



# Plasma Surrogate Modelling using Fourier Neural Operators

IAEA Workshop on AI for Accelerating Fusion and Plasma Science

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Vignesh Gopakumar

# Acknowledgements

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Matt Kusner (UCL)



PRINCETON  
UNIVERSITY

Caltech



# Why do we need surrogate modelling ?



Computational  
Complexity



Latency

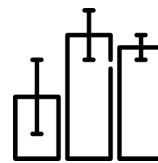


Unknown unknowns

# What does surrogate modelling offer ?



Neighbourhood  
Approximations



Uncertainty  
Quantification



Speed

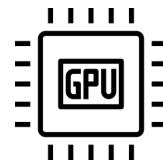
# Why are we using surrogate modelling now ?



Models



Big Data



Hardware



API

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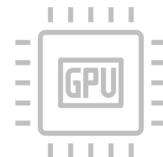
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Models



Big Data



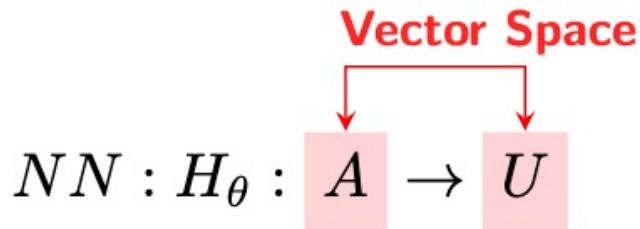
Hardware



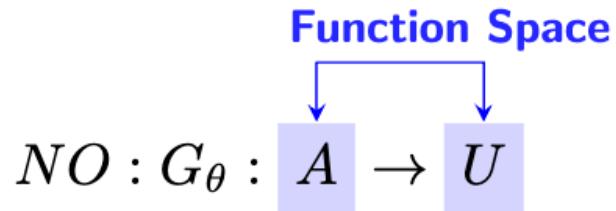
API

# Neural Operators: Operator Learning using Neural Networks

Traditional Neural Networks (MLPs, CNNs, RNNs ...) map from the **input vector space** to the **output vector space**, **learning the function** that performs the required transformation.



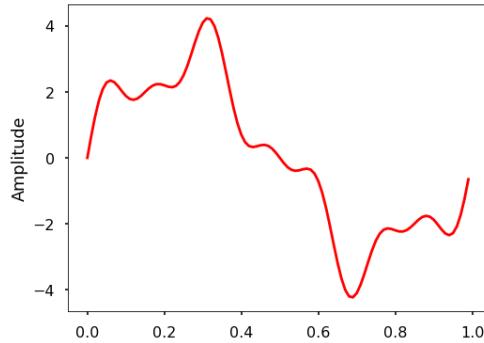
Neural Operators map the **input function space** to the **output function space**, **learning the operator** that performs the function transformation.



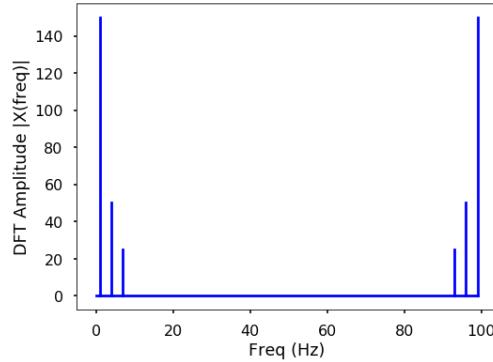
# Neural Operators: Operator Learning using Neural Networks

But learning in the function space means learning the continuous operators ?  
 How does one do that numerically ?

## \*\*Basis Functions\*\*

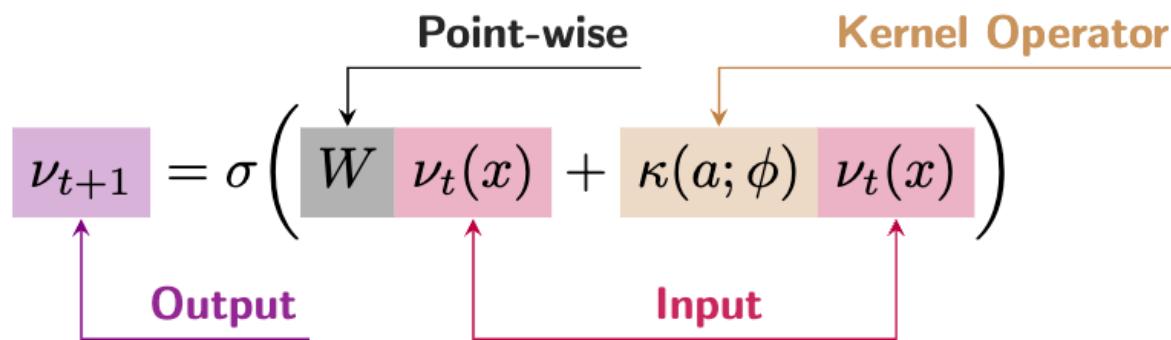
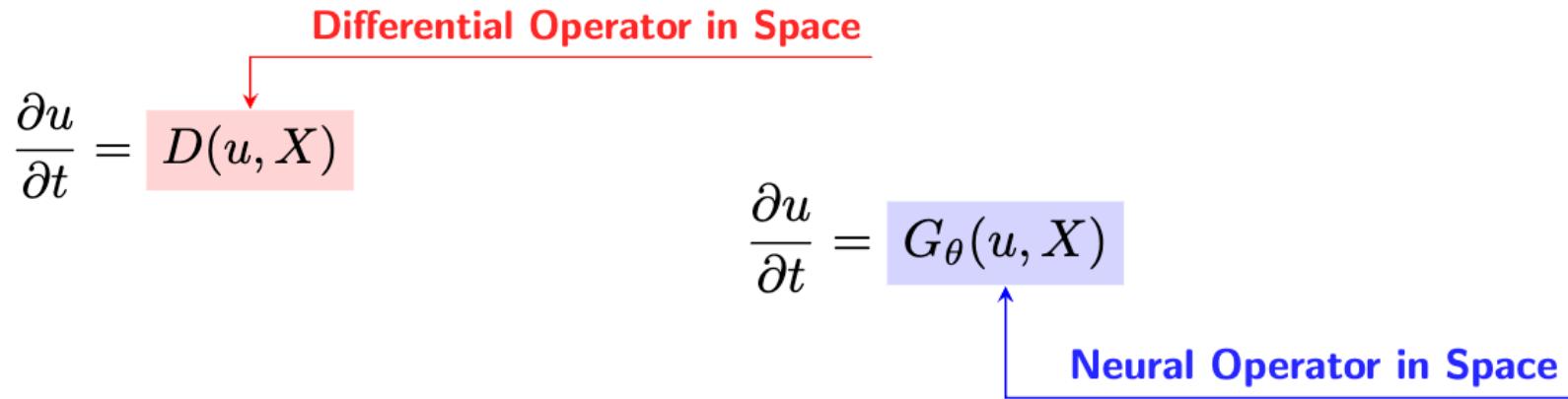


Change of Basis →



Network is composed of **Kernels that learn within the basis decomposition** and **point-wise operations** allowing us to learn continuous representations on arbitrary discretised inputs and outputs.

# Neural Operators for PDEs



# Choose your Basis

Wavelet Decomposition	→	Wavelet Neural Operator <sup>[1]</sup>
Laplace Transform	→	Laplace Neural Operator <sup>[2]</sup>
Complex Transform	→	Complex Neural Operator <sup>[3]</sup>
Polynomial Basis	→	DeepONet <sup>[4]</sup>
Fourier Decomposition	→	Fourier Neural Operator <sup>[5]</sup>

[1] Tripura et al. – Wavelet neural operator: a neural operator for parametric partial differential equations

[2] Cao et al. – LNO: Laplace Neural Operator for Solving Differential Equations

[3] Tiwari et al. – CoNO: Complex Neural Operator for Continuous Dynamical Systems

[4] Lu et al. – DeepONet: Learning nonlinear operators for identifying differential equations based on the universal approximation theorem of operators

[5] Li et al. – Fourier Neural Operator for Parametric Partial Differential Equations

