Basic Topology

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1 Introduction

1.1 Abstract spaces

We ask for a set X and for each point x of X a nonempty collection of subsets of X, called neighbourhoods of x. These neighbourhoods are required to satisfy four axioms

- 1. *x* lies in each of its neighbourhoods
- 2. The intersection of two neighbourhoods of *x* is itself a neighbourhood of *x*
- 3. If N is a neighbourhood of x and if U is a subset of X which contains N, then U is a neighbourhood of x
- 4. If N is a neighbourhood of x and if \mathring{N} denotes the set $\{z \in N \mid N \text{ is a neighbourhood of } z\}$, then \mathring{N} is a neighbourhood of x. (The set \mathring{N} is called the **interior** of N)

This whole structure is called a **topological space**. The assignment of a collection of neighbourhoods satisfying axioms $(1) \to (4)$ to each point $x \in X$ is called a **topology** on the set X.

Let X and Y be topological spaces. A function $f: X \to Y$ is **continuous** if for each point $x \in X$ and each neighbourhood N of f(x) in Y the set $f^{-1}(N)$ is a neighbourhood of x in X. A function $h: X \to Y$ is called a **homeomorphism** if it is one-one, onto, continuous and has a continuous inverse. When such a function exists, X and Y are called **homeomorphic** spaces

Example 1.1. 1. Let X be a topological space and let Y be a subset of X. We can define a topology on Y as follows. Given a point $y \in Y$ take the collection of its neighbourhoods in the topological space X and intersect each of these neighbourhood with Y. The resulting sets are the neighbourhoods of y in Y. We say that Y has the **subspace topology**.

Definition 1.1. A **surface** is a topological space in which each point has a neighbourhood homeomorphic to the plane, and for which any two distinct points possess disjoint neighbourhoods

2 Continuity

2.1 Open and closed sets

Let *X* be a topological space and call a subset *O* of *X* **open** if it is a neighbourhood of each of its points. The union of any collection of open sets is open by axiom (3) and the intersection of *finite* number of open sets is open by axiom (2).

Suppose we have a set X together with a nonempty collection of subsets of X, which we call open sets, such that any union of open sets is itself open, any finite intersection of open sets is open, and both the whole set and the empty set are open. Given a point x of X, we shall call a subset N of x a **neighbourhood of** x if we can find an open set X s.t. $X \in X$ if X if we can find an open set X s.t. X if X

We claim that this definition of neighbourhood makes X into a topological space.

Verification for axiom (4). Suppose N is a neighbourhood of x and let \mathring{N} denote the set of points z s.t. N is a neighbourhood of z. Choose an open set O s.t. $x \in O \subseteq N$. Now O, being open, is a neighbourhood of each of its points, so O is contained in \mathring{N} .

Definition 2.1. A **topology** on a set X is a nonempty collection of subsets of X, called open sets, such that any union of open sets is open, any finite intersection of open sets is open, and both X and the empty set are open. A set together with a topology on it is called a **topological space**

The open sets of the "usual" topology on \mathbb{R}^n are characterized as follows. A set U is open if given $x \in U$ we can always find a positive real number ϵ s.t. the ball with centre x and radius ϵ lies entirely in U.

For **discrete topology** on X, every subset of X is an open set and we call X discrete space.

A subset of a topological space is **closed** if its complement is open.

Consider the set A on \mathbb{R}^2 whose points x,y satisfy $x\geq 0$ and y>0. This set is neither closed nor open. Take the space X whose points are those points $(x,y)\in\mathbb{R}^2$ s.t. $x\geq 1$ or $x\leq -1$ and whose topology is induced from \mathbb{R}^2 . The subsets of X consisting of those points with positive first coordinate is both open and closed.

Let A be a subset of a topological space X and call a point p of X a **limit point** (or accumulation point) of A if every neighbourhood of p contains at least one point of $A - \{p\}$

Example 2.1. 1. Take X to be the real line \mathbb{R} , and let A consist of the

- points 1/n, n = 1, 2, ... Then A has exactly one limit point, namely the origin
- 2. X the real line, take A = [0, 1). Then each point of A is a limit point of A, and in addition 1 is a limit point
- 3. Let $X \subseteq \mathbb{R}^3$ and let A consist of those points all of whose coordinates are rational. Then every point of \mathbb{R}^3 is a limit point of A
- 4. Let $A \subseteq \mathbb{R}^3$ be the set of points which have integer coordinates. Then A does not have any limit points
- 5. Take *X* to be the set of all real numebers with the so called **finite-complement topology**. Here a set is open if its complement is finite or all of *X*. If we now take *A* to be an infinite subset of *X* (say the set of all integers), then every point of *X* is a limit point of *A*. On the other hand a finite subset of *X* has no limit points in this topology

Theorem 2.2. A set is closed if and only if it contains all its limit points

Proof. If A is closed, its complement X - A is open. Since an open set is a neighbourhood of each of its points, no point of X - A can be a limit point of A.

Suppose A contains all its limit point and let $x \in X - A$. Since x is not a limit point of A, we can find a neighbourhood N of x which does not meet A. So N is inside X - A, showing X - A to be a neighbourhood of each of its points and consequently open. Therefore A is closed.

The union of A and all its limit points is called the **closure** of A and is written \overline{A}

Theorem 2.3. The closure of A is the smallest closed set containing A, in other words the intersection of all closed sets which contain A

Proof. For if $x \in X-A$, we can find an open neighbourhood U of x which does not contain any points of A. Since an open set is a neighbourhood of each of its points, U cannot contain any of the limit points of A. Therefore we have an open set U s.t. $x \in U \subseteq X-\overline{A}$. Consequently $X-\overline{A}$ is a neighbourhood of each of its points and must be open.

