

# UNIT-II

## Control Unit:

Control Unit and instruction set,  
Hardwired control and microprogrammed control,  
Microoperation sequencing logic,  
Control memory

- + Instruction set architecture:  
Instruction set,  
instruction cycle and state diagram,  
Instruction factors, addressing modes  
CISE and RISE systems

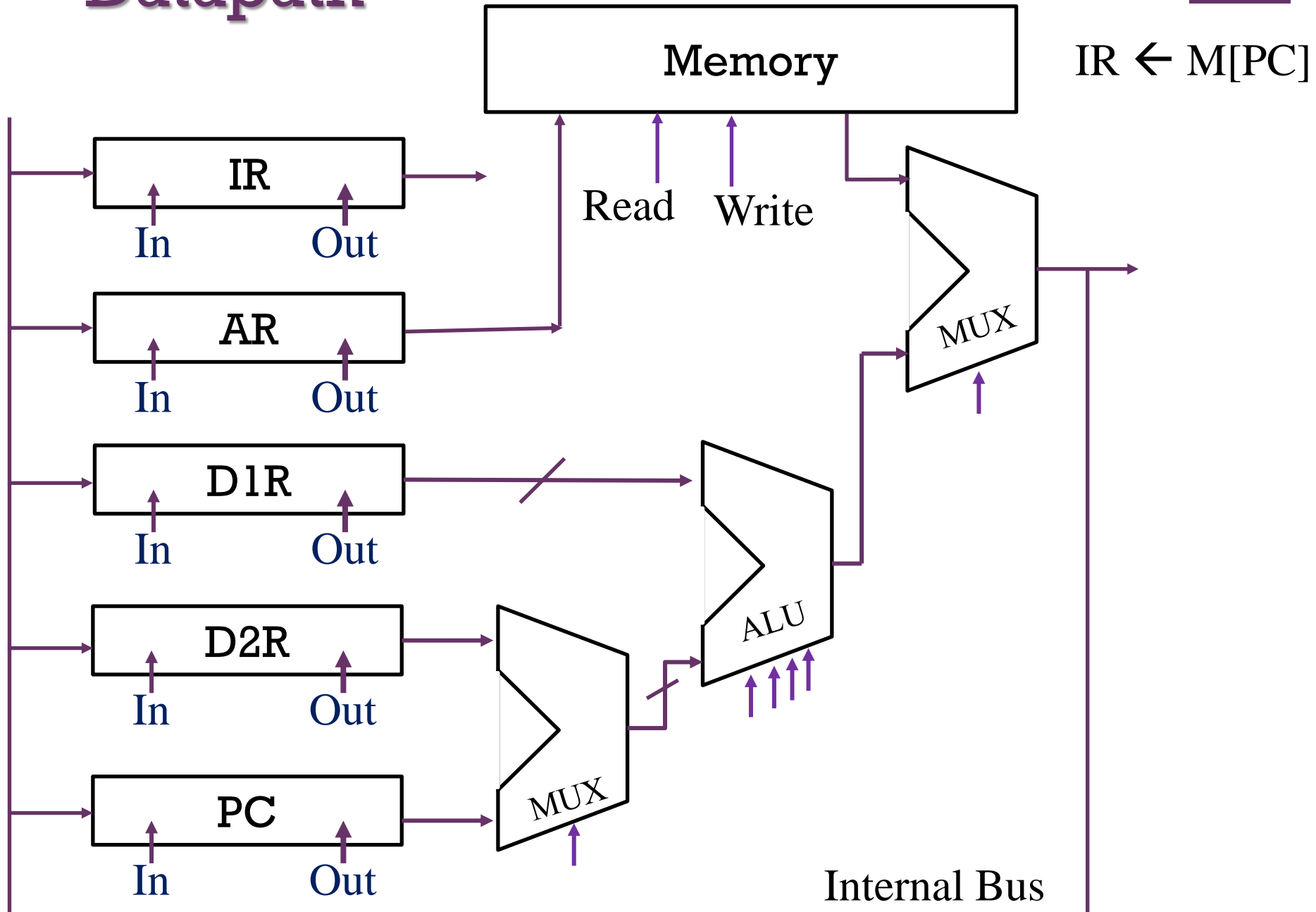
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# Control Unit

