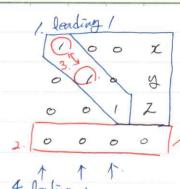
(사라리를). # Echelon Forms.



- 1. First non-zero olement in every is 1. (= leading 1)
- 2. All zero rows are grouped together at the bottom.
- 3. Leading above defler must be upper.
- 4. Each calcan containing loading 1 has zero everythere else.

"Reduced flow Echelon Forms " (= RREF). BRPV 除布K

ceithout 4

Row Echelon Forms" (= REF).

\* C.x.1.

0/07 is PREF.

[00] is RREP. > landing 101 思如从,

(= (book) is leading / exists ADD Conditions)

ex) Augmented Matrix

deading variable oxtoy+02=1 -> No salution.

ex).  $\begin{bmatrix} 1 & 0 & 3 & 4 \\ 0 & 1 & -4 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$  (x) + 32 = -1

\* leading variables free uniables 50 15.

DATE. 24 . 03. . 14.

# Ediavination Medhods. . Goal: any augmented marker > RDEF.

\* ERO: Edementary Dow Operation.

- 1) Constant multiple
- 2) Interchange
- 3). Add constant times you to other.

. Step 1. Locate the left most col that not all zero.

. step 2. Interchange the top row if (0,0) is zero.

\* Making looding 1.

· Step 3. Use ERO D to make leading 1. (x=d).

Step 4. Use ERO 3) to make Zero helow leading 1.

forward phase. steps. Report step / ~ 4 custil matrix become REF.

· step 6. Make zero above the leading 1's.

Step1-6: Gaus-Jordan Edinination. (Making PREF). Step1-5: Gaussian Edimination (Making REF).

DATE.

4 Homogeneous Cinear Systems.

\* Haurgeneous Linear Systems.

an Z+ ... + a, n × n = 0.

aux+ ... +aux Zn = 0.

→ Consistant "gildet".

शास्त्र मार्टिक : एस म्येव स्ट औ?

ax+by=0. Cztdg = 0. ) > 2/2 2/4. > (0,0) 01 2/9 34.

but 음=움면 7을/ 칼다 > 해 무슨이 많다.

ex6) Hemogeneous Cinear System of Augmented Matrix2foot. विशेष ) देशका शर्वा

# Free Variables in Homogeneous Cinear Systems.

(Cinear Systems).

1. LS: homogeneous > PREF: homogeneous.

2. LS: al equations

> MIZZ. (All zero round that the offe).

PREF: requations

· a untagons + r leading variables then n-r free vaciables.

0 3 0 4 2 0 0 ∫
3H Nz row. ⇒ leading Variables.
0 0 0 0 0 0 0 0

DATE. 24. 08 . 14

Page 19, book.

\* Then 1.2.2. A lowogeneous LS couth more unknowns

Han equations

has infinitely many solutions.

 $u \stackrel{\angle}{\sim} v \rightarrow n-r > 0$ 

\* Ex 7. Back substitution. (deflorted off).

 $\chi_{6} = \frac{1}{3}$   $\chi_{3} = -2\chi_{4} - 1$   $\chi_{1} = -3\chi_{2} + 2\chi_{3} + 2\chi_{5}$ 

DATE. 24 . 08 . 19



\*Ex8. a. o / 2 -4 /

0 0 1 6 9
0 0 0 0 i) No solution.

b. (1) -3 7 2 5

0 (1) 2 -4 /

0 0 (1) 6 9

10 0 0 (1) 0

Ly Leading 1 # 4 = Dow # 4 → Unique One Salution

C. 1 -3 7 2 5

0 1 2 -4 1

0 0 1 6 9

10 0 0 0 0 > Infinitely Many.

# Same facts about Echelon Forms.

1. Every matrix has a unique PREP. ... EPO 23001 CH 3te DD, Sold Std.
But 322 3td 20043td.

2. DEFs are not unique

3. The RREF and all REFs have the same # of zerous, I and the landing 1's always occur in the same positions all state (habit).

pivol positions ... \* 4.

DATE. 20.08 .19.

· pivot positions?	0 -	-3 7	2	5
(1,1), (2,2)	0	2	- 4	1
(3,3), (4.4).	0 0		6	9

- · pivat columns o o o o o
- : 1,2,3,4.
- · pivat rows
  - : 1,2,3,4.