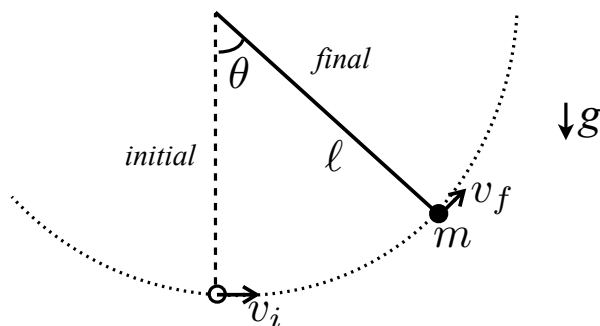


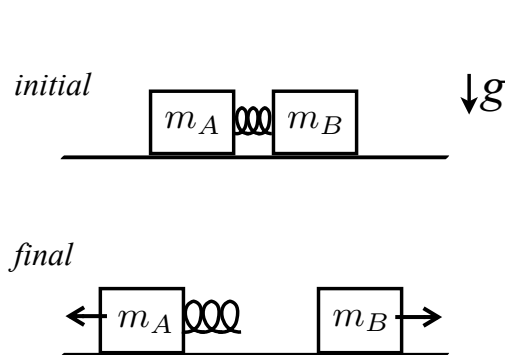
1. [10 pts.] Two objects of equal mass m collide elastically. After the collision, one object has velocity v_{1f} , but the second object is no longer moving: $v_{2f} = 0$. What were the initial velocities before the collision? Assume the objects are constrained to move along a line. Express your answer in terms of m and v_{1f} .
2. [20 pts.] A metallic weight with $m = 4.00$ kg swings on a massless rod whose length is $\ell = 0.500$ m, under gravitational acceleration. At the bottom of its trajectory, the velocity is 8.00 m/s. At some later time t_f , the mass has swung through $\pi/4$ angle (or 45.0 degrees) to a height $h = \ell(1 - 1/\sqrt{2})$.
 - (a) [5 pts.] What is the speed v_f ?
 - (b) [5 pts.] What is the tangential acceleration a_t at time t_f ?
 - (c) [5 pts.] How much work has been done by the rod on the mass, during this interval?
 - (d) [5 pts.] How much work is done by gravity on the mass, during the same interval?



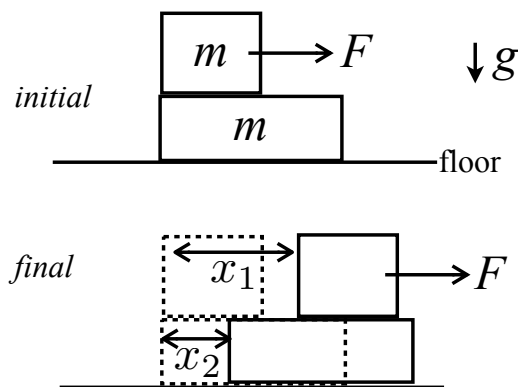
Problem 2.

3. [30 pts.] Two blocks of masses $m_A = 2.00\text{ kg}$ and $m_B = 3.00\text{ kg}$ are placed on a horizontal frictionless surface. A nearly massless spring with $k = 3.00\text{ N/m}$ is attached to the left block, and the blocks are pushed together with the spring between them, putting 20.0 J of potential energy into the spring. The blocks are then released.

- [5 pts.] By what amount (distance) is the spring compressed?
- [5 pts.] What is the final kinetic energy, if the surface is frictionless?
- [10 pts.] If the surface is frictionless, what is the final speed of each block?
- [10 pts.] If instead the surface has a coefficient of friction $\mu_k = 0.300$, how far will each block slide before coming to rest?



Problem 3.



Problem 4.

4. [30 pts.] A stack of two blocks sits on a frictionless surface; however, between the two blocks is a static coefficient of friction μ_s and a kinetic coefficient of friction μ_k . External force F is applied to the top block. During the time the force is applied, the top block is displaced by x_1 , and the bottom block is displaced by x_2 . Assume enough force is applied that $x_1 > x_2$, as shown above. Express your answers in terms of m , x_1 , x_2 , F , g , μ_s , and μ_k :

- [5 pts.] What is the magnitude of the frictional force between the two blocks?
- [5 pts.] What is the final velocity of the centre of mass?
- [10 pts.] What is the final kinetic energy of the system?
- [10 pts.] How much energy is lost to heat?

