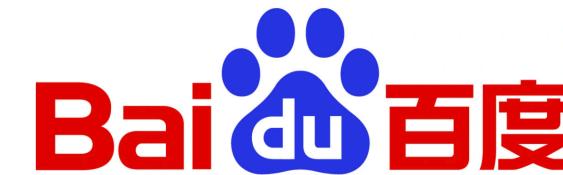


The 1st Solution for AutoNUE21 Challenge Semantic Segmentation Track

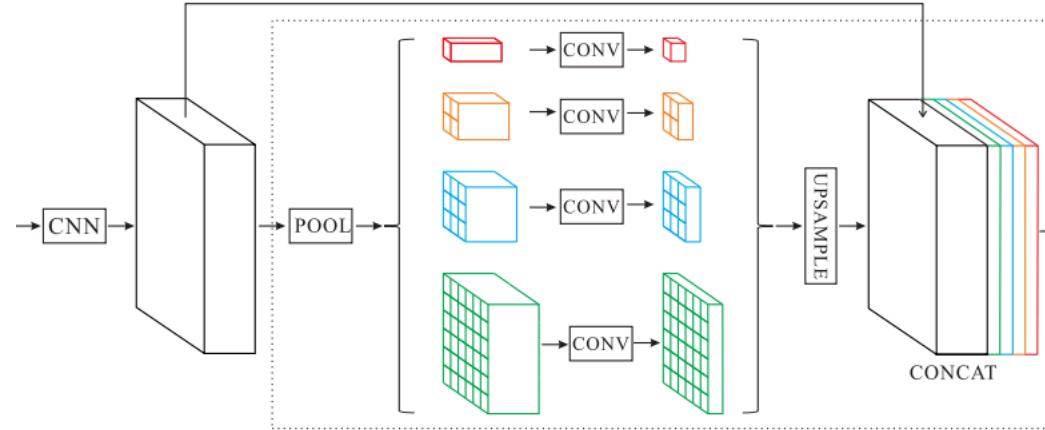
Liulei Li, Tianfei Zhou, Yi Liu, Lu Yang, Zeyu Chen, Wenguan Wang



