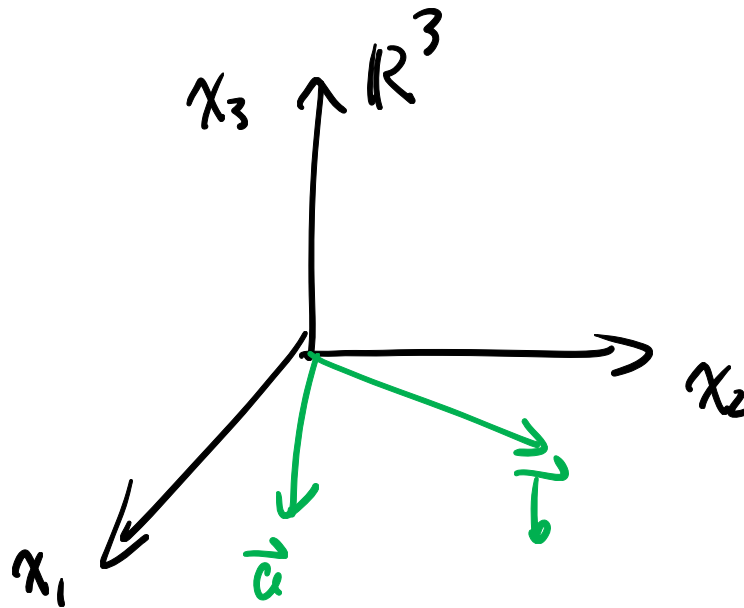
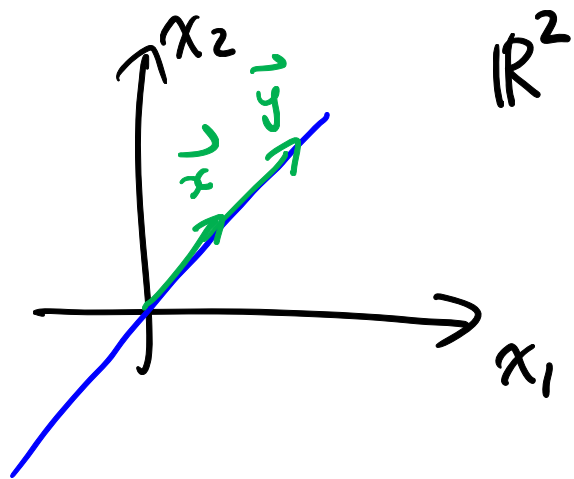


Lec 8 subspace.



Def A subspace H of \mathbb{R}^n is a subset of vectors in \mathbb{R}^n s.t.

$$(1) \vec{0} \in H$$

H cannot be empty

$$(2) \vec{u}, \vec{v} \in H, \text{ then } \vec{u} + \vec{v} \in H \quad \text{closed under addition}$$

$$(3) \vec{u} \in H, c \in \mathbb{R} \text{ then } c\vec{u} \in H \quad \text{closed under scalar mult.}$$

Ex. \mathbb{R} . Possible subspaces.

$$\{0\}$$

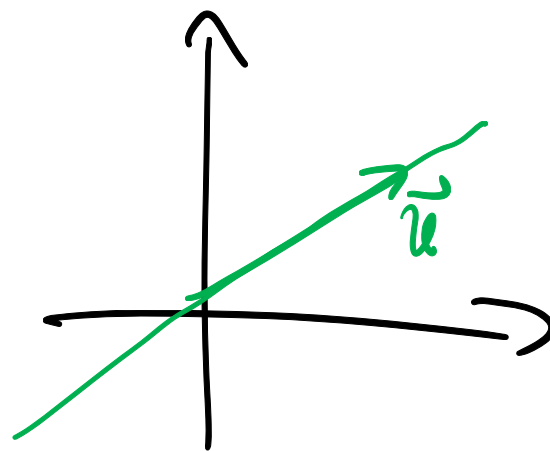
$$\{0, 1, 2\} \quad \times$$

\mathbb{R} 2 subspaces.

Ex. \mathbb{R}^2 possible subspaces.

$\{\vec{0}\}$. \mathbb{R}^2 .