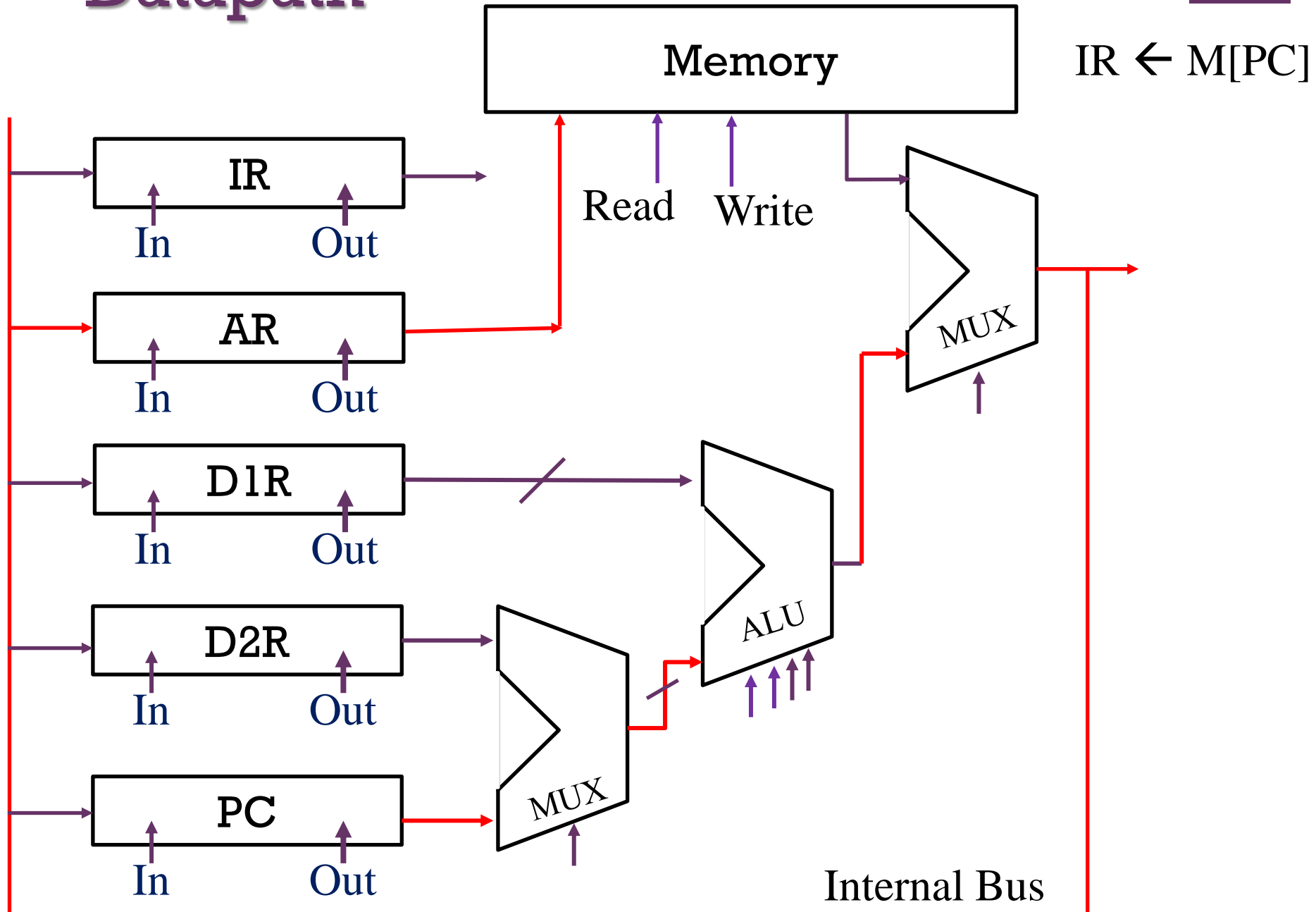


- Datapath
  - It is the collection of functional units such as ALU, multiplexers, registers, etc. Perform data processing operations

