TRUST Baltik Project Tutorial V1.9.5

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TRUST initialization

TRUST commands

- Load TRUST environment:
 - On CEA Saclay PCs, TRUST versions are available with: source /home/trust trio-public/env TRUST-1.9.4.sh
 - On your own computer, download and install the latest version of TRUST in your local folder \$MyPathToTRUSTversion (unless this was done), then write on the terminal:

source \$MyPathToTRUSTversion/env_TRUST.sh

Ensure that the configuration is ok and locate the sources:

- \$ echo \$TRUST_ROOT
- Now, copy a TRUST test case that we will need later:
 - \$ mkdir -p Formation_TRUST/yourname
 - \$ cd Formation_TRUST/yourname
 - \$ trust -copy upwind
 - \$ cd upwind
 - Replace "format Iml" by "format lata" in the data file





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Download Eclipse

Download Eclipse

- Visit the Eclipse Foundation website:
 http://www.eclipse.org/downloads/eclipse-packages/
- In "More Downloads", select version Eclipse 2022-09 (4.25).
- Select Eclipse IDE for C/C++ Developers → Linux 64-bits
- Download the eclipse-cpp-2022-09-R-linux-gtk-x86_64.tar.gz package in your directory Formation_TRUST/yourname

Untar the downloaded archive

- \$ cd Formation_TRUST/yourname
- \$ tar xfz eclipse-*.tar.gz
- \$ cd eclipse



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Create a TRUST platform project under Eclipse (I)

Launch Eclipse

- \$ mkdir -p Formation_TRUST/yourname/workspace
- \$ cd Formation_TRUST/yourname/eclipse
- \$./eclipse &
 - Workspace: Browse the directory Formation_TRUST/yourname/workspace
 - Welcome : close x button

Create the project

- Create a preconfigured TRUST project:
 - \$ cd Formation_TRUST/yourname
 - \$ trust -eclipse-trust
- Then, follow the instructions displayed on the terminal to import TRUST sources.

Create a TRUST platform project under Eclipse (II)

Configure the project and launch a computation

- \bullet From the "Project Explorer" tab, right click on your TRUST project \to "Debug As" \to "Debug Configurations..."
 - \Rightarrow Click on the triangle on the left of "C/C++ Application" \to Select the debug configuration already created with trust -eclipse-trust
 - The "Main" tab tells Eclipse which binary will be used:
 - ⇒ Project: your project's name
 - ⇒ "C/C++ Application": points to the TRUST \$exec_debug
 - The "Arguments" tab tells Eclipse which datafile to run:
 - \Rightarrow "Program arguments" \rightarrow specifies datafile's name (here upwind)
 - \Rightarrow "Working directory" \rightarrow contains path to datafile
 - ⇒ "Debug" : your datafile will be run with the specified executable

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Creation of a Baltik project

Create an empty Baltik

- Create a directory for your project:
 - \$ cd Formation_TRUST/yourname
- Create your project from a basic project template using TRUST commands:
 - \$ trust -baltik my_project
 - \$ cd my_project
 - \$ ls -1

You can see that you have now:

- o three directories: share, src and tests, and
- o one "project.cfg" file.
- one "RFADMF BALTIK" file.
- o one "configure" script.

Add sources to your Baltik

- Copy the following TRUST .cpp file into your baltik project:
 - \$ mkdir -p src/Trust_fixes
 - \$ cp \$TRUST_ROOT/src/MAIN/mon_main.cpp src/Trust_fixes/

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Create your git repository

Git commands

You will now create a git repository to manage your developments.

- Initialize an empty git repository:
 - \$ git init
- Display your working tree status:
 - \$ git status
- You can see 3 file and src directory on the "untracked" files section. It means that they are not yet followed by the git repository.
- Add src and project.cfg to your git repository in order to prepare a commit: \$ git add src project.cfg
- Now, you can commit your files to add it to your git repository: \$ git commit -m "Initial commit" Remark: If you are not able to commit files, you should first configure your username and email in git with: git config --global user.name "Your Name" git config --global user.email you@example.com

Create your git repository

Git commands

- Display your working tree status:
 - \$ git status
 Only README.BALTIK and configure script (automatically generated) are
 not added to your git repository.
- Display the list of commits:\$ git log

Baltik commands

- Edit your project file "project.cfg" to specify name, author and executable.
- Then configure your project:
 - \$ baltik_build_configure -execute
 this command launches both scripts: the "baltik_build_configure" and
 "configure".

