TRUST Baltik Project Tutorial V1.9.6

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- TRUST initialization
- 2 Eclipse initialization
- 3 Create a Baltik project
- 4 Modify the cpp sources
- Parallel exercise
- **6** Validation form and test cases
- Code coverage exercise
- Tools
- For more

TRUST initialization

- Eclipse initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
- 3 Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- Validation form and test cases
 - "Run_fiche"
 - Validation test case
- Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

TRUST initialization

TRUST commands

- Load TRUST environment:
 - On CEA Saclay PCs, TRUST versions are available with: source /home/trust trio-public/env TRUST-1.9.5.sh
 - On your own computer, download and install the latest version of TRUST in your local folder \$MyPathToTRUSTversion (unless this was done), then write on the terminal:

source \$MyPathToTRUSTversion/env_TRUST.sh

Ensure that the configuration is ok and locate the sources:

- \$ echo \$TRUST_ROOT
- Now, copy a TRUST test case that we will need later:
 - \$ mkdir -p Formation_TRUST/yourname
 - \$ cd Formation_TRUST/yourname
 - \$ trust -copy upwind
 - \$ cd upwind
 - Replace "format Iml" by "format lata" in the data file

■ TRUST initialization

- Eclipse initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
- 3 Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- 4 Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- Validation form and test cases
 - "Run_fiche"
 - Validation test case
- Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

Download Eclipse

Download Eclipse

- Visit the Eclipse Foundation website:
 http://www.eclipse.org/downloads/eclipse-packages/
- In "More Downloads", select version Eclipse 2022-09 (4.25).
- Select Eclipse IDE for C/C++ Developers → Linux 64-bits
- Download the eclipse-cpp-2022-09-R-linux-gtk-x86_64.tar.gz package in your directory Formation_TRUST/yourname

Untar the downloaded archive

- \$ cd Formation_TRUST/yourname
- \$ tar xfz eclipse-*.tar.gz
- \$ cd eclipse



6 / 83

TRUST initialization

- Eclipse initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
- Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- 4 Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- Output Test Cases
 Output Test Cases
 - "Run_fiche"
 - Validation test case
- Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

Create a TRUST platform project under Eclipse (I)

Launch Eclipse

- \$ mkdir -p Formation_TRUST/yourname/workspace
- \$ cd Formation_TRUST/yourname/eclipse
- \$./eclipse &
 - Workspace: Browse the directory Formation_TRUST/yourname/workspace
 - Welcome : close x button

Create the project

- Create a preconfigured TRUST project:
 - \$ cd Formation_TRUST/yourname
 - \$ trust -eclipse-trust
- Then, follow the instructions displayed on the terminal to import TRUST sources.

Create a TRUST platform project under Eclipse (II)

Configure the project and launch a computation

- \bullet From the "Project Explorer" tab, right click on your TRUST project \to "Debug As" \to "Debug Configurations..."
 - \Rightarrow Click on the triangle on the left of "C/C++ Application" \rightarrow Select the debug configuration already created with trust -eclipse-trust
 - The "Main" tab tells Eclipse which binary will be used:
 - ⇒ Project: your project's name
 - ⇒ "C/C++ Application": points to the TRUST \$exec debug
 - The "Arguments" tab tells Eclipse which datafile to run:
 - \Rightarrow "Program arguments" \rightarrow specifies datafile's name (here upwind)
 - \Rightarrow "Working directory" \rightarrow contains path to datafile
 - ⇒ "Debug" : your datafile will be run with the specified executable

- TRUST initialization
 - Eclipse initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
- 3 Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- Validation form and test cases
 - "Run_fiche"
 - Validation test case
- Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

Creation of a Baltik project

Create an empty Baltik

- Create a directory for your project:
 - \$ cd Formation_TRUST/yourname
- Create your project from a basic project template using TRUST commands:
 - \$ trust -baltik my_project
 - \$ cd my_project
 - \$ ls -1

You can see that you have now:

- o three directories: share, src and tests, and
- o one "project.cfg" file.
- one "RFADMF BALTIK" file.
- o one "configure" script.

Add sources to your Baltik

- Copy the following TRUST .cpp file into your baltik project:
 - \$ mkdir -p src/Trust_fixes
 - \$ cp \$TRUST_ROOT/src/MAIN/mon_main.cpp src/Trust_fixes/

- TRUST initialization
 - 2 Eclipse initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
- Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- Validation form and test cases
 - "Run_fiche"
 - Validation test case
- Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

Create your git repository

Git commands

You will now create a git repository to manage your developments.

