COMMUNICATION MANUAL DIGITAL PID CONTROLLER

FY100 FY101 FY400 FY600 FY700 FY800 FY900

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FY_COMM_EN_V1



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1 Set up of the controller

Press



key 3 seconds to configure parameters in Level 3

Character	Name , Functions and Setting range	Default	
PSL	Protocol Selection	r E U	
	┌ 上 IJ: MODBUS RTU Protocol		
	R5 € r: MODBUS ASCII Protocol		
	₽₽ E: TAIE Protocol		
b , E 5	Communication Bits	0_81	
	$\Box\Box$: Odd parity , Data bits = 8 , Stop Bit = 1		
	\Box _ \Box \Box :Odd parity , Data bits = 8 , Stop Bit = 2		
	$\mathcal{E}_{-}\mathcal{B}$ /: Even parity , Data bits = 8 , Stop Bit = 1		
	E = B = 2: Even parity , Data bits = 8 , Stop Bit = 2		
1 d.N D	ID Number	1	
	Range : 0 ~ 255		
ьяиа	Communication Baud rate	384	
	ਟੋ Ч: 2400 bps		
	└ 년 : 4800 bps		
	☐ 5: 9600 bps		
	/ 月		
	∃ 🛮 Ч: 38400 bps		

When parameter b + E 5 or b R U d was changed, always turn on the power again. Otherwise, no communication is performed by using the changed value.

2 System Configuration

2.1 RS485 Communication System

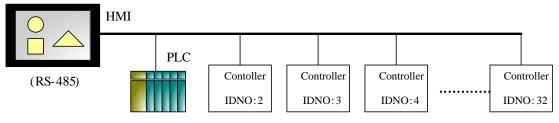


Figure: 2.1-1

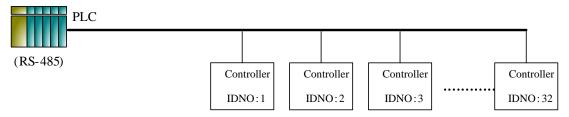


Figure: 2.1-2

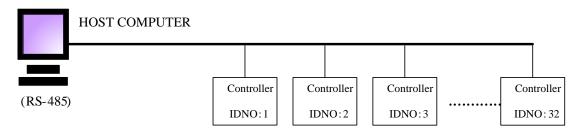


Figure: 2.1-3

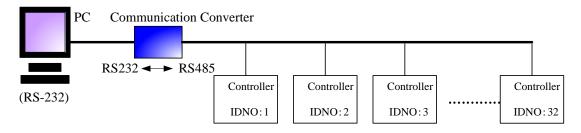


Figure: 2.1-4

2.2 RS232 Communication System

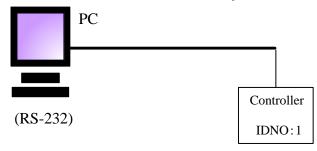


Figure: 2.2-1

3 Wiring Connection

3.1 RS485 Communication Wiring

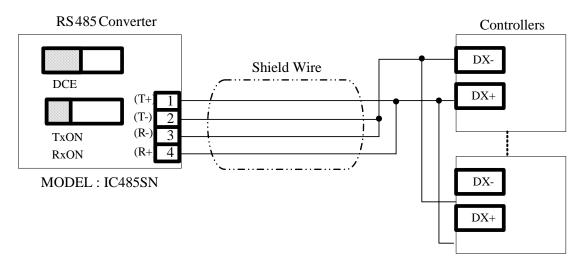


Figure: 3.1-1

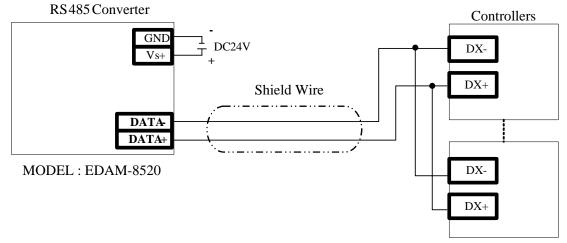
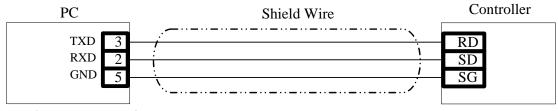


Figure: 3.1-2

Note: 1. The length of shield wire should be less than 1200M.

