

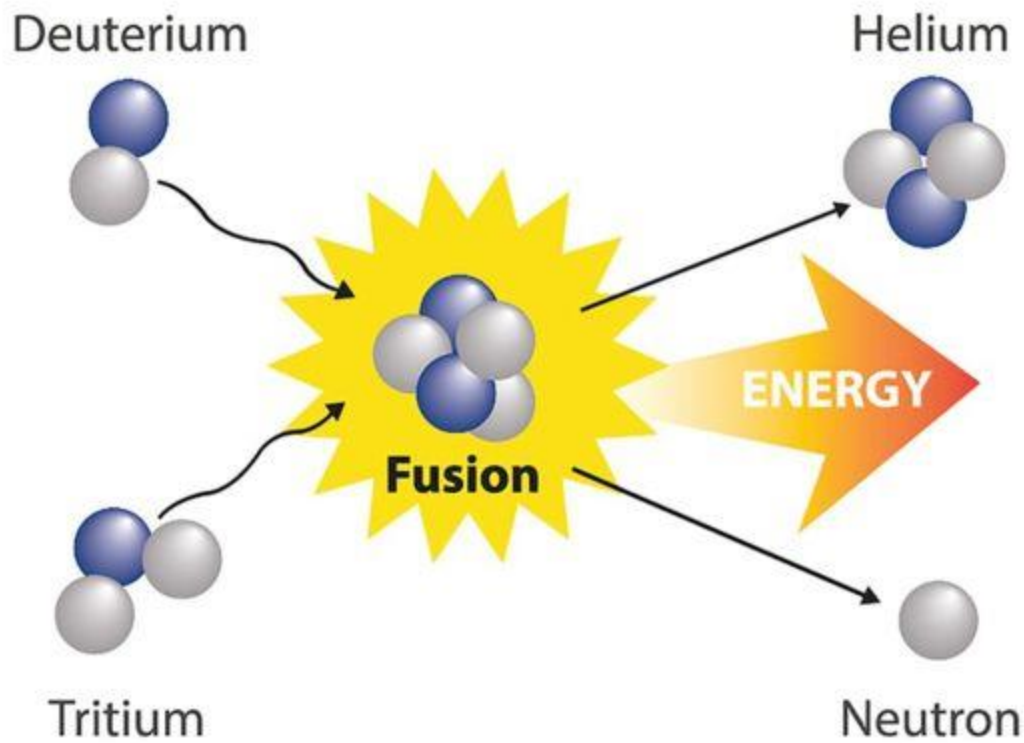
UKAEA

Data Driven Modelling of Plasma in Tokamaks

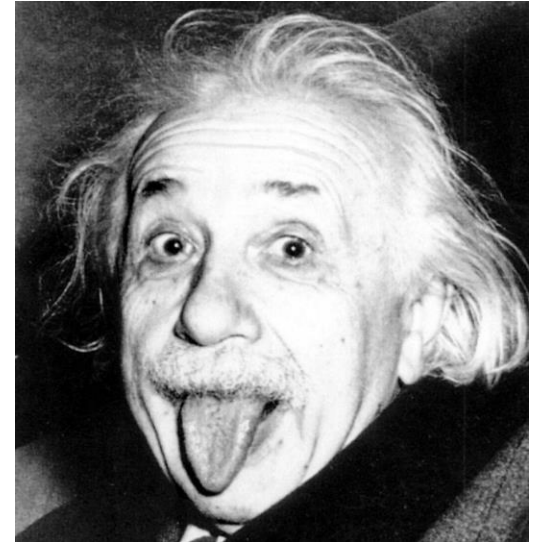
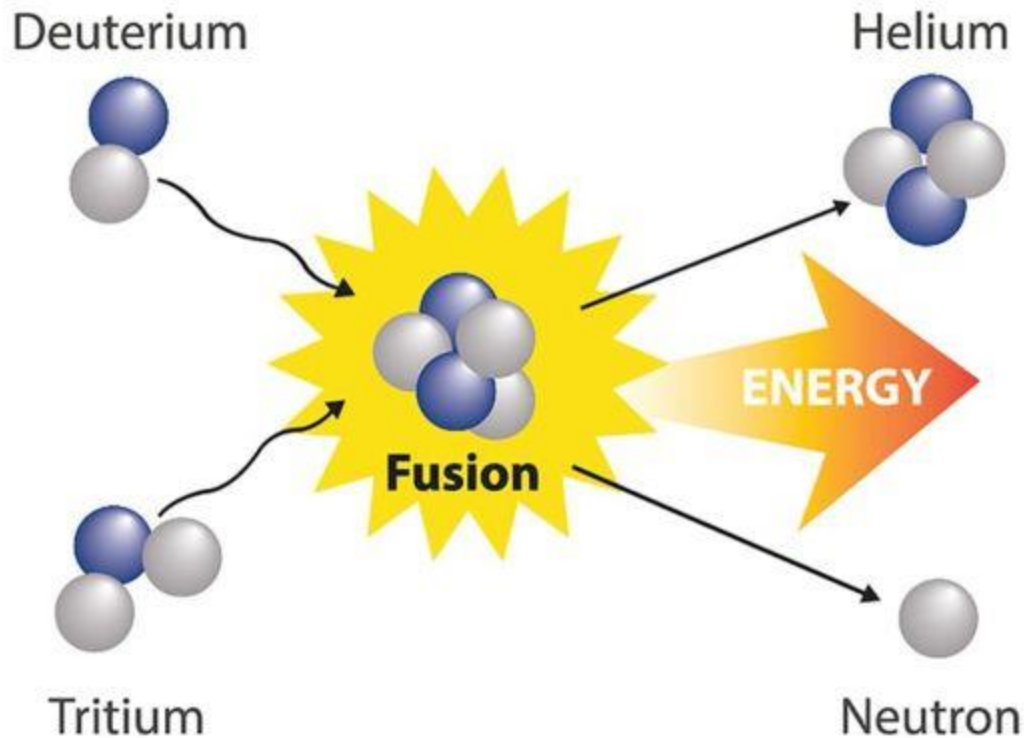
Vignesh Gopakumar