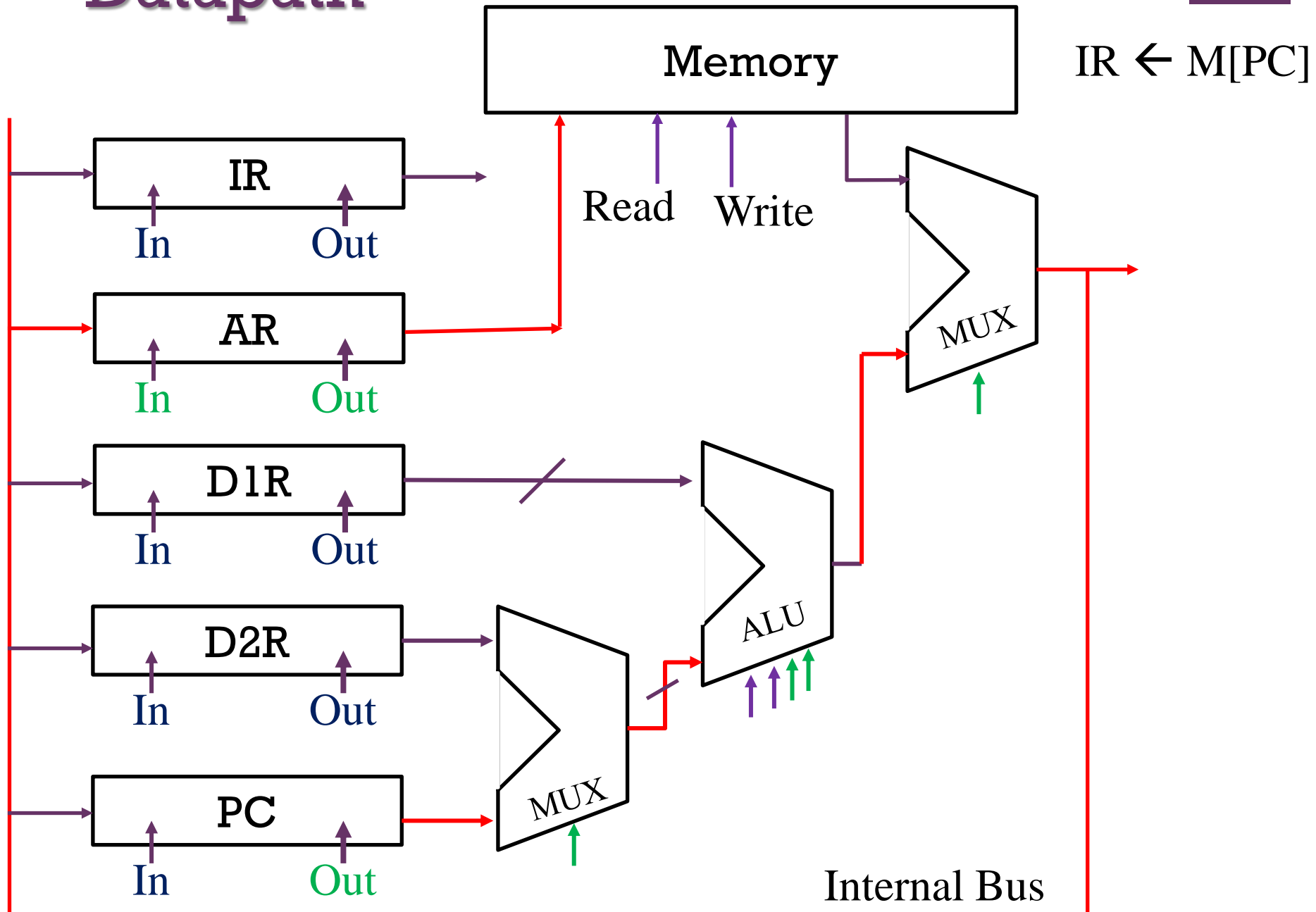
# Datapath



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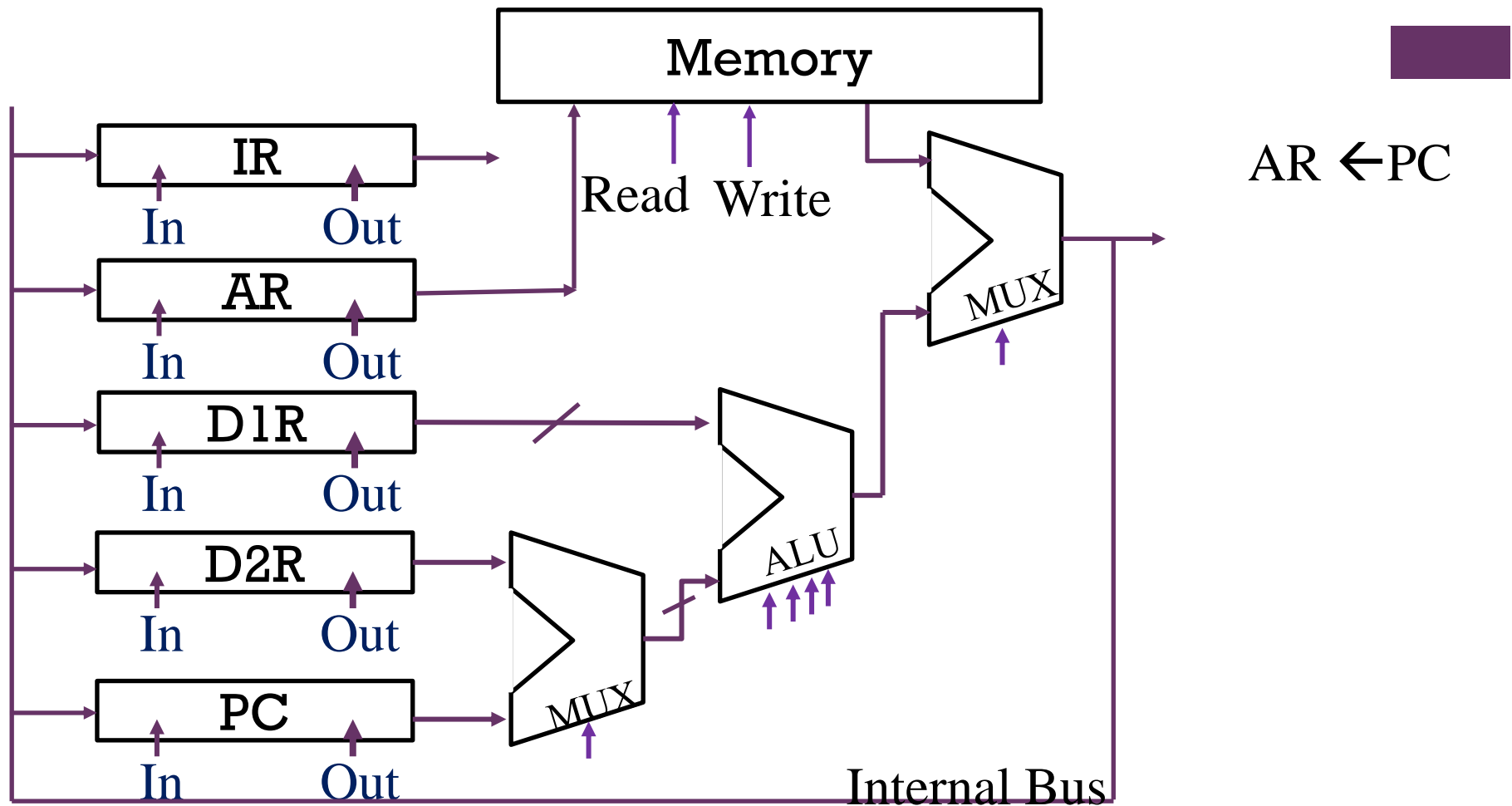
# Control Unit



- It generates control signals and sends them to various components of the computer. All components operate according to these control signals.
- **Control Variables:** Name of a control signals
- **Control word:** Collections of signals generated by control at once.

IR		AR		D1		D2		PC		Mux1		Mux2		ALU		Mem
----	--	----	--	----	--	----	--	----	--	------	--	------	--	-----	--	-----

In		out		in		out		in		out		in		out		inc		Sel		Sel		opcode		R		W
----	--	-----	--	----	--	-----	--	----	--	-----	--	----	--	-----	--	-----	--	-----	--	-----	--	--------	--	---	--	---



AR ← PC

IR		AR		D1		D2		PC		Mux1	Mux2	ALU	Mem		
In	out	in	out	in	out	in	out	in	out	inc	Sel	Sel	opcode	R	W
0	0	1	0	0	0	0	0	0	1	0	1	1	0010	0	0

