# Charles Sun

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### **EDUCATION**

# UNIVERSITY OF CALIFORNIA, BERKELEY

B.A., COMPUTER SCIENCE Aug 2018 - May 2022 Berkeley, CA GPA: 4.00

### **COURSEWORK**

#### **GRADUATE**

Deep Reinforcement Learning Natural Language Processing

#### **UNDERGRADUATE**

Machine Learning
Probability & Random Processes
Convex Optimization
Algorithms
Computer Security
Computer Graphics
Discrete Math and Probability
Computer Architecture
Data Structures

### **SKILLS**

#### **LANGUAGES**

Python C++ Java C

#### **FRAMEWORKS**

TensorFlow PyTorch TensorRT NumPy PyBullet

#### **TECHNOLOGY**

Arduino ROS

Docker

Linux

LaTeX

Git

Blender

Unity

**Unreal Engine** 

CAD

#### EXPERIENCE

#### **AEVA** | SOFTWARE ENGINEERING INTERN

May 2021 - August 2021 | Mountain View, CA

- Worked on the perception team at a company developing 4D FMCW LiDAR.
- Researched SotA point cloud semantic segmentation algorithms and wrote documentation for production engineers to use.
- Implemented GPU accelerated inference pipeline using C++, CUDA, and TensorRT, optimized for inference speed which is used in production.
- Wrote evaluation pipeline on proprietary LiDAR point-cloud dataset used by R&D team to speed up iterations.

# **BERKELEY AI RESEARCH LAB (BAIR)** | UNDERGRADUATE RESEARCHER February 2020 - Present | Berkeley, CA

- Supervised by Professor Sergey Levine.
- Working on state-of-the-art research on reinforcement learning, sequence modeling, robotics, and machine learning.
- Currently researching how to extend sequence modeling with transformer models (GPT) into model-based planning for RL.
- Developed ReLMM, a mobile manipulation system that can learn continuously on a real-world platform without any environment instrumentation, with minimal human intervention, and without access to privileged information, such as maps, objects positions, or a global view of the environment.

#### **UC BERKELEY** | TEACHING ASSISTANT

August 2019 - May 2021 | Berkeley, CA

- TA for EECS 126 Probability & Random Processes (Spring 2021).
- Responsible for leading weekly office hours, creating weekly discussion worksheets, and answering student questions on Piazza.
- Previously TA for CS 170 Efficient Algorithms (Fall 2020) and CS 61A Structure and Interpretation of Computer Programs (Fall 2019, Spring 2020).

#### **SKYCURRENT** | Software Engineering Intern

June 2019 - August 2019 | Oakland, CA

- Worked for a startup building skyscraper window cleaning robots.
- Designed and developed the software infrastructure of the main control system.
- Collaborated directly with the mechanical and electrical team to develop interface between software and hardware.
- Refactored existing codebase for modularity and readability, speeding up workflow.
- Reduced robot automated window cleaning time from ~2 months to ~1 day.

## **ROBOTICS AT BERKELEY PROJECT TEAM** | LEAD SYSTEMS ENGINEER February 2019 - June 2019 | Berkeley, CA

- Led team of students in the creation of a cubic rolling-by-flipping robot.
- Designed and built the electrical system of the flipping mechanic using a flywheel.
- Implemented software control using Arduino to enable robot movement.

#### **PUBLICATIONS**

• Charles Sun\*, Jędrzej Orbik\*, Coline Devin, Brian Yang, Ahbishek Gupta, Glen Berseth, Sergey Levine. "Fully Autonomous Real-World Reinforcement Learning for Mobile Manipulation" arXiv preprint, 2021.