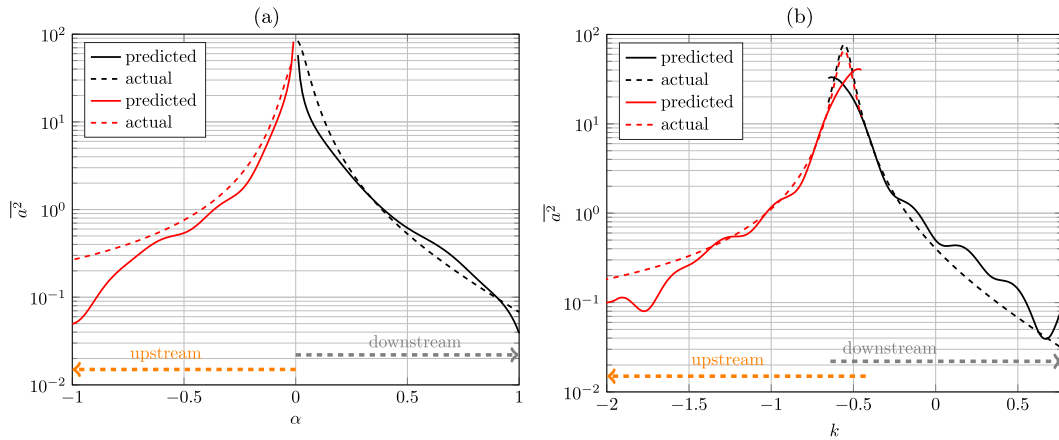


Fig. 11. Prediction results for $\overline{a^2}$ for the axial flow shown in Fig. 4a and solid body swirl of $M_\theta(r) = 0.3r$. (a): α -based method, (b): k -based method.

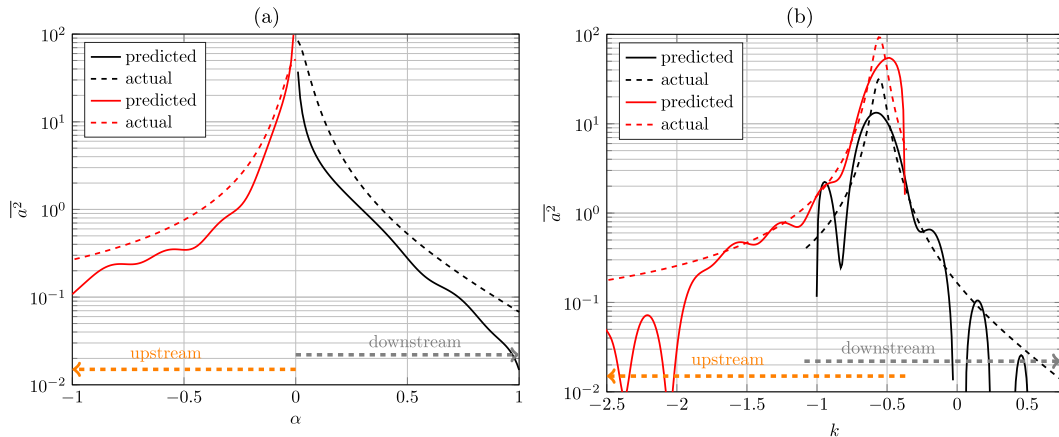


Fig. 12. Prediction results for $\overline{a^2}$ for the axial flow shown in Fig. 4a and swirl of $M_\theta(r) = 0.1r + 0.4$. (a): α -based method, (b): k -based method.

modes compared to the actual distribution. Generally good levels of agreement are established for the k -based method, except for large negative k values owing to the relatively poor estimate of $\eta(k)$ deduced in this example for the most cut-on modes, again stemming from the relative sparseness of these modes. Once again, the poor performance of the α -based method in this example is consistent with the generally large deviation of $k(\alpha)$ from the theoretical relationship in Eq. (2) assumed in the method, shown in Fig. 6c.

