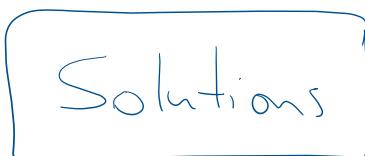


## ECE259H1: Electromagnetism

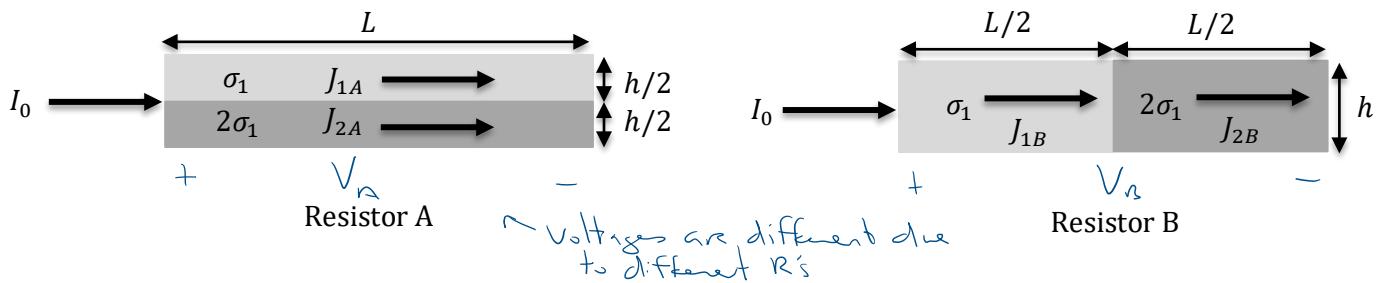
*Homework Review Quiz 3 – Friday March 24, 2023*



- Make sure to **accurately** enter your first name, last name, and student number above.
- The quiz is worth 20 marks and has two questions. Question 1 is worth 6 marks, and Question 2 is work 14 marks.
- Show all of your work.
- The final page has some reference material that you might find helpful.
- Take a deep breath and relax 😊.

### Question #1 (6 marks)

Two resistors are shown below as *Resistor A* and *Resistor B*. Both have a current of  $I_0$  flowing through them from left to right. You can assume that each current density is uniformly distributed throughout the cross-sectional areas of each part of these resistors. The resistors have a square cross-sectional area ( $h \times h$ ) and the same total length,  $L$ .



For the statements below, identify if they are *True* or *False* and justify your answer.

*True*

*False*

The total resistance of *Resistor A* is larger than that of *Resistor B*.

$$\begin{aligned} * \text{ Recognizing that } E_{1A} = E_{2A} = \frac{V_A}{L}, \text{ then } J_{1A} = \sigma_1 \frac{V_A}{L} \text{ and } J_{2A} = 2\sigma_1 \frac{V_A}{L} \\ \therefore I_0 = J_{1A}(h)(\frac{h}{2}) + J_{2A}(h)(\frac{h}{2}) = (\frac{h^2}{2})(\sigma_1 \frac{V_A}{L} + 2\sigma_1 \frac{V_A}{L}) = V_A (\frac{h^2}{2L})(3\sigma_1) \\ \therefore R_A = \frac{V_A}{I_0} = \frac{2L}{3h^2\sigma_1} \end{aligned}$$

$$\text{For } R_B: \quad J_{1B} = J_{2B} = \frac{I_0}{L^2} \quad (\text{due to the continuity of current})$$

$$\text{But } E_{1B} = \frac{J_{1B}}{\sigma_1} = \frac{I_0}{\sigma_1 L^2} \text{ and } E_{2B} = \frac{J_{2B}}{2\sigma_1} = \frac{I_0}{2\sigma_1 L^2}$$

$$\text{And } V_B = E_{1B}(\frac{L}{2}) + E_{2B}(\frac{L}{2}) = \frac{I_0}{\sigma_1 L^2} \left( \frac{L}{2} \right) + \frac{I_0}{2\sigma_1 L^2} \left( \frac{L}{2} \right) \rightarrow R_B = \frac{V_B}{I_0} = \frac{3L}{4\sigma_1 h^2} \\ \therefore R_B > R_A$$

OR: For  $R_A$ : This is like two resistors in parallel:

$$R_A = R_{1A} // R_{2A} = \frac{L}{\sigma_1(h)(\frac{h}{2})} // \frac{L}{2\sigma_1 h(\frac{h}{2})} = \left( \frac{\sigma_1 h^2}{2L} + \frac{2\sigma_1 h^2}{2L} \right)^{-1} = \frac{2L}{3\sigma_1 h^2}$$

For  $R_B$ : This is like two resistors in series:

$$R_B = R_{1B} + R_{2B} = \frac{L/2}{\sigma_1(h^2)} + \frac{L/2}{2\sigma_1 h^2} = \frac{3L}{4\sigma_1 h^2}$$

$$\therefore R_B > R_A$$

True  False

The electric field intensity in Part 1 of Resistor B is smaller than the electric field intensity of Part 2 of Resistor B. Meaning  $E_{1B} < E_{2B}$ .

