

Numerical study of the airflow over a high-altitude pseudo-satellite wing

Adjoint Implementation

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January 17, 2024



**von KARMAN INSTITUTE
FOR FLUID DYNAMICS**

Sections

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Continuous Adjoint

1 Implementation

- Continuous Adjoint: equations available
- Steady (an unsteady version is also implemented, is just faster for validation)
- Stabilized: SUPG stabilization - same order element interpolation

Procedure

1 Implementation

Define the objective function I to minimize (eg: Drag coefficient)

```
function compute_drag(uh,ph,nΓ,dΓ,params)
    CD, _ = compute_airfoil_coefficients(uh,ph,nΓ,dΓ,params)
    return CD, CD
end

function compute_airfoil_forces(uh,ph,nΓ,dΓ,params::Dict{Symbol,Any})
    @unpack tagname,v = params
    IForce =  $\int (-ph \cdot n\Gamma + v * \text{transpose}(\nabla(uh)) \cdot n\Gamma) d\Gamma$ 
    D,L = sum(IForce)
    return D,L
end
```

Procedure

1 Implementation

Solve the primal Flow

```
function primal_steady_SUPG(params::Dict{Symbol,Any})
@unpack v, dt, dΩ, D, Ω, θ, uh = params
h = h_param(Ω, D)
updatekey(params, :h, h)
a((u, p), (v, q)) = ∫(v * ∇(v) ⊙ ∇(u) + ∇(p) ⊙ v + q * (∇ · u))dΩ + ∫(v ⊙ (conv ⊙ (uh, ∇(u))))dΩ
Rm(u, p) = conv ⊙ (uh, ∇(u)) + ∇(p)
astab((u, p), (v, q)) = ∫( τsu(uh, h, v, dt) · (uh · ∇(v) + ∇(q)) ⊙ Rm(u, p))dΩ
+ ∫( τb(uh, h, v, dt) · (∇ · v) ⊙ (∇ · u))dΩ
res_prim((u, p), (v, q)) = a((u, p), (v, q)) + astab((u, p), (v, q))
return res_prim
end
```

Procedure

1 Implementation

Solve the adjoint Flow

```
function adjoint_steady_SUPG(params::Dict{Symbol,Any})
    @unpack v, dt, dΩ, D, Ω, θ, uh = params
    h = h_param(Ω, D)
    updatekey(params, :h, h)
    Rmadj(u, p) = -uh · ∇(u) - ∇(u) · uh - ∇(p)
    Rcadj(u) = -1 .* (∇ · (u))
    a_adj((u, p), (v, q)) = ∫(v * ∇(v) ⊙ ∇(u) - q * (∇ · u))dΩ + ∫(v ⊙ Rmadj(u, p))dΩ
    a_adj_stab((u, p), (v, q)) = ∫( τsu(uh, h, v, dt) · (-uh · ∇(v) - ∇(v) · uh - ∇(q))
        ⊙ Rmadj(u, p))dΩ + -1 * ∫( τb(uh, h, v, dt) · (∇ · v) ⊙ Rcadj(u))dΩ
    res_adj((u, p), (v, q)) = a_adj((u, p), (v, q)) + a_adj_stab((u, p), (v, q))
    return res_adj
end
```

Parametrization

1 Implementation

The airfoil is parametrized using Class Shape Transformations (CST), to obtain easily airfoil-like shapes. We start from a classic NACA0012 airfoil. Identified by CST weights for top and bottom surface:

```
wu = [0.17085744048372403, 0.15451770272052714, 0.15810479767059346, 0.1359573306370066,  
      0.14221259398479932, 0.14001089993692417]  
wl = -1 .* [0.17085744048372403, 0.15451770272052714, 0.15810479767059346, 0.1359573306370066,  
            0.14221259398479932, 0.14001089993692417]
```

6 parameters for the top, and 6 for the bottom surface: $\beta_i, i = 1, \dots, 12, i = 1, \dots, 6$: top, $i = 7, \dots, 12$ bottom.

Computing Reference values

1 Implementation

Both primal and adjoint flow are solved on the original mesh Ω .

$$I = I_c + \int_{\Omega} \Psi \cdot \mathcal{R} = I_{1,ref} + I_{2,ref}$$

If we want to minimize C_D : $I_c = C_D$

$$I_2 = \text{sum}(\int (\phi u \cdot ((\nabla(uh))' \cdot uh + \nabla(ph))) d\Omega + \int (\phi p \cdot (\nabla \cdot (uh))) d\Omega)$$

