tags:

- Machine Learning
- Hands on ML book

Chapter 4 - Hands on

- This chapter dives into how machine learning models work under the hood. It covers:
 - Linear Regression using closed-form solutions and Gradient Descent (plus its variants).
 - Polynomial Regression, overfitting, and how to prevent it with learning curves and regularization.
 - Logistic and Softmax Regression for classification tasks.

Linear Regression

- What is Linear Regression?
 - It's a model that predicts an output by computing a weighted sum of input features, plus a bias (intercept).
 - The general form is:

$$\hat{\mathbf{y}} = \mathbf{\theta}_0 + \mathbf{\theta}_1 \mathbf{x}_1 + \mathbf{\theta}_2 \mathbf{x}_2 + \dots + \mathbf{\theta}_n \mathbf{x}_n$$

In vector form:

$$\hat{\mathbf{y}} = \mathbf{\theta}^{\mathsf{T}} \cdot \mathbf{x}$$

- (where θ is the vector of parameters, and x is the vector of input features including a 1 for the bias term)
- How Do We Train It?
 - We adjust θ (the model's parameters) to best fit the training data.
 - To measure how well it fits, we use **Mean Squared Error (MSE)** as the cost/loss function: $\text{MSE}(\theta) = \frac{1}{m} \sum_{i=1}^m (\theta^T x^{(i)} y^{(i)})^2$
 - This helps us find the values of θ that minimize prediction errors.
- Training loss (like MSE) is optimized during training.
- Evaluation metrics (like precision/recall) may differ from training loss, especially for classifiers.
- Good loss functions are easy to optimize and correlate with real-world goals.

The Normal Equation

- What is the Normal Equation?
 - It's a **direct formula** to compute the best parameters θ that minimize the MSE (no iteration needed): $\hat{\theta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T y$
- How It Works:
 - 1. Generate training data with some noise:

$$y = 4 + 3x +$$
noise

- 2. Add a column of 1s to X (to handle the bias term).
- 3. Use NumPy to compute **0** directly using matrix operations.
- 4. Predictions are made by multiplying new input data by the computed **0**.
- Example Results:
 - The true parameters were 4 and 3.
 - The model estimated them as 4.215 and 2.770 close, but slightly off due to noise.
- Using Scikit-Learn:
 - You can use LinearRegression() from scikit-learn to do the same thing with .fit()
 and .predict().
 - It separates the intercept_ (bias) and coef_ (feature weights).
- Pseudoinverse Alternative:
 - Instead of using the Normal Equation, you can use the pseudoinverse:

$$\hat{\theta} = X^+ y$$

- Computed using np.linalg.pinv(X)
- More stable and handles edge cases where X^TX is not invertible (e.g., redundant features or too few data points).
- Normal Equation is a fast, direct way to compute parameters for linear regression.
- Pseudoinverse is more robust and always works, even when the Normal Equation fails.
- Libraries like scikit-learn and NumPy make it easy to use both.

Computational Complexity

- Normal Equation & SVD Complexity:
 - Normal Equation has a complexity of about O(n².⁴) to O(n³) → gets slow with many features.
 - SVD (used by Scikit-Learn) is about $O(n^2) \rightarrow \text{still slow when } n \text{ (features)}$ is very large.
 - Both handle large datasets (many rows, m) well, since they are linear in m: O(m).
- Prediction Time:
 - Once the model is trained, making predictions is very fast.
 - Time grows linearly with the number of instances and features.

Gradient Descent

- What is Gradient Descent?
 - An **optimization algorithm** that finds the best model parameters (like θ) by minimizing a **cost function** (e.g., MSE).
 - It does this by iteratively moving in the direction of the steepest slope (i.e., negative gradient).
- How It Works:
 - 1. **Start** with random parameter values (random initialization).
 - 2. Repeatedly **adjust parameters** to reduce the cost.
 - 3. **Stop when** the gradient becomes zero \rightarrow minimum reached.
- Learning Rate (Step Size):
 - Too small → slow convergence (takes many steps).
 - Too large → may overshoot or diverge (never settles).
 - Must choose a balanced learning rate!
- hallenges:
 - Some cost functions can have plateaus, local minima, or complex shapes.
 - BUT for linear regression, the MSE cost function is:
 - Convex (no local minima)
 - Smooth (no sharp changes)
 - So, gradient descent is guaranteed to find the global minimum eventually.
- Feature Scaling:
 - If features have different scales, gradient descent:
 - Takes weird zigzag paths,
 - Converges very slowly.
 - Use tools like StandardScaler to normalize feature scales.

