
ECE259: Electromagnetism

Vector calculus quiz - January 29th, 2024

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This is the first version "A" of the quiz with "vector-calculus-quiz" written near the QR code

SOLUTION

Marking scheme:
0.5 points for choosing the correct answer
0.5 points for the justification

Instructions

- Duration: 15 minutes
- Exam Paper Type: A. Closed book. Only the aid sheet provided at the end of this booklet is permitted.
- Calculator Type: 2. All non-programmable electronic calculators are allowed.
- **Only answers that are fully justified will be given full marks!**
- Please write with a **dark** pen or pencil. This test will be scanned.

Question 1 [1 pt]

Consider the closed surface S made by the union of the following two surfaces:

$$S_1 : R = 1 \quad \theta \in [0, \pi/2] \quad \varphi \in [0, 2\pi] \quad (1)$$

$$S_2 : R \in [0, 1] \quad \theta = \pi/2 \quad \varphi \in [0, 2\pi] \quad (2)$$

The normal vector to the surface, pointing **outwards** is:

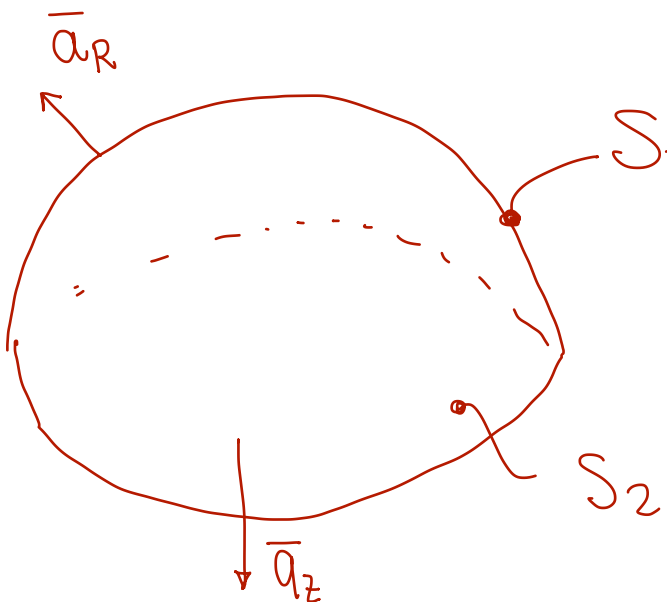
(a) $+\mathbf{a}_R$ on S_1 , $+\mathbf{a}_z$ on S_2

(b) $+\mathbf{a}_R$ on S_1 , $-\mathbf{a}_z$ on S_2

(c) $-\mathbf{a}_R$ on S_1 , $+\mathbf{a}_z$ on S_2

(d) $-\mathbf{a}_R$ on S_1 , $-\mathbf{a}_z$ on S_2

Please justify your answer by sketching the two surfaces and the normal vectors on S_1 and S_2 .



Question 2 [1 pt]

The unit vector \mathbf{a}_θ is equal to:

- (a) $-\sin \varphi \mathbf{a}_x + \cos \varphi \mathbf{a}_y$;
- (b) $\cos \varphi \mathbf{a}_x + \sin \varphi \mathbf{a}_y$;
- (c) $\cos \theta \cos \varphi \mathbf{a}_x + \cos \theta \sin \varphi \mathbf{a}_y - \sin \theta \mathbf{a}_z$;
- (d) $\sin \theta \cos \varphi \mathbf{a}_x + \sin \theta \sin \varphi \mathbf{a}_y + \cos \theta \mathbf{a}_z$;

Please provide a brief justification.

$$\begin{aligned}\bar{\mathbf{a}}_\theta &= (\bar{\mathbf{a}}_\theta \cdot \bar{\mathbf{a}}_x) \bar{\mathbf{a}}_x + (\bar{\mathbf{a}}_\theta \cdot \bar{\mathbf{a}}_y) \bar{\mathbf{a}}_y + (\bar{\mathbf{a}}_\theta \cdot \bar{\mathbf{a}}_z) \bar{\mathbf{a}}_z = \\ &= \cos \theta \cos \varphi \bar{\mathbf{a}}_x + \cos \theta \sin \varphi \bar{\mathbf{a}}_y - \sin \theta \bar{\mathbf{a}}_z\end{aligned}$$

Question 3 [1 pt]

Let S be the boundary of the volume $r \in [0, 1]$, $\varphi \in [0, \pi/2]$, $z \in [0, 1]$.