Create your git repository

Git commands

- Check the status of your git repository with the "--ignored" option to see the status of all files:
 - \$ git status
- You can see that
 - "project.cfg" has been modified.
 - there are new untracked files: these files are not on the git repository
- To see only the changes on the git repository files:
 - \$ git status -uno
- Track changes via gitk (GUI interface of Git):
 - \$ gitk &

You can see information about your first commit and actual untracked changes.

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Make a basic build

- To make a basic build:
 - \$ cd Formation_TRUST/yourname/my_project
- Configure your project:
 - \$./configure
- Build your project in different modes:
 - Build an optimized (-03 option) version:
 - \$ make optim
 - Build a debug (-g -O0 option with asserts) version:
 - \$ make debug
- Initialize your baltik project environment:
 - \$ source env_my_project.sh
- Check that executables are available:
 - \$ 1s \$exec
 - \$ ls \$exec_opt
 - \$ ls \$exec_debug



Other builds

- List other options available for the make command:
 - \$ make help
- Build an :
 - optimized binary for profiling (option -pg -O3):
 - \$ make prof
 - \$ ls \$exec_pg
 - optimized binary for test coverage (option -gcov -O3):
 - \$ make gcov
 - \$ ls \$exec_gcov

Notice that TRUST optimized binary for profiling or a TRUST optimized binary for test coverage must exist in order to be able to compile your baltik's profiling or test coverage executable.

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Create a basic BALTIK project without dependency (I)

Initialize baltik environnement

\$ source env_my_project.sh

Launch Eclipse

- cd Formation_TRUST/yourname/eclipse
- \$./eclipse &

Create the project

\$ trust -eclipse-baltik
then follow the instructions displayed on the terminal.

Create a basic BALTIK project without dependency (II)

Launch a computation

- \bullet From the "Project Explorer" tab, right click MY_BALTIK \to "Debug As" \to "Debug Configurations..."
 - \Rightarrow C/C++ Application \rightarrow Select the configuration containing your baltik's name
 - In the "Main" tab:
 - ⇒ Project: MY BALTIK
 - ⇒ C/C++ Application: contains path to \$exec_debug
 - ⇒ "Apply"
 - In the "Arguments" tab:
 - ⇒ Program arguments: contains datafile's name (upwind)
 - ⇒ Working directory: path to datafile's directory
 - \Rightarrow "Apply"
 - \Rightarrow Debug



Useful shortcuts in sources

Shortcuts

- Open a cpp file from Project Explorer tab: Double click on TRUST-1.9.4 \rightarrow Kernel \rightarrow Framework \rightarrow Probleme base.cpp
 - or : Ctrl+shift+R then type $Probleme_base.cpp$
- In the cpp file: Right click on method "postraiter()"
 - ⇒ F3: Opens Declaration
 - ⇒ F4: Open Type Hierarchy
 - ⇒ Ctrl+Alt+H: Open Call Hierarchy
 - \Rightarrow "Ctrl+PageUp" and "Ctrl+PageDown": Move from a tab to another
- you can also:
 - ⇒ search files by name using: "Ctrl+shift+R"
 - ⇒ serach attributes/methods/functions/... using: "Ctrl+shift+T"

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Baltik commands

- Create a new folder for your own classes:
 - \$ mkdir -p \$project_directory/src/my_module
 - \$ cd \$project_directory/src/my_module
- Create your first class "my first class" with template:
 - \$ baltik_gen_class my_first_class

Git commands

- Display the status of your repository:
 - \$ git status .
- Add your new class to your git repository to follow your modifications:
 - \$ git add my_first_class.*
 - \$ git commit -m "Add my_first_class src"

Baltik commands

- Have a look at the 2 files my_first_class.h|cpp.
- Each time a source file is added to the project, you need to reconfigure your project to take new files into account when building the exectuable:
 - \$ cd \$project_directory
 - \$./configure
- Build your project with Eclipse or in the terminal.
- Edit the 2 files with vim|nedit|gedit|emacs.

Eclipse

- Edit the 2 files with Eclipse.
- For Eclipse use, you have to update your project to see your new files:
 - → "Index/Rebuild" from "my_project" of "Project Explorer"
 - → Click on "▶" button of "my project" in the "Project Explorer"

Baltik commands

- We want to change the inheritance of the class in order that it inherits from "Interprete geometrique base" class instead of "Objet U".
 - "Interprete geometrique base" class is the base class of all the keywords doing tasks on domains (eg: Mailler, Lire fichier,...).