2. Controllers in RS485 parallel connection should be less than 32 units

3.2 RS232 Communication Wiring



D sub connector (9 Pin)

Note: 1. The length of shield wire should be less than 12M.

2. There is only 1 unit of controller available in RS232 communication..

4 MODBUS RTU Protocol

4.1 Message Configuration

ID Number	Function Code	Data	CRC
1 Byte	1 Byte	N Byte	2 Byte

4.2 ID Number (Slave Address)

Range: 1~255.

Master instrument identifies slave controllers by the ID Number of the requested message. ID Number should be configuring in individual slave controller by setting parameter "IDNO" in operation LEVEL 3.

4.3 Function Code

Function Code	Contents		
03 (03H)	Reading multiple registers value from slave controller		
	(Max register count: 8)		
06 (06H)	Setting 1 register value to slave controller		
16 (10H)	Setting multiple registers value to slave controller.		
	(Max register count: 8)		

4.4 Data

Data depends on function code.

Request message from Master instrument is include "register address", "data count" and "setting data".

Response data from Slave controller is include "byte count", "data" and "abnormal code".

4.5 Error Check CRC

CRC16 generation polynomial: $X^{16} + X^{15} + X^2 + X^1$

CRC generation step is as below:

- (1). CRC is initialized as FFFFH
- ②. Calculate XOR with 1^{st} data and the low byte of CRC. This is assumed as Y(16bit).
- 3. Shift Y one bit to the right. This assumed as Y.
- (4). If a carry is generated at step 3, then calculate XOR with Y and "A001H", else jump to step 5.
- ⑤. Repeat step 3 and 4, until Y is shifting right 8 times.
- 6. Calculate XOR with next data and the low byte of Y. This is assumed as Y.
- 7. Repeat step 3 ~5.

- 8. Repeat step 3~5, until last data is processed.
- (9). Swap the low byte and high byte of Y.
- (10). CRC=Y

4.6 Abnormal Code

Abnormal Code	Contents
01 (01H)	Illegal function code (Non-existent function code)
02 (02H)	Illegal register address (Register address is out of range)
03 (03H)	Illegal data value (Data value is out of setting range)

4.7 Message example of RTU mode

4.7.1 Reading (Read PV from slave controller 1)

Request message from master instrument:

ID Number	Function Code	Register	Data Count	CRC
		Address		
(01H)	(03H)	(008AH)	(0001H)	(A5E0H)

Response data from slave controller in normal status (Assumed PV=100.0)

ID Number	Function Code	Byte Count	Data	CRC
(01H)	(03H)	(02H)	(03E8H)	(B8FAH)

Response from slave controller in abnormal status (Assumed as illegal data value)

ID Number	Function Code	Error Code	CRC
(01H)	(83H)	(03H)	(0131H)

¹ is set to the MSB of function code in abnormal status (83H).

4.7.2 Setting (Set SV = 10.0 to slave controller 1)

Request message from master instrument:

ID Number	Function Code	Register	Setting Data	CRC
		Address		
(01H)	(06H)	(0000H)	(0064H)	(8821H)

Response message from slave controller in normal status (When SV = 10.0)

ID Number	Function Code	Register	Setting Data	CRC
		Address		
(01H)	(06H)	(0000H)	(0064H)	(8821H)

The abnormal code (03H) is returned as contents of error.

Response from slave controller in abnormal status (Assumed as illegal data value)

ID Number	Function Code	Error Code	CRC	
(01H)	(86H)	(03H)	(0261H)	

1 is set to the MSB of function code in abnormal status (86H).

The abnormal code (03H) is returned as contents of error.