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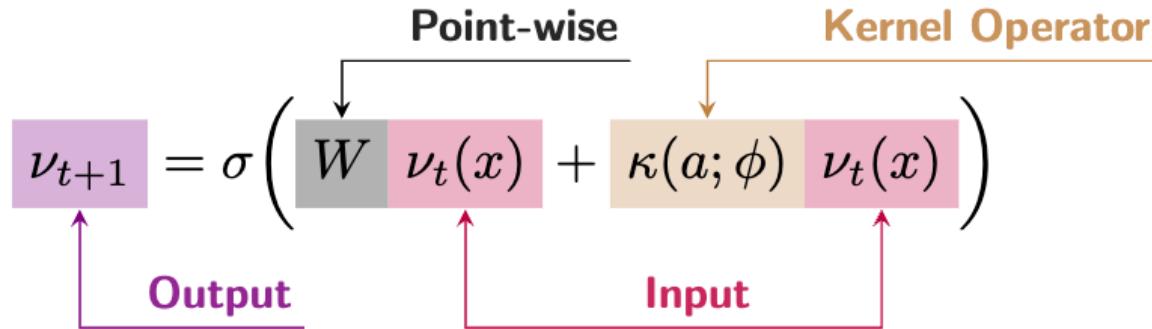
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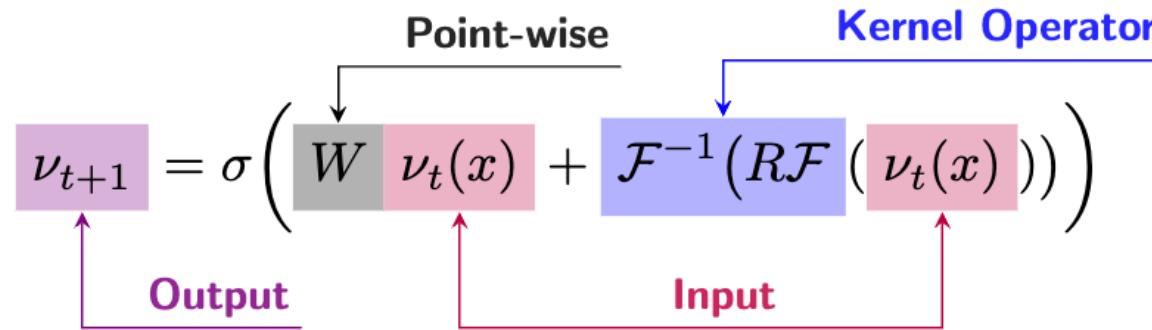
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# Fourier Neural Operator

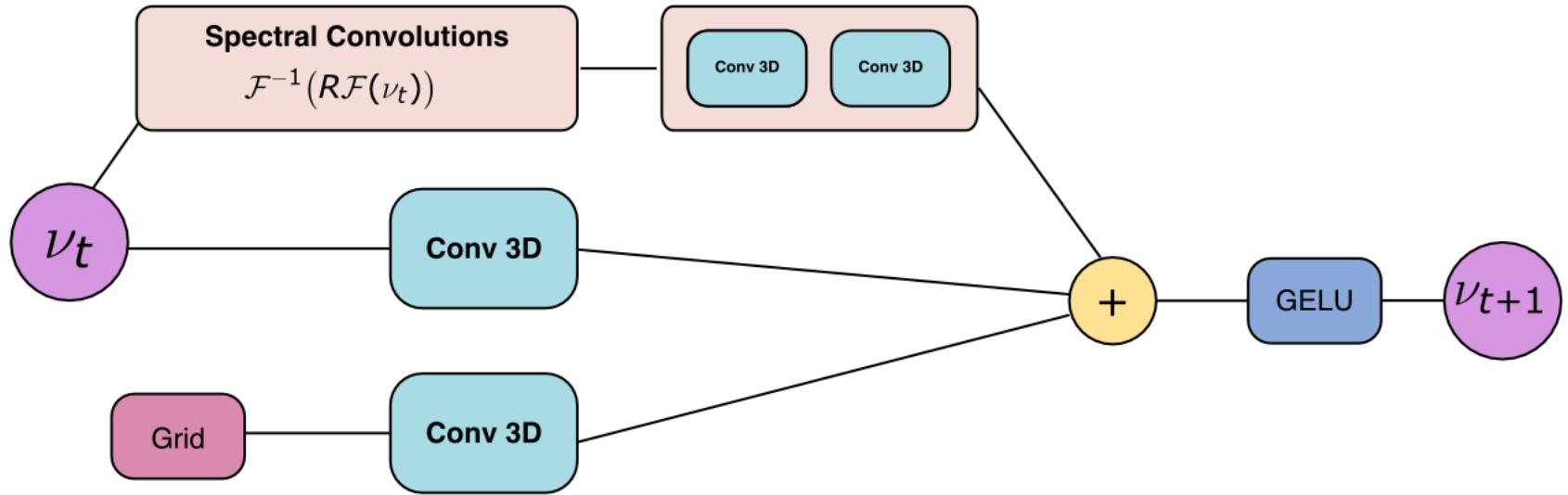
General Neural Operator Framework:



Fourier Neural Operator Framework:



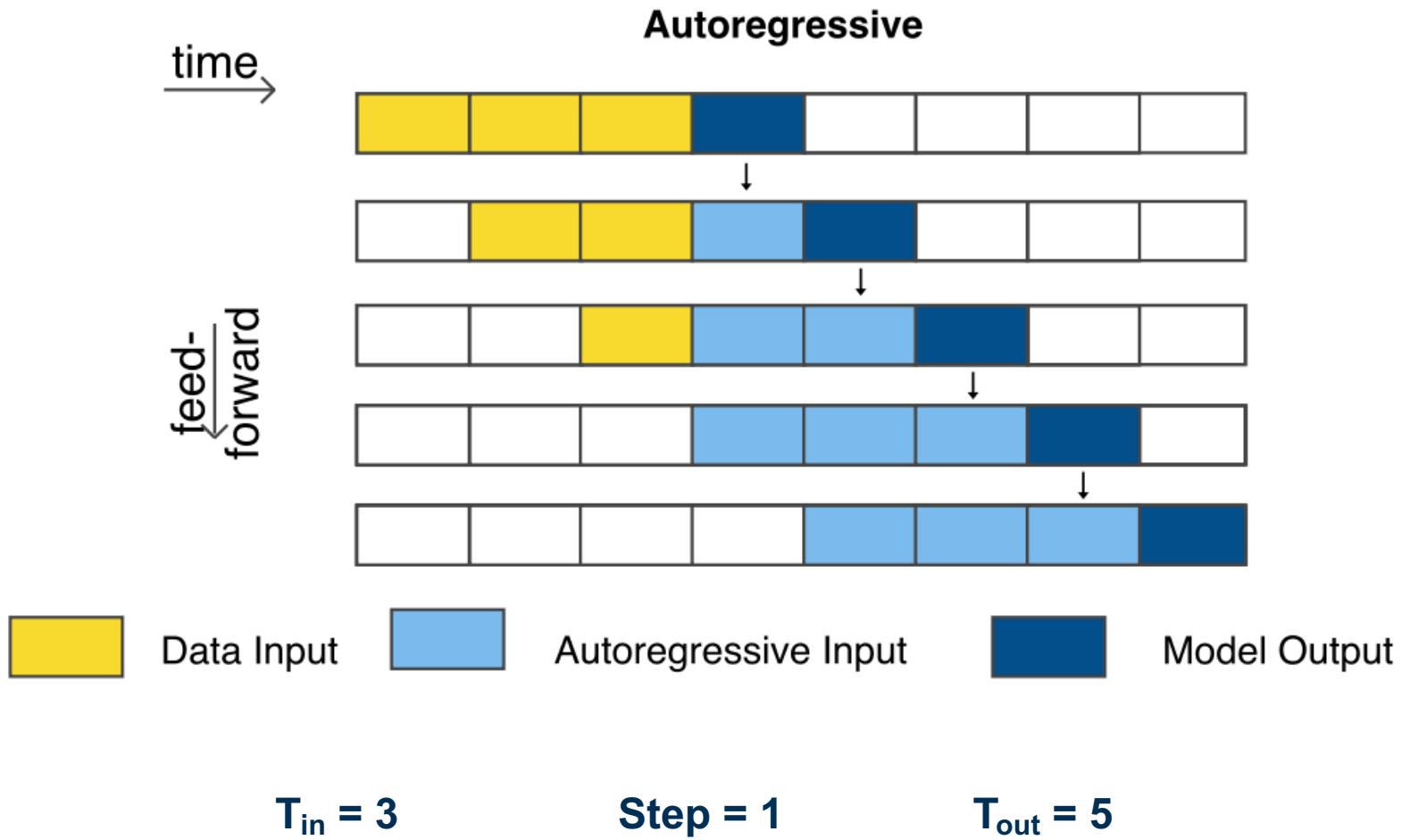
# Fourier Layer



Our Contribution:

Multi-variable FNO : FNO modified with additional channel to accommodate multiple variables associated with a family of PDEs.

