

Elementary Matrices.

• Elementary row operations.

↙ ...? ↘

① c times $\rightarrow 1/c$ times.

② interchange \rightarrow interchange.

③ another $+ c$ times \rightarrow another $+ (-c)$ times.

* Page 55, Book, table 1.

* Def 1.

• $A \xrightarrow{ERO} B$ then $B \xrightarrow{R-ERO} A$ "행 등가"

\Rightarrow Matrices A and B are said to be "row equivalent"

if either (hence each) can be obtained from the other by a sequence of elementary row operations.

* Def 2.

• A matrix E is called an elementary matrix

if it can be obtained from an identity matrix by performing a single elementary row operation.

• ex) $\begin{bmatrix} 1 & 0 \\ 0 & -3 \end{bmatrix}$ is elementary matrix.

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \times 3$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \text{ is elementary matrix.}$$

* Thm 1.5.1

If, the elementary matrix E results from performing a certain row operation on I_n and A is an $n \times n$ matrix, then the product EA is the matrix that results when this same row operation is performed on A .

* Ex 2)

$$\text{ex 1. } E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix} \rightarrow I_3 + 3E_1$$

$$EA = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 2 & 3 \\ 2 & -1 & 3 & 6 \\ 1 & 4 & 4 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 2 & 3 \\ 2 & -1 & 3 & 6 \\ 4 & 4 & 10 & 9 \end{bmatrix}$$

$$(EA)_3 = A_3 + 3A_1$$

$\therefore E$ is Elementary Row Operation of $3A_1$ row "3rd row of A "

* Ex 3)

Inverse Elementary Row Operations.

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \xrightarrow{+5 \text{ times}} \begin{bmatrix} 1 & 5 \\ 0 & 1 \end{bmatrix} \xrightarrow{-5 \text{ times}} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$\xleftarrow{\text{ERO}} \quad \xleftarrow{\text{Inverse ERO}}$

\downarrow 정리.

* Thm 15.2).

Every elementary matrix is invertible,
and the inverse is also an elementary matrix

"등가"

Equivalence Theorem.

If A is an $n \times n$ matrix, below is all true or all false.

(필요충분조건).

- (a) A is invertible.
- (b) $Ax = 0$ has only the trivial solution.
- * (c) The reduced row echelon form of A is I_n .
- (d) A is expressible as a product of elementary matrices.

(b). $AX=0$, A is invertible.then $A^{-1}AX = A^{-1}0$. $X=0$. \rightarrow trivial solution.

(d) $A = E_k E_{k+1} \dots E_1$

 \downarrow $k \dots A$ 의 행에 따라 달라짐.하지만 항상 0 의 용으로 표현 가능.

Inverting Matrices.

$$E_k \dots E_2 E_1 A = I_n$$

$$(E_k \dots E_2 E_1)^{-1} (E_k \dots E_2 E_1) A = (E_k \dots E_2 E_1)^{-1} I_n$$

$$\therefore \begin{cases} A = (E_k \dots E_2 E_1)^{-1} I_n \\ A^{-1} = (E_k \dots E_2 E_1) I_n \end{cases}$$

" row-3의 elimination A 의 ERO는 역행렬 구하는 G 관련 없다 " \downarrow 정리

Inversion Algorithm.

$$\begin{aligned} * \text{Ex 4). } & \begin{cases} [A] \xrightarrow{GJ} [I] \\ [A|I] \xrightarrow{GJ} [I|A^{-1}] \end{cases} \end{aligned}$$

$$\begin{array}{cc} (A) & (I) \\ \left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 2 & 5 & 3 & 0 & 1 & 0 \\ 1 & 0 & 8 & 0 & 0 & 1 \end{array} \right] \end{array}$$

 \downarrow

$$\begin{array}{cc} (I) & (A^{-1}) \\ \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & -40 & 16 & 9 \\ 0 & 1 & 0 & 13 & -5 & -3 \\ 0 & 0 & 1 & 5 & -2 & -1 \end{array} \right] \end{array}$$

Ex 5). Showing Matrix is not invertible
Using Inversion Algorithm.

$$\left[\begin{array}{ccc|ccc} 1 & 6 & 4 & 1 & 0 & 0 \\ 0 & -8 & -9 & -2 & 1 & 0 \\ 0 & 0 & 0 & -1 & 1 & 1 \end{array} \right]$$

Left matrix
Cannot be I \Rightarrow not invertible.

More on Linear Systems and Invertible Matrices.

*Thm 1.6.1 A system of linear equations has $\begin{cases} \text{zero.} \\ \text{one.} \\ \text{infinitely many} \end{cases}$ solutions.

*Thm 1.6.2. A : an invertible matrix of size $n \times n$.

b : $n \times 1$ column vector.