Morphing mesh

1 Implementation

1. A design variable β_i is perturbed by ϵ : $\beta_i + \epsilon$
2. The airfoil boundary and the mesh move accordingly obtaining a new Ω' domain
3. Evaluate

$$I' = I'_c + \int_{\Omega'} \Psi \cdot \mathcal{R} = I_{1,i} + I_{2,i}$$

4. The sensitivity is obtained through

$$\frac{\partial I}{\partial \beta_i} = \frac{I' - I}{\epsilon}$$

Morphing mesh

1 Implementation

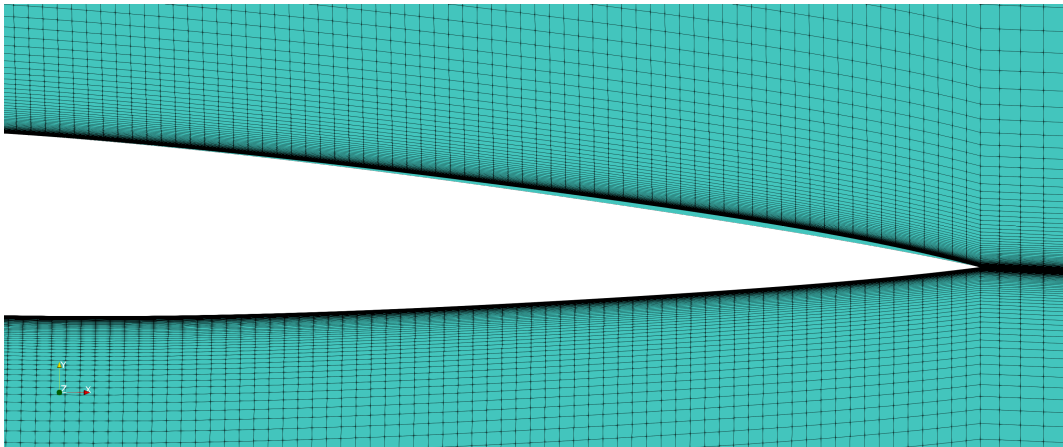


Figure: Ω in light blue, morphed mesh Ω' in black. Shift is emphasized for demonstration.

Sections

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► Implementation

► Test Cases

► Considerations

Is the Adjoint Flow Solved Correctly?

2 Test Cases

Not many quantitative solutions of the adjoint field are available. From¹ 2 adjoint flows are reported.

¹Giuseppe Sorgiovanni, Maurizio Quadrio, and Raffaele Ponzini. "A robust open-source adjoint optimization method for external aerodynamics". In: (2016).

Cylinder Reynolds 50

2 Test Cases

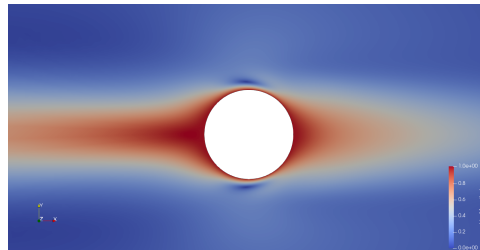
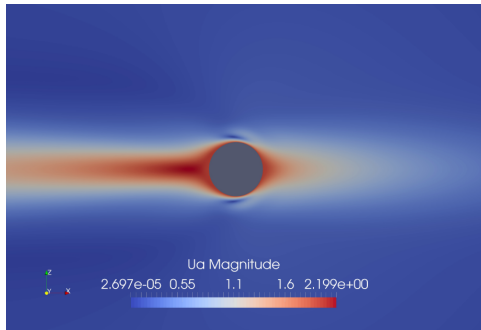


Figure: Adjoint Velocity

Cylinder Reynolds 50

2 Test Cases

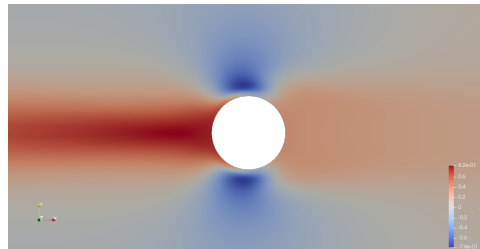
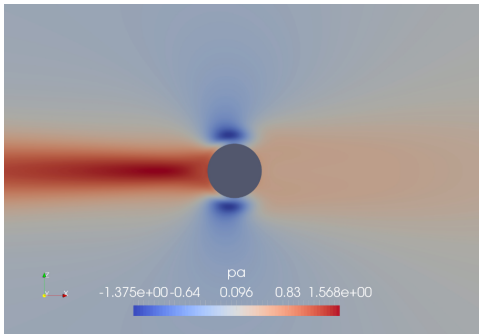


Figure: Adjoint Pressure

NACA0012 $AoA = 2.5^\circ$, $Re = 1000$

2 Test Cases

Drag minimization. Boundary conditions:

- $\Gamma_{airfoil} : \Psi_u = [-1.0, 0.0]$ or $\Psi_u = [-C_{D,0}, 0.0]$
- $\Gamma_{inlet} : \Psi_p = 0.0$
- $\Gamma_{outlet} : \Psi_u = [0.0, 0.0]$
- $\Gamma_{limits} : \Psi_u = [0.0, 0.0]$