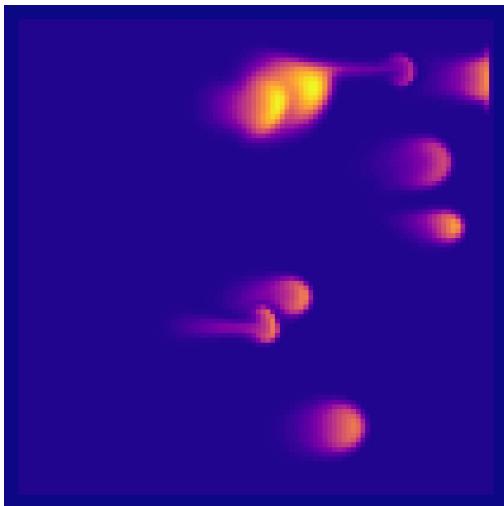
# Now that we have a model, how do we train ?



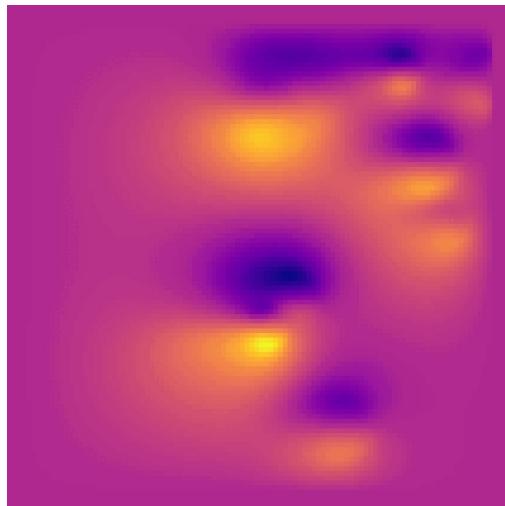
# Reduced-MHD

Radial Convection of plasma blobs in toroidal geometry using JOREK

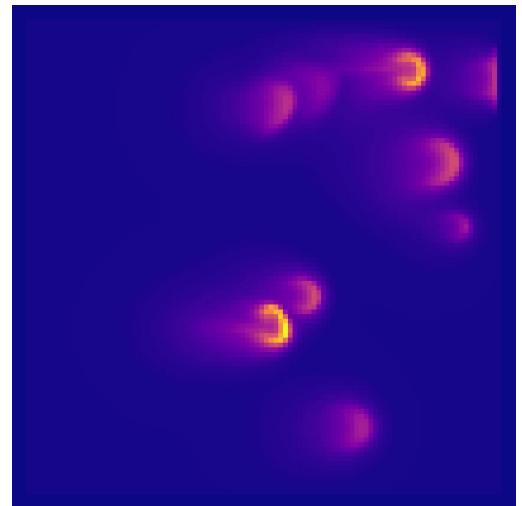
Absence of a plasma current equilibrium generates a buoyancy effect, causing the blob to move outwards towards the edge.



Density



Electric Potential

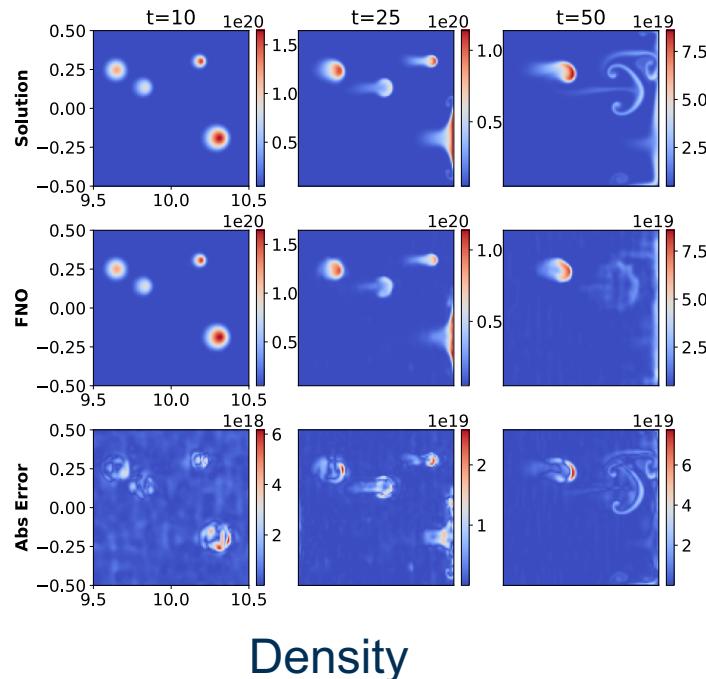


Temperature

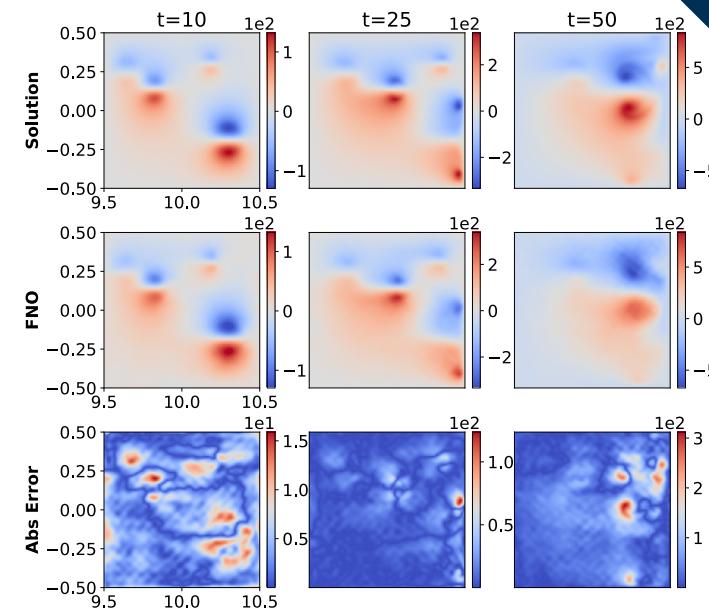
2000 simulations built by varying the initial conditions of the plasma blobs:  
number, position, width and amplitude

# FNO over MHD

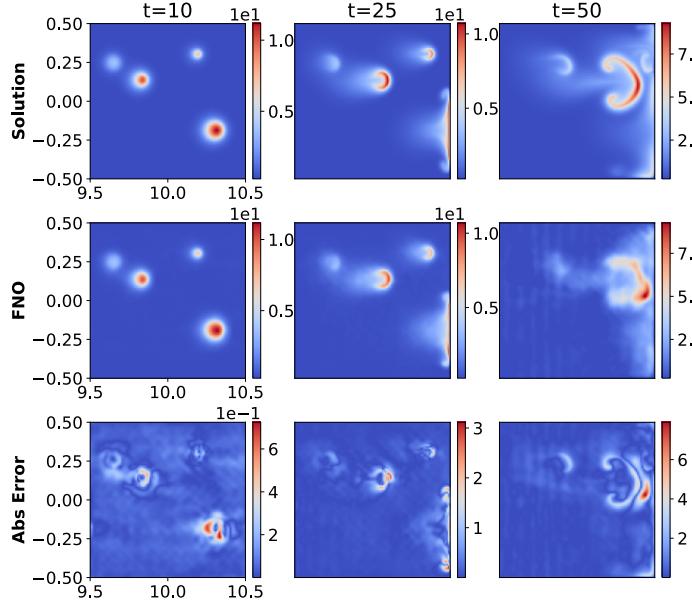
FNO: 6 orders of magnitude faster than JOREK



