

k230 self-learning object recognition

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k230 and ESP32S3 communication

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1. Experimental Prerequisites

This tutorial uses the ESP32S3 development board, and the corresponding routine path is [14.export\ESP32-K230\16_k230_self_learning].

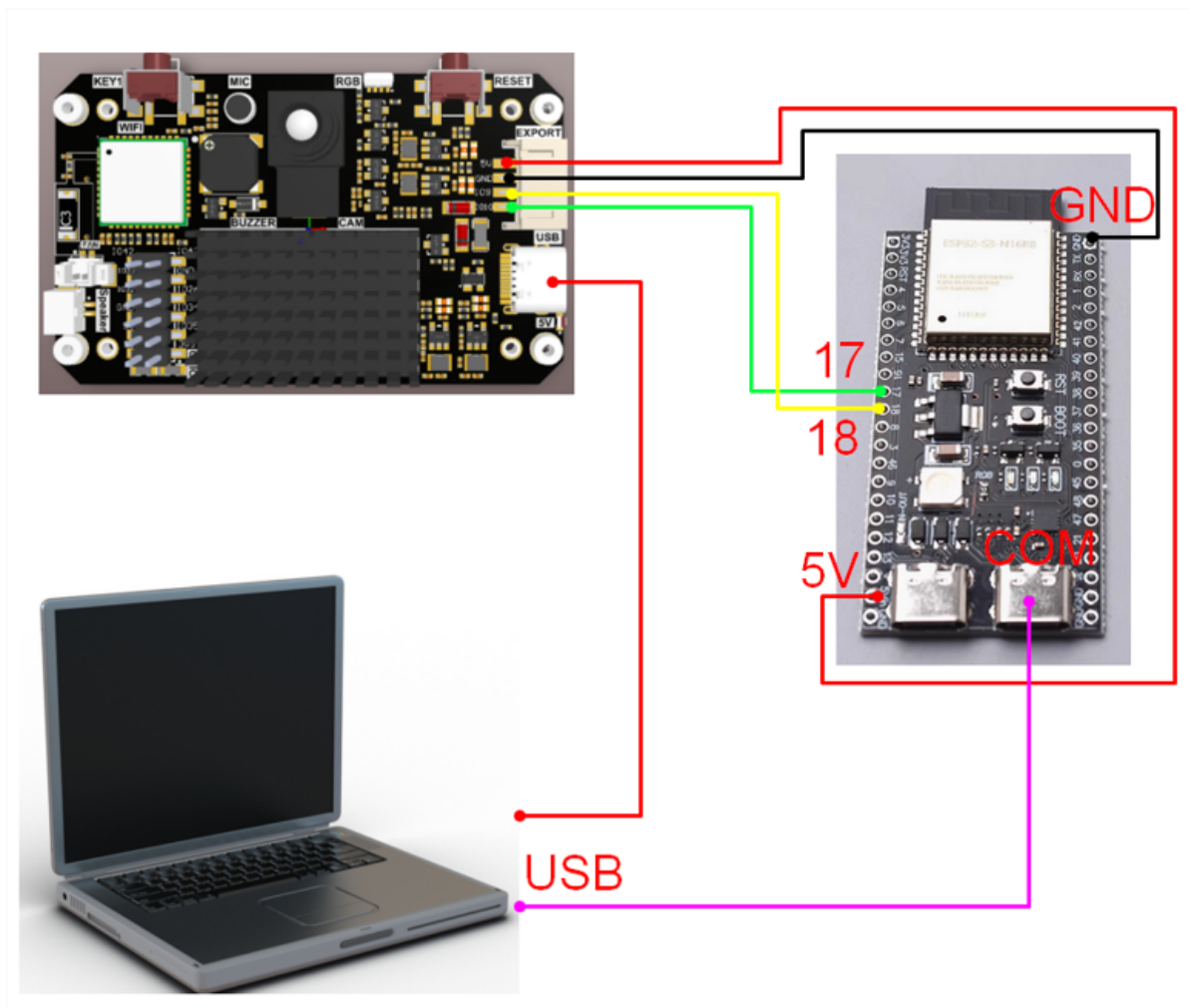
K230 needs to run the [14.export\CanmvIDE-K230\16.self_learning.py] program to start the experiment. It is recommended to download it as an offline program.