Calculate the **outward** flux through S of the vector field $\mathbf{F} = \varphi \mathbf{a}_\varphi$.

The flux is equal to:

(a) $\int_S \mathbf{F} \cdot d\mathbf{S} = \pi/2$

(b) $\int_S \mathbf{F} \cdot d\mathbf{S} = -\pi/2$

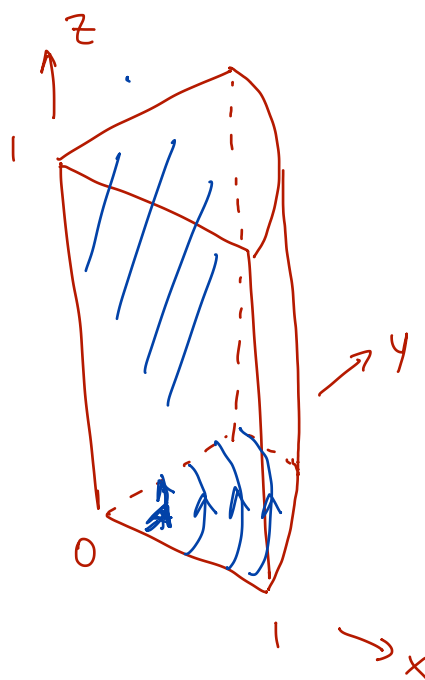
(c) $\int_S \mathbf{F} \cdot d\mathbf{S} = 0$

(d) $\int_S \mathbf{F} \cdot d\mathbf{S} = \pi$

(e) $\int_S \mathbf{F} \cdot d\mathbf{S} = -\pi$

Please justify your answer.

- No flux on upper and lower bases, and on side face since $\bar{\mathbf{F}} \cdot \bar{d\mathbf{S}} = 0$
- No flux on face on $y=0$ since $\bar{\mathbf{F}} = 0$ for $\varphi = 0$



- On face on $x=0 \Rightarrow \bar{\mathbf{F}} = \frac{\pi}{2} \bar{\mathbf{a}}_\varphi \quad \bar{d\mathbf{S}} = \bar{\mathbf{a}}_\varphi dr dz$

$$\int \bar{\mathbf{F}} \cdot \bar{d\mathbf{S}} = \int_{r=0}^1 \int_{z=0}^1 \frac{\pi}{2} \bar{\mathbf{a}}_\varphi \cdot \bar{\mathbf{a}}_\varphi dr dz = \frac{\pi}{2}$$

Question 4 [1 pt]

Consider two points P_1 and P_2 with coordinates

$$P_1 = (r = 5, \varphi = +\pi/2, z = 1) \quad (3)$$

$$P_2 = (x = 2, y = +2, z = 2) \quad (4)$$

Which expression is correct for the distance vector \mathbf{d} which goes from P_1 to P_2 ?

(a) $\mathbf{d} = (2\sqrt{2} - 5)\mathbf{a}_r + \mathbf{a}_z$

(b) $\mathbf{d} = (5 - 2\sqrt{2})\mathbf{a}_r - \mathbf{a}_z$

(c) $\mathbf{d} = +2\mathbf{a}_x - 3\mathbf{a}_y + \mathbf{a}_z$

(d) $\mathbf{d} = -2\mathbf{a}_x + 3\mathbf{a}_y - \mathbf{a}_z$

Please provide a brief justification.

