



# PROGRAMMING IN C++

## Jülich Supercomputing Centre

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# Chapter 3

# Templates

# Using STL containers and algorithms

# ALGORITHMS

```
// examples/strtrans.cc
#include <iostream>
#include <algorithm>
#include <string>
auto main() -> int {
    std::string name;
    std::cout << "What's your name ? ";
    getline(std::cin, name);
    auto bkpname {name};
    std::transform(begin(name), end(name), begin(name), toupper);
    std::cout << bkpname << " <-----> " << name << "\n";
}
```

- What does this code do ?

# ALGORITHMS

---

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#include <iostream>
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auto main() -> int {
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    std::transform(begin(name), end(name), begin(name), toupper);
    std::cout << bkpname << " <-----> " << name << "\n";
}
```

---

- What does this code do ?
- `std::transform` transforms each element in an input range, and writes the results to an output range using a given operation

# ALGORITHMS

---

```
1 #include <iostream>
2 #include <fstream>
3 #include <vector>
4 #include <ranges>
5 #include <algorithm>
6 #include <string>
7 auto main(int argc, char* argv[]) -> int {
8     std::vector<std::string> names;
9     std::ifstream input_file{argv[1]};
10    std::string name;
11    while (getline(input_file, name))
12        if (not name.empty())
13            names.push_back(name);
14
15    std::ranges::sort(names);
16    //
17    //
18    //
19    //
20
21    for (auto n : names)
22        std::cout << n << "\n";
23 }
```

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15    std::ranges::sort(names);
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```

- What does this code do ?
- `vector`, `string` grow to accommodate any new element added using `push_back`

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```

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  - `sort` sorts a range in increasing order

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23 }
```

- What does this code do ?
  - `vector`, `string` grow to accommodate any new element added using `push_back`
- `sort` sorts a range in increasing order
- What is "increasing" order is decided by using the operator `<` to compare elements of the sequence

# ALGORITHMS WITH LAMBDA FUNCTIONS

- What does this code do ?

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3 #include <vector>
4 #include <ranges>
5 #include <algorithm>
6 #include <string>
7 auto main(int argc, char* argv[]) -> int {
8     std::vector<std::string> names;
9     std::ifstream input_file{argv[1]};
10    std::string name;
11    while (getline(input_file, name))
12        if (not name.empty())
13            names.push_back(name);
14
15    std::ranges::sort(names,
16                      [](auto name1, auto name2) {
17                          return name1 > name2;
18                      });
19
20
21    for (auto n : names)
22        std::cout << n << "\n";
23 }
```

# ALGORITHMS WITH LAMBDA FUNCTIONS

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2 #include <fstream>
3 #include <vector>
4 #include <ranges>
5 #include <algorithm>
6 #include <string>
7 auto main(int argc, char* argv[]) -> int {
8     std::vector<std::string> names;
9     std::ifstream input_file{argv[1]};
10    std::string name;
11    while (getline(input_file, name))
12        if (not name.empty())
13            names.push_back(name);
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15    std::ranges::sort(names,
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```

- What does this code do ?
- We can give `std::sort` a comparison function as the sorting criterion

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8     std::vector<std::string> names;
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10    std::string name;
11    while (getline(input_file, name))
12        if (not name.empty())
13            names.push_back(name);
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15    std::ranges::sort(names,
16                      [](auto name1, auto name2) {
17                          return name1 > name2;
18                      });
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21    for (auto n : names)
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23 }
```

- What does this code do ?
- We can give `std::sort` a comparison function as the sorting criterion
- This can be used to order the elements in lots of different ways. Like sorting **in decreasing order**.

# ALGORITHMS WITH LAMBDA FUNCTIONS

---

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4 #include <algorithm>
5 #include <string>
6 auto main(int argc, char* argv[]) -> int
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9     std::ifstream input_file{argv[1]};
10    std::string name;
11    while (getline(input_file, name))
12        if (not name.empty())
13            names.push_back(name);
14
15    std::ranges::sort(names,
16                      [](auto name1, auto name2) {
17                          return name1.length() <
18                                 name2.length();
19                      });
20    for (auto n : names)
21        std::cout << n << "\n";
22    }
23 }
```

- What does this code do ?
- We can give `std::sort` a comparison function as the sorting criterion
- This can be used to order the elements in lots of different ways. Like sorting **in decreasing order**.
- Or, sorting **by the length of the strings ...**

# ALGORITHMS WITH LAMBDA FUNCTIONS

```
1 #include <iostream>
2 #include <fstream>
3 #include <vector>
4 #include <algorithm>
5 #include <string>
6 auto main(int argc, char* argv[]) -> int
7 {
8     using namespace std;
9     vector<std::string> names;
10    ifstream input_file{argv[1]};
11    string name;
12    while (getline(input_file, name))
13        if (not name.empty()) names.push_back(name);
14
15    sort(names.begin(), names.end(),
16          [](auto name1, auto name2) -> bool {
17              return name1.length() < name2.length();
18          });
19
20    for (auto n : names) cout << n << "\n";
21 }
22 }
```

- `sort()` needs a function comparing two elements
- If we have such a function, we can pass its name
- If we don't, we can use a lambda function, as the argument to the function `sort()`
- Notation resembles a mapping  $a, b, c \dots \mapsto value$  from some inputs to an output value
- Like normal functions, we can skip the trailing return type if the return type is unambiguous

# Function and class templates

# FUNCTION OVERLOADING

```
1 auto power(int x, unsigned n) -> unsigned
2 {
3     ans = 1;
4     for (; n > 0; --n) ans *= x;
5     return ans;
6 }
7 auto power(double x, double y) -> double
8 {
9     return exp(y * log(x));
10 }
```

- When specialised strategies are needed to accomplish the same task for different types

```
1 auto someother(double mu, double alpha,
2                 int rank) -> double
3 {
4     double st=power(mu,alpha)*exp(-mu);
5
6     if (n_on_bits(power(rank,5))<8)
7         st=0;
8
9     return st;
10 }
```

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- When specialised strategies are needed to accomplish the same task for different types
- Static polymorphism: no virtual dispatch, everything resolved at compilation time

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7         st=0;
8
9     return st;
10 }
```

# FUNCTION OVERLOADING

---

```
1 void copy(int* start, int* end, int* start2)
2 {
3     for (; start != end; ++start, ++start2) {
4         *start2 = *start;
5     }
6 }
7 void copy(string* start, string* end,
8           string* start2)
9 {
10    for (; start != end; ++start, ++start2) {
11        *start2 = *start;
12    }
13 }
14 void copy(double* start, double* end,
15           double* start2)
16 {
17     for (; start != end; ++start, ++start2) {
18         *start2 = *start;
19     }
20 }
21 double a[10], b[10];
22 copy(a, a + 10, b);
```

---

- When specialised strategies are needed to accomplish the same task for different types
- Static polymorphism: no virtual dispatch, everything resolved at compilation time
- But sometimes we need the opposite: same operations to be performed on different kinds of input

# INTRODUCTION TO C++ TEMPLATES

```
1 void copy(int* start, int* end, int* start2)
2 {
3     for (; start != end; ++start, ++start2) {
4         *start2 = *start;
5     }
6 }
7 void copy(string* start, string* end,
8             string* start2)
9 {
10    for (; start != end; ++start, ++start2) {
11        *start2 = *start;
12    }
13 }
14 void copy(double* start, double* end,
15             double* start2)
16 {
17     for (; start != end; ++start, ++start2) {
18         *start2 = *start;
19     }
20 }
21 double a[10], b[10];
22 copy(a, a + 10, b);
```

## Same operations on different types

- Exactly the same high level code
- Assigning a string to another may involve very different low level operations compared to assigning an integer to another. But once we have written our string class, we may write the exact same code for the string and integer versions of this kind of operations!
- Couldn't we automate the process of writing the 3 variants shown, by perhaps, using a placeholder type, and generating the right variant wherever required ?

# INTRODUCTION TO C++ TEMPLATES

Dear compiler, in the following, T is a placeholder!

```
void copy(T* start, T* end, T* start2)
{
    for (; start != end; ++start, ++start2) {
        *start2 = *start;
    }
}
```

Wouldn't it be nice,

- if we could write the function in terms of some placeholder for the actual type ?

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Dear compiler, in the following, T is a placeholder!

```
void copy(T* start, T* end, T* start2)
{
    for (; start != end; ++start, ++start2) {
        *start2 = *start;
    }
}
```

```
double a[10], b[10];
copy<double>(a, a + 10, b);
string names[10], onames[10];
copy<string>(onames, onames + 10, names);
```

Wouldn't it be nice,

- if we could write the function in terms of some placeholder for the actual type ?
- and when we need to use the function, we indicate what to substitute in place of the placeholder ?

