

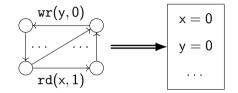
SCooL / GandALF 2024 in Reykjavik

Stephan Spengler
Uppsala University, Sweden

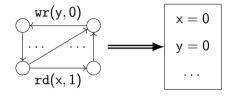


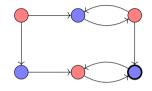




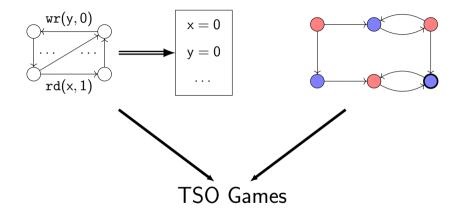








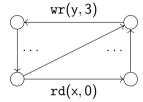






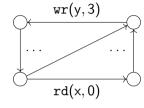


Proc¹:

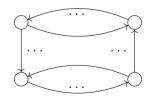




Proc¹:

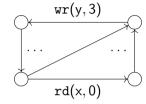


Proc²:

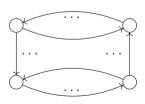




Proc¹:



Proc²:

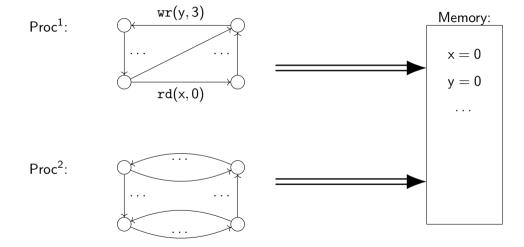


Memory:

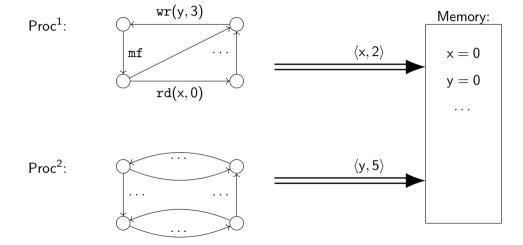
x = 0y = 0

. . .

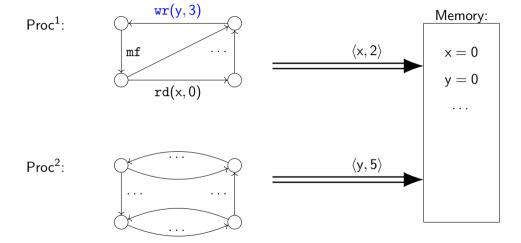




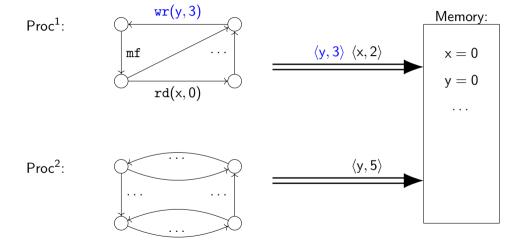




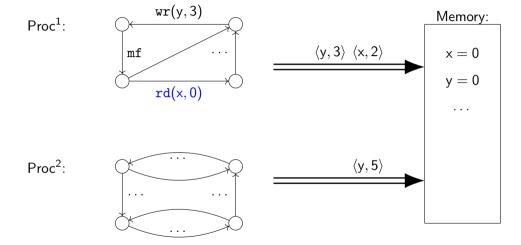




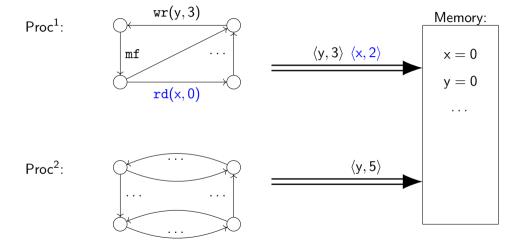




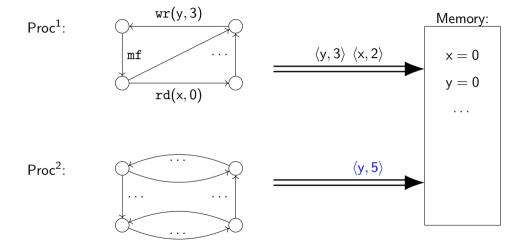




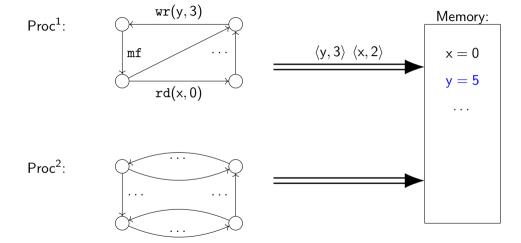












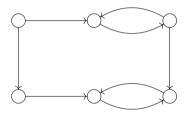




players A and B

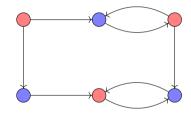


- ▶ players A and B
- configurations C
- ightharpoonup transition relation \rightarrow