- Initialize an empty git repository:
 - \$ git init
- Display your working tree status:
 - \$ git status
- You can see 3 file and src directory on the "untracked" files section. It means that they are not yet followed by the git repository.
- Add src and project.cfg to your git repository in order to prepare a commit: \$ git add src project.cfg
- Now, you can commit your files to add it to your git repository: \$ git commit -m "Initial commit" Remark: If you are not able to commit files, you should first configure your username and email in git with: git config --global user.name "Your Name" git config --global user.email you@example.com

Create your git repository

Git commands

- Display your working tree status:
 - \$ git status
 Only README.BALTIK and configure script (automatically generated) are
 not added to your git repository.
- Display the list of commits:\$ git log
 - ____

Baltik commands

- Edit your project file "project.cfg" to specify name, author and executable.
- Then configure your project:
 - \$ baltik_build_configure -execute
 this command launches both scripts: the "baltik_build_configure" and
 "configure".

Create your git repository

Git commands

- Check the status of your git repository with the "--ignored" option to see the status of all files:
 - \$ git status
- You can see that
 - "project.cfg" has been modified.
 - there are new untracked files: these files are not on the git repository
- To see only the changes on the git repository files:
 - \$ git status -uno
- Track changes via gitk (GUI interface of Git):
 - \$ gitk &

You can see information about your first commit and actual untracked changes.

- TRUST initialization
 - Eclipse initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
- 3 Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- 4 Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- Validation form and test cases
 - "Run_fiche"
 - Validation test case
- Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

Make a basic build

- To make a basic build:
 - \$ cd Formation_TRUST/yourname/my_project
- Configure your project:
 - \$./configure
- Build your project in different modes:
 - Build an optimized (-03 option) version:
 - \$ make optim
 - Build a debug (-g -O0 option with asserts) version:
 - \$ make debug
- Initialize your baltik project environment:
 - \$ source env_my_project.sh
- Check that executables are available:
 - \$ 1s \$exec
 - \$ ls \$exec_opt
 - \$ ls \$exec_debug

Other builds

- List other options available for the make command:
 - \$ make help
- Build an:
 - semi-optimized -O3 option and assert enabled mode:
 - \$ make semi_optim
 - \$ ls \$exec_semi_optim
 - optimized binary for profiling (option -pg -O3):
 - \$ make prof
 - \$ ls \$exec_pg
 - optimized binary for test coverage (option -gcov -O3):
 - \$ make gcov
 - \$ ls \$exec_gcov

Notice that TRUST optimized binary for profiling or a TRUST optimized binary for test coverage must exist in order to be able to compile your baltik's profiling or test coverage executable.

- TRUST initialization
 - Eclipse initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
- Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- Validation form and test cases
 - "Run_fiche"
 - Validation test case
- Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

Create a basic BALTIK project without dependency (I)

Initialize baltik environnement

\$ source env_my_project.sh

Launch Eclipse

- \$ cd Formation_TRUST/yourname/eclipse
- \$./eclipse &

Create the project

\$ trust -eclipse-baltik
then follow the instructions displayed on the terminal.

Create a basic BALTIK project without dependency (II)

Launch a computation

- \bullet From the "Project Explorer" tab, right click MY_BALTIK \to "Debug As" \to "Debug Configurations..."
 - \Rightarrow C/C++ Application \rightarrow Select the configuration containing your baltik's name
 - In the "Main" tab:
 - ⇒ Project: MY BALTIK
 - ⇒ C/C++ Application: contains path to \$exec_debug
 - ⇒ "Apply"
 - In the "Arguments" tab:
 - ⇒ Program arguments: contains datafile's name (upwind)
 - ⇒ Working directory: path to datafile's directory
 - ⇒ "Apply"
 - \Rightarrow Debug



Useful shortcuts in sources

Shortcuts

- Open a cpp file from Project Explorer tab:
 Double click on TRUST → Kernel → Framework → Probleme_base.cpp
 - or : Ctrl+shift+R then type Probleme_base.cpp
- In the cpp file: Right click on method "postraiter()"
 - ⇒ F3: Opens Declaration
 - ⇒ F4: Open Type Hierarchy
 - ⇒ Ctrl+Alt+H: Open Call Hierarchy
 - ⇒ "Ctrl+PageUp" and "Ctrl+PageDown": Move from a tab to another
- you can also:
 - ⇒ search files by name using: "Ctrl+shift+R"
 - ⇒ serach attributes/methods/functions/... using: "Ctrl+shift+T"



- TRUST initialization
 - Eclipse initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
- Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Darallel exercise
- Validation form and test cases
 - "Run_fiche"
 - Validation test case
- Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

Baltik commands

- Create a new folder for your own classes:
 - \$ mkdir -p \$project_directory/src/my_module
 - \$ cd \$project_directory/src/my_module
- Create your first class "my first class" with template:
 - \$ baltik_gen_class my_first_class

Git commands

- Display the status of your repository:
 - \$ git status .
- Add your new class to your git repository to follow your modifications:
 - \$ git add my_first_class.*
 - \$ git commit -m "Add my_first_class src"

Baltik commands

- Have a look at the 2 files my_first_class.h|cpp.
- Important remark: Each time a source file is added to the project, you need to reconfigure your project to take new files into account when building the exectuable:
 - \$ cd \$project_directory
 - \$./configure
- Build your project with Eclipse or in the terminal.
- Edit the 2 files with gedit vim or use Eclipse.