Batch Gradient Descent

- What is Batch Gradient Descent?
 - Batch Gradient Descent is an optimization algorithm used to minimize the cost function (like MSE in linear regression) by adjusting model parameters θ\thetaθ.
- Key Concepts
 - 1. Cost Function (MSE)

Measures how bad the model's predictions are: $ext{MSE}(heta) = rac{1}{m} \sum_{i=1}^m (\hat{y}^{(i)} - y^{(i)})^2$

2. Gradient (Slope Vector)

Tells you how to tweak θ to reduce the error. It's the vector of **partial derivatives** of the cost function with respect to each parameter θ_i .

manual for each paramete :

$$rac{\partial}{\partial heta_j} ext{MSE}(heta) = rac{2}{m} \sum_{i=1}^m (heta^ op \mathbf{x}^{(i)} - y^{(i)}) x_j^{(i)}$$

vectorized for all parameters :

$$abla_{ heta} ext{MSE}(heta) = rac{2}{m} extbf{X}^ op (extbf{X} heta - extbf{y})$$

3. Gradient Descent Update Rule

Use the gradient to update θ by taking a step **opposite the slope**:

$$\theta := \theta - \eta \cdot \nabla_{\theta} MSE(\theta)$$

- η = learning rate (step size)
- 4. Code :-

```
eta = 0.1  # learning rate
n_epochs = 1000  # number of passes over the dataset
m = len(X_b)  # number of samples

theta = np.random.randn(2, 1)  # random initialization

for epoch in range(n_epochs):
    gradients = 2 / m * X_b.T @ (X_b @ theta - y)
    theta = theta - eta * gradients
```

- Learning Rate Matters
 - Too small → very slow convergence
 - Just right → fast and stable
 - Too large → divergence (jumps around, doesn't settle)
- 6. When to Stop?
 - Set a max number of epochs, or
 - Stop early when the gradient becomes very small (i.e., close to minimum)
- 7. Convergence
 - Gradient descent will converge for convex functions like MSE
 - The convergence speed depends on the **learning rate** and **tolerance** ϵ

Stochastic Gradient Descent

- What is SGD?
 - Unlike Batch Gradient Descent (which uses the whole dataset per step), SGD uses only one random data point per update.

This makes each step much faster and allows training on very large datasets.

Pros and Cons

- pros
 - Faster updates
 - Can escape local minima
 - Scalable to huge datasets
- Cons
 - More noisy (bouncy) path to minimum
 - Doesn't settle exactly at the minimum
 - May require careful tuning of learning rate

Epochs and Iterations

- One **epoch** = one full pass through the dataset.
- Each epoch consists of m updates (one per training example).
- If random sampling is used, some examples might be picked multiple times or not at all in one epoch.

Learning Rate Schedule

- To reduce noise and allow convergence, learning rate should shrink over time.
- This is done using a learning schedule, e.g.:

```
def learning_schedule(t):
    return t0 / (t + t1)
```

• Starts with larger steps (fast progress), then gets smaller (finer tuning).

Important Considerations

- Data must be IID (independent and identically distributed) shuffle it!
- If data is ordered (e.g., by label), SGD can behave badly.

SGD in Code

```
for epoch in range(n_epochs):
    for iteration in range(m): # m training instances
        random_index = np.random.randint(m)
        xi = X_b[random_index : random_index + 1]
        yi = y[random_index : random_index + 1]
        gradients = 2 * xi.T @ (xi @ theta - yi)
        eta = learning_schedule(epoch * m + iteration)
        theta = theta - eta * gradients
```

Scikit-Learn's SGDRegressor

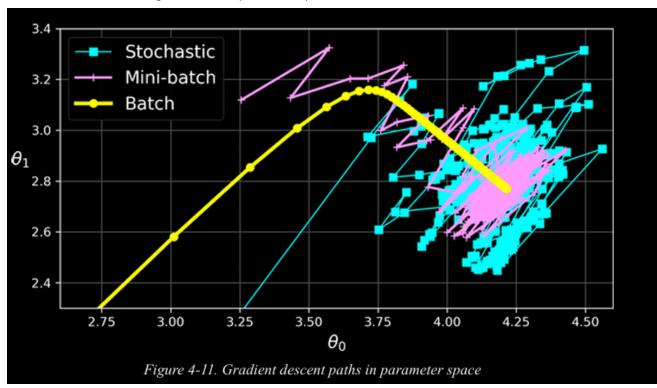
```
from sklearn.linear_model import SGDRegressor
sgd_reg = SGDRegressor(
    max_iter=1000, tol=1e-5, eta0=0.01, penalty=None,
    n_iter_no_change=100, random_state=42
)
sgd_reg.fit(X, y.ravel())
```

