# MATH 335 S2019

# Practice Problems for Midterm Exam II

Exam II covers chapters 3-5 ( $\nabla$  operators, suffix notation, and integral theorems). Here are a number of practice problems for the exam. The actual exam will be about the same length as the first exam.

- 1. Practice with the  $\nabla$  operator
  - (a) What is the geometrical interpretation of  $\nabla f$ ?

## Solution

If we consider the level sets of f, i.e. the curves in 2D or surfaces in 3D defined by  $f(\vec{x}) = c$ , then  $\nabla f$  points in the direction normal to the curve/surface and the magnitude of  $\nabla f$  is the rate of change of f in that direction.

(b) What are the definitions of the divergence and curl?

### Solution

The divergence is defined as

$$\nabla \cdot \vec{u} = \lim_{|\delta V| \to 0} \frac{1}{|\delta V|} \iint_{\delta S} \vec{u} \cdot \hat{n} \, dS \; ,$$

where  $\delta S$  is the surface bounding the small volume  $\delta V$ . In standard coordinates, we have  $\nabla \cdot \vec{u} = \partial_i u_i = \partial_1 u_1 + \partial_2 u_2 + \partial_3 u_3$ 

The curl is a vector valued quantity which we define in terms of its component in a given direction. Let  $\hat{n}$  be a unit vector. Then

$$\nabla \times \vec{u} = \lim_{|\delta S| \to 0} \frac{1}{|\delta S|} \int_{\delta C} \vec{u} \cdot d\vec{r} \,,$$

where  $\delta S$  is a piece of surface which is perpendicular to  $\hat{n}$  and  $\delta C$  is the boundary curve of  $\delta S$ , oriented according to the right hand rule. In standard coordinates, we can compute the curl using the mnemonic

$$abla imes ec{u} = \left| egin{array}{ccc} ec{e}_1 & ec{e}_2 & ec{e}_3 \ \partial_1 & \partial_2 & \partial_3 \ u_1 & u_2 & u_3 \end{array} 
ight|.$$

(c) Show that  $\vec{F} = (2x + y, x, 2z)$  is conservative.

# Solution

One way to show that  $\vec{F}$  is conservative is to find a function  $\phi$  such that  $\nabla \phi = \vec{F}$ . Reading off each component of  $\nabla \phi = \vec{F}$ , we get  $\partial_x \phi = 2x + y$ ,  $\partial_y \phi = x$ , and  $\partial_z \phi = 2z$ . Performing partial integration, we get  $\phi = x^2 + xy + f_1(y, z)$ ,  $\phi = xy + f_2(x, z)$ , and  $\phi = z^2 + f_3(x, y)$ . Observe that setting  $\phi = x^2 + xy + z^2$ , we get such a  $\phi$ . Thus,  $\vec{F}$  is conservative.

Alternatively, we can compute the curl of  $\vec{F}$  if  $\nabla \times \vec{F} = 0$  over a domain with no holes, then  $\vec{F}$  is conservative on that domain. We have

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{e}_1 & \vec{e}_2 & \vec{e}_3 \\ \partial_1 & \partial_2 & \partial_3 \\ 2x + y & x & 2z \end{vmatrix}$$
$$= \vec{e}_1 (0 - 0) - \vec{e}_2 (0 - 0) + \vec{e}_3 (1 - 1)$$
$$= \vec{0}$$

and  $\vec{F}$  and  $\nabla \times \vec{F}$  are well-defined everywhere (no holes) so  $\vec{F}$  is conservative.

