

Swipe >>>

Algorithm



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ALGORITHM #1

Time & Space Complexities

Time and Space complexities describe the amount of time and memory an algorithm takes with respect to the amount of input.

O(1) - Summing of two numbers

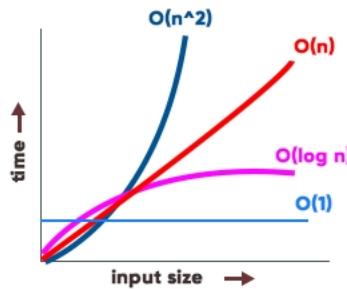
O(log n) - Looking up people in a phone book

O(n) - Finding a CD in a stack of CDs

O(n*log n) - Cutting a randomly sized bread loaf into 8 pieces but by dividing them from middle each time and then rearranging them according to their size.

O(n^2) - Asking every person his and all others health

O(2^n) - Solving Tower of Hanoi problem with n discs



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ALGORITHM #2 Quick Sort

Quick sort picks an element as pivot and move the elements less than pivot to the left and greater to the right.

Different versions of pivot logic :

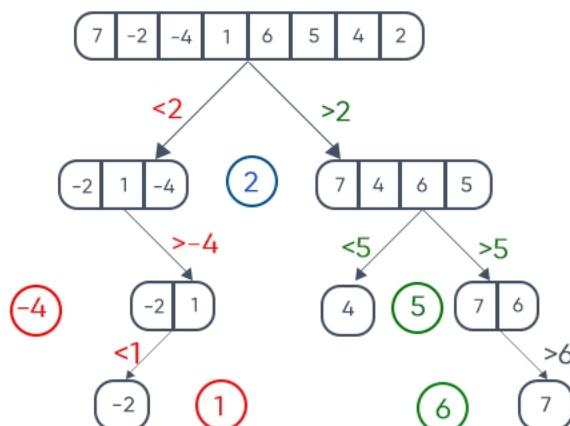
1. Pick First element
2. Pick Last element
3. Pick Random element
4. Pick Median element

Features of Quick Sort :

1. Divide-and-conquer algorithm
2. Not-stable
3. In-place

Time Complexity = $O(n \log n)$
Space Complexity = $O(\log n)$
where, n is the size

Last element pick implementation



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ALGORITHM #3 Merge Sort]

Merge sort divides the array into two halves recursively till the size becomes 1 and then merge the two sorted halves.

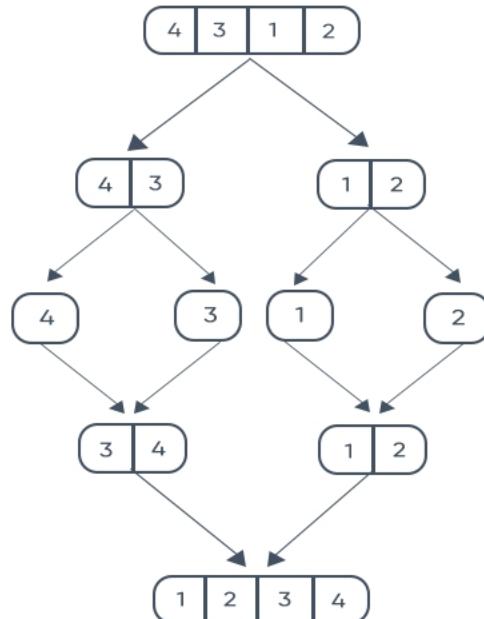
Features of Merge Sort :

1. Divide-and-conquer algorithm
2. Stable
3. Not in-place

Time Complexity = $O(n \log n)$

Space Complexity = $O(n)$

where, n is the size



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ALGORITHM #4 **Insertion Sort**

Insertion sort places an unsorted element at its suitable place in each iteration.

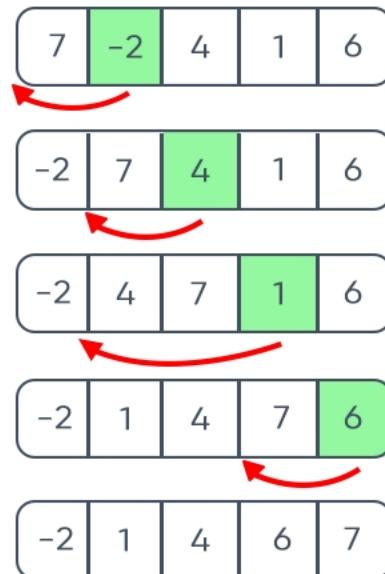
Features of Insertion Sort :

