

ECE259: Electromagnetism

Term Test 1 - Monday February 3, 2020 Instructors: Profs. Micah Stickel and Piero Triverio

Last name:		 	 	
First name:		 	 	
Student number:		 	 	
Tutorial section numb	oer:	 	 	

Section	Day	Time	Room
TUT0101	Monday	14:00-15:00	BA1230
TUT0102	Monday	14:00-15:00	BA2175
TUT0103	Monday	14:00-15:00	BA2135
TUT0104	Monday	14:00-15:00	BA2159
TUT0105	Wednesday	13:00-14:00	BA2165
TUT0106	Wednesday	13:00-14:00	BA2195
TUT0107	Wednesday	13:00-14:00	BA1230
TUT0108	Wednesday	13:00-14:00	BAB024

Instructions

- Duration: 1 hour 30 minutes (9:10 to 10:40)
- Exam Paper Type: A. Closed book. Only the aid sheet provided at the end of this booklet is permitted.
- Calculator Type: 2. All non-programmable electronic calculators are allowed.
- Answers written in pen are typically eligible for remarking. Answers written in pencil may *not* be eligible for remarking.
- Only answers that are fully justified will be given full credit!

Marks: Q1: /20 | Q2: /20 | Q3: /15 | TOTAL: /55

Question 1

A uniform surface charge density, ρ_{S0} lies in the xy-plane, centered about the origin, and exists between r=a and r=b (b>a).

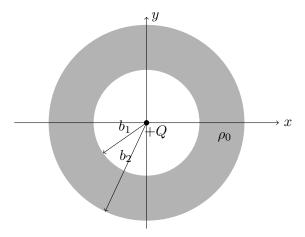
(a) Draw a picture of this situation. Clearly indicate on the figure and state separately the expressions for dQ', \mathbf{R} , and \mathbf{R}' . [4 points]

(b) For this charge distribution, determine the expression for the electric field intensity at any point on the positive z-axis. [10 points]

(c) Use the results of part (b) above to show that the electric field intensity for an infinitely large plate charged with a uniform charge density ρ_{S0} is given by $\mathbf{E}(0,0,z) = \frac{\rho_{S0}}{2\varepsilon_0} \mathbf{a}_z$ for z>0. Make sure to clearly describe your process and reasoning. [2 points]

(d) For the charge distribution geometry described above, identify a non-uniform ρ_S that would result in the electric field intensity along the positive z-axis to only have a y-component. Briefly justify your answer. [4 points]

Question 2



Consider the system made by

- a point charge +Q located at the origin;
- a uniform charge distribution in the **spherical** shell $b_1 < R < b_2$, where volume charge density is equal to ρ_0 .

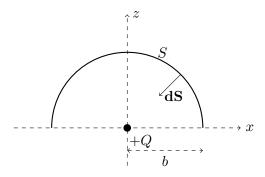
A cross section of the system is shown in the figure above.

i) Use Gauss' law to find the electric field $\bf E$ in the region $R < b_1$ [4 points].

ii) Use Gauss' law to find the electric field ${\bf E}$ in the region $b_1 < R < b_2$ [10 points].

iii) Use Gauss' law to find the electric field ${\bf E}$ in the region $R>b_2$ [6 points].

Question 3.1



We have a point charge Q at the origin. Let S be the hemispherical surface of radius b shown in the figure $(S: R = b, \varphi \in [0, 2\pi], \theta \in [0, \pi/2])$, with normal oriented inwards. The flux

$$\int_S \mathbf{E} \cdot \mathbf{dS}$$

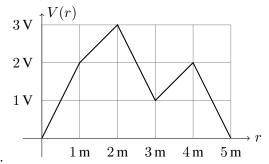
is equal to:

- (a) $-\frac{Q}{2\varepsilon_0}$;
- (b) $-\frac{Q}{\varepsilon_0}$;
- (c) 0
- (d) $+\frac{Q}{\varepsilon_0}$;
- (e) $+\frac{Q}{2\varepsilon_0}$;

Briefly justify your answer. [5 points]

Question 3.2

An electrostatic potential V(r) is present in the xy plane and is function of r only. The following graph depicts

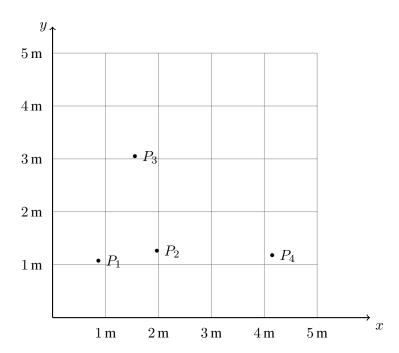


V(r) as a function of r.

