

UNIVERSITY OF TORONTO  
Faculty of Applied Science and Engineering

## Term Test III

First Year — Program 5

*MAT185S — Linear Algebra*

*Examiners: J W Lorimer & G M T D'Eleuterio*

31 March 2011

Student Name:

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Last Name

First Names

Student Number:

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Tutorial Section:

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### Instructions:

1. Attempt *all* questions.
2. The value of each question is indicated at the end of the space provided for its solution; a summary is given in the table opposite.
3. Write the final answers *only* in the boxed space provided for each question.
4. No aid is permitted.
5. The duration of this test is 90 minutes.
6. There are 10 pages and 5 questions in this test paper.

For Markers Only		
Question	Value	Mark
A		
1	10	
B		
2	10	
C		
3	10	
4	10	
5	10	
Total	50	

## A. Definitions and Statements

*Fill in the blanks.*

1(a). The *coordinates* of a vector  $\mathbf{v} \in \mathcal{V}$  in terms of the basis  $B = \{\mathbf{b}_1, \mathbf{b}_2 \cdots \mathbf{b}_n\}$  are

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1(b). The function  $\Delta : {}^n\mathbb{R}^n \mapsto \mathbb{R}$  is a *determinant function* if and only if

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1(c). The  $(i, j)$ -*minor matrix* of  $\mathbf{A} \in {}^n\mathbb{R}^n$  is

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1(d). The cross product of two vectors  $\vec{u} = (u_1, u_2, u_3)$  and  $\vec{v} = (v_1, v_2, v_3) \in \mathbb{R}^3$  can be expressed using the determinant as

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1(e). State the *Cauchy-Binet product theorem* for determinants.

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## B. True or False

Determine if the following statements are true or false and indicate by “T” (for true) and “f” (for false) in the box beside the question. The value of each question is 2 marks.

2(a). If  $\mathbf{P}$  is the transition (transformation) matrix between two bases for a vector space, then  $\mathbf{P}\mathbf{x} = \mathbf{0}$  has a nontrivial solution.

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2(b). If  $\mathbf{A}, \mathbf{E} \in {}^n\mathbb{R}^n$  and  $\mathbf{E}$  is an elementary matrix of Type III, then  $\det \mathbf{AE} = \det \mathbf{A}$ .

☐

2(c). The determinant function  $\det : {}^n\mathbb{R}^n \mapsto \mathbb{R}$  is injective.

☐

2(d). If  $\mathbf{A} \in {}^m\mathbb{R}^n$  and  $\text{rank } \mathbf{A} = m$ , then  $\det \mathbf{AA}^T \neq 0$ .

☐

2(e). There is only one determinant function  $\Delta_n : {}^n\mathbb{R}^n \mapsto \mathbb{R}$ .

☐

### C. Problems

3. Let  $F = \{\mathbf{f}_1, \mathbf{f}_2 \cdots \mathbf{f}_n\}$  and  $G = \{\mathbf{g}_1, \mathbf{g}_2 \cdots \mathbf{g}_n\}$  be two bases for  ${}^n\mathbb{R}$ . Also let  $\mathbf{Q}_1$  be the transition (transformation) matrix from  $F$  to the standard basis  $E$  and  $\mathbf{Q}_2$  be the transition (transformation) matrix from  $G$  to  $E$ .

(a) Show that  $\mathbf{Q} = \mathbf{Q}_1^{-1}\mathbf{Q}_2$  is the transition (transformation) matrix from  $G$  to  $F$ .

(b) Find an invertible matrix  $\mathbf{P}$  such that  $\mathbf{P}\mathbf{f}_j = \mathbf{g}_j, j = 1 \cdots n$ .

3(a). Show that  $\mathbf{Q} = \mathbf{Q}_1^{-1}\mathbf{Q}_2$  is the transition (transformation) matrix from  $G$  to  $F$ .

/5

3(b). Find an invertible matrix  $\mathbf{P}$  such that  $\mathbf{P}\mathbf{f}_j = \mathbf{g}_j, j = 1 \cdots n$ .

/5

4. Let  $\{\mathbf{x}_1, \mathbf{x}_2 \cdots \mathbf{x}_{n-1}\} \subset {}^n\mathbb{R}$  be linearly independent and  $\mathbf{x} \in {}^n\mathbb{R}$ . Show that  $\mathbf{x} \in \text{span}\{\mathbf{x}_1, \mathbf{x}_2 \cdots \mathbf{x}_{n-1}\}$  if and only if  $\det \begin{bmatrix} \mathbf{x}_1 & \mathbf{x}_2 & \cdots & \mathbf{x}_{n-1} & \mathbf{x} \end{bmatrix} = 0$ .

*...cont'd*

4. ...cont'd

/10

5. Let  $\Delta_1 : {}^n\mathbb{R}^n \mapsto \mathbb{R}$  and  $\Delta_2 : {}^n\mathbb{R}^n \mapsto \mathbb{R}$  be two determinant functions where  $\Delta_1 \neq 0$ , i.e.,  $\Delta_1(\mathbf{A})$  is not zero for all  $\mathbf{A} \in {}^n\mathbb{R}^n$ .

(a) Show that  $\Delta_1(\mathbf{1}) \neq 0$ .

(b) Show that

$$\Delta_2(\mathbf{A}) = \frac{\Delta_2(\mathbf{1})}{\Delta_1(\mathbf{1})} \Delta_1(\mathbf{A})$$

for any  $\mathbf{A} \in {}^n\mathbb{R}^n$ .

5(a). Show that  $\Delta_1(\mathbf{1}) \neq 0$ .

/4



5(b). Show that

$$\Delta_2(\mathbf{A}) = \frac{\Delta_2(\mathbf{1})}{\Delta_1(\mathbf{1})} \Delta_1(\mathbf{A})$$

for any  $\mathbf{A} \in {}^n\mathbb{R}^n$ .

*...cont'd*

5(b). . . .*cont'd*

/6