New Functions for Multivariate Analysis

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R (and S-PLUS) used to have limited support for multivariate tests. We had the manova function, which extended the features of aov to multivariate responses, but like aov, this effectively assumed a balanced design, and was not capable of dealing with the within-subject transformations that are commonly used in repeated measurement modelling.

Although the methods encoded in procedures available in SAS and SPSS can seem somewhat old-fashioned, they do have some added value relative to analysis by mixed model methodology, and they have a strong tradition in several applied areas. It was thus worthwhile to extend R's capabilities to handle contrast tests, as well as Greenhouse-Geisser and Huynh-Feldt epsilons. The extensions also provide flexible ways of dealing with linear models with a multivariate response.

Theoretical setting

The general setup is given by

$$Y \sim N(\Xi B, I \otimes \Sigma)$$

Here, *Y* is $N \times p$ matrix and Σ is a $p \times p$ covariance matrix. The rows y_i of *Y* are independent with the same covariance Σ .

 Ξ is a $N \times k$ design matrix (the reader will have to apologise that I am not using the traditional X, but that symbol is reserved for other purposes later on) and B is a $k \times p$ matrix of regression coefficients.

Thus, we have the same linear model for all p response coordinates, with separate parameters contained in the columns of B.

Standard test procedures

From classical univariate and multivariate theory, a number of standard tests are available. We shall focus on three of them:

 Testing hypotheses of simplified mean value structure: This reduction is required to be the same for all coordinates, effectively replacing the design matrix Ξ with one spanning a subspace. Such tests take the form of generalized *F* tests, replacing the variance ratio by

$$R = MS_{res}^{-1}MS_{eff}$$

in which the MS terms are matrices which generalize the mean square terms from analysis of variance. Under the hypothesis, *R* should be distributed around the unit matrix (in the sense

that the two MS matrices both have mean Σ ; notice, however, that MS_{eff} will be rank deficient whenever the degrees of freedom for the effect is less than p), but for a test statistic we need to reduce R to a scalar measure. Four such measures are cited in the literature, namely Wilks's Λ , the Pillai trace, the Hotelling-Lawley trace, and Roy's greatest root. These are all based on combinations of the eigenvalues of R. Details can be found in, e.g., Hand and Taylor (1987).

Wilks's Λ is equivalent to the likelihood ratio test, but R and S-PLUS have traditionally favoured the Pillai trace based on the (rather vague) recommendations cited in Hand and Taylor (1987). Each test can be converted to an approximately F distributed statistic. If the tests are for a single-degree-of-freedom hypothesis, the matrix R has only one non-zero eigenvalue and all four tests are equivalent.

2. Testing whether Σ is proportional to a given matrix, say Σ_0 (which is usually the unit matrix I): This is known as Mauchly's test of sphericity. It is based on a comparison of the determinant and the trace of $U = \Sigma_0^{-1} S$ where S is the SSD (deviation sum-of-squares-and-products) matrix (MS_{res} instead of S is equivalent). Specifically

$$W = \det(U)/\operatorname{tr}(U/p)^p$$

is close to 1 if U is close to a diagonal matrix of dimension p with a constant value along the diagonal. The test statistic $-f \log W$ is an asymptotic χ^2 on p(p+1)/2-1 degrees of freedom (where f is the degrees of freedom for the covariance matrix. An improved approximation is found in Anderson (1958).

3. Testing linear hypotheses as in point 1 above, but *assuming* that sphericity holds. In this case, we are assuming that the covariance is known up to a constant, and thus are effectively in a univariate setting of (weighted) least squares theory. The relevant F statistic will have (pf_1, pf_2) degrees of freedom if the coordinatewise tests have (f_1, f_2) degrees of freedom.

Within-subject transformations

It is often necessary to consider a transformation of responses: If, for instance, coordinates are repeated measures, we might wish to test for "no change over time" or "same changes over time in different groups" (profile analysis). This leads to analysis of

within-subjects contrasts, rather than of the observations themselves.

If we assume a covariance structure with random effects both between and within subject, the contrasts will cancel out the between-subject variation. They will effectively behave *as if* the between-subject term wasn't there and satisfy a sphericity condition.

Hence we consider the transformed response YT' (which has rows Ty_i). In many cases T is chosen to annihilate another matrix X, i.e. it satisfies TX = 0; by rotation invariance, different such choices of T will lead to the same inference as long as they have maximal rank. In such cases it may well be more convenient to specify X rather than T.