Using the axis at the bottom of this page:

- sketch the equipotential lines that pass through the points (1 m, 0), (2 m, 0), (3 m, 0), (4 m, 0);
- Indicate with an arrow the direction of the electric field \mathbf{E} at points P_1, P_2, P_3 and P_4 .

Briefly justify your answer. [5 points]



Question 3.3

A very large plate has a constant charge density of $\rho_S = \rho_{SA}$ and is located at z = -a, where a > 0. A sphere of radius $R = b = \frac{a}{2}$ is centered about the origin and is uniformly charged with a charge density of $\rho_S = \rho_{SB}$. Which of the statements below represents the total electric field intensity at P(x, y, z) = (0, a, 0). Note: You may assume the electric field from the very large plate is the same as it would be for an infinitely-large plate.

(a)
$$\mathbf{E}_{total} = \left(\frac{\rho_{SA}}{2\varepsilon_0} + \frac{\rho_{SB}}{2\varepsilon_0}\right) \mathbf{a}_z$$

(b)
$$\mathbf{E}_{total} = \frac{\rho_{SA}}{2\varepsilon_0} \mathbf{a}_z$$

(c) 0

(d)
$$\mathbf{E}_{total} = \frac{\rho_{SA}}{2\varepsilon_0} \mathbf{a}_z + \frac{\rho_{SB}}{4\varepsilon_0} \mathbf{a}_y$$

(e)
$$\mathbf{E}_{total} = \frac{\rho_{SA}}{2\varepsilon_0} \mathbf{a}_z + \frac{\rho_{SB}}{2b\varepsilon_0} \mathbf{a}_R$$

(f) None of the above.

Briefly justify your answer. [5 points]

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1. Coordinate Systems

1.1 Cartesian coordinates

Position vector: $\mathbf{R} = x\mathbf{a}_x + y\mathbf{a}_y + z\mathbf{a}_z$

Differential length elements: $d\mathbf{l}_x = \mathbf{a}_x dx$, $d\mathbf{l}_y = \mathbf{a}_y dy$, $d\mathbf{l}_z = \mathbf{a}_z dz$

Differential surface elements: $d\mathbf{S}_x = \mathbf{a}_x dy dz$, $d\mathbf{S}_y = \mathbf{a}_y dx dz$, $d\mathbf{S}_z = \mathbf{a}_z dx dy$

Differential volume element: dV = dxdydz

1.2 Cylindrical coordinates

Position vector: $\mathbf{R} = r\mathbf{a}_r + z\mathbf{a}_z$

Differential length elements: $\mathbf{dl}_r = \mathbf{a}_r dr$, $\mathbf{dl}_\phi = \mathbf{a}_\phi r d\phi$, $\mathbf{dl}_z = \mathbf{a}_z dz$

Differential surface elements: $d\mathbf{S}_r = \mathbf{a}_r r d\phi dz$, $d\mathbf{S}_\phi = \mathbf{a}_\phi dr dz$, $d\mathbf{S}_z = \mathbf{a}_z r d\phi dr$

Differential volume element: $dV = rdrd\phi dz$

1.3 Spherical coordinates

Position vector: $\mathbf{R} = R\mathbf{a}_R$

Differential length elements: $\mathbf{dl}_R = \mathbf{a}_R dR$, $\mathbf{dl}_\theta = \mathbf{a}_\theta R d\theta$, $\mathbf{dl}_\phi = \mathbf{a}_\phi R \sin \theta d\phi$

Differential surface elements: $d\mathbf{S}_R = \mathbf{a}_R R^2 \sin \theta d\theta d\phi$, $d\mathbf{S}_{\theta} = \mathbf{a}_{\theta} R \sin \theta dR d\phi$, $d\mathbf{S}_{\phi} = \mathbf{a}_{\phi} R dR d\theta$