# Control Unit Functional Requirements

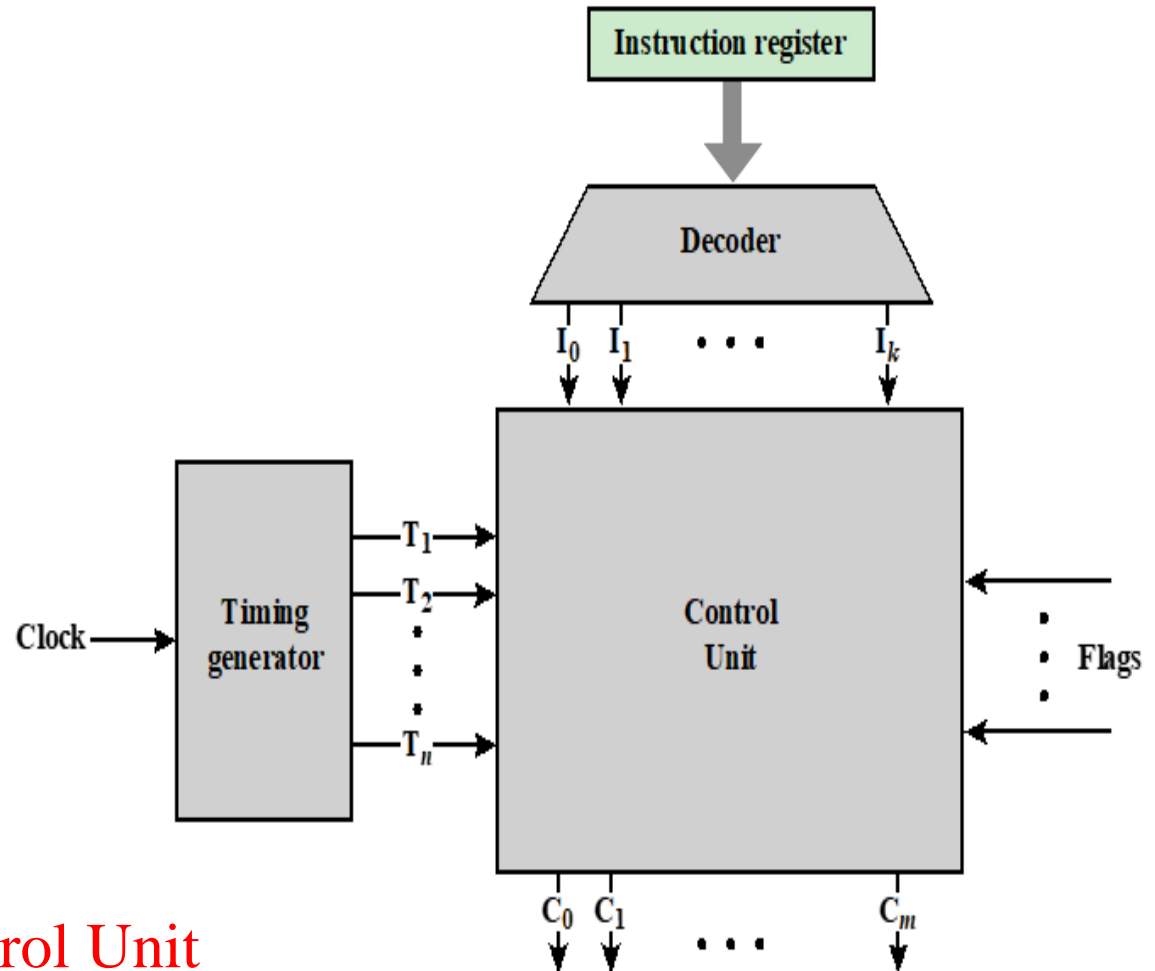


- Three step process to lead to a characterization of the control unit:
  - Define basic elements of processor
  - Describe micro-operations processor performs
  - Determine the functions that the control unit must perform to cause the micro-operations to be performed
- The control unit performs two basic tasks:
  - Sequencing
  - Execution



# Control Unit Organization

- How Control Unit generates the control signals:



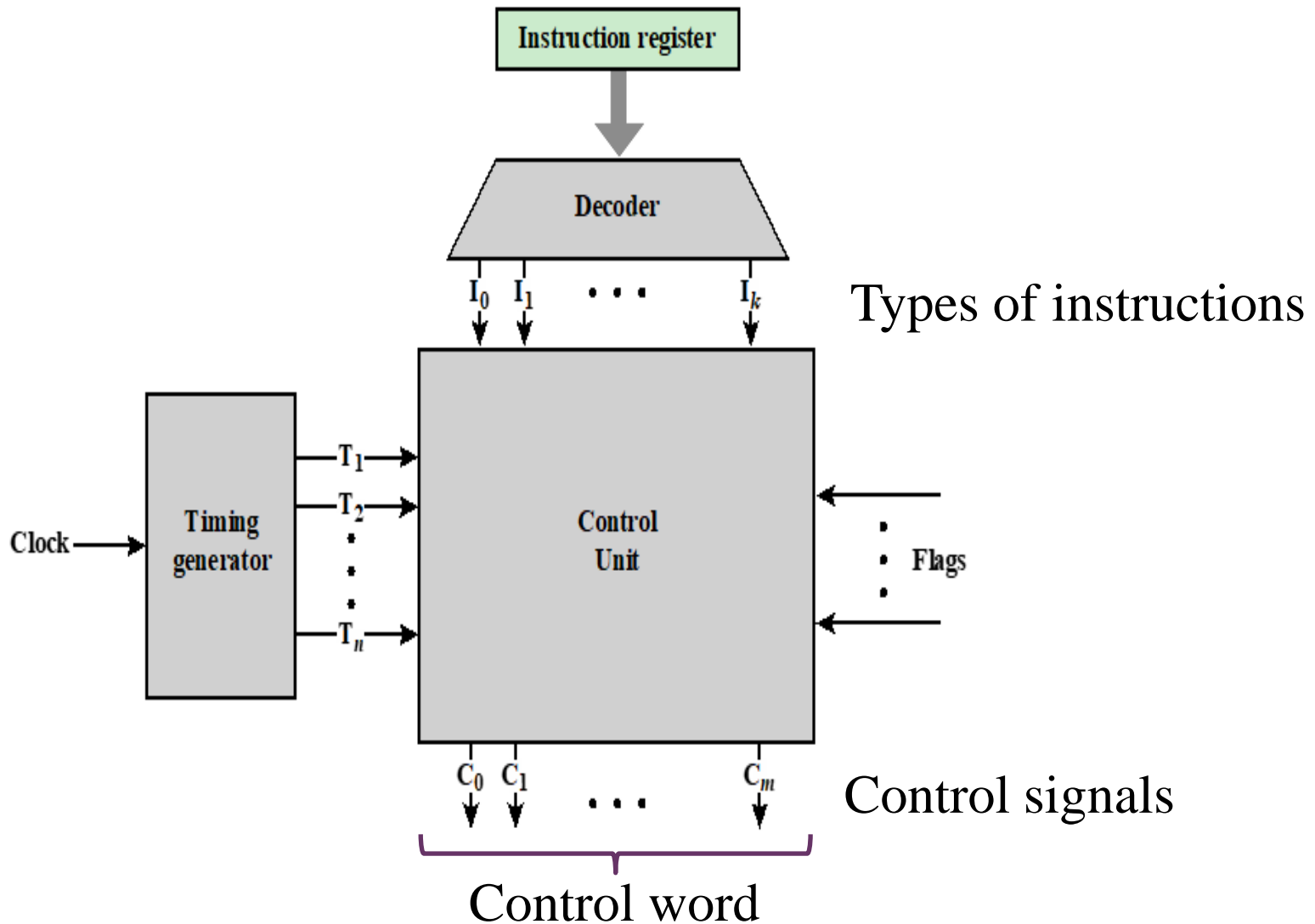
- Two mechanisms:**
  - Hardwired Control Unit
  - Microprogrammed Control Unit

# Hardwired Control Unit



- Control logic is implemented with Gates, Flip-flops, Encoder, decoder, multiplexer, and other digital circuits:
- **Advantages:**
  - Can be optimized to produce a faster mode of operation.
- **Disadvantages**
  - Adapting additional requirements is very difficult.

# Hardwired Control Unit



# Hardwired Control Unit



Inst./ Timer	I1	I2	I3	I4	In
T1	C2, C6,C8	...	...	...	...
T2	C1, C5	...	...	...	...
T3	...	...	...	...	...
T4	...	...	...	...	...
T5	...	...	...	...	...
T6	...	...	...	...	...

# Hardwired Control Unit

A hardwired CPU uses 10 control signals  $S_1$  to  $S_{10}$ , in various time steps  $T_1$  to  $T_5$ , to implement 4 instructions  $I_1$  to  $I_4$  as shown below:

	$T_1$	$T_2$	$T_3$	$T_4$	$T_5$
$I_1$	$S_1, S_3, S_5$	$S_2, S_4, S_6$	$S_1, S_7$	$S_{10}$	$S_3, S_8$
$I_2$	$S_1, S_3, S_5$	$S_8, S_9, S_{10}$	$S_5, S_6, S_7$	$S_6$	$S_{10}$
$I_3$	$S_1, S_3, S_5$	$S_7, S_8, S_{10}$	$S_2, S_6, S_9$	$S_{10}$	$S_1, S_3$
$I_4$	$S_1, S_3, S_5$	$S_2, S_6, S_7$	$S_5, S_{10}$	$S_6, S_9$	$S_{10}$

Which of the following pairs of expressions represent the circuit for generating control signals  $S_5$  and  $S_{10}$  respectively?

$((I_j + I_k)T_n)$  indicates that the control signal should be generated in time step  $T_n$  if the instruction being executed is  $I_j$  or  $I_k$

A.  $S_5 = T_1 + I_2 \cdot T_3$  and

$$S_{10} = (I_1 + I_3) \cdot T_4 + (I_2 + I_4) \cdot T_5$$

B.  $S_5 = T_1 + (I_2 + I_4) \cdot T_3$  and

$$S_{10} = (I_1 + I_3) \cdot T_4 + (I_2 + I_4) \cdot T_5$$

C.  $S_5 = T_1 + (I_2 + I_4) \cdot T_3$  and

$$S_{10} = (I_2 + I_3 + I_4) \cdot T_2 + (I_1 + I_3) \cdot T_4 + (I_2 + I_4) \cdot T_5$$