①

Q1 [10pts]

We know from class that in 1D elastic collisions,

$$(V_{rel})_i = -(V_{rel})_f.$$

$$V_{1i} - V_{2i} = -(V_{1f} - V_{2f})$$

$L = 0$ in this problem

so

$$\underline{V_{1i} - V_{2i} = -V_{1f}} \quad \dots \text{Eq (1)}$$

combine with conservation of momentum,

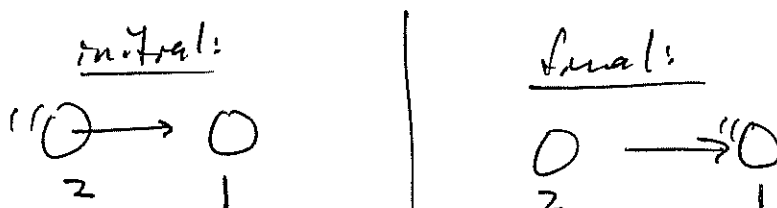
$$P_i = P_f$$

$$m V_{1i} + m V_{2i} = m V_{1f} + m V_{2f}^0$$

$$\rightarrow \underline{V_{1i} + V_{2i} = V_{1f}} \quad \dots \text{Eq (2)}$$

Add these 2 eqs & find that $\boxed{V_{1i} = 0}$

in which case $\boxed{V_{2i} = V_{1f}}$.



Q1 cont

(2)

Alternately can rederive $(V_{rel})_i = -(V_{rel})_f$ result, by conserving kinetic energy:

$$K_i = K_f$$

$$\frac{1}{2} m V_{1i}^2 + \frac{1}{2} m V_{2i}^2 = \frac{1}{2} m V_{1f}^2 + \frac{1}{2} m \cancel{V_{2f}^2} \rightarrow 0$$

cancel $m/2$, rearrange:

$$V_{1i}^2 - V_{1f}^2 = -V_{2i}^2$$

$$\underbrace{(V_{1i} - V_{1f})(V_{1i} + V_{1f})}_{= -V_{2fi}} = -V_{2i}^2$$

= $-V_{2fi}$ by conservation of momentum,
Eq (2) on previous page

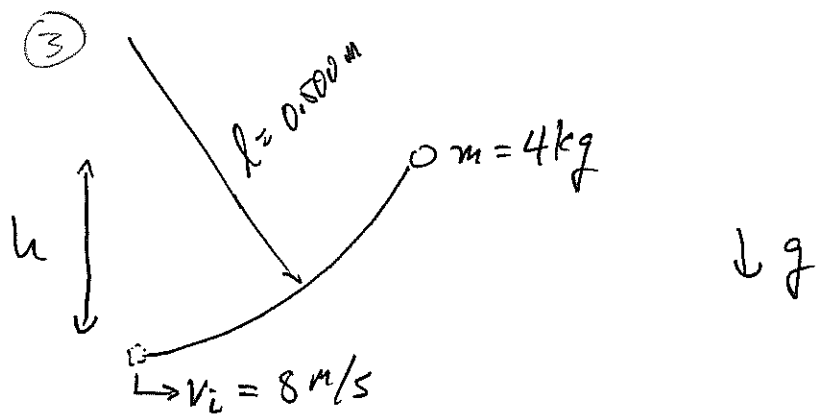
so

$$-V_{1i} - V_{1f} = -V_{2i}$$

or $V_{1i} - V_{2i} = -V_{1f}$, which is Eq (1)
rederived.

Another initial condition that conserves
p & E is that $V_{1i} = V_{1f}$, $V_{2i} = V_{2f} = 0 \dots$ but this
means no collision occurred!

Q2 [20pts]



[5pts]

(a) Conservation of energy gives $E_i = E_f$, which we can apply in this case because the system is energetically isolated, if we include mass + earth + gravity in system.

$$\text{So } K_i = \frac{1}{2} m v_i^2, \quad K_f = \frac{1}{2} m v_f^2$$

$$v_f - v_i = \Delta U = mgh = mgl(1 - 1/\sqrt{2}) \text{ as given.}$$

$$\text{Thus } K_f = K_i + U_i - U_f$$

$$\frac{1}{2} m v_f^2 = \frac{1}{2} m v_i^2 - mgh$$

$$v_f^2 = v_i^2 - 2gh$$

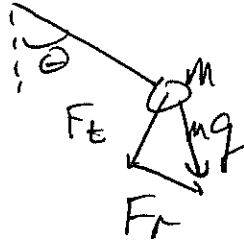
$$v_f = \sqrt{v_i^2 - 2gh} = \underline{7.82 \text{ m/s}}$$