Eclipse

- Edit the 2 files with Eclipse.
- For Eclipse use, you have to update your project to see your new files:
 - → "Index/Rebuild" from "my project" of "Project Explorer"
 - → Click on "▶" button of "my project" in the "Project Explorer"

Baltik commands

- We want to change the inheritance of the class in order that it inherits from "Interprete" class instead of "Objet U".
 - "Interprete" class is the base class of all the keywords doing tasks when read from the datafile, example (read, associate, solve, ...).

So:

- o add an "#include <Interprete.h>" in my first class.h,
- replace "Objet_U" to "Interprete" in the .h and .cpp files,
- Interprete class is an abstact class, it contains a pure virtual method which should be implemented!
- o rebuild your application and an error will occur!
- Look at the "Interprete" class:
 - in Eclipse: highlight the string "Interprete" and push the F3 button of your keyboard to open the declaration file of this class

Baltik commands

Look at "interpreter()" method
 This method is called each time a keyword is read from the datafile (eg: "Read file dom dom.geom", "Solve pb",...).

• Define the public method "interpreter(Entree&)" in the include file and

- implement it (just print a message with "Cerr" like "- My first keyword!") into the cpp file.

 "Entree" is a TRUST class to read an input stream (from a file for example):
 - "Entree" is a TRUST class to read an input stream (from a file for example) Entree& interpreter(Entree&) override;
- Rebuild your project and fix errors until the debug binary of your project is generated

Test your new class

- Copy a test case to the build folder of your Baltik project:
 - \$ cd \$project_directory/build/
 - \$ trust -copy Cx
 - ERROR...

Test your new class

- The error occurs because this test case is not in your baltik but in TRUST project. To be able to copy it, you have to load the full environment (TRUST+your baltik).
 - \$ source ../full_env_my_project.sh
 - \$ trust -copy Cx
 - \$ cd Cx
- Edit the data file:
 - \$ gedit Cx.data & Add keywords "my_first_class" and "End" after the line where the problem is discretized.
- Run this datafile with your baltik binary and check that this new keyword is recognized (see next slide).

With Eclipse:

- \rightarrow In the project explorer, right click on "my_project" and select "Debug As/Debug configurations..."
- ightarrow In "Main" tab, check "Disable auto build" then click on "Apply"
- \rightarrow In "Arguments" tab, fill "Program arguments:" with "Cx"
- → "Working directory:" Copy the path to datafile matching

\$project_directory/build/Cx

- \rightarrow "Apply" and "Debug"
- \rightarrow Click on "Yes" to switch to the debug view
- ightarrow Click on "Resume" button (or F8) to run the calculation until the end

On a terminal, you can only run:

- \$ cd \$project_directory/build/Cx/
- \$ exec=\$exec_debug trust Cx

- TRUST initialization
 - Eclipse initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
- Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- 4 Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- - "Run_fiche"
 - Validation test case
- Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- 9 For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

Now, instead of reading:

```
my_new_keyword
```

we want you to read this syntax from the datafile:

```
my_new_keyword { domain dom_name option 0 }
```

- The recommended way is to use Param objects.
- As an example, see the next slide to see how to use Param to read the syntax:

```
my_new_keyword { problem pb_name option 1 }
```

Example of Param use

```
#include <Param h>
Entree& Class::interpreter(Entree& is)
int opt = 0;
Nom pb_name;
Cerr << "Reading parameters of A from a stream (cin or file)" << finl;
Param param(que_suis_je());
// Register parameters to be read:
param.ajouter("option", & opt);
param.ajouter("problem",&pb_name,Param::REQUIRED);
// Read now the parameters from the stream is and produces an error
// if unknown keyword is read or if braces are not found at the
// beginning and the end:
param.lire_avec_accolades_depuis(is);
. . .
return is;
```

• As said before, we want to read this syntax from the data:

```
my first class { domain dom option 0 } # dom is domain name #
```

here is how to do:

```
Entree& Class::interpreter(Entree& is)
Nom domain_name;
... // read params from the datafile
// Retrieve the domain object name given by the user, and find
// back the actual instance in memory:
Objet U& obj = Interprete::objet(domain_name);
// Sanity check: if read domain name does not correspond to a
domain, exit
if(!sub_type(Domaine, obj))
Process::exit("Object passed to 'Class' is of wrong type!");
// Fill the local reference to domain:
Domaine& domaine_ref_ = ref cast(Domaine, obj);
. . .
```

- Fix your implementation of "interpreter()" method (add missing includes)
- Add a print at the end of the method "interpreter(Entree&)" and find how to print the domain name:

```
Cerr << "Option number " << option_number << " has been
read on the domain named " << ??? << finl:</pre>
```

- With Eclipse:
 - Build/fix/re-build your project:
 - → "Project" and "Build project"
 - Run the test case:
 - \rightarrow "Run" and "Debug"
- Or in a terminal:
 - Build/fix/re-build your project:
 - \$ cd \$project_directory
 - \$ make debug
 - Run the test case:
 - \$ cd \$project_directory/build/Cx/
 - \$ export exec=\$exec_debug
 - \$ trust Cx

In this case, TRUST runs with exec debug.

