Mateusz Baczek

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Software engineer with 3+ years of experience, both in writing code and leading a team of programmers. Familiar with web development, systems programming and digital signal processing. Fascinated with computer-aided design processes, especially generative art and music.

Experience

Mission operations software development lead

SatRev

Wrocław, PL

Developed and maintained Satrev's in-house missionoperations software, used to operate the entire fleet of company's satellites. Leading a team of 3-5 programmers.

- Management & monitoring of software infrastructure
- Real-time communication protocols
- · Message queues
- Metrics visualisation



Software Developer

SatRev

 \square 2020 — 2021

Wrocław, PL

Developed the telemetry software and automation/testing tools used during the testing and integration processes of the STORK satellites. Worked on the software for the onboard computer for the STORK platform.

- · Telemetry and ground station software
- Radio communication protocols
- Automatic testing tools



Sofware Developer

BZB UAS

1 2020

Wrocław, PL

Worked on an integrated telemetry collection & sharing service for a semi-autonomous UAV dedicated to conducting photogrammetry scans.

- · Telemetry and ground station software
- Radio communication protocols
- Automatic testing tools

Python ArduPilot MavLink Embedded Linux

OpenWRT

Education

Higher

Wrocław University of Science and Technology

□ Sep 2022 − 2023

Wrocław, PL

M.Sc. Computer Science. Thesis title: Design of a DSP graph generation algorithm for solving the sound synthesis problem.

Wrocław University of Science and Technology

□ Sep 2017 − 2021

• Wrocław, PL

B.Sc. Computer Science. Thesis title: Autonomous dronebased scouting system. Student activity

At the university I participated in a student research circle, the Academic Aviation Club (Original Polish name: Akademicki Klub Lotniczy), dedicated to developing unmanned aerial vehicles. As a member, I've participated in the following competitions:

SAE Aero Design

1 2020

• Florida, USA

Second place in general classification, second place in the Advance category. Developed a mathematical model predicting an optimal position for dropping a payload from a flying plane and built the telemetry software required to operate the system.

Droniada

2021

Kakolewo, PL

Designed a visual marker detection system, based on machine learning algorithms. The system facilitated realtime marker detection on-board an autonomous drone, which then performed a precise release of pesticides (the subject matter of the competition were new technologies in agriculture). The team won the second place.

IAV - Intelligent Autonomous Vehicles

2019

Gdańsk, PL

Designed a system for determining the position of Bluetooth LE beacons, using an autonomous drone. The team won the first place.

Languages

- English fluent
- Polish native

Personal Projects

Running a personal website and a personal cloud

I'm using a VPS server to run a personal website and a number of personal cloud services. Everything is monitored via the Grafana stack.

Collaborative sampler

Written in a team of 4, the sampler is meant to reproduce the Digitakt-style workflow in a distributed environment. Each user has their own DSP engine running to assure minimal latency, but the changes each user makes in the sequencer state are synchronised in real time across a virtual "jam session".