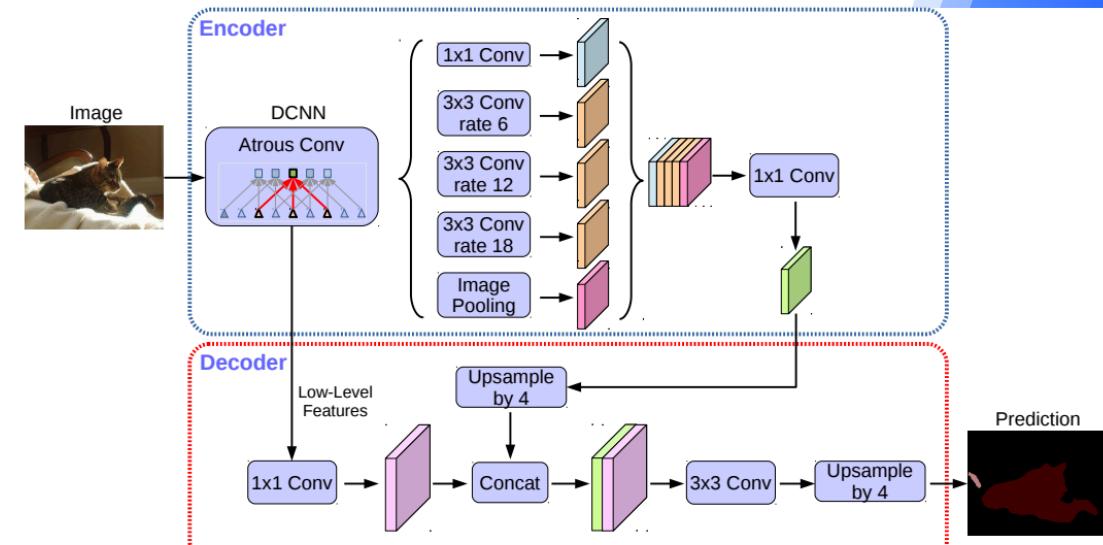
Preliminary

飞桨

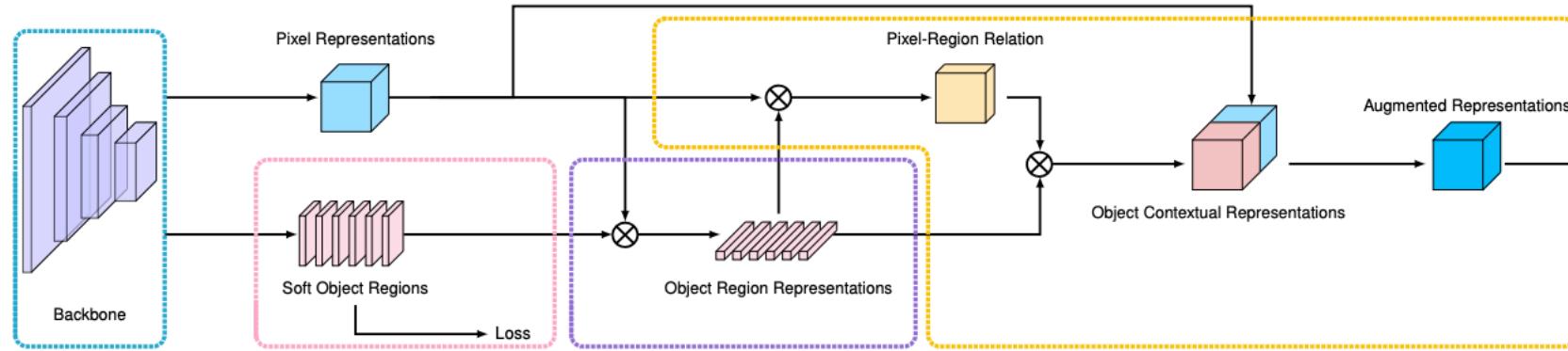
Encoder-Decoder Based CNNs for Semantic Segmentation



a) PSPNet¹



b) DeepLabV3²



c) OCRNet³

1. Zhao H, Shi J, Qi X, et al. Pyramid scene parsing network[C]//Proceedings of the IEEE conference on computer vision and pattern recognition. 2017: 2881-2890.

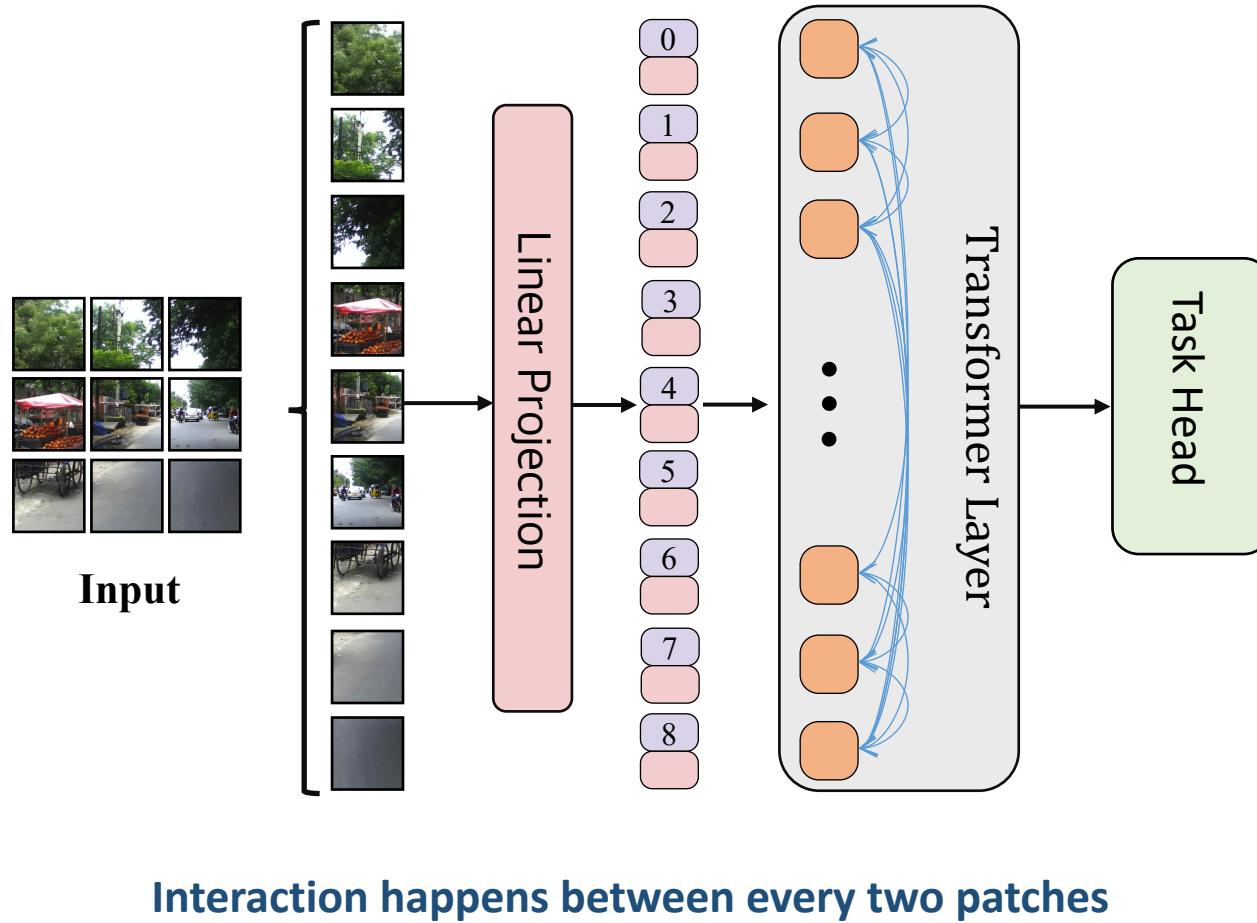
2. Chen L C, Zhu Y, Papandreou G, et al. Encoder-decoder with atrous separable convolution for semantic image segmentation[C]//Proceedings of the European conference on computer vision (ECCV). 2018: 801-818.