Display information about domain boundaries

- Edit the "my_first_class.cpp" file and add into the "interpreter()" method a
 loop on the boundaries.
 Look for help inside the "Domaine" "Bord" "Frontiere" classes in Eclipse or
 - Look for help inside the "Domaine", "Bord", "Frontiere" classes in Eclipse or in the HTML documentation to access to the:
 - Number of boundaries (nb_bords() method)
 - Boundaries (bord(int) method)
 - Name of the boundaries (le_nom() method)
 - Number of faces of each boundary (nb faces() method)

Print these information with something like:

```
Cerr << "The boundary named " << ??? << " has " << ??? << "
faces." << finl;</pre>
```

Modify your cpp class (Part 2)

Compute the sum of the control volumes of a domain discretized in VEF

 Information about control volumes is in the "Domaine VF" class (discretized domain) which can't be accessed from the domain, but only from the problem.

So, you need to read another parameter from your datafile:

```
my first class { domain dom option 0 problem pb }
```

- Add the read of a new parameter problem into "my first class.cpp" file (see the example at the beggining of this part).
- Remember the "equation" or "problem" UML diagram of the presentation's slides.
- Look for help inside the "Domaine VF", "Probleme base" and "Domaine dis base" in Eclipse or the HTML documentation to access to the:
 - discretized domain (domaine dis() method)
 - control volumes (volumes entrelaces() method)

Modify your cpp class (Part 2)

- You will need to cast the discretized domain returned by the domaine_dis()
 method into a "Domaine_VF" object.
- Print the size of the control volumes array with something like:

```
Cerr << control_volumes.size() << finl;</pre>
```

Where control_volumes is a **DoubleVect** returned by the **Domaine VF::volumes entrelaces()** method.

• Now, compute and print the sum of the control volumes with a "for" loop.

- TRUST initialization
 - Eclipse initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
- Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- 4 Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- Validation form and test cases
 - "Run_fiche"
 - Validation test case
- Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

Create automated documentation

- We want now to add XD tags to create the automated documentation of your new code.
- First, we have to create this documentation for the first time.
 - \$ cd \$project_directory
 - \$ make gui
- Open the documentation file:
 - \$ evince \$project_directory/build/xdata/XTriou/doc.pdf &
- Now will add XD tags (keyword documentation) in cpp files.
- For this open the help of the TRAD_2 syntaxe:
 - \$ gedit \$project_directory/build/xdata/XTriou/doc_TRAD_2 &

Create automated documentation

 Add a first tag (in comments) into your cpp file just after the openning brace of the 'interpreter_()' method:

```
// XD english_class_name base_class_name TRUST_class_name
mode description
where "english_class_name" and "TRUST_class_name" can be
"my first class".
```

- The "base_class_name" is the name of the section in which will appear the information of your new class in the 'doc.pdf' file.
- The "mode" is to choose with the help of the doc_TRAD_2 file. Here set it to "-3".

Create automated documentation

Then add at the end of the lines of type "param.ajouter...", an XD comment like:

```
param.ajouter(...); // XD_ADD_P type description
where "type" can be (cf 'doc_TRAD_2' file): 'int', 'floattant', 'chaine',
'rien'...
```

- rebuild the documentation:
 - \$ make gui
- Check that the documentation of your new class is in the new doc:
 \$ evince \$project_directory/build/xdata/XTriou/doc.pdf &
- To check that the GUI is validated:
 - \$ make check_gui
- Notice that you must have XD commands in all your cpp classes.

- TRUST initialization
 - Eclipse initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
- Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- 4 Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- Validation form and test cases
 - "Run_fiche"
 - Validation test case
- Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

- Edit the "\$project_directory/src/Trust_fixes/mon_main.cpp" file of your baltik project using text editor or Eclipse.
- Add these lines after "Process::imprimer_ram_totale(1);" : std::cout << "Hello World to cout." << std::endl; std::cerr << "Hello World to cerr." << std::endl; Cout << "Hello World to Cout." << finl; Cerr << "Hello World to Cerr." << finl; Process::Journal() << "Hello World to Journal." << finl;</p>

in a terminal: Rebuild the code

- \$ cd \$project_directory
- \$ make debug optim

- Create an empty data file:
 - \$ mkdir -p \$project_directory/build/hello
 - \$ cd \$project_directory/build/hello
 - \$ touch hello.data
- Run the code
 - sequentially:
 - \$ trust hello
 - in parallel:
 - \$ trust hello 4

and see the differences.

