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NAME:	S((n)s	Fall 2021 Midterm #1
STUDENT NUM	IBER:	
TUTORIAL GR	OUP:	

Time: 60 minutes

This is a closed-book exam worth a total of 60 points. Please answer all questions.

## ONLY THE FOLLOWING ITEMS ARE ALLOWED ON YOUR DESK DURING THE EXAM:

- THIS EXAM BOOK It contains this cover page, three question pages and a formula sheet (which may be torn off). Make sure you start by putting your NAME, ID NUMBER, and TUTORIAL GROUP on the front (cover) page of the exam. The entire exam book (minus the formula sheet) will be handed in at the end of the exam and marked.
  - a. **FORMULA SHEET**, annotated on the printed page. The formula sheet has to be printed from Quercus.
- 2. A CALCULATOR, which can be anything that does NOT connect to wifi and does NOT communicate with other devices. ACCEPTABLE calculators include programmable and graphing calculators, scientific calculators, etc. UNACCEPTABLE calculators include: cell phones, tablets, laptops, etc.
- 3. A PEN OR PENCIL.
- 4. YOUR STUDENT ID CARD, used to check your identity.

If you are missing anything from the above items, raise your hand and ask an exam supervisor to supply what is missing. If you are missing an item that should have been brought by you (e.g., calculator, pen/pencil) there is a limited supply of extras and are on a first come, first served basis.

## **COMPLETE SOLUTION INCLUDES:**

- a) A sketch with a coordinate system, where appropriate. Where a diagram is provided, additional markings can be added to it.
- b) Clear and logical workings, including quoting the equations that were used, proper substitutions of numbers (when necessary) with all steps clearly indicated.
- c) The final answer with units and three significant figures.

	FOR O	FFICE USE O	NLY	
QUESTION	Ĭ	11	i III	TOTAL
MARK				
MAXIMUM	20	20	20	60

## Question I

A mass m=0.250 kg, attached to two horizontal springs (one on each side) with spring constants  $k_a=$  $137\frac{N}{m}$  a and  $k_b = 59.0\frac{N}{m}$ , is placed in a frictionless container so that it can oscillate without any losses, as shown in the picture. The spring is oscillating with an amplitude  $A=0.0529~\mathrm{m}$ . At time  $t=0~\mathrm{s}$  the spring is moving with velocity  $\vec{v}(0) = -0.367 \frac{\text{m}}{\epsilon}$  and is slowing down.

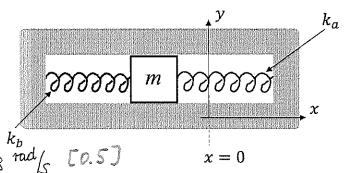
a. Determine the angular frequency of the motion,  $\omega_0$ . [2 points]

motion, 
$$\omega_0$$
. [2 points]
$$\omega_0 = \sqrt{\frac{k}{m}} \quad (0.5)$$

$$k_{eff} = k_a + k_b []$$

$$\omega_0 = \sqrt{\frac{k_a + k_b}{m}} = \sqrt{\frac{137 + 59}{0.15}} = k_b$$

$$\omega_0 = \sqrt{\frac{k_a + k_b}{m}} = \sqrt{\frac{137 + 59}{0.15}} = k_b$$



b. Determine the initial phase constant of the motion if the position of the oscillator is described with equation  $x(t) = A \cos(\omega t + \phi_0)$ . [8 points]

with equation 
$$x(t) = A\cos(\omega t + \phi_0)$$
. [8 points]
$$x(t) = A\cos(\omega t + \phi_0) \rightarrow x(0) = A\cos\phi_0 \leftarrow \text{not necessary}$$

$$v(t) = -A\omega\sin(\omega t + \phi_0) \quad v_0(0) = -A\omega\sin\phi. \quad \text{[1]}$$

 $-0.367 = -(0.0529)(28) - \sin \phi_0 [2]$ 

 $\Rightarrow 2$  SOLUTIONS [1] sin  $\phi_0 = 0.248$   $\Leftrightarrow$   $\phi_0 = 0.25$  rad or  $\phi_0 = 2.89$  rad [1] NOT CONSIDERING showing down means a>0 for v<0 (also in the fig x(0)<0) [2]