NACA0012 $AoA = 2.5^\circ$, $Re = 1000$

2 Test Cases

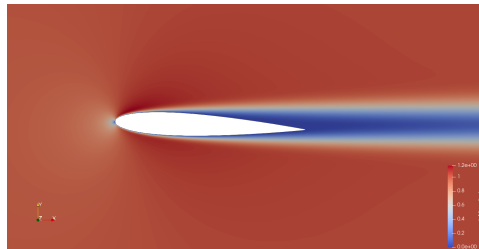
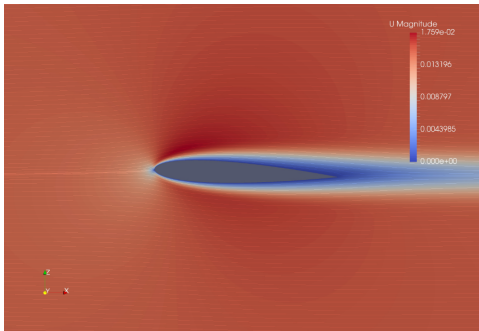


Figure: Primal Velocity

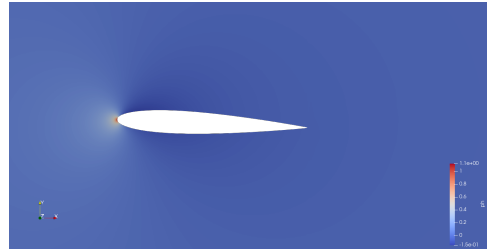
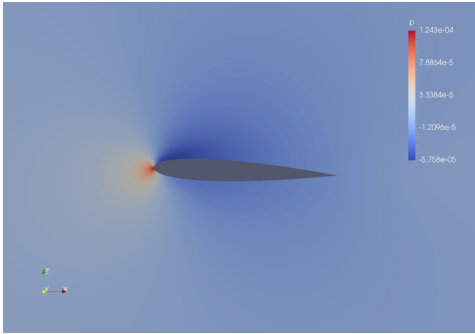


Figure: Primal Pressure

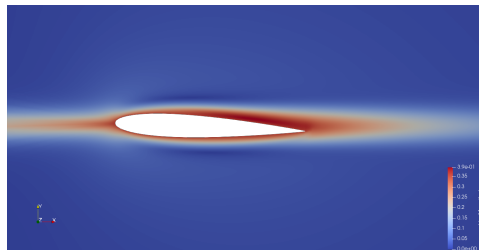
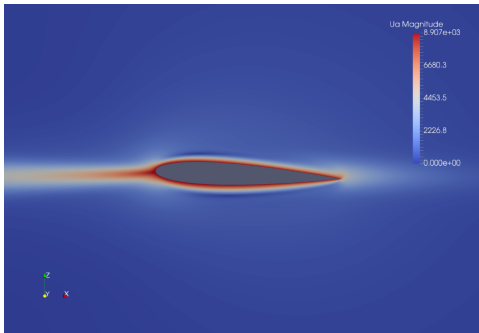


Figure: Adjoint Velocity

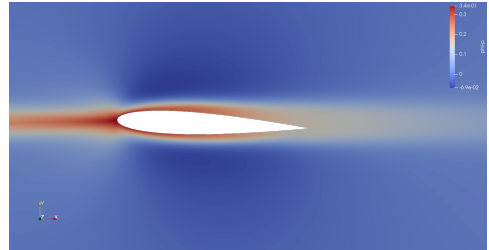
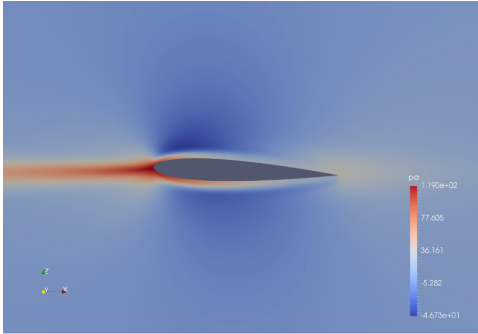


Figure: Adjoint Pressure

Finite Difference Tests

2 Test Cases

Computing the gradients for a STEADY case. NACA0012, $AoA = 0.0^\circ$, $Re=100$. In FD, each β_i is perturbed by ϵ and the flow is solved.

$$\frac{\partial C_D}{\partial \beta_i} = \frac{C'_D - C_D}{\epsilon}$$

Gradients computed with FD and Adjoint should be the same, but they are not. The perturbation ϵ is the same for FD and adjoint.

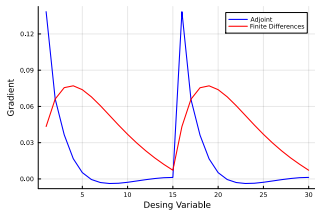


Figure: C_D gradient, finite difference vs adjoint

Finite Difference Tests

2 Test Cases

Gradients are symmetric in top and bottom design variables Order of magnitude really are close but not matching

Sections

3 Considerations

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► Considerations

- Gradients for FD and Adjoint do not depend on ϵ . $\epsilon = 0.001$, same results for $\epsilon = 0.01, 0.0001$.
- FD and Adjoint different results, but at least the sign is the same
- The adjoint results are sensible to the boundary condition on the airfoil surface. Fixing $\Psi_u = [-1.0, 0.0]$ or $\Psi_u = [-C_D, 0.0]$ impact the gradients.
- Error in boundary conditions? The error should be eliminated due to the difference $I' - I$.