So:

- o add an "#include <Interprete geometrique base.h>" in my first class.h,
- o replace "Objet U" to "Interprete geometrique base" in the .h and .cpp files,
- o Interprete geometrique base contains a pure virtual method which you should implement
- rebuild your application and an error will occur!

This error indicates that a pure virtual function ("interpreter") should be implemented.

- Look at the "Interprete geometrique base" class:
 - o in Eclipse: highlight the string "Interprete geometrique base" and push the F3 button of your keyboard to open the declaration file of this class

Baltik commands

• Look at "interpreter()" method, which calls the "interpreter_()" method. This method is called each time a keyword is read in the data file (eg: "Read file dom dom.geom", "Solve pb",...).

• Define the public method "interpreter (Entree&)" in the include file and

- implement it (just print a message with "Cerr" like "- My first keyword!") into the cpp file.

 "Entree" is a TRUST class to read an input stream (from a file for example):
 - "Entree" is a TRUST class to read an input stream (from a file for example) virtual Entree& interpreter_(Entree&) override;
- Rebuild your project and fix errors until the binary of your project is built

Test your new class

- Copy a test case to the build folder of your Baltik project:
 - \$ cd \$project_directory/build/
 - \$ trust -copy Cx
 - ERROR...

Test your new class

- The error occurs because this test case is not in your baltik but in TRUST project. To be able to copy it, you have to load the full environment (TRUST+your baltik).
 - \$ source ../full_env_my_project.sh
 - \$ trust -copy Cx
 - \$ cd Cx
- Edit the data file:
 - \$ nedit Cx.data &
 Add keywords "my_first_class" and "End" after the line where
 the problem is discretized.
- Run this datafile with your baltik binary to check that this new keyword is recognized (see next slide).

With Eclipse:

- → In the project explorer, right click on "my project" and select "Debug As/Debug configurations..."
- ightarrow In "Main" tab, check "Disable auto build" then click on "Apply"
- → In "Arguments" tab, fill "Program arguments:" with "Cx"
- → "Working directory:" Copy the path to datafile matching

\$project directory/build/Cx

- \rightarrow "Apply" and "Debug"
- → Click on "Yes" to switch to the debug view
- → Click on "Resume" button (or F8) to run the calculation until the end

On a terminal:

```
$ cd $project_directory/build/Cx/
```

```
$ exec=$exec_debug trust Cx
```

Nota bene: "Interprete geometrique base::interpreter()" method is called first, then it calls "my first class::interpreter ()" method.

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• Now, we want to read from the datafile this syntax:

```
my_new_keyword { problem pb_name option 1 }
```

and we will use Param objects as shown on the next slide.

Example of Param use

```
#include <Param h>
Entree& Class::interpreter(Entree& is)
Nom opt;
Nom pb_name;
Cerr << "Reading parameters of A from a stream (cin or file)" << finl;
Param param(que_suis_je());
// Register parameters to be read:
param.ajouter("option", & opt);
param.ajouter("problem",&pb_name,Param::REQUIRED);
// Read now the parameters from the stream is and produces an error
// if unknown keyword is read or if braces are not found at the
// beginning and the end:
param.lire_avec_accolades_depuis(is);
. . .
return is;
```

In our case, the read of the parameters will be done by the interpreter_()
method. We want to read this syntax from the data:

```
my_first_class { domaine dom option 0 }
# dom is the domain name #
```

Have a look at the "Interprete_geometrique_base" sub-class "Extruder" which is very similar to what we want. The data file syntax is:

```
Extruder { domaine DomainName nb_tranches N direction X Y Z }
```

- Add into the "my_first_class::interpreter_(Entree&)" method the read of these parameters into braces using the Param object.
- Do not forget to add "#include <Param.h>" into the my_first_class.cpp file, cause you are using now Param object.

- Now we want to obtain the domain object using its name.
 - You can have a look at the following method:
 Interprete geometrique base::associer domaine (Nom & nom dom)
 - Look for this method on the HTML documentation or via Eclipse.
 What is the task of this method?
- Once implementation is finished, add a check at the end of the method "interpreter (Entree&)" and find how to print the domain name:

```
Cerr << "Option number " << option_number << " has been
read on the domain's named " << ??? << finl;</pre>
```

- With Eclipse:
 - Build/fix/re-build your project:
 - → "Project" and "Build project"
 - Run the test case:
 - \rightarrow "Run" and "Debug"
- Or in a terminal:
 - Build/fix/re-build your project:
 - \$ cd \$project_directory
 - \$ make debug
 - Run the test case:
 - \$ cd \$project_directory/build/Cx/
 - \$ export exec=\$exec_debug
 - \$ trust Cx

In this case, TRUST runs with exec debug.