$\overline{R}_1 = 5\overline{a}_r + \overline{a}_z = \overbrace{5\overline{a}_y}^{\text{since } \varphi = \frac{\pi}{2}} + \overline{a}_z$

$$\overline{R}_2 = 2\overline{a}_x + 2\overline{a}_y + 2\overline{a}_z$$

$$\overline{d} = \overline{R}_2 - \overline{R}_1 = 2\overline{a}_x - 3\overline{a}_y + \overline{a}_z$$

1. Coordinate Systems

1.1 Cartesian coordinates

Position vector: $\mathbf{R} = x\mathbf{a}_x + y\mathbf{a}_y + z\mathbf{a}_z$

Differential length elements: $d\mathbf{l}_x = \mathbf{a}_x dx$, $d\mathbf{l}_y = \mathbf{a}_y dy$, $d\mathbf{l}_z = \mathbf{a}_z dz$

Differential surface elements: $d\mathbf{S}_x = \mathbf{a}_x dydz$, $d\mathbf{S}_y = \mathbf{a}_y dxdz$, $d\mathbf{S}_z = \mathbf{a}_z dxdy$

Differential volume element: $dV = dxdydz$

1.2 Cylindrical coordinates

Position vector: $\mathbf{R} = r\mathbf{a}_r + z\mathbf{a}_z$

Differential length elements: $d\mathbf{l}_r = \mathbf{a}_r dr$, $d\mathbf{l}_\phi = \mathbf{a}_\phi r d\phi$, $d\mathbf{l}_z = \mathbf{a}_z dz$

Differential surface elements: $d\mathbf{S}_r = \mathbf{a}_r r d\phi dz$, $d\mathbf{S}_\phi = \mathbf{a}_\phi dr dz$, $d\mathbf{S}_z = \mathbf{a}_z r d\phi dr$

Differential volume element: $dV = r dr d\phi dz$

1.3 Spherical coordinates

Position vector: $\mathbf{R} = R\mathbf{a}_R$

Differential length elements: $d\mathbf{l}_R = \mathbf{a}_R dR$, $d\mathbf{l}_\theta = \mathbf{a}_\theta R d\theta$, $d\mathbf{l}_\phi = \mathbf{a}_\phi R \sin \theta d\phi$

Differential surface elements: $d\mathbf{S}_R = \mathbf{a}_R R^2 \sin \theta d\theta d\phi$, $d\mathbf{S}_\theta = \mathbf{a}_\theta R \sin \theta dR d\phi$, $d\mathbf{S}_\phi = \mathbf{a}_\phi R dR d\theta$

Differential volume element: $dV = R^2 \sin \theta dR d\theta d\phi$

2. Relationship between coordinate variables

-	Cartesian	Cylindrical	Spherical
x	x	$r \cos \phi$	$R \sin \theta \cos \phi$
y	y	$r \sin \phi$	$R \sin \theta \sin \phi$
z	z	z	$R \cos \theta$
r	$\sqrt{x^2 + y^2}$	r	$R \sin \theta$
ϕ	$\tan^{-1} \frac{y}{x}$	ϕ	ϕ
z	z	z	$R \cos \theta$
R	$\sqrt{x^2 + y^2 + z^2}$	$\sqrt{r^2 + z^2}$	R
θ	$\cos^{-1} \frac{z}{\sqrt{x^2 + y^2 + z^2}}$	$\tan^{-1} \frac{r}{z}$	θ
ϕ	$\tan^{-1} \frac{y}{x}$	ϕ	ϕ