vignesh.gopakumar@ukaea.uk

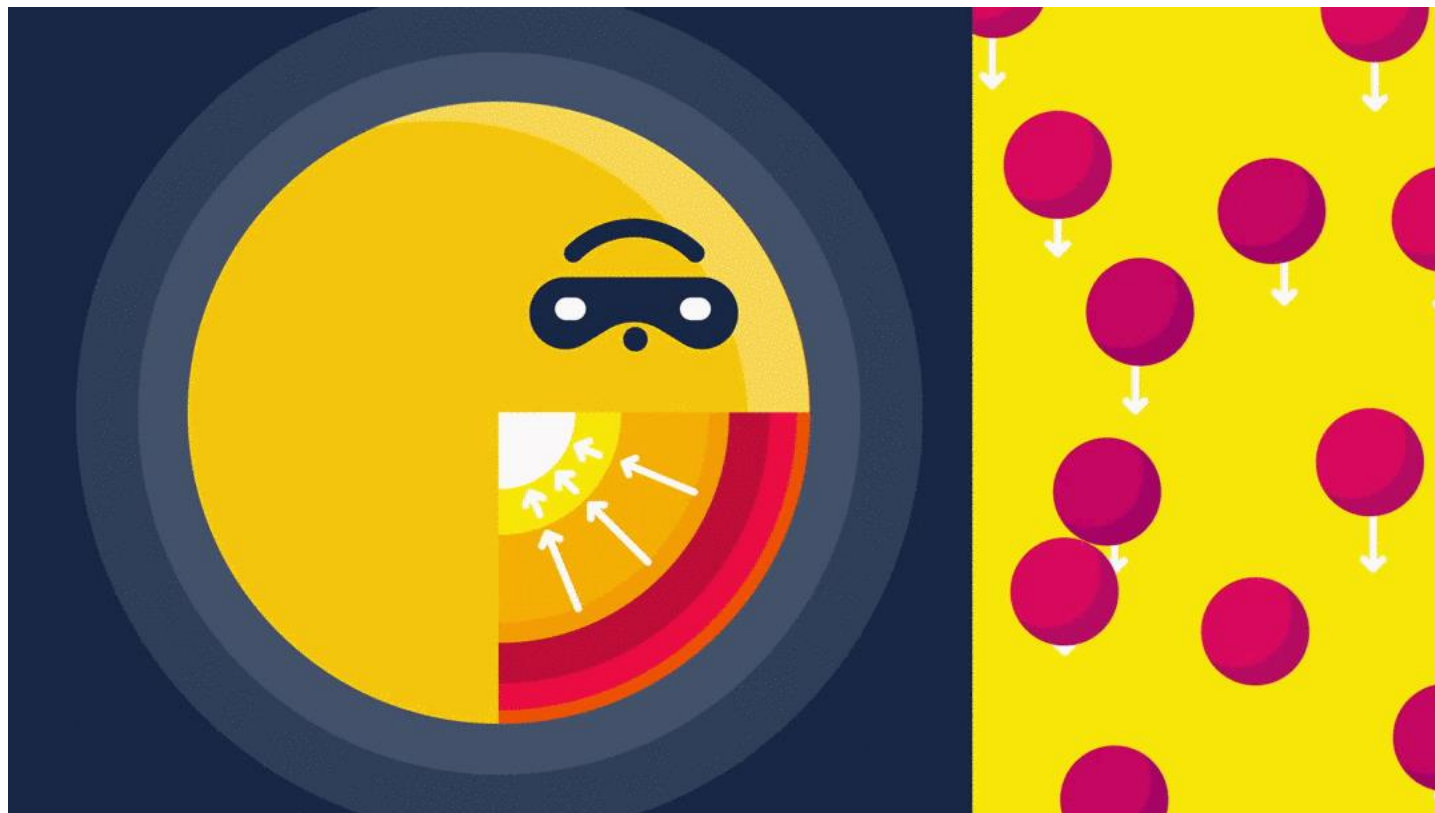
What is Fusion ?