Display information about domain boundaries

- Edit the "my_first_class.cpp" file and add into the "interpreter_()" method a loop on the boundaries.
 - Look for help inside the "Domaine", "Bord", "Frontiere" classes in the HTML documentation to access to the:
 - Number of boundaries (nb_bords() method)
 - Boundaries (bord(int) method)
 - Name of the boundaries (le_nom() method)
 - Number of faces of each boundary (nb faces() method)

Print these information with something like:

```
Cerr << "The boundary named " << ??? << " has " << ??? << "
faces." << finl;</pre>
```

Modify your cpp class (Part 2)

Compute the sum of the control volumes of a domain discretized in VEF

- Information about control volumes is in the "Domaine_VF" class (a "Domaine_dis" discretized domain) which can't be accessed from the domain, but only from the problem.
 - So, you need to read another parameter in your data file:

```
my_first_class { domaine dom option 0 problem pb }
```

- Add the read of a new parameter problem into "my_first_class.cpp" file (see "Extraire_plan::interpreter_(Entree&)" method for instance).
- Remember the "equation" or "problem" UML diagram of the presentation's slides.
- Look for help inside the "Domaine_VF", "Probleme_base" and "Domaine_dis_base" into the HTML documentation to access to the:
 - discretized domain (domaine dis() method)
 - o control volumes (volumes entrelaces() method)

Modify your cpp class (Part 2)

- You will need to cast the discretized domain returned by the domaine_dis() method into a "Domaine_VF" object.
- Print the size of the control volumes array with something like:

```
Cerr << control_volumes.size() << finl;</pre>
```

Where control_volumes is a **DoubleVect** returned by the **Domaine VF::volumes entrelaces()** method.

- If you look at the "Problem" UML diagram of the presentation's slides, you will notice a better path to access to the discretized domain.

 What is this path?
- Now, compute and print the sum of the control volumes with a "for" loop.

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Create automated documentation

- We want now to add XData tag to create the automated documentation of your new code.
- First we have to create this documentation for the first time.
 - \$ cd \$project_directory
 - \$ make gui
- Open the documentation file:
 - \$ evince \$project_directory/build/xdata/XTriou/doc.pdf &
- Now we will add comments in our cpp files to add information in the documentation.
- For this open the help of the TRAD_2 syntaxe:
 \$ gedit \$project_directory/build/xdata/XTriou/doc_TRAD_2 &

Create automated documentation

 Add a first tag (in comments) into your cpp file just after the openning brace of the 'interpreter_()' method:

```
// XD english_class_name base_class_name TRUST_class_name
mode description
```

- The "english_class_name" and "TRUST_class_name" can be "my_first_class".
- The "base_class_name" is the name of the section in which will appear the information of your new class in the 'doc.pdf' file.
- The "mode" is to choose with the help of the doc_TRAD_2 file. Here we use "-3".

Create automated documentation

Then add at the end of the lines of type "param.ajouter...", an XD comment like:

```
param.ajouter(...); // XD_ADD_P type description
where "type" can be (cf 'doc_TRAD_2' file): 'int', 'floattant', 'chaine',
'rien'...
```

- Compile the documentation:
 - \$ make gui
- Check that the documentation of your new class is in the new doc:
 \$ evince \$project_directory/build/xdata/XTriou/doc.pdf &
- To check that the GUI is validated:
 - \$ make check_gui
- Notice that you must have XD commands in all your cpp classes.

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- Edit the "\$project_directory/src/Trust_fixes/mon_main.cpp" file of your baltik project using text editor or Eclipse.
- Add these lines after "Process::imprimer_ram_totale(1);" : std::cout << "Hello World to cout." << std::endl; std::cerr << "Hello World to cerr." << std::endl; Cout << "Hello World to Cout." << finl; Cerr << "Hello World to Cerr." << finl; Process::Journal() << "Hello World to Journal." << finl;</p>

in a terminal: Rebuild the code

```
$ cd $project_directory
```

\$ make debug optim

- Create an empty data file:
 - \$ mkdir -p \$project_directory/build/hello
 - \$ cd \$project_directory/build/hello
 - \$ touch hello.data
- Run the code
 - sequentially:
 - \$ trust hello
 - in parallel:
 - \$ trust hello 4

and see the differences.

