

ST227 Symbols (forked from DenysMelnyk6/ST227table)

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Note: need to change descriptions and equations to use set notation.

ST227 Definitions

| Name | Symbol | Equation | Description |
|--|-----------------------|--|--|
| State Space | S | — | Possible values taken by the Markov chain. |
| Transition matrix | P | — | A matrix containing the probabilities of going between state spaces, rows being "old" and columns being "new" spaces, all 1-step. |
| Transition probability | P_{ij}^n | $\mathbb{P}(X_n = j \mid X_0 = i)$ $= \mathbb{P}_i(X_n = j)$ | A probability of Markov Chain going from state i to state j in n -steps. |
| Initial distribution | λ | — | A vector containing the distribution of the first state of the chain. |
| Initial probability of state i | λ_i | $\mathbb{P}(X_0 = i)$ | i^{th} entry of λ , probability of state i being the first state of the Markov's chain. |
| Period of a state | d_i | $\gcd\{n \in \mathbb{N} \mid (P^n)_{ii} > 0\}$ | Greatest Common divisor of all loops leading from state i to i . |
| First hitting time | H_j/H_A | $\min\{n \in \mathbb{N}_0 \mid X_n = j\}$ | Number of steps until state j is hit. Is 0 if the start point is state j or the set is \emptyset . (Similarly for set A) |
| Hitting probability | h_{ij}/h_{iA} | $\sum_{n=1}^{\infty} \mathbb{P}_i(H_A = n)$ | Probability of reaching state j from state i . (Similarly for set A) |
| Expected hitting time | η_{ij}/η_{iA} | $\mathbb{E}_i[H_A]$ $= \sum_{n=1}^{\infty} n \mathbb{P}_i(H_A = n)$ | Expected number of steps until state j is reached from state i . (Similarly for set A) |
| First return time | T_i | $\min\{n \in \mathbb{N} \mid X_n = i\}$ | Number of steps until state i loops on itself. |
| Return probability | f_i | $\mathbb{P}_i(T_i < \infty)$ $= \sum_{j \in S} P_{ij} h_{ji}$ | h_{ii} , probability of chain returning back to state i , from i . |

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| Name | Symbol | Equation | Description |
|--|---------------|---|---|
| Expected return time | m_i | $\mathbb{E}_i[T_i]$ | η_{ii} , expected number of steps until state i loops on itself. |
| Number of visits | V_j/V_A | $\sum_{n=0}^{\infty} \mathbb{1}_{\{X_n=i\}}$ | Number of visits to state j /set A . |
| Expected number of visits | γ_j^i | $\mathbb{E}_i \left[\sum_{n=0}^{T_j-1} \mathbb{1}_{\{X_n = j\}} \right]$ | Expected number of visits to state j before chain returns to state i |
| Set of transient states | \mathcal{T} | — | Subset of S , containing all transient states. |
| Invariant measure | μ | — | A vector of positive entries, describing the measure, or "weight" of each state at every step of the chain. Has a property of $\mu P = \mu$. |
| Invariant distribution | π | — | A special case of invariant measure, distribution describing the distribution of the chain at every step of the chain, has a property of $\pi P = \pi$ and $\sum_{i \in S} \pi_i = 1$. Not every chain has a π . |
| Long-term transition matrix | Π | $\lim_{n \rightarrow \infty} P^n$ | All rows are equal to π . Describes the behaviour of the chain after arbitrarily many steps. Not applicable to every Markov Chain. |
| Graph | $G = (V, E)$ | — | Graph G , where V is a set of vertices and $E \subset S \times S$, set of all edges. All graphs in this module are connected and weighted. |

Note: A trick to memorize the Expected hitting time η is that it looks like a deformed "h".
Similarly for the Expected number of visits γ with "v".