Now let B be a closed set which contains A. Then every limit point of A is a limit point of B and therefore must lie in B since B is closed. This gives $\overline{A} \subseteq B$

Corollary 2.4. A set is closed if and only if it is equal to its closure

A set whose closure is the whole space is said to be **dense** in the space

The **interior** of a set, usually written \mathring{A} , is the union of all open sets contained in A. A point lies in \mathring{A} if and only if it's a neighbourhood of A.

We define the **frontier** of *A* to be the $\overline{A} \cap \overline{X - A}$.

Suppose we have a topology on a set X, and a collection β of open set s.t. every open set is a union of members of β . Then β is called a **base** for the topology and elements of β are called **basic open sets**. An equivalent formulation is to ask that given a point $x \in X$, and a neighbourhood N of x, there is always an element B of β s.t. $x \in B \subseteq N$.

Theorem 2.5. Let β be a nonempty collection of subsets of a set X. If the intersection of any finite number of members of β is always in β , and if $\bigcup \beta = X$, then β is a base for a topology on X

2.1.1 Exercise

Exercise 2.1.1. If *A*is a dense subset of a space *X*, and if *O* is open in *X*, show that $O \subseteq \overline{A - O}$

Proof. Suppose $O \nsubseteq \overline{A \cap O}$, then there is $x \in O$ and $x \notin \overline{A \cap O}$. Hence there is a open set $x \in O_x$ s.t.

$$\overline{A \cap O} \cap (O_x - \{x\}) = \emptyset$$

But as $x \notin \overline{A \cap O}$, we have

$$\overline{A\cap O}\cap O_x=\emptyset$$

and consequently, $A\cap O\cap O_x=\emptyset$. But then, setting $B=O\cap O_x$, B is open, but $A\cap B=\emptyset$

Exercise 2.1.2. Show that the frontier of a set always contains the frontier of its interior. How does the frontier of $A \cup B$ relate to the frontiers of A and B

Proof. Let (X, τ) be a topological space, and let $A \subset X$. Let $x \in \operatorname{Fr} A^{\operatorname{o}}$. Then

$$x \in \overline{A^{o}} \cap \overline{X - A^{o}} = \overline{A^{o}} \cup \overline{(X - A) \cup (X - A^{o})}$$

Now if $x \in \overline{A^{\circ}}$ and $x \in \overline{X - A}$, we are done. So suppose that $x \in \overline{A^{\circ}}$ and $x \in \overline{A - A^{\circ}}$. But then $x \in \overline{A^{\circ}} \cup \overline{A - A^{\circ}} = \overline{A}$.

$$\operatorname{Fr}(A \cup B) \subset \operatorname{Fr}(A) \cup \operatorname{Fr}(B) \qquad \qquad \square$$

Exercise 2.1.3. Let X be the set of real numbers and β the family of all subsets of the form $\{x \mid a \leq x < b \text{ where } a < b\}$. Prove that β is a base for a topology on X and that in this topology each member of β is both open and closed. Show that this topology does not have a countable base.

Proof. Suppose this topology has a countable base $\{B_n\}_{n\in\omega}$. Define the function $f:\mathbb{R}\to\mathbb{N}$ as follows: for each $x\in\mathbb{R}$, let f(x)=n s.t. $B_n\subset[x,1+x)$ Suppose x< y and f(x)=f(y). Hence $[x,x+1)\subset[y,y+1)$, a contradiction

Exercise 2.1.4. Show that if X has a countable base for its topology, then X contains a countable dense subset. A space whose topology has a countable base is called a **second countable** space. A space which contains a countable dense subset is said to be **separable**.

Proof. Let $\{B_n\}_{n\in\omega}$ be a countable base for τ . By the Axiom of Choice, let A be the elements of elements $\{a_i\}_{i\in\omega}$ s.t. $a_i\in B_i$. The claim is that $\overline{A}=X$ Let $\mathcal{O}\in\tau$. Then $\mathcal{O}=\bigcup_i B_i$. Now, as $A=\bigcup_i x_i$, we have $A\cap\mathcal{O}\neq\emptyset$. \square

2.2 Continuous functions

Theorem 2.6. A function from X to Y is continuous if and only if the inverse image of each open set of Y is open in X

A continuous function is often called a **map**

Theorem 2.7. *The composition of two maps is a map*

Theorem 2.8. Suppose $f: X \to Y$ is continuous, and let $A \subseteq X$ have the subspace topology. Then the restriction $f|A:A \to Y$ is continuous

Theorem 2.9. *The following are equivalent*

- 1. $f: X \to Y$ is a map
- 2. If β is a base for the topology of Y, the inverse image of every member of β is open in X
- 3. $f(\overline{A}) \subseteq f(A)$ for any subset A of X
- 4. $f^{-1}(B) \subseteq f^{-1}(\overline{B})$ for any subset B of Y
- 5. The inverse image of each closed set in Y is closed in X

Proof. $(2) \to (3)$. $f(A) \subseteq \overline{f(A)}$. If $x \in \overline{A} - A$ and $f(x) \notin f(A)$. If N is a neighbourhood of f(x) we can find a basic open set B in β s.t. $f(x) \in B \subseteq N$. $f^{-1}(B)$ is open and is therefore a neighbourhood of x. But x is a limit

point of A, which means that $f^{-1}(B)$ must contain a point of A. So B, and therefore N, contains a point of f(A).

$$(3) \to (4). \ \underline{f(\overline{f^{-1}(B)})} \subseteq ff^{-1}(\overline{B}) \Leftrightarrow f(\overline{f^{-1}(B)}) \subseteq \overline{ff^{-1}(B)}$$

$$(4) \to (5). \ \overline{f^{-1}(B)} \subseteq f^{-1}(\overline{B}) = f^{-1}(B).$$