- "Cout" is equivalent to "std::cout" on the master process only. Use this
 output for infos about the physics (convergence, fluxes,...).
- "Cerr" is equivalent to "std::cerr" on the master process only. Use this output for warning/errors only.
- "finl" is equivalent to "std::endl" + "flush()" on the master process.
- "Journal()" prints to "datafile_000n.log" files. Use this output during parallel development to print plumbing infos which would be hidden during production runs.

- During a parallel run, the "Journal()" output can be disabled.
 To verify this, first clean your folder:
 - \$ ls *.log
 - \$ trust -clean

and run computation with -journal=0 option

- \$ trust hello 4 -journal=0
- \$ ls *.log
- Other options are available. To get it, run:
 - \$ trust hello.data -help_trust

Printing into a file

- Now, we will print the control volumes sum into a file for test case Cx.
- We want to write in a file with name similar to:
 DataFileName_result.txt
 where "DataFileName" is the name of the data file (eg: Cx).
- For that, you will:
 - create an object of the class Nom and fill it by collecting the datafile's name using Objet U::nom du cas() method.
 - complete the datafile's name with the string "_result.txt" thanks to the "operator+=" method of the class Nom.
 - create the output file with the SFichier class and print the sum into it.
- Compile your project and run Cx datafile:
 - \$ cd \$project_directory/build/Cx/
 - \$ exec=\$exec_debug trust Cx
- Then open the "Cx result.txt" file.



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Part 1

- Run your test case Cx in parallel mode:
 - \$ cd \$project_directory/build/Cx/
 - \$ trust -partition Cx 2 # Partition in 2 subdomains
 - \$ trust PAR_Cx 2 # 2 processes used
- Compare the files: Cx_result.txt, PAR_Cx_result.txt.
 Differences come from the fact that the 2 processors write into the file one after the other one. So the final content will be the value calculated on the last processor which will acces to the file.
- You can try to launch one more time the calculation, the result may differ.
- To have the entire sum, you can apply the mp_sum() method on the sum obtained and add the print in the .txt file.
- Compare it to the sum obtained in the sequential run.
- It is better but we counted several times faces that belongs to the joint and to the virtual zones.

Part 1

- To parallelize the algorithm, rewrite it with the help of the mp_somme_vect(DoubleVect&) method.
- Add this print in the .txt file.
- You should find the same value for the sequential and parallel calculation.

Part 2 (Optional)

- Create a "verifie" script to check the resulting value (sequential then parallel).
- Add a call to "compare sonde" in your "verifie" script...

Part 3

- To validate parallelization in TRUST, you can use the command "compare lata":
 - \$ ls *lata
 - \$ compare_lata Cx.lata PAR_Cx.lata

Part 3

- You can see that there is no differences and the maximal relative error encountered is about 4.e-12.
- Performances \$ 1s *TU
 - \$ meld Cx.TU PAR_Cx.TU &
 - \$ meld Cx_csv.TU PAR_Cx_csv.TU &

Part 4 Debog

- Copy a debog test case:
 - \$ cd \$project_directory/build
 - \$ trust -copy Debog_VEF
 - \$ cd Debog_VEF
- Open the Debog VEF.data file and search the "Debog" command.
- Sequential run:
 - \$ trust Debog_VEF
- You get "seq" and "faces" files.

Part 4 Debog

- Partitionning step and creation of the parallel data file:
 - \$ trust -partition Debog_VEF 2
- Verify the parallel data file, you must have now "Debog pb seg faces 1.e-6 1".
- Run in parallel:
 - \$ trust PAR_Debog_VEF 2
- You get debog*.log and DEBOG files.
- If a value of an array differs between the two calculations and the difference is greater than 1.e-6 then "ERROR" message appears in the log files else we will get "OK" (cf debog.log).
- Add a debog instruction in your file mon main.cpp located in \$project directory/Trust fixes, after the "Hello world" prints put: double var = 2.5; Debog::verifier("- Debog test message",var);
- Do not forget to add the "#include <Debog.h>"!

