Airplane Simulator Design

Class Diagrams

Angle

Everything we need to know about an angle.

Angle - radian : Double + Angle() + Angle(degrees : Double) + Angle(rhs : Angle) + getDegrees(): Double + GetRadians(): Double + setDegrees(degrees : Double) + setRadians(radians : Double) + setUp() + setDown() + setLeft() + setRight() + reverse() + addOnto(delta : Double) - convertToDegrees(radians : Double) : Double - convertToRadians(degrees : Double) : Double - normalize(radians : Double

Acceleration

Everything we need to know about acceleration.

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Acceleration

- ddx : Double

- ddy : Double

+ Acceleration()
+ Acceleration(ddx : Double, ddy : Double)
+ getDDX() : Double
+ getDDY() : Double
+ setDDX(ddx : Double)
+ setDDY(ddy : Double)
+ set(a : angle, magnitude : Double)
+ addDDX(ddx : Double)
+ addDDY(ddy : Double)
+ addDDY(ddy : Double)
+ add(rhs : Acceleration)
```

Velocity

Everything we need to know about speed.

Velocity - dx : Double - dy : Double + Velocity() + Velocity(dx : Double, dy : Double) + getDX() : Double + getDY() : Double + getDY() : Double + setDX(ddx : Double) + setDY(ddy : Double) + set(a : angle, magnitude : Double) + addDX(ddx : Double) + addDY(ddy : Double) + add(rhs : Acceleration, t : Double)

Position

Everything we need to know about the position.

Position
- x : Double - y : Double
+ Position() + Position(x : Double, y : Double) + Position(rhs : Position) + assign(rhs : Position) : Position + getX() : Double + getY() : Double + equals(rhs : Position) : Boolean + notEquals(rhs : Position) : Boolean + setX(ddx : Double) + setY(ddy : Double) + addX(ddx : Double) + addY(ddy : Double)
+ add(rhs : Acceleration, v : Velocity, t : Double)

Airplane

The airplane, its status, velocity, angle, position, and fuel.

Airplane

- status : {PLAYING, SAFE, DEAD}

pos: Positionv: Velocityangle: Anglefuel: Double

+ Airplane(ptUpperRight : Position) + reset(ptUpperRight : Position)

+ isDead(): Boolean + isLanded(): Boolean + isFlying(): Boolean + getPosition(): Position + getSpeed(): Double

+ getFuel() : Int + getWidth() : Int

+ getMaxSpeed() : Double

+ draw(thrust : Thrust, gout : ogstream)

+ input(thrust : Thrust, gravity : Double) : Acceleration

+ coast(a : Acceleration, time : Double)

+ land() + crash()

Thrust

The mainEngine, the rotation, and user input of the module.

Thrust

- mainEngine : Boolean - clockwise : Boolean

- counterClockwise : Boolean

+ Thrust()

+ rotation(): Double

+ mainEngineThrust() : Double

+ isMain(): Boolean + isClock(): Boolean + isCounter(): Boolean + set(pUI: Interface)