Since  $I_o$  is continuous throughout the resistor  $\nu_B$ ,

$$I_o = J_{1B}(l^2) = J_{2B}(l^2) \Rightarrow J_{1B} = J_{2B} = \frac{I_o}{l^2}$$

$$\text{Since } J = \sigma E \rightarrow E_{1B} = \frac{J_{1B}}{\sigma_1} = \frac{I_o}{\sigma_1 l^2} \text{ and } E_{2B} = \frac{J_{2B}}{2\sigma_1} = \frac{I_o}{2\sigma_1 l^2}$$

$$\therefore E_{2B} = \frac{1}{2} E_{1B} \rightarrow E_{2B} < E_{1B}$$

OR: Since  $E_{1B} = \frac{V_{1B}}{l/2}$  and  $V_{1B} = I_o R_{1B} = I_o \left( \frac{l/2}{\sigma_1 l^2} \right)$

$$= \frac{I_o}{\sigma_1 l^2}$$

and  $E_{2B} = \frac{V_{2B}}{l/2}$  and  $V_{2B} = I_o R_{2B} = I_o \left( \frac{l/2}{2\sigma_1 l^2} \right)$

$$= \frac{I_o}{2\sigma_1 l^2}$$

$$\therefore E_{2B} = \frac{1}{2} E_{1B} \rightarrow E_{2B} < E_{1B}$$

### Question #2 (14 marks)

A spherical capacitor consists of two concentric perfectly conducting spheres of radii  $R_i = a$  and  $R_o = 2a$ . Between the conducting spheres exists a volume charge density given by  $\rho_v = -\rho_0 \epsilon_0$  [C/m<sup>3</sup>] in air (i.e.,  $\epsilon_r = 1$ ), where  $\rho_0$  is a positive constant. It is known that the outer sphere is grounded, and the inner sphere is held at a potential of  $V_0$ .

(10 marks) i) Determine the expression for the electric scalar potential  $V(R)$  between these spheres.

\* Using Poisson's Equation:  $\nabla \cdot (\epsilon_r \epsilon_0 \nabla V) = \nabla^2 V = -\frac{\rho_v}{\epsilon_0} = +\rho_0$

In spherical coordinates:  $\frac{1}{R^2} \frac{d}{dR} (R^2 \frac{dV}{dR}) = +\rho_0$

Integration #1:  $\int d(R^2 \frac{dV}{dR}) = R^2 \frac{dV}{dR} = \int \rho_0 R^2 dR = \frac{\rho_0}{3} R^3 + C_1$

Integration #2:  $\int dV = V(R) = \int \left( \frac{\rho_0}{3} R^3 + C_1 \right) dR = \frac{\rho_0}{6} R^2 - \frac{C_1}{R} + C_2$

Using Boundary Values:  $V(a) = V_0 = \frac{\rho_0}{6} a^2 - \frac{C_1}{a} + C_2 \quad (1)$

$$V(2a) = 0 = \frac{\rho_0}{6} (4a^2) - \frac{C_1}{2a} + C_2 \quad (2)$$

$$(1) - (2): V_0 = -\frac{3\rho_0 a^2}{8} - \frac{C_1}{2a} \rightarrow C_1 = -\rho_0 a^3 - 2a V_0 \quad (3)$$

$$(3) \rightarrow (2): C_2 = -\frac{2\rho_0 a^2}{3} + \frac{1}{2a} (-\rho_0 a^3 - 2a V_0) = -\frac{2\rho_0 a^2}{3} - \frac{\rho_0 a^2}{2} - V_0 = -\frac{7\rho_0 a^2}{6} - V_0$$

$$\therefore V(R) = \underbrace{\frac{\rho_0}{6} R^2 + \frac{\rho_0 a^3}{R}}_{\text{constant}} + \frac{2a V_0}{R} - \frac{7\rho_0 a^2}{6} - V_0$$

**Question #2 (continued)**

(4 marks) ii) Determine the expression for the electric field intensity  $\mathbf{E}(R)$  between these spheres.