- ▶ players A and B
- ightharpoonup configurations $C = C_A \cup C_B$
- ightharpoonup transition relation ightarrow
 - $\blacktriangleright \ \ \longrightarrow \ \subseteq (\mathsf{C}_A \times \mathsf{C}_B) \cup (\mathsf{C}_B \times \mathsf{C}_A)$

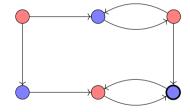




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$$\blacktriangleright \ \ \longrightarrow \ \subseteq (\mathsf{C}_A \times \mathsf{C}_B) \cup (\mathsf{C}_B \times \mathsf{C}_A)$$

▶ final configuration $c_F \in C$

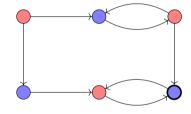




- players A and B
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- ► transition relation →

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- ▶ final configuration $c_F \in C$
- reachability game:
 - ► A tries to reach C_F
 - ightharpoonup B tries to avoid C_F

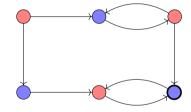




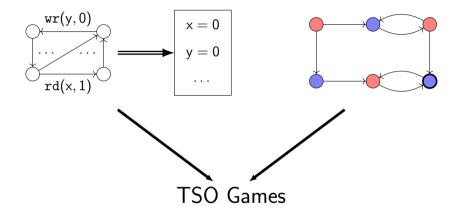
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- reachability game:
 - ► A tries to reach C_F
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- ► safety game: reversed roles











TSO (configuration graph): $c_1 \xrightarrow{instr} c_2 \xrightarrow{up^*} c_3$



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TSO Game: $c_1 \longrightarrow c_2 \longrightarrow c_3$



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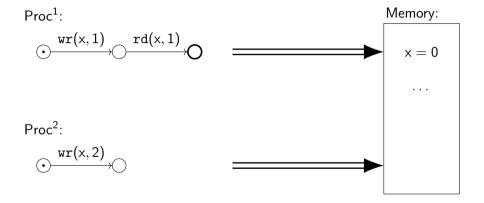


TSO (configuration graph): $c_1 \xrightarrow{instr} c_2 \xrightarrow{up^*} c_3$ up^0

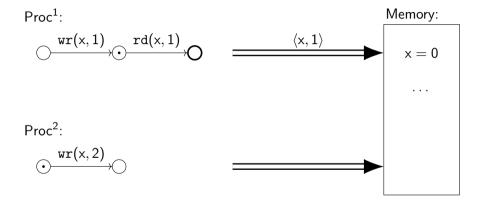
TSO Game: $c_1 \longrightarrow c_2 \longrightarrow c_3$