 $a(0) = -Aco^2 \cos \phi_0 \quad \therefore \quad \cos \phi_0 < 0 \quad \therefore \quad \phi_0 = 2.89 \text{ rad CID}$ 

Considering 2 realizes but armining to wrong Solution: 6.5/8

c. The container is filled with a thick liquid, causing the mass to undergo critical oscillations. What

is the drag coefficients of the liquid? [4 points]

(nitical 
$$\omega_0^2 - \frac{1}{4}^2 = 0$$
 [2]

 $\chi^2 = 4\omega_0^2$ ,  $\chi = 4\omega_0 = 56 \frac{\text{rad}}{5}$ 

drag coefficient:  $\chi = \frac{1}{2} + \frac{1}{2$ 

d. After the mass stops, it is displaced from the equilibrium by being given an initial velocity  $ec{v}_i$  in positive x direction. Show that it will take the mass  $t = \frac{1}{\omega_0}$  to reach the maximum displacement from the equilibrium position. [6 points

rom the equilibrium position. [6 points]
$$x(t) = Ae^{-\frac{1}{2}t/2} + Bt e^{-\frac{1}{2}t/2}$$

$$x(t) = -A^{\frac{x}{2}}e^{-\frac{1}{2}t/2} + Be^{-\frac{1}{2}t/2}$$

$$t(t) = -A^{\frac{x}{2}}e^{-\frac{1}{2}t/2} + Be^{-\frac{1}{2}t/2}$$

 $x(\theta=0, v=+v; [1]$ 

$$x(0) = 0 = A$$

$$x(0) = -A\frac{\lambda}{2} + B = v; \text{ as } A = 0, B = v;$$

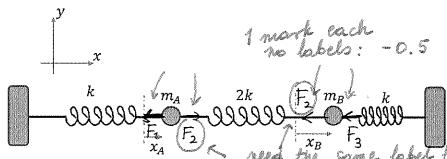
$$\max \text{ displacement } \frac{dx}{dt} = 0 \rightarrow P \text{ } v; e^{-\frac{\lambda t}{2}} - V; t \frac{\lambda}{2} e^{-\frac{\lambda t}{2}} = 0$$

$$v; e^{-\frac{\lambda t}{2}} \left[ 1 - \frac{\lambda t}{2} \right] = 0 \quad \text{[I]}$$

$$1 - \frac{\lambda t}{2} = 0 \rightarrow \lambda t = 2, \quad t = \frac{1}{\lambda} = \frac{2}{2\omega_0} = \frac{1}{\omega_0} \quad \text{[I]}$$

Two masses,  $m_A=m_B=m$  are connected horizontally by three springs of spring constants  $k_1=k, k_2=2k$ , and  $k_3=k$ , in such a way that  $k_1$  connects mass  $m_A$  to a rigid support on its left,  $k_3$  connects mass  $m_B$  to the rigid support on its right, and  $k_2$  connects two masses together, as shown in the picture below.

a. Assuming both masses are displaced in the +x direction, draw arrows **clearly** indicating the direction of forces on each mass due to each spring attached to it. Label each force. If it is impossible for you to draw the vectors in the picture, provide labels for the forces and their directions (e.g  $F_{12}$  – force on object 1 by agent 2, -y direction). [4 points]



b. Write the equation of motion for each mass. Clearly label the equations so it is obvious, which mass it is for. [4 points]

[2] 
$$m_A \frac{d^2 x_A}{dt^2} = -k(x_A) + 2k(x_B - x_A) = -kx_A - 2kx_A + 2kx_B = -3kx_A + 2kx_A$$
  
[2)  $m_B \frac{d^2 x_B}{dt^2} = -2k(x_B - x_A) = -kx_B = +2kx_A - 3kx_B$ 

c. Assuming masses  $m_A$  and  $m_B$  move according to the equations  $x_A(t) = A\cos(\omega t + \phi_A)$  and  $x_B = B\cos(\omega t + \phi_B)$ , determine the coefficient matrix M for the system. Express all elements of the matrix in terms of k and m). [6 points]

$$- m_{A}\omega^{2}A = -3k_{A}A + 2k_{B}B \qquad [2]$$

$$- m_{B}\omega^{2}B = +2k_{B}A - 3k_{B}B \qquad [2]$$

$$- \omega^{2} \begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} -\frac{3k_{B}}{m} & \frac{2k}{m} \\ \frac{2k}{m} & -\frac{3k}{m} \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix}$$

$$M \qquad [2] \qquad (needs to be identified)$$

d. Determine the normal frequencies of this oscillation. [6 points]