Differential volume element: $dV = R^2 \sin \theta dR d\theta d\phi$

2. Relationship between coordinate variables

-	Cartesian	Cylindrical	Spherical
\overline{x}	x	$r\cos\phi$	$R\sin\theta\cos\phi$
y	$\mid y$	$r\sin\phi$	$R\sin\theta\sin\phi$
z	z	z	$R\cos\theta$
r	$\sqrt{x^2+y^2}$	r	$R\sin heta$
ϕ		ϕ	ϕ
z	z	z	$R\cos\theta$
R	$\sqrt{x^2 + y^2 + z^2}$	$\sqrt{r^2 + z^2}$	R
θ		$\sqrt{r^2 + z^2}$ $\tan^{-1}\frac{r}{z}$	θ
ϕ		ϕ	ϕ

3. Dot products of unit vectors

•	\mathbf{a}_x	\mathbf{a}_y	\mathbf{a}_z	\mathbf{a}_r	\mathbf{a}_{ϕ}	\mathbf{a}_z	\mathbf{a}_R	$\mathbf{a}_{ heta}$	\mathbf{a}_{ϕ}
\mathbf{a}_x	1	0	0	$\cos \phi$	$-\sin\phi$	0	$\sin \theta \cos \phi$	$\cos \theta \cos \phi$	$-\sin\phi$
\mathbf{a}_y	0	1	0	$\sin \phi$	$\cos \phi$	0	$\sin\theta\sin\phi$	$\cos\theta\sin\phi$	$\cos \phi$
\mathbf{a}_z	0	0	1	0	0	1	$\cos \theta$	$-\sin\theta$	0
\mathbf{a}_r	$\cos \phi$	$\sin \phi$	0	1	0	0	$\sin \theta$	$\cos \theta$	0
\mathbf{a}_{ϕ}	$-\sin\phi$	$\cos \phi$	0	0	1	0	0	0	1
\mathbf{a}_z	0	0	1	0	0	1	$\cos \theta$	$-\sin\theta$	0
\mathbf{a}_R	$\sin \theta \cos \phi$	$\sin\theta\sin\phi$	$\cos \theta$	$\sin \theta$	0	$\cos \theta$	1	0	0
$\mathbf{a}_{ heta}$	$\cos \theta \cos \phi$	$\cos\theta\sin\phi$	$-\sin\theta$	$\cos \theta$	0	$-\sin\theta$	0	1	0
\mathbf{a}_{ϕ}	$-\sin\phi$	$\cos \phi$	0	0	1	0	0	0	1

4. Relationship between vector components

=	Cartesian Cartesian	Cylindrical	Spherical
A_x	A_x	$A_r \cos \phi - A_\phi \sin \phi$	$A_R \sin \theta \cos \phi + A_\theta \cos \theta \cos \phi -$
		·	$A_{\phi}\sin\phi$
A_y	A_y	$A_r \sin \phi + A_\phi \cos \phi$	$A_R \sin \theta \sin \phi + A_\theta \cos \theta \sin \phi +$
			$A_{\phi}\cos\phi$
A_z	A_z	A_z	$A_R \cos \theta - A_\theta \sin \theta$
A_r	$A_x \cos \phi + A_y \sin \phi$	A_r	$A_R \sin \theta + A_\theta \cos \theta$
A_{ϕ}	$-A_x\sin\phi + A_y\cos\phi$	A_{ϕ}	A_{ϕ}
A_z	A_z	A_z	$A_R \cos \theta - A_\theta \sin \theta$
A_R	$A_x \sin \theta \cos \phi + A_y \sin \theta \sin \phi +$	$A_r \sin \theta + A_z \cos \theta$	A_R
	$A_z \cos \theta$		
A_{θ}	$A_x \cos \theta \cos \phi + A_y \cos \theta \sin \phi -$	$A_r \cos \theta - A_z \sin \theta$	$A_{ heta}$
	$A_z \sin \theta$		
A_{ϕ}	$-A_x \sin \phi + A_y \cos \phi$	A_{ϕ}	A_{ϕ}