$\Rightarrow Ax = b$ has exactly one solution.

$$x = A^{-1}b$$

*ex 2).

$$\begin{array}{l} Ax = b_1 \\ Ax = b_2 \end{array} \dots \left[A \mid \begin{array}{c} 4 \\ 5 \\ 9 \end{array} \right] \Rightarrow \left[\begin{array}{ccc|c} 1 & 0 & 0 & \checkmark \\ 0 & 1 & 0 & \checkmark \\ 0 & 0 & 1 & \checkmark \end{array} \right]$$

$$\hookrightarrow \left[A \mid \begin{array}{c} 4 \\ 5 \\ 9 \end{array} \mid \begin{array}{c} 1 \\ 6 \\ -6 \end{array} \right] \leftarrow \text{Augmented Augmented Matrix.}$$

$$\downarrow$$

$$\left[I \mid \begin{array}{c} 1 \\ 0 \\ 1 \end{array} \mid \begin{array}{c} 2 \\ 1 \\ -1 \end{array} \right]$$

* Thm 1.6.3.

A : square matrix.

(a) If B is a square matrix
satisfying $BA = I$
then $B = A^{-1}$.

(b) $AB = I$ then $B = A^{-1}$.

* Thm 1.6.4.

A : $n \times n$ matrix.

The following are equivalent.

(Thm 1.5.3 + a).

(a) A is invertible.

(b)

(c)

(d)

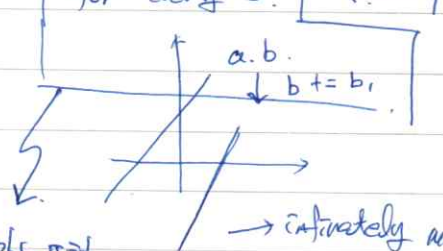
(e) $Ax = b$ is consistent for every $n \times 1$ matrix b
= at least one solution.

(f) has exactly one solution for
every $n \times 1$ matrix b .

\propto Thm 1.6.2.

$$\Rightarrow A^{-1} \dots Ax = b \quad x = A^{-1}b \quad \begin{cases} \rightarrow (f) \checkmark \\ \downarrow \\ (e) \checkmark \end{cases}$$

• (e) \Rightarrow (a)?

for some $b \dots Ax = b$ has one solution.
for every b \leftarrow infinitely many solutions.


every b is not ...

b is ~~not~~ infinitely many or no solution of $Ax = b$.
 \Rightarrow every b is one b .

* Thm 16.5.

Let A and B be square matrices of the same size.

If AB is invertible,

Then A and B must also be invertible. $\Rightarrow (AB)^{-1} = B^{-1}A^{-1}$.

* A fundamental problem.

"fixed"

Let A be a fixed $n \times n$ matrix.

Find all $n \times 1$ matrix \underline{b} such that $A\underline{x} = \underline{b}$ is consistent.

$A\underline{x} = \underline{b} \Rightarrow \exists \underline{x} \text{ s.t. } \underline{b} \in \text{range}(A)$



* EX 3.

$$\begin{aligned} x_1 + x_2 + 2x_3 &= b_1 \\ x_1 + x_3 &= b_2 \\ 2x_1 + x_2 + 3x_3 &= b_3 \end{aligned} \rightarrow \begin{bmatrix} 1 & 1 & 2 & b_1 \\ 1 & 0 & 1 & b_2 \\ 2 & 1 & 3 & b_3 \end{bmatrix}$$

\searrow GF.

$$\begin{bmatrix} 1 & 1 & 2 & b_1 \\ 0 & 1 & 1 & b_1 - b_2 \\ 0 & 0 & 0 & b_3 - b_2 - b_1 \end{bmatrix}$$

infinitely many \leftarrow

$$b_3 = b_2 + b_1 \Rightarrow \underline{b} = \begin{bmatrix} b_1 \\ b_2 \\ b_1 + b_2 \end{bmatrix}$$

$$\begin{aligned} x_1 + 2x_2 + 3x_3 &= b_1 \\ 2x_1 + 5x_2 + 3x_3 &= b_2 \\ x_1 + 8x_3 &= b_3 \end{aligned} \rightarrow \begin{bmatrix} 1 & 2 & 3 & b_1 \\ 2 & 5 & 3 & b_2 \\ 1 & 0 & 8 & b_3 \end{bmatrix}$$

\searrow GF.

$$\begin{cases} x_1 \rightarrow \\ x_2 \rightarrow \\ x_3 \rightarrow \end{cases} \begin{bmatrix} 1 & 0 & 0 & -40b_1 + 16b_2 + 9b_3 \\ 0 & 1 & 0 & 13b_1 - 5b_2 - 3b_3 \\ 0 & 0 & 1 & 5b_1 - 2b_2 - b_3 \end{bmatrix}$$