(d) Find the gradient and Laplacian of  $\phi = \sin(kx)\sin(ly)\exp(\sqrt{k^2+l^2}z)$ 

## Solution

We have

$$\partial_x \phi = k \cos(kx) \sin(ly) \exp(\sqrt{k^2 + l^2}z)$$

$$\partial_{xx} \phi = -k^2 \sin(kx) \sin(ly) \exp(\sqrt{k^2 + l^2}z)$$

$$\partial_y \phi = l \sin(kx) \cos(ly) \exp(\sqrt{k^2 + l^2}z)$$

$$\partial_{yy} \phi = -l^2 \sin(kx) \sin(ly) \exp(\sqrt{k^2 + l^2}z)$$

$$\partial_z \phi = \sqrt{k^2 + l^2} \sin(kx) \sin(ly) \exp(\sqrt{k^2 + l^2}z)$$

$$\partial_{zz} \phi = (k^2 + l^2) \sin(kx) \sin(ly) \exp(\sqrt{k^2 + l^2}z)$$

so that

$$\nabla \phi = \begin{pmatrix} k \cos(kx) \sin(ly) \exp(\sqrt{k^2 + l^2}z) \\ l \sin(kx) \cos(ly) \exp(\sqrt{k^2 + l^2}z) \\ \sqrt{k^2 + l^2} \sin(kx) \sin(ly) \exp(\sqrt{k^2 + l^2}z) \end{pmatrix}, \qquad \Delta \phi = \nabla^2 \phi = \partial_{xx} \phi + \partial_{yy} \phi + \partial_{zz} \phi = 0$$

Note that  $\Delta \phi = 0$ , i.e.  $\phi$  is a solution of Laplace's equation (we call solutions of Laplace's equation *harmonic*).

(e) Find the unit normal to the surface  $x^2 + y^2 - z = 0$  at the point (1, 1, 2).

# Solution

This surface is a level set of  $f = x^2 + y^2 - z$  so we can use the gradient  $\nabla f = (2x, 2y, -1)$ , which is (2, 2, -1) at (1, 1, 2). To get a unit vector, we divide by the length  $\sqrt{2^2 + 2^2 + (-1)^2} = \sqrt{9} = 3$ , so we have (2/3, 2/3, -1/3).

- 2. Practicing suffix notation.
  - (a) Simplify the suffix expression  $\epsilon_{ijk}\epsilon_{klm}\epsilon_{mni}$ .

# Solution

We recall the identity  $\epsilon_{ijk}\epsilon_{klm} = \delta_{il}\delta_{jm} - \delta_{im}\delta_{jl}$ . We then have  $\epsilon_{ijk}\epsilon_{klm}\epsilon_{mni} = (\delta_{il}\delta_{jm} - \delta_{im}\delta_{jl})\epsilon_{mni}$ . Using the substitution property, i.e.  $\delta_{ij}a_j = a_i$ , we get  $(\delta_{il}\delta_{jm} - \delta_{im}\delta_{jl})\epsilon_{mni} = \epsilon_{jnl} - \delta_{jl}\epsilon_{mnm} = \epsilon_{jnl}$ .

(b) Show that  $\nabla \times (f\nabla f) = 0$ .

## Solution

$$[\nabla \times (f\nabla f)]_i = \epsilon_{ijk}\partial_j (f\partial_k f) = \epsilon_{ijk}(\partial_j f\partial_k f + f\partial_{jk} f)$$

Because the order of the derivatives and products on the right doesn't matter, this is equal to

$$[\nabla \times (f\nabla f)]_i = \epsilon_{ikj}(\partial_j f \partial_k f + f \partial_{jk} f) = -\epsilon_{ijk}(\partial_j f \partial_k f + f \partial_{jk} f) = -[\nabla \times (f\nabla f)]_i$$

Because  $[\nabla \times (f\nabla f)]_i$  is the negative of itself, it must be 0.

