

# Charles Sun

✉ Email: charlesjsun@berkeley.edu | ☎ Phone: 925.998.1189

🌐 Website: charlesjsun.github.io | 📄 Github: charlesjsun | 🔗 LinkedIn: charlesjsun

## EDUCATION

### UNIVERSITY OF CALIFORNIA, BERKELEY

B.A., COMPUTER SCIENCE

Aug 2018 - May 2022

Berkeley, CA

GPA: 4.00

## COURSEWORK

\* denotes in progress, Fall 2020

### GRADUATE

Deep Reinforcement Learning\*

### UNDERGRADUATE

Machine Learning

Probability & Random Processes

Convex Optimization\*

Algorithms

Computer Security

Discrete Math and Probability

Computer Architecture

Data Structures

## SKILLS

### LANGUAGES

Python

C++

Java

C

### FRAMEWORKS

TensorFlow

PyTorch

NumPy

PyBullet

### TECHNOLOGY

Arduino

ROS

Linux

LaTeX

Git

Blender

CAD

## RESEARCH

### ROBOTIC AI & LEARNING LAB (RAIL) | UNDERGRADUATE RESEARCHER

February 2020 - Present | Berkeley, CA

- Advised by **Coline Devin**, **Glen Berseth**, and **Sergey Levine**.
- Interested in reinforcement learning, robotics, game playing, deep learning, and artificial intelligence, particularly in sample-efficient learning in vision-based settings for robotic systems.

*"Reset-Free Autonomous Practicing of Mobile Manipulation Skills"*

- We investigate how mobile manipulation platforms can use mobility as a tool to set up a variety of practice problems for manipulation, enabling robust learning.
- Current work with **Coline Devin**, **Glen Berseth**, **Ahishhek Gupta**, and **Sergey Levine**.

## EXPERIENCE

### SKYCURRENT | SOFTWARE ENGINEERING INTERN

June 2019 - August 2019 | Oakland, CA

- Worked on software team developing window cleaning robots for skyscrapers.
- Led design and development of software control system for manual and automated operations, reducing window cleaning time from 2 months to 1 day.
- Developed interface with touchscreen, sensors, and motors with hardware team.
- Refactored existing codebase for modularity and readability, speeding up workflow.

### ROBOTICS AT BERKELEY PROJECT TEAM | LEAD SYSTEMS ENGINEER

June 2019 - August 2019 | Oakland, CA

- Led team with creation of cubic "rolling" robot.
- Designed the software and electrical system of the rolling mechanic using a flywheel.

## TEACHING

### UC BERKELEY EECS | TEACHING ASSISTANT

CS 170 EFFICIENT ALGORITHMS AND INTRACTABLE PROBLEMS

August 2020 - Present | Berkeley, CA

- Creating high-quality class videos for online learning and holding weekly remote office hours to help students with concepts and homework.

CS 61A THE STRUCTURE AND INTERPRETATION OF COMPUTER PROGRAMS

August 2019 - May 2020 | Berkeley, CA

- Lead weekly lab and discussion section of 30 students and held weekly office hours to help students with concepts, homework, and labs.

## PROJECTS

### FUNDAMENTAL DEEP RL LIBRARY 📄

August 2019 - February 2020

- PyTorch implementations of fundamental deep reinforcement learning algorithms including Q-Learning, Policy Gradient, GAE, PPO, DDPG, and TD3.

### VOXEL GAME 📄

March 2017 - April 2018

- Video game with procedurally generated infinite world consisting of cubes, developed in UE4 and C++.