3. Yuan Y, Chen X, Wang J. Object-contextual representations for semantic segmentation[J]. arXiv preprint arXiv:1909.11065, 2019.

Motivation

飞桨

Vision Transformer¹

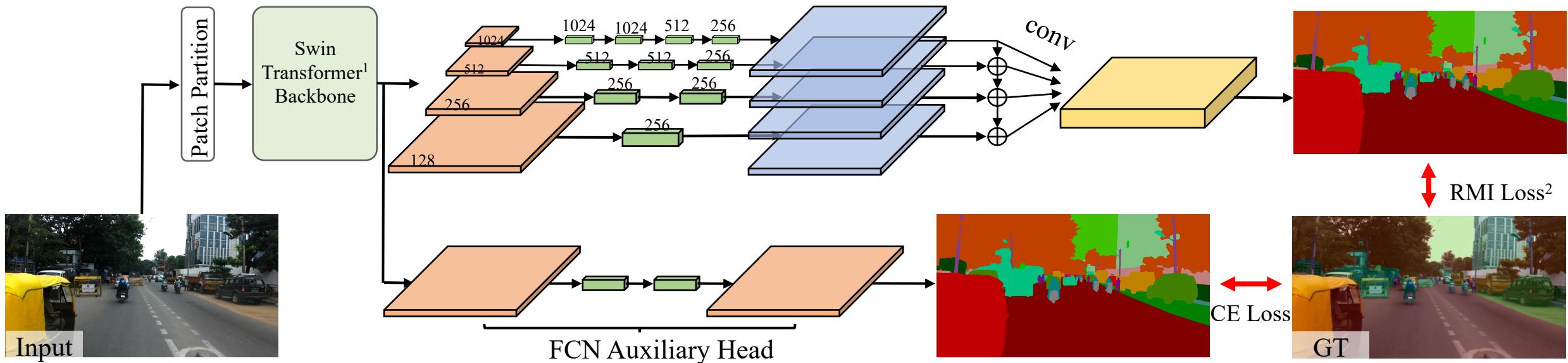


1. Dosovitskiy A, Beyer L, Kolesnikov A, et al. An image is worth 16x16 words: Transformers for image recognition at scale[J]. arXiv preprint arXiv:2010.11929, 2020.

Approach

飞桨

Transformer-based Semantic Segmentation



1. Liu Z, Lin Y, Cao Y, et al. Swin transformer: Hierarchical vision transformer using shifted windows[J]. arXiv preprint arXiv:2103.14030, 2021.

2. Zhao S, Wang Y, Yang Z, et al. Region mutual information loss for semantic segmentation[J]. arXiv preprint arXiv:1910.12037, 2019.