University of Toronto Question III PHY 293

A horizontal tube of length L is filled with Argon at temperature  $T=-3.0\,^{\circ}\text{C}$  ( $v_{sound_{Ar}}=306\,^{\frac{\text{m}}{\text{s}}}$ ). At time

t=0 s, all Ar particles are placed at their respective amplitudes. The open, left handed side of the tube is placed at x = 0 m. The characteristic of the other end of the tube is unknown.

a. Fill in the missing elements (numbers, symbols, constants) in the equation so that it correctly

describes  $n^{th}$  standing **displacement** wave of amplitude  $A_n$  in the tube. [5 points] HAS TO BE ZERO  $S_n(x,t) = (\underbrace{n_{ll}}_{m_{ll}}x) + \underbrace{n_{ll}}_{m_{ll}}x) + \underbrace{n_{ll}}_{m_{ll}}x)$ m is 1 or 2., but  $\frac{1}{k}$  No 7  $\frac{1}{mL}$  is totally correct b. Two consecutive harmonics heard in the tube have wavelengths of 0.060 m and 0.068 m. What

are their mode numbers? [4 points] longer  $\lambda$ , smaller f

 $\lambda_n = 0.060m$  $\lambda m = 0.068 m$   $\int n = 0.068 m$   $\int n = \frac{v}{\lambda n} = 0.068 m$   $\int n = \frac{v}{\lambda n} = \frac{v}{\lambda n} = \frac{v}{\lambda n} = \frac{v}{\lambda n} = \frac{0.068}{68 cm} = \frac{3.0 cm}{3.4 cm} = \frac{15}{17} = \frac{0.060}{0.060}$ 

c. What can you deduce about the other end of the tube? Briefly (1-2 sentences) justify your answer. [4 points]

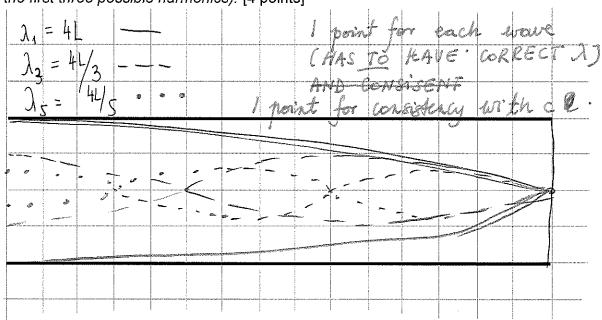
As the radio of consecutive harmonics is a ratio of two odd numbers, tube is closed at one end & open on the

· Correct Conclusion [2 marks]

• correct / reasonable justification [2]
d. What is the length of the tube? [3 points]

 $\lambda_n = \frac{4L}{n} \rightarrow L = \frac{n\lambda_u}{4} = \frac{17 \cdot 0.060}{4} = 0.255 m$ 1 point for consistent In with c , 2 points for correct & n 2 In

e. In the space below sketch a tube and the first three possible harmonics of a displacement wave in it as carefully as possible. The outline of the top and the bottom of the tube is provided, boundary conditions at the ends need to be identified. It should be clear from the sketch how various characteristics of the standing waves compare. (If you are unable to sketch, describe the first three possible harmonics). [4 points]