# INTRODUCTION TO C++ TEMPLATES

```
template <class T>
void copy(T* start, T* end, T* start2)
{
    for (; start != end; ++start, ++start2) {
        *start2 = *start;
    }
}

double a[10], b[10];
copy<double>(a, a + 10, b);
string names[10], onames[10];
copy<string>(onames, onames + 10, names);
```

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- and when we need to use the function, we indicate what to substitute in place of the placeholder ?
- For the first point : Sure!

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```

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- if we could write the function in terms of some placeholder for the actual type ?
- and when we need to use the function, we indicate what to substitute in place of the placeholder ?
- For the first point : Sure!
- For the second point: the compiler already knows those types based on the inputs at the point of usage!

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- Test it! [examples/template\\_intro.cc](#)

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void copy(T* start, T* end, T* start2)
{
    for (; start != end; ++start, ++start2) {
        *start2 = *start;
    }
}

double a[10], b[10];
copy(a, a + 10, b);
string names[10], onames[10];
copy(onames, onames + 10, names);
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Wouldn't it be nice,

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- and when we need to use the function, we indicate what to substitute in place of the placeholder ?
- For the first point : Sure!
- For the second point: the compiler already knows those types based on the inputs at the point of usage!
- Test it! [examples/template\\_intro.cc](#)

Although we seemingly call a function we only wrote once, with different kinds of inputs, the compiler sees these as calls to two different functions. No runtime decision is needed to find the function to call.

# TEMPLATES

**Generic code** The logic of the copy operation is quite simple. Given a pair of “iterators” (Behaviourally pointer like entities: can be advanced along a sequence, can be dereferenced) `first` and `last` in an input sequence, and a target location `result` in an output sequence, we want to:

- Loop over the input sequence
- For each position of the input iterator, copy the current element to the output iterator position
- Increment the input and output iterators
- Stop if the input iterator has reached `last`

# A TEMPLATE FOR A GENERIC COPY OPERATION

---

```
1 template <class InputIterator, class OutputIterator>
2 OutputIterator copy(InputIterator first, InputIterator last, OutputIterator result)
3 {
4     while (first != last) *result++ = *first++;
5     return result;
6 }
```

---

## C++ template notation

- A **template** with which to generate code!
- If you had iterators to two kinds of sequences, you could substitute them in the above template and have a nice copy function!
- The compiler does the necessary substitution when you try to use the function
- The compiler needs access to the template source code at the point where it is trying to instantiate it!

# ORDERED PAIRS

---

```
1  struct double_pair
2  {
3      double first, second;
4  };
5  ...
6  double_pair coords[100];
7  ...
8  struct int_pair
9  {
10     int first, second;
11 };
12 ...
13 int_pair line_ranges[100];
14 ...
15 struct int_double_pair
16 {
17     // wait!
18     // can I make a template out of it?
19 };
```

---

## Class templates

- Classes can be templates too

# ORDERED PAIRS

```
1 pair<double,double> coords[100];
2 pair<int,int> line_ranges[100];
3 pair<int,double> whatever;
```

pair<int, double>, after the template substitutions, becomes

```
struct pair<int, double>
{
    int first;
    double second;
};
```

## Class templates

- Classes can be templates too
- Generated when the template is “instantiated”

---

```
1 template <class T, class U>
2 struct pair
3 {
4     T first;
5     U second;
6 };
```

---

# ORDERED PAIRS

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1 pair<double,double> coords[100];
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- Generated when the template is “instantiated”

---

```
1 template <class T, class U>
2 struct pair
3 {
4     T first;
5     U second;
6 };
```

- Useful for creating many generic types

# CLASS TEMPLATES YOU HAVE ALREADY SEEN...

- `std::vector<T>` , `std::array<T, N>` , `std::valarray<T>` , `std::map<K, V>` ,  
`std::string` ...

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`std::string` ...
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- The code required to write containers of `int` , `double` , `complex_number` or any other class type will only differ by the type of the elements

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- The code required to write containers of `int` , `double` , `complex_number` or any other class type will only differ by the type of the elements
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- No inheritance relationship between vectors of different types

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- `std::vector<T>`, `std::array<T, N>`, `std::valarray<T>`, `std::map<K, V>`,  
`std::string` ...
- A vector means ... 
- The code required to write containers of `int`, `double`, `complex_number` or any other class type will only differ by the type of the elements
- The template captures the essential structure, and we don't need to separately develop, debug or test these parameterised types for every possible element type
- No inheritance relationship between vectors of different types
- No inheritance relationship required between entities which can be vector elements

# VARIABLE TEMPLATES

---

```
1 template <class T> constexpr auto algocategory = 0;
2 template<> constexpr auto algocategory<int> = 1;
3 template<> constexpr auto algocategory<long> = 1;
4 template<> constexpr auto algocategory<int*> = 2;
5 template<> constexpr auto algocategory<long*> = 2;
6 template <class T>
7 auto proc(T x)
8 {
9     if constexpr (algocategory<T> == 2) {
10         std::cout << "Using method for category 2 \n";
11     } else if constexpr (algocategory<T> == 1) {
12         std::cout << "Using method for category 1 \n";
13     } else {
14         std::cout << "Using method for category 0 \n";
15     }
16 }
```

---

```
18 auto main() -> int
19 {
20     int v{7};
21     proc(1);
22     proc(1.);
23     proc(1L);
24     proc(v);
25     proc(&v);
26 }
```

- Can be a static data member of a class or a global variable parameterised by template parameters
- Can be used along with `compile time if` statements to decide between different algorithms

# ONE CLASS TEMPLATE IN DETAIL

## Initialiser list constructors

- The `darray` class we saw earlier in some examples represents a dynamic array, like the `std::vector`. It is a good example to illustrate more about class templates

# ONE CLASS TEMPLATE IN DETAIL

## Initialiser list constructors

- The `darray` class we saw earlier in some examples represents a dynamic array, like the `std::vector`. It is a good example to illustrate more about class templates
- We want to be able to initialise our `darray<T>` like this:

```
darray<double> D(400, 0.);  
darray<string> S{"A", "B", "C"};  
darray<int> I{1, 2, 3, 4, 5};
```

# ONE CLASS TEMPLATE IN DETAIL

## Initialiser list constructors

- The `darray` class we saw earlier in some examples represents a dynamic array, like the `std::vector`. It is a good example to illustrate more about class templates
- We want to be able to initialise our `darray<T>` like this:

```
darray<double> D(400, 0.);  
darray<string> S{"A", "B", "C"};  
darray<int> I{1, 2, 3, 4, 5};
```

- And then we want to be able to use it as follows...

```
for (auto i = 0UL; i < D.size(); ++i) {  
    D[i] = i * i;  
    std::cout << D[i] << "\n";  
}
```

# ONE CLASS TEMPLATE IN DETAIL

## Initialiser list constructors

- Making it into a template and writing many of the special functions is easy.

```
template <class T>
class darray {
    std::unique_ptr<T[]> dat;
    size_t sz{};
public:
    darray() = default;
    ~darray() = default;
    darray(const darray& other);
    darray(darray&&) noexcept = default;
    darray& operator=(const darray& other);
    darray& operator=(darray&&) noexcept = default;
};
```

- Using the `unique_ptr` to manage the heap allocation/deallocation means we don't need to do anything special for default constructor, destructor and the move operations. Only copy needs to be carefully implemented!

# ONE CLASS TEMPLATE IN DETAIL

## Initialiser list constructors

- To initialise our `darray<T>` like this:

---

```
1 darray<string> S{"A", "B", "C"};
2 darray<int> I{1, 2, 3, 4, 5};
```

---

we need an `initialiser_list` constructor

---

```
1 darray(initializer_list<T> l) {
2     arr = std::make_unique<T[]>(l.size());
3     for (auto i{0UL}; auto& el : l) arr[i++] = el;
4 }
```

---

# A DYNAMIC ARRAY CLASS TEMPLATE

```
1 template <class T>
2 class darray {
3 public:
4     auto operator[](size_t i) const
5         -> const T& { return arr[i]; }
6     auto operator[](size_t i) -> T& { return arr[i]; }
7 };
```

- Two versions of the [] operator for read-only and read/write access

# A DYNAMIC ARRAY CLASS TEMPLATE

```
1 template <class T>
2 class darray {
3 public:
4     auto operator[](size_t i) const
5         -> const T& { return arr[i]; }
6     auto operator[](size_t i) -> T& { return arr[i]; }
7 };
```

- Two versions of the `[]` operator for read-only and read/write access
- Use `const` qualifier in any member function which does not change the object

# A DYNAMIC ARRAY CLASS TEMPLATE

```
1 template <class T>
2 class darray {
3 public:
4     auto operator[](size_t i) const
5         -> const T& { return arr[i]; }
6     auto operator[](size_t i) -> T& { return arr[i]; }
7 };
```

- Two versions of the `[]` operator for read-only and read/write access
- Use `const` qualifier in any member function which does not change the object
- Both versions let us to use a `darray<int>` object, say, `D` with array style indexing, e.g., `D[5UL]`. The second is usable only when `D` is not declared `const`.

