

TERM TEST SOLUTIONS

Q18 FIND A POINT ON EACH PLANE

$$P_1 \text{ ON } ax+by+cz=d_1$$

$$(x_1, y_1, \frac{d_1 - ax_1 - by_1}{c})$$

$$P_2 \text{ ON } ax+by+cz=d_2$$

$$(x_1, y_1, \frac{d_2 - ax_1 - by_1}{c})$$

FIND $\vec{P_1 P_2}$

$$\vec{P_1 P_2} = \begin{bmatrix} 0 \\ 0 \\ \frac{d_2 - ax_1 - by_1}{c} - \frac{d_1 - ax_1 - by_1}{c} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \frac{d_2 - d_1}{c} \end{bmatrix}$$

$|\text{proj}_{\vec{n}} \vec{P_1 P_2}|$ IS THE SHORTEST DISTANCE

BETWEEN THE TWO PLANES WHERE $\vec{n} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$

$$|\text{proj}_{\vec{n}} \vec{P_1 P_2}| = \frac{|\vec{P_1 P_2} \cdot \vec{n}|}{\|\vec{n}\|}$$

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$$\vec{P_1 P_2} \cdot \vec{n} = d_2 - d_1$$

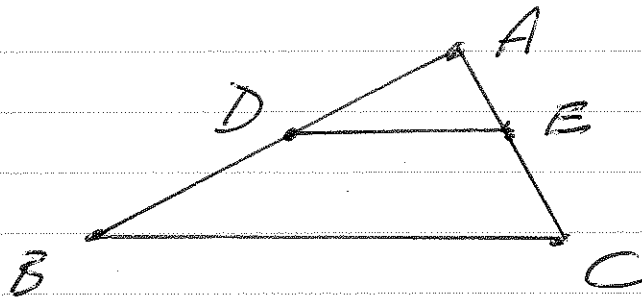
$$\|\vec{n}\| = \sqrt{a^2 + b^2 + c^2}$$

∴ SHORTEST DISTANCE BETWEEN THE TWO

$$\text{PLANES IS } \frac{|d_2 - d_1|}{\sqrt{a^2 + b^2 + c^2}}$$

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Q2:



GIVEN INFORMATION:

$$2 \vec{DA} = \vec{BA}$$

$$\therefore \vec{DA} = \frac{1}{2} \vec{BA}$$

And

$$2 \vec{EA} = \vec{CA}$$

$$\vec{EA} = \frac{1}{2} \vec{CA}$$

BY VECTOR ADDITION:

$$\vec{ED} = \vec{EA} + \vec{AD} = \frac{1}{2} \vec{CA} - \frac{1}{2} \vec{BA} = \frac{1}{2} (\vec{CA} - \vec{BA})$$

$$\vec{CB} = \vec{CA} + \vec{AB} = \vec{CA} - \vec{BA}$$

$$\therefore \vec{ED} = \frac{1}{2} \vec{CB}$$

\therefore LINE SEGMENT DE IS PARALLEL TO BC
AND IS HALF AS LONG.

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Q3:

AUGMENTED MATRIX:

$$\left[\begin{array}{ccc|c} 1 & 2 & -4 & 4 \\ 3 & -1 & 13 & 2 \\ 4 & 1 & a^2 & a+3 \end{array} \right]$$

$$\begin{array}{l} R_2 - 3R_1 \\ R_3 - 4R_1 \end{array} \left[\begin{array}{ccc|c} 1 & 2 & -4 & 4 \\ 0 & -7 & 25 & -10 \\ 0 & -7 & a^2+16 & a+3-16 \end{array} \right]$$

$$R_2 \div (-7) \left[\begin{array}{ccc|c} 1 & 2 & -4 & 4 \\ 0 & 1 & -25/7 & 10/7 \\ 0 & -7 & a^2+16 & a-13 \end{array} \right]$$

$$R_3 + 7R_2 \left[\begin{array}{ccc|c} 1 & 2 & -4 & 4 \\ 0 & 1 & -25/7 & 10/7 \\ 0 & 0 & a^2-9 & a-3 \end{array} \right]$$

WE CAN STOP HERE AND EXAMINE
THE LAST ROW.