(c) Show that the vector field  $\vec{u} = \nabla f \times \nabla g$  is solenoidal (divergence is zero)

### Solution

$$\nabla \cdot \vec{u} = \partial_i \epsilon_{ijk} \partial_j f \partial_k g = \epsilon_{ijk} \partial_{ij} f \partial_k g + \epsilon_{ijk} \partial_j f \partial_{ik} g$$

Again, changing the order of i and j doesn't change the derivative of f in the first term and the order of i and k doesn't change the derivative of g in the second, so

$$\nabla \cdot \vec{u} = \epsilon_{iki} \partial_{ij} f \partial_k q + \epsilon_{kij} \partial_i f \partial_{ik} q = -\epsilon_{ijk} \partial_{ij} f \partial_k q + -\epsilon_{ijk} \partial_i f \partial_{ik} q = -\nabla \cdot \vec{u}$$

Because the divergence is the negative of itself, it must be 0.

(d) Use suffix notation to show that  $\nabla \cdot (\vec{u} \times \vec{v}) = \nabla \times \vec{u} \cdot \vec{v} - \nabla \times \vec{v} \cdot \vec{u}$ .

### Solution

$$\nabla \cdot (\vec{u} \times \vec{v}) = \partial_i \epsilon_{ijk} u_j v_k = \epsilon_{ijk} \partial_i u_j v_k + \epsilon_{ijk} u_j \partial_i v_k = v_k \epsilon_{kij} \partial_i u_j - u_j \epsilon_{jik} \partial_i v_k = \nabla \times \vec{u} \cdot \vec{v} - \nabla \times \vec{v} \cdot \vec{u}$$

- 3. Working with the divergence theorem.
  - (a) Let  $\vec{F} = (2x, y^2, z^2)$  and S be the sphere defined by  $x^2 + y^2 + z^2 = R^2$ . Evaluate

$$\iint_{S} \vec{F} \cdot \hat{n} \, dS$$

Solution

$$\iint_{S} F \cdot \hat{n} \, dS = \iiint_{V} \nabla \cdot \vec{F} \, dV$$

Note that  $\nabla \cdot \vec{F} = 2 + 2y + 2z$ . We will use spherical coordinates, i.e.  $x = \rho \cos(\theta) \sin(\phi)$ ,  $y = \rho \sin(\theta) \sin(\phi)$ , and  $z = \rho \cos(\phi)$  with  $dV = \rho^2 \sin(\phi) d\rho d\theta d\phi$ .

$$\begin{split} \iint_S F \cdot \hat{n} \, dS &= \iiint_V \nabla \cdot \vec{F} \, dV \\ &= \int_0^R \int_0^{2\pi} \int_0^\pi \left(2 + 2\rho \sin(\theta) \sin(\phi) + 2\rho \cos(\phi)\right) \, \rho^2 \sin(\phi) d\rho d\theta d\phi \\ &= 4\pi \int_0^R \rho^2 \, d\rho \int_0^\pi \sin\phi \, d\phi + 2 \int_0^R \int_0^\pi \rho^3 \sin^2\phi \, d\rho d\phi \int_0^{2\pi} \sin(\theta) \, d\theta \\ &+ 2\pi \int_0^R \rho^3 \, d\rho \int_0^\pi \sin(2\phi) \, d\phi \\ &= \frac{8\pi R^3}{3} \end{split}$$

(b) Use the divergence theorem to evaluate  $\iint_S x^2 + y + z \, dS$  where S is the sphere  $x^2 + y^2 + z^2 = R^2$ .

#### Solution

This one is tricky. We can figure out the normal by taking the gradient of  $f = x^2 + y^2 + z^2 - R^2$  and dividing by the length. This gives  $\hat{n} = (x/R, y/R, z/R)$ . To use the divergence theorem, we need a vector field  $\vec{F}$  such that  $\vec{F} \cdot \hat{n} = x^2 + y + z$ . Note that  $\vec{F} = (Rx, R, R)$  works. The divergence of  $\vec{F}$  is simple, i.e.  $\nabla \cdot \vec{F} = R$ , a constant. Then

$$\iint_{S} x^{2} + y + z \, dS = \iint_{S} \vec{F} \cdot \hat{n} \, dS = \iiint_{V} R \, dV = R \iiint_{V} dV = \frac{4\pi R^{4}}{3}$$

(c) Evaluate the surface integral  $\iint_S \vec{F} \cdot \hat{n} \, dS$  where  $\vec{F} = (xy^2, x^2y, y)$  and S is the surface of the cylinder  $x^2 + y^2 = R^2$  between z = 1 and z = -1, including the two disc shaped caps where  $x^2 + y^2 \le R^2$  with  $z = \pm 1$ .