# TYPE DEDUCTIONS

- Template parameters can be type names or compile time constant values of different types.
- Until C++20, non-type template parameters were limited to integral types. Now, a lot of other types are allowed.

```
1 template <class T, int N>
2 struct my_array {
3     T data[N];
4 };
```

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- Until C++20, non-type template parameters were limited to integral types. Now, a lot of other types are allowed.
- Can be used to specify compile time constant sizes

```
1 template <class T, int N>
2 struct my_array {
3     T data[N];
4 };
```

```
1 template <class T,
2                 int nrows, int ncols>
3 struct my_matrix {
4     T data[nrows * ncols];
5 };
```

# TYPE DEDUCTIONS

- Template parameters can be type names or compile time constant values of different types.
- Until C++20, non-type template parameters were limited to integral types. Now, a lot of other types are allowed.
- Can be used to specify compile time constant sizes
- but also give you a peculiar kind of “function” in effect
- Old uses of template integer arithmetic are by now obsolete. `constexpr` functions constitute a vastly superior alternative.
- But, type-deductions remain an important use for template meta-programs

```
1 template <class T, int N>
2 struct my_array {
3     T data[N];
4 };
```

```
1 template <class T,
2                 int nrows, int ncols>
3 struct my_matrix {
4     T data[nrows * ncols];
5 };
```

```
1 template <int i, int j>
2 struct mult {
3     static const int value=i*j;
4 };
5 ...
6 my_array< mult<19,21>::value > vals;
```

# EVALUATE DEPENDENT TYPES

- Suppose we want to implement a template function

```
template <class T> auto f(T a) -> U;
```

such that when T is a non-pointer type, U should take the value T. But if T is itself a pointer, U is the type obtained by dereferencing the pointer

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- We could use a template function to "compute" the type U like this:

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template <class T> struct remove_pointer { using type = T; };
template <class T> struct remove_pointer<T*> { using type = T; };
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```
template <class T> struct remove_pointer { using type = T; };
template <class T> struct remove_pointer<T*> { using type = T; };
```

- We can then declare the function as:

```
template <class InputType>
auto f(InputType a) -> remove_pointer<InputType>::type ;
```

# TYPE FUNCTIONS

- Compute properties of types
- Compute dependent types
- Typically used with convenient alias template declarations for the **dependent type** or the **constant value**

```
template <class T1, class T2>
std::is_same<T1,T2>::value

template <class T>
std::is_integral<T>::value

template <class T>
std::make_signed<T>::type

template <class T>
std::remove_reference<T>::type

template <class T>
using remove_reference_t = 
    typename remove_reference<T>::type;

template <class T>
inline constexpr bool is_integral_v =
    std::is_integral<T>::value;
```

# TYPETRAITS

- `is_integral_v<T>` : `T` is an integer type
- `is_const_v<T>` : has a `const` qualifier
- `is_class_v<T>` : struct or class
- `is_pointer_v<T>` : Pointer type
- `is_abstract_v<T>` : Abstract class with at least one pure virtual function
- `is_copy_constructible_v<T>` : Class allows copy construction
- `is_same_v<T1, T2>` : `T1` and `T2` are the same types
- `is_base_of_v<T, D>` : `T` is base class of `D`
- `is_convertible_v<T, T2>` : `T` is convertible to `T2`

# FORWARDING REFERENCES

```
1 template <class T>
2 auto wrapperfunc( T&& t)
3 {
4     other(std::forward<T>(t));
5 }
6 auto main() -> int
7 {
8     std::string x{"Solar"};
9     std::string y{"System"};
10    wrapperfunc(x);
11    wrapperfunc(x + " " + y);
12 }
```

- Function argument written as if it were an R-value reference to a cv-unqualified template parameter
- If `wrapperfunc` is called with a constant L-value, `T` is deduced to be a constant L-value reference, and `other` receives a constant L-value reference
- If `wrapperfunc` is called with an L-value, `T` is deduced to be an L-value reference, and `other` receives an L-value reference
- If the input is an R-value, then `T` is inferred to be a plain type, and `forward` ensures that `other` receives an R-value reference

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- Type deduction for variables declared with `auto&&` follows the same rules. The declared variable is a `const` L-value reference, mutable L-value reference or an R-value reference depending on the initialiser.

- Function argument written as if it were an R-value reference to a `cv-unqualified template parameter`
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# REF-QUALIFIERS

---

```
1 template <class T>
2 struct myopt {
3     T v;
4     bool hasval { false };
5     auto internal() const -> const T&
6     {
7         if (hasval)
8             return v;
9         throw std::runtime_error { "Bad optional" };
10    }
11    auto internal() -> T&
12    {
13        if (hasval)
14            return v;
15        throw std::runtime_error { "Bad optional" };
16    }
17};
```

---

- Requirement: return a constant from a `const` qualified object, and a mutable answer from a mutable object

# REF-QUALIFIERS

```
1  auto internal() const -> const T&
2  {
3      if (hasval)
4          return v;
5      throw std::runtime_error { "Bad optional" };
6  }
7  auto internal() -> T&
8  {
9      if (hasval)
10         return v;
11     throw std::runtime_error { "Bad optional" };
12 }
13 };
14 auto f() -> myopt<Vbose>
15 {
16     return myopt<Vbose> { Vbose { "A very long string" } };
17 }
18 auto main() -> int
19 {
20     auto B = f().internal();
21     std::cout << "Message: " << B.value() << "\n";
22 }
```

- Requirement: return a constant from a `const` qualified object, and a mutable answer from a mutable object
- The construction of the object `B` here invokes the copy constructor

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- Requirement: return a constant from a **const** qualified object, and a mutable answer from a mutable object
- The construction of the object **B** here invokes the copy constructor
- How do we indicate that the implicit argument (calling instance) is a temporary? (to hopefully engage the move constructor!)

# REF-QUALIFIERS

---

```
1   auto internal() const& -> const T&
2   {
3     // ...
4   }
5   auto internal()& -> T&
6   {
7     // ...
8   }
9   auto internal() const&& -> const T&&
10  {
11    if (hasval)
12      return v;
13    throw std::runtime_error { "Bad optional" };
14  }
15  auto internal()&& -> T&&
16  {
17    if (hasval)
18      return v;
19    throw std::runtime_error { "Bad optional" };
20  }
21 };
```

---

- Requirement: return a constant from a **const** qualified object, and a mutable answer from a mutable object
- The construction of the object **B** here invokes the copy constructor
- How do we indicate that the implicit argument (calling instance) is a temporary? (to hopefully engage the move constructor!)
- Just like the **const** qualifier, we can place L- and R- value reference symbols to the right of the function parameter list

# "DEDUCING THIS" FROM C++23

---

```
1 template <class T>
2 struct myopt {
3     T v;
4     bool hasval { false };
5     auto internal() const& -> const T&
6     {
7         // ...
8     }
9     auto internal() & -> T&
10    {
11        // ...
12    }
13    auto internal() const&& -> const T&&
14    {
15        // ...
16    }
17    auto internal() && -> T&&
18    {
19        // ...
20    }
21};
```

---

- The C++11 way of qualifying member functions by L- and R- value references is able to avoid more unnecessary copies. When done right, it's good for performance!

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---

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3     T v;
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```

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- The C++11 way of qualifying member functions by L- and R- value references is able to avoid more unnecessary copies. When done right, it's good for performance!
- But, we end up with 4 versions of many member functions, 4 times as many lines to maintain or making mistakes. (often overlooked for this reason!)

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---

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1 template <class T>
2 struct myopt {
3     T v;
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5     auto internal() const& -> const T&
6     {
7         // ...
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- But, we end up with 4 versions of many member functions, 4 times as many lines to maintain or making mistakes. (often overlooked for this reason!)
- In C++23, it is possible to explicitly specify the formerly implicit calling instance for a member function

# "DEDUCING THIS" FROM C++23

```
1 template <class T>
2 struct myopt {
3     T v;
4     bool hasval { false };
5     template <class Self>
6     auto&& internal(this Self&& self)
7     {
8         if (hasval)
9             return std::forward<Self>(self).v;
10        throw std::runtime_error { "Bad optional" };
11    }
12};
```

- The C++11 way of qualifying member functions by L- and R- value references is able to avoid more unnecessary copies. When done right, it's good for performance!
- But, we end up with 4 versions of many member functions, 4 times as many lines to maintain or making mistakes. (often overlooked for this reason!)
- In C++23, it is possible to explicitly specify the formerly implicit calling instance for a member function
- It is possible to use the explicit `this` parameter with the rules to template argument deduction to combine the 4 versions into one!

# NOT A TEXT SUBSTITUTION ENGINE!

## Template specialisation

---