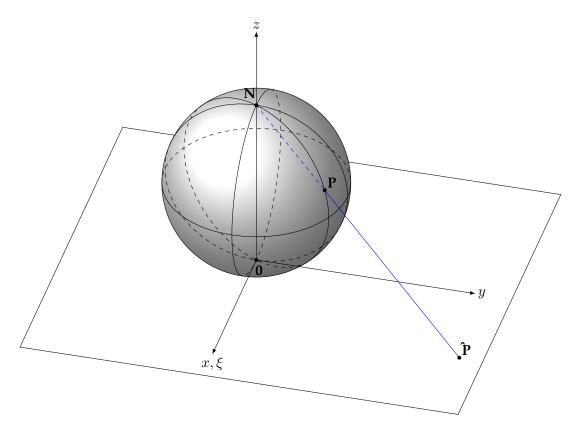
Example 2.2. Let C denote the unit circle in the complex plane, taken with the subspace topology, and give the interval [0,1) the induced topology from the real line. Define $f:[0,1)\to C$ by $f(x)=e^{2\pi ix}$. f is continuous. We can take the set of all open segments of the circle as a base for the topology on C. Now if S is such a segment and if S does not contain the complex number 1, then $f^{-1}(S)$ is just an open interval of the form (a,b) where 0< a< b< 1. If S does happen to contain 1, then $f^{-1}(S)$ has the form $[0,a)\cup(b,1)$, where 0< a< b< 1. This is open in [0,1) because it is the intersection of the open set $(-1,a)\cup(b,1)$ of the real line with [0,1).

However its inverse is not continuous. Take O to be the interval [0,1/2); this is open in [0,1) but its image is not open in C

A **homeomorphism** $h:X\to Y$ is a function which is continuous, one-one, and onto, and which has continuous inverse. From Theorem 2.6 we see that a set O is open iff h(O) is open. Therefore, h induces a one-one onto correspondence between the topologies of X and Y

Example 2.3. Let S^n denote the n-dimensional sphere whose points are those of \mathbb{R}^{n+1} which have distance 1 from the origin, taken with the subspace topology. We claim that removing a single point from S^n gives a space homeomorphic to \mathbb{R}^n .

Which point we remove is irrelevant because we can rotate any point of S^n into any other; for convenience we choose to remove the point $p=(0,\dots,0,1)$. Now the set of points of \mathbb{R}^{n+1} , which have zero as their final coordinate, when given the induced topology, is clearly homeomorphic to \mathbb{R}^n . We define a function $h:S^n-\{p\}\to\mathbb{E}$, called **stereographic projection** as follows. If $x\in S^n-\{p\}$, then h(x) is the point of intersection of \mathbb{R}^n and the straight line determined by x and p



By a **disc** we mean any space homeomorphic to the closed unit disc D in \mathbb{R}^2 . C stands for the unit circle. If A is a disc, and if $h:A\to D$ is a homeomorphism, then $h^{-1}(C)$ is called the **boundary** of A and is written ∂A .

Lemma 2.10. Any homeomorphism from the boundary of a disc to itself can be extended to a homeomorphism of the whole disc

Proof. Let A be a disc and choose a homeomorphism $h:A\to D$. Given a homeomorphism $g:\partial A\to\partial A$, we can easily extend $hgh^{-1}:C\to C$ to a homeomorphism of all of Das follows. Send 0 to 0, and if $x\in D-\{0\}$ send x to the point $\|x\|\,hgh^{-1}(x/\|x\|)$. In other words extend conically

Lemma 2.11. Let A and B be discs which intersect along their boundaries in an arc. Then $A \cup B$ is a disc.

Proof. Let γ denote the arc $A \cap B$, and use α , β for the complementary arcs in the boundaries of A and B. We construct a homeomorphism from $A \cup B$ to D with the aid of lemma 2.10

The y axis in the plain divides up D as the union of two discs D_1 and D_2 . We label the three arcs which together make up the boundaries of D_1 and D_2 as α' , β' and γ' . Both α and α' are homeomorphic to the clsoed unit interval [0,1], so we can find a homeomorphism from α to α' . We first extend this over γ , to give a homeomorphism from $\alpha \cup \gamma$ to $\alpha' \cup \gamma'$; then over A to give a homeomorphism from A to D_1 , which take γ to γ' , using lemma 2.10.

2.2.1 Exercise

Exercise 2.2.1. If $f : \mathbb{R} \to \mathbb{R}$ is a map, show that the set of points which are left fixed by f is a closed subset of \mathbb{R} . If g is a continuous real-valued function on X show that the set $\{x \mid g(x) = 0\}$ is closed

Proof. Define
$$f_0(x) = f(x) - x$$

Exercise 2.2.2. Let $f: \mathbb{R} \to \mathbb{R}$ be a map and define its graph $\Gamma_f: \mathbb{R} \to \mathbb{R}^2$ by $\Gamma_f(x) = (x, f(x))$. Show that Γ_f is continuous and that its image (taken with the topology induced from \mathbb{R}^2) is homeomorphic to \mathbb{R}

Proof. The function $p_1: \operatorname{im}\Gamma_f \to \mathbb{E}$ defined by $(x,f(x)\mapsto x)$ is the desired homeomorphism \qed

Exercise 2.2.3. What topology must *X* have if every real-valued function defined on *X* is continuous

Proof. Discrete topology. It suffices to show points in X are open Fix $x \in X$ and define $f: X \to \mathbb{R}$ by

$$f(x) = \begin{cases} f(x) = 0 \\ f(y) = 1 \quad y \neq x \end{cases}$$

Then
$$f^{-1}((-0.5, 0.5)) = \{x\}$$

Exercise 2.2.4. An **open map** is one which sends open sets to open sets: a **closed map** takes closed sets to closed sets. Which of the following maps are open or closed

- 1. The exponential map $x\mapsto e^{ix}$ from the real line to the circle
- 2. The folding map $f: \mathbb{R}^2 \to \mathbb{R}^2$ given by $(x, y) \mapsto (x, |y|)$
- 3. The map which winds the plane three times on itself given in terms of complex numbers, by $z\mapsto z^3$

Proof. 1.