Part 4 Debog

- Then compile and do the sequential run.
- You can see a first message.
- Then do the parallel run and check the debog.log file.
- Becarefull the debog instruction in the data file must be between the "Discretize" and "Read pb" lines.
- For more information:
 - \$ trust -doc &
 - → Open the TRUST Generic Guide
 - → Click onto the TRUST Reference Manual
 - \rightarrow Search for "Debog" keyword.



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New share/Validation/Rapports_automatiques

Baltik commands

- Create a new Jupyter validation form:
 - \$ cd Formation_TRUST/yourname/upwind
 - \$ trust -jupyter
- Now you have a upwind.ipynb file (i.e. a new Jupyter notebook).
- You have to add this notebook into your baltik:
 - \$ cd \$project_directory
 - \$ cd share/Validation/Rapports_automatiques
- Create a new directory for your new validation form:
 - \$ mkdir -p upwind/src
- Add the needed files (data file, mesh & .ipynb file):
 - \$ cp Formation_TRUST/yourname/upwind/upwind.data upwind/src
 - \$ cp Formation_TRUST/yourname/upwind/upwind.geo upwind/src
 - \$ cp Formation_TRUST/yourname/upwind/upwind.ipynb upwind/

New share/Validation/Rapports_automatiques

Git commands

- Add it to your git repository:
 - \$ git add upwind
 - \$ git commit -m "New validation notebook"

Baltik commands

- Run this Jupyter notebook:
 - \$ cd upwind/
 - \$ Run_fiche
- Build directly a PDF report from the notebook:
 - \$ Run_fiche -export_pdf
- Open the pdf report:
 - \$ evince build/rapport.pdf &



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Baltik commands

- Create automatically the non-regression test case:
 - \$ cd \$project_directory
 - \$ make check_optim
 - Creation of upwind_jdd1
 - Creation of upwind jdd1/lien fiche validation
 - Extracting test case (upwind.data) ...End.
 - Creation of the file upwind_jdd1.lml.gz

...

 $\bullet \to \mathsf{You}$ can see in the report table that PAR_upwind_jdd1 has crashed: "CORE" message.

Git commands

- Lets check the git status before solving this problem:
 - \$ git status -uno
- A new test case based on your validation form has been created in the directory:
 - \$project_directory/tests/Reference/Validation/upwind_jdd1

Baltik commands

- Now we want to correct the error, so copy the test case:
 - \$ cd \$project_directory/build
 - \$ trust -copy upwind_jdd1
 - ERROR...
- We have to re-run the configure script to take into account the new test case:
 - \$ cd \$project_directory
 - \$./configure
 - \$ cd build
 - \$ trust -copy upwind_jdd1

Baltik commands

- Now we will analyse the error:
 - \$ cd upwind_jdd1
 - \$ trust -partition upwind_jdd1
 - \$ trust PAR_upwind_jdd1 2
- Correct the data file PAR_upwind_jdd1.data and re-run it.
- If it's ok, update the data file in \$project_directory/share/Validation/Rapports_automatiques/upwind/src ("Scatter ../upwind/DOM.Zones dom" → "Scatter DOM.Zones dom")
- To Relaunch the last test cases which do not run:
 - \$ cd \$project_directory
 - \$ make check_last_pb_optim Changement du jeu de donnees...

suite a une modification d'un jeu de donnees de la fiche de validation associee.

...

Successful tests cases :1/1

Git commands

Add this non-regression test in configuration:

```
$ git status -uno
$ git add
```

tests/Reference/Validation/upwind_jdd1/upwind_jdd1.data

• Commit the modifications on your git repository:

```
$ git commit -m "New reference test"
```

\$ git log

Baltik commands

- To run all the non regression tests with a optimized binary:
 - \$ make check_all_optim
- To run all the non regression tests with a debug binary:
 - \$ make check_all_debug
- To create an archive to share your work:
 - \$ make distrib
 - \$ 1s
- You have now an archive in tar.gz format of your baltik project.

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Code coverage exercise

- We want to run test cases using rational Runge-Kutta scheme of ordre 2.
 - For this go to the Doxygen documentation of RRK2 class to see the methods of this class.
 - Use the "trust -check function|class|class::method" command to find and launch tests cases
 - For example:
 - \$ trust -check RRK2::RRK2

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Debug with GDB

With Eclipse:

Run a test case with GDB:

- ightarrow "Debug As" and "Debug configurations..." from "my project"
- ightarrow in "Arguments", "Program arguments:" upwind
- → "Working directory:" Formation TRUST/yourname/upwind/
- \rightarrow "Apply" and "Debug"

For more information about GDB commands, refer to the help menu.