process player / update player

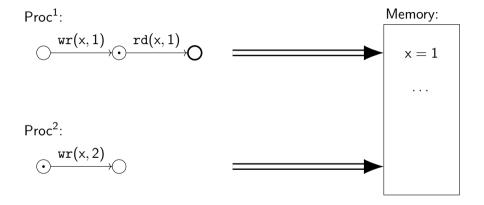




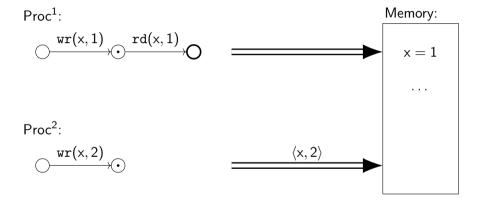




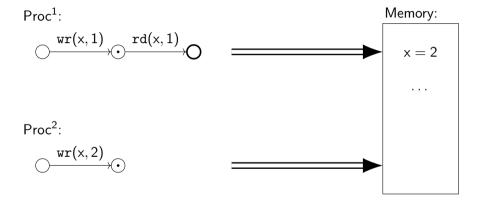




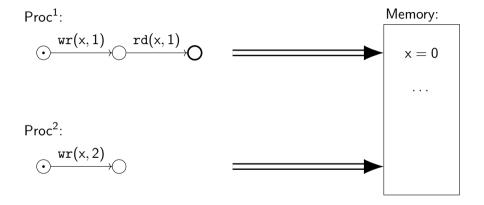




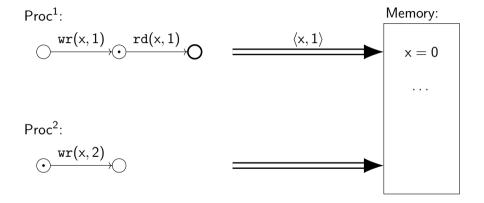




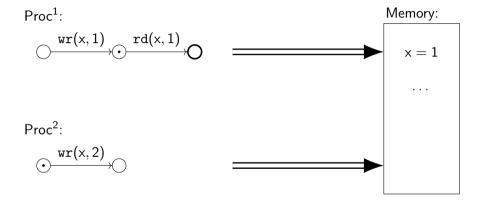




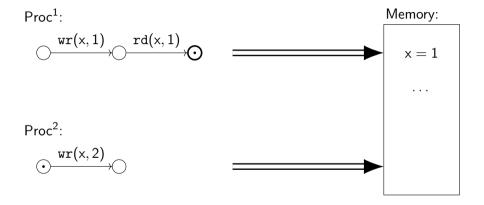




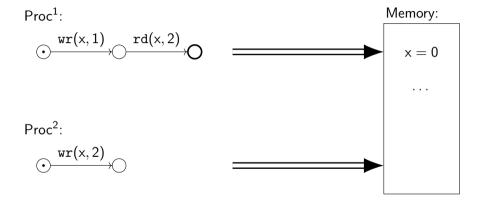




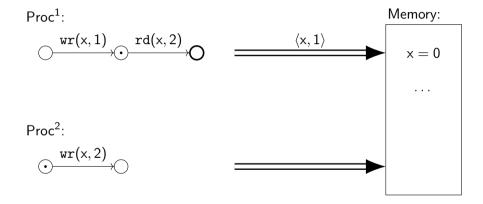




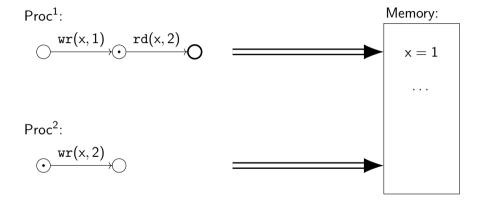




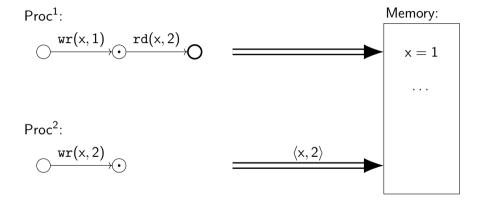




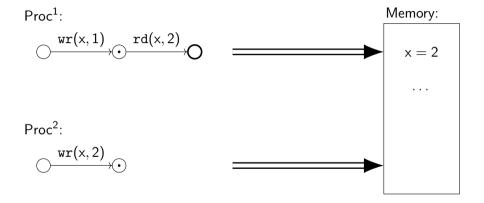




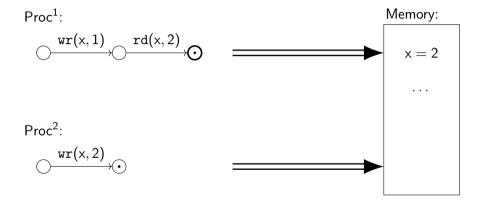




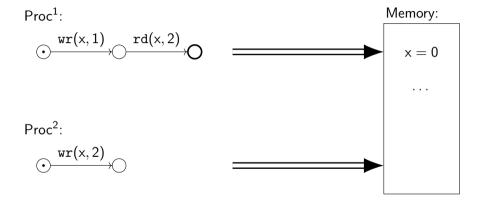




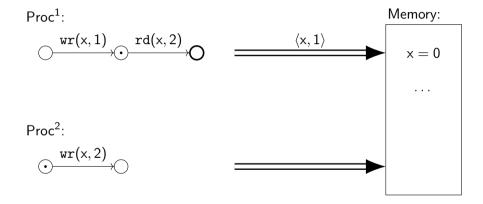




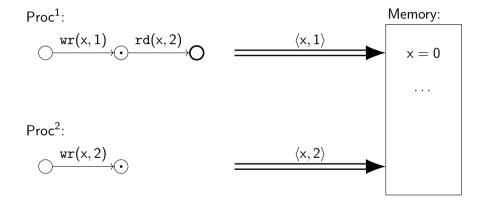
















► Proc^t can reach final state **without** help from other processes: winning strategy for process player: only play in Proc^t



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- ▶ analysis reduces to single-process programs (finite behaviour)



- ightharpoonup Proc¹ can reach final state **without** help from other processes: winning strategy for process player: only play in Proc^t
- \triangleright Proc^t can reach final state **only with** help from other processes: winning strategy for update player: do not update any message
- similar for safety games
- ▶ analysis reduces to single-process programs (finite behaviour)
- ► complexity: PSPACE-complete





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Process Fairness:

Every enabled process must be executed infinitely often.