3. Dot products of unit vectors

\cdot	\mathbf{a}_x	\mathbf{a}_y	\mathbf{a}_z	\mathbf{a}_r	\mathbf{a}_ϕ	\mathbf{a}_z	\mathbf{a}_R	\mathbf{a}_θ	\mathbf{a}_ϕ
\mathbf{a}_x	1	0	0	$\cos \phi$	$-\sin \phi$	0	$\sin \theta \cos \phi$	$\cos \theta \cos \phi$	$-\sin \phi$
\mathbf{a}_y	0	1	0	$\sin \phi$	$\cos \phi$	0	$\sin \theta \sin \phi$	$\cos \theta \sin \phi$	$\cos \phi$
\mathbf{a}_z	0	0	1	0	0	1	$\cos \theta$	$-\sin \theta$	0
\mathbf{a}_r	$\cos \phi$	$\sin \phi$	0	1	0	0	$\sin \theta$	$\cos \theta$	0
\mathbf{a}_ϕ	$-\sin \phi$	$\cos \phi$	0	0	1	0	0	0	1
\mathbf{a}_z	0	0	1	0	0	1	$\cos \theta$	$-\sin \theta$	0
\mathbf{a}_R	$\sin \theta \cos \phi$	$\sin \theta \sin \phi$	$\cos \theta$	$\sin \theta$	0	$\cos \theta$	1	0	0
\mathbf{a}_θ	$\cos \theta \cos \phi$	$\cos \theta \sin \phi$	$-\sin \theta$	$\cos \theta$	0	$-\sin \theta$	0	1	0
\mathbf{a}_ϕ	$-\sin \phi$	$\cos \phi$	0	0	1	0	0	0	1

4. Differential operators

4.1 Gradient

$$\nabla V = \frac{\partial V}{\partial x} \vec{a}_x + \frac{\partial V}{\partial y} \vec{a}_y + \frac{\partial V}{\partial z} \vec{a}_z = \frac{\partial V}{\partial r} \vec{a}_r + \frac{1}{r} \frac{\partial V}{\partial \phi} \vec{a}_\phi + \frac{\partial V}{\partial z} \vec{a}_z = \frac{\partial V}{\partial R} \vec{a}_R + \frac{1}{R} \frac{\partial V}{\partial \theta} \vec{a}_\theta + \frac{1}{R \sin \theta} \frac{\partial V}{\partial \phi} \vec{a}_\phi$$

4.2 Divergence

$$\nabla \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z} = \frac{1}{r} \frac{\partial(r A_r)}{\partial r} + \frac{1}{r} \frac{\partial A_\phi}{\partial \phi} + \frac{\partial A_z}{\partial z} = \frac{1}{R^2} \frac{\partial(R^2 A_R)}{\partial R} + \frac{1}{R \sin \theta} \frac{\partial(\sin \theta A_\theta)}{\partial \theta} + \frac{1}{R \sin \theta} \frac{\partial A_\phi}{\partial \phi}$$

4.3 Laplacian

$$\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial V}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 V}{\partial \phi^2} + \frac{\partial^2 V}{\partial z^2} = \frac{1}{R^2} \frac{\partial}{\partial R} \left(R^2 \frac{\partial V}{\partial R} \right) + \frac{1}{R^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial V}{\partial \theta} \right) + \frac{1}{R^2 \sin^2 \theta} \frac{\partial^2 V}{\partial \phi^2}$$

4.4 Curl

$$\begin{aligned} \nabla \times \vec{A} &= \left(\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) \vec{a}_x + \left(\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) \vec{a}_y + \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \vec{a}_z \\ &= \left(\frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right) \vec{a}_r + \left(\frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right) \vec{a}_\phi + \frac{1}{r} \left(\frac{\partial(r A_\phi)}{\partial r} - \frac{\partial A_r}{\partial \phi} \right) \vec{a}_z \\ &= \frac{1}{R \sin \theta} \left(\frac{\partial(\sin \theta A_\phi)}{\partial \theta} - \frac{\partial A_\theta}{\partial \phi} \right) \vec{a}_R + \frac{1}{R} \left(\frac{1}{\sin \theta} \frac{\partial A_R}{\partial \phi} - \frac{\partial(R A_\phi)}{\partial R} \right) \vec{a}_\theta \\ &\quad + \frac{1}{R} \left(\frac{\partial(R A_\theta)}{\partial R} - \frac{\partial A_R}{\partial \theta} \right) \vec{a}_\phi \end{aligned}$$