$T_{in} = 10$   
 $Step = 5$   
 $T_{out} = 40$



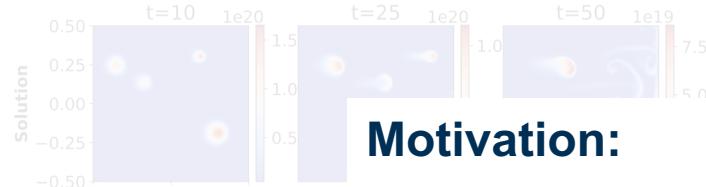
Electric Potential



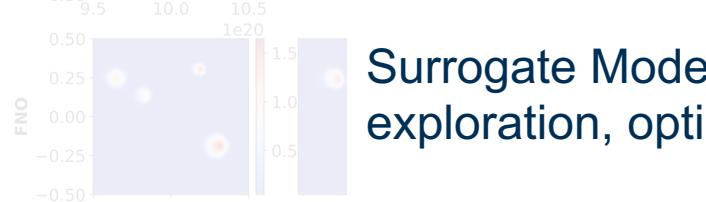
Temperature

# FNO over MHD

FNO: 6 orders of magnitude faster than JOREK

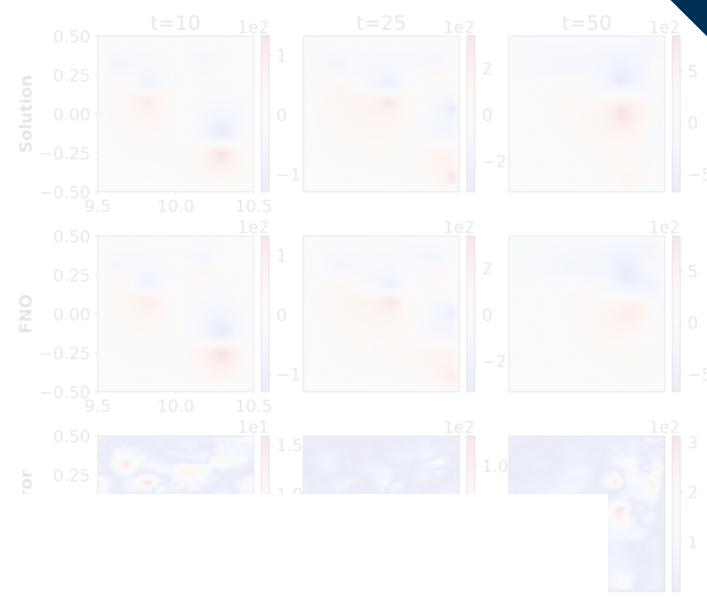


## Motivation:



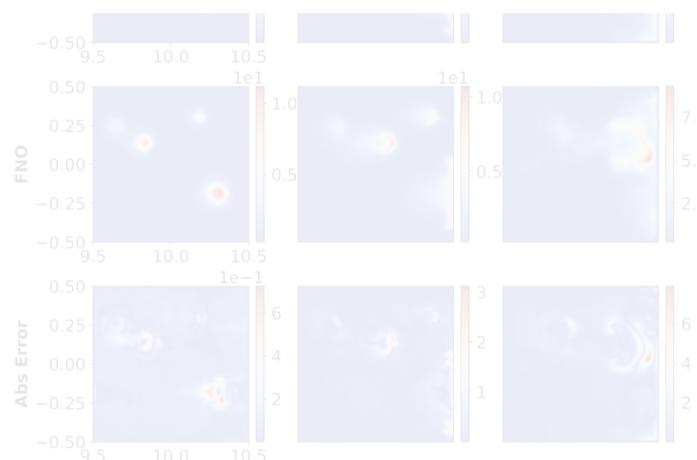
Density

$$\begin{aligned} T_{in} &= 10 \\ \text{Step} &= 5 \\ T_{out} &= 40 \end{aligned}$$



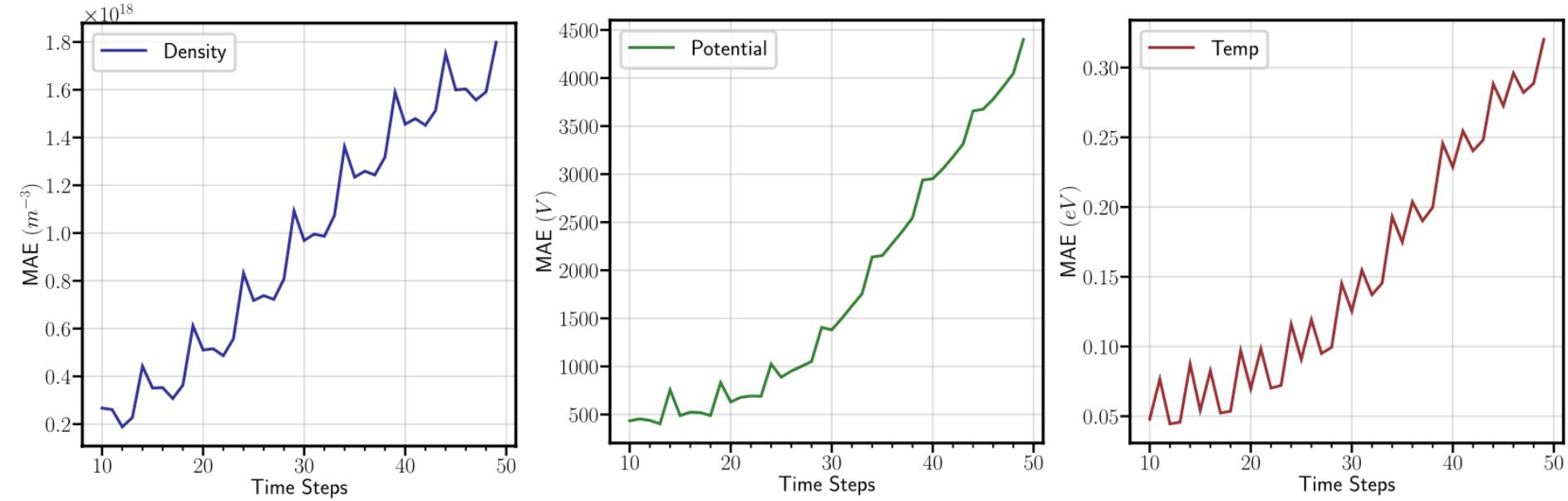
Electric Potential

Surrogate Modelling for quick, iterative scenario exploration, optimisation and design of experiments.

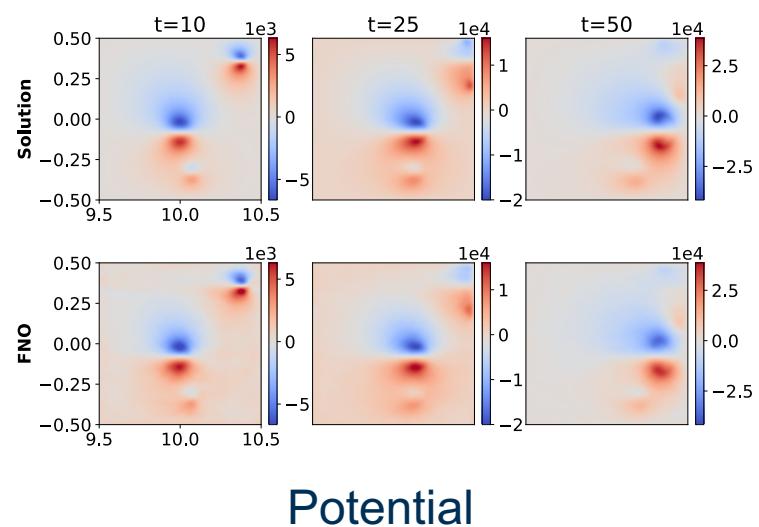
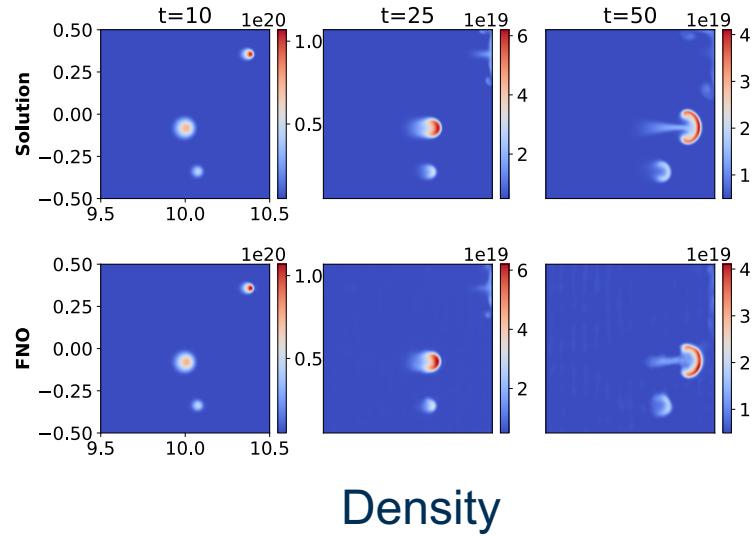