For profile analysis, X could be a p-vector of ones. In that case, the hypothesis of *compound symmetry* implies sphericity of $T\Sigma T'$ w.r.t. TT' (but sphericity does not imply compound symmetry), and the hypothesis $\Xi YT' = 0$ is equivalent to a flat (constant level) profile.

More elaborate within-subject designs exist. As an example, consider a a complete two-way layout, in which case we might want to look at the sets of (a) Contrasts between row means, (b) Contrasts between column means, and (c) Interaction contrasts,

These contrasts connect to the theory of balanced mixed-effects analysis of variance. A model with "all interactions with subject are considered random", i.e. random effects of subjects, as well as random interaction between subject and rows and between subjects and columns, implies sphericity of each of the above contrasts. The proportionality constants will be different linear combinations of the random effect variances.

A common pattern for such sets of contrasts is as follows: Define two subspaces of \mathbb{R}^p , defined by matrices X and M, such that $\mathrm{span}(X) \subset \mathrm{span}(M)$. The transformation is calculated as $T = P_M - P_X$ where P denotes orthogonal projection. Actually, T defined like this would be singular and therefore T is thinned by deletion of linearly dependent rows (it can fairly easily be seen that it does not matter exactly how this is done). Putting M = I (the identity matrix) will make T satisfy TX = 0 which is consistent with the situation described earlier.

The choice of *X* and *M* is most easily done by viewing them as design matrices for linear models in *p*-dimensional space. Consider again a two-way intrasubject design. To make *T* a transformation which calculates contrasts between column means, choose *M* to describe a model with different means in each column and *X* to describe a single mean for all data. Preferably, but equivalently for a balanced design, let *M* describe an additive model in rows and columns and let *X* be a model in which there is only a row effect.

There is a hidden assumption involved in the choice of the *orthogonal* projection onto $\operatorname{span}(M)$. This calculates (for each subject) an ordinary least

squares (OLS) fit and for some covariance structures, a weighted fit may be more appropriate. However, OLS is not actually biased, and the efficiency that we might gain is offset by the need to estimate a rather large number of parameters to find the optimal weights.

The epsilons

Assume that the conditions for a balanced analysis of variance are roughly valid. We may decide to compute, say, column means for each subject and test whether the contrasts are zero on average. There could be a loss of efficiency in the use of unweighted means, but the critical issue for an *F* test is whether the sphericity condition holds for the contrasts between column means.

If the sphericity condition is not valid, then the *F* test is in principle wrong. Instead, we could use one of the multivariate tests, but they will often have low power due to the estimation of a large number of parameters in the empirical covariance matrix.

For this reason, a methodology has evolved in which "near-sphericity" data are analyzed by F tests, but applying the so-called epsilon corrections to the degrees of freedom. The theory originates in Box (1954a) in which it is shown that F is approximately distributed as $F(\varepsilon f_1, \varepsilon f_2)$, where

$$\varepsilon = \frac{\sum \lambda_i^2/p}{(\sum \lambda_i/p)^2}$$

and the λ_i are the eigenvalues of the true covariance matrix (after contrast transformation, and with respect to a similarly transformed identity matrix). One may notice that $1/p \le \varepsilon \le 1$; the upper limit corresponds to sphericity (all eigenvalues equal) and the lower limit corresponds to the case where there is one dominating eigenvalue, so that data are effectively one-dimensional. Box (1954b) details the result as a function of the elements of the covariance matrix in the two-way layout.

The Box correction requires knowledge of the true covariance matrix. Greenhouse and Geisser (1959) suggest the use of $\varepsilon_{\rm GG}$, which is simply the empirical verson of ε , inserting the empirical covariance matrix for the true one. However, it is easily seen that this estimator is biased, at least when the true epsilon is close to 1, since $\varepsilon_{\rm GG} < 1$ almost surely when p > 1.

The Huynh-Feldt correction (Huynh and Feldt, 1976) is

$$\varepsilon_{\rm HF} = \frac{(f+1)p\varepsilon_{\rm GG} - 2}{p(f-p\varepsilon_{\rm GG})}$$

where f is the number of degrees of freedom for the empirical covariance matrix. (The original paper has N instead of f+1 in the numerator for the split-plot design. A correction was published 15 years later

Vol. 7/2, October 2007

(Lecoutre, 1991), but another 15 years later, this error is still present in SAS and SPSS.)

Notice that ε_{HF} can be larger than one, in which case you should use the uncorrected F test. Also, ε_{HF} is obtained by bias-correcting the numerator and denominator of ε_{GG} , which is not guaranteed to be helpful, and simulation studies in (Huynh and Feldt, 1976) indicate that it actually makes the approximations worse when $\varepsilon_{GG} < 0.7$ or so.