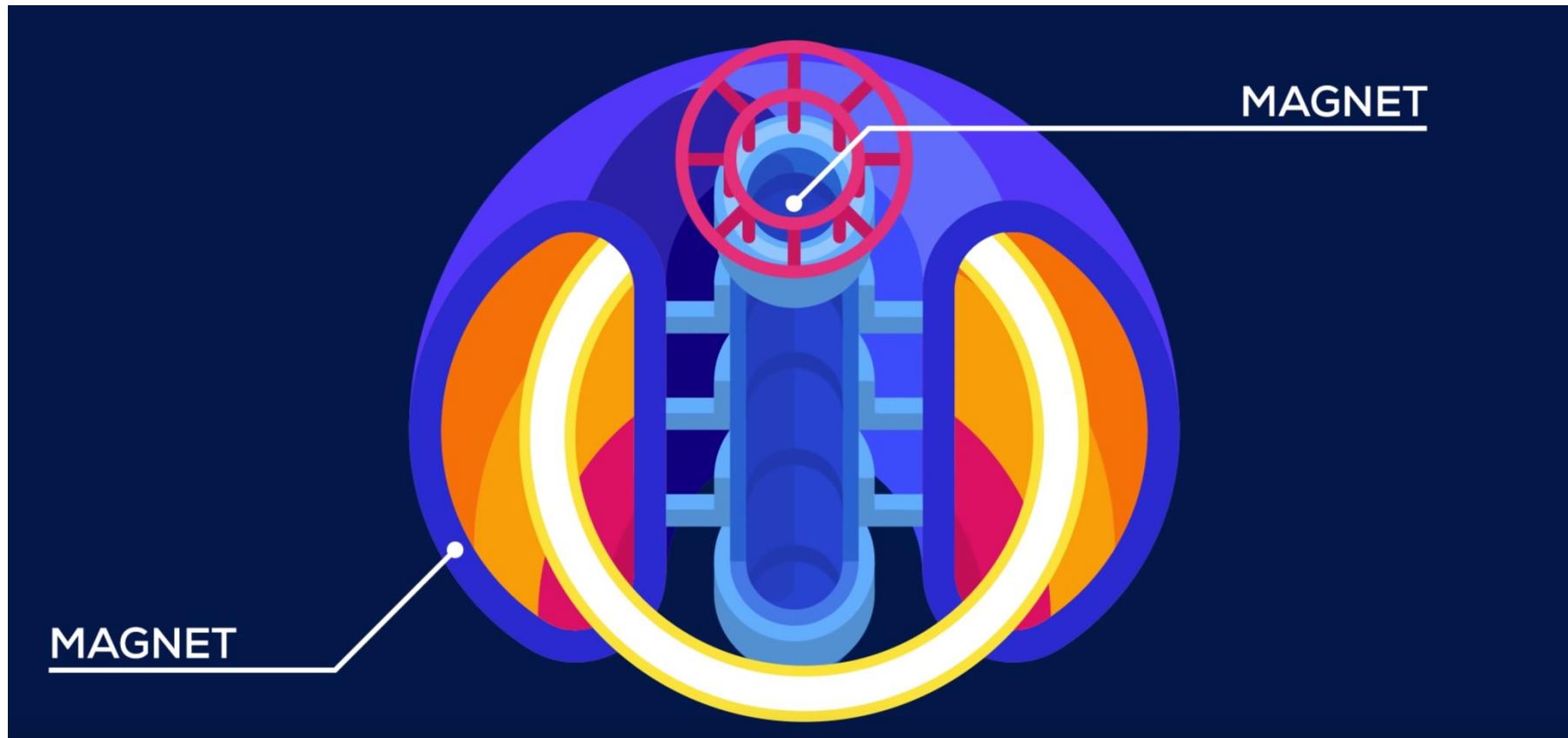
What is Fusion ?



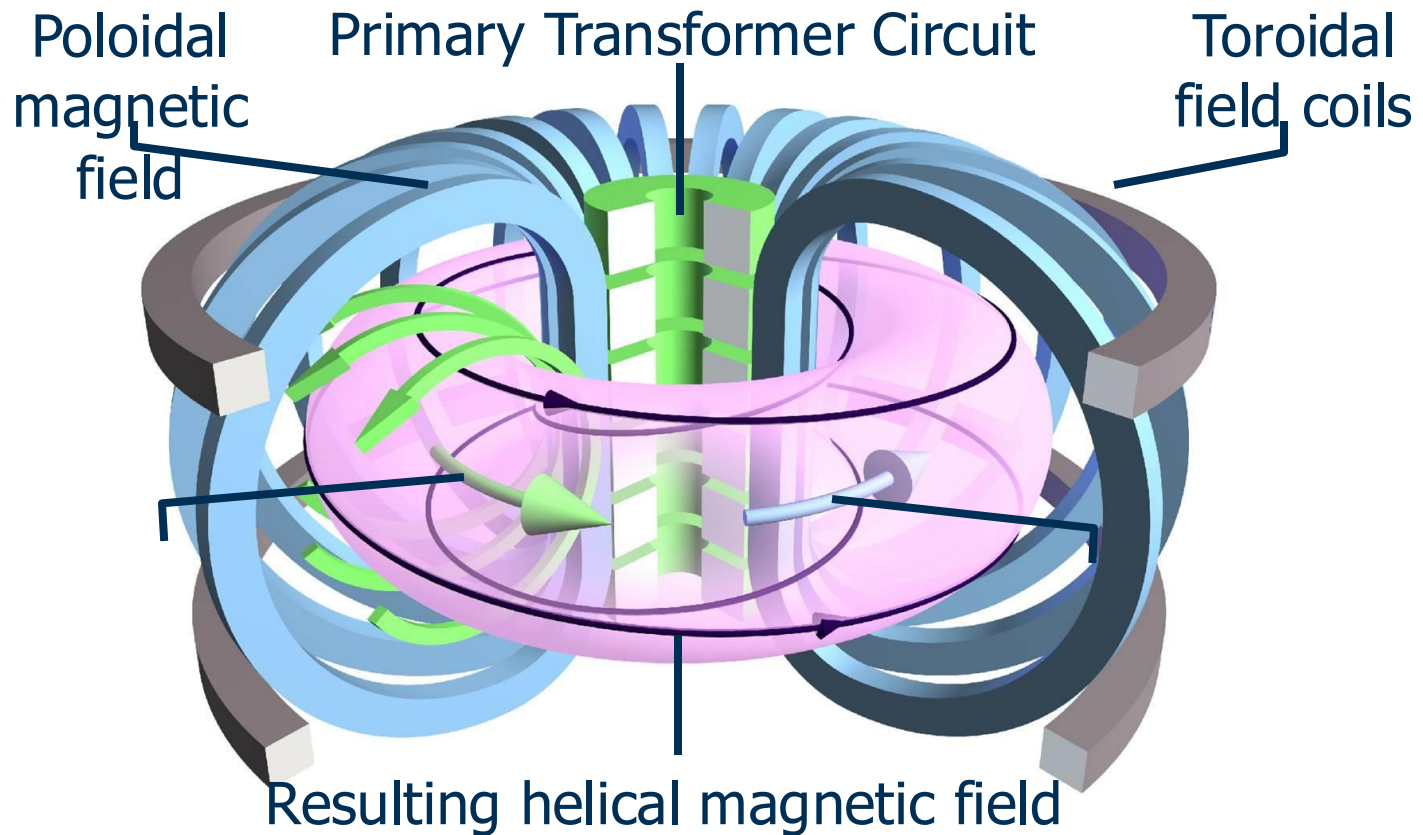
$$\text{Energy} = \text{Mass} \times c^2$$