Things you need:

Windows computer, ESP32S3 development board, K230 visual module (including TF card with burned image), two type-C data cables, Connection cable

2. Experimental wiring

k230 vision module	ESP32S3 Development Board
5V	5V
GND	GND
TXD(IO9)	18
RXD(IO10)	17



3. Main code explanation

```
void Pto_Data_Parse(uint8_t *data_buf, uint8_t num)
{
    uint8_t pto_head = data_buf[0];
    uint8_t pto_tail = data_buf[num-1];
    if (!(pto_head == PTO_HEAD && pto_tail == PTO_TAIL))
    {
        printf("pto error:pto_head=0x%02x , pto_tail=0x%02x\n", pto_head,
pto_tail);
        return;
    }
    uint8_t data_index = 1;
    uint8_t field_index[PTO_BUF_LEN_MAX] = {0};
    int i = 0;
    int values[PTO_BUF_LEN_MAX] = {0};
    char msg[PTO_BUF_LEN_MAX] = {0};
    for (i = 1; i < num-1; i++)
    {
        if (data_buf[i] == ',')
        {
            data_buf[i] = 0;
            field_index[data_index] = i;
            data_index++;
        }
    }

    for (i = 0; i < data_index; i++)
```

```

{
    if (i == 2)
    {
        memcpy(msg, (char*)data_buf+field_index[i]+1, field_index[i+1]-
field_index[i]);
    }
    else
    {
        values[i] = Pto_Char_To_Int((char*)data_buf+field_index[i]+1);
    }
}

uint8_t pto_len = values[0];

if (pto_len != num)
{
    printf("pto_len error:%d , data_len:%d\n", pto_len, num);
    return;
}
uint8_t pto_id = values[1];
if (pto_id != PTO_FUNC_ID)
{
    printf("pto_id error:%d, func_id:%d\n", pto_id, PTO_FUNC_ID);
    return;
}
float score = values[3]/100.0;
printf("category: '%s', score: %.2f\n", msg, score);
}

```

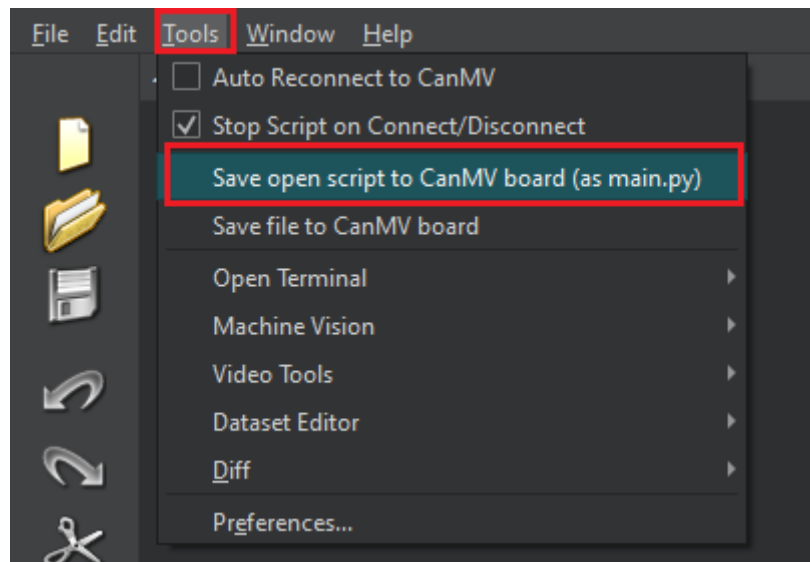
The above functions are for parsing K230 data. Only when they meet specific protocols can the corresponding data be parsed.

