

^{163}Lu - Energy Ellipsoid

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1 Calculations

The initial energy function \mathcal{H} is given in terms of the polar coordinates (θ, φ) .

1.1 Cartesian coordinate system - calculations

The maximal MOI is around 1-axis. As a result, quantization axis is the 1-axis. Thus, the coordinate system becomes:

$$\begin{cases} x_1 = I \cos \theta, \\ x_2 = I \sin \theta \cos \varphi, \\ x_3 = I \sin \theta \sin \varphi. \end{cases} \quad (1)$$

The energy function, in Cartesian form, will have the following expression:

$$H = c_0 + c_1(x_1) + c_2(x_1, x_2, x_3). \quad (2)$$

The constant (free-term) can be ignored, so we focus on the analytical expression for the last two terms, namely c_1 and c_2 .

$$c_1(x_1) = -2jA_1 \sqrt{I^2 - x_1^2} \quad (3)$$

and

$$c_2(x_1, x_2, x_3) = (A_3 - a_3)x_1^2 + (A_1 - a_1)x_2^2 + (A_2 - a_2)x_3^2 \quad (4)$$

with $a_k = \frac{A_k}{2I}$. Full calculations can be seen in the attached hand-written notes at the end of this document.

2 Features of the Energy Function - Cartesian form

Based on the expressions given in 3 and 4, one can see that:

- The energy function has an **ellipsoidal** shape, given by the *main* term c_2 .
- The contribution of the x_1 -dependent term has a negative sign and $c_1 \approx x_1$. This will create a shift in the ellipsoid, along the x_1 -direction.
- Since c_0 doesn't have any dependence on the Cartesian coordinates, it can be neglected during the graphical representation procedure.

3 Hand-written notes

$$\mathcal{H} = \frac{I}{2}(A_1 + A_2) + A_3 I^2 + I(I - \frac{1}{2}) \sin^2 \theta (A_1 \cos^2 \varphi + A_2 \sin^2 \varphi - A_3) \\ + \frac{j}{2}(A_2 + A_3) + A_1 j^2 - 2A_1 I j \sin \theta - V \frac{2j-1}{j+1} \sin\left(\gamma + \frac{\pi}{6}\right).$$

$$H(\theta, \varphi) = \underbrace{h_0}_{\text{const.}} + \underbrace{h_\theta}_{f(\theta)} + \underbrace{h_\varphi}_{g(\theta, \varphi)} \quad \left\{ \begin{array}{l} x_1 = I \cos \theta \\ x_2 = I \sin \theta \cos \varphi \\ x_3 = I \sin \theta \sin \varphi \end{array} \right. \quad \begin{array}{l} x_1 - \\ \text{maximum} \\ \text{moi} \end{array}$$

$$h_0 = \frac{I}{2}(A_1 + A_2) + A_3 I^2 + \frac{j}{2}(A_2 + A_3) + A_1 j^2 - \sqrt{\frac{2j-1}{j+1}} \sin\left[\gamma + \frac{\pi}{6}\right] \\ \rightarrow \text{constant (can be ignored)}$$

$$h_\theta = -2Ij A_1 \sin \theta = -2j A_1 \sqrt{I^2 - I^2 \cos^2 \theta} \\ = -2j A_1 \sqrt{I^2 - x_1^2} \\ \hookrightarrow x_1^2 \leq I^2 \\ |x_1| \leq I$$

$$h_\varphi = I(I - \frac{1}{2}) \sin^2 \theta (A_1 \cos^2 \varphi + A_2 \sin^2 \varphi - A_3)$$