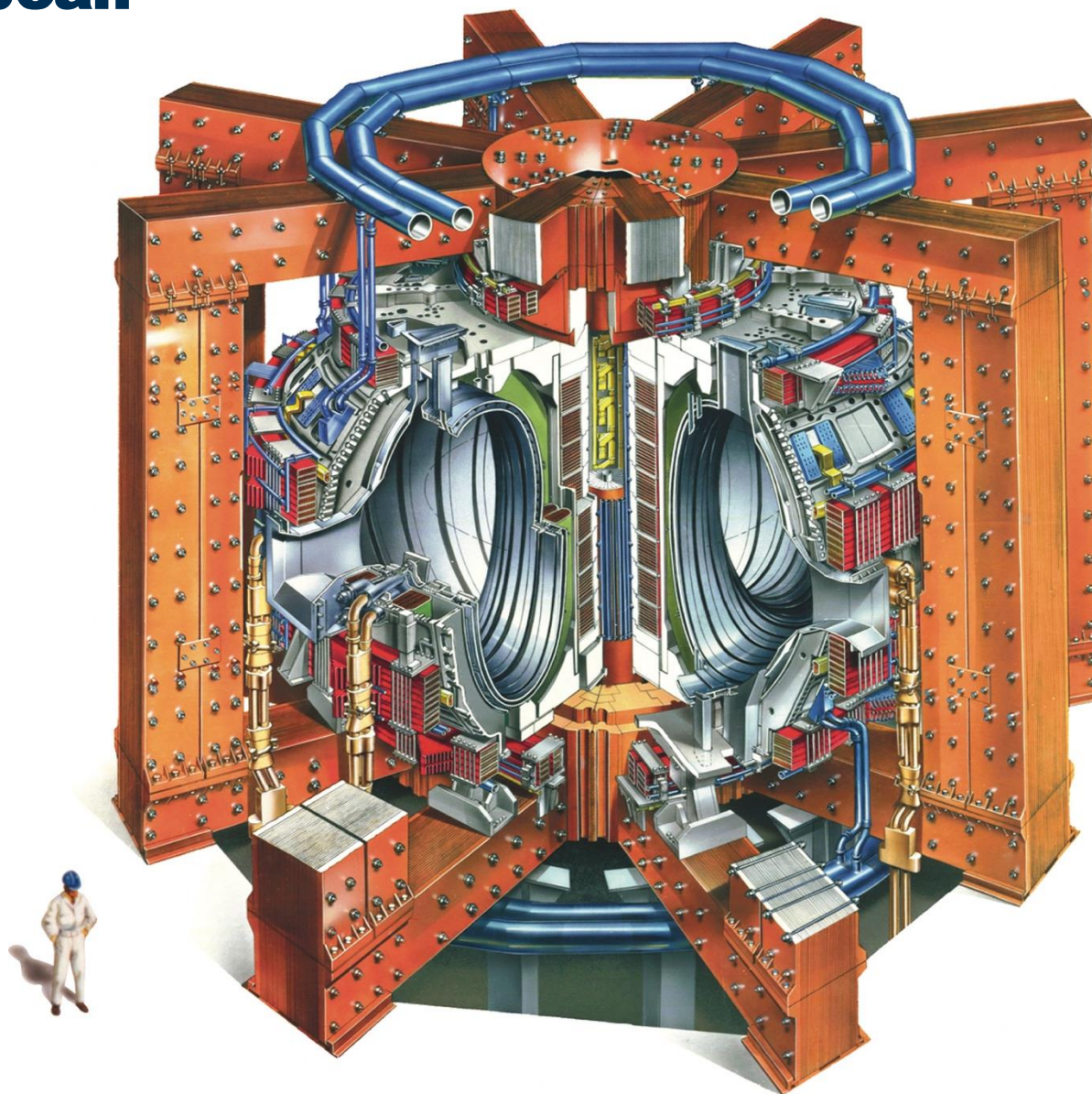
Magnetic Confinement



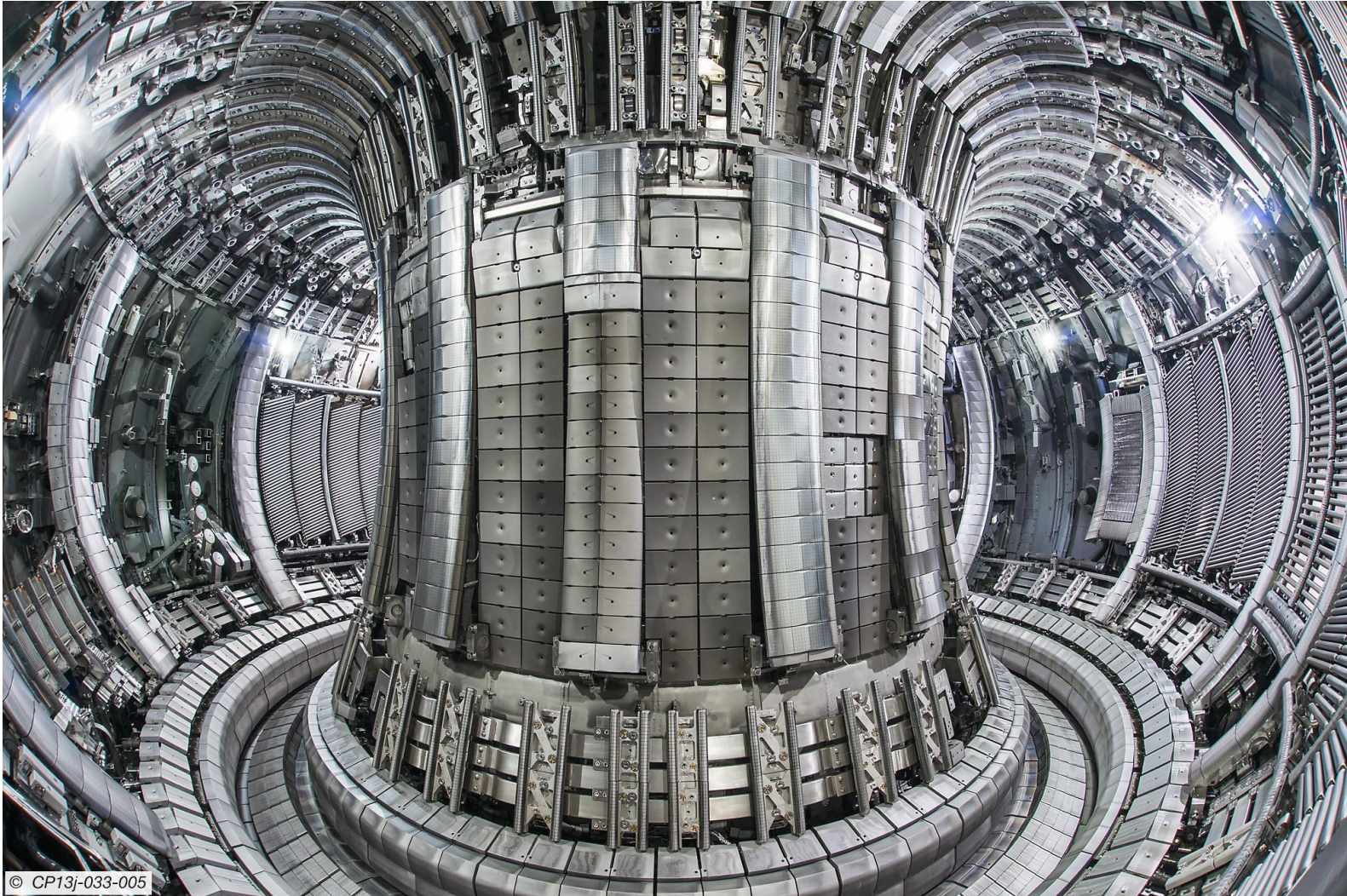
Tokamak – Structure



Joint European Torus (JET)