Approach

Regional Progressive Segmentation

飞桨

Densely Laid Objects



Images from the IDD Segmentation dataset

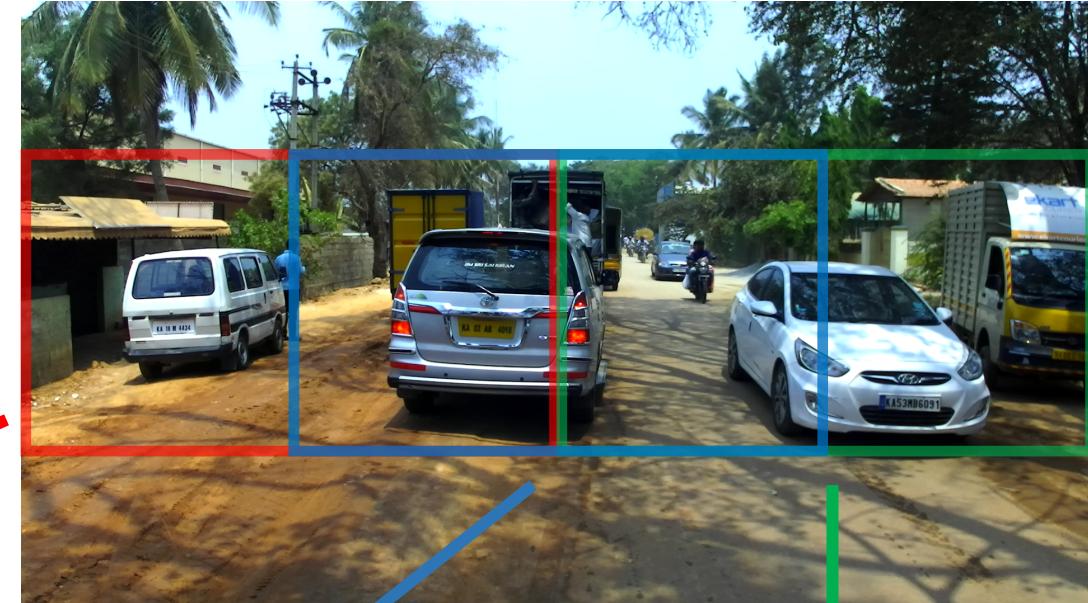


Exemplar samples of CoCo-Stuff dataset

Approach

飞桨

Regional Progressive Segmentation

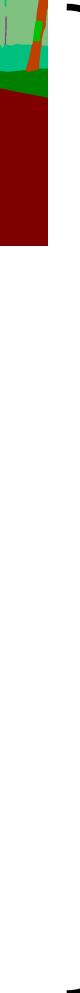
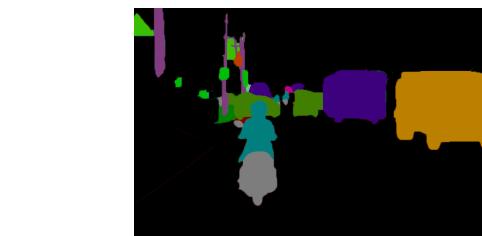
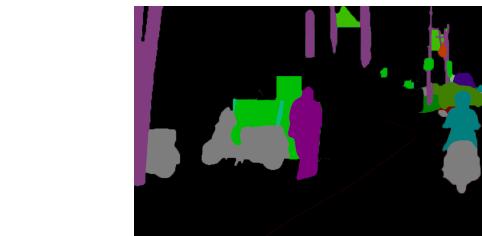
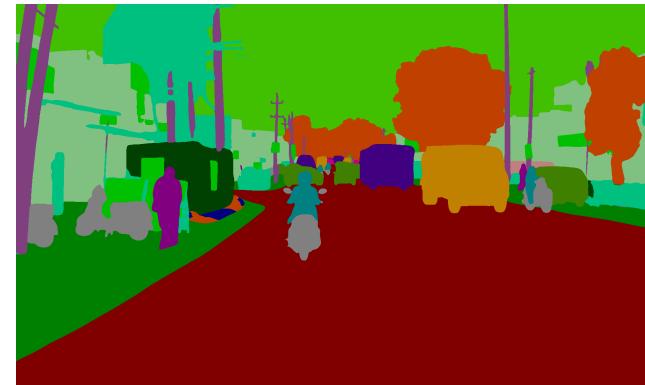


Approach

Regional Progressive Segmentation

Thing: person, animal, rider, motorcycle, bicycle, auto rickshaw, car, truck, bus, caravan, trailer, vehicle fallback, billboard, traffic sign, traffic light, pole, pole group.