$$a_k = \frac{A_k}{2I}$$

$$\begin{aligned} &= A_1 I^2 \sin^2 \theta \cos^2 \varphi + A_2 I^2 \sin^2 \theta \sin^2 \varphi - I^2 \sin^2 \theta A_3 - \\ &\quad - \frac{A_1}{2} I \sin^2 \theta \cos^2 \varphi - \frac{A_2}{2} I \sin^2 \theta \sin^2 \varphi + \frac{A_3 I}{2} \sin^2 \theta \\ &= A_1 x_2^2 + A_2 x_3^2 - A_3 I^2 (1 - \cos^2 \theta) - a_1 x_2^2 - a_2 x_3^2 + a_3 I^2 (1 - \cos^2 \theta) \\ &= (A_1 - a_1) x_2^2 + (A_2 - a_2) x_3^2 + A_3 x_1^2 - A_3 I^2 + a_3 I^2 - a_3 x_1^2 \\ &= (A_3 - a_3) x_1^2 + (A_1 - a_1) x_2^2 + (A_2 - a_2) x_3^2 - (A_3 - a_3) I^2 \end{aligned}$$

↑ cartesian form of H $C_2(x_1, x_2, x_3)$

$$H = h_0 - \underbrace{\left(2j A_1 \sqrt{I^2 - x_1^2} \right)}_{C_1(x_1)} + (A_3 - a_3)x_1^2 + (A_1 - a_1)x_2^2 + (A_2 - a_2)x_3^2 -$$

← cartesian expression of H

$$H = C_0 + C_1(x_1) + C_2(x_1, x_2, x_3)$$

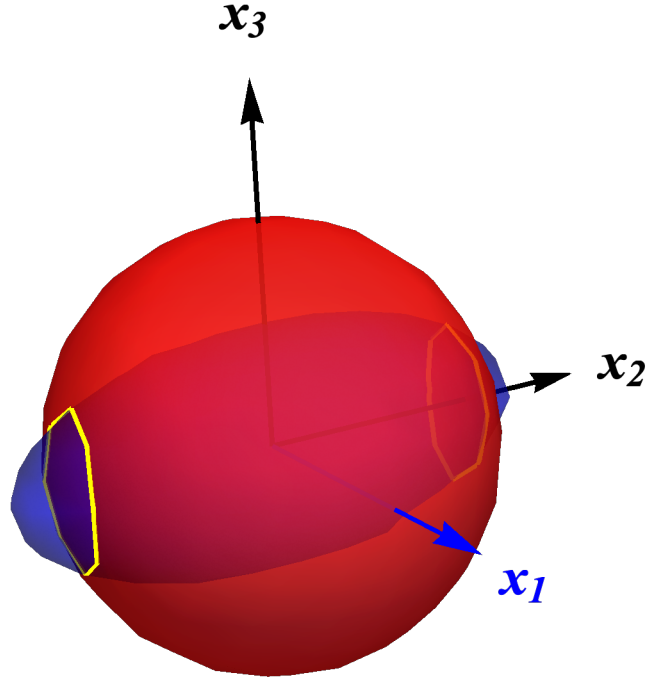


Figura 1: Energy Ellipsoid 1.

4 Energy ellipsoid: 3d representations

For the these calculations, the angular momentum is $I = 17/2$. The moments of inertia are as follows: $\mathcal{I}_1 = 72$, $\mathcal{I}_2 = 15$, $\mathcal{I}_3 = 7$.

The intersection between the angular momentum sphere (of radius $I(I+1)$) and the ellipsoid of energy E is represented by the yellow contour. By keeping I fixed, and increasing the energy E , the shape of the ellipsoid changes (according to the ratio of the three moments of inertia).