Or in a terminal:

- Run a test case with GDB:
 - \$ cd Formation_TRUST/yourname/upwind/
 - \$ exec=\$exec_debug trust -gdb upwind
- You are now in GDB.
- Add a breakpoint and stop into the SSOR preconditionner: (gdb) break SSOR::ssor

Debug with GDB

- Run the test case: (gdb) run upwind
- Have a look at the stack (gdb) where
- Go to the next instruction: (gdb) n
- Print an array: (gdb) print tab1
- Or print matrice.tab1_ if "optimized out" message printed: (gdb) print tab1[10]
- Print only a value of an array:
 (gdb) dumpint tab1 # Dump the array
 (gdb) print tab1.size_array() # Array size
 - (gdb) up
 - (gdb) list 100

Debug with GDB

• Print lines after the 100th line: (gdb) print matrice (gdb) print matrice.que_suis_je() # Kind of matrix ? (gdb) print matrice.que_suis_je().nom_ # Kind of matrix ? (gdb) up 5 # Move up 5 levels (gdb) list 900 Print others variables: (gdb) # Pressure field (gdb) print la_pression.que_suis_je().nom_ (gdb) # Pressure values (DoubleTab) (gdb) print la_pression.valeurs() (gdb) # DoubleTab dimension (gdb) print la_pression.valeurs().nb_dim() (gdb) # Dump the field values (gdb) dumptab la_pression.valeurs()

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Find memory bugs with valgrind

- Run a test case with Valgrind:
 - \$ cd \$project_directory
 - \$ source env_my_project.sh
 - \$ cd build/Cx/
 - \$ VALGRIND=1 trust Cx
- The Valgrind messages appear on the screen with the beginning of each line the same number. For example:
 - \$ ==26645== ...
- The last line indicates if errors have occurred. An example with 0 error:
 - \$ ==26645== ERROR SUMMARY: 0 errors from 0 contexts
 (suppressed: 0 from 0)
- Now we will modify the sources in your baltik project to generate a Valgrind error on the Cx test case.

Find memory bugs with valgrind

- Edit the "my_first_class.cpp" file and remove the initialization of the sum to calcule the total of control volumes.
 In place of "double sum=0;", put only "double sum;".
- Rebuild your project and run the test case:
 - \$ cd \$project_directory
 - \$ make debug optim
 - \$ cd build/Cx/
 - o in mode optim:
 - \$ exec=\$exec_opt trust Cx
 In this case, no error appears.
 - o in mode debug:
 - \$ exec=\$exec_debug trust Cx
 In this case also, no error appears.
 - o in mode valgrind:
 - \$ VALGRIND=1 exec=\$exec_opt trust Cx
 On the other hand, in this case, there are errors.
 - \$ ==7517== ERROR SUMMARY: 187 errors from 109 contexts

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For more

- You can find the commented solution of the exercise:
 - \$ cd \$TRUST_ROOT/doc/TRUST/exercices/my_first_class
- You can practice on a tutorial:
 - \$ cd \$TRUST_ROOT/doc/TRUST/exercices/
 - \$ evince equation_convection_diffusion/rapport.pdf &

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Create a TRUST platform project under Eclipse (I)

On a terminal

Load TRUST environment and copy "upwind" test case as described on p.4:

- \$ echo \$TRUST_ROOT/src
- \$ echo \$exec_debug

Launch Eclipse

- \$ mkdir -p Formation_TRUST/yourname/workspace
- \$ cd Formation_TRUST/yourname/eclipse
- \$./eclipse &
 - Workspace: Browse the directory Formation_TRUST/yourname/workspace
 - Welcome : close x button

Create a TRUST platform project under Eclipse (II)

Create the project

- File \rightarrow New \rightarrow C/C++ Project \rightarrow C++ Managed Build
 - ⇒ Project name: TRUST-X.Y.Z (e.g.: TRUST-1.8.2)
 - \Rightarrow Project type: "Executable" \rightarrow "Empty Project"
 - ⇒ Toolchains: "Linux GCC"
 - \Rightarrow Finish

Import TRUST source files into the project

- \bullet From the "Project Explorer" tab, right click on TRUST-X-Y-Z \rightarrow "Import..."
 - \Rightarrow General \rightarrow File System \rightarrow Next
 - ⇒ From directory: copy the string matching \$TRUST_ROOT/src/
 - ⇒ Check "Select All"
 - ⇒ Into folder: TRUST-X.Y.Z
 - \Rightarrow Finish
 - \Rightarrow Wait to have 100% at the bottom right corner of the window (C/C++ indexer).