#### Solution

The divergence of  $\vec{F}$  is  $\nabla \cdot \vec{F} = y^2 + x^2 + 0$ . We will integrate in cylindrical coordinates where  $\nabla \cdot \vec{F} = r^2$ . Thus

$$\iint_{S} \vec{F} \cdot \hat{n} \, dS = \iiint_{V} \nabla \cdot \vec{F} \, dV$$
$$= \int_{0}^{R} \int_{0}^{2\pi} \int_{-1}^{1} r^{2} r \, dr d\theta dz$$
$$= \frac{R^{4}}{4} 4\pi = \pi R^{4}$$

(d) Find the flux of the vector field  $\vec{F} = (x - y^2, y, x^3)$  out of the rectangular solid  $[0, 1] \times [1, 2] \times [1, 4]$ .

#### Solution

We can again use the divergence theorem. The divergence of  $\vec{F}$  is  $\nabla \cdot \vec{F} = 1 + 1 + 0 = 2$ . Then

$$\iint_{S} \vec{F} \cdot \hat{n} \, dS = \iiint_{V} \nabla \cdot \vec{F} \, dV = \iiint_{V} 2 \, dV = 6$$

where in the last equality we used that the volume of the rectangular solid is 3.

(e) Suppose  $\vec{F}$  is tangent to the closed surface S bounding a region V. Show that  $\iiint_V \nabla \cdot \vec{F} \, dV = 0$ .

### Solution

If  $\vec{F}$  is tangent to the surface, then  $\vec{F} \cdot \hat{n} = 0$  along the surface. Thus  $\iiint_V \nabla \cdot \vec{F} \, dV = \iint_S \vec{F} \cdot \hat{n} \, dS = 0$ .

- 4. Working with Stokes theorem.
  - (a) Let S be a surface and let  $\vec{F}$  be perpendicular to the tangent to the boundary of S. Show that  $\iint_S \nabla \times \vec{F} \cdot \hat{n} \, dS = 0$ .

### Solution

By Stokes' theorem  $\iint_S \nabla \times \vec{F} \cdot \hat{n} \, dS = \oint_C \vec{F} \cdot d\vec{r}$ . The second integral is zero because  $\vec{F}$  is perpendiculaar to the tangent to the boundary of S (which is the direction of  $d\vec{r}$ ).

(b) For a surface S and a fixed vector  $\vec{v}$ , prove that  $2\iint_S \vec{v} \cdot \hat{n} dS = \oint_C (\vec{v} \times \vec{r}) \cdot d\vec{r}$ , where C is the boundary ("rim") of S.

### Solution

Another tricky one.

To apply Stokes' theorem, we need the curl of  $\vec{v} \times \vec{r}$  with  $\vec{v}$  a constant.

$$\begin{aligned} [\nabla \times (\vec{v} \times \vec{r})]_i &= \epsilon_{ijk} \partial_j \epsilon_{klm} v_l r_m \\ &= (\delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}) v_l \partial_j r_m \\ &= v_i \delta_{jm} \partial_j r_m - v_j \partial_j r_i \end{aligned}$$

Note that  $\partial_i r_j = \delta_{ij}$  for  $\vec{r}$  the position vector. Further, note that  $\delta_{ij}\delta_{ij} = 3$  by taking the implied sums. Thus,

$$[\nabla \times (\vec{v} \times \vec{r})]_i = v_i \delta_{jm} \partial_j r_m - v_j \partial_j r_i$$
  
