

UNIVERSITY OF TORONTO
Faculty of Applied Science and Engineering

Term Test III

First Year — Program 5

MAT185H1S — Linear Algebra

Examiners: A D Rennet & G M T D'Eleuterio

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Student Name:

<i>Fair Copy</i>	
Last Name	First Names

Student Number:

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Tutorial Section: TUT

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Instructions:

1. Attempt *all* questions.
2. The value of each question is indicated at the end of the space provided for its solution; a summary is given in the table opposite.
3. Write the final answers *only* in the boxed space provided for each question.
4. No aid is permitted.
5. The duration of this test is 90 minutes.
6. There are 10 pages and 5 questions in this test paper.

For Markers Only		
Question	Value	Mark
A		
1	10	
B		
2	10	
C		
3	10	
4	10	
5	10	
Total	50	

A. Definitions and Statements

Fill in the blanks.

1(a). The *coordinates* of $v \in \mathcal{V}$ in a basis $B = \{b_1 \cdots b_n\}$ are defined as

the coefficients $\alpha_i, i = 1 \cdots n$, such that $v = \alpha_1 b_1 + \cdots + \alpha_n b_n$.

/2

1(b). The (i, j) -minor of $A \in {}^n\mathbb{R}^n$ is defined as

$M_{ij} \in {}^{n-1}\mathbb{R}^{n-1}$ obtained from A by eliminating the i th row and j th column.

/2

1(c). The (i, j) -cofactor of $A \in {}^n\mathbb{R}^n$ is defined as

$c_{ij} = (-1)^{i+j} \det M_{ij}$, where M_{ij} is the (i, j) -minor of A .

/2

1(d). The *Laplace expansion* of the determinant of $A \in {}^n\mathbb{R}^n$ is defined as

$$\det A = \sum_{i=1}^n a_{ij} c_{ij}$$

where a_{ij} is the (i, j) entry in A and c_{ij} is the (i, j) -cofactor of A .

/2

1(e). State the *Maclaurin-Cramer rule*.

The solution to $Ax = b$, where $A \in {}^n\mathbb{R}^n$ is invertible, can be expressed as

$$x_i = \det A_i / \det A$$

where x_i is the i th variable in $x \in {}^n\mathbb{R}$ and $A_i \in {}^n\mathbb{R}^n$ is obtained from A by replacing the i th column with b .

/2

B. True or False

Determine if the following statements are true or false and indicate by “T” (for true) and “F” (for false) in the box beside the question. The value of each question is 2 marks.

2(a). The matrix

$$\begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

F

cannot be a transformation (transition) matrix.

2(b). Let $v_1 \cdots v_m \in \mathcal{V}$, a vector space of dimension n , with coordinates $\mathbf{v}_1 \cdots \mathbf{v}_m$ in some basis. Then $\{v_1 \cdots v_m\}$ is linearly dependent in \mathcal{V} if and only if $\{\mathbf{v}_1 \cdots \mathbf{v}_m\}$ is linearly dependent in ${}^n\mathbb{R}$.

T

2(c). The determinant of

$$\begin{bmatrix} 1 & 2 & 1 & 0 & 0 \\ 2 & 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 1 & 2 \\ 0 & 1 & 2 & 0 & 0 \\ 0 & 2 & 0 & 2 & 1 \end{bmatrix}$$

F

is 9.

2(d). If $\mathbf{A}^T = -\mathbf{A} \neq \mathbf{O}$ then $\det \mathbf{A} = -1$.

F

2(e). For any $\mathbf{A} \in {}^n\mathbb{R}^n$, $\text{adj}(\lambda\mathbf{A}) = \lambda^{n-1}\text{adj} \mathbf{A}$ for any $\lambda \in \mathbb{R}$.

T

C. Problems

3. The first three *Legendre polynomials* are $L = \{1, x, \frac{1}{2}(3x^2 - 1)\}$ and the first three *Gegenbauer polynomials* are $G = \{1, 2x, 4x^2 - 1\}$. Note that L and G are bases for \mathbb{P}_2 .
- (a) Determine the transformation (transition) matrix from G to L .
- (b) If $p(x) = 2g_1(x) + g_2(x) - 3g_3(x)$, where g_1, g_2, g_3 are the basis elements of G as given above, determine the coordinates of p in L .

