

Lab5 实验报告

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Here's the check5 test results.

— Experimental Results

```
Total Test time (real) = 7.90 sec
Built target check5
(base) kenaz@Kenaz:~/minnow$ cmake --build build --target check5
Test project /home/kenaz/minnow/build
  Start 1: compile with bug-checkers
1/2 Test #1: compile with bug-checkers ..... Passed 0.29 sec
  Start 35: net_interface
2/2 Test #35: net_interface ..... Passed 0.03 sec

100% tests passed, 0 tests failed out of 2

Total Test time (real) = 0.33 sec
Built target check5
(base) kenaz@Kenaz:~/minnow$
```

图 1: passing lab5 tests

二 Implementation

I used `cur_time` to record the current time, and used `arp_life_` to record the lifetime of the sent arp message. When the lifetime of the arp table is exceeded, the arp table will be deleted. The `wait_queue_` is used to store the frames that are waiting for the arp table to be updated. When the arp table is updated, the frames in the `wait_queue_` will be sent out.

```
private:
    // Datagrams that have been received
    std::queue<InternetDatagram> datagrams_received_ {};
```

```

// map:生命周期, multimap: 地址映射
std::unordered_map<uint32_t, std::pair<uint32_t, EthernetAddress>> arp_table_
{};
std::unordered_map<uint32_t, std::pair<uint32_t, EthernetFrame>> arp_life_ {};
std::multimap<uint32_t, EthernetFrame> wait_queue_ {};
uint32_t cur_time { 0 };

```

Here is the Implementation of the send_message function.

```

void NetworkInterface::send_datagram( const InternetDatagram& dgram, const
    Address& next_hop )
{
    EthernetFrame ethernetframe;
    ethernetframe.header.src = ethernet_address_;
    if ( !arp_table_.contains( next_hop.ipv4_numeric() ) ) {
        if ( arp_life_.contains( next_hop.ipv4_numeric() ) ) {
            return; // 发送还在lifetime内的ARP请求
        }
        ethernetframe.header.type = EthernetHeader::TYPE_ARP;
        ethernetframe.header.dst = ETHERNET_BROADCAST;
        ARPMessage arpmessage;
        arpmessage.opcode = ARPMessage::OPCODE_REQUEST;
        arpmessage.sender_ethernet_address = ethernet_address_;
        arpmessage.sender_ip_address = ip_address_.ipv4_numeric();
        arpmessage.target_ip_address = next_hop.ipv4_numeric();
        ethernetframe.payload = serialize( arpmessage );
        arp_life_.emplace( arpmessage.target_ip_address, make_pair( cur_time,
            ethernetframe ) );
        EthernetFrame waitframe{
            .header = {
                .dst = ETHERNET_BROADCAST,
                .src = ethernet_address_,
                .type = EthernetHeader::TYPE_IPv4,
            },
            .payload = serialize(dgram),
        };
        wait_queue_.emplace( next_hop.ipv4_numeric(), waitframe );
        // datagrams_received_.emplace(dgram);
        transmit( ethernetframe );
        return;
    }
    ethernetframe.header.type = EthernetHeader::TYPE_IPv4;
    ethernetframe.header.dst = arp_table_[next_hop.ipv4_numeric()].second;
    ethernetframe.payload = serialize( dgram );
    transmit( ethernetframe );
}

```

In the `frame__recv` function,when receiving arp message,I need to update the arp table and try to send the corresponding frames in the `wait_queue`.(Implementation omitted here)

≡ Challenge