```
1 template <class T>
2 class vector {
3     // implementation of a general
4     // vector for any type T
5 };
6 template <>
7 class vector<bool> {
8     // Store the true false values
9     // in a compressed way, i.e.,
10    // 32 of them in a single int
11 };
12 void somewhere_else()
13 {
14     vector<bool> A;
15     // Uses the special implementation
16 }
```

---

- Templates are defined to work with generic template parameters
- But special values of those parameters, which should be treated differently, can be specified using "template specialisations" as shown
- If a matching specialisation is found, it is preferred over the general template

---

```
1 template <class A, class B>
2 constexpr auto are_same = false;
3 template <class A>
4 constexpr auto are_same<A, A> = true;
5 static_assert(are_same<int, long>); // Fails
6 using Integer = int;
7 static_assert(are_same<int, Integer>); // Passes
```

---

# NOT A TEXT SUBSTITUTION ENGINE!

## Recursion and integer arithmetic

```
1 template <unsigned N> constexpr unsigned fact = N * fact<N-1>;
2 template <> constexpr unsigned fact<0> = 1U;
3 static_assert(fact<7> == 5040)
```

- Templates support recursive instantiation
- Combined with specialisation to terminate recursion
- Recursion and specialisation can be used to emulate “loop” like calculations via tail-recursion

### Exercise 3.1:

The example source file `examples/no_textsub.cc` demonstrates recursion and specialisation in templates, and uses `static_assert` to verify that the arithmetic calculations in this case indeed happen during compilation.

# NOT A TEXT SUBSTITUTION ENGINE!

Because: SFINAE

---

```
1 template <bool Cond, class T> struct enable_if {};
2 template <class T> struct enable_if<true, T> { using type = T; }
3 template <class T>
4 auto func(T x) -> enable_if<sizeof(T) == 8UL, T>::type {
5 //impl1
6 }
7 template <class T>
8 auto func(T x) -> enable_if<sizeof(T) != 8UL, T>::type {
9 //impl2
10 }
```

---

- Substitution Failure Is Not An Error
- If substituting a template parameter results in incomplete or invalid function declarations, that overload is ignored.
- The compiler simply tries to find another template with the same name that might match
- If it can't find any, then you have an error
- `func(1)` will resolve to the second version and `func(1.0)` will resolve to the first version during compilation!

# NOT A TEXT SUBSTITUTION ENGINE!

Because: concepts

---

```
1 template <class T>
2 auto func(T x) -> T requires (sizeof(T) == 8UL) {
3 //impl1
4 }
5 template <class T>
6 auto func(T x) -> T requires (sizeof(T) != 8UL) {
7 //impl2
8 }
```

---

- Different implementations can be provided requiring different properties of the input type
- Before C++20, this sort of selection was done using `std::enable_if`. Now, `concepts` provide a far cleaner alternative.
- Again, `func(1)` will resolve to the second version and `func(1.0)` will resolve to the first version during compilation!

# Constrained templates

# CONSTRAINED TEMPLATES

- We created overloaded functions so that different strategies can be employed for different input types

```
auto power(double x, double y) -> double ;  
auto power(double x, int i) -> double ;
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- Some way to impose requirements on permissible matches for the template parameters. Something like:

```
template <class T> auto power(double x, T i) -> double requires floating_point<T>;
template <class T> auto power(double x, T i) -> double requires integer<T>;
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- If we could do that, we can combine the generality of templates with the selectiveness of function overloading
- We can

# CONCEPTS

## Named requirements on template parameters

- **concept**s are named requirements on template parameters, such as `floating_point`, `contiguous_range`
- If `MyAPI` is a **concept**, and `T` is a type, `MyAPI<T>` evaluates at compile time to either true or false.
- Concepts can be combined using conjunctions (`&&`) and disjunctions (`||`) to make other concepts.
- A **requires** clause introduces a constraint on a template type

A suitably designed set of concepts can greatly improve readability of template code

# CREATING CONCEPTS

```
template <template-pars>
concept conceptname = constraint_expr;
```

```
template <class T>
concept Integer = std::is_integral_v<T>;
template <class D, class B>
concept Derived = std::is_base_of<B, D>;
```

```
class Counters;
template <class T>
concept Integer_ish = Integer<T> ||
                     Derived<T, Counters>;
```

- Out of a simple `type_traits` style boolean expression
- Combine with logical operators to create more complex requirements
- The `requires` expression allows creation of syntactic requirements as shown in the last two examples.

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class Counters;
template <class T>
concept Integer_ish = Integer<T> ||
                     Derived<T, Counters>;

template <class T>
concept Addable = requires (T a, T b) {
    { a + b };
};
template <class T>
concept Indexable = requires(T A) {
    { A[0UL] };
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- Out of a simple `type_traits` style boolean expression
- Combine with logical operators to create more complex requirements
- The `requires` expression allows creation of syntactic requirements as shown in the last two examples.
- The `requires` expression can contain a parameter list and a brace enclosed sequence of requirements, which can be:
  - type requirements, e.g., `typename T::value_type`;
  - simple requirements as shown on the left
  - compound requirements with optional return type constraints, e.g.,  
`{ A[0UL] } -> convertible_to<int>;`

# USING CONCEPTS

```
template <class T>
requires Integer_ish<T>
auto categ0(T&& i, double x) -> T;

template <class T>
auto categ1(T&& i, double x) -> T
    requires Integer_ish<T>;

template <Integer_ish T>
auto categ2(T&& i, double x) -> T;

void erase(Integer_ish auto&& i)
```

To constrain template parameters, one can

- place a `requires` clause immediately after the template parameter list
- place a `requires` clause after the function parameter parentheses
- Use the `concept` name in place of `class` or `typename` in the template parameter list
- Use ConceptName `auto` in the function parameter list

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- Use the **concept** name in place of **class** or **typename** in the template parameter list
- Use ConceptName **auto** in the function parameter list

# DECLARING FUNCTION INPUT PARAMETERS WITH AUTO

```
1 template <class T>
2 auto sqr(const T& x) { return x * x; }
```

- Because of syntax introduced for functions with constrained templates in C++20, we have a new way to write fully unconstrained function templates...

# DECLARING FUNCTION INPUT PARAMETERS WITH AUTO

```
1 auto sqr(const auto& x) { return x * x; }
```

- Because of syntax introduced for functions with constrained templates in C++20, we have a new way to write fully unconstrained function templates...
- Functions with `auto` in their parameter list are implicitly function templates

# DECLARING FUNCTION INPUT PARAMETERS WITH AUTO

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- Because of syntax introduced for functions with constrained templates in C++20, we have a new way to write fully unconstrained function templates...
- Functions with `auto` in their parameter list are implicitly function templates

## Exercise 3.6:

The program `examples/gcd_w_concepts.cc` shows a very small concept definition and its use in a function calculating the greatest common divisor of two integers.

## Exercise 3.7:

The series of programs `examples/generic_func1.cc` through `generic_func4.cc` shows some trivial functions implemented with templates with and without constraints. The files contain plenty of comments explaining the rationale and use of concepts.

# OVERLOADING BASED ON CONCEPTS

---

```
1 template <class N>
2 concept Number = std::floating_point<N>
3             or std::integral<N>;
4
5
6 void proc(Number auto&& x) {
7     std::cout << "Called proc for numbers";
8 }
9
10
11
12 auto main() -> int {
13     proc(-1);
14     proc(88UL);
15     proc("0118 999 88199 9119725    3");
16     proc(3.141);
17     proc("eighty"s);
18 }
```

---

- Constraints on template parameters are not just “documentation” or decoration.

# OVERLOADING BASED ON CONCEPTS

---

```
1 template <class N>
2 concept Number = std::floating_point<N>
3             or std::integral<N>;
4 template <class N>
5 concept NotNumber = not Number<N>;
6 void proc(Number auto&& x) {
7     std::cout << "Called proc for numbers";
8 }
9 void proc(NotNumber auto&& x) {
10    std::cout << "Called proc for non-numbers";
11 }
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18 }
```

---

- Constraints on template parameters are not just “documentation” or decoration.
- The compiler can choose between different versions of a function based on concepts

# OVERLOADING BASED ON CONCEPTS

---

```
1 template <class N>
2 concept Number = std::floating_point<N>
3             or std::integral<N>;
4 template <class N>
5 concept NotNumber = not Number<N>;
6 void proc(Number auto&& x) {
7     std::cout << "Called proc for numbers";
8 }
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10    std::cout << "Called proc for non-numbers";
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13     proc(-1);
14     proc(88UL);
15     proc("0118 999 88199 9119725      3");
16     proc(3.141);
17     proc("eighty"s);
18 }
```

---

- Constraints on template parameters are not just “documentation” or decoration.
- The compiler can choose between different versions of a function based on concepts
- The version of a function chosen depends on *properties* of the input types, rather than their identities. “It’s not who you are underneath, it’s what you (can) do that defines you.”

# OVERLOADING BASED ON CONCEPTS

---

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1 template <class N>
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18 }
```

---

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- During overload resolution, in case multiple matches are found, the most constrained overload is chosen.