	OSCILLA	TIONS	
$\omega = 2\pi f = \frac{2\pi}{T}$	$\omega_0 = \sqrt{\frac{k}{m}}$	$\omega_0 = \sqrt{\frac{mgd}{I}}$	$\omega_0 = \frac{1}{\sqrt{LC}}$
$x(t) = A\cos\left(\omega t + \phi_i\right)$	$x(t) = A_0 \exp\left(-\frac{1}{2}\right)$	$\left(\frac{\sqrt{t}}{2}\right)\cos(\omega t + \phi_i)$	$x(t) = A(\omega)\cos(\omega t - \delta)$
	$x(t) = A \exp\left(-\frac{\gamma t}{2}\right)$	$+Bt \exp\left(-\frac{\gamma t}{2}\right)$	
x(t) =	$A \exp\left(\left(-\frac{\gamma}{2} + \left(\left \omega_0^2 - \frac{\gamma^2}{4}\right \right)^{\frac{1}{2}}\right)t\right)$	$+B \exp\left(\left(-\frac{\gamma}{2} - \left(\left \omega_0^2 - \frac{\gamma^2}{4}\right \right)\right)\right)$	$\left  \frac{1}{2} \right  \left  \frac{1}{2} \right  t$
$q_0(\omega) = \frac{\varepsilon_0}{\omega Z}$	$q(t) = q_0(\omega)\cos(\omega t - \delta)$	$Z = \sqrt{\left(\frac{1}{\omega C} - \omega L\right)^2 + I}$	$i = \frac{dq}{dt}$
$V_R = i(t)R$	$V_C = \frac{q}{C}$	$V_L = L \frac{di}{dt}$	
$K = \frac{1}{2}mv^2$	$V_C = \frac{q}{C}$ $U = \frac{1}{2}kx^2$ $\omega^2 = \omega_0^2 - \frac{\gamma^2}{4}$	$E(t) = E_0 \exp(-\gamma t)$	$P = \frac{dE}{dt} = Fv$
$Q = \frac{\omega_0}{\gamma}$	$\omega^2 = \omega_0^2 - \frac{\gamma^2}{4}$		
$A(\omega) = \frac{1}{\sqrt{(\omega_0^2)}}$	$\frac{a\omega_0^2}{-\omega^2)^2 + (\gamma\omega)^2}$	1	$=\frac{\omega\gamma}{\omega_0^2-\omega^2}$
$\bar{P}(\omega) = \frac{b[v_0(\omega)]^2}{2}$	$\overline{P}_{max} = \frac{F_0^2}{2m\gamma}$	$\bar{P}(\omega) = \frac{1}{2n}$	$\frac{F_0^2}{v\gamma \left[\frac{4(\Delta\omega)^2}{\gamma^2} + 1\right]}$
12 1 f		S(x,t) = Ac	$a \in (lex + cut + d)$
$v = \lambda f$ $h = \frac{2\pi}{2\pi}$	$y(x,t) = f(x \pm vt)$	y(x,t) = A co	$\cos\left(kx \pm \omega t + \phi_i\right)$
$v = \lambda f$ $k = \frac{2\pi}{\lambda}$	$y(x,t) = f(x \pm vt)$		
$v = \sqrt{\frac{F_T}{\mu}}$	$y(x,t) = f(x \pm vt)$ $y(x,t) =$	$y(x,t) = A co$ $= (A \sin(kx) + B \cos(kx))$	
$v = \sqrt{\frac{F_T}{\mu}}$	$y(x,t) = f(x \pm vt)$	y(x,t) = A co	cos(ωt)
	$y(x,t) = f(x \pm vt)$ $y(x,t) = v = \sqrt{\frac{B}{\rho}}$	$y(x,t) = A \cos(kx)$ $v = \sqrt{\frac{Y}{\rho}}$	cos(ωt)
$v = \sqrt{\frac{F_T}{\mu}}$	$y(x,t) = f(x \pm vt)$ $y(x,t) = \frac{B}{\rho}$ $\omega = \frac{2\pi}{T}$ $\omega_n = \frac{n\pi v}{2L}$	$y(x,t) = A \cos(kx)$ $v = \sqrt{\frac{Y}{\rho}}$ $f = \frac{1}{T}$	$cos(\omega t)$ $v = \sqrt{\frac{\gamma RT}{M}}$