3(a). Determine the transformation (transition) matrix from G to L .

We write G in terms of L :

$$\begin{aligned} 1 &= 1 \cdot 1 + 0 \cdot x + 0 \cdot \frac{1}{2}(3x^2 - 1) \\ 2x &= 0 \cdot 1 + 2 \cdot x + 0 \cdot \frac{1}{2}(3x^2 - 1) \\ 4x^2 - 1 &= \frac{1}{3} \cdot 1 + 0 \cdot x + \frac{8}{3} \cdot \frac{1}{2}(3x^2 - 1) \end{aligned}$$

Thus, the transformation matrix from G to L is

$$\mathbf{P} = \begin{bmatrix} 1 & 0 & \frac{1}{3} \\ 0 & 2 & 0 \\ 0 & 0 & \frac{8}{3} \end{bmatrix}$$

3(b). If $p(x) = 2g_1(x) + g_2(x) - 3g_3(x)$, where g_1, g_2, g_3 are the basis elements of G as given above, determine the coordinates of p in L .

The coordinates for $p(x)$ using the basis G are

$$\mathbf{v}_G = \begin{bmatrix} 2 \\ 1 \\ -3 \end{bmatrix}$$

Therefore the coordinates in L are

$$\mathbf{v}_L = \mathbf{P}\mathbf{v}_G = \begin{bmatrix} 1 \\ 2 \\ -8 \end{bmatrix}$$

4. Define $\Delta_{\mathbf{B}}(\mathbf{A}) = \det_n \mathbf{B}\mathbf{A}\mathbf{B}^T$ for $\mathbf{A} \in {}^m\mathbb{R}^m$ and $\mathbf{B} \in {}^n\mathbb{R}^m$.

- (a) Let $m < n$. Prove that $\Delta_{\mathbf{B}}(\mathbf{A}) = 0$ for all \mathbf{A}, \mathbf{B} .
- (b) Let $m = n$. Prove that $\Delta_{\mathbf{B}}$ is a determinant function for all \mathbf{B} .
- (c) Let $m > n$. Disprove that, for all \mathbf{B} , $\Delta_{\mathbf{B}}$ is a determinant function.

4(a). Let $m < n$. Prove that $\Delta_{\mathbf{B}}(\mathbf{A}) = 0$ for all \mathbf{A}, \mathbf{B} .

If $m < n$ then

$$\mathbf{B}^T \mathbf{x} = \mathbf{0}$$

has a nontrivial solution. (Formally, this is given by the fact that $\dim \text{null } \mathbf{B}^T = n - \text{rank } \mathbf{B}$ and $\text{rank } \mathbf{B} \leq m$ making $\dim \text{null } \mathbf{B}^T > 0$.)

Hence,

$$\mathbf{B}\mathbf{A}\mathbf{B}^T \mathbf{x} = \mathbf{0}$$

has a nontrivial solution which implies that $\mathbf{B}^T \mathbf{A} \mathbf{B}^T$ is singular. (Formally, Theorem III, Chapter 7.)

Therefore, $\det \mathbf{B}^T \mathbf{A} \mathbf{B}^T = 0$ regardless of \mathbf{A} or \mathbf{B} and so $\Delta_{\mathbf{B}} = 0$.

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4(b). Let $m = n$. Prove that $\Delta_{\mathbf{B}}$ is a determinant function for all \mathbf{B} .

If $m = n$, \mathbf{A} and \mathbf{B} are square. We can thus use the Cauchy-Binet product rule for determinants.

Now, we check that properties DI and DII hold:

DI. Note that

$$\Delta_{\mathbf{B}}[\mathbf{E}(1; i, j)\mathbf{A}] = \det \mathbf{B} \det \mathbf{E}(1; i, j) \mathbf{A} \mathbf{B}^T = \det \mathbf{B} \det \mathbf{E}(1; i, j) \det \mathbf{A} \det \mathbf{B}^T$$

but $\det \mathbf{E}(1; i, j) \mathbf{A} = \det \mathbf{A}$. Hence,

$$\Delta_{\mathbf{B}}[\mathbf{E}(1; i, j)\mathbf{A}] = \det \mathbf{B} \det \mathbf{A} \det \mathbf{B}^T = \det \mathbf{B} \mathbf{A} \mathbf{B}^T = \Delta_{\mathbf{B}}(\mathbf{A})$$