5. Conclusions

The concept of modal cut-on ratio has been widely used as a non-dimensional measure of the degree to which an acoustic mode propagating along a duct is cut-on. In general terms, it represents how far in frequency a single mode is excited above its cut-on frequency. In the idealised case of a uniform mean axial flow its definition and its relation to the modal wavenumber components is clear and unambiguous, and can be used to deduce modal transmission and radiation angles. Equally importantly, the modal cut-on ratio α can be used in place of the usual modal indices (m, n) to characterise modal propagation. However, the definition of cut-on ratio in the more realistic case in which the axial flow speed is radially varying, and which may also contain swirl, is not clear and is open to interpretation. This paper sought to clarify these issues.

In the case of a uniform axial mean flow, the definition of cut-on ratio arises naturally as the ratio of the frequency and transverse modal wavenumber (cf. Eq. (3)). This definition of cut-on ratio can in turn be expressed in terms of the excitation frequency relative to its cut-on frequency ω_{mn} , as in Eq. (4). In the more general case of arbitrary flow profile there is no simple relation between α and the modal wavenumber components. However, in this paper we choose, arbitrarily, the identical expression of cut-on ratio

$$\alpha_{mn} = \pm \sqrt{1 - \left(\frac{\omega_{mn}}{\omega} \right)^2}, \quad (27)$$

for arbitrary flow profiles, where ω_{mn} must be computed numerically. This definition has the advantage of being consistent for the uniform flow case, has the range $[-1, 1]$ for propagating modes, and unexpectedly appears to have the same probability density function $\eta(\alpha)$, irrespectively of flow profile. The reasons for this is currently unknown but provides some confidence in the choice of definition of α . However, this paper has shown that this definition leads to difficulties in its interpretation and application. We found that in general the relationship between axial wavenumber and cut-on ratio is significantly more complicated in swirling flow.

By way of illustrating the difficulty with defining a generalised cut-on ratio in an arbitrary flow profile, the accuracy of a new but previously studied measurement method (the two-microphone method) was investigated in this paper. The aim of the method was to express the mode amplitude distribution as a function of α from measurements of the coherence function between the acoustic pressures at two closely spaced microphones at the duct wall. Central to the validity of the measurement technique is the assumption that the relationship between k and α for a uniform axial mean flow is accurate in all flow profiles. The two-microphone method was applied to predictions of the coherence function for four flow profiles based on an assumed mode amplitude distribution function of α . Two of the profiles were purely radially varying axial flows while the other two involved different degrees of swirl. As expected, agreement between the recovered distributions and the exact distributions were poorest when the variation of k with α deviated furthest from the relationship for a uniform axial mean flow.

This difficulty was circumvented by simply re-formulating the two-microphone method directly in terms of axial wavenumber k without making any assumed dependence between k and α . This new formulation is therefore completely general and applies to any arbitrary flow profile. However, whilst we showed this new formulation allows for the good estimation of mode amplitude in any flow profile, it has the following disadvantages:

1. The interpretation of k , and its relationship to modal propagation angles is complicated for arbitrary profiles and must generally be determined numerically.
2. The modal density function $\eta(k)$ must be determined by numerical computation whereas for α it appears to closely follow Eq. (9) irrespective of flow profile, even in the presence of swirl.
3. Modal axial wavenumbers k are no longer unique for upstream and downstream going modes, with the size of the overlap region dependent on the flow profile. This is only an issue when upstream and downstream going modes of comparable amplitude are present simultaneously.

Throughout this paper, we have considered a wide range of flows and non-dimensional frequencies when considering the relationship between the axial wavenumber k and cut-on ratio α (from $\omega = 20$ to $\omega = 150$), and the two microphone method ($\omega = 1$ and $\omega = 101$). In typical applications, we would be interested in frequencies between 50 Hz and 10 kHz and engine radii between 0.5 m and 1.5 m, which corresponds to $0.5 \lesssim \omega \lesssim 280$. The conclusions in this paper about the relationship between k and α would hold for all of these frequencies, but calculating quantities such as $\eta(k)$ and $\eta(\alpha)$ for very low frequencies would be difficult due to the sparseness of modes at low frequencies. Additionally, the two-microphone method relies on a high frequency limit ($\omega \gtrsim 10$) in order to be able to write the mode amplitude function as a continuous variable.