$$\begin{aligned}\bar{\mathbf{E}}(R) &= -\frac{\partial V}{\partial R} \hat{\mathbf{a}}_R = -\frac{\partial}{\partial R} \left( \frac{\rho_0}{6} R^2 + \frac{\rho_0 a^3}{R} + \frac{2aV_0}{R} - \frac{7\rho_0 a^3}{6} - V_0 \right) \\ &= \underbrace{\left( -\frac{\rho_0 R}{3} - \frac{\rho_0 a^3}{R^2} - \frac{2aV_0}{R^2} \right)}_{\hat{\mathbf{a}}_R} \hat{\mathbf{a}}_R\end{aligned}$$

OR:

$$\begin{aligned}\bar{\mathbf{E}}(R) &= -\frac{\partial V}{\partial R} \hat{\mathbf{a}}_R = \left( -\frac{\rho_0}{3} R + \frac{C_1}{R^2} \right) \hat{\mathbf{a}}_R \quad \text{But } C_1 = -\rho_0 a^3 - 2aV_0 \\ &= \underbrace{\left( -\frac{\rho_0}{3} R - \frac{\rho_0 a^3}{R^2} - \frac{2aV_0}{R^2} \right)}_{\hat{\mathbf{a}}_R} \hat{\mathbf{a}}_R\end{aligned}$$

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## Reference Formulae

### 1. Coordinate Systems

#### 1.1 Cartesian coordinates

Position vector:  $\mathbf{R} = x\mathbf{a}_x + y\mathbf{a}_y + z\mathbf{a}_z$

Differential length elements:  $d\mathbf{l}_x = \mathbf{a}_x dx$ ,  $d\mathbf{l}_y = \mathbf{a}_y dy$ ,  $d\mathbf{l}_z = \mathbf{a}_z dz$

Differential surface elements:  $d\mathbf{S}_x = \mathbf{a}_x dy dz$ ,  $d\mathbf{S}_y = \mathbf{a}_y dx dz$ ,  $d\mathbf{S}_z = \mathbf{a}_z dx dy$

Differential volume element:  $dV = dx dy dz$

#### 1.2 Cylindrical coordinates

Position vector:  $\mathbf{R} = r\mathbf{a}_r + z\mathbf{a}_z$

Differential length elements:  $d\mathbf{l}_r = \mathbf{a}_r dr$ ,  $d\mathbf{l}_\phi = \mathbf{a}_\phi r d\phi$ ,  $d\mathbf{l}_z = \mathbf{a}_z dz$

Differential surface elements:  $d\mathbf{S}_r = \mathbf{a}_r r d\phi dz$ ,  $d\mathbf{S}_\phi = \mathbf{a}_\phi r dr dz$ ,  $d\mathbf{S}_z = \mathbf{a}_z r dr d\phi$

Differential volume element:  $dV = r dr d\phi dz$

#### 1.3 Spherical coordinates

Position vector:  $\mathbf{R} = R\mathbf{a}_R$

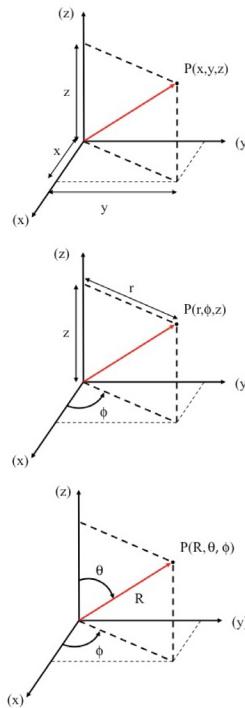
Differential length elements:  $d\mathbf{l}_R = \mathbf{a}_R dR$ ,  $d\mathbf{l}_\theta = \mathbf{a}_\theta R d\theta$ ,  $d\mathbf{l}_\phi = \mathbf{a}_\phi R \sin \theta d\phi$

Differential surface elements:  $d\mathbf{S}_R = \mathbf{a}_R R^2 \sin \theta d\phi d\theta$ ,  $d\mathbf{S}_\theta = \mathbf{a}_\theta R \sin \theta dR d\phi$ ,  $d\mathbf{S}_\phi = \mathbf{a}_\phi R dR d\theta$

