

terminal - bucher@debian: ~
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bucher@debian:~\$ pysimCoder

Library

File

AR2INO

common

Communication

input

linear

math

nonlin

NuttX

NuttX Sensors

output

K
Gain

G(s)
LTI_continous

G(z)
LTI_discrete

Plot

RT Plot

Step

untitled

Library File Edit Simulation Settings Communication

/home/bucher

Ready