1. Stable
2. In-place

Time Complexity = $O(n^2)$

Space Complexity = $O(1)$

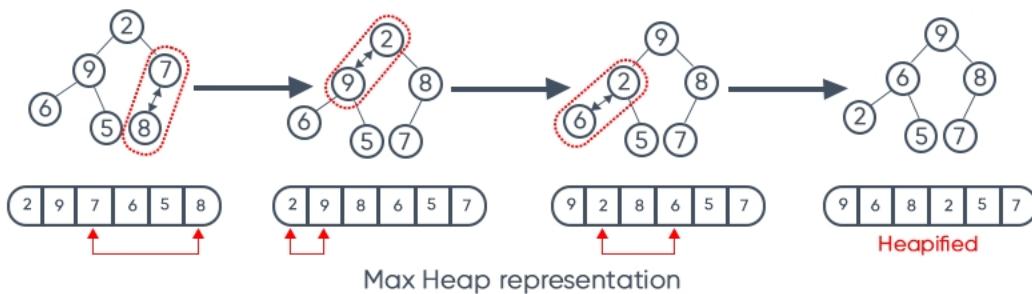
where, n is the size



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ALGORITHM #5 [Heap Sort]

Heap sort is a comparison based sorting technique where we first find the minimum/maximum element (Min/Max heap) and place at the beginning. We repeat the same process for remaining elements.



Features of Heap Sort :

1. Not Stable
2. In-place
3. Comparison based

Time Complexity = $O(n \log n)$

Space Complexity = $O(1)$
where, n is the size
{No auxiliary space}

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ALGORITHM #6

Bubble Sort

Bubble sort compares adjacent elements and swaps them if they are not in order.

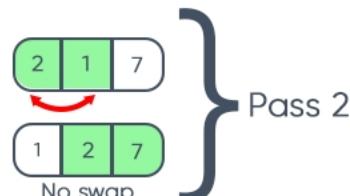
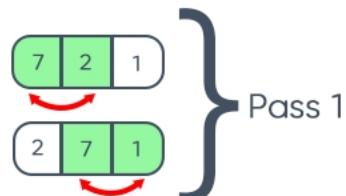
Features of Bubble Sort :

1. Stable
2. In-place

Time Complexity = $O(n^2)$

Space Complexity = $O(1)$

where, n is the size



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ALGORITHM #7 [Selection Sort]

Selection Sort recursively finds the minimum/maximun element from unsorted part of array and swaps it at the beginning.

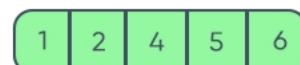
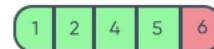
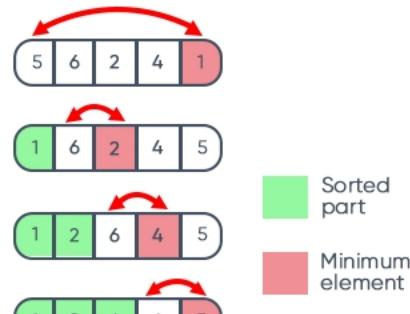
Features of Selection Sort :

1. Not Stable
2. In-place

Time Complexity = $O(n^2)$

Space Complexity = $O(1)$

where, n is the size



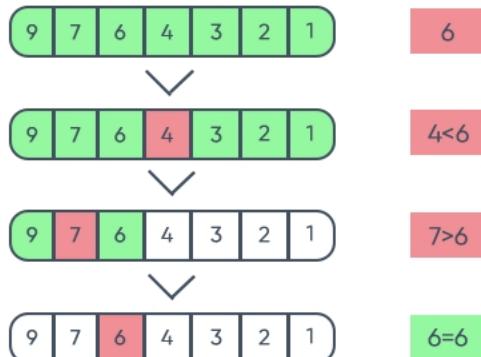
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ALGORITHM #8 [Binary Search]

Binary Search searches for an element in a sorted array by repeatedly dividing the search interval in half.

Important Points :

1. Only works on sorted arrays.
2. If value of search key is less than the middle item of interval, narrow interval to lower half, otherwise to the upper half.