# OVERLOADING BASED ON CONCEPTS

---

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---

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- Not based on any inheritance relationships

# OVERLOADING BASED ON CONCEPTS

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---

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- During overload resolution, in case multiple matches are found, the most constrained overload is chosen.
- Not based on any inheritance relationships
- Not a “quack like a duck, or bust” approach either.

# OVERLOADING BASED ON CONCEPTS

---

```
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```

---

- Constraints on template parameters are not just “documentation” or decoration.
- The compiler can choose between different versions of a function based on concepts
- The version of a function chosen depends on *properties* of the input types, rather than their identities. “It’s not who you are underneath, it’s what you (can) do that defines you.”
- During overload resolution, in case multiple matches are found, the most constrained overload is chosen.
- Not based on any inheritance relationships
- Not a “quack like a duck, or bust” approach either.
- Entirely compile time mechanism

## Exercise 3.8:

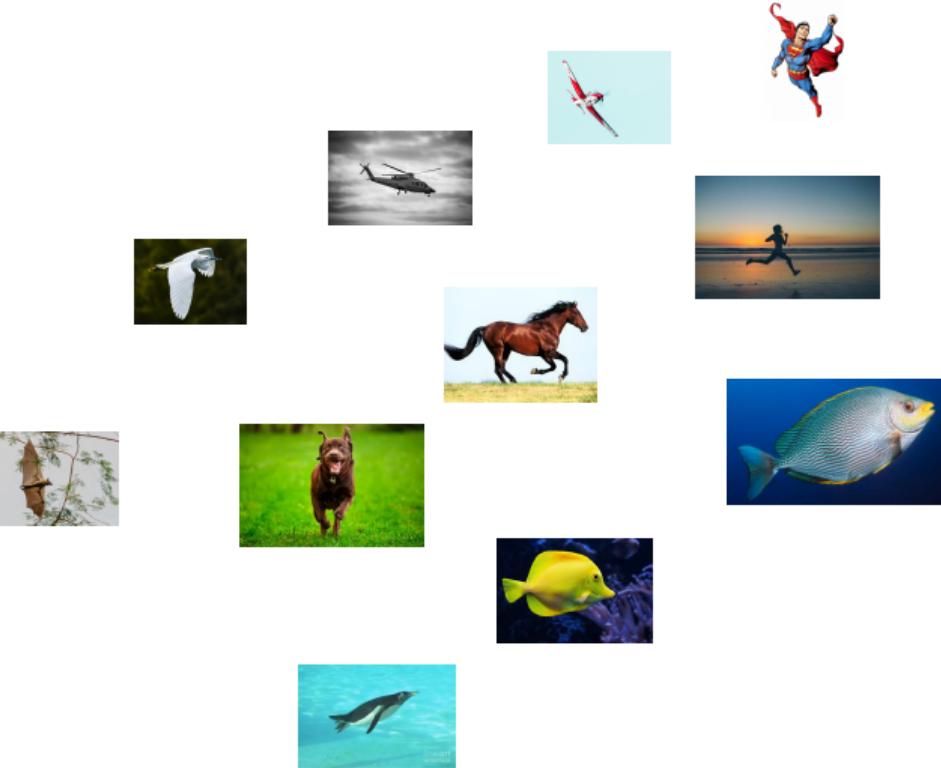
Check how you can use concepts to implement alternative versions of a function based on properties of the input parameters! The program `examples/overload_w_concepts.cc` contains the code just shown. Can you add another overload that is picked if the input type is an array? This means, if `X` is the input parameter, `X[i]` is syntactically valid for unsigned integer `i`. The array version should be picked up if the input is a `vector`, `array`, etc., but also `string`. How would you prevent the `string` and C-style strings picking the array version?

# PREDEFINED USEFUL CONCEPTS

Many concepts useful in building our own concepts are available in the standard library header `<concepts>`.

- `same_as`
- `convertible_to`
- `signed_ingroup`, `unsigned_integral`
- `floating_point`
- `assignable_from`
- `swappable`, `swappable_with`
- `derived_from`
- `move_constructible`,  
`copy_constructible`
- `invocable`
- `predicate`
- `relation`

# CONCEPTS: SUMMARY



f(those who can fly)

f(runners)

f(swimmers)

# Chapter 4

# SOLID principles

# DESIGN GOALS

- Correctness
- Readability
- Extendability
- Speed
- Adaptability

A large scale software project is better off being built out of components which are resilient to unforeseen changes.

# DEPENDENCIES

- Impede modifications
- Hamper testing
- Increase rebuild times
- Good design helps us control dependencies.
- Variation points
- Flexible adaptable software

**Guideline:** Keep dependencies among software components to a minimum.

# ENCAPSULATION

- Member functions abstracting properties
- Resilient to internal data reorganisation
- More flexible design

---

```
1 class complex_number {  
2 public:  
3     double real, imag;  
4     double modulus();  
5 };
```

---

---

```
1 class complex_number {  
2 public:  
3     auto real() const -> double;  
4     auto imag() const -> double;  
5     void real(double x);  
6     void imag(double x);  
7     auto modulus() const -> double;  
8 };
```

---

# ENCAPSULATION

- Scott Meyer: degree of encapsulation is gauged by the number of things which break if the internal design changes
- Less member functions : better!
- If a function can be implemented as a non-friend, non-member function, it should be.

---

```
1 // Class definition: bare essentials
2 namespace ns {
3     class Example {
4         public:
5             auto property1() const -> double;
6             auto property2() const -> double;
7     };
8 }
```

---

```
1 // Use case 1 header
2 namespace ns {
3     auto calc(Example & ex) {
4         //ex.property1() + ...
5         //ex.property2();
6         return haha;
7     }
8 }
```

---

# THE SOLID PRINCIPLES

- Single responsibility principle
- Open-closed principle
- Liskov's substitution principle
- Interface segregation principle
- Dependency inversion principle

# SRP: THE SINGLE RESPONSIBILITY PRINCIPLE

Every class should have a single responsibility and that responsibility should be entirely encapsulated by that class.

- However tempting it might seem, avoid adding member functions **not related to the core idea** of the class
- Related principle: Don't repeat yourself. Avoids opportunity for bugs and reduces maintenance overhead.

---

```
1 class Rectangle {
2     public:
3         auto area() const -> double;
4         auto width() const -> double;
5         auto height() const -> double;
6         void width(double x);
7         void height(double x);
8         void draw() const;
9     };
```

---

# OCP: THE OPEN CLOSED PRINCIPLE

A software component should be open for extension, but closed for modifications.

- Closed: can be used by other components. Well defined stable interface.
- Open: Available for extension. Add new data fields, new functionality.
- Inheritance (possibly from abstract base classes)

# LSP: LISKOV'S SUBSTITUTION PRINCIPLE

"If, for each object  $o_1$  of type S, there is an object  $o_2$  of type T, such that for all programs P defined in terms of T, the behaviour of P is unchanged when  $o_1$  is substituted for  $o_2$ , then S is a subtype of T."

– Barbara Liskov

- Subtypes must be able to substitute the base type
- Deriving type fully reflects the behaviour of the base class
- True "is a" relationship
- **Guideline:** Don't inherit and then restrict the derived class so that it loses some behaviour expected from the base class

# ISP: THE INTERFACE SEGREGATION PRINCIPLE

Clients should not be forced to depend on methods they do not use.

- See under "encapsulation" above
- Avoid "fat" classes. When one client forces a change, every other client is affected, even if they are not using the same part of the fat class.
- Think how the functionality available through the namespace `std` is segregated.

# DIP: THE DEPENDENCY INVERSION PRINCIPLE

- 1 High-level modules should not depend on low level modules. Both should depend on abstractions.
  - 2 Abstractions should not depend on details. Details should depend on abstractions.
- 
- High level components own the interface they depend on.
  - They specify their requirements.
  - If low level components implement that interface, they can be used with the high level client interface.
  - Cut the dependency chain
  - Adaptor layers

# SUMMARY: SOLID PRINCIPLES

- Avoiding tight coupling between different components may require extra work at first, but wins out in the life time of a project.
- Assign responsibilities carefully.
- SOLID principles are known to help develop and maintain flexible software.

# Chapter 5

# Lambda functions

# FUNCTION LIKE ENTITIES

- In C++, there are a few different constructs which can be used in a context requiring a “function”
  - Functions in all varieties constitute one category ( `inline` or not, `constexpr` or not, `virtual` or not ...)
  - Classes may overload the function call operator `operator()` to give us another type of `callable` object
  - Lambda functions are similar, language provided entities
- 

```
1  class Wave {  
2      double A, ome, pha;  
3  public:  
4      auto operator()(double t) -> double  
5      {  
6          return A * sin(ome * t + pha);  
7      }  
8  };  
9  void elsewhere()  
10 {  
11     Wave W{1.0, 0.15, 0.9};  
12     for (auto i = 0; i < 100; ++i) {  
13         std::cout << i << W(i) << "\n";  
14     }  
15 }
```

---

# LAMBDA FUNCTIONS

- Locally defined callable entities
- Uses
  - Effective use of STL
  - Initialisation of const
  - Concurrency
  - New loop styles
- Like a function object defined on the spot
- Fine grained control over the visibility of the variables in the surrounding scope

---