- 2. not open. closed.
- 3. open. closed

2.3 A space-filling curve

2.4 The Tietze extension theorem

Let X be a topological space and A a subspace of X. Given a real-valued continuous function defined on A, it is natural to ask whether or not we can always extend it to all of X.

Definition 2.12. A **metric** or **distance function** on a set X is a real-valued function d defined on the cartesian product $X \times X$ s.t. for all $x, y, z \in X$

- 1. $d(x,y) \ge 0$ with equality iff x = y
- 2. d(x, y) = d(y, x)
- 3. $d(x,y) + d(y,z) \ge d(x,z)$

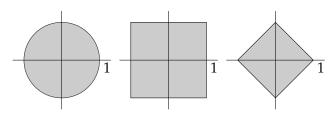
A set together with a metric on it is called a metric space

A metric on a set gives rise to a topology on the set as follows. Let d be a metric on the set X. Given $x \in X$, the set $\{y \in X \mid d(x,y)\} \le \epsilon$ is called the **ball of radius** ϵ , or ϵ -ball, centered at the point x, and is denoted by $B(x,\epsilon)$. We define a subset O of X to be **open** if given $x \in O$ we can find a positive real number ϵ s.t. $B(x,\epsilon) \subset O$.

Different metrics on a set may give the same topology. For example, we can make the underlying set of points of euclidean n-space into a metric space in three different ways as follows. Write $\mathbf{x}=(x_1,\dots,x_n)\in\mathbb{R}^n$, define:

- 1. $d_1(\mathbf{x}, \mathbf{y}) = \sqrt{(x_1 y_1)^2 + \dots + (x_n y_n)^2}$
- 2. $d_2(\mathbf{x}, \mathbf{y}) = \max_{1 \le i \le n} |x_i y_i|$
- 3. $d_3(\mathbf{x}, \mathbf{y}) = |x_1 y_1| + \dots + |x_n y_n|$

Following shows the ball of radius 1, centered at the origin for each of these three metrics when n=2.



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To see that d_1 and d_2 give rise to the same topology, we note that inside any disc we can find a square, and conversely inside a square we can find a disc.

Given two distinct points in a metric space, we can always find disjoint open sets containing them. For if $d(x,y)=\delta>0$, set $U=\{z\in X\mid d(x,z)<\delta/2\}$ and $V=\{z\in X\mid d(y,z)\leq\delta/2\}$. Then both U and V are open sets. The set U is usually called the **open ball** with center x and radius $\delta/2$. A topological space with the property that two distinct points can always be surrounded by disjoint open sets is called a **Hausdorff space**.

If d is a metric on X and if A is a subset of X, the distance d(x,A) of the point x from A is defined to be the infimum of the numbers d(x,a) where $a \in A$

Lemma 2.13. The real-valued function on X defined by $x \mapsto d(x, A)$ is continuous

Proof. Let $x \in X$ and let N be a neighbourhood of d(x,A) on the real line. Choose $\epsilon > 0$ small enough so that the interval $(d(x,A) - \epsilon, d(x,A) + \epsilon)$ lies inside N. Let U denote the open ball centered x, radius $\epsilon/2$, $z \in U$, and choose a point $a \in A$ s.t. $d(x,a) < d(x,A) + \epsilon/2$. If $z \in U$ we have

$$d(z,A) \le d(z,a) \le d(z,x) + d(x,a) < d(x,A) + \epsilon$$

By reversing the roles of x and z, we also have $d(x,A) < d(z,A) + \epsilon$. Therefore U is mapped inside $(d(x,A) - \epsilon, d(x,A) + \epsilon)$ and hence inside N, by our function, showing that the inverse image of N is a neighbourhood of x in X as required. \square

Lemma 2.14. If A, B are disjoint closed subsets of a metric space X, there is a continuous real-valued function on X which takes the value 1 on points of A, -1 on points of B, and values strictly between ± 1 on points of $X - (A \cup B)$

Proof. Since A and B are both closed and are disjoint, the expression d(x,A)+d(x,B) can never be zero by Exercise 2.4.1. Therefore we can define a real-valued function f on X by

$$f(x) = \frac{d(x,B) - d(x,A)}{d(x,B) + d(x,A)}$$

Lemma 2.15. If A is closed in Y and Y is closed in X, then A is closed in X

Proof.
$$Y - A = B \cap Y$$
 and $Y - A \subset B$. $X - Y \cup B$ is open and $X - Y \cup B = X - A$

Definition 2.16. For each $n \in \mathbb{N}$, let $f_n : A \to \mathbb{R}$ for $A \subset \mathbb{R}$. The sequence (f_n) converges pointwise on A to a function $f : A \to \mathbb{R}$ if for all $x \in A$ the sequence of real numbers $f_n(x)$ converges to f(x)

Definition 2.17. Let f_n be a sequence of functions defined on $A \subset \mathbb{R}$. We say that (f_n) **converges uniformly on** A to a limit function f on A if for every $\epsilon > 0$ there exists an $N \in \mathbb{N}$ s.t. $|f_n(x) - f(x)| < \epsilon$ for all $x \in A$ whenever $n \geq N$

Definition 2.18. A sequence $\{a_n\}$ of real numbers is called a **Cauchy sequence** if for every $\epsilon>0$ there exists an N s.t. $|a_n-a_m|<\epsilon$ whenever $n,m\geq N$.