FOR INFINITE SOLUTIONS (AT LEAST ONE FREE VARIABLE):

$$a^2 - 9 = 0 \text{ AND } a - 3 = 0$$

$$a^2 = 9 \text{ AND } a = 3$$

$$\therefore a = 3$$

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FOR UNIQUE SOLUTION (ALL VARIABLES LEADING) :

$$a^2 - 9 \neq 0$$

$$a^2 \neq 9$$

$$\therefore a \neq 3, -3$$

FOR NO SOLUTION (LAST ROW $[0 \ 0 \ 0 \ | \ *]$) :

$$a^2 - 9 = 0 \text{ AND } a - 3 \neq 0$$

$$a^2 = 9 \text{ AND } a \neq 3$$

$$\therefore a = -3$$

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Q4:

ASSUME $PQ = QP$

$$\begin{aligned}(P+Q)^2 &= (P+Q)(P+Q) \\&= P^2 + PQ + QP + Q^2 \\&= P^2 + PQ + PQ + Q^2 \\&= P^2 + 2PQ + Q^2 \quad \text{AS DESIRED}\end{aligned}$$

ASSUME $(P+Q)^2 = P^2 + 2PQ + Q^2$

$$P^2 + PQ + QP + Q^2 = P^2 + 2PQ + Q^2$$

$$PQ + QP = 2PQ$$

$$QP = 2PQ - PQ$$

$$QP = PQ \quad \text{AS DESIRED}$$

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Q5:

$$a) \quad \vec{u} = \begin{bmatrix} x \\ y \end{bmatrix} \quad T(\vec{u}) = \begin{bmatrix} x+2y \\ xy \end{bmatrix}$$

CHECK PROPERTY a)

$$\begin{aligned} T(k\vec{u}) &= T\left(\begin{bmatrix} kx \\ ky \end{bmatrix}\right) = \begin{bmatrix} kx+2ky \\ k^2xy \end{bmatrix} \\ &\neq k \begin{bmatrix} x+2y \\ xy \end{bmatrix} \end{aligned}$$

∴ T IS NOT A LINEAR TRANSFORMATION.

$$b) \quad D\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} x+y \\ x-2y \\ x \end{bmatrix}$$

IF D IS A LINEAR TRANSFORMATION, WE CAN FIND MATRIX M_D SUCH THAT:

$$\begin{bmatrix} x+y \\ x-2y \\ x \end{bmatrix} = M_D \begin{bmatrix} x \\ y \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 \\ 1 & -2 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

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$$80 \quad M_D = \begin{bmatrix} 1 & 1 \\ 1 & -2 \\ 1 & 0 \end{bmatrix}$$

$$c) \quad E\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = \begin{bmatrix} x \\ x+y+z \\ 2x+y+z \end{bmatrix}$$

IF E IS A LINEAR TRANSFORMATION, WE CAN FIND MATRIX M_E SUCH THAT:

$$\begin{bmatrix} x \\ x+y+z \\ 2x+y+z \end{bmatrix} = M_E \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 2 & 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$$80 \quad M_E = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 2 & 1 & 1 \end{bmatrix}$$

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c)

$$E(D\left(\begin{bmatrix} x \\ y \end{bmatrix}\right)) = M_E M_D \begin{bmatrix} x \\ y \end{bmatrix}$$

$\begin{matrix} \nearrow & \nearrow & \nearrow \\ 3 \times 3 & 3 \times 2 & 2 \times 1 \end{matrix}$

⊗ COMPOSITION IS DEFINED.

$$M_E M_D = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 2 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -2 \\ 1 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 \\ 3 & -1 \\ 4 & 0 \end{bmatrix}$$

$$E(E\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right)) = M_E M_E \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$\begin{matrix} \nearrow & \nearrow & \nearrow \\ 3 \times 3 & 3 \times 3 & 3 \times 1 \end{matrix}$

⊗ COMPOSITION IS DEFINED.

$$M_E M_E = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 2 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 2 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 4 & 2 & 2 \\ 5 & 2 & 2 \end{bmatrix}$$

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Q6⁹⁸

A IS $n \times n$ WITH DISTINCT EIGENVALUES $\lambda_1, \lambda_2, \dots, \lambda_n$

a) k IS A POSITIVE INTEGER

∞ A^k IS ALSO AN $n \times n$ MATRIX

∞ A^k HAS n EIGENVALUES.

b) EIGENVALUES OF A SATISFY:

$$A\vec{u} = \lambda\vec{u}$$

$$\infty A^2\vec{u} = A\lambda\vec{u} = \lambda A\vec{u} = \lambda^2\vec{u}$$

$$A^3\vec{u} = A\lambda^2\vec{u} = \lambda^2 A\vec{u} = \lambda^3\vec{u}$$

$$\vdots$$
$$A^k\vec{u} = \lambda^k\vec{u}$$

∞ A^k HAS EIGENVALUES $\lambda_1^k, \lambda_2^k, \dots, \lambda_n^k$.