4.7.3 Setting (Set SV = 10.0 and OUTL=100.0 to slave controller 1)

Request message from master instrument:

ID	Function	Register	Data	Byte	Data1	Data2	CRC
Number	Code	Address	Count	Count			
(01H)	(10H)	(0000H)	(0002H)	(04H)	(0064H)	(03E8H)	(B2CEH)

Response message from slave controller in normal status (When SV = 10.0 and OUTL=100.0)

ID	Function	Register	Data	CRC
Number	Code	Address	Count	
(01H)	(10H)	(0000H)	(0002H)	(41C8H)

Response from slave controller in abnormal status (Assumed as illegal register address)

ID Number Function Code		Error Code	CRC
(01H)	(90H)	(02H)	(C001H)

1 is set to the MSB of function code in abnormal status (90H).

The abnormal code (02H) is returned as contents of error.

5 MODBUS ASCII Protocol

5.1 Message Configuration

Header	ID Number	(Function Code)	Data	LRC	Delimiter
(:)					(CR+LF)
1 Byte	2 Byte	2 Byte	2N Byte	2 Byte	2 Byte

5.2 ID Number(Slave Address)

Range: 1~255

Master instrument identifies slave controllers by the ID Number of the requested message. ID Number should be configuring in individual slave controller by setting parameter "IDNO" in operation LEVEL 3.

5.3 Function Code

Function Code	Contents			
03 (30H 33H)	Reading multiple registers value from slave controller			
	(Max register count: 8)			
06 (30H 36H)	Setting 1 register value to slave controller			
16 (31H 30H)	Setting multiple registers value to slave controller.			
	(Max register count: 8)			

5.4 Data

Data depends on function code.

Request message from Master instrument is include "register address", "data count" and "setting data".

Response data from Slave controller is include "byte count", "data" and "abnormal code".

5.5 Error Check LRC

LRC generation step is as below:

- ①. Convert all the messages to RTU mode (HEX code) •
- ②. Add all the values from "ID Number" to the end of "Data". This is assumed as Y(8Bit).
- 3. Calculate 2's complement with Y.
- 4. Convert Y to ASCII characters (16 bit)
- (5). LRC=Y

5.6 Abnormal Code

Abnormal Code	Contents
01 (30H 31H)	Illegal function code (Non-existent function code)
02 (30H 32H)	Illegal register address (Register address is out of range)
03 (30H 33H)	Illegal data value (Data value is out of setting range)

5.7 Message example of ASCII mode

• Reading (Read PV from slave controller 1)

Request message from master instrument:

Header	ID Number	Function	Register Address	Data Count	LRC	Delimiter
		Code				
(3AH)	(30H 31H)	(30H 33H)	(30H 30H 38H 41H)	(30H 30H 30H 31H)	(37H31H)	(0DH 0AH)

Response data from slave controller in normal status (Assumed PV=100.0)

Header	ID Number	Function	Byte Count	Data	LRC	Delimiter
		Code				
(3AH)	(30H 31H)	(30H 33H)	(30H32H)	(30H 33H 45H 38H)	(30H 46H)	(0DH 0AH)

Response from slave controller in abnormal status (Assumed as illegal data value)

Header	ID Number	Function	Error Code	LRC	Delimiter
		Code			
(3AH)	(30H 31H)	(38H 33H)	$(30H\ 33H)$	(37H 39H)	(0DH 0AH)

5.7.1 Setting (Set SV = 10.0 to slave controller 1)

Request message from master instrument:

Не	eader	ID Number	Function	Register Address	Data	LRC	Delimiter
			Code				
(3.	AH)	(30H 31H)	(30H 36H)	(30H 30H 30H 30H)	(30Н 30Н 36Н 34Н)	(39H35H)	(0DH 0AH)

Response message from slave controller in normal status (When SV = 10.0)

Header	ID Number	Function	Register Address	Data	LRC	Delimiter
		Code				
(3AH)	(30H 31H)	(30H 36H)	(30H 30H 30H 30H)	(30Н 30Н 36Н 34Н)	(39H35H)	(0DH 0AH)

Response from slave controller in abnormal status (Assumed as illegal data value)

Header	ID Number	Function	Error Code	LRC	Delimiter
		Code			
(3AH)	(30H 31H)	(38H 36H)	(30H 33H)	(37H 36H)	(0DH 0AH)

1 is set to the MSB of function code in abnormal status (86H).