Temperature

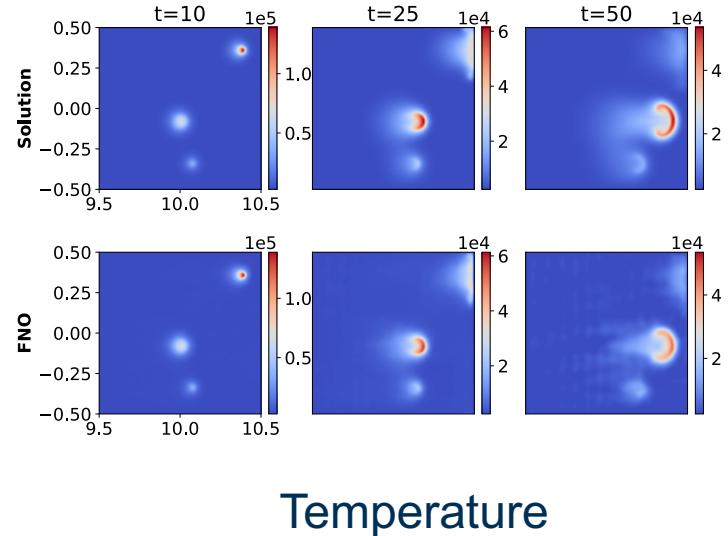
# Error Growth



# Super-Resolution



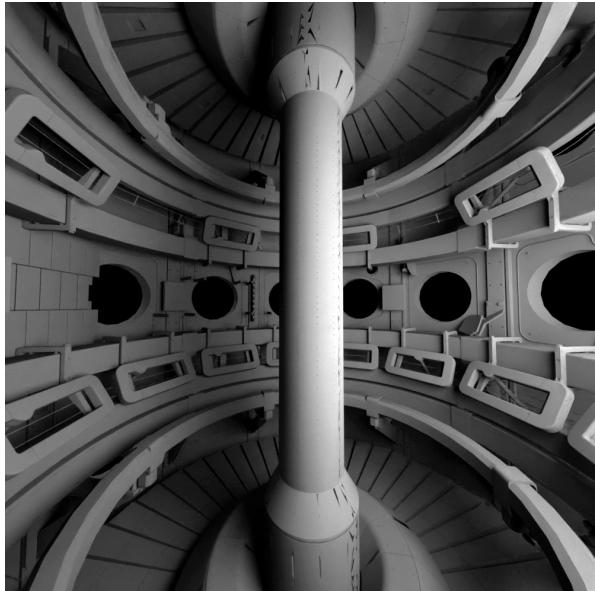
Being discretisation-invariant,  
 FNO trained on coarser grids ( $100 \times 100$ ),  
 can be deployed for finer grids ( $500 \times 500$ ).



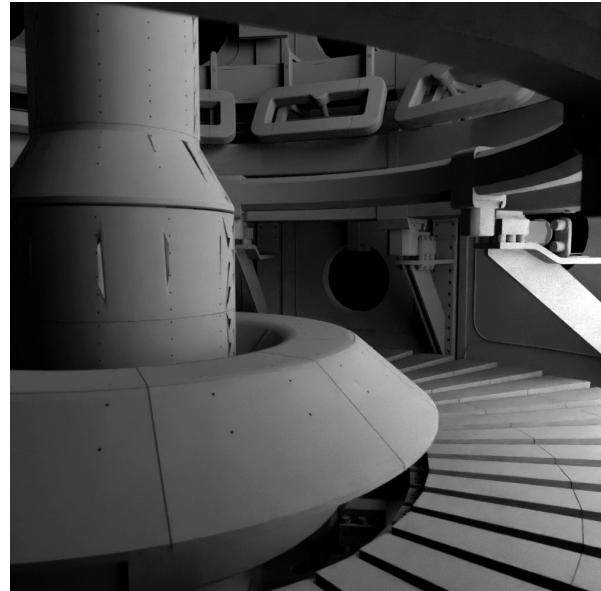
# FNO Over Camera

Modelling the plasma as diagnostically captured by the Fast Cameras on MAST

Modelled over the entire shot duration of 55 shots  
from the last campaign on MAST (M9)



Camera viewing the  
central solenoid (rbb)<sup>[1]</sup>



Camera viewing the  
divertor (rba)<sup>[1]</sup>

[1] Synthetic renders of the camera views created using the CAD model of MAST and Nvidia Omniverse.

# FNO Over Camera

Modelling the plasma as diagnostically captured by the Fast Cameras on MAST

Modelled over the entire shot duration of 55 shots  
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## Motivation:

Real-time forecasting of fast camera images to track

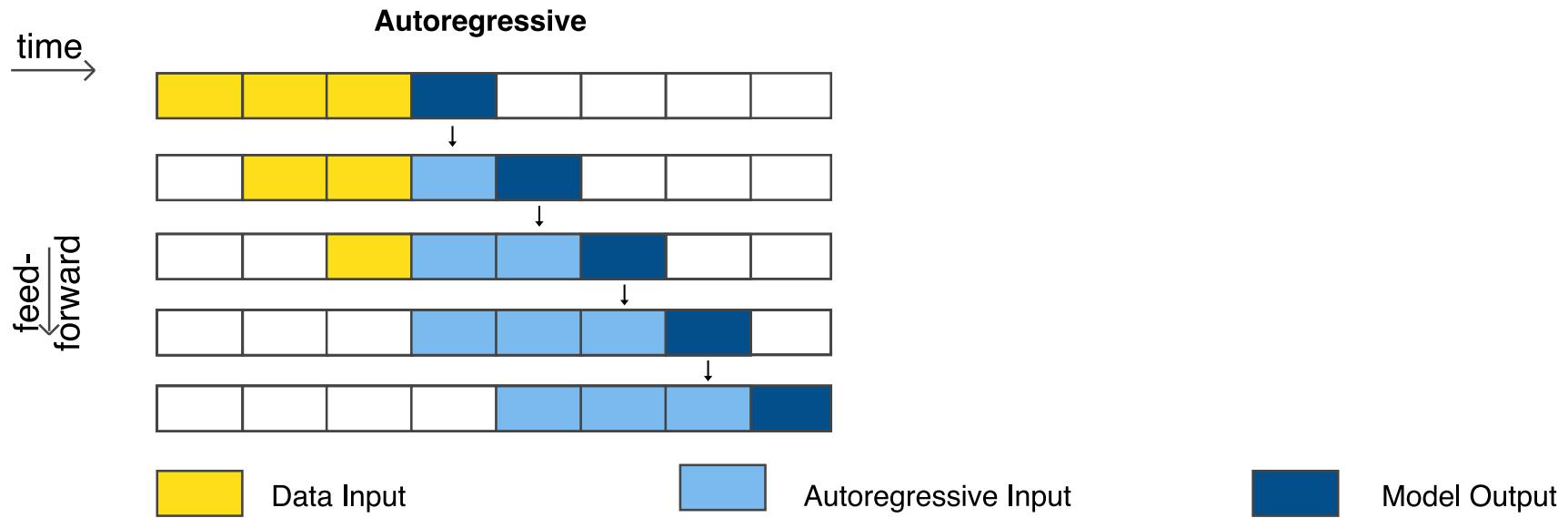
- plasma evolution,
- predict L-H transition,
- build further unto disruption prediction.
- data assimilation (Sim2Real)