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Update Fairness:

Eventually, every buffer message must be updated to the memory.



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safety games?



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 $\textcolor{red}{\sf safety \ games?} \rightarrow \mathsf{reachability \ games!}$

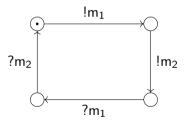


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safety games? → reachability games!

Idea: Reduction from Perfect Channel Systems

nondeterministic finite state automata augmented by FIFO channel



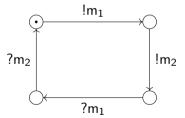


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Idea: Reduction from Perfect Channel Systems

- nondeterministic finite state automata augmented by FIFO channel
- ▶ use TSO buffer to simulate channel



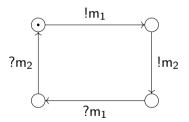


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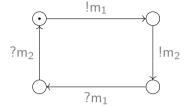
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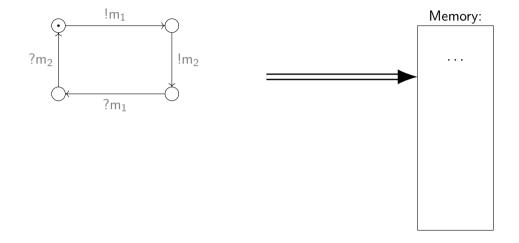