D.  $S_5 = T_1 + (I_2 + I_4) \cdot T_3$  and

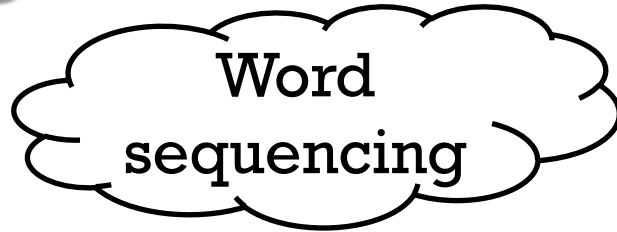
$$S_{10} = (I_2 + I_3) \cdot T_2 + I_4 \cdot T_3 + (I_1 + I_3) \cdot T_4 + (I_2 + I_4) \cdot T_5$$

# Microprogrammed Control Unit



- **Hardwired Control:**
  - It generates the signal for each instruction type.
- **Microprogrammed Control:**
  - It stores all the defined **Control words** in the **Control memory**.
  - Control logic is implemented with micro-programs.
- **Advantage:**
  - Updating the control logic is easy.
- **Disadvantage:**
  - Slower than hardwired control

# Microprogrammed Control Unit



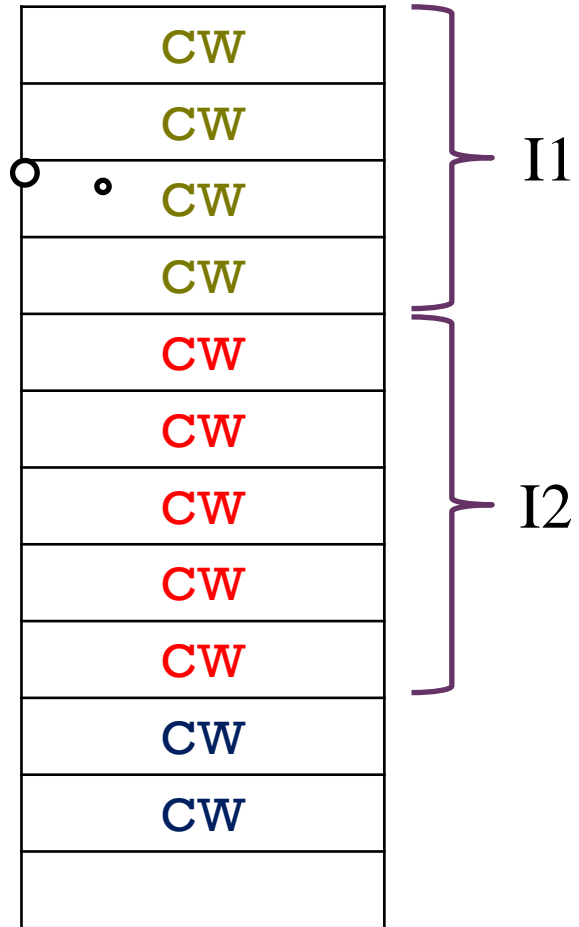
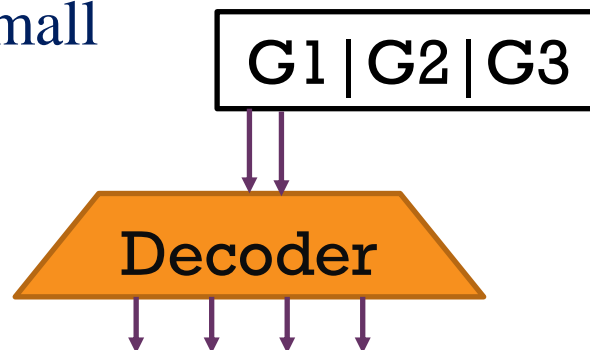
## Types