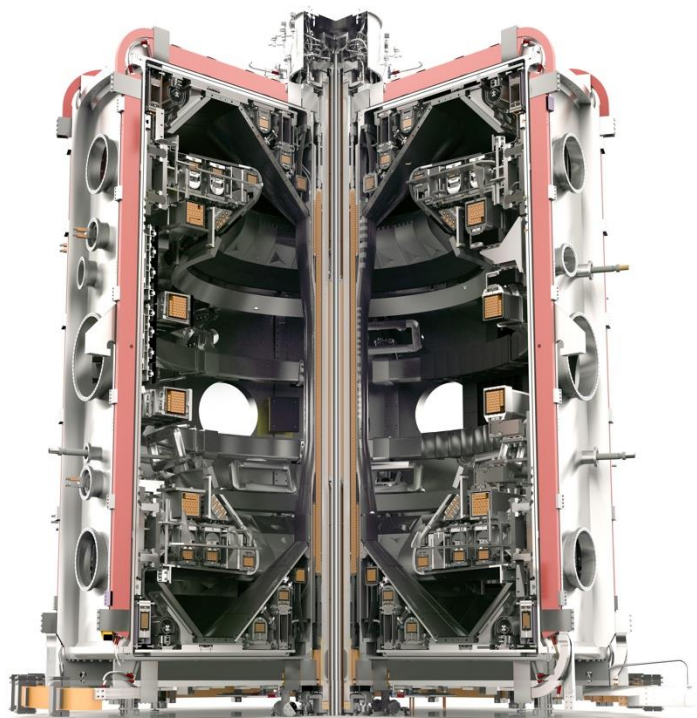


Tokamak – Internal View of JET

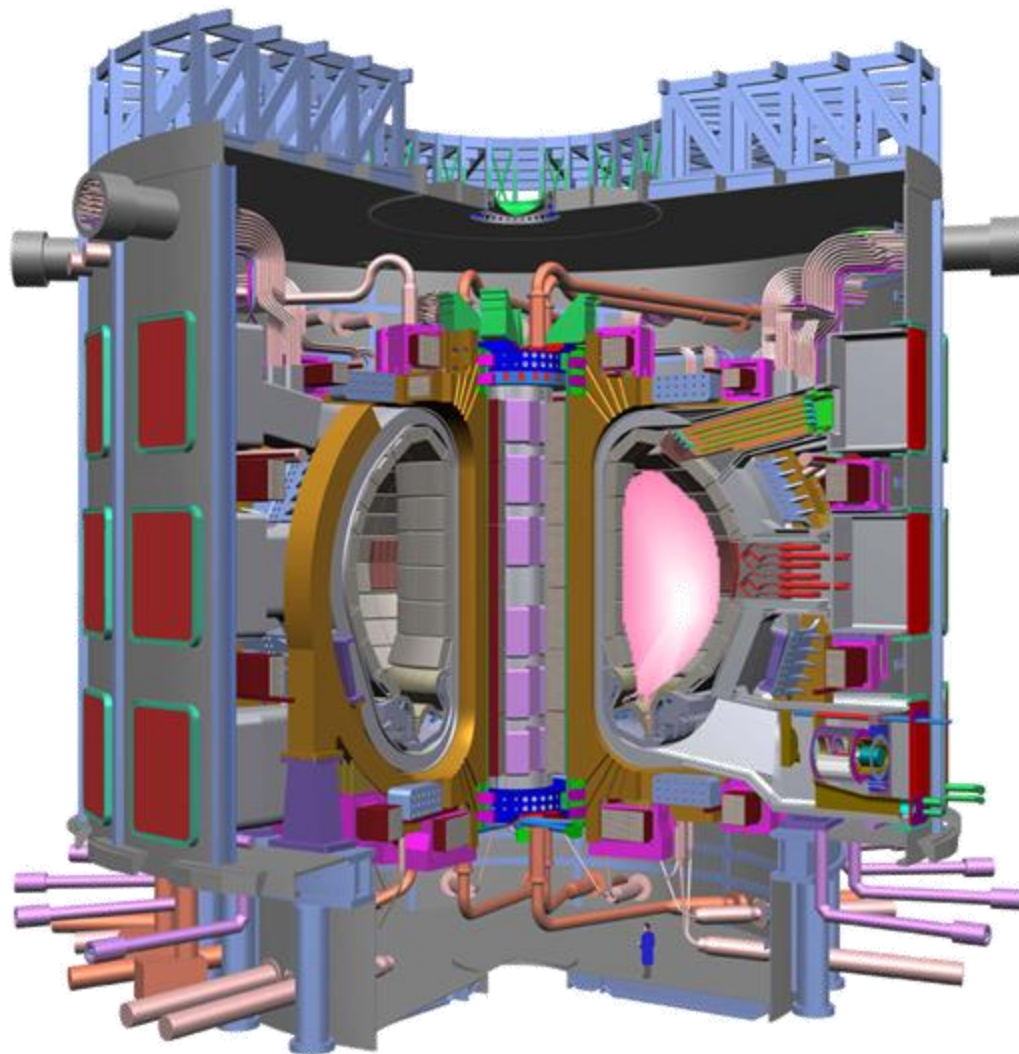