- "Cout" is equivalent to "std::cout" on the master process only. Use this
 output for infos about the physics (convergence, fluxes,...).
- "Cerr" is equivalent to "std::cerr" on the master process only. Use this output for warning/errors only.
- "finl" is equivalent to "std::endl" + "flush()" on the master process.
- "Journal()" prints to "datafile_000n.log" files. Use this output during parallel development to print plumbing infos which would be hidden during production runs.

- During a parallel run, the "Journal()" output can be disabled.
 To verify this, first clean your folder:
 - \$ ls *.log
 - \$ trust -clean

and run computation with -journal=0 option

- \$ trust hello 4 -journal=0
- \$ ls *.log
- Other options are available. To get it, run:
 - \$ trust hello.data -help_trust

Printing into a file

- Now, we will print the control volumes sum into a file for test case Cx.
- We want to write in a file with name similar to: DataFileName_result.txt where "DataFileName" is the name of the data file (eg: Cx).
- For that, you will:
 - create an object of the class Nom and fill it by collecting the datafile's name using Objet U::nom du cas() method.
 - complete the datafile's name with the string "_result.txt" thanks to the "operator" += method of the class Nom.
 - create the output file with the SFichier class and print the sum into it.
- Compile your project and run Cx datafile:
 - \$ cd \$project_directory/build/Cx/
 - \$ exec=\$exec_debug trust Cx
- Then open the "Cx result.txt" file.

- TRUST initialization
 - 2 Eclipse initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
 - 3 Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- 4 Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- **5** Parallel exercise
- Validation form and test cases
 - "Run_fiche"
 - Validation test case
- Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- 9 For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

Part 1

- Run your test case Cx in parallel mode:
 - \$ cd \$project_directory/build/Cx/
 - \$ trust -partition Cx 2 # Partition in 2 subdomains
 - \$ trust PAR_Cx 2 # 2 processes used
- Compare the files: Cx_result.txt, PAR_Cx_result.txt.
 Differences come from the fact that the 2 processors write into the file one after the other one. So the final content will be the value calculated on the last processor which will acces to the file.
- You can try to launch one more time the calculation, the result may differ.
- To have the entire sum, you can apply the **mp_sum()** method on the sum obtained and add the print in the .txt file.
- Compare it to the sum obtained in the sequential run.
- It is better but we counted several times faces that belongs to the joint and to the virtual zones.

Part 1

- To parallelize the algorithm, rewrite it with the help of the mp_somme_vect(DoubleVect&) method.
- Add this print in the .txt file.
- You should find the same value for the sequential and parallel calculation.

Part 2 (Optional)

- Create a "verifie" script to check the resulting value (sequential then parallel).
- Add a call to "compare sonde" in your "verifie" script...

Part 3

- To validate parallelization in TRUST, you can use the command "compare lata":
 - \$ ls *lata
 - \$ compare_lata Cx.lata PAR_Cx.lata

Part 3

- You can see that there is no differences and the maximal relative error encountered is about 4.e-12.
- Performances \$ 1s *TU
 - \$ meld Cx.TU PAR_Cx.TU &
 - \$ meld Cx_csv.TU PAR_Cx_csv.TU &

Part 4 Debog

- Copy a debog test case:
 - \$ cd \$project_directory/build
 - \$ trust -copy Debog_VEF
 - \$ cd Debog_VEF
- Open the Debog VEF.data file and search the "Debog" command.
- Sequential run:
 - \$ trust Debog_VEF
- You get "seq" and "faces" files.

Part 4 Debog

- Partitionning step and creation of the parallel data file:
 - \$ trust -partition Debog_VEF 2
- Verify the parallel data file, you must have now "Debog pb seg faces 1.e-6 1".
- Run in parallel:
 - \$ trust PAR_Debog_VEF 2
- You get debog*.log and DEBOG files.
- If a value of an array differs between the two calculations and the difference is greater than 1.e-6 then "ERROR" message appears in the log files else we will get "OK" (cf debog.log).

TRUST Baltik Project Tutorial V1.9.6

- Add a debog instruction in your file mon main.cpp located in \$project directory/Trust fixes, after the "Hello world" prints put: double var = 2.5; Debog::verifier("- Debog test message",var);
- Do not forget to add the "#include <Debog.h>"!

Part 4 Debog

- Then compile and do the sequential run.
- You can see a first message.
- Then do the parallel run and check the debog.log file.
- Becarefull the debog instruction in the data file must be between the "Discretize" and "Read pb" lines.
- For more information:
 - \$ trust -doc &
 - → Open the TRUST Generic Guide
 - → Click onto the TRUST Reference Manual
 - \rightarrow Search for "Debog" keyword.



- TRUST initialization
 - Eclipse initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
- 3 Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- 6 Validation form and test cases

 "Run fiche"
 - Validation test case
 - Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

New share/Validation/Rapports_automatiques

Baltik commands

- Go the the directory where to create your notebook:
 - \$ cd \$project_directory
 - \$ cd share/Validation/Rapports_automatiques
- Create a new directory for your new validation form:
 - \$ mkdir -p upwind/src
- Add the needed files (data file, mesh & .ipynb file):
 - \$ cp Formation_TRUST/yourname/upwind/upwind.data upwind/src
 - \$ cp Formation_TRUST/yourname/upwind/upwind.geo upwind/src
- Create a new Jupyter validation form:
 - \$ cd upwind
 - \$ trust -jupyter
- Now you have a upwind.ipynb file (i.e. a new Jupyter notebook).