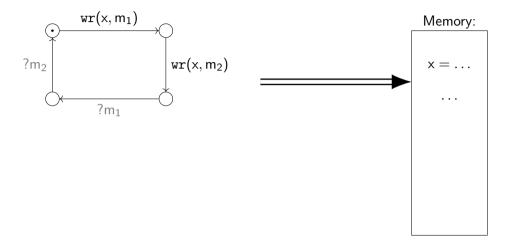




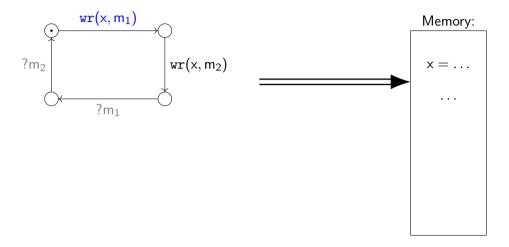




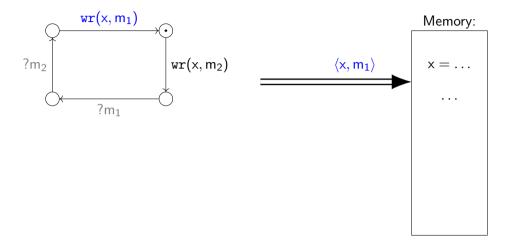




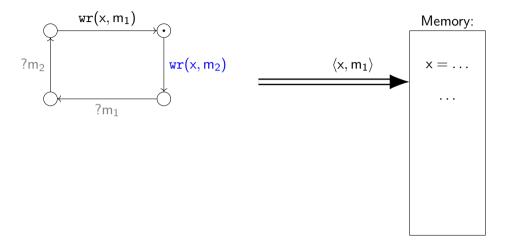




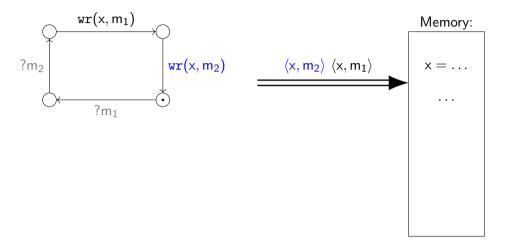




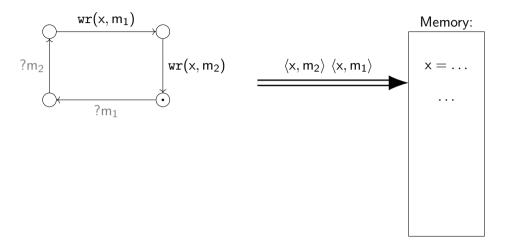




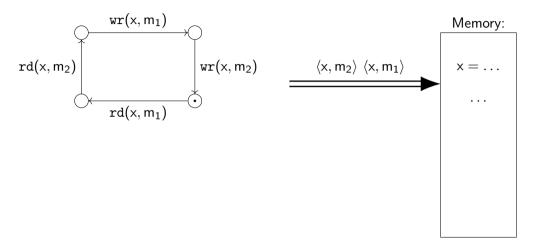




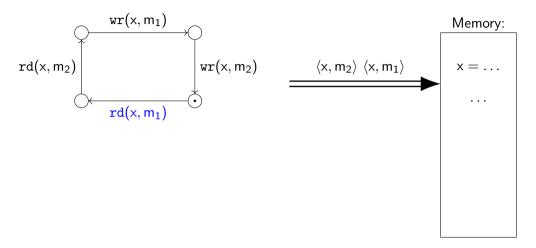




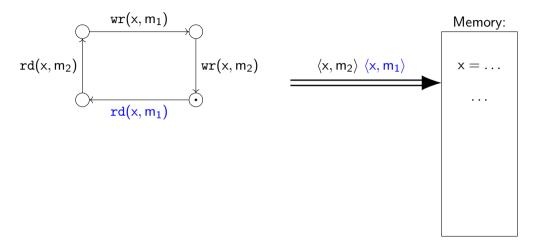




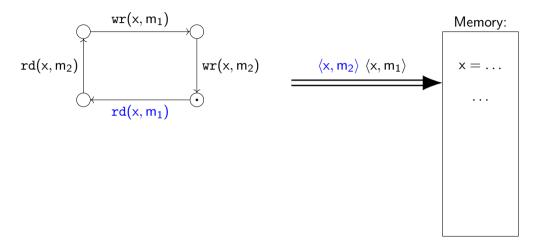




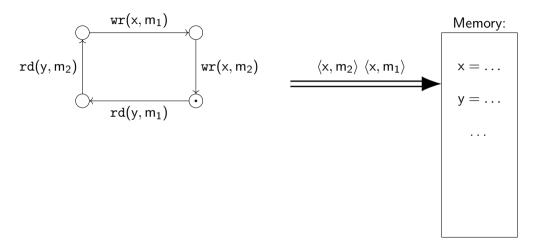




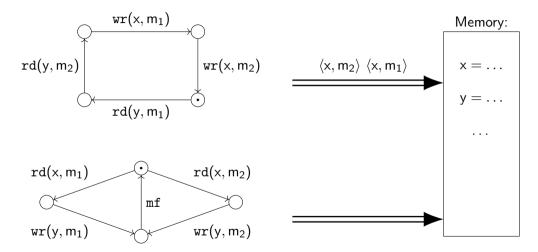




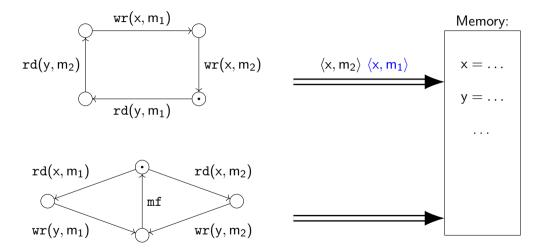




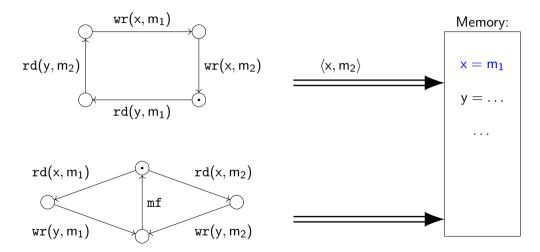




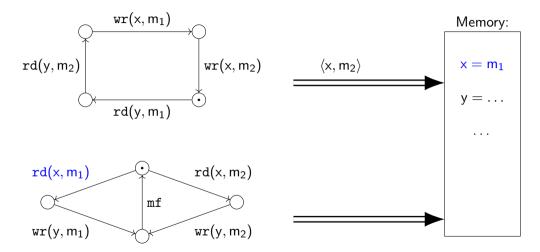




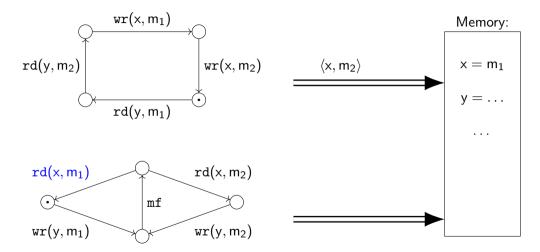




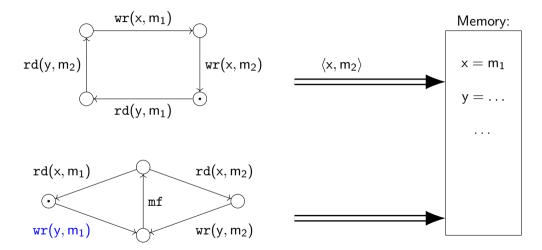




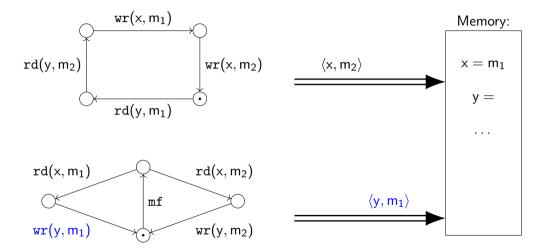




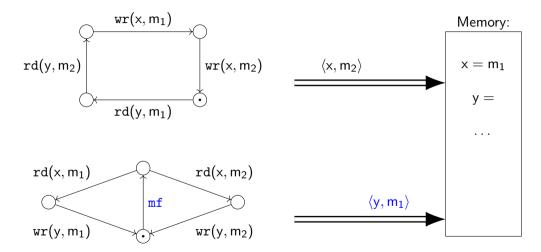