© CP13j-033-005

MAST-U



ITER

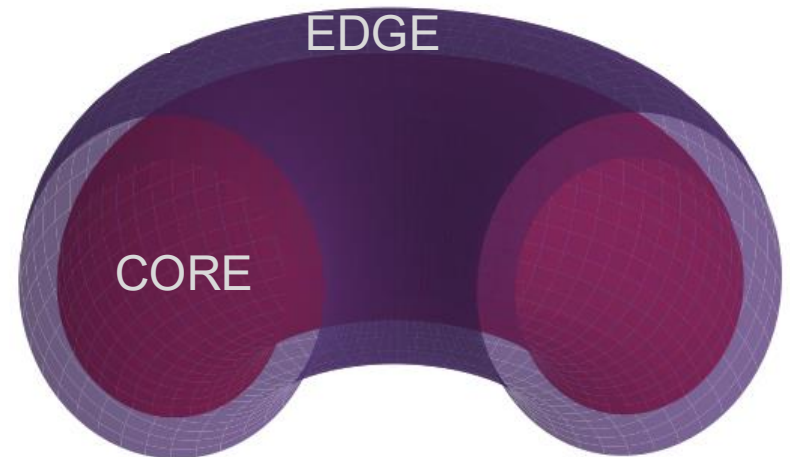
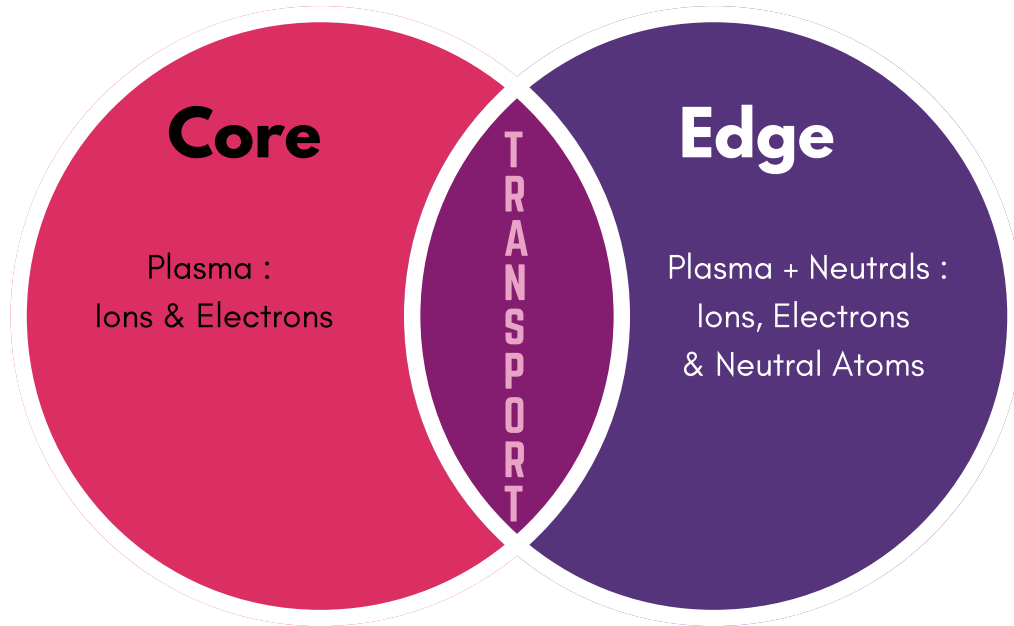