=  $v_i \delta_{jm} \delta_{jm} - v_j \delta_{ji}$   
=  $3v_i - v_i = 2v_i$ 

Then Stokes' theorem implies

$$\oint_C (\vec{v} \times \vec{r}) \cdot d\vec{r} = \iint_S \nabla \times (\vec{v} \times \vec{r}) \cdot \hat{n} \, dS = 2 \iint_S \vec{v} \cdot \hat{n} \, dS$$

(c) Let  $\vec{F}=(3y,-xz,-yz^2)$ , and let S be the surface  $2z=x^2+y^2$  below the plane z=2 (i.e. consider the parabaloid shape  $z=(x^2+y^2)/2$  between z=0 and z=2). Calculate  $\iint_S \nabla \times \vec{F} \cdot \hat{n} \, dS$  both directly and by using Stokes theorem.

#### Solution

First, we use Stokes' theorem. This gives that the flux is  $\iint_S \nabla \times \vec{F} \cdot \hat{n} \, dS = \oint_C \vec{F} \cdot d\vec{r}$ . The boundary curve of S is the circle  $x^2 + y^2 = 4$  with z = 2. We can discretize this as  $r(t) = (2\cos(t), 2\sin(t), 2)$  so that  $d\vec{r} = (-2\sin(t), 2\cos(t), 0)dt$ .

$$\begin{split} \iint_{S} \nabla \times \vec{F} \cdot \hat{n} \, dS &= \oint_{C} \vec{F} \cdot d\vec{r} \\ &= \int_{0}^{2\pi} (6 \sin(t), -4 \cos(t), -8 \sin(t)) \cdot (-2 \sin(t), 2 \cos(t), 0) \, dt \\ &= \int_{0}^{2\pi} -12 \sin^{2}(t) - 8 \cos^{2}(t) \, dt \\ &= -8 \int_{0}^{2\pi} \, dt - 4 \int_{0}^{2\pi} \sin^{2}(t) \, dt \\ &= -16\pi - 4 \int_{0}^{2\pi} \sin^{2}(t) \, dt \end{split}$$

Note that  $\int_0^{2\pi} \sin^2(t) dt = \int_0^{2\pi} \cos^2(t) dt$  so that  $2 \int_0^{2\pi} \sin^2(t) dt = \int_0^{2\pi} \sin^2(t) + \cos^2(t) dt = 2\pi$ . Thus

$$\iint_{S} \nabla \times \vec{F} \cdot \hat{n} \, dS = -16\pi - 4 \int_{0}^{2\pi} \sin^{2}(t) \, dt$$
$$= -16\pi - 4\pi = -20\pi$$

Second, we compute the flux directly. We can parameterize the surface over r and t where  $x = r \cos t$ ,  $y = r \sin t$ , and  $z = r^2/2$  with  $0 \le r \le 2$  and  $0 \le t \le 2\pi$ . It is straightforward to compute  $\nabla \times \vec{F} = (x - z^2, 0, -3 - z)$ . In these coordinates,  $\nabla \times \vec{F} = (r \cos t - r^4/4, 0, -3 - r^2/2)$ . We will use the formula for the flux over a parameterized surface which requires  $\partial_r \vec{p} \times \partial_t \vec{p}$  with  $\vec{p} = (r \cos t, r \sin t, r^2/2)$ . This is

$$\partial_r \vec{p} \times \partial_t \vec{p} = \begin{vmatrix} \vec{e}_1 & \vec{e}_2 & \vec{e}_3 \\ \cos t & \sin t & r \\ -r \sin t & r \cos t & 0 \end{vmatrix} = (-r^2 \cos t, -r^2 \sin t, r).$$

