# **Streaming Algorithms**

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### Reminder

Written Assignment #1 is due by tonight. You need to LaTex your solution and submit it on New E3 (https://e3new.nctu.edu.tw).

You are encouraged to discuss with your classmates, TA, or me. However, the writeup shall be your own.

## Reference

• "Space-Efficient Online Computation of Quantile Summaries," Greenwald and Khanna (2001)

**Quantile Summaries** 

#### **Problem Definition**

Input: a sequence of n (possibly repeat) values  $a_1, a_2, ..., a_n$  where n is unknown before the end of input is reached, an integer  $q \in [1, n]$ , and a value  $\varepsilon \in [1/n^2, 1]$ . Define  $A = \{a_i : i \in [n]\}$  and rank

$$r(a_i) = |\{a_j \in A: a_j < a_i \text{ or } (a_j = a_i \text{ and } j \le i)\}|.$$

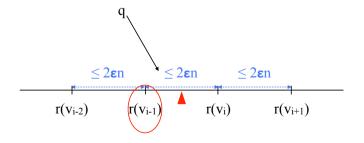
Output:

an  $a_i$  for some i so that  $|r(a_i) - q| \le \varepsilon n$ 

Goal: use  $O(\varepsilon^{-1}\log \varepsilon n)$  space (not bits).

#### A Subset V of A

Roughly speaking, we will maintain a subset  $V = \{v_0, v_1, ..., v_{s-1}\}$  of A as A grows so that (1)  $s = O(\varepsilon^{-1}\log \varepsilon n)$ , (2)  $r(v_0) = 1$ , (3)  $r(v_{s-1}) = n$ , (4)  $r(v_{i-1}) \le r(v_i)$  for each  $i \ge 1$ , and (5)  $r(v_i) - r(v_{i-1}) \le 2\varepsilon n$ .



#### Data Structure

## Reducing to the Bin-Ball Problem

We already know that if we sample  $O(\epsilon^{-1}log\ n)$   $a_i$ 's uniformly at random from A with replacement and keep track the min (resp. max) element in A, then we get a subset V that satisfies the desired property w.h.p., but we have no idea what  $r(a_i)$  for  $a_i \in V$  are.

In our programming assignment #0, we scan the input for one additional pass to figure what  $r(a_i)$  for  $a_i \in V$  are.

In today's lecture, we will see a deterministic algorithm that can answer this question in a single pass.

### A Set S of Triples

Let  $r_{min}(v_i)$  and  $r_{max}(v_i)$  be under- and over-estimates of  $r_n(v_i)$  among the values seen so far, after all values are read, we get  $r_{min}(v_i) \le r(v_i)$   $\le r_{max}(v_i)$ .

We define a set  $S = \{(v_i, g_i, \Delta_i) : v_i \in V\}$  so that

- (1)  $g_i = r_{min}(v_i)$   $r_{min}(v_{i-1})$  for each  $i \ge 1$ , // gap between two consecutive under-estimates
- (2)  $\Delta_i = r_{max}(v_i)$   $r_{min}(v_i)$  for each i, // difference between under- and over-estimates of an single  $v_i$
- (3)  $(v_0, g_0, \Delta_0) = (v_0, 1, 0),$
- (4)  $(v_{s-1}, g_{s-1}, \Delta_{s-1}) = (v_{s-1}, 1, 0).$

### Bounded $g_i + \Delta_i$

Claim. Given S, if  $\max_i g_i + \Delta_i \le 2\varepsilon n$ , then for any q one can output some v so that  $|r(v) - q| \le \varepsilon n := e$ .

Proof. Case 1. If q > n-e, setting  $v = v_{s-1}$  suffices.

Case 2. Otherwise, picking the smallest t (such a t exists) so that

$$r_{max}(v_t) = (\sum_{j \le t} g_j) + \Delta_t \ge q + e$$
, i.e.  $r_{max}(v_{t-1}) < q + e$ .

Then 
$$r_{min}(v_{t-1}) = (\sum_{j \le t} g_j) = r_{max}(v_t) - g_t - \Delta_t \ge q + e - 2e = q - e$$
.

Hence, setting  $v = v_{t-1}$  suffices.

Goal: Maintain a set of triples S whose  $max_i g_i + \Delta_i \le 2e$ .