Implementation in R

Basics

Quite a lot of the calculations could be copied from the existing manova and summary.manova code for balanced designs. Also, objects of class mlm, inheriting from lm, were already defined as the output from $lm(Y^*...)$ when Y is a matrix.

It was necessary to add the following new functions

- SSD creates an object of (S3) class SSD which is the sums of squares and products matrix augmented by degrees of freedom and information about the call. This is a generic function with a method for mlm objects.
- estVar calculates the estimated variancecovariance matrix. It has methods for SSD and mlm objects. In the former case, it just normalizes the SSD by the degrees of freedom, and in the latter case it calculates SSD(object) and then applies the SSD method.
- anova.mlm is used to compare two multivariate linear models or partition a single model in the usual cumulative way. The various multivariate tests can be specified using test="Pillai", etc., just as in summary.manova. In addition, it is possible to specify test="Spherical" which gives the F test under assumption of sphericity.
- mauchly.test tests for sphericity of a covariance matrix with respect to another.
- sphericity calculates the ε_{GG} and ε_{HF} based on the SSD matrix and its degrees of freedom. This function is private to the stats namespace (at least currently, as of R version 2.6.0) and used to generate the headings and adjusted pvalues in anova.mlm.

Representing transformations

As previously described, sphericity tests and tests of linear hypotheses may make sense only for a transformed response. Hence we need to be able to specify transformations in anova.mlm and mauchly.test. The code has several ways to deal with this:

- The transformation matrix can be given directly using the argument T.
- It is possible to specify the arguments X and M
 as the matrices described previously. The defaults are set so that the default transformation
 is the identity.
- It is also possible to specify X and/or M using model formulas. In that case, they usually need to refer to a data frame which describes the intra-subject design. This can be given in the idata argument. The default for idata is a data frame consisting of the single variable index=1:p which may be used to specify, e.g., a polynomial response for equispaced data.

Example

These data from the book by Maxwell and Delaney (1990) are also used by Baron and Li (2006). They show reaction times where ten subjects respond to stimuli in the absence and presence of ambient noise, and using stimuli tilted at three different angles.

```
> reacttime <- matrix(c(
+ 420, 420, 480, 480, 600, 780,
+ 420, 480, 480, 360, 480, 600,
+ 480, 480, 540, 660, 780, 780,
+ 420, 540, 540, 480, 780, 900,
+ 540, 660, 540, 480, 660, 720,
+ 360, 420, 360, 360, 480, 540,
+ 480, 480, 600, 540, 720, 840,
+ 480, 600, 660, 540, 720, 900,
+ 540, 600, 540, 480, 720, 780,
+ 480, 420, 540, 540, 660, 780),
+ ncol = 6, byrow = TRUE,
+ dimnames=list(subj=1:10,
+ cond=c("deg0NA", "deg4NA", "deg8NA",
+ "deg0NP", "deg4NP", "deg8NP")))</pre>
```

The same data are used by example(estVar) and example(anova.mlm), so you can load the reacttime matrix just by running the examples. The following is mainly an expanded explanation of those examples.

First let us calculate the estimated covariance matrix:

```
> mlmfit <- lm(reacttime~1)</pre>
> estVar(mlmfit)
        degONA deg4NA deg8NA deg0NP deg4NP deg8NP
cond
  degONA
          3240
                 3400
                        2960
                               2640
                                      3600
                                             2840
                 7400
                        3600
          3400
                               800
                                      4000
  deg4NA
                                             3400
                 3600
                        6240
  deg8NA
          2960
                               4560
                                      6400
                                             7760
  degONP
          2640
                 800
                        4560
                               7840
                                      8000
                                             7040
  deg4NP
          3600
                 4000
                        6400
                               8000 12000
                                            11200
  deg8NP
          2840
                 3400
                        7760
                               7040 11200
                                            13640
```

In this case there is no between-subjects structure, except for a common mean, so the result is equivalent to var(reacttime).

Next we consider tests for whether the response depends on the design at all. We generate a contrast transformation which is orthogonal to an intercept-only within-subject model; this is equivalent to any full-rank set of within-subject contrasts. A test based on multivariate normal theory is performed as follows.

```
> mlmfit0 <- update(mlmfit, ~0)
> anova(mlmfit, mlmfit0, X=~1)
Analysis of Variance Table

Model 1: reacttime ~ 1
Model 2: reacttime ~ 1 - 1

Contrasts orthogonal to ~1

Res.Df Df Gen.var. Pillai approx F
1 9 1249.57
2 10 1 2013.16 0.95 17.38
  num Df den Df Pr(>F)
1
2 5 5 0.003534 **
```

This gives the default Pillai test, but actually, you get the same result with the other multivariate tests since the degrees of freedom (per coordinate) only changes by one.