Then, we have

$$\iint_{S} \nabla \times \vec{F} \cdot \hat{n} \, dS = \int_{0}^{2} \int_{0}^{2\pi} (r \cos t - r^{4}/4, 0, -3 - r^{2}/2) \cdot (-r^{2} \cos t, -r^{2} \sin t, r) \, dr dt$$

$$\begin{split} &= \int_0^2 \int_0^{2\pi} \left( -r^3 \cos^2 t + (r^6 \cos t)/4 - 3r - r^3/2 \right) dr dt \\ &= \int_0^2 -r^3 dr \int_0^{2\pi} \cos^2 t \, dt + \int_0^2 r^6/4 dr \int_0^{2\pi} \cos t \, dt + 2\pi \int_0^2 -3r - r^3/2 \, dr \\ &= -\frac{2^4 \pi}{4} + \frac{2^7 \cdot 0}{28} - 2\pi \left( 3 \cdot 2^2/2 + 2^4/8 \right) \\ &= -4\pi - 12\pi - 4\pi = -20\pi \end{split}$$

Note that in the above, because we are using the formula for any parameterization, the area in the integral is drdt not rdrdt. Though, you can see that there is an r in the cross product of  $\partial_r \vec{p} \times \partial_t \vec{p}$ .

(d) Let  $\vec{F} = (yze^x + xyze^x, xze^x, xye^x)$ . Show that the circulation of  $\vec{F}$  around an oriented simple curve C that is the boundary of a surface S is zero.

# Solution

The curl of  $\vec{F}$  is zero (on the test, show your work). Thus, by Stokes' theorem,

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_S \nabla \times \vec{F} \cdot \hat{n} \, dS = 0$$

(e) Find the circulation of  $\vec{F} = (x^2, y^2, -z)$  around the triangle with vertices (0, 0, 0), (0, 2, 0) and (0, 0, 3), both directly and by using Stokes theorem.

#### Solution

As with the previous problem, the curl of  $\vec{F}$  is zero (on test, show your work). So, using Stokes' theorem:

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_S \nabla \times \vec{F} \cdot \hat{n} \, dS = 0$$

To compute the circulation directly, we discretize the three segments that make up the triangle C. Let  $C_1$  be  $\vec{r}_1(t) = (0, 2t, 0)$ ,  $C_2$  be  $\vec{r}_2(t) = (0, 2-2t, 3t)$ , and  $C_3$  be  $\vec{r}_3(t) = (0, 0, 3-3t)$  where t ranges from 0 to 1 over each piece. This gives

$$\int_{C_1} \vec{F} \cdot d\vec{r} = \int_0^1 (0, 4t^2, 0) \cdot (0, 2, 0) dt$$

$$= 8/3$$

$$\int_{C_2} \vec{F} \cdot d\vec{r} = \int_0^1 (0, 4 - 8t + 4t^2, -3t) \cdot (0, -2, 3) dt$$

$$= -8 + 8 - 8/3 - 9/2$$

$$\int_{C_3} \vec{F} \cdot d\vec{r} = \int_0^1 (0, 0, 3t - 3) \cdot (0, 0, -3) dt$$

$$= -9/2 + 9$$

Adding all 3 contributions we see we again get 0.

5. Show that

$$\iiint_V (\nabla f) \cdot \vec{F} \, dV = \iint_S f \vec{F} \cdot \hat{n} \, dS - \iiint_V f \nabla \cdot \vec{F} \, dV$$

Solution

We can use suffix notation to expand  $\nabla \cdot (f\vec{F})$ :

$$\nabla \cdot (f\vec{F}) = \partial_i [f\vec{F}]_i = \partial_i f\vec{F}_i + f\partial_i \vec{F}_i = \nabla f \cdot \vec{F} + f\nabla \cdot \vec{F}$$

Thus, by the divergence theorem

$$\begin{split} \iint_{S} f \vec{F} \cdot \hat{n} \, dS &= \iiint_{V} \nabla \cdot (f \vec{F}) \, dV \\ &= \iiint_{V} (\nabla f) \cdot \vec{F} \, dV + \iiint_{V} f \nabla \cdot \vec{F} \, dV \end{split}$$

which we can re-arrange to get the desired result.