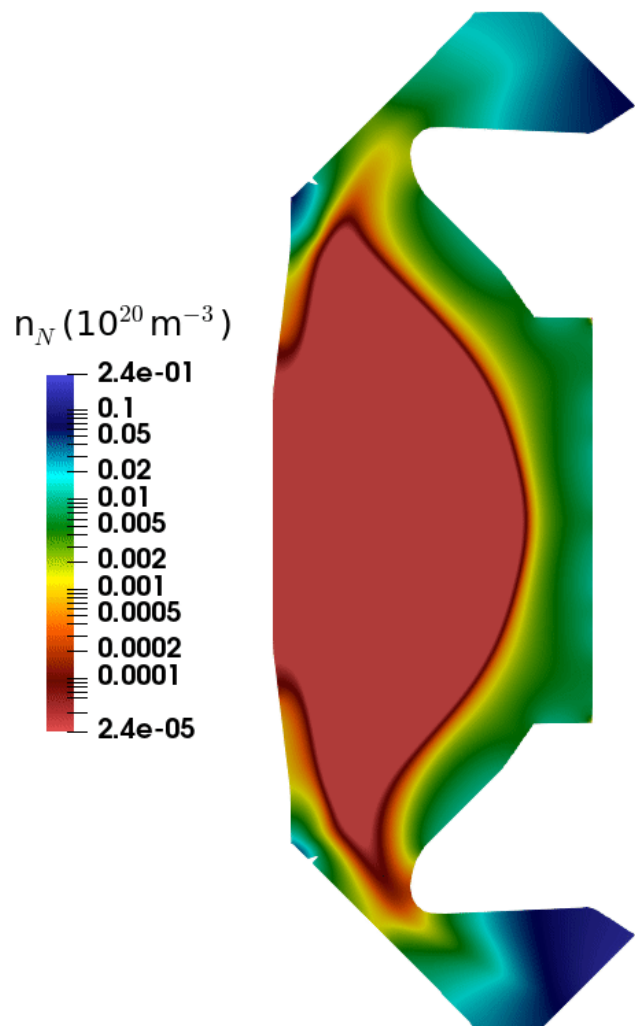
Data Driven Plasma Modelling

Fusion Research : Conundrum

- Physical Experiments are Expensive, Complex and Time Intensive
- Physicists have to rely on developing vast code packages that can extensively perform simulations to understand plasma behavior under various conditions
- Complexity of the problems involved makes simulations often difficult to execute even on vast super clusters.