### Some Identities (as n increases)

(1) 
$$r_{min}(v_0) = r_{max}(v_0) = 1$$

(2) 
$$r_{min}(v_{s-1}) = r_{max}(v_{s-1}) = n$$

(3) 
$$\sum_{0 \le i \le s} g_i = (\sum_{1 \le i \le s} r_{min}(v_i) - r_{min}(v_{i-1})) + 1 = n-1+1 = n$$

$$(4) r_{\min}(v_i) = \sum_{j \le i} g_j$$

$$(5) r_{\max}(v_i) = (\sum_{j \le i} g_j) + \Delta_i$$

(6) 
$$|\{a_i : r(v_{i-1}) < r(a_i) < r(v_i)\}| \le g_i + \Delta_i - 1$$
.

## Algorithm

#### Pseudocode

```
Generate-S() { S \leftarrow \varnothing; s \leftarrow 0; n \leftarrow 0; for each incoming a_i { Insert (S, a_i); // add a triple into S + + n; }  if(n \equiv 0 \bmod 1/(2\epsilon))  Compress(S); // merge some triples in S }
```

#### Pseudocode

```
Delete(S, v<sub>i</sub>){ // a building block of Compress(S)
```

replace the two triples  $(v_i, g_i, \Delta_i)$ ,  $(v_{i+1}, g_{i+1}, \Delta_{i+1})$  with  $(v_{i+1}, g_i+g_{i+1}, \Delta_{i+1})$ ; // Exercise: verifying this replacement doesn't change the  $r_{min}(v)$  and  $r_{max}(v)$  for all v in V.

```
s \leftarrow s-1;
```

#### Pseudocode

```
\begin{split} & \text{Insert}(S, a_i) \{ \\ & \text{if}(a_i \text{ has } r(a_i) < r(a_j) \text{ for all } j < i) \{ \text{ // i.e. } a_i < a_j \text{ for all } j < i \\ & \text{insert a triple } (a_i, 1, 0) \text{ to } S; \text{ // it requires to increase } r_{\text{min}}(v) \text{ and } r_{\text{max}}(v) \text{ by } 1 \text{ for all } v \text{ in } V \text{ where } r(v) \neq r(a_i) \\ & \} \\ & \text{if}(a_i \text{ has } r(a_i) > r(a_j) \text{ for all } j > i) \{ \text{ // i.e. } a_i \geq a_j \text{ for all } j < i \\ & \text{insert a triple } (a_i, 1, 0) \text{ to } S; \text{ // no effect on } r_{\text{min}}(v) \text{ for other } v's \\ & \} \\ & \text{if}(a_i \text{ is any other value}) \{ \\ & \text{find } v_{t\text{-}1}, v_t \text{ in } V \text{ so that } v_{t\text{-}1} \leq a_i < v_t; \\ & \text{insert a triple } (a_i, 1, \text{int}(2\epsilon n)\text{-}1) \text{ in-between } (v_{t\text{-}1}, g_{t\text{-}1}, \Delta_{t\text{-}1}) \text{ and } \\ & (v_t, g_t, \Delta_t); \text{ // all triples before } a_i'\text{s triple have no changes} \\ & \} \text{ // all triples after } a_i'\text{s need to increase } r_{\text{min}}(v) \text{ and } r_{\text{max}}(v) \text{ by } 1 \\ \} \text{ // } r_{\text{min}}(a_i) \geq r_{\text{min}}(v_{t\text{-}1}) + 1 \text{ and } r_{\text{max}}(a_i) \leq r_{\text{max}}(v_t) = r_{\text{min}}(v_{t\text{-}1}) + 1 + g_t + \Delta_{t\text{-}1} \end{split}
```

#### Pseudocode

```
\begin{split} & \text{Compress}(S) \{ \\ & \text{for}(\ i = s\text{-}2;\ i \geq 0;\ i\text{--}) \{ \\ & \text{if}(\text{band}(\Delta_i, \text{int}(2\epsilon n)) \leq \text{band}(\Delta_{i\text{+}1}, \text{int}(2\epsilon n)) \text{ and } g_i * + g_{i\text{+}1} + \Delta_{i\text{+}1} \\ & \leq \text{int}(2\epsilon n)) \{ \\ & \text{Delete}(S, v) \text{ for all triples } (v, g(v), \Delta(t)) \text{ in } S \text{ whose ancestor is triple } (v_i, g_i, \Delta_i) \text{ (including } v_i); // g_i * := \sum_{v \text{ is a descendant of } v_i} g(v) \\ & \text{Replace}(v_{i\text{+}1}, g_{i\text{+}1}, \Delta_{i\text{+}1}) \text{ with } (v_{i\text{+}1}, g_i * + g_{i\text{+}1}, \Delta_{i\text{+}1}); \\ & \} \\ & \\ & \dots & (v_{i\text{-}c}, g_{i\text{-}c}, \Delta_{i\text{-}c}) \text{ ($v_{i\text{-}c+1}, g_{i\text{-}c+1}, \Delta_{i\text{-}c+1})$ } \dots \text{ ($v_i, g_i, \Delta_i$) } \text{ ($v_{i\text{+}1}, g_{i\text{+}1}, \Delta_{i\text{+}1}$)} \\ & \text{triple } (v_i, g_i, \Delta_i) \text{'s descendants} \end{split}
```