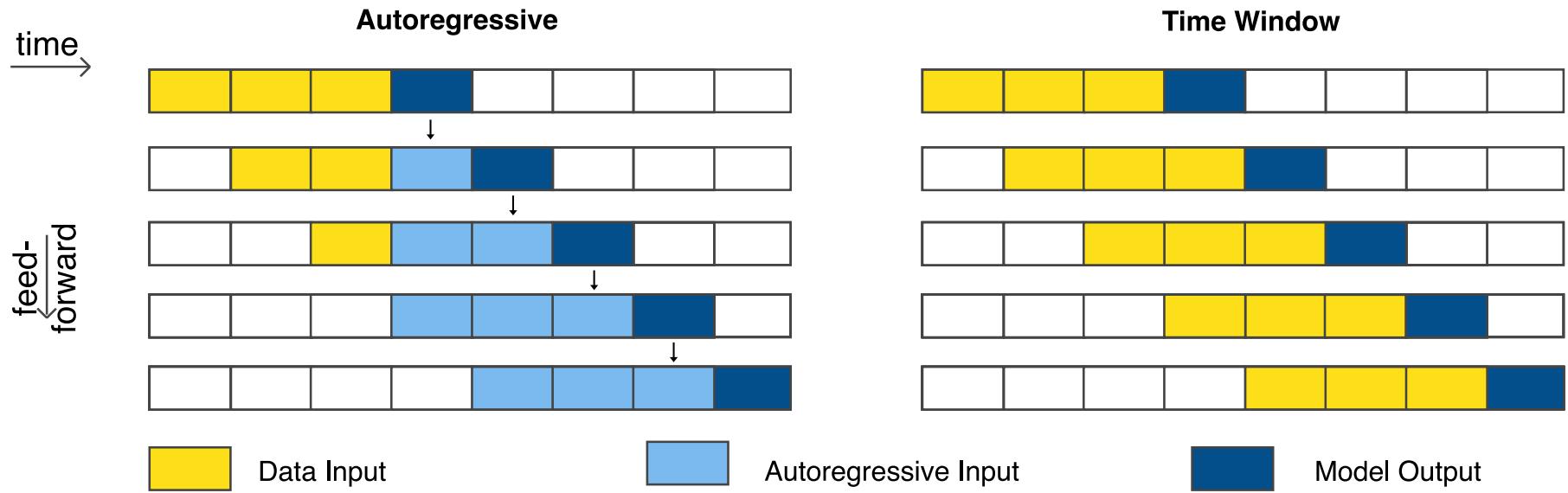
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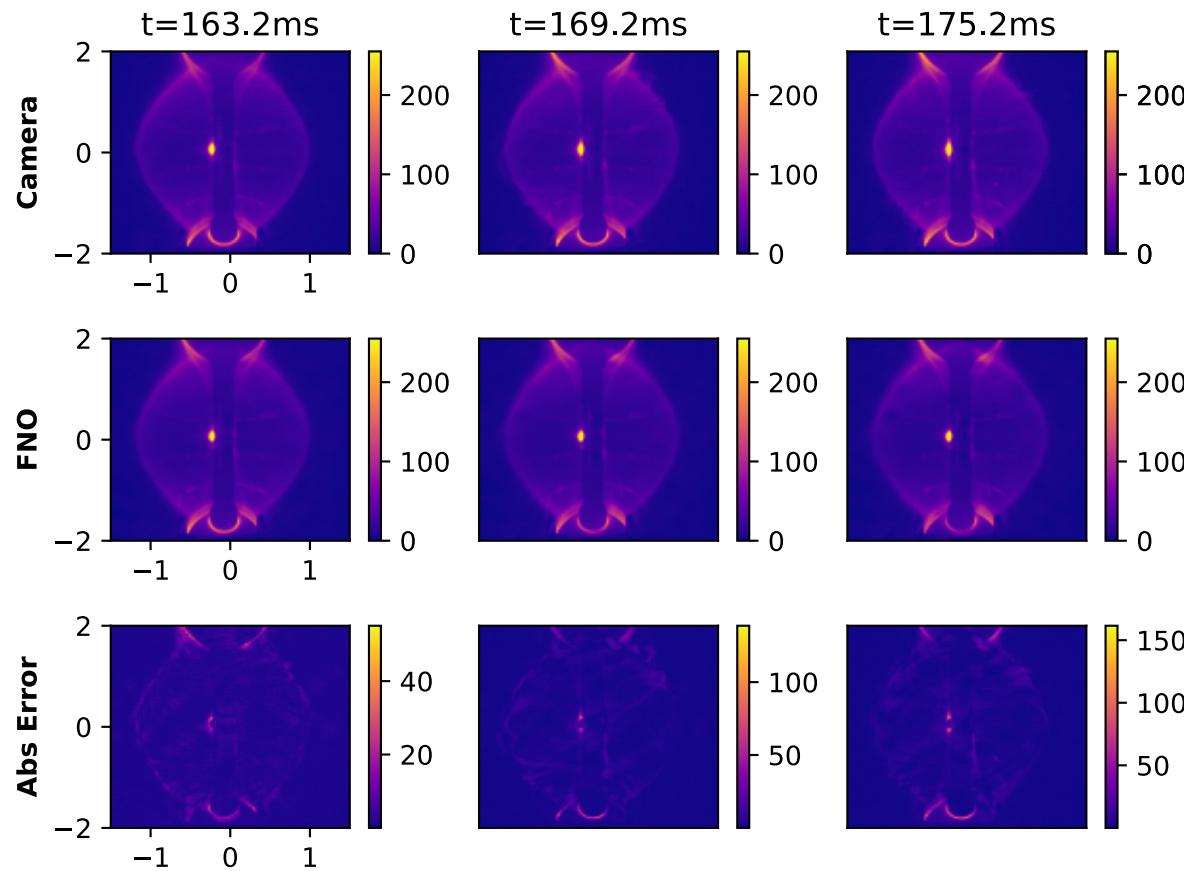
# Time Window Pipeline



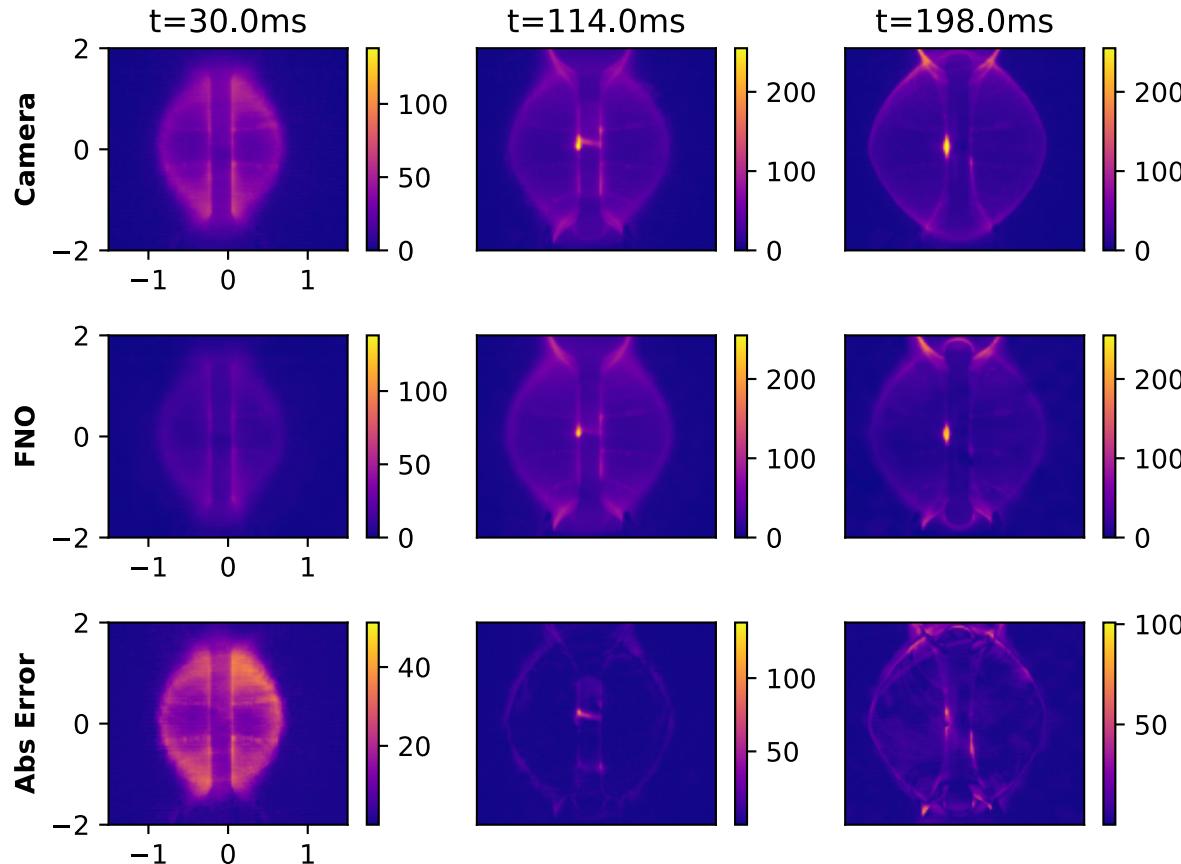
# Time Window Pipeline



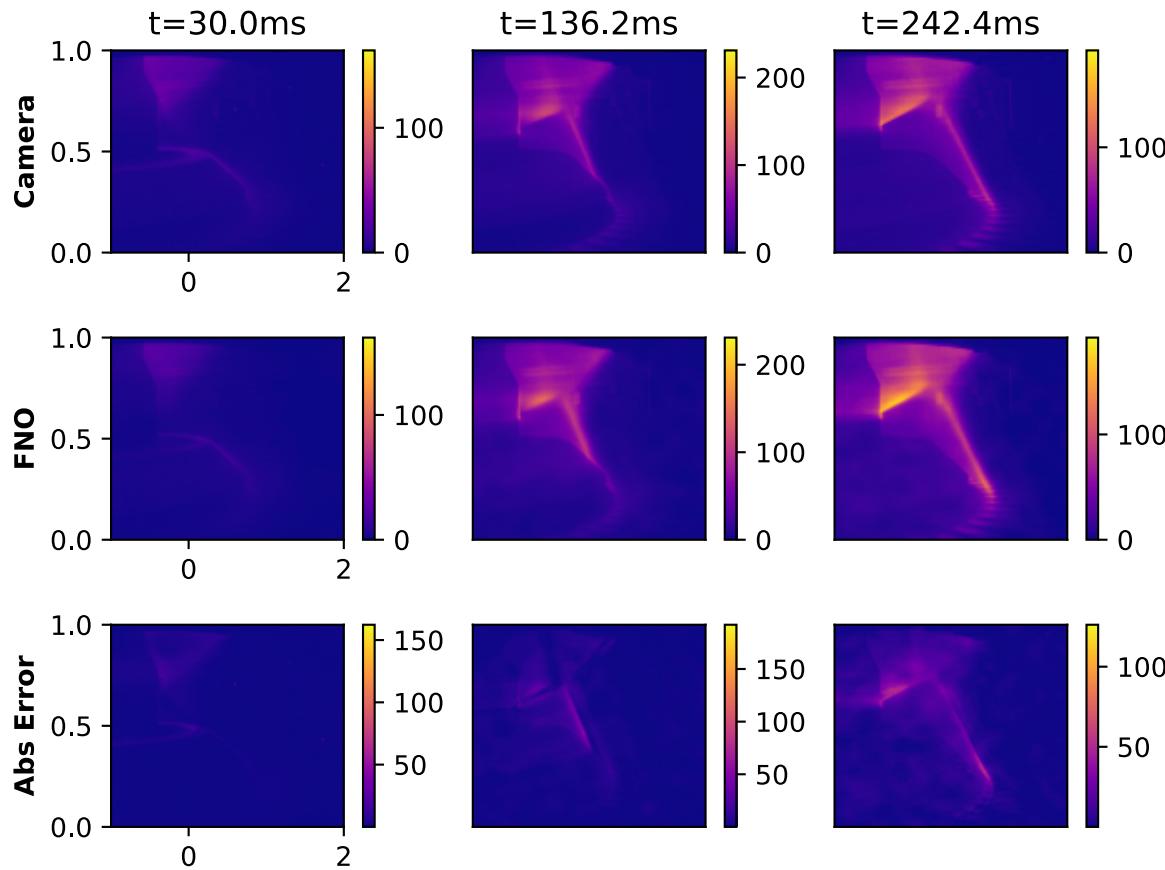
# Camera viewing the central solenoid (rbb)