\uparrow \uparrow \uparrow
 $(8.00)^2$ 9.80 $h = l(1 - 1/\sqrt{2}) = 0.146 \text{ m}$

Q2 cont

(4)

(b) [5 pts] Tangential acceleration is provided by the tangential component of gravity.



$$F_t = -mg \sin \theta$$

$$= -4 \text{ kg} \cdot 9.8 \text{ m/s}^2 \cdot \frac{1}{\sqrt{2}}$$

$$F_t = -27.7 \text{ N}$$

Why negative? Restoring force, pulling in negative theta direction. Oh, wait, asking for a_t :

$$a_t = -9.80 \text{ m/s}^2 \cdot \frac{\sin \theta}{1/\sqrt{2}}$$

$$a_t = -6.93 \text{ m/s}^2$$

Q2 cont.

(5)

(c) [5 pts.] Work = $\int \vec{F} \cdot d\vec{r}$, but
the rod always exerts a radial
force, that is ~~the~~ perpendicular
to $d\vec{r} = \vec{v} dt$.

$$\rightarrow \boxed{W = 0} \text{ for rod.}$$

(d) [5 pts.] Gravity is the force that
removes kinetic energy from the
moving mass.

$$\Delta K = W = -\Delta U = -mgh$$
$$h = l(1 - 1/r_2)$$
$$= 0.146 \text{ m}$$

$$\rightarrow \boxed{W = -5.72 \text{ J}}$$

Accept answers within 2%

Accept negative or positive sign, since
question asks "how much".

Q3. [30 pts]

(6)

(a) $U = \frac{1}{2}kx^2$ for a spring, where x is displacement [5 pts] from equilibrium, or compression in this case.

$$\text{So } \frac{1}{2}kx_i^2 = U_i$$

$$\rightarrow x_i = \sqrt{2U_i/k}$$

$$= \sqrt{2 \cdot 20.5 / 3 \text{ N/m}}$$

$$= \boxed{3.65 \text{ m}}$$

(b) Final kinetic energy is initial potential [5 pts] energy:

$$E_i = E_f$$

$$U_i + K_i = U_f + K_f \quad \text{but } K_i = 0 \text{ \& } U_f = 0$$

$$\text{So } \boxed{K_f = U_i = 20.0 \text{ J}}$$

(c) By conservation of momentum, after release [10 pts]

$$m_A v_A + m_B v_B = p_f = \underbrace{p_i}_{=0} = 0$$

since $v_A = v_B = 0$ initially

$$\text{This means that } v_A = -\left(\frac{m_B}{m_A}\right)v_B \quad \text{or} \quad \frac{v_A}{v_B} = -\frac{m_B}{m_A}$$

$$\text{So ratio of kinetic energies is } \frac{\frac{1}{2}m_A v_A^2}{\frac{1}{2}m_B v_B^2} = \frac{m_A}{m_B} \left(\frac{m_B}{m_A}\right)^2 = \frac{m_B}{m_A} = \frac{3}{2}$$

$$\text{Solve } \frac{K_A}{K_B} = \frac{3}{2} \text{ and } K_A + K_B = 20 \text{ J} \rightarrow \begin{aligned} K_A &= 12.0 \text{ J} \\ K_B &= 8.0 \text{ J} \end{aligned}$$

(7)

Q3 (c), cont.

$$\text{Velocity A: } \frac{1}{2} m_A v_A^2 = K_A = 12.0 \text{ J} \rightarrow$$

$$|v_A| = 3.46 \text{ m/s}$$

$$\text{B: } \frac{1}{2} m_B v_B^2 = K_B = 8.00 \text{ J} \rightarrow$$

$$|v_B| = 2.31 \text{ m/s}$$

There's probably a faster way of doing this, without finding K_A & K_B . For instance, just write down conservation of momentum & cons of energy:

$$m_A v_A + m_B v_B = 0$$

$$\frac{1}{2} m_A v_A^2 + \frac{1}{2} m_B v_B^2 = U_i$$

Solve for v_B in first eq, & sub into second:

$$v_B = -\frac{m_A}{m_B} v_A \xrightarrow{\text{sub:}} \left(\frac{1}{2} m_A + \frac{1}{2} m_B \left(\frac{m_A}{m_B} \right)^2 \right) v_A^2 = U_i$$

$$= \frac{1}{2} m_A \left(1 + \frac{m_A}{m_B} \right) = 1.67 \text{ kg}$$

$$\rightarrow \text{gives } |v_A| = 3.46 \text{ m/s}$$

$$\text{Then use } |v_B| = \left| -\frac{m_A}{m_B} v_A \right| \rightarrow |v_B| = 2.31 \text{ m/s}$$

Question asks for "speed", so answers given should be positive.