New share/Validation/Rapports_automatiques

Git commands

- Add it to your git repository:
 - \$ git add upwind
 - \$ git commit -m "New validation notebook"

Baltik commands

- Run this Jupyter notebook:
 - \$ cd upwind/
 - \$ Run_fiche
- Build directly a PDF report from the notebook:
 - \$ Run_fiche -export_pdf
- Open the pdf report:
 - \$ evince build/rapport.pdf &

- TRUST initialization
 - **Eclipse** initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
- 3 Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- 4 Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- 6 Validation form and test cases
 - "Run fiche"
 - Validation test case
 - Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

Baltik commands

- Create automatically the non-regression test case:
 - \$ cd \$project_directory
 - \$ make check_optim
 - Creation of upwind_jdd1
 - Creation of upwind_jdd1/lien_fiche_validation
 - Extracting test case (upwind.data) ...End.
 - Creation of the file upwind_jdd1.lml.gz

...

 $\bullet \to \mathsf{You}$ can see in the report table that PAR_upwind_jdd1 has crashed: "CORE" message.

Git commands

- Lets check the git status before solving this problem:
 - \$ git status -uno
- A new test case based on your validation form has been created in the directory:
 - \$project_directory/tests/Reference/Validation/upwind_jdd1

Baltik commands

- Now we want to correct the error, so copy the test case:
 - \$ cd \$project_directory/build
 - \$ trust -copy upwind_jdd1
 - ERROR...
- We have to re-run the configure script to take into account the new test case:
 - \$ cd \$project_directory
 - \$./configure
 - \$ cd build
 - \$ trust -copy upwind_jdd1

Baltik commands

- Now we will analyse the error:
 - \$ cd upwind_jdd1
 - \$ trust -partition upwind_jdd1
 - \$ trust PAR_upwind_jdd1 2
- Correct the data file PAR upwind jdd1.data and re-run it.
- If it's ok, update the data file in
 \$project_directory/share/Validation/Rapports_automatiques/upwind/src ("Scatter ../upwind/DOM.Zones dom" → "Scatter DOM.Zones dom")
- To Relaunch the last test cases which do not run:
 - \$ cd \$project_directory
 - \$ make check_last_pb_optim Changement du jeu de donnees...

suite a une modification d'un jeu de donnees de la fiche de validation associee.

...

Successful tests cases :1/1

Git commands

Add this non-regression test in configuration:

```
$ git status -uno
$ git add
```

tests/Reference/Validation/upwind_jdd1/upwind_jdd1.data

• Commit the modifications on your git repository:

```
$ git commit -m "New reference test"
$ git log
```



Baltik commands

- To run all the non regression tests with a optimized binary:
 - \$ make check_all_optim
- To run all the non regression tests with a debug binary:
 - \$ make check_all_debug
- To create an archive to share your work:
 - \$ make distrib
 - \$ ls
- You have now an archive in tar.gz format of your baltik project.

- TRUST initialization
 - Eclipse initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
 - 3 Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- 4 Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- Validation form and test cases
 - "Run_fiche"
 - Validation test case
- **7** Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

Code coverage exercise

- We want to run test cases using rational Runge-Kutta scheme of ordre 2.
 - For this go to the Doxygen documentation of RRK2 class to see the methods of this class.
 - Use the "trust -check function|class|class::method" command to find and launch tests cases
 - For example:
 - \$ trust -check RRK2::RRK2

- TRUST initialization
 - **Eclipse initialization**
 - Download eclipse
 - Create TRUST platform project under Eclipse
 - 3 Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- Validation form and test cases
 - "Run_fiche"
 - Validation test case
 - Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

Debug with GDB

With Eclipse:

Run a test case with GDB:

- \rightarrow "Debug As" and "Debug configurations..." from "my project"
- \rightarrow in "Arguments", "Program arguments:" upwind
- → "Working directory:" Formation TRUST/yourname/upwind/
- \rightarrow "Apply" and "Debug"

For more information about GDB commands, refer to the help menu.

