

Mathematics 227

Linear combinations

As always, Sage cells are available at <http://gvsu.edu/s/0Ng>.

In general, given a set of vectors $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$ and weights c_1, c_2, \dots, c_n , we form the linear combination

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_n\mathbf{v}_n.$$

1. Given the vectors

$$\mathbf{v}_1 = \begin{bmatrix} 4 \\ 0 \\ 2 \\ 1 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} 1 \\ -3 \\ 3 \\ 1 \end{bmatrix}, \mathbf{v}_3 = \begin{bmatrix} -2 \\ 1 \\ 1 \\ 0 \end{bmatrix}, \mathbf{b} = \begin{bmatrix} 0 \\ 1 \\ 2 \\ -2 \end{bmatrix},$$

we can ask if \mathbf{b} can be expressed as a linear combination of \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 . Rephrase this question by writing a linear system for the weights c_1 , c_2 , and c_3 . Then solve this linear system to determine whether \mathbf{b} can be written as a linear combination of \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 .

2. Consider the following linear system.

$$3x_1 + 2x_2 - x_3 = 4$$

$$x_1 + 2x_3 = 0$$

$$-x_1 - x_2 + 3x_3 = 1$$

Identify vectors \mathbf{v}_1 , \mathbf{v}_2 , \mathbf{v}_3 , and \mathbf{b} and rephrase the question "Is this linear system consistent?" by asking "Can \mathbf{b} be expressed as a linear combination of \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 ?"

3. Consider the vectors

$$\mathbf{v}_1 = \begin{bmatrix} 0 \\ -2 \\ 1 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, \mathbf{v}_3 = \begin{bmatrix} 2 \\ 0 \\ -1 \end{bmatrix}, \mathbf{b} = \begin{bmatrix} -1 \\ 3 \\ -1 \end{bmatrix}.$$

Can \mathbf{b} be expressed as a linear combination of \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 ? If so, can \mathbf{b} be written as a linear combination of these vectors in more than one way?

4. Considering the vectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 from the previous part, can we write every three-dimensional vector \mathbf{b} as a linear combination of these vectors? Explain how the pivot positions of the matrix $\begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 & \mathbf{v}_3 \end{bmatrix}$ help answer this question.

5. Now consider the vectors

$$\mathbf{v}_1 = \begin{bmatrix} 0 \\ -2 \\ 1 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, \mathbf{v}_3 = \begin{bmatrix} 1 \\ -1 \\ -2 \end{bmatrix}, \mathbf{b} = \begin{bmatrix} 0 \\ 8 \\ -4 \end{bmatrix}.$$

Can \mathbf{b} be expressed as a linear combination of \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 ? If so, can \mathbf{b} be written as a linear combination of these vectors in more than one way?

6. Considering the vectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 from the previous part, can we write every three-dimensional vector \mathbf{b} as a linear combination of these vectors? Explain how the pivot positions of the matrix $\begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 & \mathbf{v}_3 \end{bmatrix}$ help answer this question.