- **Horizontal**

- One bit for each control signal
- CW size is large

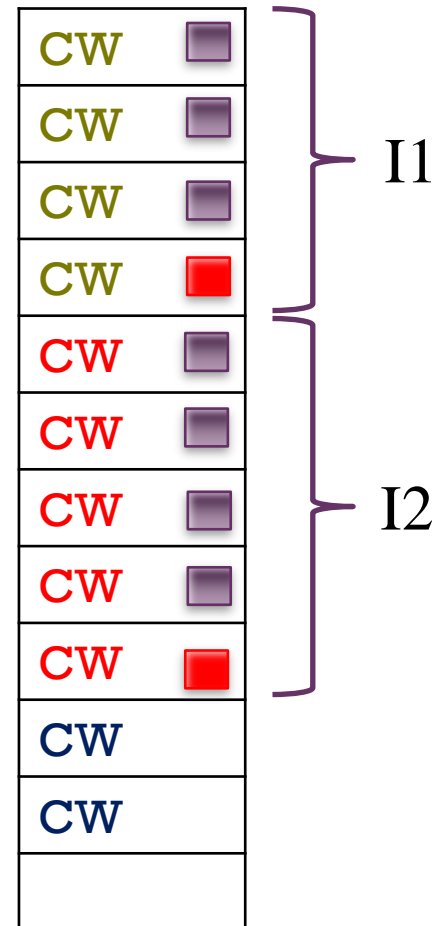
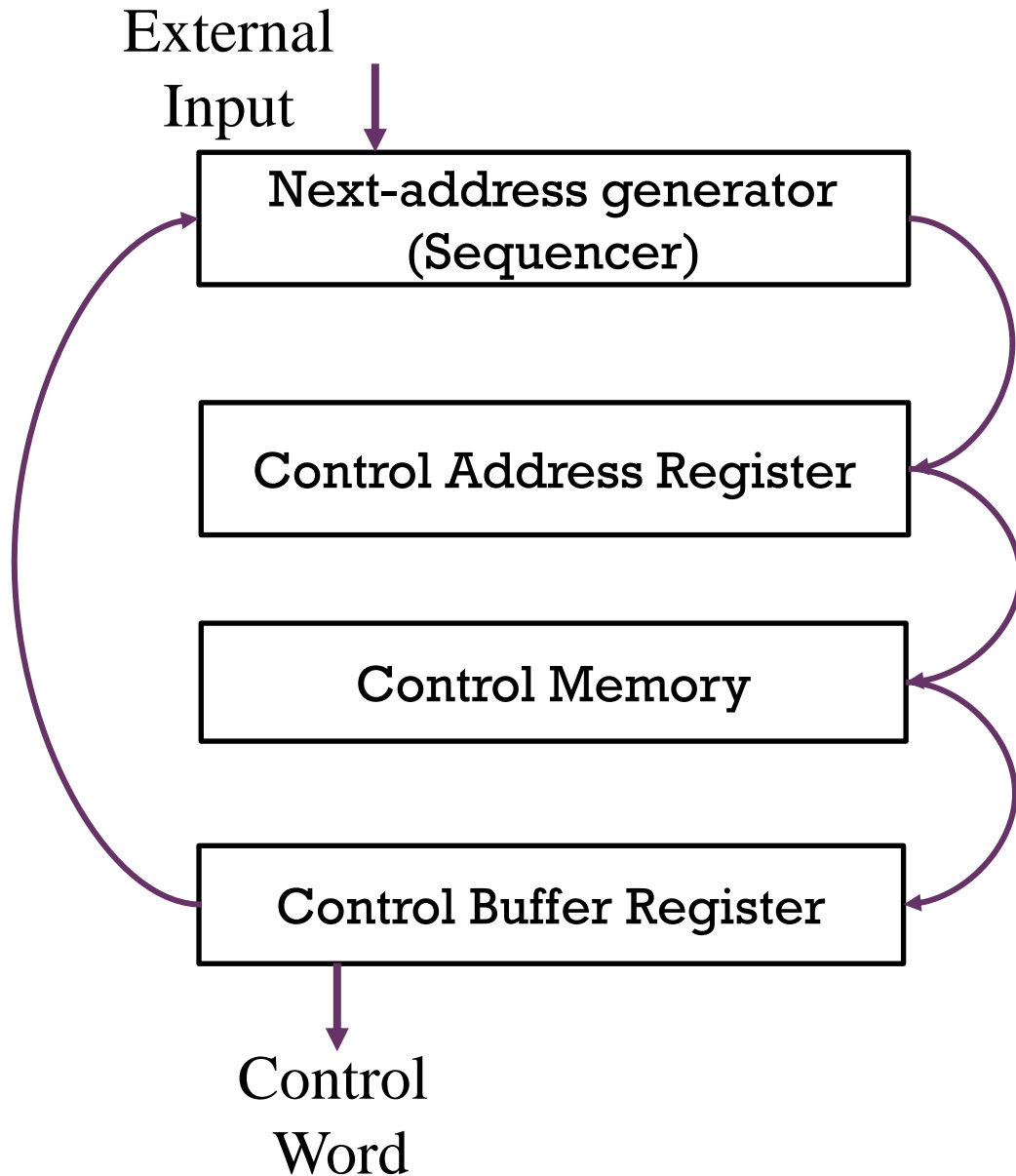
- **Vertical**

- Signals are divided into multiple groups in such a way that within each group, only one signal can be active at a time.
- CW size is small



Control Memory

# Control Word Sequencing





# Functioning of Microprogrammed Control Unit