Theorem 2.19 (Cauchy criterion for uniform convergence). A sequence of functions (f_n) defined on $A \subset \mathbb{R}$ converges uniformly on A iff for every $\epsilon > 0$ there exists an $N \in \mathbb{N}$ s.t.

$$|f_n(x) - f_m(x)| < \epsilon$$

for all $n, m \ge N$ and for all $x \in A$

Proof. Suppose f_n converges uniformly to f on A. Then for $\epsilon>0$ there exists $N\in\mathbb{N}$ s.t. $|f_n(x)-f(x)|<\epsilon/2$ for all $n\geq N$ and all $x\in A$

Then for $n, m \ge N$ and any $x \in A$ we have

$$\begin{split} |f_n(x)-f_m(x)| &= |f_n(x)-f(x)+f(x)-f_m(x)|\\ &\leq |f_n(x)-f(x)|+|f_m(x)-f(x)|\\ &< \epsilon/2+\epsilon/2\\ &= \epsilon \end{split}$$

Now suppose that for all $\epsilon>0$ there exists $N\in\mathbb{N}$ s.t. $|f_n(x)-f_m(x)|<\epsilon$ for all $n,m\geq M$ and all $x\in A$

Then for each $x \in A$, the sequence $(f_n(x))$ is a Cauchy sequence of real numbers, and therefore it converges to a real number, call it f(x) (Check Proof).

We have found a function $f:A\to\mathbb{R}$ which is the pointwise limit of f_n By the Algebraic Limit and Order Limit Theorem we have for all $n\geq N$ and all $x\in A$ that

$$|f_n(x) - f(x)| = \lim_{m \to \infty} |f_n(x) - f_m(x)| \leq \epsilon$$

which says that f_n converges uniformly to f on A

Theorem 2.20 (Continuous limit theorem). Let (f_n) be a sequence of functions defined on $A \subseteq \mathbb{R}$ that converges uniformly on A to f. If each f_n is continuous at $c \in A$, then f is continuous at c too

Proof. Fix $x \in A$ and for $\epsilon > 0$ choose $N \in \mathbb{N}$ s.t. for all $x \in A$ we have

$$|f_N(x) - f(x)| < \frac{\epsilon}{3}$$

By the continuity of f_N at c there exists $\delta>0$ s.t. whenever $|x-c|<\delta$ we have

$$|f_N(x) - f_N(c)| < \frac{\epsilon}{3}$$

Thus

$$|f(x) - f(c)| \le |f(x) - f_N(x)| + |f_N(x) - f_N(c)| + |f_N(c) - f(c)| < \epsilon$$

Theorem 2.21 (Tietze extension theorem). Any real-valued continuous function defined on a closed subset of a metric space can be extended over the whole space

Proof. Let X be a metric space, C a closed subset, and $f:C\to\mathbb{R}$ a map. To begin with we shall assume that f is bounded; say $|f(x)|\leq M$ for all $x\in C$

Let $A_1=\{x\mid f(x)\geq M/3\},\, B_1=\{x\mid f(x)\leq -M/3\}.\,\, A$ and B are disjoint and are both closed in X. Since A_1 is the inverse image of the closed subset $[M/3,+\infty)$ of $\mathbb R$. A_1 is closed in C, and C is closed in X. Hence A_1 is closed in X. By Lemma 2.14, we can find a map $g_1:X\to [-M/3,M/3]$ which takes the value M/3 on $A_1,-M/3$ on B_1 , and which takes values in (-M/3,M/3) on $X-(A_1\cup B_1)$. Notice that $|f(x)-g_1(x)|\leq 2M/3$ on C

Now consider the function $f(x)-g_1(x)$ and let A_2 consists of those points of C for which $f(x)-g_1(x)\geq 2M/9$ and B_2 those points for which $f(x)-g_1(x)\leq -2M/9$. By Lemma 2.14 we have a map $g_2:X\to [-2M/9,2M/9]$ which takes the value 2M/9 on A_2 , -2M/9 on B_2 . $|f(x)-g_1(x)-g_2(x)|<4M/9$ on C

By repeating this process we can construct a sequence of maps $g_n:X\to [-2^{n-1}M/3^n,x^{n-1}M/3^n]$ which satisfy

- $1. \ |f(x)-g_1(x)-\cdots-g_n(x)| \leq 2^n M/3^n \text{ on } C \text{ and }$
- 2. $|g_n(x)| < 2^{n-1}M/3^n$ on X C

The series $\sum_{n=1}^{\infty} g_n(x)$ converges uniformly on X by the Weierstrass Mtest, so it has a well-defined sum g(x) which is continuous. Also f and g

agree on C by (1). Therefore g extends f to all of X. We note, for use in the unbounded case |g(x)| is bounded by M because

$$|g(x)| = \sum_{n=1}^{\infty} |g_n(x)| \le M \sum_{n=1}^{\infty} x^{n-1}/c^n = M$$

and |g(x)| is strictly less than M on X - C by (2)

If g is not bounded, choose a homeomorphism h from the real line to the interval (-1,1) and consider the composition $h \circ f$. This is bounded and we can extend it to a continuous real-valued function

2.4.1 Exercise

Exercise 2.4.1. Show d(x, A) = 0 iff x is a point of \overline{A}

Proof. Suppose that $d(x,A)=0=\inf_{a\in A}d(x,a)$. Then for every $\epsilon>0$, there exists $a\in A$ s.t.

$$|d(x,a) - 0| = d(x,a) < \epsilon$$

Now let $\mathcal O$ be an open subset of X, $x \in \mathcal O$. Choose $a \in A$ s.t. $d(x,a) < \epsilon$. Then $a \in \mathcal O$ and $\mathcal O \cap A \neq \emptyset$. Thus $x \in \overline{A}$

Suppose $x \in A$. For $n \in \mathbb{N}$, let $B_n = \{y \mid d(x,y) < 1/n\}$. Then B_n is open, so $B_n \cap A \neq \emptyset$. Let $a_n \in B_n \cap A$. Then $d(x,a_n) < 1/n$ thus $\inf_{a \in A} d(x,a) < 1/n$ for every n. Thus $\inf_{a \in A} d(x,a) = 0$

3 Compactness and Connectedness

3.1 Closed bounded subsets of \mathbb{R}^n

Let X be a topological space and let \mathcal{F} be a family of open subsets of X whose union is all of X. Such a family will be called an **open cover** of X. If \mathcal{F}' is a subfamily of \mathcal{F} and if $\bigcup \mathcal{F}' = X$, then \mathcal{F}' is called a **subcover** of \mathcal{F} .