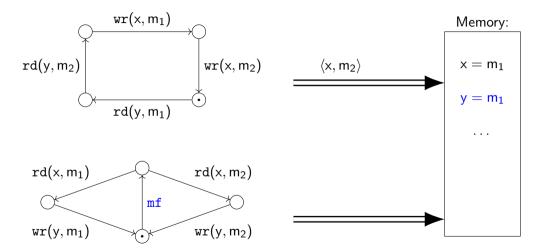




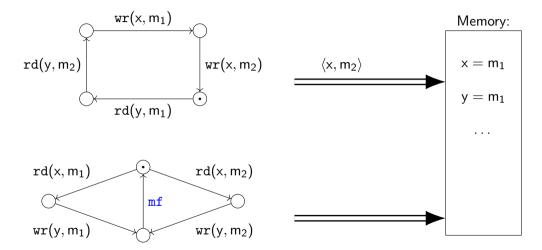




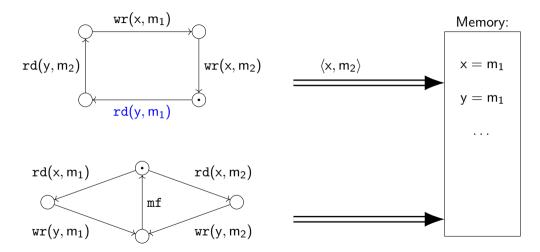




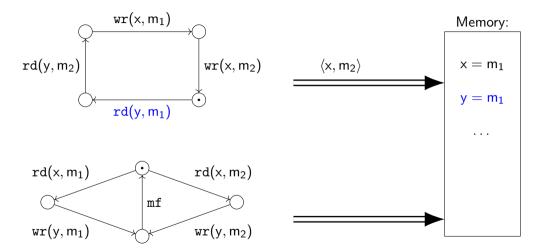




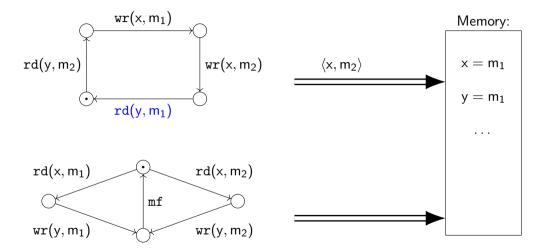




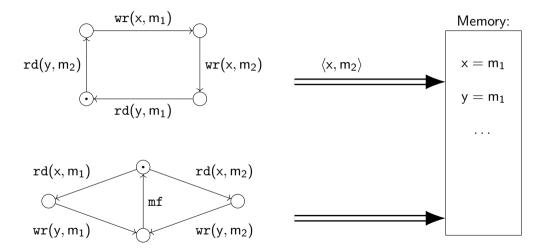










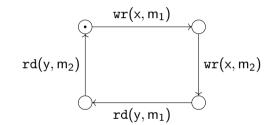




Update Fairness

Eventually, every buffer message must be updated to the memory.

- use TSO buffer to simulate PCS channel
- reduce PCS reachability (undecidable) to TSO reachability game



Theorem

The reachability problem under TSO semantics with update fairness is undecidable.



Every enabled process must be executed infinitely often.



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reachability games?



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reachability games? → safety games!