Create a TRUST platform project under Eclipse (III)

Configure the project and launch a computation

- ullet From the "Project Explorer" tab, right click on TRUST-X.Y.Z o Properties
 - \Rightarrow Builders: uncheck "CDT Builder" \rightarrow OK \rightarrow apply and close
- From the "Project Explorer" tab, right click on TRUST-X.Y.Z \rightarrow "Debug As" \rightarrow "Debug Configurations..."
 - \Rightarrow Right click on "C/C++ Application" \rightarrow New configuration
 - In the "Main" tab (tell Eclipse which binary will be used):
 - ⇒ Project: TRUST-X.Y.Z
 - \Rightarrow "C/C++ Application": copy the string matching \$exec_debug
 - \Rightarrow "Apply"
 - In the "Arguments" tab (tell Eclipse which datafile to run):
 - \Rightarrow "Program arguments" \rightarrow specify datafile's name (here upwind)
 - \Rightarrow "Working directory" \rightarrow uncheck "Use default" and type path to datafile
 - ⇒ "Apply"
 - ⇒ "Debug": your datafile will be run with the specified executable

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Create a basic BALTIK project without dependency (I)

Initialize baltik environnement

```
$ source env_my_project.sh
```

\$ echo \$project_directory/src

Launch Eclipse

```
$ cd Formation_TRUST/yourname/eclipse
```

\$./eclipse &

Create the project

- File \rightarrow New \rightarrow Project \rightarrow C/C++ \rightarrow "Makefile Project with Existing Code"
 - ⇒ Project name: MY BALTIK
 - ⇒ Existing Code Location: copy string matching \$project_directory/src
 - ⇒ Toolchain for Indexer Settings: "Linux GCC"
 - \Rightarrow Finish
 - \Rightarrow Wait to have 100% at the bottom right corner of the window (C/C++ indexer).

Create a basic BALTIK project without dependency (II)

Configure the BALTIK project and link it with TRUST

- ullet From the "Project Explorer" tab, right click on MY_BALTIK o Properties
 - ⇒ Builders: check "CDT Builder"
 - \Rightarrow C/C++ Build :
 - Builder Settings: Build directory: \${workspace_loc:/MY_BALTIK}/../ or copy the string matching \$project_directory/
 - Behavior: check "Build (Incremental build)": debug optim (instead of all)
 - \Rightarrow Project References: check your TRUST project \rightarrow Apply and Close

Build the BALTIK project

From the "Project Explorer" tab, right click MY_BALTIK \rightarrow Index \rightarrow Rebuild \Rightarrow Wait to have 100% at the bottom right corner of the window (C/C++ indexer).

Right click MY BALTIK → Build Project



Create a basic BALTIK project without dependency (III)

Launch a computation

- \bullet From the "Project Explorer" tab, right click MY_BALTIK \to "Debug As" \to "Debug Configurations..."
 - \Rightarrow C/C++ Application \rightarrow New configuration
 - In the "Main" tab:
 - ⇒ Project: MY_BALTIK
 - \Rightarrow C/C++ Application: $\{\text{workspace_loc:/MY_BALTIK}\}$../my_project or copy the string matching $\{\text{exec_debug}\}$
 - ⇒ "Apply"
 - In the "Arguments" tab:
 - \Rightarrow Program arguments \rightarrow specify the name of your datafile (upwind)
 - \Rightarrow Working directory \rightarrow uncheck "Use default" and type path to datafile's directory
 - ⇒ "Apply"
 - \Rightarrow Debug

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TPP files in Eclipse

tpp format in TRUST is not natively recognized by eclipse and code is not highlighted. If you want to edit tpp files, you can:

- open Eclipse
- click on "Window" then select "Preferences"
- search for "File Associations" and add *.tpp to the list
- search for "File types" and add *.tpp to pattern the select for type "C++ header file"
- save preferences

Launch Eclipse

- \$ mkdir -p Formation_TRUST/yourname/workspace
- \$ cd Formation_TRUST/yourname/eclipse
- \$./eclipse &
 - Workspace: Browse the directory Formation_TRUST/yourname/workspace
 - Welcome : close x button