```
1 sort(begin(v), end(v), [](auto x, auto y) {  
2     return x > y;  
3 });  
4  
5 const auto inp_file = []{  
6     string resourcefl;  
7     cout << "resource file : "  
8     cin >> resourcefl;  
9     return resourcefl;  
10 }();  
11 tbb::parallel_for(0, 1000000, [](int i){  
12     // process element i  
13 });
```

---

# LAMBDA FUNCTIONS

## Function

```
auto sqr(double x) -> double
{
    return x * x;
}
```

## Lambda expression

```
auto lsqr = [] (double x) -> double
{
    return x * x;
};
```

- Normal C++ functions can not be defined in block scope
- Lambda expressions are expressions, which when evaluated yield callable entities. Like  $2^9$  is an expression, which when evaluated yields 512.
- Such callable entities can be created in global as well as block scope

# LAMBDA FUNCTIONS

## Function

```
auto sqr(double x) -> double
{
    return x * x;
}
```

## Lambda expression

```
auto lsqr = [] (double x) -> double
{
    return x * x;
};
```

- The lambda expression contains information which is used to make the callable entity: such as, expected **input**, **output** and the **body**("recipe").
- Unlike normal functions, which have **names**, these callable entities themselves are **nameless**, but **named variables** can be constructed out of them, if desired. Those named variables can then be used like functions.

# LAMBDA FUNCTIONS

## Function

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auto sqr(double x) -> double
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```
std::vector X{0.1, 0.2, 0.3, 0.4};
auto sqsum = 0.;
for (auto i = 0UL; i < X.size(); ++i) {
    sqsum += sqr(X[i]);
}
```

# LAMBDA FUNCTIONS

## Function

```
auto sqr(double x) -> double
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    return x * x;
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```
std::vector X{0.1, 0.2, 0.3, 0.4};
auto sqsum = 0.;
for (auto i = 0UL; i < X.size(); ++i) {
    sqsum += lsqr(X[i]);
}
```

# LAMBDA FUNCTIONS

```
template <Callable F>
auto aggregate(const std::vector<double>& inp, F f) -> double
{
    auto s{0.};
    for (auto i = 0UL; i < inp.size(); ++i) { s += f(inp[i]); }
    return s;
}
```

- Typical use: arguments to higher order functions. Function parameter that specifies an operation to be performed on a value or (as in this case) a range of values

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auto aggregate(const std::vector<double>& inp, F f) -> double
{
    auto s{0.};
    for (auto i = 0UL; i < X.size(); ++i) { s += f(X[i]); }
    return s;
}
// ...
std::vector X{0.1, 0.2, 0.3, 0.4};
auto sqsum = aggregate(X, sqr);
```

- Typical use: arguments to higher order functions. Function parameter that specifies an operation to be performed on a value or (as in this case) a range of values
- Named callable entities can be used when available.

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{
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    return s;
}
// ...
std::vector X{0.1, 0.2, 0.3, 0.4};
auto sqsum = aggregate(X, lsqr);
```

- Typical use: arguments to higher order functions. Function parameter that specifies an operation to be performed on a value or (as in this case) a range of values
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# LAMBDA FUNCTIONS

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auto aggregate(const std::vector<double>& inp, F f) -> double
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    return s;
}
// ...
std::vector X{0.1, 0.2, 0.3, 0.4};
auto sqsum = aggregate(X, [](double x) -> double { return x * x; });
```

- Typical use: arguments to higher order functions. Function parameter that specifies an operation to be performed on a value or (as in this case) a range of values
- Named callable entities can be used when available.
- Often it is more convenient to pass a lambda expression, and let the higher order function create the callable entity it needs!

# LAMBDA FUNCTIONS WITH ALGORITHMS

`std::for_each` is a higher order function, similar to this:

```
template <class InputIterator, class UnaryFunction>
void for_each(InputIterator start, InputIterator end, UnaryFunction f)
{
    for (auto it = start; it != end; ++it) f(*it);
}
```

# LAMBDA FUNCTIONS WITH ALGORITHMS

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template <class InputIterator, class UnaryFunction>
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What do the following lines do ?

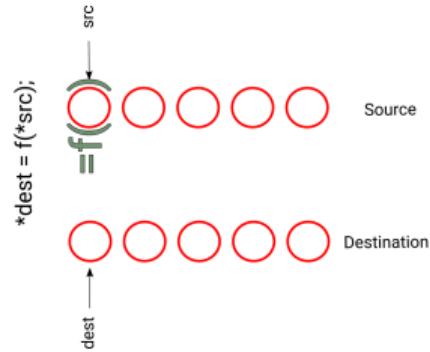
---

```
1 std::vector X{9, 8, 7, 6, 5, 4, 3, 2, 1, 0};
2 for_each(X.begin(), X.end(), [](int& elem){ elem = elem * elem; });
3 for_each(X.begin(), X.end(), [](int& elem){ elem -= 100; });
4 for_each(X.begin(), X.end(), [](int elem){ std::cout << elem << "\n"; });
```

---

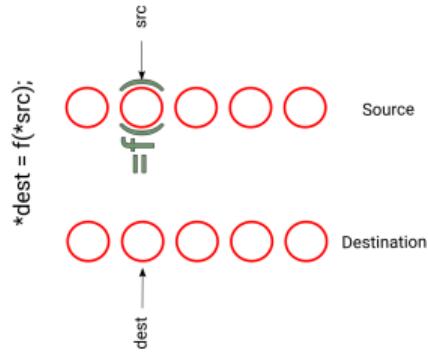
# LAMBDA FUNCTIONS WITH ALGORITHMS

`std::transform` is a higher order function, slightly more general than `std::for_each`. It has a few overloads. One of them is similar to this:



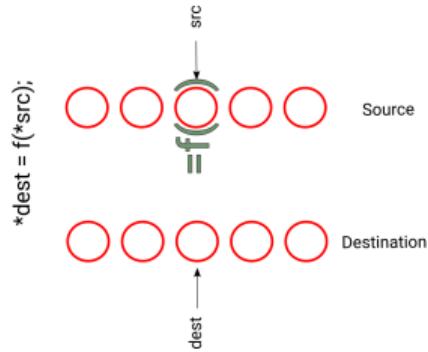
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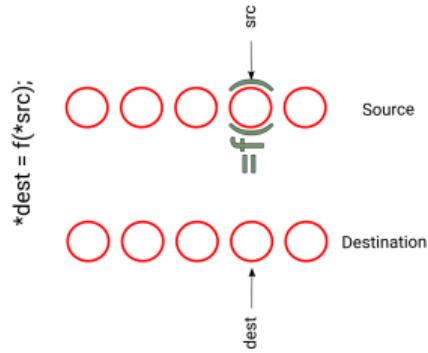
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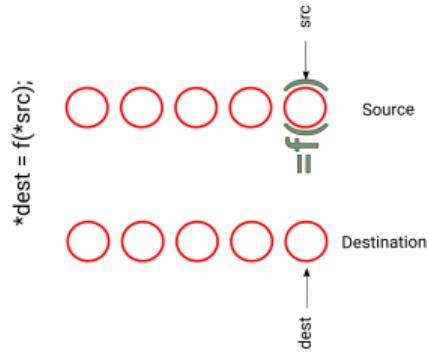
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```
template <class InputIt, class OutputIt,
          class UnaryFunction>
void transform(InputIt start, InputIt end,
               OutputIt out,
               UnaryFunction f)
{
    for (; start != end; ++start, ++out)
        *out = f(*start);
}
```

# LAMBDA FUNCTIONS WITH ALGORITHMS

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for general than `std::for_each`. It has a few overloads. One of them is similar to this:

What do the following lines do ?