(Give full credit for answers within 2%.)

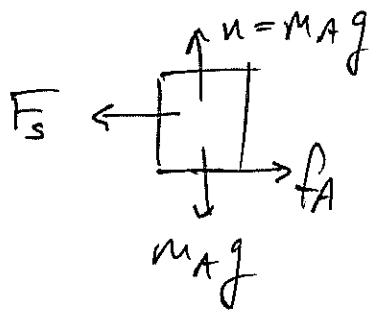
Q3 (A) [10pts]

⑧

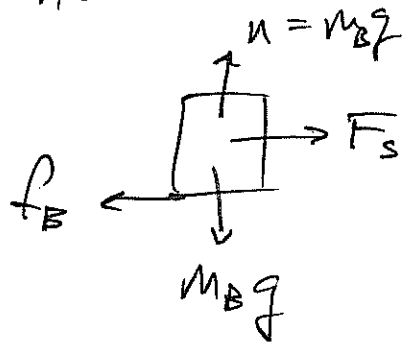
This question is too difficult to solve correctly, with analytics. Principles involved are:

(1) Energy lost from mass + spring system, because friction creates a thermal internal energy $f_k \cdot d$, where d is displacement.

(2) Momentum not conserved because frictional force on B is stronger than frictional force on A.



$$f_A = \mu_k m_A g$$



$$f_B = \mu_k m_B g$$

(9)

Q3(d), cont.

We can say that spring does not expand fully. Compression from part (c) is $\approx 3.65 \text{ m}$. Pushing blocks apart this distance would generate at least

$$fd = (\underbrace{\mu m_A g}_{5.88 \text{ N}})(3.65 \text{ m}) = 21.5 \text{ J}$$

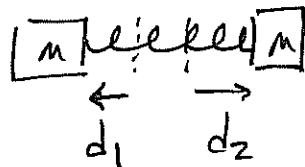
of heat,

which is more than $U_i = 20.0 \text{ J}$. Thus, blocks are still touching spring at final positions.

Q3(d) - cont. (10)

If masses were equal, situation would be simpler because momentum conserved ($=0$).

Then: by symmetry, $d_1 = d_2 \equiv d$



energy lost to heat

In final configuration, $\Delta U = \overbrace{-f(d_1 + d_2)}^{\text{energy lost to heat}} = -2fd$,
 $= U_f - U_i$

and $\Delta U = -U_i + \frac{1}{2}k(x_i + 2d)^2$, where $x_i = -3.65 \text{ m}$

This is a quadratic equation:

$$-\cancel{U_i} + \cancel{\frac{1}{2}kx_i^2} + 2kx_id + 2kd^2 = -2fd$$

$$-d(2kd + 2kx_i + 2f) = 0$$

$d=0$ soln says
 energy conserved
 @ initial condition

$$\hookrightarrow d = -x_i \cdot \frac{-f}{k} = \underline{\underline{1.69 \text{ m}}}$$

(check: $2d = 3.38 \text{ m}$, less than $x_i = 3.65 \text{ m}$
 compression, so assumption valid.)

Lost to heat: $2fd = 19.9 \text{ J}$

Remaining in spring: $\frac{1}{2}k(x_i + 2d)^2 = 0.1 \text{ J}$

|| Almost
 expanded,
 but not quite. ||

Q4 [30 pts]

(11)

[5 pts]

(a) Question states that $x_1 > x_2$, so it means blocks must have slid with respect to one another. But in fact, they must always be sliding, since ~~the~~ the forces are constant & accelerations constant, during the problem.

$$\text{Thus } f = f_k = \mu_k mg$$

This force is equal & opposite between the blocks, but magnitude (asked for) is positive.