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Appendix A. Calculating the eigenmodes in swirling flow

We now discuss how to calculate the eigenmodes k_{mn} and associated eigenfunction (or mode shape) $P_{mn}(r)$ for swirling, inviscid, homentropic flow in a duct. This is based upon the method in Posson and Peake [16] and Mathews and Peake [18], which is outlined below. A cylindrical coordinate system is used, with x the axial coordinate, r the radial coordinate and θ the azimuthal coordinate, with \underline{u} , \underline{v} and \underline{w} being the velocity components in the x , r and θ directions respectively.

We non-dimensionalised quantities as follows. Distances are non-dimensionalised by the outer tip of the duct R_t . Velocities are non-dimensionalised by the speed of sound at the outer tip, $c_0(R_t)$, while densities and pressures non-dimensionalised by the density and pressure at the outer tip. Frequencies are non-dimensionalised by $c_0(R_t)/R_t$.

Given a base flow of the form

$$(M_x(r), 0, M_\theta(r)), \quad (\text{A.1})$$

we calculate from the Euler equations and the gas thermodynamic relations that the base flow speed of sound is given by

$$c_0^2(r) = 1 + (\gamma - 1) \int_1^r \frac{M_\theta^2(s)}{s} ds, \quad (\text{A.2})$$

while the density is given by

$$\rho_0(r) = [c_0^2(r)]^{1/(\gamma-1)}, \quad (\text{A.3})$$

and finally the pressure is given by

$$p_0(r) = \frac{1}{\gamma} - \int_r^1 \frac{\rho_0(s)M_\theta^2(s)}{s} ds, \quad (\text{A.4})$$

where γ is the ratio of specific heat capacities ($\gamma = 1.4$) for air. We then Fourier transform the standard mass, energy and momentum equations using

$$\{u, v, w, p\}(r, x, \theta, t) = \int \sum_m \int \{U(r), V(r), W(r), P(r)\} e^{i\omega k x} dk e^{im\theta} e^{-i\omega t} d\omega. \quad (\text{A.5})$$

After rearranging, the eigenvalues satisfy

$$\frac{M_x \bar{\Lambda}}{c_0^2 \zeta} iU + \left[\frac{M_x}{c_0^2 \zeta} \frac{dM_x}{dr} - \frac{1}{r\zeta} - \frac{M_\theta^2}{\zeta r c_0^2} \right] V - \frac{1}{\zeta} \frac{dV}{dr} - \frac{m}{r\zeta} iW - \frac{i\bar{\Lambda}}{c_0^2 \rho_0 \zeta} P = k\omega iU, \quad (\text{A.6a})$$

$$-\frac{\bar{\Lambda}}{M_x} V - \frac{2M_\theta}{rM_x} iW + \frac{i}{\rho_0 M_x} \frac{dP}{dr} - \frac{iM_\theta^2}{\rho_0 M_x r c_0^2} P = k\omega V, \quad (\text{A.6b})$$

$$-\frac{1}{M_x} \left[\frac{M_\theta}{r} + \frac{dM_\theta}{dr} \right] V - \frac{\bar{\Lambda}}{M_x} iW - \frac{im}{r\rho_0 M_x} P = k\omega iW, \quad (\text{A.6c})$$

$$-\frac{\rho_0 \bar{\Lambda}}{\zeta} U + i\frac{\rho_0}{\zeta} \left[\frac{dM_x}{dr} - \left(1 + \frac{M_\theta^2}{c_0^2} \right) \frac{M_x}{r} \right] V - \frac{i\rho_0 M_x}{\zeta} \frac{dV}{dr} + \frac{m\rho_0 M_x}{r\zeta} W + \frac{M_x \bar{\Lambda}}{c_0^2 \zeta} P = k\omega P, \quad (\text{A.6d})$$

with the Myers boundary condition in hard walls:

$$V(h) = 0 \text{ and } V(1) = 0, \quad (\text{A.6e})$$

where

$$\bar{\Lambda} = \frac{mM_\theta}{r} - \omega \text{ and } \zeta = 1 - \frac{M_x^2}{c_0^2}, \quad (\text{A.7})$$

with $\bar{\Lambda}$ the reduced frequency and ζ^2 is local compressibility factor. We solve this eigenvalue problem using Chebfun [19] in MATLAB, which avoids having to discretise the derivatives. This allows the calculation of k_{mn} and $P_{mn}(r)$. Our numerical

eigenmode solver was validated against the results from the program in Posson and Peake [16]. We find that we get perfect agreement in all cases with Posson and Peake [16] for a duct with hard walls.