Theorem 3.1. A subset X of \mathbb{R}^n is closed and bounded iff every open cover of X (with the induced topology) has a finite subcover

Definition 3.2. A topological space *X* is **compact** if every open cover of *X* has a finite subcover

With this terminology, theorem 3.1 can be restated as follows. *The closed bounded subsets of a euclidean space are precisely those subsets which (when given the induced topology) are compact*

3.2 The Heine-Borel theorem

Theorem 3.3 (The Heine-Borel theorem). *A closed interval of the real line is compact*

'Creeping along' proof. Let [a,b] be a closed interval of the real line, with the induced topology, and let \mathcal{F} be an open cover of [a,b]. We define a subset X of [a,b] by

 $X = \{x \in [a,b] \mid [a,x] \text{ is contained in the union of a finite subfamily of } \mathcal{F}\}$

Then X is nonempty $(a \in X)$ and is bounded above (by b). So X has a supremum, say s. We claim that $s \in X$ and that s = b. For let O be the member of $\mathcal F$ which contains s. Since O is open we can choose $\epsilon > 0$ small enough that $(s-\epsilon,s] \subseteq O$, and if s is less than b we can assume $(s-\epsilon,s+\epsilon) \subseteq O$. Now s is the *least* upper bound of X, consequently there are points of X arbitrarily closed to s. Also, X has the property that if $x \in X$ and if $a \le y \le x$ then $y \in X$. Therefore we may assume $s - \epsilon/2 \in X$. By the definition of X, the interval $[a,s-\epsilon/2]$ is contained in the union of some finite subfamily $\mathcal F'$ of $\mathcal F$. Adding O to $\mathcal F'$ we obtain a finite collection of members of $\mathcal F$ whose union certainly contains [a,s]. Therefore $s \in X$. If s is less than b then $\bigcup \mathcal F' \cup O$ contains $[a,s+\epsilon/2]$ contradicting the fact that s is an upper bound for X.

'subdivision' proof. Suppose that theorem 3.3 is false. Let $\mathcal F$ be an open cover of [a,b] which does not contain a finite subcover. Set $I_1=[a,b]$. Subdivide [a,b] into two closed subintervals of equal length [a,(a+b)/2],[a,b]/2,b. At least one of these have the property that it is not contained in the union of any finite subfamily of $\mathcal F$. Select one of them and call it I_2 . Continuing in this way we obtain a nested sequence of closed intervals

$$I_1 \supseteq I_2 \supseteq I_3 \supseteq \dots$$

whose lengths tend to zero.

We claim that $\bigcap_{n=1}^\infty I_n$ consists of precisely one point. In our first proof of theorem 3.3, we used the so-called completeness property of the real numbers (a nonempty set of real numbers which is bounded above has a least upper bound). We let x_n denote the left-hand end point of the interval I_n and we consider the sequence $\{x_n\}$. This sequence is monotonic increasing and bounded. Therefore if p denotes the supremum of the x_n we know that $\{x_n\}$ converges to p. It's now elementary to check that $p \in I_n$ for all p. Also,

since the lengths of the I_n tend to zero as n tend to infinity, it should be clear that $\bigwedge_{n=1}^{\infty} I_n$ cannot contain more than one point. Therefore $\bigwedge_{n=1}^{\infty} I_n = \{p\}$

Now p belongs to [a,b] and so lies in some open set O of \mathcal{F} . We choose $\epsilon>0$ small enough that $(p-\epsilon,p+\epsilon)\cap [a,b]\subseteq O$, and we choose a positive integer n large enough that length $(I_n)<\epsilon$. Since $p\in I_n$, we see that I_n is completely contained in O. But I_n was selected so that it did not lie in the union of any finite subfamily of \mathcal{F} , and here we have I_n inside a single member of \mathcal{F} .

Suppose $f:[a,b]\to\mathbb{R}$ is continuous. Given $x\in[a,b]$ we can find a neighbourhood O(x) of x in [a,b] s.t. |f(x')-f(x)|<1 for all points $x'\in O(x)$. The family of all such O(x) forms an open cover of [a,b]. Therefore by the Heine-Borel theorem we can find a finite subfamily, say $O(x_1),\dots,O(x_k)$ s.t. $O(x_1)\cup\dots\cup O(x_k)=[a,b]$. Now if $x\in O(x_i)$ then $|f(x)|\leq |f(x_i)|+1$. So for any point $x\in [a,b]$ we have

$$|f(x)| \le \max\{|f(x_1)|, \dots, |f(x_k)|\} + 1$$

3.2.1 Exercise

Exercise 3.2.1. Find an open cover of \mathbb{R} which does not contain a finite subcover. Do the same for [0,1) and (0,1]

Proof.
$$I_n = [0, 1 - \frac{1}{n}]. I_n = (\frac{1}{n}, 1 - \frac{1}{n})$$

Exercise 3.2.2. Let $S \supseteq S_1 \supseteq S_2 \supseteq ...$ be a nested sequence of squares in the plane whose diameters tend to zero as we proceed along the sequence. Prove that the intersection of all these squares consists of exactly one point.