$\text{span}\{\vec{u}\}$, $\vec{u} \in \mathbb{R}^2, \vec{u} \neq \vec{0}$



Ex. Sol set to hom. lin. sys.

$$A\vec{x} = \vec{0} \quad S. \quad A \in \mathbb{R}^{m \times n}$$

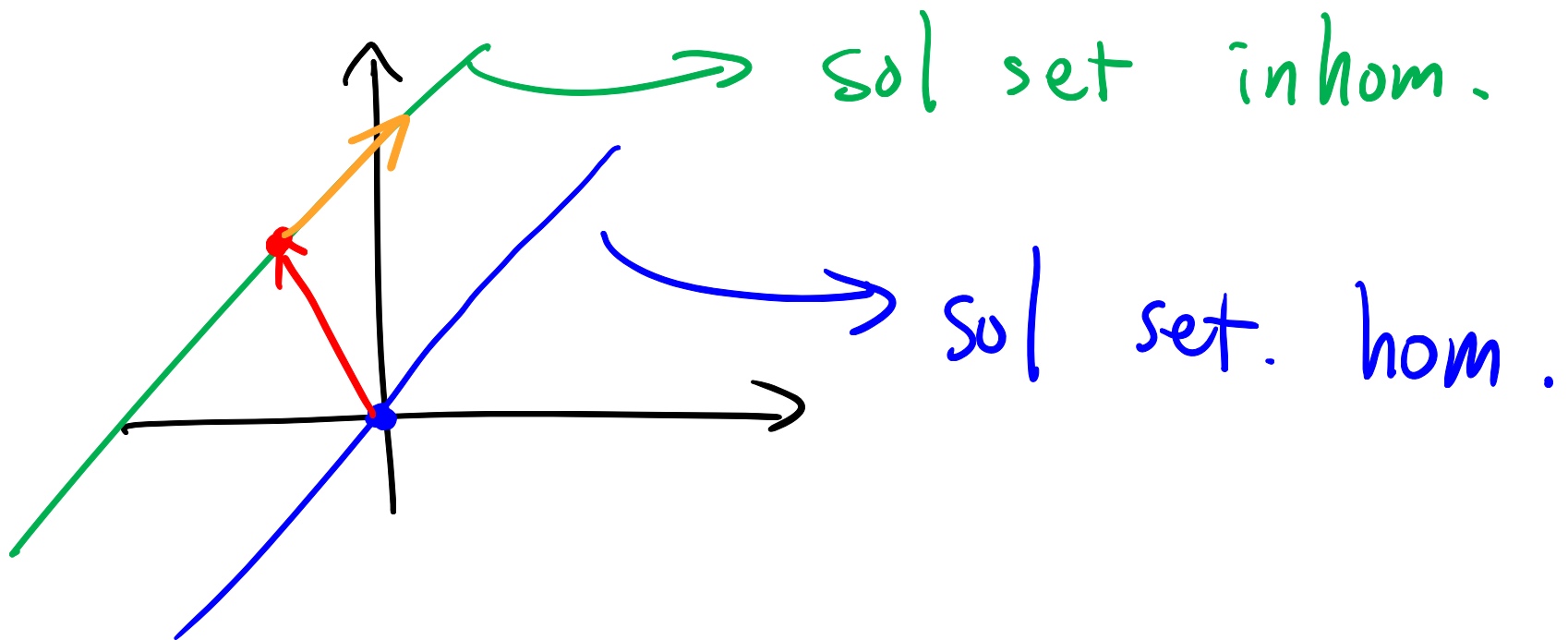
$$(1) \vec{0} \in S$$

$$(2) \vec{x}, \vec{y} \in S, \quad \vec{x} + \vec{y} \in S$$

$$(3) c \in \mathbb{R}, \quad \vec{x} \in S, \quad c\vec{x} \in S.$$

S is a subspace. of \mathbb{R}^n

what about $A\vec{x} = \vec{b}$



$$\{\vec{v}_1, \dots, \vec{v}_k\} \subseteq \mathbb{R}^n$$

Then $\text{span}\{\vec{v}_1, \dots, \vec{v}_k\}$ is a subspace of \mathbb{R}^n .

Two important examples of subspace

$$A \in \mathbb{R}^{m \times n}$$

(1) Column space.

$\text{col}(A)$ = span of all column
vectors of A .