The abnormal code (03H) is returned as contents of error.

5.7.2 Setting (Set SV = 10.0 and OUTL=100.0 to slave controller 1)

Request message from master instrument:

Header	ID Number	Function	Register Address	Data Count	BYTE	Data1
		Code			Count	
(3AH)	(30H 31H)	(31H 30H)	(30H 30H 30H 30H)	(30H 30H 30H 32H)	(30H 34H)	(30H 30H 36H 34H)

Data2	LRC	Delimiter
(30H 33H 45H 38H)	(39H 41H)	(0DH 0AH)

Response message from slave controller in normal status (When SV = 10.0 and OUTL=100.0)

Header	ID Number	Function	Register Address	Data Count	LRC	Delimiter
		Code				
(3AH)	(30H 31H)	(31H 30H)	(30H 30H 30H 30H)	(30H 30H 30H 32H)	(45H 44H)	(0DH 0AH)

Response from slave controller in abnormal status (Assumed as illegal register address)

Header	ID Number	Function	Error Code	LRC	Delimiter
		Code			
(3AH)	(30H 31H)	(39H 30H)	(30H 32H)	(36H 44H)	(0DH 0AH)

6 TAIE Protocol

6.1 Message Configuration

Master → Slave (7 Bytes):

Command	ID Number	Register	Data	Check Sum
		Address		
1 Byte	1 Byte	2 Byte	2 Byte	1 Byte

Master **←** Slave (8 Bytes)

Header	Command	ID Number	Register	Data	Check Sum
(07H)	(4DH)		Address		
1 Byte	1 Byte	1 Byte	2 Byte	2 Byte	1 Byte

6.2 Command

Command	Contents		
R (52H)	Reading 1 register value from slave controller		
M (4DH)	Modify 1 register value in RAM.		
	(Data are not maintained after power off)		
W (57H)	Write 1 register value in both RAM and EEPROM.		
	(Data are maintained after power off)		

6.3 ID Number

Range: 1~255.

Master instrument identifies slave controllers by the ID Number of the requested message. ID Number should be configuring in individual slave controller by setting parameter "IDNO" in operation LEVEL 3.

6.4 Register Address

Register Address is including register address High byte and Low byte.

Totally, there are 2 bytes.

For detail, please check with Register Map(Page:12)

6.5 Data

Data is including setting data High byte and Low byte.

Totally, there are 2 bytes.

6.6 Check Sum

Add all the values from "Command" to the end of "Data".

The result is Check Sum (1 byte).

EX : 52H + 01H + 00H + 8AH + 00H + 00H = DDH

6.7 Message example of TAIE Protocol

6.7.1 Read (Read PV from slave controller 1)

Request message from master instrument:

Command	ID Number	Register	Data	Check Sum
		Address		
(52H)	(01H)	(008AH)	(0000H)	(DDH)

Response data from slave controller (Assumed PV=100.0)

Header	Command	ID Number	Register	Data	Check Sum
			Address		
(07H)	(4DH)	(01H)	(008AH)	(03E8H)	(C3H)

6.7.2 Modify (Modify SV = 10.0 to slave controller 1)

Request message from master instrument:

Command	ID Number	Register	Data	Check Sum
		Address		
(4DH)	(01H)	(0000H)	(0064H)	(B2H)

6.7.3 Write (Write SV = 100.0 to slave controller 1)

Request message from master instrument:

Command	ID Number	Register	Data	Check Sum
		Address		
(57H)	(01H)	(0000H)	(03E8H)	(43H)