Or in a terminal:

- Run a test case with GDB:
 - \$ cd Formation_TRUST/yourname/upwind/
 - \$ exec=\$exec_debug trust -gdb upwind
- You are now in GDB.
- Add a breakpoint and stop into the SSOR preconditionner: (gdb) break SSOR::ssor

Debug with GDB

- Run the test case: (gdb) run upwind
- Have a look at the stack (gdb) where
- Go to the next instruction: (gdb) n
- Print an array: (gdb) print tab1
- Or print matrice.tab1_ if "optimized out" message printed: (gdb) print tab1[10]
- Print only a value of an array:

```
(gdb) dumpint tab1 # Dump the array
```

- (gdb) print tab1.size_array() # Array size
- (gdb) up
- (gdb) list 100



Debug with GDB

• Print lines after the 100th line: (gdb) print matrice (gdb) print matrice.que_suis_je() # Kind of matrix ? (gdb) print matrice.que_suis_je().nom_ # Kind of matrix ? (gdb) up 6 # Move up 6 levels (gdb) list 865 Print others variables: (gdb) # Pressure field (gdb) print la_pression->que_suis_je().nom_ (gdb) # Pressure values (DoubleTab) (gdb) print la_pression->valeurs() (gdb) # DoubleTab dimension (gdb) print la_pression->valeurs().nb_dim()

(gdb) # Dump the field values
(gdb) pttab la_pression->valeurs()

- TRUST initialization
 - **Eclipse initialization**
 - Download eclipse
 - Create TRUST platform project under Eclipse
 - 3 Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- **6** Validation form and test cases
 - "Run_fiche"
 - Validation test case
 - Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

Find memory bugs with valgrind

- Run a test case with Valgrind:
 - \$ cd \$project_directory
 - \$ source env_my_project.sh
 - \$ cd build/Cx/
 - \$ VALGRIND=1 trust Cx
- The Valgrind messages appear on the screen with the beginning of each line the same number. For example:
 - \$ ==26645== ...
- The last line indicates if errors have occurred. An example with 0 error:
 - \$ ==26645== ERROR SUMMARY: 0 errors from 0 contexts
 (suppressed: 0 from 0)
- Now we will modify the sources in your baltik project to generate a Valgrind error on the Cx test case.

Find memory bugs with valgrind

- Edit the "my_first_class.cpp" file and remove initialization the following line (before computing the sum of control volumes): double sum = 0;
- Edit "my_first_class.h" and add in protected: double sum; // do not initialize it to 0
- Rebuild your project and run the test case:
 - \$ cd \$project_directory
 - \$ make debug optim
 - \$ cd build/Cx/
 - \$ exec=\$exec_opt trust Cx # in mode optim, no error!
 - \$ exec=\$exec_debug trust Cx # in mode debug, no error too
 - \$ VALGRIND=1 exec=\$exec_opt trust Cx # in mode valgrind Valgrind detects that there is a "Conditional jump or move depends on
 - valgrind detects that there is a "Conditional jump or move depends or uninitialised value(s)"

On the other hand, in this case, there are errors.

\$ ==28400== ERROR SUMMARY: 772 errors from 114 contexts
NB: In valgrind+debug mode, you'll get the file+line number

- TRUST initialization
- 2 Eclipse initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
- 3 Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- 4 Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- 6 Validation form and test cases
 - "Run_fiche"
 - Validation test case
 - Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- For more
 - Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

For more

- You can find the commented solution of the exercise:
 - \$ cd \$TRUST_ROOT/doc/TRUST/exercices/my_first_class
- You can practice on a tutorial:
 - \$ cd \$TRUST_ROOT/doc/TRUST/exercices/
 - \$ evince equation_convection_diffusion/rapport.pdf &



- **TRUST** initialization
 - Eclipse initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
 - 3 Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- Validation form and test cases
 - "Run_fiche"
 - Validation test case
- Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

Create a TRUST platform project under Eclipse (I)

On a terminal

Load TRUST environment and copy "upwind" test case as described on p.4:

- \$ echo \$TRUST_ROOT/src
- \$ echo \$exec_debug

Launch Eclipse

- \$ mkdir -p Formation_TRUST/yourname/workspace
- \$ cd Formation_TRUST/yourname/eclipse
- \$./eclipse &
 - Workspace: Browse the directory Formation_TRUST/yourname/workspace
 - Welcome : close x button

Create a TRUST platform project under Eclipse (II)

Create the project

- File \rightarrow New \rightarrow C/C++ Project \rightarrow C++ Managed Build
 - ⇒ Project name: TRUST-X.Y.Z (e.g.: TRUST-1.9.5)
 - \Rightarrow Project type: "Executable" \rightarrow "Empty Project"
 - ⇒ Toolchains: "Linux GCC"
 - \Rightarrow Finish

Import TRUST source files into the project

- ullet From the "Project Explorer" tab, right click on TRUST-X-Y-Z ightarrow "Import..."
 - \Rightarrow General \rightarrow File System \rightarrow Next
 - ⇒ From directory: copy the string matching \$TRUST_ROOT/src/
 - ⇒ Check "Select All"
 - ⇒ Into folder: TRUST-X.Y.Z
 - \Rightarrow Finish
 - \Rightarrow Wait to have 100% at the bottom right corner of the window (C/C++ indexer).