# FNO predicting across both L and H-modes of Confinement.



# Camera at the Divertor (rba)



# Paper

## Plasma Surrogate Modelling using Fourier Neural Operators

- Vignesh Gopakumar, Stanislas Pamela, Lorenzo Zanisi, Zongyi Li, Ander Gray, Daniel Brennand, Nitesh Bhatia, Gregory Stathopoulos, Matt Kusner, Marc Peter Deisenroth, Anima Anandkumar, JOREK Team, MAST Team

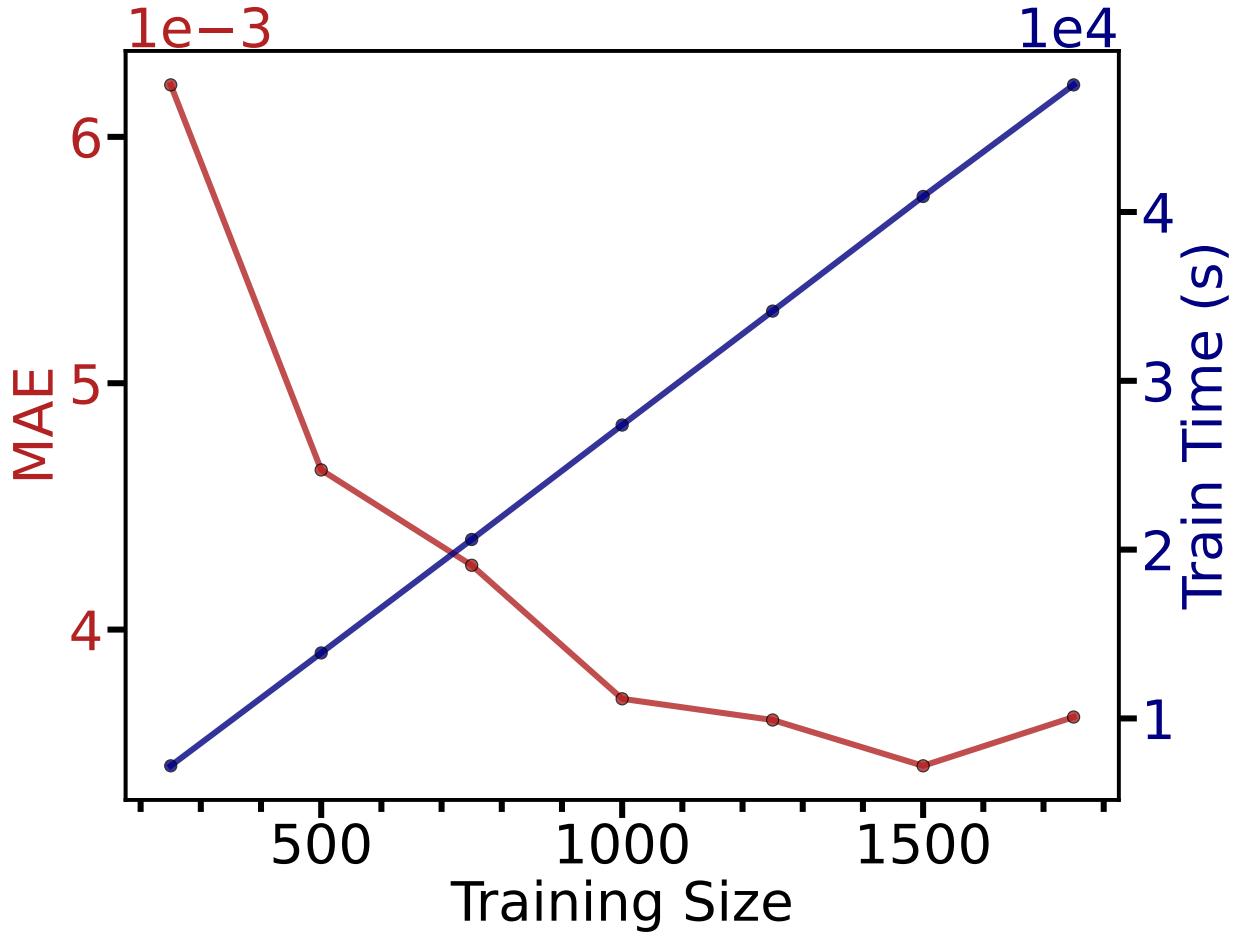
Submitted to Nuclear Fusion



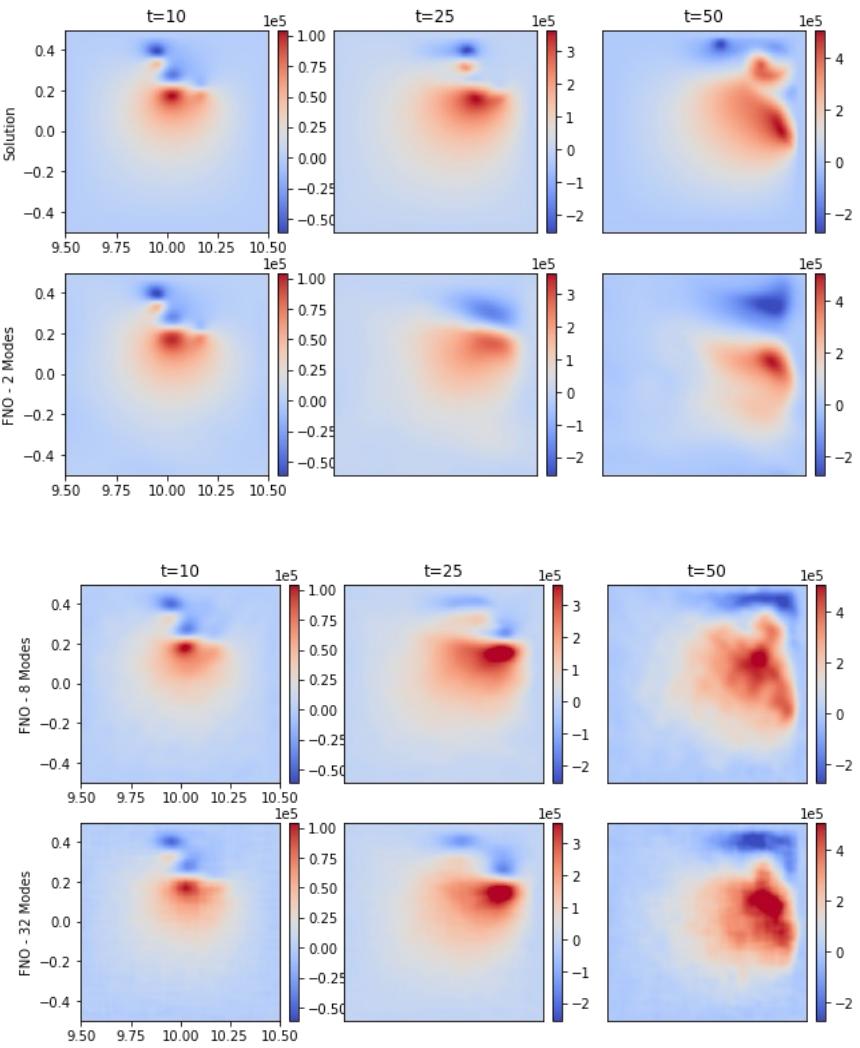
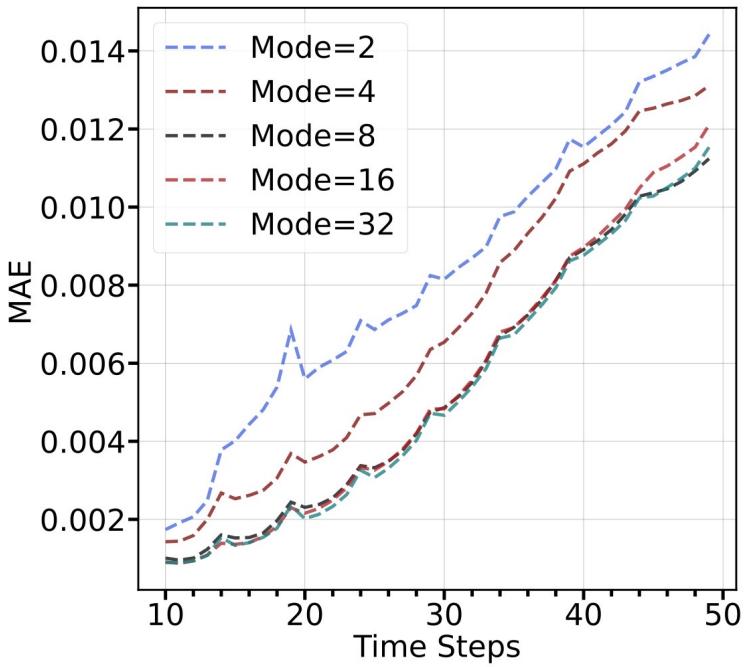
QR code to ArXiv preprint