Stuff: road, parking, drivable fallback, sidewalk, non-drivable fallback, rail track, curb, wall, fence, guard rail, building, bridge, tunnel, vegetation, sky, fallback background.



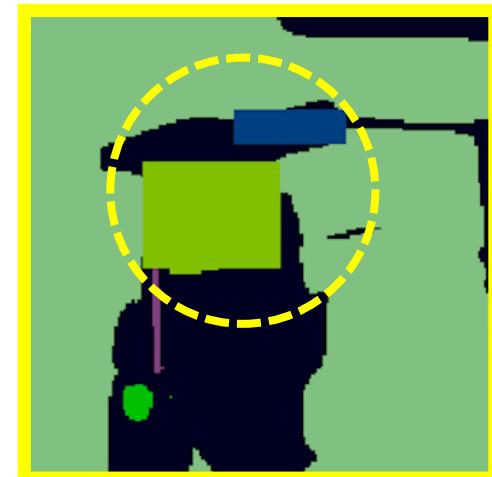
Approach

飞桨

Pseudo-labeling



Bounding-Box annotation of IDD
Detection Dataset



Experiments

<https://github.com/PaddlePaddle/PaddleSeg>

Model	Method	mIoU (%)
Swin Transformer	UperNet	75.73
	Multi-Scale feature Aggre.	76.78(+1.05)
	MSD + pseudo-labeling	77.32(+0.54)
OCRNet	baseline	76.12
	Regional Progressive Seg	76.69(+0.57)
	RPS + pseudo-labeling	77.08(+0.39)
Ensemble	Swin + OCRNet	78.28 (+2.16)

Table 1: Ablation studies on each component of our method. All of them are evaluated on the IDD Segmentation validation set.

Results

Team/Uploader Name	Method Name	mIoU, L3	mIoU, L2	mIoU, L1
PaddleSeg	PaddleSeg	0.7862	0.8046	0.9099
Anonymous	Anonymous	0.7845	0.8028	0.9081
Anonymous	Anonymous	0.7839	0.8022	0.9077
Anonymous	Anonymous	0.7748	0.7954	0.9022
Prabahkar	HR	0.769	0.7929	0.9044
Александр	SENet	0.767	0.7914	0.9035
Tsubasa	infomer_40	0.7655	0.7904	0.9022
OCRNet	final ocr	0.7649	0.7887	0.9006
lovasz loss	Lovasz	0.7637	0.7857	0.899
SKK.AL	HRNet	0.7621	0.786	0.898

Table 2: Final leaderboard of Semantic Segmentation Track.

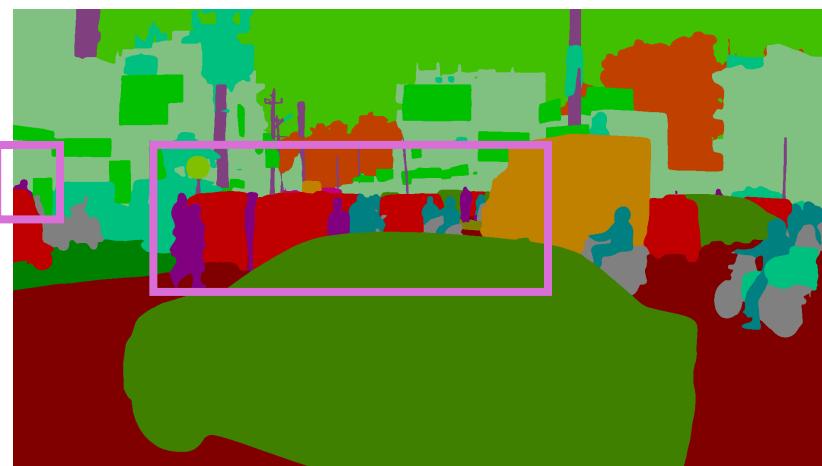
Qualitative Results

飞桨

Prediction



Prediction + Image



Qualitative Results

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Prediction



Prediction + Image



Thanks for your attention !



<https://github.com/PaddlePaddle/PaddleSeg>