$$A = [\vec{a}_1, \dots, \vec{a}_n].$$

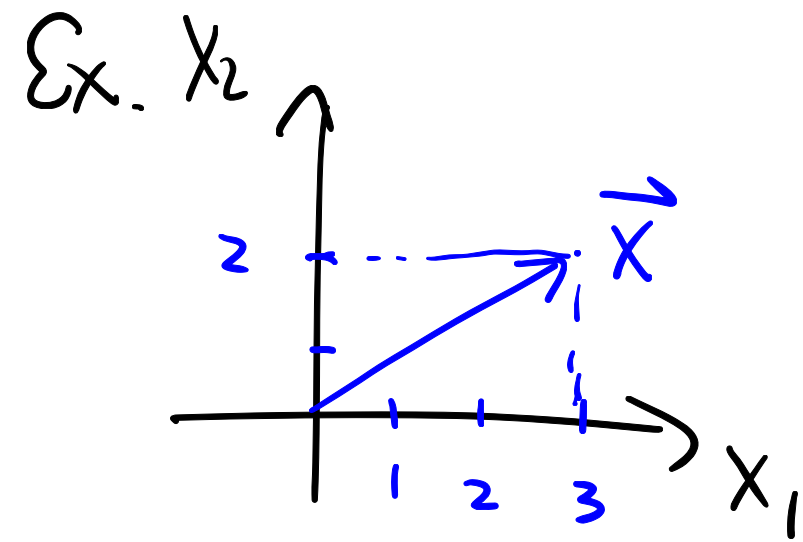
$$\text{col}(A) = \text{span} \{ \vec{a}_1, \dots, \vec{a}_n \}$$

a subspace of \mathbb{R}^m

(2) Null space.

$\text{Null}(A)$ = sol set of $A\vec{x} = \vec{0}$.

a subspace of \mathbb{R}^n



$$\vec{x} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$$

$$\vec{b}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \vec{b}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\vec{x} \in \mathbb{R}^2.$$

$$\vec{x} = x_1 \vec{b}_1 + x_2 \vec{b}_2 = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$[\vec{x}]_{\mathcal{B}} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$$

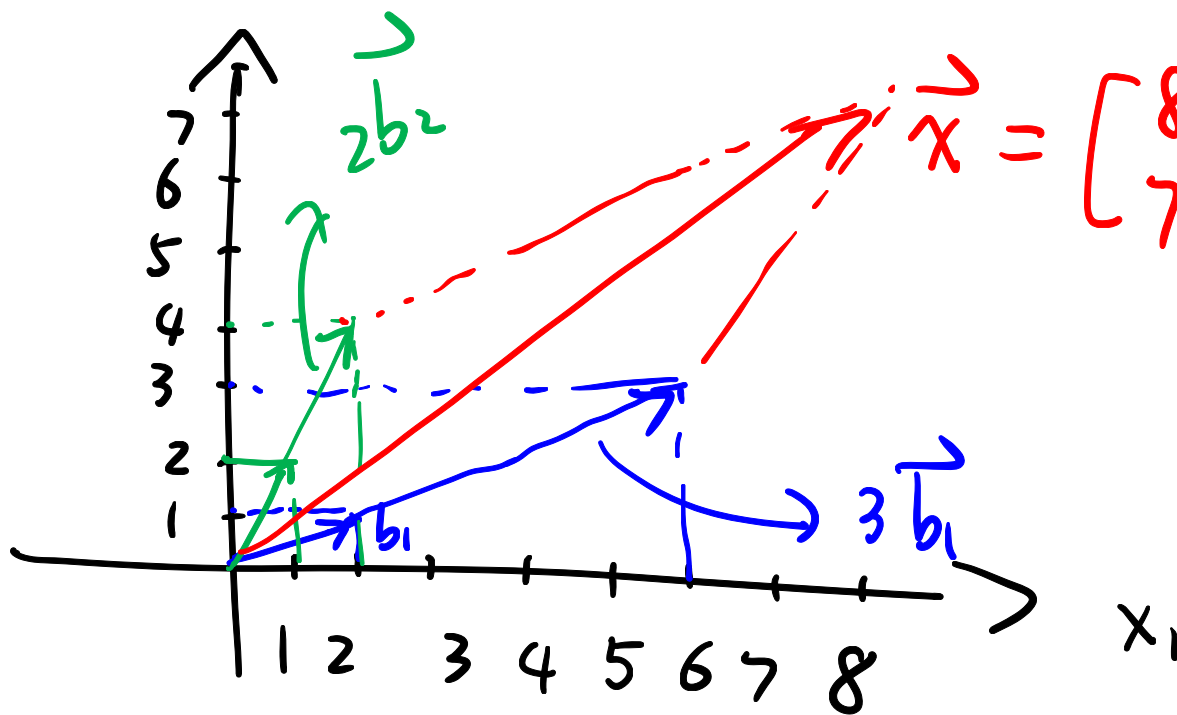
$$\mathcal{B} = \{ \vec{b}_1, \vec{b}_2 \} \text{ basis}$$

"standard basis"

Ex. $\vec{b}_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$, $\vec{b}_2 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

$\vec{x} = 3\vec{b}_1 + 2\vec{b}_2$. $B = \{\vec{b}_1, \vec{b}_2\}$

$[\vec{x}]_B = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$



Def A basis for a subspace H
of \mathbb{R}^n is an ordered set
of vectors

What is coordinate