7 Register Map

Parameters	Reg	ister Address	MODBUS	Cotting Dongs
rarameters	HEX	DECIMAL	Function Code	Setting Range
SV	0000	000	03/06/10H	
Set Point	0000	000	03/00/10H	
OUTL	0001	001	03/06/10H	0 ~ 1000
Output Limit	0001	001	03/00/1011	0 1 1000
AT	0002	002	03/06/10H	0000H=NO
Auto Tuning	0002	002	03/00/1011	0001H=YES
AL1	0003	003	03/06/10H	
Alarm 1 set value	0003	003	03/00/1011	
AL2	0004	004	03/06/10H	
Alarm 2 set value	0001	001	03/00/1011	
AL3	0005	005	03/06/10H	
Alarm 3 set value	0003	003	03/00/1011	
PTN	0006	006	03/06/10H	0 ~ 2
Program Pattern	0000	000	03/00/1011	0 2
SEG				
Program Segment	0007H	007	03H	
Display				
TIMR				
Program Countdown	0008	008	03H	
Display				
SV_1				
Set Point of Seg.1	0009	009	03/06/10H	
(Pattern 1)				
TM_1				
Run Time of Seg.1	000A	010	03/06/10H	
(Pattern 1)				
OUT1				
Output Limit of Seg.1	000B	011	03/06/10H	
(Pattern 1)				
SV_2				
Set Point of Seg.2	000C	012	03/06/10H	
(Pattern 1)				

Parameters	Reg	ister Address	MODBUS	Setting Range
rarameters	HEX	DECIMAL	Function Code	Setting Kange
TM_2				
Run Time of Seg.2	000D	013	03/06/10H	
(Pattern 1)				
OUT2				
Output Limit of Seg.2	000E	014	03/06/10H	
(Pattern 1)				
SV_3				
Set Point of Seg.3	000F	015	03/06/10H	
(Pattern 1)				
TM_3				
Run Time of Seg.3	0010	016	03/06/10H	
(Pattern 1)				
OUT3				
Output Limit of Seg.3	0011	017	03/06/10H	
(Pattern 1)				
SV_4				
Set Point of Seg.4	0012	018	03/06/10H	
(Pattern 1)				
TM_4				
Run Time of Seg.4	0013	019	03/06/10H	
(Pattern 1)				
OUT4				
Output Limit of Seg.4	0014	020	03/06/10H	
(Pattern 1)				
SV_5				
Set Point of Seg.5	0015	021	03/06/10H	
(Pattern 1)				
TM_5				
Run Time of Seg.5	0016	022	03/06/10H	
(Pattern 1)				
OUT5				
Output Limit of Seg.5	0017	023	03/06/10H	
(Pattern 1)				
SV_6				
Set Point of Seg.6	0018	024	03/06/10H	
(Pattern 1)				

Parameters	Regi	ister Address	MODBUS	Setting Range
rarameters	HEX	DECIMAL	Function Code	Setting Kange
TM_6				
Run Time of Seg.6	0019	025	03/06/10H	
(Pattern 1)				
OUT6				
Output Limit of Seg.6	001A	026	03/06/10H	
(Pattern 1)				
SV_7				
Set Point of Seg.7	001B	027	03/06/10H	
(Pattern 1)				
TM_7				
Run Time of Seg.7	001C	028	03/06/10H	
(Pattern 1)				
OUT7				
Output Limit of Seg.7	001D	029	03/06/10H	
(Pattern 1)				
SV_8				
Set Point of Seg.8	001E	030	03/06/10H	
(Pattern 1)				
TM_8				
Run Time of Seg.8	001F	031	03/06/10H	
(Pattern 1)				
OUT8				
Output Limit of Seg.8	0020	032	03/06/10H	
(Pattern 1)				
SV_12				
Set Point of Seg.1	0021	033	03/06/10H	
(Pattern 2)				
TM_12				
Run Time of Seg.1	0022	034	03/06/10H	
(Pattern 2)				
OUT12				
Output Limit of Seg.1	0023	035	03/06/10H	
(Pattern 2)				
SV_22				
Set Point of Seg.2	0024	036	03/06/10H	
(Pattern 2)				