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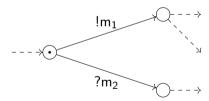
Idea: update player simulates PCS run, process player is passive



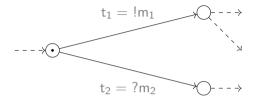
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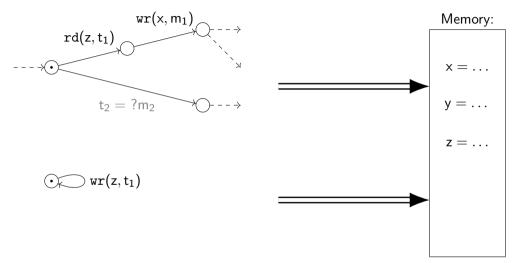
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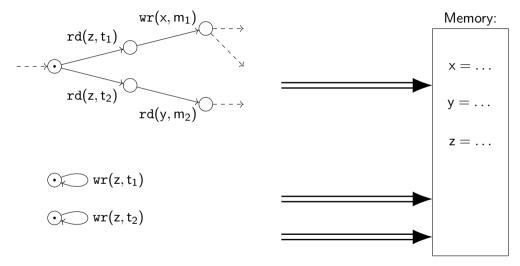




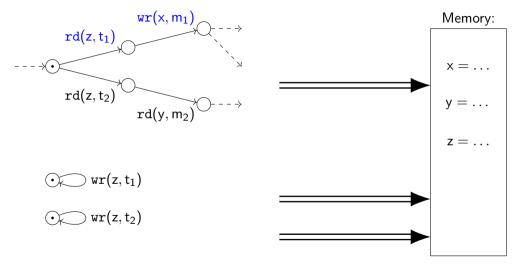




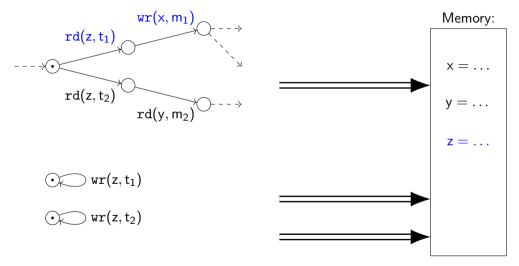




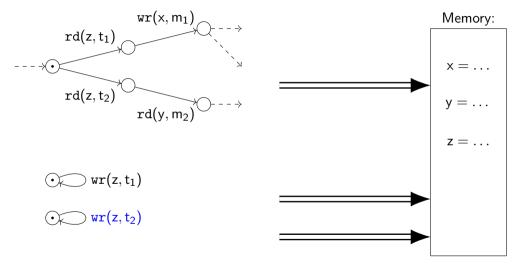




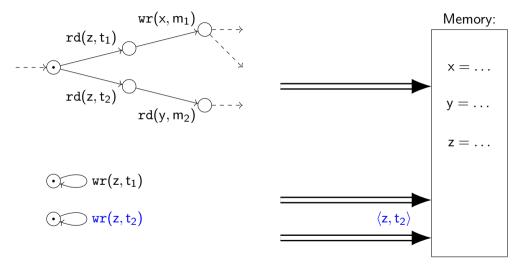




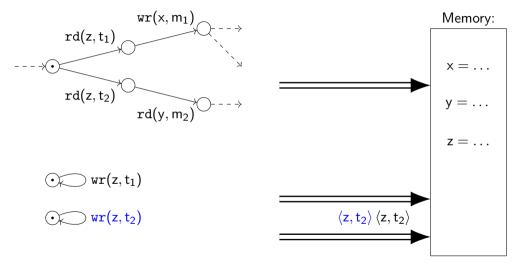




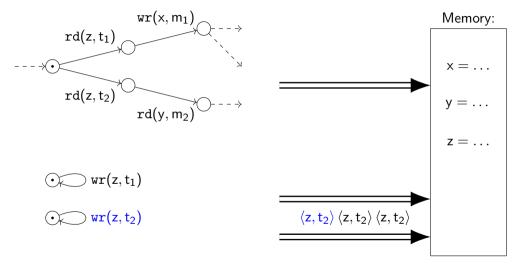




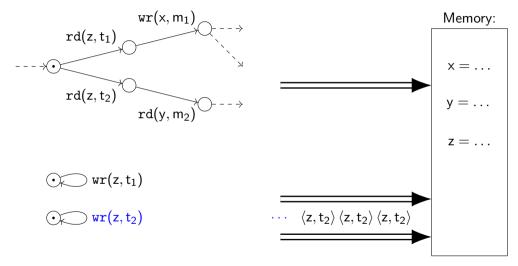




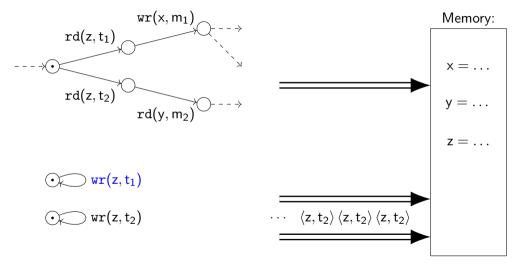




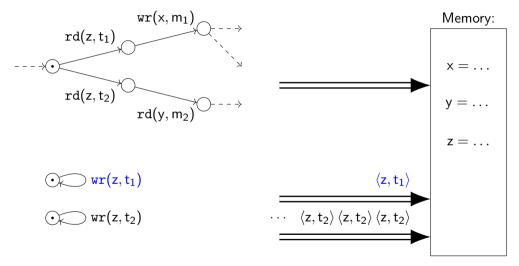




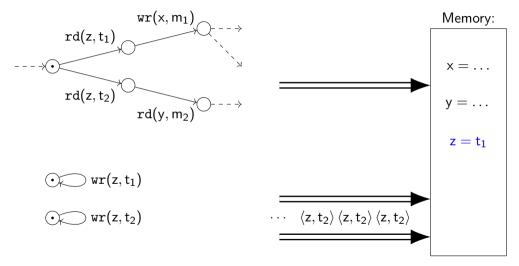




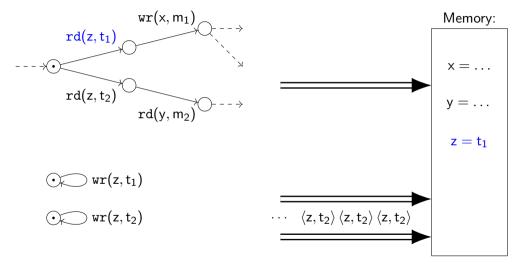




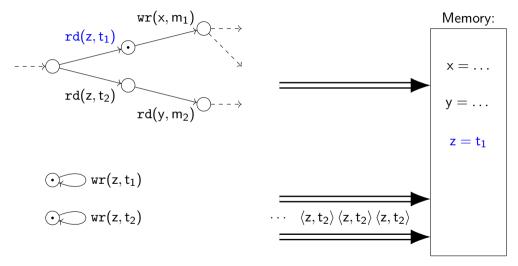




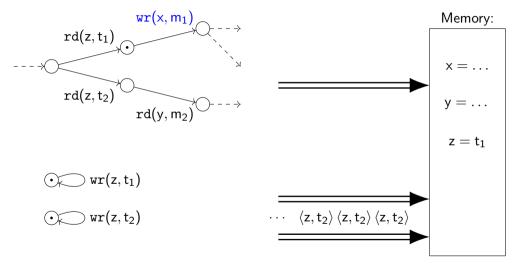




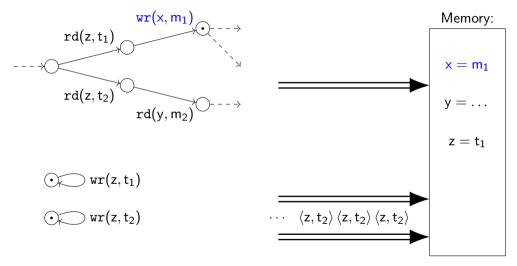








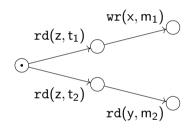






Every enabled process must be executed infinitely often.

- similar to reachability games
- update player simulates PCS run, process player is passive
- reduce PCS reachability (undecidable) to TSO safety game



Theorem

The safety problem under TSO semantics with process fairness is undecidable.



Conclusion

- reachability and safety without fairness
 - ► reduce to single-process programs
 - ▶ finite behaviour / PSPACE-complete



Conclusion

- reachability and safety without fairness
 - ► reduce to single-process programs
 - ► finite behaviour / PSPACE-complete
- reachability with update fairness and safety with process fairness
 - reduction from PCS reachability
 - undecidable



Conclusion

- reachability and safety without fairness
 - ► reduce to single-process programs
 - ► finite behaviour / PSPACE-complete
- reachability with update fairness and safety with process fairness
 - reduction from PCS reachability
 - undecidable
- further work could consider other
 - winning conditions
 - fairness conditions
 - weak memory models





Reachability and Safety Games under TSO Semantics

SCooL / GandALF 2024 in Reykjavik

Stephan Spengler
Uppsala University, Sweden
20 June 2024