Differential volume element:  $dV = R^2 \sin \theta dR d\theta d\phi$

### 2. Relationship between coordinate variables

-	Cartesian	Cylindrical	Spherical
$x$	$x$	$r \cos \phi$	$R \sin \theta \cos \phi$
$y$	$y$	$r \sin \phi$	$R \sin \theta \sin \phi$
$z$	$z$	$z$	$R \cos \theta$
$r$	$\sqrt{x^2 + y^2}$	$r$	$R \sin \theta$
$\phi$	$\tan^{-1} \frac{y}{x}$	$\phi$	$\phi$
$z$	$z$	$z$	$R \cos \theta$
$R$	$\sqrt{x^2 + y^2 + z^2}$	$\frac{r}{\sin \theta}$	$R$
$\theta$	$\cos^{-1} \frac{z}{\sqrt{x^2 + y^2 + z^2}}$	$\tan^{-1} \frac{r}{z}$	$\theta$
$\phi$	$\tan^{-1} \frac{y}{x}$	$\phi$	$\phi$



### 3. Dot products of unit vectors

.	$\mathbf{a}_x$	$\mathbf{a}_y$	$\mathbf{a}_z$	$\mathbf{a}_r$	$\mathbf{a}_\phi$	$\mathbf{a}_z$	$\mathbf{a}_R$	$\mathbf{a}_\theta$	$\mathbf{a}_\phi$
$\mathbf{a}_x$	1	0	0	$\cos \phi$	$-\sin \phi$	0	$\sin \theta \cos \phi$	$\cos \theta \cos \phi$	$-\sin \phi$
$\mathbf{a}_y$	0	1	0	$\sin \phi$	$\cos \phi$	0	$\sin \theta \sin \phi$	$\cos \theta \sin \phi$	$\cos \phi$
$\mathbf{a}_z$	0	0	1	0	0	1	$\cos \theta$	$-\sin \theta$	0
$\mathbf{a}_r$	$\cos \phi$	$\sin \phi$	0	1	0	0	$\sin \theta$	$\cos \theta$	0
$\mathbf{a}_\phi$	$-\sin \phi$	$\cos \phi$	0	0	1	0	0	0	1
$\mathbf{a}_z$	0	0	1	0	0	1	$\cos \theta$	$-\sin \theta$	0
$\mathbf{a}_R$	$\sin \theta \cos \phi$	$\sin \theta \sin \phi$	$\cos \theta$	$\sin \theta$	0	$\cos \theta$	1	0	0
$\mathbf{a}_\theta$	$\cos \theta \cos \phi$	$\cos \theta \sin \phi$	$-\sin \theta$	$\cos \theta$	0	$-\sin \theta$	0	1	0
$\mathbf{a}_\phi$	$-\sin \phi$	$\cos \phi$	0	0	1	0	0	0	1

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### 5. Differential operators

#### 5.1 Gradient

$$\nabla V = \frac{\partial V}{\partial x} \mathbf{a}_x + \frac{\partial V}{\partial y} \mathbf{a}_y + \frac{\partial V}{\partial z} \mathbf{a}_z = \frac{\partial V}{\partial r} \mathbf{a}_r + \frac{1}{r} \frac{\partial V}{\partial \phi} \mathbf{a}_\phi + \frac{\partial V}{\partial z} \mathbf{a}_z = \frac{\partial V}{\partial R} \mathbf{a}_R + \frac{1}{R} \frac{\partial V}{\partial \theta} \mathbf{a}_\theta + \frac{1}{R \sin \theta} \frac{\partial V}{\partial \phi} \mathbf{a}_\phi$$

#### 5.2 Divergence

$$\nabla \cdot \mathbf{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z} = \frac{1}{r} \frac{\partial (r A_r)}{\partial r} + \frac{1}{r} \frac{\partial A_\phi}{\partial \phi} + \frac{\partial A_z}{\partial z} = \frac{1}{R^2} \frac{\partial (R^2 A_R)}{\partial R} + \frac{1}{R \sin \theta} \frac{\partial (A_\theta)}{\partial \theta} + \frac{1}{R \sin \theta} \frac{\partial A_\phi}{\partial \phi}$$

#### 5.3 Laplacian

$$\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} = \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial V}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 V}{\partial \phi^2} + \frac{\partial^2 V}{\partial z^2} = \frac{1}{R^2} \frac{\partial}{\partial R} \left( R^2 \frac{\partial V}{\partial R} \right) + \frac{1}{R^2 \sin^2 \theta} \frac{\partial^2 V}{\partial \theta^2} + \frac{1}{R^2 \sin^2 \theta} \frac{\partial^2 V}{\partial \phi^2}$$