Parameters	Reg	ister Address	MODBUS	Setting Range
rarameters	HEX	DECIMAL	Function Code	Setting Kange
TM_22				
Run Time of Seg.2	0025	037	03/06/10H	
(Pattern 2)				
OUT22				
Output Limit of Seg.2	0026	038	03/06/10H	
(Pattern 2)				
SV_32				
Set Point of Seg.3	0027	039	03/06/10H	
(Pattern 2)				
TM_32				
Run Time of Seg.3	0028	040	03/06/10H	
(Pattern 2)				
OUT32				
Output Limit of Seg.3	0029	041	03/06/10H	
(Pattern 2)				
SV_42				
Set Point of Seg.4	002A	042	03/06/10H	
(Pattern 2)				
TM_42				
Run Time of Seg.4	002B	043	03/06/10H	
(Pattern 2)				
OUT42				
Output Limit of Seg.4	002C	044	03/06/10H	
(Pattern 2)				
SV_52				
Set Point of Seg.5	002D	045	03/06/10H	
(Pattern 2)				
TM_52				
Run Time of Seg.5	002E	046	03/06/10H	
(Pattern 2)				
OUT52				
Output Limit of Seg.5	002F	047	03/06/10H	
(Pattern 2)				
SV_62				
Set Point of Seg.6	0030	048	03/06/10H	
(Pattern 2)				

Parameters	Regi	ister Address	MODBUS	Setting Range
rarameters	HEX	DECIMAL	Function Code	Setting Kange
TM_62				
Run Time of Seg.6	0031	049	03/06/10H	
(Pattern 2)				
OUT62				
Output Limit of Seg.6	0032	050	03/06/10H	
(Pattern 2)				
SV_72				
Set Point of Seg.7	0033	051	03/06/10H	
(Pattern 2)				
TM_72				
Run Time of Seg.7	0034	052	03/06/10H	
(Pattern 2)				
OUT72				
Output Limit of Seg.7	0035	053	03/06/10H	
(Pattern 2)				
SV_82				
Set Point of Seg.8	0036	054	03/06/10H	
(Pattern 2)				
TM_82				
Run Time of Seg.8	0037	055	03/06/10H	
(Pattern 2)				
OUT82				
Output Limit of Seg.8	0038	056	03/06/10H	
(Pattern 2)				
P1	0039	057	03/06/10H	0~2000
OUT1 Proportional Band	0027	057	03/ 00/ 1011	0 2000
I1	003A	058	03/06/10H	0~3600
OUT1 Integral Time	******			
D1	003B	059	03/06/10H	0~900
OUT1 Derivative Time	303B		35/00/1011	
DB1	003C	060	03/06/10H	0~1000
Dead-band Time		1 5 5		
ATVL	003D	061	03/06/10H	
Auto Tuning Offset				
CYT1	003E	062	03/06/10H	0~150
OUT1 Cycle Time			_	

Parameters	Regi	ster Address	MODBUS	Setting Range
1 at affecters	HEX	DECIMAL	Function Code	Setting Kange
HYS1	003F	063	03/06/10H	0~1000
OUT1 Hysteresis	003F	003	03/00/10H	0~1000
P2	0040	064	03/06/10H	0~2000
OUT2 Proportional Band	0040	004	03/00/1011	0-2000
12	0041	065	03/06/10H	0~3600
OUT2 Integral Time				
D2	0042	066	03/06/10H	0~900
OUT2 Derivative Time				
CYT2	0043	067	03/06/10H	0~150
OUT2 Cycle Time				
HYS2	0044	068	03/06/10H	0~1000
OUT2 Hysteresis				
GAP1	0045	069	03/06/10H	
OUT1 Control Gap GAP2				
OUT2 Control Gap	0046	070	03/06/10H	
LCK	0047	071	03/06/10H	0000H = 0000
Function Lock	0047	071	03/00/1011	1111H = 1111
Tunetion Book				0100H = 0100
				0110H = 0110
				0001H = 0001
				0101H = 0101
INP1	0048	072	03/06/10H	0000H = K1
Input Type Selection				0001H = K2
				0002H = K3
				0003H = K4
				0004H = K5
				0005H = K6
				0006H = J1
				0007H = J2
				0008H = J3
				0009H = J4
				000AH = J5
				000BH = J6
				000CH = R1
				000DH = R2