#### Pseudocode

```
\begin{split} & \text{Compress}(S) \{ \\ & \text{for}(\ i = \text{s-2}; \ i \geq 0; \ i\text{---}) \{ \\ & \text{if}(\text{band}(\Delta_i, \text{int}(2\epsilon n)) \leq \text{band}(\Delta_{i+1}, \text{int}(2\epsilon n)) \text{ and } \mathbf{g_i}^* + \mathbf{g_{i+1}} + \Delta_{i+1} \\ & \leq \text{int}(2\epsilon n)) \{ \\ & \text{Delete}(S, \mathbf{v}) \text{ for all triples } (\mathbf{v}, \mathbf{g}(\mathbf{v}), \Delta(t)) \text{ in } S \text{ whose ancestor } \\ & \text{is triple } (\mathbf{v}_i, \mathbf{g}_i, \Delta_i) \text{ (including } \mathbf{v}_i); // \ \mathbf{g_i}^* \coloneqq \sum_{\mathbf{v} \text{ is a descandant of } \mathbf{v} \text{ i } \mathbf{g}(\mathbf{v}) \\ & \text{Replace}(\mathbf{v}_{i+1}, \mathbf{g}_{i+1}, \Delta_{i+1}) \text{ with } (\mathbf{v}_{i+1}, \mathbf{g}_i^* + \mathbf{g}_{i+1}, \Delta_{i+1}); \\ & \} \\ & \} \\ & \dots \qquad (\mathbf{v}_{i\text{-c}}, \mathbf{g}_{i\text{-c}}, \Delta_{i\text{-c}}) \end{cases}
```

#### Definition of band( $\Delta$ , $2\varepsilon n$ )

```
band(\Delta, int(2\varepsilon n)) = \alpha so that
```

$$p - 2\alpha - (p \mod 2\alpha) < \Delta \le p - 2\alpha - 1 - (p \mod 2\alpha - 1)$$

where  $p = int(2\varepsilon n)$ .

int(2ɛn) may increase as n increase, and setting band() function as the above makes the cutting boundaries stable.

	111111111122222222233333
$2\epsilon n$	01234567890123456789012345678901234
24	
25	
26	
27	
28	
29	
30	
31	
32	
33	
34	

Figure 1: Band boundaries as  $2\epsilon n$  progresses from 24 to 34. The rightmost band in each row is band 0.

#### Definition of Descendant

Map each triple  $(v_i, g_i, \Delta_i)$  in S to a node  $X_i$  in tree T. Let R be a special node created as the root for T. Note that T has s+1 nodes.

We let  $V_j$  be the parent of  $V_i$  if j is the samllest index greater than i whose  $band(\Delta_j, int(2\epsilon n)) > band(\Delta_j, int(2\epsilon n))$ ; if no such a j exists, let R be the parent of  $V_i$ .

Claim. For any V<sub>i</sub>, its descendant nodes form a consecutive segment in S.

## Analysis

### Result

 $s = O(\epsilon^{-1}log \ \epsilon n)$ . It needs to get familiar with the above notion to understand the analysis. We may lose our focus to go through the details in class. If interested, pick up Section 2.3 (< 2 pages) in the reference paper.

## Heavy Hitter (Insertion-only)

If a value appears more than rn times, if we query the Greenwald and Kanna structure for every  $q \in [2\epsilon n, 4\epsilon n, 6\epsilon n, ..., n]$ , we can output a set K so that every value  $k \in K$  has frequency  $\geq (r-2\epsilon)n$  and every value k whose frequency  $\geq rn$  is in K.

# **Applications**

#### Convex Hull

One can use Greenswald and Kanna quantile structure to compute the convex hull of n given points in  $R^2$  in  $O(1/\delta)$  passes using  $O(h n^{\delta} \log n)$  space.

You may find more applications from the papers that cite Greenswald and Kanna's paper.