Proof. We have
$$\{x_n\}$$
 and $\{y_n\}$.

Exercise 3.2.3. Use the Heine-Borel theorem to show that an infinite subset of a closed interval must have a limit point

Proof. Let I be a closed interval. Let $A\subseteq I$ be an infinite subset. Suppose A does not have any limit points. Then for each $x\in I$ there is an open set $U_x\subseteq I$ s.t. $x\in U_x$ and $U_x\cap A-\{x\}=\emptyset.$ $\{U_x\}$ is an open cover of I, by the Heine-Borel theorem there is a finite subcover $\{U_{x_1},\dots,U_{x_n}\}$. It must be that $A\subseteq U_{x_1}\cup\dots\cup U_{x_n}$. But the only element of each U_x that is in A is x. Thus $U_{x_1}\cup\dots\cup U_{x_n}=\{x_1,\dots,x_n\}$ a finite set. Thus A must be finite. \square

3.3 Properties of compact spaces

Theorem 3.4. The continuous image of a compact space is compact

Proof. If $f: X \to Y$ is an onto continuous function, and if X is compact, then we must show Y compact. Let \mathcal{F} be an open cover of Y. If $O \in \mathcal{F}$ then $f^{-1}(O)$ is an open subset of X by the continuity of f, and so the family

$$\mathcal{G} = \{ f^{-1}(O) \mid O \in \mathcal{F} \}$$

is an open cover of X. Since X is compact, $\mathcal G$ contains a finite subcover, say $X=f^{-1}(O_1)\cup\cdots\cup f^{-1}(O_k)$. Now f is an onto function, therefore $f(f^{-1}(O_i))=O_i$, and we have $Y=O_1\cup\cdots\cup O_k$.

A subset of C of a topological space X is called a **compact subset of** X if C with the induced topology from X is a compact space. C is a compact subset of X iff every family of open subsets of X whose union contains C has a finite subfamily whose union also contains C

Theorem 3.5. A closed subset of a compact space is compact

Proof. Let X be a compact space, C a closed subset of X, and $\mathcal F$ a family of open subsets of X s.t. $C\subseteq\bigcup\mathcal F$. If we add the open set X-C to $\mathcal F$ we obtain an open cover of X. Therefore we can find $O_1,\dots,O_k\in\mathcal F$ s.t. $O_1\cup\dots\cup O_k\cup(X-C)=X$. This gives $C\subseteq O_1\cup\dots\cup O_k$

Theorem 3.6. If A is a compact subset of a Hausdorff space X, and if $x \in X - A$, then there exist disjoint neighbourhoods of x and A. Therefore a compact subset of a Hausdorff space is closed

Proof. Let z be a point of A. Since X is Hausdorff, we can find disjoint open sets U_z and V_z s.t. $x \in U_z$ and $z \in V_z$. Varying z throughout A produces a family of open sets $\{V_z \mid z \in A\}$ whose union contains A. But A is compact, so $A \subset V_{z_1} \cup \dots \cup V_{z_k}$ for some finite collection of points $z_1, \dots, z_k \in A$. Let $V = V_{z_1} \cup \dots \cup V_{z_k}$. Since V_{z_1} is disjoint from the open neighbourhood U_{z_1} of x, V is disjoint from the intersection $U = U_{z_1} \cap \dots \cap U_{z_k}$. The sets U, V are disjoint open neighbourhoods of x and A

Hence
$$X \setminus A = \bigcup_{a \in X-A} U_a$$
. So $X \setminus A$ is open, hence A is closed. \square

Theorem 3.7. A one-one, onto, and continuous function from a compact space X to a Hausdorff space Y is a homeomorphism

Proof. Let C be a closed subset of X. Then C is compact by Theorem 3.5. Therefore f(C) is compact by Theorem 3.4 and consequently closed in Y by Theorem 3.6. So f takes closed sets to closed sets, which proves that f^{-1} is continuous

Theorem 3.8 (Bolzano-Weierstrass property). *An infinite subset of a compact space must have a limit point*

Proof. Let X be a compact space and let S be a subset of X which has no limit point. We shall show that S is finite. Given $x \in X$ we can find an open neighbourhood O(x) of x s.t.

$$O(x) \cap S = \begin{cases} \emptyset & x \notin S \\ \{x\} & x \in S \end{cases}$$

since otherwise x would be a limit point of S. By the compactness of X the open cover $\{O(x) \mid x \in X\}$ has a finite subcover. But each set O(x) contains at most one point of S and therefore S must be finite. \Box

Theorem 3.9. A compact subset of a euclidean space is closed and bounded

Proof. Let C be a compact subset of \mathbb{R}^n . Then C is closed by theorem 3.6. Now the open balls, centre the origin with integer radius, fill out all of \mathbb{R}^n . Therefore if C is compact it must be contained inside the union of finite many of these balls, i.e., there is an integer n s.t. C is contained in the ball with centre the origin and radius n. In other words C is bounded

Theorem 3.10. A continuous real-valued function defined on a compact space is bounded and attains its bounds

Proof. If $f: X \to \mathbb{R}$ is continuous and if X is compact, then f(X) is compact. Therefore f(X) is a closed bounded subset of \mathbb{R} by theorem 3.9 and f is certainly bounded. Since f(X) is closed, both the supremum and infimum of f(X) lie in f(X). We can therefore find points $x_1, x_2 \in X$ s.t.

$$f(x_1) = \sup(f(X)) \quad \text{ and } \quad f(x_2) = \inf(f(X))$$

which says precisely that *f* attains its bounds

Lemma 3.11 (Lebesgue's lemma). Let X be a compact metric space and let \mathcal{F} be an open cover of X. Then there exists a real number $\delta > 0$ (called a Lebesgue number of \mathcal{F}) s.t. any subset of X of diameter less than δ is contained in some member of \mathcal{F}

Proof. If Lebesgue's lemma is false we can find a sequence $A_1, A_2, A_3, ...$ of subsets of X, none of which are contained inside a member of \mathcal{F} , and whose diameters tend to zero as we proceed along the sequence.