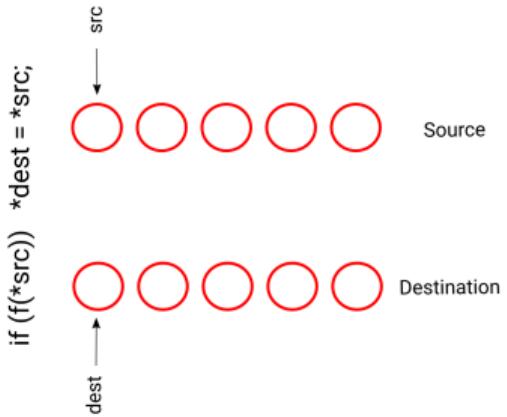
---

```
1 std::vector X{9, 8, 7, 6, 5, 4, 3, 2, 1, 0};
2 std::vector<int> Y;
3 transform(X.begin(), X.end(), std::back_inserter(Y),
4           [](int elem) { return elem * elem; });
```

---

# LAMBDA FUNCTIONS WITH ALGORITHMS

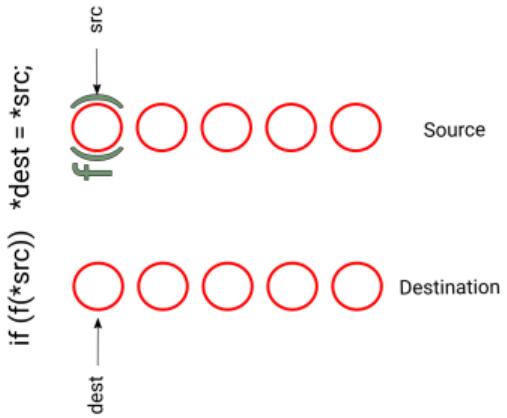
`std::copy_if` Conditionally copies elements from a source sequence to a destination sequence:



```
if (f(*src)) *dest = *src;
```

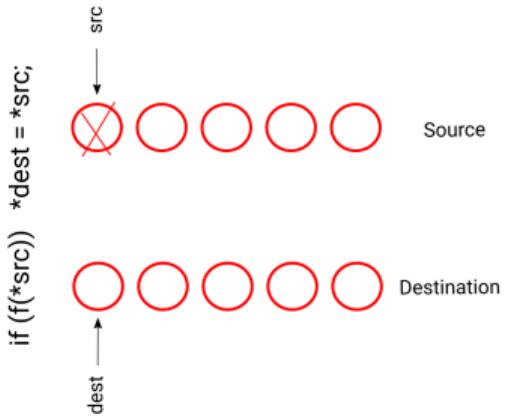
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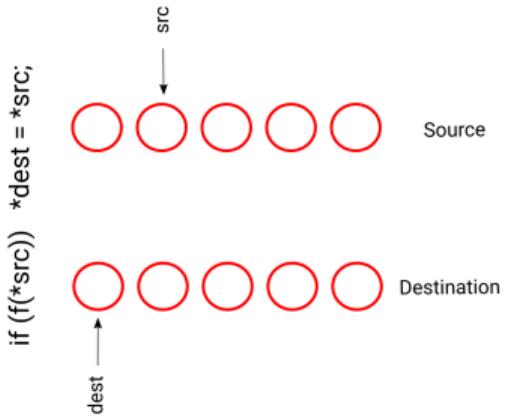
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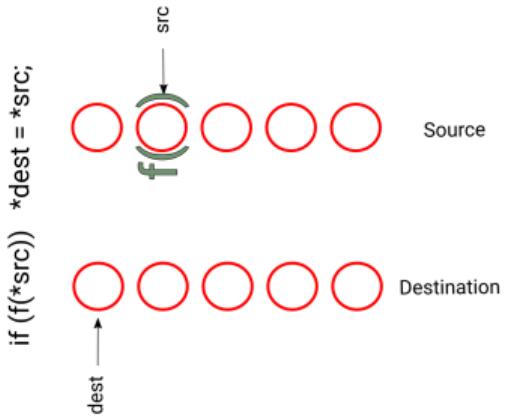
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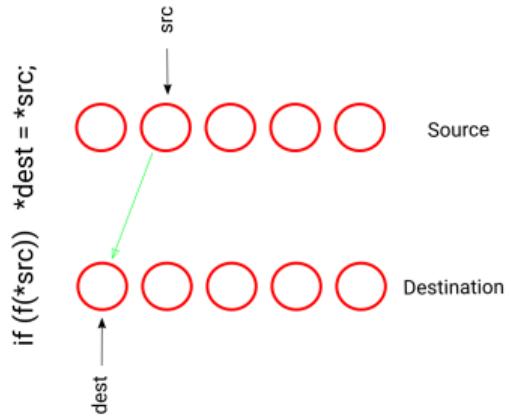
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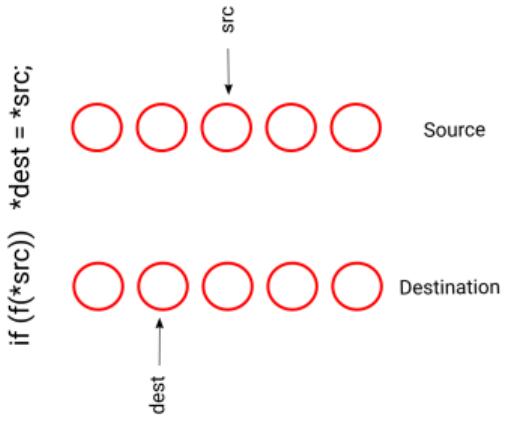
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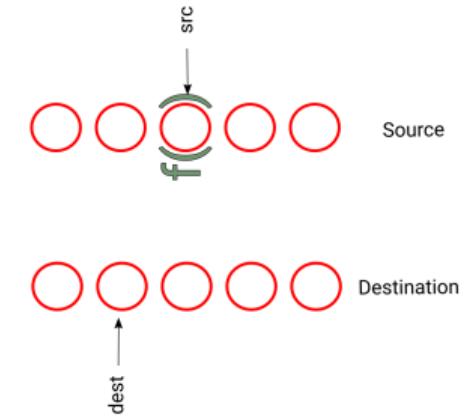
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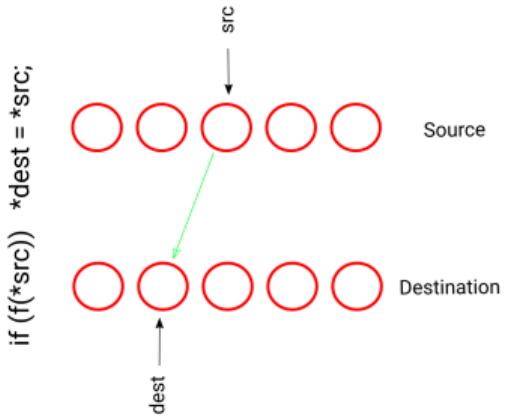
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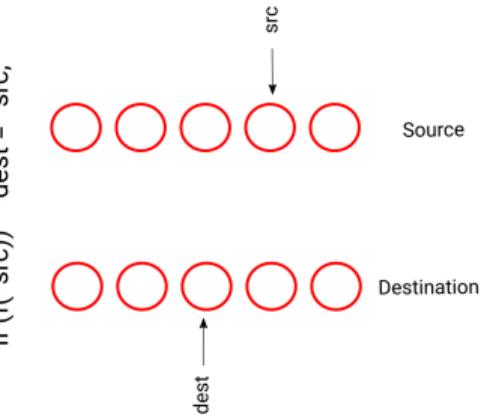
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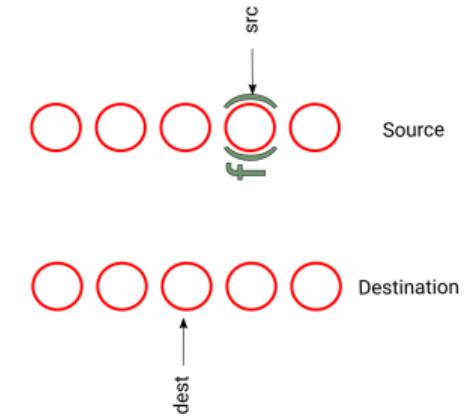
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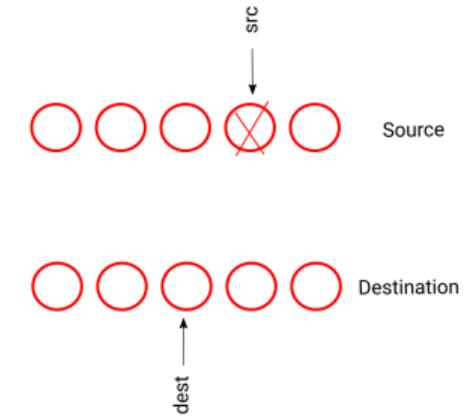
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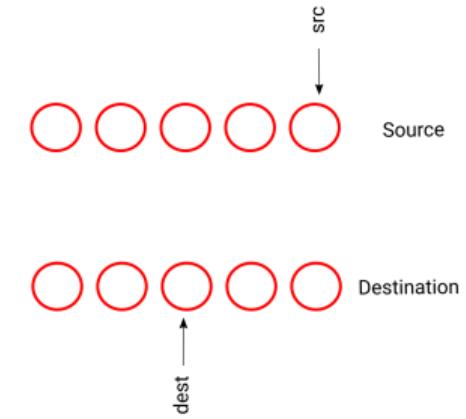
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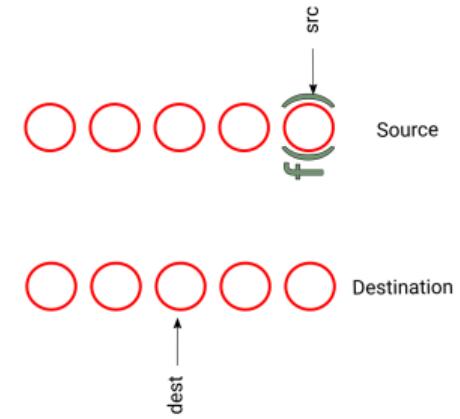
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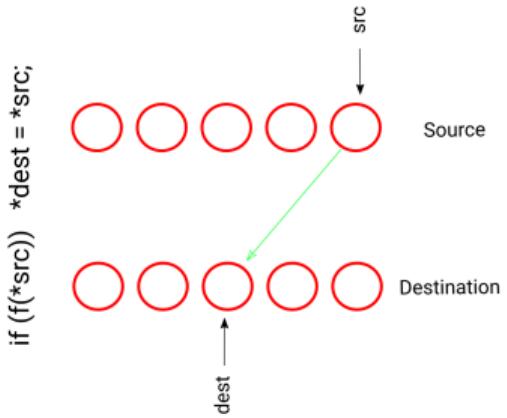
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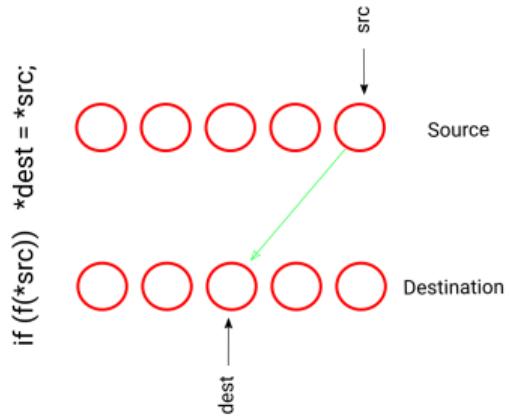