5. Differential operators

5.1 Gradient

$$\nabla V = \frac{\partial V}{\partial x} \mathbf{a}_x + \frac{\partial V}{\partial y} \mathbf{a}_y + \frac{\partial V}{\partial z} \mathbf{a}_z = \frac{\partial V}{\partial r} \mathbf{a}_r + \frac{1}{r} \frac{\partial V}{\partial \phi} \mathbf{a}_\phi + \frac{\partial V}{\partial z} \mathbf{a}_z = \frac{\partial V}{\partial R} \mathbf{a}_R + \frac{1}{R} \frac{\partial V}{\partial \theta} \mathbf{a}_\theta + \frac{1}{R \sin \theta} \frac{\partial V}{\partial \phi} \mathbf{a}_\phi$$

5.2 Divergence

$$\nabla \cdot \mathbf{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z} = \frac{1}{r} \frac{\partial (rA_r)}{\partial r} + \frac{1}{r} \frac{\partial A_\phi}{\partial \phi} + \frac{\partial A_z}{\partial z} = \frac{1}{R^2} \frac{\partial (R^2 A_R)}{\partial R} + \frac{1}{R \sin \theta} \frac{\partial (\sin \theta A_\theta)}{\partial \theta} + \frac{1}{R \sin \theta} \frac{\partial A_\phi}{\partial \phi} + \frac{1}$$

5.3 Laplacian

$$\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial V}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 V}{\partial \phi^2} + \frac{\partial^2 V}{\partial z^2} = \frac{1}{R^2} \frac{\partial}{\partial R} \left(R^2 \frac{\partial V}{\partial R} \right) + \frac{1}{R^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial V}{\partial \theta} \right) + \frac{1}{R^2 \sin^2 \theta} \frac{\partial^2 V}{\partial \phi^2}$$

$$\nabla \times \mathbf{A} = \left(\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z}\right) \mathbf{a}_x + \left(\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x}\right) \mathbf{a}_y + \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y}\right) \mathbf{a}_z
= \left(\frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z}\right) \mathbf{a}_r + \left(\frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r}\right) \mathbf{a}_\phi + \frac{1}{r} \left(\frac{\partial (rA_\phi)}{\partial r} - \frac{\partial A_r}{\partial \phi}\right) \mathbf{a}_z
= \frac{1}{R \sin \theta} \left(\frac{\partial (\sin \theta A_\phi)}{\partial \theta} - \frac{\partial A_\theta}{\partial \phi}\right) \mathbf{a}_R + \frac{1}{R} \left(\frac{1}{\sin \theta} \frac{\partial A_R}{\partial \phi} - \frac{\partial (RA_\phi)}{\partial R}\right) \mathbf{a}_\theta
+ \frac{1}{R} \left(\frac{\partial (RA_\theta)}{\partial R} - \frac{\partial A_R}{\partial \theta}\right) \mathbf{a}_\phi$$

6. Electromagnetic formulas

 Table 1
 Electrostatics

$$\mathbf{F} = \frac{1}{4\pi\varepsilon} \frac{Q_1 Q_2}{|\mathbf{R}_2 - \mathbf{R}_1|^3} (\mathbf{R}_2 - \mathbf{R}_1) \quad \mathbf{E} = \frac{1}{4\pi\varepsilon} \int_v \frac{(\mathbf{R} - \mathbf{R}')}{|\mathbf{R} - \mathbf{R}'|^3} dQ'$$

$$\nabla \times \mathbf{E} = 0 \qquad \nabla \cdot \mathbf{D} = \rho_v$$

$$\oint_C \mathbf{E} \cdot d\mathbf{l} = 0 \qquad \oint_S \mathbf{D} \cdot d\mathbf{S} = Q$$

$$\mathbf{E} = -\nabla V \qquad V = \frac{1}{4\pi\varepsilon} \int_v \frac{dQ'}{|\mathbf{R} - \mathbf{R}'|}$$

$$V = V(P_2) - V(P_1) = \frac{W}{Q} = -\int_{P_1}^{P_2} \mathbf{E} \cdot d\mathbf{l}$$

$$\mathbf{D} = \varepsilon_0 \mathbf{E} + \mathbf{P} = \varepsilon \mathbf{E} \qquad \mathbf{P} = \chi_e \varepsilon_0 \mathbf{E}$$

$$\rho_{p,v} = -\nabla \cdot \mathbf{P} \qquad \mathbf{a}_n$$

$$\rho_{p,s} = -\mathbf{a}_n \cdot (\mathbf{P}_2 - \mathbf{P}_1)$$

$$\mathbf{a}_n \cdot (\mathbf{D}_2 - \mathbf{D}_1) = \rho_s \qquad 1$$

$$E_{1,t} = E_{2,t}$$

$$Q = CV \qquad W_e = \frac{1}{2} QV$$

$$W_e = \frac{1}{2} \int_{vol} \rho_v V dv = \frac{1}{2} \int_{vol} \mathbf{D} \cdot \mathbf{E} dv$$

$$\nabla \cdot (\varepsilon \nabla V) = -\rho_v \qquad \nabla \cdot (\varepsilon \nabla V) = 0$$