3.3.1 Exercise

Exercise 3.3.1. which of the following are compact

- 1. the space of rational numbers
- 2. S^n with a finite number of points removed
- 3. the torus with an open disc removed
- 4. the Klein bottle
- 5. the Möbius strip with its boundary circle removed
- 1. $\mathbb Q$ is not compact. By Theorem 3.9 a compact subset of $\mathbb R$ is closed and bounded. $\mathbb Q$ is neither. Enumerate the rational numbers $q_1,q_2,...$ and cover the entire set with a collection of open sets U_n where U_n is an open interval of length $1/2^n$

The collection $\{U_n\}_{n=1}^\infty$ is clearly an open covering of $\mathbb Q$. However, any finite subcollection cannot cover.

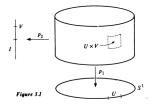
- 2. No. Not closed
- 3. Yes. bounded and closed
- 4. Yes
- 5. No.

3.4 Product spaces

Take a specific cylinder in \mathbb{R}^3 , say

$$\{(x, y, z) \mid x^2 + y^2 = 1, 0 \le z \le 1\}$$

and give it the induced topology. As a set it is the cartesian product $S^1 \times I$, where S^1 denotes the unit circle in the (x,y) plane and I the unit inverval on the z axis. We claim that the topology of the cylinder is the product of the topologies of the circle and the interval. Note that if U is an open set in S^1 and if V is open in I, then the product $U \times V$ is open in the cylinder.



Also, if we are given an open set O of the cylinder, and a point p belonging to O, then we can easily find open sets $U \subseteq S^1, V \subseteq I$ s.t. $p \in U \times V \subseteq O$. In other words, these product sets $U \times V$ form a base for the topology of the cylinder.

Let X and Y be topological spaces and let \mathcal{B} denote the family of all subsets of $X \times Y$ of the form $U \times V$, where U is open in X and Y open in Y. Then $\bigcup \mathcal{B} = X \times Y$ and the intersection of any two members of \mathcal{B} lies in \mathcal{B} . Therefore \mathcal{B} is a base for a topology on $X \times Y$. This topology is called the **product topology** and the set $X \times Y$, when equipped with the product topology, is called a **product space**. We note that the natural topology of euclidean n-space is precisely the product topology relative to the decomposition of \mathbb{R}^n as the product of n copies of the real line.

The functions $p_1: X \times Y \to X$ and $p_2: X \times Y \to Y$ defined by $p_1(x,y) = x, p_2(x,y) = y$ are called **projections**

Theorem 3.12. If $X \times Y$ has the product topology then the projections are continuous functions and they take open sets to open sets. The product topology is the smallest topology on $X \times Y$ for which both projections are continuous

Proof. Suppose U is an open subset of X, then $p_1^{-1}(U) = U \times Y$ which is open in the product topology. Therefore p_1 is continuous

Suppose that we have some topology on $X\times Y$ and that both projections are continuous. Take open sets $U\subseteq X, V\subseteq Y$ and form $p_1^{-1}(U)\cap p_2^{-1}(V)$. This must be open and is precisely $U\times V$

Theorem 3.13. A function $f: Z \to X \times Y$ is continuous iff the two composite functions $p_1 f: Z \to X, p_2 f: Z \to Y$ are both continuous

Proof. Suppose that both p_1f and p_2f are continuous. To check the continuity of f we need only show that $f^{-1}(U\times V)$ is open in Z for each basic open set $U\times V$ of $X\times Y$. But

$$f^{-1}(U\times V)=(p_1f)^{-1}(U)\cap (p_2f)^{-1}(V)$$

Therefore $f^{-1}(U\times V)$ is open in Z. Conversely, if f is continuous then p_1f and p_2f are continuous, by the continuity of the projections p_1,p_2

Theorem 3.14. The product space $X \times Y$ is a Hausdorff space iff both X and Y are Hausdorff

Lemma 3.15. Let X be a topological space and let \mathcal{B} be a base for the topology of X. Then X is compact iff every open cover of X by members of \mathcal{B} has a finite subcover

Proof. Suppose that every open cover of X by members of \mathcal{B} has a finite subcover, and let \mathcal{F} be an arbitrary open cover of X. Since \mathcal{B} is a base for the topolgoy of X we know that we can express each member of \mathcal{F} as a union of members of \mathcal{B} . Let \mathcal{B}' denote the family of those members of \mathcal{B} which are used in this process. By construction, we have $\bigcup \mathcal{B}' = \bigcup \mathcal{F} = X$; so \mathcal{B}' is an open cover of X and must therefore contain a finite subcover \Box

Theorem 3.16. $X \times Y$ is compact iff both X and Y are compact

Proof. If $X \times Y$ is compact, then both X and Y have to be compact since the projections are onto and continuous.

Suppose both X and Y are compact spaces and let \mathcal{F} be an open cover of $X \times Y$ by *basic* open sets of the form $U \times V$, where U and V are open in X,Y respectively.

Select a point $x \in X$ and consider the subset $\{x\} \times Y$ of $X \times Y$ with the induced topology. It is easy to check that

$$p_2|_{\{x\}\times Y}:\{x\}\times Y\to Y$$

is a homeomorphism. So $\{x\} \times Y$ is compact and we can find a minimal finite subfamily of $\mathcal F$ whose union contains $\{x\} \times Y$. We shall label the member s of this finite subfamily

$$U_1^x \times V_1^x, \dots, U_{n_x}^x \times V_{n_x}^x$$