# LAMBDA FUNCTIONS WITH ALGORITHMS

`std::copy_if` Conditionally copies elements from a source sequence to a destination sequence:

What do the following lines do ?

```
1 std::vector X{9, 8, 7, 6, 5, 4, 3, 2, 1, 0};  
2 std::vector<int> Y;  
3 copy_if(X.begin(), X.end(), std::back_inserter(Y),  
4         [](int elem) { return elem % 3 == 0; });
```



## Exercise 5.1:

Use the notebook `lambda_practice_0.ipynb` to quickly practice writing a few small lambdas and using them with a few standard library algorithms.

# CAPTURE BRACKETS

- Suppose we want to transfer some elements from one vector to another

```
std::vector<int> v{1, -1, 9, 3, 4, -7, 3, -2}, w;
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```
copy_if(v.begin(), v.end(), back_inserter(w), [](int i){ return i>0; });
```

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std::vector<int> v{1, -1, 9, 3, 4, -7, 3, -2}, w;
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copy_if(v.begin(), v.end(), back_inserter(w), [](int i){ return i>0; });
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- Copy to `w` all elements larger than a user specified value

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copy_if(v.begin(), v.end(), back_inserter(w), [](int i){ return i>0; });
```

- Copy to `w` all elements larger than a user specified value

- This does not work

```
std::cin >> lim;
copy_if(v.begin(), v.end(), back_inserter(w), [](int i){ return i > lim; });
// Lambda function has its own scope, and lim is not visible
```

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std::cin >> lim;
copy_if(v.begin(), v.end(), back_inserter(w), [](int i){ return i > lim; });
// Lambda function has its own scope, and lim is not visible
```

- A way to make the lambda selectively aware of chosen variables in its context:

```
std::cin >> lim;
copy_if(v.begin(), v.end(), back_inserter(w),
        [lim](int i){ return i > lim; });
// Lambda function "captures" lim, and lim is now visible inside the lambda
```

# LAMBDA EXPRESSIONS: SYNTAX

```
[capture] <templatepars> (arguments) lambda-specifiers { body }
```

- Variables in the body of a lambda function are either passed as function arguments or "captured", or are global variables
- Function arguments field is optional if empty. e.g. `[&cc] { return cc++; }`
- The *lambda-specifiers* field can contain a variety of things: Keywords `mutable`, `constexpr` or `consteval`, exception specifiers, attributes, the return type, and any `requires` clauses. All of these are optional.
- The return type is optional if there is one return statement. e.g.  
`[a,b,c] (int i) mutable { return a*i*i + b*i + c; }`
- The optional keyword `mutable` can be used to create lambdas with state
- `auto` can be used to declare the formal input parameters of the lambda (since C++14)
- Template parameters can be optionally provided where shown (since C++20)

# EXPLICIT TEMPLATE PARAMETERS FOR LAMBDA FUNCTIONS

---

```
1 // examples/saxpy_2.cc
2 // includes ...
3 auto main() -> int {
4     const std::vector inpl { 1., 2., 3., 4., 5. };
5     const std::vector inp2 { 9., 8., 7., 6., 5. };
6     std::vector outp(inpl.size(), 0.);
7
8     auto saxpy = [] <class T, class T_in, class T_out>
9         (T a, const T_in& x, const T_in& y, T_out& z) {
10         std::transform(x.begin(), x.end(), y.begin(), z.begin(),
11                         [a](T X, T Y){ return a * X + Y; });
12     };
13
14     std::ostream_iterator<double> cout { std::cout, "\n" };
15     saxpy(10., inpl, inp2, outp);
16     copy(outp.begin(), outp.end(), cout);
17 }
```

---

For normal function templates, we could easily express relationships among the types of different parameters.  
With C++20, we can do that for generic lambdas as well

# LAMBDA CAPTURE SYNTAX I

```
[capture] <templatepars> (arguments) lambda-specifiers { body }
```

- `[ ](int a, int b) -> bool { return a > b; }` : Capture nothing. Work only with the arguments passed, or global objects.
- `[=](int a) -> bool {return a > somevar; }` : Capture everything needed by value.
- `[&](int a) {somevar += a; }` : Capture everything needed by reference.
- `[=, &somevar](int a) { somevar += max(a,othervar); }` : `somevar` by reference, but everything else as value.
- `[a, &b] { f(a,b); }` : `a` by value, `b` by reference.
- `[a=std::move(b)] { f(a,b); }` : Init capture. Create a variable `a` with the initializer given in the capture brackets. It is as if there were an implicit `auto` before the `a`.

## Exercise 5.2:

The program `lambda_captures.cc` (alternatively, notebook `lambda_practice_1.ipynb`) declares a variable of the `Vbose` type (with all constructors, assignment operators etc. written to print messages), and then defines a lambda function. By changing the capture type, and the changing between using and not using the `Vbose` value inside the lambda function, try to understand, from the output, the circumstances under which the captured variables are copied into the lambda. In the cases where you see a copy, where does the copy take place ? At the point of declaration of the lambda or at the point of use ?

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```
auto L = [p](int i){ std::cout << i*3 + p; };
L(3); // result : prints out 14
auto M = [p](int i){ p = i*3; }; // syntax error! p is read-only!
```

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- We can capture `p` by value (make a copy), but use the `mutable` keyword, to let the lambda function change its local copy of `p`

```
auto M = [p](int i) mutable { return p += i*3; };
std::cout << M(1) << " "; std::cout << M(2) << " "; std::cout << p << "\n";
// result : prints out "8 14 5"
```

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std::cout << M(1) << " "; std::cout << M(2) << " "; std::cout << p << "\n";
// result : prints out "8 14 5"
```

- We can capture `p` by reference and modify it

```
auto M = [&p](int i){ return p += i*3; };
std::cout << M(1) << " "; std::cout << M(2) << " "; std::cout << p << "\n";
// result : prints out "8 14 14"
```

# NO DEFAULT CAPTURE!

[ ]	Capture nothing
[ = ]	Capture used by value (copy)
[ =, &x ]	Capture used by value, except x by reference
[ & ]	Capture used by reference
[ &, x ]	Capture used by reference, except x by value
[a=init]	Init capture

- A lambda with empty capture brackets is like a local function, and can be assigned to a regular function pointer. It is not aware of identifiers defined previously in its context
- When you use a (non-global) variable defined outside the lambda in the lambda, you have to capture it

# STATEFUL LAMBDAS

- Mutable lambdas have "state", and remember any changes to the values captured by value
  - Combined with "init capture", gives us interesting generator functions
- 

```
1  vector<int> v, w;
2  generate_n(back_inserter(v), 100, [i=0]() mutable {
3      ++i;
4      return i*i;
5  });
6  // v = [1, 4, 9, 16 ... ]
7  generate_n(back_inserter(w), 50, [i=0, j=1]() mutable {
8      i = std::exchange(j, j+i); // exchange(a,b) sets a to b and returns the old value of a
9      return i;
10 });
11 // See the videos on Fibonacci sequence on the
12 // YouTube channel "C++ Weekly" by Jason Turner
13 // w = [1, 1, 2, 3, 5, 8, 11 ...]
```

## Exercise 5.3:

The program `mutable_lambda.cc` shows the use of mutable lambdas for sequence initialisation.