in

- category: is the recognized name
- score: is the score

4. Experimental Phenomenon

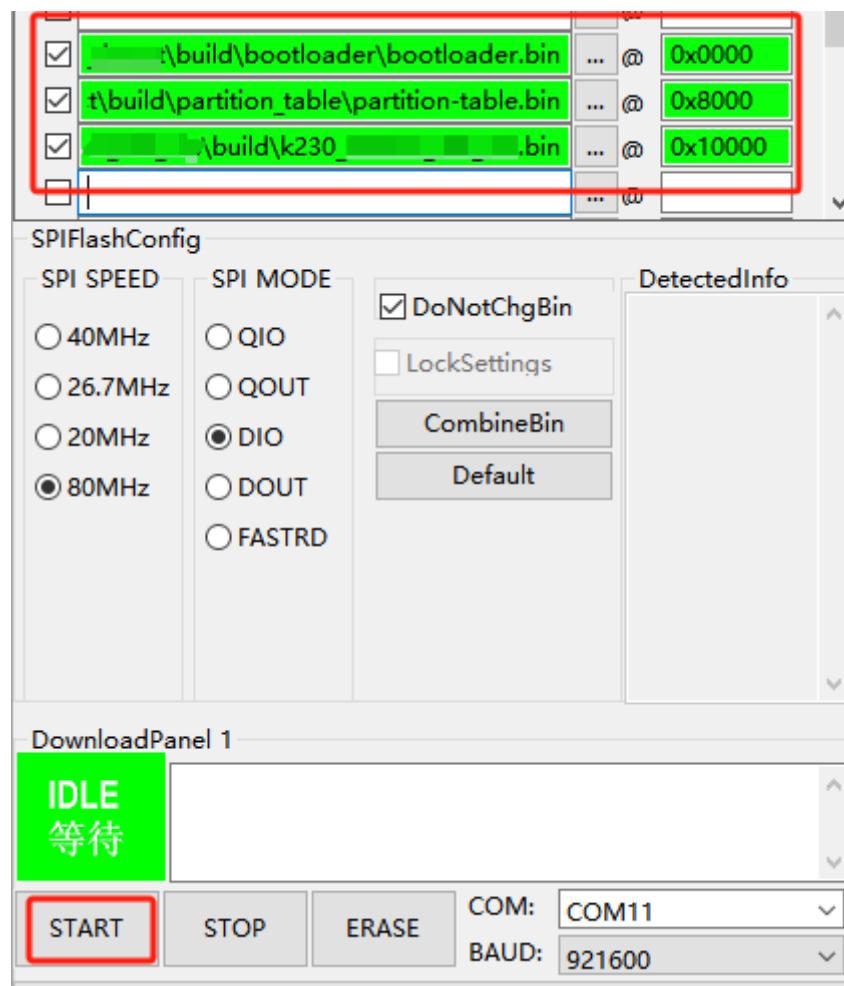
1. After connecting the cables, the k230 visual module runs offline. After K230 is connected to Canmv IDE, open the corresponding program, click [Save open script to CanMV board (as main.py)] on the toolbar, and then restart K230.



When K230 is turned on, a purple box will appear on the screen. Please align the purple box with the objects to be learned. There are two objects in total. Follow the on-screen prompts to learn the two objects.

After both objects have been learned, if the corresponding object appears in the purple box, the object name and score will be displayed.

2. The bin file generated by the ESP32S3 burning routine. Open the ESP32S3 burning tool, configure it according to the figure below, click the [START] button, and download the bin file to the ESP32S3 development board.



3. Set the serial port assistant to the interface shown in the figure and open the serial port of ESP32S3.

Port


COM25:USB 串行设备

Baud rate 115200

Stop bits 1

Data bits 8

Parity None

Operation  Close

Save Data Clear Data

☐ Hex ☐ DTR

☐ RTS ☐ 自动保存

☐ TimeStamp 1000 ms

4. When the K230 camera recognizes an object, the serial port assistant will print out the information transmitted from K230 to ESP32S3.

in

- category: is the recognized name
- score: is the score

As shown in the figure below

```
category:'ultrasonic', score:0.96
category:'ultrasonic', score:0.96
category:'ultrasonic', score:0.95
category:'ultrasonic', score:0.89
category:'ultrasonic', score:0.85
category:'ultrasonic', score:0.72
category:'earphone', score:0.61
category:'earphone', score:0.71
category:'earphone', score:0.77
category:'earphone', score:0.82
category:'earphone', score:0.86
category:'earphone', score:0.87
category:'earphone', score:0.88
category:'earphone', score:0.88
```