$v = \sqrt{\frac{F_T}{\mu}}$ $\frac{\partial y^2}{\partial t^2} = v^2 \frac{\partial^2 y}{\partial x^2}$ $\omega_n = \frac{n\pi v}{L}$	$y(x,t) = f(x \pm vt)$ $y(x,t) = \frac{B}{\rho}$ $\omega = \frac{2\pi}{T}$ $\omega_n = \frac{n\pi v}{2L}$ MATHEMATICAL	$y(x,t) = A \cos(kx)$ $v = \sqrt{\frac{Y}{\rho}}$ $f = \frac{1}{T}$ $f_n = nf_1$	$cos(\omega t)$ $v = \sqrt{\frac{\gamma RT}{M}}$
$v = \sqrt{\frac{F_T}{\mu}}$ $\frac{\partial y^2}{\partial t^2} = v^2 \frac{\partial^2 y}{\partial x^2}$ $\omega_n = \frac{n\pi v}{L}$ $\cos \alpha + \cos \beta = 2 \cos \alpha$	$y(x,t) = f(x \pm vt)$ $y(x,t) = \frac{B}{\rho}$ $\omega = \frac{2\pi}{T}$ $\omega_n = \frac{n\pi v}{2L}$	$y(x,t) = A \cos(kx)$ $v = \sqrt{\frac{Y}{\rho}}$ $f = \frac{1}{T}$ $f_n = nf_1$ FORMULAE $\cos \alpha - \cos \beta = -2$	$cos(\omega t)$ $v = \sqrt{\frac{\gamma RT}{M}}$ $E = \frac{1}{4}\mu \omega_n^2 A_n^2 L$
$v = \sqrt{\frac{F_T}{\mu}}$ $\frac{\partial y^2}{\partial t^2} = v^2 \frac{\partial^2 y}{\partial x^2}$ $\omega_n = \frac{n\pi v}{L}$ $\cos \alpha + \cos \beta = 2 \cos \alpha$ $\cos(\alpha \pm \beta) = \cos \alpha$	$y(x,t) = f(x \pm vt)$ $y(x,t) = \frac{B}{\rho}$ $\omega = \frac{2\pi}{T}$ $\omega_n = \frac{n\pi v}{2L}$ $\cos\left[\frac{\alpha + \beta}{2}\right] \cos\left[\frac{\alpha - \beta}{2}\right]$ $\alpha \cos \beta \mp \sin \alpha \sin \beta$	$y(x,t) = A \cot x$ $v = \sqrt{\frac{Y}{\rho}}$ $v = \sqrt{\frac{Y}{\rho}}$ $f = \frac{1}{T}$ $f_n = nf_1$ FORMULAE $\cos \alpha - \cos \beta = -2$ $\sin(\alpha \pm \beta) = \sin \alpha$ $\tan^{-1}(x) = -2$	$cos(\omega t)$ $v = \sqrt{\frac{\gamma RT}{M}}$ $E = \frac{1}{4}\mu \omega_n^2 A_n^2 L$ $2 \sin\left[\frac{\alpha + \beta}{2}\right] \sin\left[\frac{\alpha - \beta}{2}\right]$
$v = \sqrt{\frac{F_T}{\mu}}$ $\frac{\partial y^2}{\partial t^2} = v^2 \frac{\partial^2 y}{\partial x^2}$ $\omega_n = \frac{n\pi v}{L}$ $\cos \alpha + \cos \beta = 2 \cos \alpha$ $\cot \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} = \cos^2 \theta = \frac{1}{2}$	$y(x,t) = f(x \pm vt)$ $y(x,t) = \frac{B}{\rho}$ $\omega = \frac{2\pi}{T}$ $\omega_n = \frac{n\pi v}{2L}$ $\cos\left[\frac{\alpha + \beta}{2}\right] \cos\left[\frac{\alpha - \beta}{2}\right]$	$y(x,t) = A \cos(kx)$ $v = \sqrt{\frac{Y}{\rho}}$ $f = \frac{1}{T}$ $f_n = nf_1$ FORMULAE $\cos \alpha - \cos \beta = -2$ $\sin(\alpha \pm \beta) = \sin(\alpha \pm \beta)$ $\cos^{-1}(x) = \cos^{-1}(x)$	$cos(\omega t)$ $v = \sqrt{\frac{\gamma RT}{M}}$ $E = \frac{1}{4}\mu \omega_n^2 A_n^2 L$ $2 \sin\left[\frac{\alpha + \beta}{2}\right] \sin\left[\frac{\alpha - \beta}{2}\right]$ $\alpha \cos \beta \pm \sin \beta \cos \alpha$ $\{\theta, \theta + \pi\} + 2\pi n$