Do wow of our	Register Address		MODBUS	Cotting Dongs
Parameters	HEX	DECIMAL	Function Code	Setting Range
INP1	0048	072	03/06/10H	000EH = S1
Input Type Selection				000FH = S2
				0010H = B1
				0011H = E1
				0012H = E2
				0013H = N1
				0014H = N2
				0015H = T1
				0016H = T2
				0017H = T3
				0018H = W1
				0019H = W2
				001AH = PL1
				001BH = PL2
				001CH = U1
				001DH = U2
				001EH = U3
				001FH = L1
				0020H = L2
				0021H = JP1
				0022H = JP2
				0023H = JP3
				0024H = JP4
				0025H = JP5
				0026H = JP6
				0027H = DP1
				0028H = DP2
				0029H = DP3
				002AH = DP4
				002BH = DP5
				002CH = DP6
				002DH = JP.1
				002EH = JP.2
				002FH = JP.3
				0030H = JP.4
				0031H = JP.5

Parameters	Reg	ister Address	MODBUS	C-44' D
Parameters	HEX	DECIMAL	Function Code	Setting Range
INP1	0048	072	03/06/10H	0032H = JP.6
Input Type Selection				0033H = AN1
				0034H = AN2
				0035H = AN3
				0036H = AN4
				0037H = AN5
ANL1				
Linear Input Zero	0049	073	03/06/10H	
Calibration				
ANH1				
Linear Input Span	004A	074	03/06/10H	
Calibration				
DP				0000H = 0000
Decimal Point Position	004B	075	03/06/10H	0001H = 000.0
	001B	075	03/00/1011	0002H = 00.00
				0003H = 0.000
LSPL	004C	076	03/06/10H	
Lower Set Point Limit	00.0	0,0	00/00/1011	
USPL	004D	077	03/06/10H	
Upper Set Point Limit	00.2	9,7	00/00/1011	
ANL2				
Remote Input Zero	004E	078	03/06/10H	
Calibration				
ANH2				
Linear Input Span	004F	079	03/06/10H	
Calibration				
ALD1	0050	080	03/06/10H	0~19
Alarm mode for AL1				
ALT1	0051	081	03/06/10H	
Alarm time for AL1				
ALD2	0052	082	03/06/10H	0~19
Alarm mode for AL2				
ALT2	0053	083	03/06/10H	
Alarm time for AL2				
ALD3	0054	084	03/06/10H	0~19
Alarm mode for AL3				

Parameters	Regi	ster Address	MODBUS	Setting Range
rarameters	HEX	DECIMAL	Function Code	Setting Range
ALT3	0055	085	03/06/10H	
Alarm time for AL3	0033	083	03/00/1011	
HYSA	0056	086	03/06/10H	0000H=0000
Hysteresis for all Alarms				0001H=0000
				0010H=0010
				0011H=0011
				0100H=0100
				0101H=0101
				0110H=0110
				0111H=0111
				1000H=1000
				1001H=1001
				1010H=1010
				1011H=1011
				1100H=1100
				1101H=1101
				1110H=1110
				1111H=1111
CLO1	0057	087	03/06/10H	
OUT1 Lower Calibration	0037	007	03/00/1011	
СНО1	0058	088	03/06/10H	
OUT1 Upper Calibration	0030	000	03/00/1011	
CLO2	0059	089	03/06/10H	
OUT1 Lower Calibration	0037	007	03/00/1011	
СНО2	005A	090	03/06/10H	
OUT1 Upper Calibration	003A	0,0	03/00/1011	
CLO3	005B	091	03/06/10H	
TRS Lower Calibration	003В	071	03/00/1011	
СНОЗ	005C	092	03/06/10H	
TRS Upper Calibration	0050	092	03/00/1011	
RUCY				
Full run time of motor	005D	093	03/06/10H	
valve				
WAIT				
Full run time of	005E	094	03/06/10H	
proportional motor valve				