Time Complexity = $O(\log n)$

Space Complexity = $O(1)$

where, n is the size

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ALGORITHM #9

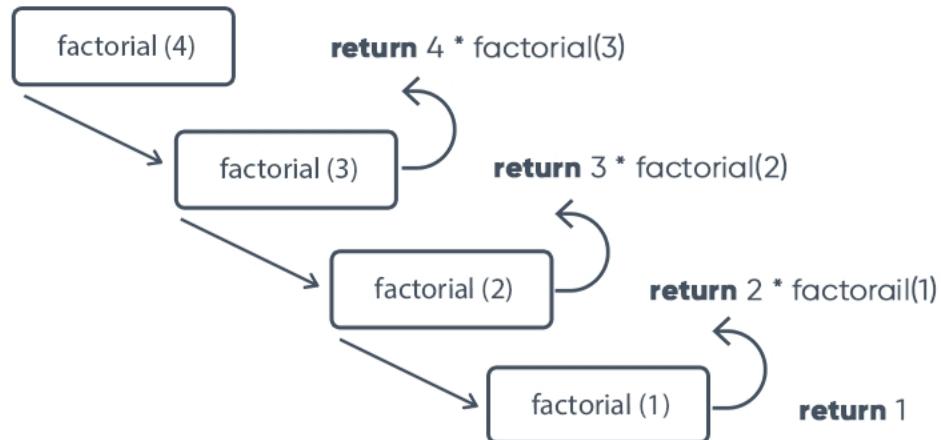
Recursion

```
function factorial(n) {  
    if (n == 1)  
        return 1;  
    return n * factorial(n-1);  
}
```

Time Complexity = O(n)

Space Complexity = O(n)

where, n is the size



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ALGORITHM #10 Sieve of Eratosthenes

The Sieve of Eratosthenes is one of the most efficient ways to find all primes smaller than n when n is smaller than 10^7 .

Pseudo code :

Let A be boolean array with default value as true,

for $i = 2, 3, 4, \dots \sqrt{n}$
if $A[i]$ is true

 for $j = i^2, i^2 + i, \dots n$
 $A[j] = \text{false}$

return all i such that $A[i]$ is true.

i = 2

2	3	4	5	6	7	8	9	10
---	---	---	---	---	---	---	---	----

i = 3

2	3	4	5	6	7	8	9	10
---	---	---	---	---	---	---	---	----

Prime Numbers

2	3	4	5	6	7	8	9	10
---	---	---	---	---	---	---	---	----

Time Complexity = $O(n \log (\log n))$

Space Complexity = $O(\sqrt{n})$

where, n is the size

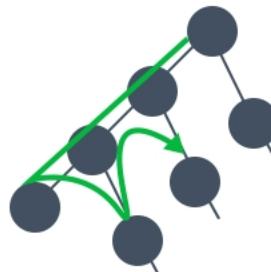
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ALGORITHM #11 Backtracking

Backtracking traces the route back upto a checkpoint from where you can again go ahead and take another route to your desired destination.

Pseudo code :

```
boolean solve(Node n)
    if n is a leaf node
        if the leaf is a goal node,
            return true
        else return false
    else
        for each child c of n
            if solve(c) succeeds,
                return true
            return false
```



Applications :

1. To find all Hamiltonian Paths.
2. To solve the N Queen problem.
3. Maze solving problem.
4. The Knight's tour problem.

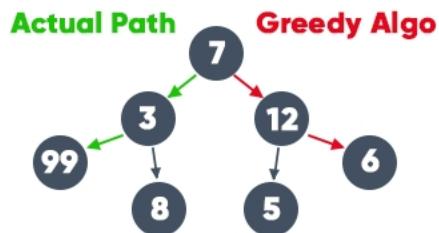
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ALGORITHM #12 Greedy

Greedy algorithm makes optimal choice at each step as it attempts to find overall optimal way to solve the problem.

Applications :

1. Finding an optimal solution
(Activity selection, Fractional Knapsack, etc).
2. Finding close to the optimal solution for NP-Hard problems like TSP.



Advantages :

1. Easy to implement.
2. Typically have less time complexities.

Disadvantages :

1. The local optimal solution may not always be global optimal.

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ALGORITHM #13 Kadane

Kadane's algorithm looks for all positive contiguous segments of the array and keep track of maximum sum contiguous segment among all positive segments.

Pseudo Code :

```
max_so_far = 0
```

```
max_ending_here = 0
```

```
loop i= 0 to n
```

```
    max_ending_here =
```

```
        max_ending_here + a[i]
```

```
    if(max_ending_here < 0)
```

```
        max_ending_here = 0
```

```
    if(max_so_far < max_ending_here)
```

```
        max_so_far = max_ending_here
```

```
return max_so_far
```



Largest Sum = 7

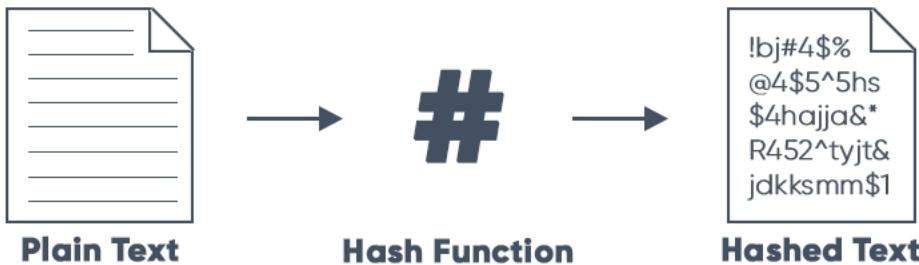
Applications :

1. Solving Maximum subarray problems.
2. Solving real-life problems involving genomic sequence analysis and computer vision.