$v = \sqrt{\frac{F_T}{\mu}}$ $\frac{\partial y^2}{\partial t^2} = v^2 \frac{\partial^2 y}{\partial x^2}$ $\omega_n = \frac{n\pi v}{L}$ $\cos \alpha + \cos \beta = 2 \cos \alpha$ $\cot \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} = 0$	$y(x,t) = f(x \pm vt)$ $y(x,t) = \frac{B}{\rho}$ $\omega = \frac{2\pi}{T}$ $\omega_n = \frac{n\pi v}{2L}$ $\alpha \cos \beta + \sin \alpha \sin \beta$ $\alpha \cos \beta + \sin \alpha \sin \beta$ $\alpha \cos \beta + \cos \alpha \cos \beta$ $\alpha \cos \beta + \sin \alpha \cos \beta$ $\alpha \cos \beta + \cos \beta$ $\alpha \cos \beta + \cos \beta + \cos \beta$ $\alpha \cos$	$y(x,t) = A \cot x$ $= (A \sin(kx) + B \cos(kx))$ $v = \sqrt{\frac{Y}{\rho}}$ $f = \frac{1}{T}$ $f_n = nf_1$ FORMULAE $\cos \alpha - \cos \beta = -2$ $\sin(\alpha \pm \beta) = \sin \cot \alpha$ $\tan^{-1}(x) = \cos^{-1}(x)$ $\sin^{-1}(x) = \frac{\alpha}{2}$ $\tilde{A} = Ae^{j\theta} = \frac{1}{2}$	$v = \sqrt{\frac{\gamma RT}{M}}$ $E = \frac{1}{4}\mu \omega_n^2 A_n^2 L$ $2\sin\left[\frac{\alpha + \beta}{2}\right] \sin\left[\frac{\alpha - \beta}{2}\right]$ $\cos \alpha \cos \beta \pm \sin \beta \cos \alpha$ $\{\theta, \theta + \pi\} + 2\pi n$ $\alpha = \pm \theta + 2\pi n$
$v = \sqrt{\frac{F_T}{\mu}}$ $\frac{\partial y^2}{\partial t^2} = v^2 \frac{\partial^2 y}{\partial x^2}$ $\omega_n = \frac{n\pi v}{L}$ $\cos \alpha + \cos \beta = 2 \cos \alpha$ $\cot \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} = \cos^2 \theta = \frac{1}{2}$	$y(x,t) = f(x \pm vt)$ $y(x,t) = \frac{B}{\rho}$ $\omega = \frac{2\pi}{T}$ $\omega_n = \frac{n\pi v}{2L}$ $\cos \left[\frac{\alpha + \beta}{2}\right] \cos \left[\frac{\alpha - \beta}{2}\right]$ $\alpha \cos \beta \mp \sin \alpha \sin \beta$ $= a_{11}a_{22} - a_{12}a_{21}$ $(1 + \cos(2\theta))$	$y(x,t) = A \cot x$ $= (A \sin(kx) + B \cos(kx))$ $v = \sqrt{\frac{Y}{\rho}}$ $f = \frac{1}{T}$ $f_n = nf_1$ FORMULAE $\cos \alpha - \cos \beta = -2$ $\sin(\alpha \pm \beta) = \sin \cot \alpha$ $\tan^{-1}(x) = \cos^{-1}(x)$ $\sin^{-1}(x) = \frac{\alpha}{2}$ $\tilde{A} = Ae^{j\theta} = \frac{1}{2}$	$cos(\omega t)$ $v = \sqrt{\frac{\gamma RT}{M}}$ $E = \frac{1}{4}\mu \omega_n^2 A_n^2 L$ $2 \sin\left[\frac{\alpha + \beta}{2}\right] \sin\left[\frac{\alpha - \beta}{2}\right]$ $\alpha \cos \beta \pm \sin \beta \cos \alpha$ $\{\theta, \theta + \pi\} + 2\pi n$ $= \pm \theta + 2\pi n$ $\{\theta, \pi - \theta\} + 2\pi n$