May 26, 2025

Create a TRUST platform project under Eclipse (III)

Configure the project and launch a computation

- ullet From the "Project Explorer" tab, right click on TRUST-X.Y.Z o Properties
 - \Rightarrow Builders: uncheck "CDT Builder" \rightarrow OK \rightarrow apply and close
- From the "Project Explorer" tab, right click on TRUST-X.Y.Z \rightarrow "Debug As" \rightarrow "Debug Configurations..."
 - \Rightarrow Right click on "C/C++ Application" \rightarrow New configuration
 - In the "Main" tab (tell Eclipse which binary will be used):
 - ⇒ Project: TRUST-X.Y.Z
 - \Rightarrow "C/C++ Application": copy the string matching \$exec_debug
 - \Rightarrow "Apply"
 - In the "Arguments" tab (tell Eclipse which datafile to run):
 - \Rightarrow "Program arguments" \rightarrow specify datafile's name (here upwind)
 - \Rightarrow "Working directory" \rightarrow uncheck "Use default" and type path to datafile
 - ⇒ "Apply"
 - ⇒ "Debug": your datafile will be run with the specified executable

- TRUST initialization
 - Eclipse initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
 - 3 Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- 4 Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- Validation form and test cases
 - "Run_fiche"
 - Validation test case
- Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- 9 For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

Create a basic BALTIK project without dependency (I)

Initialize baltik environnement

```
$ source env_my_project.sh
```

\$ echo \$project_directory/src

Launch Eclipse

```
$ cd Formation_TRUST/yourname/eclipse
```

\$./eclipse &

Create the project

- File \rightarrow New \rightarrow Project \rightarrow C/C++ \rightarrow "Makefile Project with Existing Code"
 - ⇒ Project name: MY BALTIK
 - ⇒ Existing Code Location: copy string matching \$project_directory/src
 - ⇒ Toolchain for Indexer Settings: "Linux GCC"
 - \Rightarrow Finish
 - \Rightarrow Wait to have 100% at the bottom right corner of the window (C/C++ indexer).

Create a basic BALTIK project without dependency (II)

Configure the BALTIK project and link it with TRUST

- ullet From the "Project Explorer" tab, right click on MY_BALTIK o Properties
 - ⇒ Builders: check "CDT Builder"
 - \Rightarrow C/C++ Build :
 - Builder Settings: Build directory: \${workspace_loc:/MY_BALTIK}/../ or copy the string matching \$project_directory/
 - Behavior: check "Build (Incremental build)": debug optim (instead of all)
 - \Rightarrow Project References: check your TRUST project \rightarrow Apply and Close

Build the BALTIK project

From the "Project Explorer" tab, right click MY_BALTIK \rightarrow Index \rightarrow Rebuild \Rightarrow Wait to have 100% at the bottom right corner of the window (C/C++ indexer).

Right click MY BALTIK → Build Project



Create a basic BALTIK project without dependency (III)

Launch a computation

- \bullet From the "Project Explorer" tab, right click MY_BALTIK \to "Debug As" \to "Debug Configurations..."
 - \Rightarrow C/C++ Application \rightarrow New configuration
 - In the "Main" tab:
 - ⇒ Project: MY_BALTIK
 - \Rightarrow C/C++ Application: $\{\text{workspace_loc:/MY_BALTIK}\}$../my_project or copy the string matching $\{\text{exec_debug}\}$
 - ⇒ "Apply"
 - In the "Arguments" tab:
 - \Rightarrow Program arguments \rightarrow specify the name of your datafile (upwind)
 - \Rightarrow Working directory \rightarrow uncheck "Use default" and type path to datafile's directory
 - ⇒ "Apply"
 - \Rightarrow Debug

- 1 TRUST initialization
 - Eclipse initialization
 - Download eclipse
 - Create TRUST platform project under Eclipse
 - 3 Create a Baltik project
 - Creation of a Baltik project
 - Creation of your git repository
 - Builds
 - Using Eclipse
- Modify the cpp sources
 - Create a new cpp class
 - Modify your cpp class(Part 1)
 - Modify your cpp class(Part 2)
 - Add XD tags (keyword documentation)
 - Adding prints

- Parallel exercise
- Validation form and test cases
 - "Run_fiche"
 - Validation test case
- Code coverage exercise
- Tools
 - Debug with GDB
 - Find memory bugs with valgrind
- 9 For more
- Appendix
 - Configuring TRUST project in Eclipse
 - Configuring BALTIK project in Eclipse
 - TPP files in Eclipse

TPP files in Eclipse

tpp format in TRUST is not natively recognized by eclipse and code is not highlighted. If you want to edit tpp files, you can:

- open Eclipse
- click on "Window" then select "Preferences"
- search for "File Associations" and add *.tpp to the list
- search for "File types" and add *.tpp to pattern the select for type "C++ header file"
- save preferences

Launch Eclipse

- \$ mkdir -p Formation_TRUST/yourname/workspace
- \$ cd Formation_TRUST/yourname/eclipse
- \$./eclipse &
 - Workspace: Browse the directory Formation_TRUST/yourname/workspace
 - Welcome : close x button