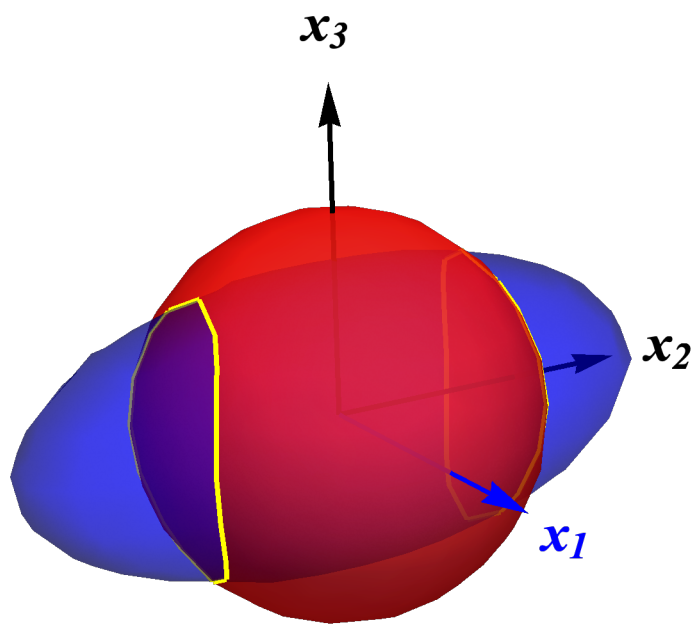


Figura 2: Energy Ellipsoid 2.

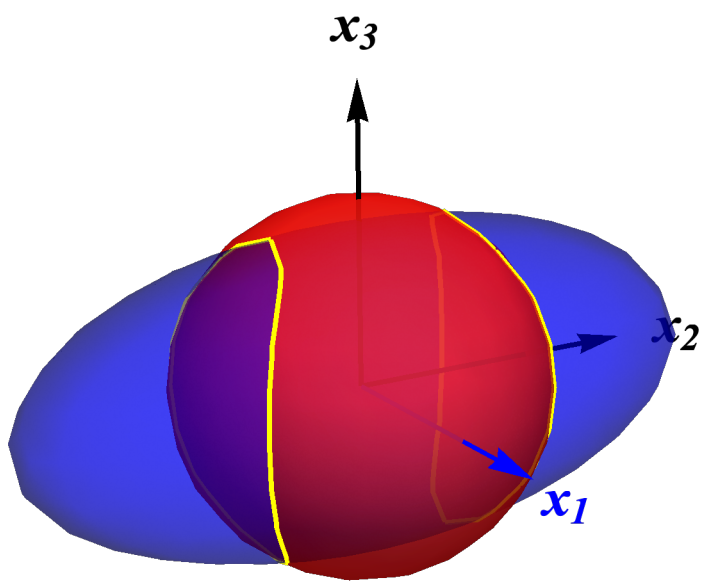


Figura 3: Energy Ellipsoid 3.

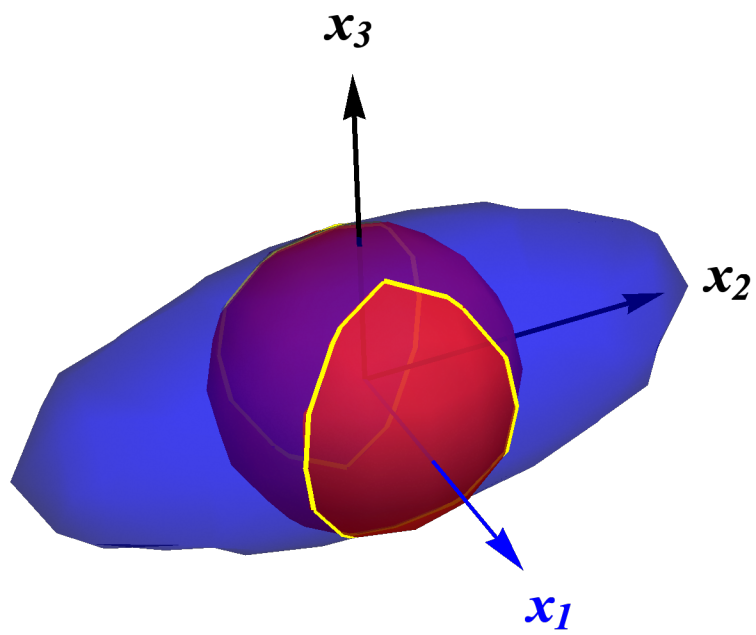


Figura 4: Energy Ellipsoid 4. One can observe that the trajectories are changed: **system starts to rotate around 1-axis.**