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ALGORITHM #14 Hashing

Hashing is a one-way mathematical algorithm that maps data of arbitrary size to a hash of a fixed size.



Popular Hashing Algorithms :

1. Message Direct 5 (MD5).
2. Secure Hash Function (SHA).
3. RIPEMD.
4. Whirlpool.

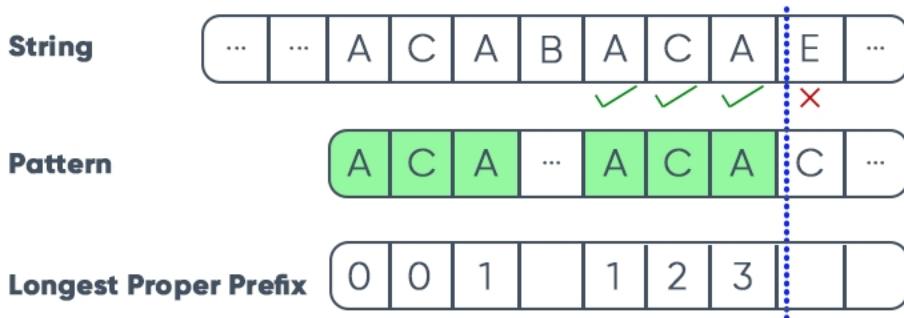
Applications :

1. Data Structures using Hash tables.
2. Message Digest.
3. Password Verification.
4. Compiler Operation.

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ALGORITHM #15 [KMP]

Knuth-Morris and Pratt (KMP) is a linear time algorithm which recognises patterns efficiently in a given string.



Applications :

1. Pattern recognition
2. Network systems
3. Database schema

Time Complexity = $O(n+m)$

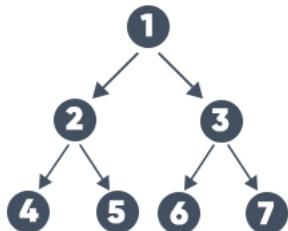
Space Complexity = $O(m)$

where, n is length of the string
m is length of pattern

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ALGORITHM #16 PreOrder, InOrder, PostOrder

Tree Traversal is a process to visit all the nodes of a tree and may print their values too.



PreOrder : 1 2 4 5 3 6 7

InOrder : 4 2 5 1 6 3 7

PostOrder : 4 5 2 6 7 3 1

PreOrder : root -> left -> right

InOrder : left -> root -> right

PostOrder: left -> right -> root

Time Complexity = $O(n+m)$

Space Complexity = $O(h)$

where, n is the number of nodes

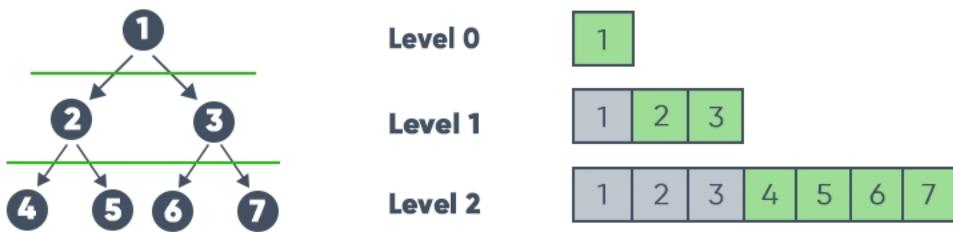
m is the number of edges

h is the height of the tree

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ALGORITHM #17 [Level Order Traversal]

Level Order Traversal is the process where we traverse every node of a level before going to the lower level.



Level Order : 1 2 3 4 5 6 7

= Deleted = Inserted

Time Complexity = $O(n)$

Space Complexity = $O(n)$

where, n is the number of nodes

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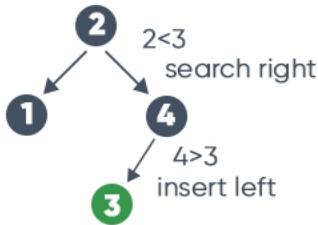
ALGORITHM #18 [Binary Search Tree]

A binary search tree (BST) is a rooted binary tree where left subtree is less and right subtree is greater than the root node.