#### 5.4 Curl

$$\begin{aligned} \nabla \times \mathbf{A} &= \left( \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) \mathbf{a}_x + \left( \frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) \mathbf{a}_y + \left( \frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \mathbf{a}_z \\ &= \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right) \mathbf{a}_r + \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right) \mathbf{a}_\phi + \frac{1}{r} \left( \frac{\partial (r A_\phi)}{\partial r} - \frac{\partial A_r}{\partial \phi} \right) \mathbf{a}_z \\ &= \frac{1}{R \sin \theta} \left( \frac{\partial (\sin \theta A_\phi)}{\partial \theta} - \frac{\partial A_\theta}{\partial \phi} \right) \mathbf{a}_R + \frac{1}{R} \left( \frac{1}{\sin \theta} \frac{\partial A_R}{\partial \phi} - \frac{\partial (R A_\phi)}{\partial R} \right) \mathbf{a}_\theta \\ &+ \frac{1}{R} \left( \frac{\partial (R A_\theta)}{\partial R} - \frac{\partial A_R}{\partial \theta} \right) \mathbf{a}_\phi \end{aligned}$$

### 4. Relationship between vector components

=	Cartesian	Cylindrical	Spherical
$A_x$	$A_x$	$A_r \cos \phi - A_\theta \sin \phi$	$A_R \sin \theta \cos \phi + A_\theta \cos \theta \cos \phi - A_\phi \sin \phi$
$A_y$	$A_y$	$A_r \sin \phi + A_\theta \cos \phi$	$A_R \sin \theta \sin \phi + A_\theta \cos \theta \sin \phi + A_\phi \cos \phi$
$A_z$	$A_z$	$A_z$	$A_R \cos \theta - A_\theta \sin \theta$
$A_r$	$A_r \cos \phi + A_y \sin \phi$	$A_r$	$A_R \sin \theta + A_\theta \cos \theta$
$A_\phi$	$-A_x \sin \phi + A_y \cos \phi$	$A_\phi$	$A_\phi$
$A_z$	$A_z$	$A_z$	$A_R \cos \theta - A_\theta \sin \theta$
$A_R$	$A_x \sin \theta \cos \phi + A_y \sin \theta \sin \phi + A_z \cos \theta$	$A_r \sin \theta + A_z \cos \theta$	$A_R$
$A_\theta$	$A_x \cos \theta \cos \phi + A_y \cos \theta \sin \phi - A_z \sin \theta$	$A_r \cos \theta - A_z \sin \theta$	$A_\theta$
$A_\phi$	$-A_x \sin \phi + A_y \cos \phi$	$A_\phi$	$A_\phi$

Table 1 Electrostatics

$\mathbf{F} = \frac{1}{4\pi\epsilon} \frac{Q_1 Q_2}{ \mathbf{R}_2 - \mathbf{R}_1 ^3} (\mathbf{R}_2 - \mathbf{R}_1)$	$\mathbf{E} = \frac{1}{4\pi\epsilon} \int_v \frac{(R - R')}{ R - R' ^3} dQ'$
$\nabla \times \mathbf{E} = 0$	$\nabla \cdot \mathbf{D} = \rho_v$
$\oint_C \mathbf{E} \cdot d\mathbf{l} = 0$	$\oint_S \mathbf{D} \cdot d\mathbf{S} = Q$
$\mathbf{E} = -\nabla V$	$V = \frac{1}{4\pi\epsilon} \int_v \frac{dQ'}{ R - R' ^3}$
$V = V(P_2) - V(P_1) = \frac{W}{Q} = - \int_{P_1}^{P_2} \mathbf{E} \cdot d\mathbf{l}$	
$\mathbf{D} = \epsilon_0 \mathbf{E} + \mathbf{P} = \epsilon \mathbf{E}$	$\mathbf{P} = \chi_e \epsilon_0 \mathbf{E}$
$\rho_{p,v} = -\nabla \cdot \mathbf{P}$	
$\rho_{p,s} = -\mathbf{a}_n \cdot (\mathbf{P}_2 - \mathbf{P}_1)$	
$\mathbf{a}_n \cdot (\mathbf{D}_2 - \mathbf{D}_1) = \rho_s$	
$E_{1,t} = E_{2,t}$	
$Q = CV$	$W_e = \frac{1}{2} QV$
$W_e = \frac{1}{2} \int_{vol} \rho_v V dv = \frac{1}{2} \int_{vol} \mathbf{D} \cdot \mathbf{E} dv$	
$\nabla \cdot (\epsilon \nabla V) = -\rho_v$	$\nabla \cdot (\epsilon \nabla V) = 0$