DII. Similarly,

$$\Delta_{\mathbf{B}}[\mathbf{E}(\lambda; i)\mathbf{A}] = \det \mathbf{B} \det \mathbf{E}(\lambda; i) \mathbf{A} \mathbf{B}^T = \det \mathbf{B} \det \mathbf{E}(\lambda; i) \det \mathbf{A} \det \mathbf{B}^T$$

but $\det \mathbf{E}(\lambda; i) \mathbf{A} = \lambda \det \mathbf{A}$. Hence,

$$\Delta_{\mathbf{B}}[\mathbf{E}(\lambda; i)\mathbf{A}] = \lambda \det \mathbf{B} \det \mathbf{A} \det \mathbf{B}^T = \lambda \det \mathbf{B} \det \mathbf{A} \det \mathbf{B}^T = \lambda \Delta_{\mathbf{B}}(\mathbf{A})$$

As DI and DII are satisfied, $\Delta_{\mathbf{B}}$ is a determinant function when $m = n$.

4(c). Let $m > n$. Disprove that, for all \mathbf{B} , $\Delta_{\mathbf{B}}$ is a determinant function.

*To disprove the result, all we have to do is find a counterexample.
Consider*

$$\mathbf{A} = \mathbf{1} \in {}^2\mathbb{R}^2, \quad \mathbf{B} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

and note that

$$\Delta_{\mathbf{B}}[\mathbf{E}(\lambda; 2)\mathbf{A}] = \det \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & \lambda \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = 1$$

yet $\lambda\Delta_{\mathbf{B}}(\mathbf{A}) = \lambda$. Clearly, $\Delta_{\mathbf{B}}[\mathbf{E}(\lambda; 2)\mathbf{A}] \neq \lambda\Delta_{\mathbf{B}}(\mathbf{A})$ if $\lambda \neq 1$. Hence, $\Delta_{\mathbf{B}}$ fails property DII and therefore cannot be a determinant function.

5. (a) If \mathbf{A} is singular, show that $\text{adj } \mathbf{A}$ is also singular.
 (b) Show that $(\det \mathbf{A})\text{adj adj } \mathbf{A} = (\det \text{adj } \mathbf{A})\mathbf{A}$.

5(a). If \mathbf{A} is singular, show that $\text{adj } \mathbf{A}$ is also singular.

If $\mathbf{A} = \mathbf{O}$, clearly from the definition of the adjoint, $\text{adj } \mathbf{A} = \mathbf{O}$ and hence is singular.

If $\mathbf{A} \neq \mathbf{O}$ but is nonetheless singular, consider that

$$(\text{adj } \mathbf{A})\mathbf{A} = \mathbf{O}$$

because $\det \mathbf{A} = 0$. Furthermore,

$$(\text{adj } \mathbf{A})\mathbf{A}\mathbf{x} = \mathbf{0}$$

where for some $\mathbf{x} \in {}^n\mathbb{R}$, $\mathbf{A}\mathbf{x} \neq \mathbf{0}$. (Note $\text{col } \mathbf{A}$ must contain nonzero vectors.) Therefore, setting $\mathbf{z} = \mathbf{A}\mathbf{x}$,

$$(\text{adj } \mathbf{A})\mathbf{z} = \mathbf{0}$$

has a nontrivial solution which means that $\text{adj } \mathbf{A}$ cannot be invertible.

5(b). Show that $(\det \mathbf{A}) \operatorname{adj} \operatorname{adj} \mathbf{A} = (\det \operatorname{adj} \mathbf{A}) \mathbf{A}$.

From Theorem VIII, Chapter 9 (interpreting \mathbf{A} as $\operatorname{adj} \mathbf{A}$),

$$(\operatorname{adj} \mathbf{A}) \operatorname{adj} \operatorname{adj} \mathbf{A} = (\det \operatorname{adj} \mathbf{A}) \mathbf{1}$$

Premultiply by \mathbf{A} :

$$\mathbf{A}(\operatorname{adj} \mathbf{A}) \operatorname{adj} \operatorname{adj} \mathbf{A} = (\det \operatorname{adj} \mathbf{A}) \mathbf{A}$$

But $\mathbf{A} \operatorname{adj} \mathbf{A} = (\det \mathbf{A}) \mathbf{1}$, which upon substitution gives the desired result.