[5 pts]

(b) CM moves & accelerates by the net external force, which is just F here.

$$\text{So } a_{cm} = \frac{F}{2m}.$$

Final position of CM is $\frac{x_1 + x_2}{2}$, so

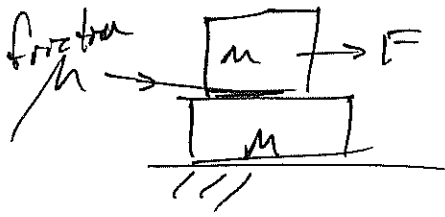
using $v_f^2 - v_i^2 = 2a \Delta x$, we find

$$\boxed{(v_f)_{cm} = \sqrt{\frac{F}{2m} (x_1 + x_2)}}$$

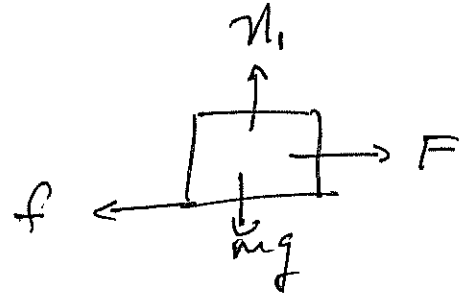
Q4 (2) [10pts]

(2)

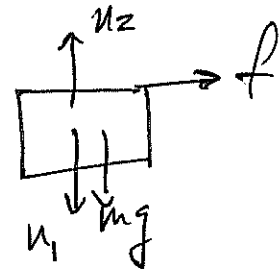
For this part the motion of the individual blocks is required.



top block:



bottom block:



Vertical equilibrium gives $n_1 = mg$, so $f = \mu mg$, as said in part (a).

Horizontal degree of freedom gives

$$x_1 = \frac{1}{2} a_1 t^2 \quad \text{where } m a_1 = F - f$$

$$v_1 = a_1 t \quad \text{so } K_1 = \frac{1}{2} m v_1^2 = \frac{1}{2} m (a_1 t)^2 = m x_1 a_1 = x_1 (F - f)$$

$$x_2 = \frac{1}{2} a_2 t^2 \quad \text{where } M a_2 = f$$

$$v_2 = a_2 t \quad K_2 = \frac{1}{2} M v_2^2 = \dots = M x_2 a_2 = x_2 f$$

So final kinetic energy is

$$K_1 + K_2 = x_1 (F - f) + x_2 f$$

$$= \boxed{x_1 F - f(x_1 - x_2)} \quad \text{where } f = \mu mg$$

Q4 (d) [10 pts]

How much work is lost to heat?

$$\text{External work} = F \cdot x_1$$

Change in system energy is

$$\Delta E = \underbrace{\Delta K}_{\parallel Fx_1} + \underbrace{\Delta U}_0 + \underbrace{\Delta E_{\text{int}}}_{\text{must be } f(x_1 - x_2)}$$

to conserve energy!

$$\rightarrow \boxed{\Delta E_{\text{int}} = f(x_1 - x_2)}$$

Note that $W \neq F \cdot \Delta x_{\text{cm}}$, but rather $F \cdot x_1$, because displacement at point of application is what counts.

④4, cont. ALTERNATE⁽¹⁴⁾ SOLN TO PART (B):

$$\begin{aligned} X_1 + X_2 &= \frac{1}{2} q_1 t^2 + \frac{1}{2} q_2 t^2 \\ &= \frac{1}{2} \frac{F-f}{m} t^2 + \frac{1}{2} \frac{f}{m} t^2 \\ &= \frac{F}{2m} t^2 \end{aligned}$$

$$\text{So } X_{cm} = \frac{X_1 + X_2}{2} = \frac{1}{2} \left(\frac{F}{2m} \right) t^2$$

$$V_{cm} = \frac{d}{dt} X_{cm} = \left(\frac{F}{2m} \right) t$$

But we were asked to write answer in terms of X_1 , X_2 , etc., ... not t . This can be written in several ways:

$$t^2 = \frac{2X_1}{q_1} = \frac{2X_1}{F-f} m \quad \text{using } X_1(t)$$

$$t^2 = \frac{2X_2}{q_2} = \frac{2X_2}{f} m \quad \text{using } X_2(t)$$

$$t^2 = \frac{2X_{cm}}{q_{cm}} = (X_1 + X_2) \left(\frac{2m}{F} \right) \quad \text{using } X_{cm}$$

In the answer I gave for (b), this last form was used because it showed independence of f, m, g, \dots

$$t = \sqrt{(X_1 + X_2) \frac{2m}{F}}$$

$$\text{so } V_{cm} = \frac{F}{2m} t = \sqrt{\frac{F}{2m} (X_1 + X_2)} \quad \text{as before.}$$

However, any correct form gets full credit.