To perform the same test, but assuming sphericity of the covariance matrix, just add an argument to the anova call:

```
> anova(mlmfit, mlmfit0, X=~1, test="Spherical")
Analysis of Variance Table
Model 1: reacttime ~ 1
Model 2: reacttime ~ 1 - 1
Contrasts orthogonal to
Greenhouse-Geisser epsilon: 0.4855
Huynh-Feldt epsilon:
                         0.6778
 Res.Df Df Gen.var.
                         F num Df
1
     9
            1249.6
     10 1 2013.2 38.028
                                5
  den Df
         Pr(>F) G-G Pr
                               H-F Pr
1
     45 4.471e-15 2.532e-08 7.393e-11
```

It can be noticed that the epsilon corrections in this case are rather strong, but that the corrected *p*-values nevertheless are considerably more significant with this approach, reflecting the low power of the multivariate test. This is commonly the case when the number of replications is low.

To test the hypothesis of sphericity, we employ Mauchly's criterion:

Accordingly, the hypothesis of sphericity is rejected at the 0.05 significance level.

However, the analysis of contrasts completely disregards the two-way intrasubject design. To generate tests for overall effects of deg and noise, as well as interaction between the two, we do as follows: First we need to set up the idata data frame to describe the design.

```
> idata <- expand.grid(</pre>
               deg=c("0", "4", "8"),
+
               noise=c("A", "P"))
> idata
  deg noise
1
   0
          Α
2
    4
          Α
3
          Α
4
          P
    0
5
    4
          Р
6
    8
```

Then we can specify the tests using model formulas to specify the X and M matrices. To test for an effect of deg we let M specify an additive model in deg and noise and let X be the model with noise alone.

```
> anova(mlmfit, mlmfit0, M = ~ deg + noise,
       X = ^n \text{ noise},
        idata = idata, test="Spherical")
Analysis of Variance Table
Model 1: reacttime ~ 1
Model 2: reacttime ~ 1 - 1
Contrasts orthogonal to
~noise
Contrasts spanned by
~deg + noise
Greenhouse-Geisser epsilon: 0.9616
Huynh-Feldt epsilon:
                          1.2176
 Res.Df Df Gen.var.
                          F num Df
             1007.0
     10 1 2703.2 40.719
                                 2
  den Df Pr(>F) G-G Pr
                                H-F Pr
1
2
      18 2.087e-07 3.402e-07 2.087e-07
```

It might at this point be helpful to explain the roles of X and M a bit further. To do this, we need to access an internal function in the stats namespace, namely proj.matrix. This function calculates

the projection matrix for a given design matrix, i.e. $P_X = X(X'X)^{-1}X'$. In the above context, we have

```
M <- model.matrix(~deg+noise, data=idata)
P1 <- stats:::proj.matrix(M)
X <- model.matrix(~noise, data=idata)
P2 <- stats:::proj.matrix(X)</pre>
```

The two design matrices are (eliminating attributes)

```
(Intercept) deg4 deg8 noiseP
          1
               0
                    0
2
                    0
                          0
          1
               1
3
               0
                          0
          1
                   1
4
             0
                  0
          1
                          1
5
             1 0
          1
                          1
6
                  1
          1
 (Intercept) noiseP
2
          1
                 Λ
3
          1
                 0
4
          1
                 1
5
          1
6
```

For printing the projection matrices, it is useful to include the fractions function from MASS.

```
> library("MASS")
> fractions(P1)
     2 3
  2/3 1/6 1/6 1/3 -1/6 -1/6
  1/6 2/3 1/6 -1/6 1/3 -1/6
 1/6 1/6 2/3 -1/6 -1/6 1/3
 1/3 -1/6 -1/6 2/3 1/6 1/6
5 -1/6 1/3 -1/6 1/6 2/3 1/6
6 -1/6 -1/6 1/3 1/6 1/6 2/3
> fractions(P2)
 1 2 3 4
1 1/3 1/3 1/3 0 0 0
2 1/3 1/3 1/3 0 0 0
3 1/3 1/3 1/3 0 0
 0 0 0 1/3 1/3 1/3
5
 0 0 0 1/3 1/3 1/3
  0 0 0 1/3 1/3 1/3
```

Here, P2 is readily recognized as the operator that replaces each of the first three values by their average, and similarly the last three. The other one, P1, is a little harder, but if you look long enough, you will recognize the formula $\hat{x}_{ij} = \bar{x}_{i\cdot} + \bar{x}_{\cdot j} - \bar{x}_{\cdot \cdot}$ from two-way ANOVA.