Any hydrodynamic modes or nearly-convected modes found by the solver are identified by comparing their wavenumber k to the wavenumbers of the critical layer and using the symmetry of the cut-on acoustic modes, and then are ignored for the purpose of this paper. More details about them can be found in Heaton and Peake [13] or Mathews and Peake [20].

Appendix B. Numerically calculating the cut-on frequency

The essential idea to calculate the cut-on frequency ω_{mn} is that we vary the frequency ω and solve the eigenvalue problem numerically for the eigenmodes k_{mn} until the n -th upstream and downstream modes coalesce and become cut-off. The precise frequency where this happens will be denoted ω_{mn}^* .

Given a fixed value of ω and an azimuthal number m , we can calculate all the eigenmodes k_{mn} by solving the eigenvalue problem in Eq. (A.6). Let k_{mn}^* denote the cut-on eigenmodes. Assume that n ranges from 1 to N . Let \mathcal{N} denote the number of cut-on modes, so $\mathcal{N}(\omega) = N$.

We illustrate the procedure when $\omega = 12$, $m = 0$, $M_x = 0.5$ and $M_\theta = 0$, for which there are three cut-on modes (so $N = 3$).

- **Make an initial guess.** We first try and find frequencies $\omega^j < \omega$ where we have 1, 2, ..., N cut-on eigenmodes. For example, we could try guessing $\omega^j = j\omega/N$ has j cut-on modes.
We calculate that $\omega^1 = 4$, $\omega^2 = 8$, $\omega^3 = 12$ and that $\mathcal{N}(\omega^1) = 1$, $\mathcal{N}(\omega^2) = 2$ and $\mathcal{N}(\omega^3) = 3$.
- **Refine guess.** Suppose we find that frequencies ω^j and ω^{j+1} have the same number of cut-on modes j , but ω^{j+2} has $j+2$ cut-on modes. We refine the guess by letting $\omega^{j+1} \leftarrow (\omega^{j+1} + \omega^{j+2})/2$ and hoping that for the new value of ω^{j+1} , $\mathcal{N}(\omega^{j+1}) = j+1$. We carry on a similar procedure until we have N different frequencies ω^j , where $\mathcal{N}(\omega^j) = j$ for $j = 1, \dots, N$.
Our initial guess had $\mathcal{N}(\omega^j) = j$ for $j = 1, \dots, N$ so this is not required.
- **Bounded regions.** Let $\omega^0 = 0$. We have now deduced a range for the cut-on frequency for each index. For $1 \leq n \leq N$ we have that $\omega^{n-1} < \omega_{mn} < \omega^n$.
- **Introduce distance function.** For a given ω , introduce the distance function $d(\omega) = |\min(k_{mn,\text{down}}^*) - \max(k_{mn,\text{up}}^*)|$, which is the distance between the closest upstream and downstream mode.
For example, we find that $d(\omega^1) = 10.6667$, $d(\omega^2) = 15.3989$ and $d(\omega^3) = 13.1893$.
- **Find zeros of the distance function.** For the cut-on frequencies, we have $d(\omega_{mn}) = 0$. In the range $\omega^{n-1} < \omega_{mn} < \omega^n$ we have precisely one zero, due to our definition of ω^n . We use a numerical solver (eg Newton-Raphson) to solve $d(\omega_{mn}) < \epsilon$ to a tolerance of ϵ , which takes $f(n, \epsilon)$ iterations to converge.
We find that the three cut-on frequencies are $\omega_{0,1} = 0$, $\omega_{0,2} = 5.5372$ and $\omega_{0,3} = 10.9346$.

Since we have to solve the eigenvalue problem at least N times to get the initial guesses ω^j , and then $\sum_{j=1}^N f(j, \epsilon)$ to find the cut-on frequencies, we can see that we have to solve the eigenvalue problem a significant amount of times. Thus, the method to find the cut-on frequency and hence the cut-on ratio from Eq. (4) will be very expensive.

One way to speed up the method would be to find the eigenmodes faster, which might be possible by reducing the required accuracy. Alternatively, we could try and investigate whether there is a method which can determine whether a matrix has repeated eigenvalues without solving for them. To the authors knowledge, there is no method for doing this at present.

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