 Table 2
 Magnetostatics

$$\mathbf{F}_{m} = q\mathbf{u} \times \mathbf{B} \qquad \qquad \mathbf{F}_{m} = I\mathbf{l} \times \mathbf{B}$$

$$\nabla \times \mathbf{B} = \mu \mathbf{J} \qquad \qquad \nabla \cdot \mathbf{B} = 0$$

$$\oint_{C} \mathbf{B} \cdot d\mathbf{l} = \mu I \qquad \qquad \oint_{S} \mathbf{B} \cdot d\mathbf{S} = 0$$

$$\mathbf{B} = \frac{\mu I}{4\pi} \oint_{C} \frac{d\mathbf{l}' \times (\mathbf{R} - \mathbf{R}')}{|\mathbf{R} - \mathbf{R}'|^{3}} \qquad \qquad \Phi = \int_{S} \mathbf{B} \cdot d\mathbf{S}$$

$$\mathbf{B} = \mu_{0} (\mathbf{H} + \mathbf{M}) = \mu \mathbf{H} \qquad \qquad \mathbf{M} = \chi_{m} \mathbf{H}$$

$$\mathbf{J}_{m,s} = \mathbf{M} \times \mathbf{a}_{n} \qquad \qquad \mathbf{J}_{m} = \nabla \times \mathbf{M}$$

$$B_{1,n} = B_{2,n} \qquad \qquad \mathbf{a}_{n} \times (\mathbf{H}_{2} - \mathbf{H}_{1}) = \mathbf{J}_{s}$$

$$\nabla \times \mathbf{H} = \mathbf{J} \qquad \qquad \oint \mathbf{H} \cdot d\mathbf{l} = I$$

$$W_{m} = \frac{1}{2} \int_{vol} \mathbf{B} \cdot \mathbf{H} dv$$

$$L = \frac{N\Phi}{I} = \frac{2W_{m}}{I^{2}} \qquad \qquad L_{12} = \frac{N_{2}\Phi_{12}}{I_{1}} = \frac{N_{2}}{I_{1}} \int_{S_{2}} \mathbf{B}_{1} \cdot d\mathbf{S}_{2}$$

$$\mathcal{R} = \frac{l}{\mu S} \qquad \qquad V_{mmf} = NI$$

Table 3 Faraday's law, Ampere-Maxwell law

$$V_{emf} = \oint_C (\mathbf{u} \times \mathbf{B}) \cdot d\mathbf{l} - \int_S \frac{\partial \mathbf{B}}{\partial t} \cdot d\mathbf{S} \quad V_{emf} = \oint_C \mathbf{E} \cdot d\mathbf{l} = -\frac{d\Phi}{dt}$$

$$\oint_C \mathbf{H} \cdot d\mathbf{l} = \int_S \mathbf{J} \cdot d\mathbf{S} + \frac{d}{dt} \int_S \mathbf{D} \cdot d\mathbf{S} \qquad \nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$$

 Table 4
 Currents

$$I = \int_{S} \mathbf{J} \cdot \mathbf{dS} \qquad \mathbf{J} = \rho \mathbf{u} = \sigma \mathbf{E}$$

$$\nabla \cdot \mathbf{J} = -\frac{\partial \rho_{v}}{\partial t} \qquad \mathbf{P} = \int_{vol} (\mathbf{E} \cdot \mathbf{J}) \, dv$$

$$J_{2,n} - J_{1,n} = -\frac{\partial \rho_{s}}{\partial t} \qquad \sigma_{2} J_{1,t} = \sigma_{1} J_{2,t}$$

$$R = \frac{l}{\sigma S} \qquad \sigma = -\rho_{e} \mu_{e} = \frac{1}{\rho}$$