Parameters	Reg	ister Address	MODBUS	Setting Range
rarameters	HEX	DECIMAL	Function Code	Setting Range
SETA	005F	095	03/06/10H	
PSL Protocol Selection	0060	096	03Н	0~2
BITS Communication Bits	0061	097	03Н	0~3
IDNO ID Number	0062	098	03Н	0~255
BAUD Baud rate	0063	099	03Н	0~4
SVOS SV Compensation	0064	100	03/06/10H	
PVOS PV Compensation	0065	101	03/06/10H	
UNIT Unit of PV and SV	0066	102	03/06/10H	0000H=C 0001H=F 0002H=A
PVFT PV Filter	0067	103	03/06/10H	0 ~ 1000
CASC	0068	104	03/06/10H	
OUD Heating / Cooling selection	0069	105	03/06/10H	0000H=HEAT 0001H=COOL
OPAD Control Algorithm	006A	106	03/06/10H	0000H=PID 0001H=FUZZY
HZ Power Frequency	006B	107	03/06/10H	0000H=60HZ 0001H=50HZ
SET1 Hide/ Display parameter	006C	108	03/06/10H	0000H=0000 0001H=0000 0010H=0010 0011H=0011 0100H=0100
				0100H=0100 0101H=0101 0110H=0110 0111H=0111

Regi	ster Address	MODBUS	Setting Range
HEX	DECIMAL	Function Code	Setting Kange
006C	108	03/06/10H	1000H=1000
			1001H=1001
			1010H=1010
			1011H=1011
			1100H=1100
			1101H=1101
			1110H=1110
			1111H=1111
006D	109	03/06/10H	Same with SET1
0002	10)	03/00/1011	Sume with SETT
006E	110	03/06/10H	Same with SET1
006F	111	03/06/10H	Same with SET1
0070	112	03/06/10H	Same with SET1
0071	113	03/06/10H	Same with SET1
0072	114	03/06/10H	Same with SET1
0073	115	03/06/10H	Same with SET1
0074	116	03/06/10H	Same with SET1
0075	117	03/06/10H	Same with SET1
0076	118	03/06/10H	0~2
0077	119	03/06/10H	0 ~ 5
	006C 006C 006D 006E 006F 0070 0071 0072 0073 0074 0075 0076	006C 108 006D 109 006E 110 006F 111 0070 112 0071 113 0072 114 0073 115 0074 116 0075 117 0076 118	HEX DECIMAL Function Code 006C 108 03/06/10H 006D 109 03/06/10H 006E 110 03/06/10H 006F 111 03/06/10H 0070 112 03/06/10H 0071 113 03/06/10H 0072 114 03/06/10H 0073 115 03/06/10H 0074 116 03/06/10H 0075 117 03/06/10H 0076 118 03/06/10H

Parameters	Regi	ster Address	MODBUS Sotting D	Catting Dongs
Parameters	HEX	DECIMAL	Function Code	Setting Range
VER	0086	134	03H	104
Firmware Version	0086	134	USH	104
OUT%	0087	135	03H	0~1000
Output percentage	0087	133	OSH	0~1000
OBIT	0088	136	03H	0000 0000 0000 0000
Controller Information				2 ¹⁵ ~ 2 ⁰
Bit				2 ¹⁵ : Message nnn2
				2 ¹⁴ : Message UUU2
				2 ¹³ : Message nnn1
				2 ¹² : Message UUU1
				2 ¹¹ : Message IN2E
				2 ¹⁰ : Message CJCE
				29 : Message ADCF
				28 : Message IN1E
				2 ⁷ : MAN LED
				2 ⁶ : PRO LED
				2 ⁵ : AL3 LED
				2 ⁴ : AL2 LED
				2 ³ : AL1 LED
				2 ² : AT LED
				2¹ : OUT2 LED
				2º : OUT1 LED
CV	0000	127	0311	0.000
CT Current Value	0089	137	03H	0~999
PV	000 4	120	0211	1000,0000
Process Value	008A	138	03H	-1999~9999