The transformation T is the difference between P1 and P2

```
> fractions(P1-P2)
   1   2   3   4   5   6
1  1/3 -1/6 -1/6  1/3 -1/6 -1/6
2 -1/6  1/3 -1/6 -1/6  1/3 -1/6
3 -1/6 -1/6  1/3 -1/6 -1/6  1/3
4  1/3 -1/6 -1/6  1/3 -1/6 -1/6
5 -1/6  1/3 -1/6 -1/6  1/3 -1/6
6 -1/6 -1/6  1/3 -1/6 -1/6  1/3
```

This is the representation of \bar{x}_i . $-\bar{x}$.. where i and j index levels of deg and noise, respectively. The matrix has (row) rank 2; for the actual computations, only the first two rows are used.

The important aspect of this matrix is that it assigns equal weights to observations at different levels of noise and that it constructs a maximal set of within-deg differences. Any other such choice of transformation leads to equivalent results, since it will be a full-rank transformation of *T*. For instance:

```
> T1 <- rbind(c(1,-1,0,1,-1,0),c(1,0,-1,1,0,-1))
> anova(mlmfit, mlmfit0, T=T1,
     idata = idata, test = "Spherical")
Analysis of Variance Table
Model 1: reacttime ~ 1
Model 2: reacttime ~ 1 - 1
Contrast matrix
1 -1 0 1 -1 0
1 0 -1 1 0 -1
Greenhouse-Geisser epsilon: 0.9616
Huynh-Feldt epsilon:
  Res.Df Df Gen.var.
                         F num Df
     9
              12084
2
     10 1
              32438 40.719
1 den Df
         Pr(>F) G-G Pr
                               H-F Pr
     18 2.087e-07 3.402e-07 2.087e-07
```

This differs from the previous analysis only in the Gen.var. column, which is not invariant to scaling and transformation of data.

Returning to the interpretation of the results, notice that the epsilons are much closer to one than before. This is consistent with a covariance structure induced by a mixed model containing a random interaction between subject and deg. If we perform the similar procedure for noise we get epsilons of exactly 1, because we are dealing with a single-df contrast.

```
> anova(mlmfit, mlmfit0, M = ~ deg + noise,
+     X = ~ deg,
+     idata = idata, test="Spherical")
Analysis of Variance Table

Model 1: reacttime ~ 1
Model 2: reacttime ~ 1 - 1

Contrasts orthogonal to ~ deg

Contrasts spanned by ~ deg + noise

Greenhouse-Geisser epsilon: 1
Huynh-Feldt epsilon: 1

Res.Df Df Gen.var. F num Df
1 9 1410
```

Vol. 7/2, October 2007

```
2 10 1 6030 33.766 1

den Df Pr(>F) G-G Pr H-F Pr

1 9 0.0002560 0.0002560 0.0002560
```

However, we really shouldn't be doing these tests on individual effects of deg and noise if there is interaction between the two, and as the following output shows, there is:

```
> anova(mlmfit, mlmfit0, X = ~ deg + noise,
        idata = idata, test = "Spherical")
Analysis of Variance Table
Model 1: reacttime ~ 1
Model 2: reacttime ~ 1 - 1
Contrasts orthogonal to
~deg + noise
Greenhouse-Geisser epsilon: 0.904
Huynh-Feldt epsilon:
                         1.118
  Res.Df Df Gen.var.
                        F num Df
      9
             316.58
     10 1 996.34 45.31
  den Df
          Pr(>F) G-G Pr
                               H-F Pr
1
      18 9.424e-08 3.454e-07 9.424e-08
```

Finally, to test between-within interactions, rephrase them as effects of between-factors on within-contrasts. To illustrate this, we introduce a fake grouping f of the reacttime data into two groups. The interaction between f and the (implied) column factor is obtained by testing whether the contrasts orthogonal to ~1 depend on f.

```
> f <- factor(rep(1:2, 5))
> mlmfit2 <- update(mlmfit, ~f)
> anova(mlmfit2, X = ~1, test = "Spherical")
Analysis of Variance Table
```

Contrasts orthogonal to

Greenhouse-Geisser epsilon: 0.4691 Huynh-Feldt epsilon: 0.6758

More detailed tests of interactions between f and deg, f and noise, and the three-way interaction can be constructed using M and X settings as described previously.

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