# Supplementary Slides

# Impact of Training Data

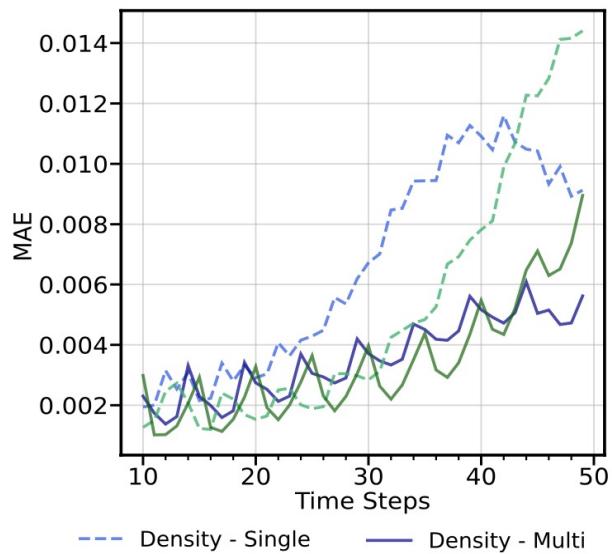


# Mode Ablation Study

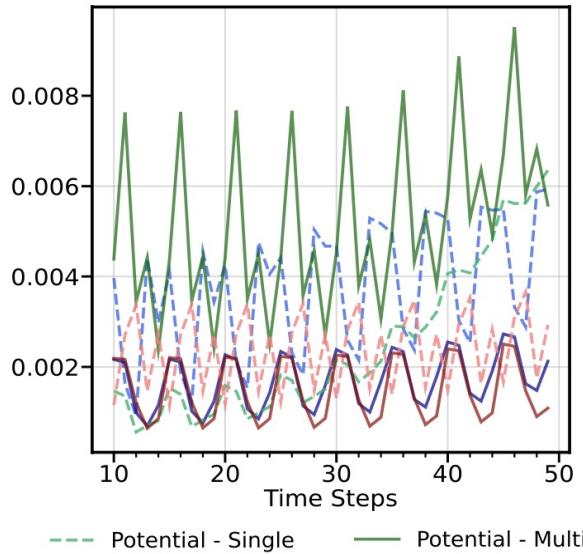


# Individual FNO vs Multi-variable FNO

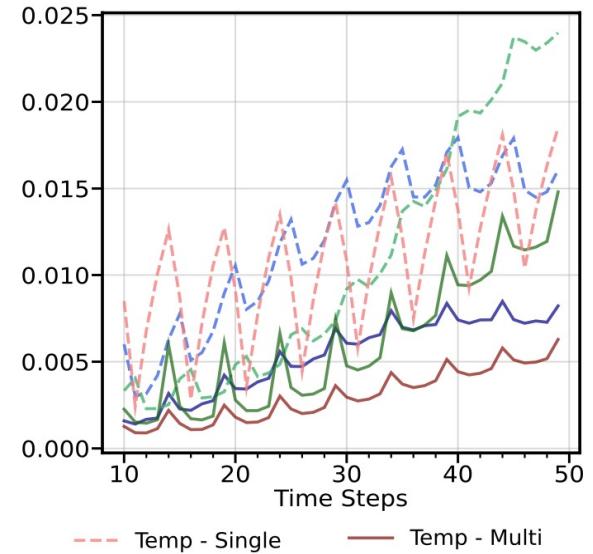
(a) Isothermal Blob



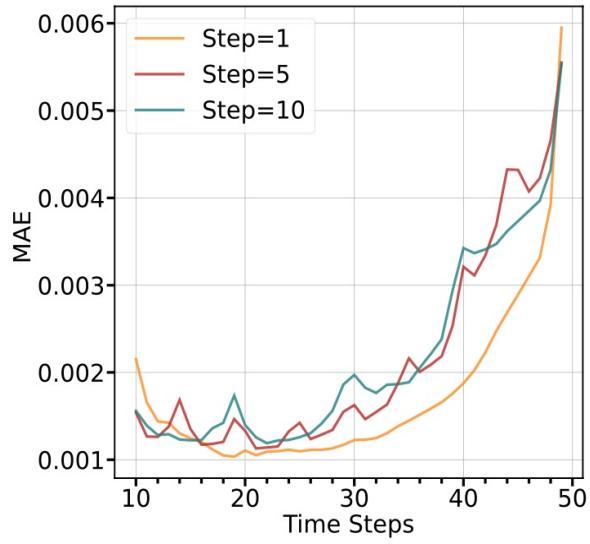
(b) Single Blob



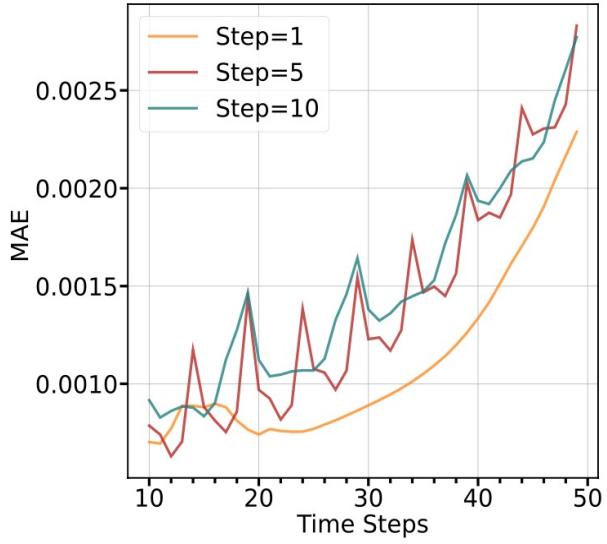
(c) Multiple Blobs



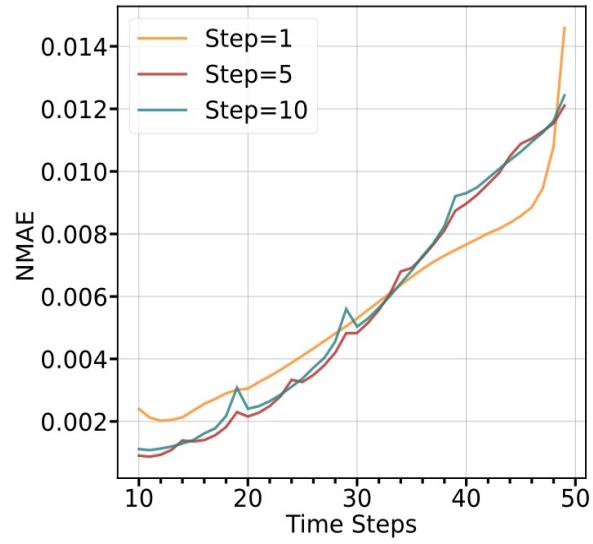
# Impact of Step Size



(a) Isothermal Blob



(b) Single Blob



(c) Multi-blobs