Mini-Batch Gradient Descent

- Mini-batch Gradient Descent (MBGD) is a hybrid between:
 - Batch GD: Uses the whole dataset per step (slow but stable).
 - Stochastic GD (SGD): Uses 1 sample per step (fast but noisy).
- MBGD uses small random batches of data (e.g. 32 or 64 samples).
- Advantages
 - Faster than Batch GD.
 - Less noisy than SGD.
 - Can benefit from hardware acceleration (like GPUs).
 - Works well with large datasets.

Disadvantages

- Still bounces around the minimum (but less than SGD).
- Might get stuck in local minima (especially for non-convex problems).
- Needs a learning schedule (like SGD).



- Batch GD: smooth, direct to the minimum, stops there.
- Stochastic GD: very noisy path, keeps bouncing.
- Mini-batch GD: less noisy than SGD, ends near the minimum.

| Algorithm | Large m | Out-of-core support | Large n | Hyperparams | Scaling required | Scikit-Learn |
|-----------------|---------|---------------------|---------|-------------|------------------|------------------|
| Normal Equation | Fast | No | Slow | 0 | No | n/a |
| SVD | Fast | No | Slow | 0 | No | LinearRegression |
| Batch GD | Slow | No | Fast | 2 | Yes | SGDRegressor |
| Stochastic GD | Fast | Yes | Fast | ≥2 | Yes | SGDRegressor |
| Mini-batch GD | Fast | Yes | Fast | ≥2 | Yes | SGDRegressor |

Polynomial Regression

- Polynomial Regression Overview
 - Goal: Fit nonlinear data using a linear model.
 - How: Add powers of features (e.g. x^2, x^3 , etc.) as new features, then apply linear regression.
- Example Process:
 - 1. Generate nonlinear data:

•
$$y = 0.5x^2 + x + 2 + noise$$

2. Use PolynomialFeatures from sklearn:

```
from sklearn.preprocessing import PolynomialFeatures
poly_features = PolynomialFeatures(degree=2, include_bias=False)
X_poly = poly_features.fit_transform(X)
```

- Turns [x] into $[x, x^2]$
- 3. Train Linear Regression on transformed data:

```
from sklearn.linear_model import LinearRegression
lin_reg = LinearRegression()
lin_reg.fit(X_poly, y)
```

Model Output Example:

The model learns:

$$\hat{y} = 0.56x^2 + 0.93x + 1.78$$

Close to the original:

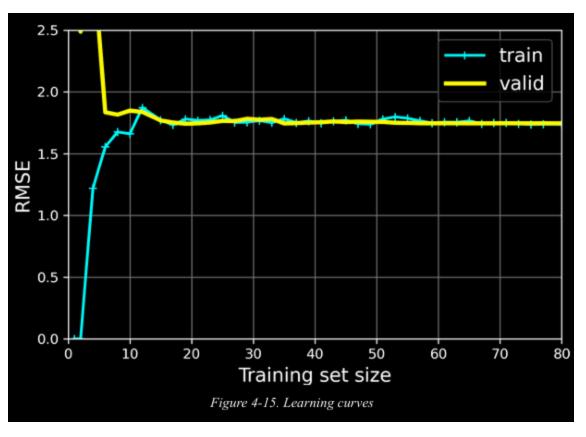
$$\hat{y}=0.5x^2+1x+2+noise$$

- Key Points:
 - Polynomial regression ≠ nonlinear model it's still linear in parameters.
 - When multiple features are present, **interactions** (e.g., ab, a^2b) are added automatically.
 - Warning: With high degree ddd and many features nnn, the number of features grows combinatorially:

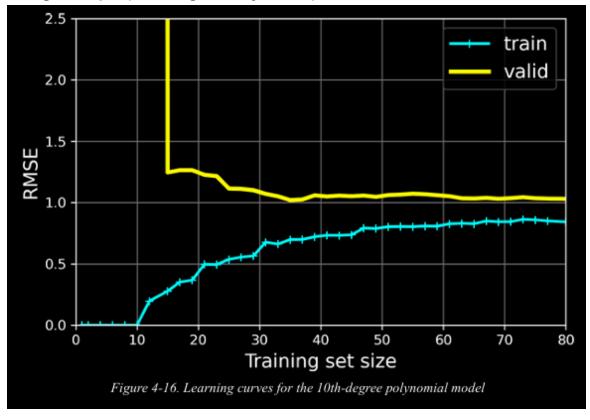
Features =
$$\frac{(n+d)!}{d! \cdot n!}$$

Learning Curves

- What Are They?
 - Plots of: Training error and Validation error vs. Training set size.
 - Help diagnose:
 - **Underfitting** (high bias)
 - Overfitting (high variance)
- Key Observations
 - Underfitting Example (Linear Model):



- Training error: Starts low (small data) then rises and plateaus
- Validation error: Starts high, decreases, then plateaus near training error
- → Both errors high & close = Model too simple (high bias)
- Overfitting Example (10th-degree Polynomial):



• Training error: Very low

- Validation error: Higher and doesn't match training error
- → Big gap between curves = Model too complex (high variance)
- Can often fix with more training data

Tips:

- Underfitting? → Try a more complex model or better features
- Overfitting? → Try regularization or add more data
- Irreducible error? → Clean up your dataset

Regularized Linear Models

- Regularization helps reduce overfitting by limiting model complexity.
- For polynomial models, reduce the degree.
- For linear models, constrain the weights using:
 - 1. Ridge Regression (L2) Shrinks all weights.
 - Lasso Regression (L1) Shrinks some weights to zero (feature selection).
 - 3. **Elastic Net** Mix of L1 and L2 regularization.

Ridge Regression

- What Is Ridge Regression?
 - Ridge Regression (aka Tikhonov regularization) is Linear Regression + L2 regularization.
 - The goal: Fit the data while keeping model weights small, reducing overfitting.

Cost Function

- $J(\theta) = \mathrm{MSE}(\theta) + \frac{\alpha}{m} \sum_{i=1}^{n} \theta_i^2$
- Adds a **penalty** for large weights.
- Bias term θ_0 is **not** regularized.
- α controls regularization strength:
 - $\alpha = 0 \rightarrow \text{plain Linear Regression}$.
 - Large $\alpha \rightarrow$ very flat model.

Important: Always Scale Your Features

 Use StandardScaler before applying Ridge. Regularization is sensitive to feature scales.

Intuition

- High α \alpha $\alpha \rightarrow$ simple, flat predictions \rightarrow low variance, high bias.
- Low $\alpha \cdot alpha\alpha \rightarrow more flexible model \rightarrow low bias, high variance.$
- This helps manage the bias-variance trade-off.
- How To Use Ridge in Scikit-Learn

1. Closed-form (exact solution):

```
from sklearn.linear_model import Ridge
ridge_reg = Ridge(alpha=0.1, solver="cholesky")
ridge_reg.fit(X, y)
ridge_reg.predict([[1.5]])
```

2. Using Stochastic Gradient Descent (SGD):

- Extra Tip: Automatic Tuning
 - Use RidgeCV for **automatic** α **tuning** with cross-validation:

```
from sklearn.linear_model import RidgeCV ridge_cv = RidgeCV(alphas=[0.01,
0.1, 1.0, 10.0])
ridge_cv.fit(X, y)
```

Lasso Regression

- What is Lasso Regression?
 - Lasso stands for Least Absolute Shrinkage and Selection Operator.
 - It's a regularized version of linear regression that adds an ℓ₁ (absolute value)
 penalty to the cost function.
- Cost Function:

$$J(heta) = ext{MSE}(heta) + 2lpha \sum_{i=1}^n | heta_i|$$

- ℓ_1 norm = sum of absolute values of the weights (no squares like Ridge).
- This encourages some weights to become exactly zero → feature selection!
- Effect of Lasso:
 - Can zero out unimportant features, making the model sparse and easier to interpret.
 - Increasing α increases regularization (more weights shrink to zero).
 - Decreasing α moves the solution toward plain linear regression (no regularization).
- Gradient and Subgradient:

- Lasso's cost function is **not differentiable at \theta = 0**.
- Gradient descent uses a subgradient instead:
 - sign(θ_i) is used: returns -1, 0, or 1 based on the sign of each θ.
- You can also use SGDRegressor(penalty="l1") to perform lasso-style training with SGD.
- Scikit-Learn Example:

```
from sklearn.linear_model import Lasso

lasso_reg = Lasso(alpha=0.1)
lasso_reg.fit(X, y)
lasso_reg.predict([[1.5]])
# Output: array([1.53788174])
```

Elastic Net Regression

- What is Elastic Net?
 - Elastic Net combines both Ridge (ℓ_2) and Lasso (ℓ_1) penalties.
 - It's a weighted average of Ridge and Lasso regularization.
- Cost Function:

```
J(\theta) = MSE(\theta) + r \cdot (2\alpha \sum |\theta i|) + (1-r) \cdot (\frac{\alpha}{m} \sum \theta i^2)
• \mathbf{r} = \mathbf{0}: behaves like Ridge
• \mathbf{r} = \mathbf{1}: behaves like Lasso
```

- When to Use Elastic Net?
 - Use regularization in general (avoid plain linear regression).
 - Ridge is a good default.
 - Use Lasso/Elastic Net if you believe:
 - Only a few features are important
 - You want automatic feature selection
 - Prefer Elastic Net over Lasso when:
 - You have more features than samples
 - Some features are highly correlated
- Scikit-Learn Example:

```
from sklearn.linear_model import ElasticNet

elastic_net = ElasticNet(alpha=0.1, l1_ratio=0.5) # l1_ratio = r
elastic_net.fit(X, y)
```

```
elastic_net.predict([[1.5]])
# Output: array([1.54333232])
```

Early Stopping

- What is Early Stopping?
 - A regularization technique for iterative learning (like gradient descent).
 - You stop training when the validation error stops improving.
 - Helps prevent overfitting by not overtraining the model.
 - Called a "beautiful free lunch" by Geoffrey Hinton because it's simple yet powerful.
- How It Works (Conceptually)
 - During training:
 - Training error keeps going down.
 - Validation error goes down, then up (indicating overfitting).
 - Early stopping halts training at the lowest validation error, before overfitting begins.
- Code
 - 1. Data Prep

2. Model Setup

```
sgd_reg = SGDRegressor(penalty=None, eta0=0.002, random_state=42)
```

- Uses Stochastic Gradient Descent (SGD).
- No regularization (penalty=None).
- Small learning rate eta0=0.002.
- 3. Training with Early Stopping

```
from copy import deepcopy
n_epochs = 500
best_valid_rmse = float('inf') # start with the worst possible error
```

```
for epoch in range(n_epochs):
    sgd_reg.partial_fit(X_train_prep, y_train) # train one step
    y_valid_predict = sgd_reg.predict(X_valid_prep)
    val_error = mean_squared_error(y_valid, y_valid_predict,
    squared=False) # RMSE

if val_error < best_valid_rmse: # if new best
    best_valid_rmse = val_error
    best_model = deepcopy(sgd_reg) # save current model</pre>
```

Logistic Regression

- A classification algorithm (despite its name).
- Predicts the probability an instance belongs to class 1 (positive class).
- If probability > 50%, it predicts 1, else 0 (negative class).
- Used for binary classification problems (e.g., spam detection).

Estimating Probabilities

· Logistic regression computes:

$$\hat{p} = \sigma(heta^T \mathbf{x})$$
 where $\sigma(t) = rac{1}{1+e^{-t}}$ is the sigmoid function.

- Output is a probability between 0 and 1.
- Prediction rule:
 - If $\hat{p} \ge 0.5$, predict class **1**.
 - If \hat{p} < 0.5, predict class **0**.

Training and Cost Function

- Train the model so that:
 - High probabilities for positive class (y = 1)
 - Low probabilities for negative class (y = 0)
- Single Instance Cost

$$ext{Cost} = egin{cases} -\log(\hat{p}) & ext{if } y=1 \ -\log(1-\hat{p}) & ext{if } y=0 \end{cases}$$

Total Cost (Log Loss)

$$J(heta) = -rac{1}{m} \sum_{i=1}^m \left[y^{(i)} \log(\hat{p}^{(i)}) + (1-y^{(i)}) \log(1-\hat{p}^{(i)})
ight]$$

- Called log loss, and it's convex, so Gradient Descent can find the global minimum.
- Gradient

$$rac{\partial J(heta)}{\partial heta_j} = rac{1}{m} \sum_{i=1}^m \Big(\sigma(heta^ op \mathbf{x}^{(i)}) - y^{(i)} \Big) x_j^{(i)}$$

- Same idea as linear regression: error × feature → average over all samples.
- Used in batch, stochastic, or mini-batch Gradient Descent to update weights.