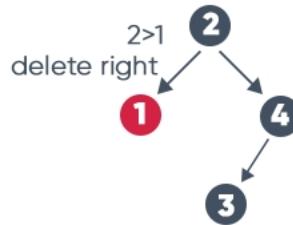
Search(4)



Insert(3)



Delete(1)



Time Complexity = $O(h)$

Space Complexity = $O(n)$

where, n is the number of nodes
h is the height of tree

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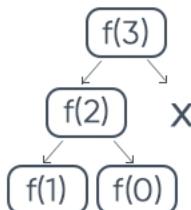
ALGORITHM #19 Dynamic Programming

Dynamic Programming solves all possible small problems and then combine to obtain solutions for bigger problems.

Dynamic Programming Methods :

1. Top-down with Memoization

Creates a memo or a “note to self” of the values returned from solving each problem.



2. Bottom-up with Tabulation

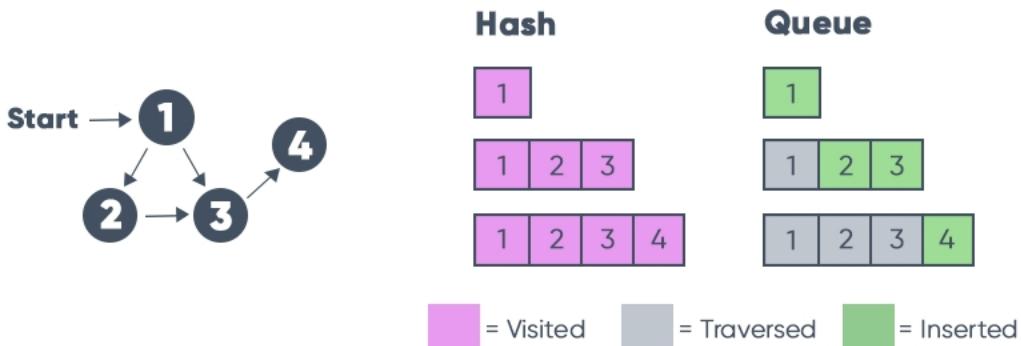
– Starts solving the sub-problems and moves up by filling up a table of n-dimensions.



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ALGORITHM #20 [Breadth First Search]

Breadth first search is a traversal algorithm that starts traversing the DS from root node and explores all the neighbouring nodes.



Applications :

1. Crawlers in Search Engines
2. GPS Navigation systems
3. Broadcasting

Time Complexity = $O(|V|)$

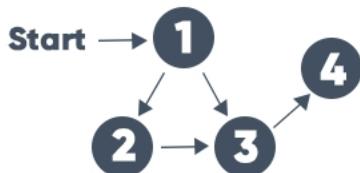
Space Complexity = $O(|V|)$

where, $|V|$ is number of nodes

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ALGORITHM #21 Depth First Search

Depth first search starts traversing the DS from root node and explores as far as possible along each branch before backtracking.



Search Order : 4 3 2 1

DFS Implementation using Stack

Applications :

1. Detecting cycle in a graph
2. Solving puzzles like mazes
3. Path Finding

Time Complexity = $O(b^m)$

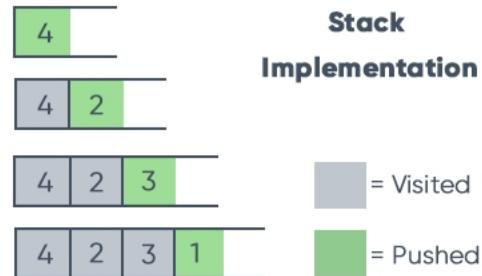
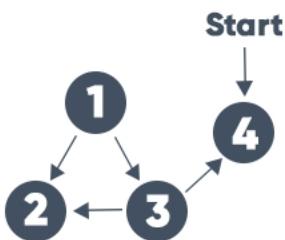
Space Complexity = $O(bm)$

where, b is branching factor
m is max depth

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ALGORITHM #22 Topological Sorting

Topological sorting takes a directed graph and returns an array of nodes where each node appears before all the nodes it points to.



Sorting Order : 1 3 2 4

Applications :

1. Maven dependency resolutions
2. Instruction Scheduling
3. Scheduling jobs

Time Complexity = $O(V+E)$

Space Complexity = $O(V)$

where, V is number of vertices
E is number of edges



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