Decision Boundaries

- Dataset Used: Iris Dataset
 - 150 iris flowers, 3 species: Setosa, Versicolor, Virginica
 - Features: sepal/petal length and width
- Goal:
 - Classify whether a flower is Iris Virginica based on petal width.
- Steps:
 - 1. Load data using load_iris()
 - Use only petal width as input feature
 - 3. Create binary labels:

- 4. **Split data** → Train/Test
- 5. **Train** logistic regression model with fit()
- Predict probabilities with predict_proba()
- Decision Boundary:
 - Model predicts Virginica if probability ≥ 0.5
 - This creates a threshold (decision boundary) at ~1.65 cm
 - If petal width > 1.65 cm → Virginica, else not

Softmax Regression

- Softmax Regression is a generalization of logistic regression that works for multiple classes directly no need to train separate binary classifiers.
- How It Works (Prediction)

- 1. For an input x, the model calculates a **score** for each class:
 - $s_k(\mathbf{x}) = \theta^{(k) op} \mathbf{x}$,Each class has its own weight vector $\theta^{(k)}$
- 2. It then applies the **softmax function** to convert these scores into **probabilities**:

$$\hat{p}_k = rac{e^{s_k}}{\sum_{j=1}^K e^{s_j}}$$

- K is the number of classes.
- The output is a probability distribution over the classes.
- 3. It **predicts** the class with the **highest probability**: $\hat{y} = \arg\max_{k} \hat{p}_{k}$ (predicted class)
- Training the Model
 - The model is trained to **maximize the probability** of the correct class.
 - It uses the cross-entropy loss function:

$$J(\Theta) = -rac{1}{m} \sum_{i=1}^{m} \sum_{k=1}^{K} y_k^{(i)} \log(\hat{p}_k^{(i)})$$

- $y_k^{(i)}$ =1 if example i belongs to class k, else 0.
- This function penalizes the model when it assigns low probability to the correct class.
- When K=2, this reduces to the familiar **log loss** used in binary logistic regression.
- Key Tip
 - Softmax is good for **mutually exclusive classes** (e.g., flower types), but **not** for multilabel problems (like detecting multiple objects in one image).
- Cross Entropy in Machine Learning
 - Used as the loss function for classification tasks.
 - Penalizes wrong class probability predictions.
 - Especially common in softmax regression and neural networks.
- Gradient of Cross Entropy
 - Helps in training the model using gradient descent:

$$abla_{ heta^{(k)}}J(\Theta) = rac{1}{m}\sum_{i=1}^m \Big(\hat{p}_k^{(i)} - y_k^{(i)}\Big)\mathbf{x}^{(i)}$$

- Compute gradient per class → update weights → repeat.
- Softmax Regression with Scikit-Learn
 - Automatically used when there are more than 2 classes.
 - Uses LogisticRegression with solver="lbfgs" (default).
 - Regularized using L2 by default (controlled by C).
 - Example: Classify Iris Flowers

```
X = iris.data[["petal length (cm)", "petal width (cm)"]].values
y = iris["target"]
X_train, X_test, y_train, y_test = train_test_split(X, y,
random_state=42)
softmax_reg = LogisticRegression(C=30, random_state=42)
softmax_reg.fit(X_train, y_train)
```

Prediction Example:

```
softmax_reg.predict([[5, 2]]) # → array([2])
softmax_reg.predict_proba([[5, 2]]) # → [[0. , 0.04, 0.96]]
```

Visualization

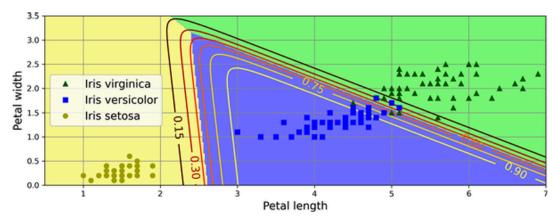


Figure 4-25. Softmax regression decision boundaries

- Softmax regression creates linear decision boundaries between classes.
- Curved lines represent equal probability contours.
- At the center where all three classes meet → model gives ~33% to each class.

Resources:

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Related notes:

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References:

- Internal:
 - •
 - •
 - .
- External :
- notebook of the chapter
- <u>hegab videos</u>
- the book