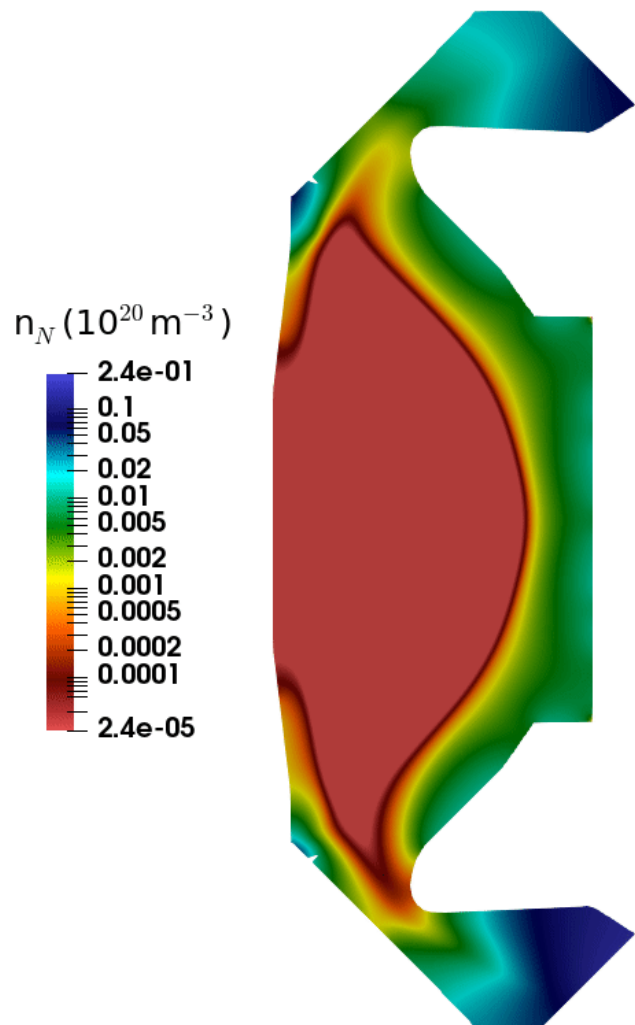
Plasma Modelling





Evolution of the Neutral Density in 3D (2D cross section shown here) using the code suite JOREK.

Source:
ELM Instabilities in MAST-U.
S.F.Smith, S.J.P. Pamela,
M. Hölzl, G.T.A. Huijsmans.
UKAEA.



Evolution of the Neutral Density in 3D (2D cross section shown here) using the code suite JOREK.

To simulate the time evolution by 14 ms took over two months on 44 nodes, with each node consisting of 48 cores clocking 2.3GHz each.

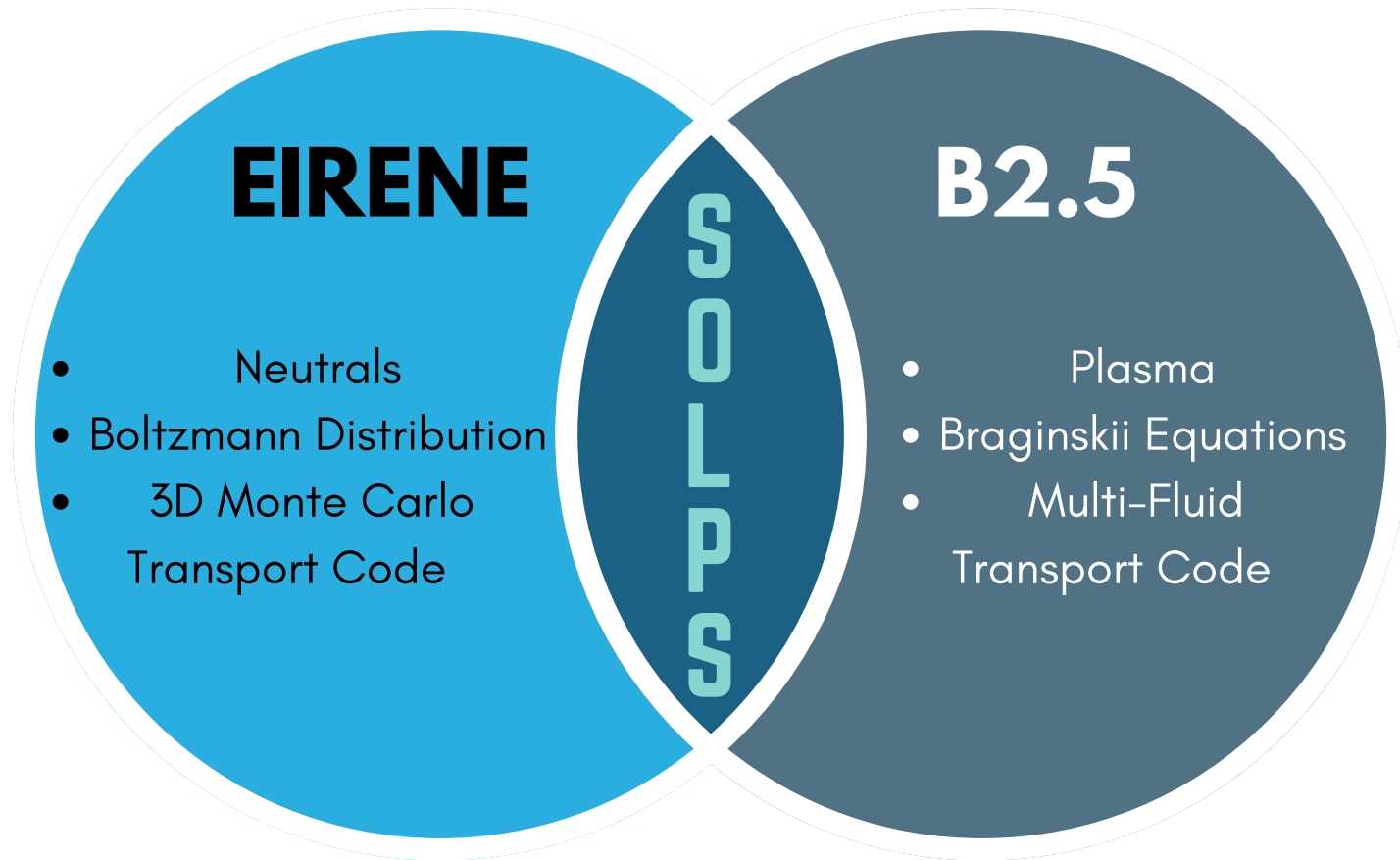
Source:
ELM Instabilities in MAST-U.
S.F.Smith, S.J.P. Pamela,
M. Hölzl, G.T.A. Huijsmans.
UKAEA.

Universal Function Approximation Theorem of Neural Networks

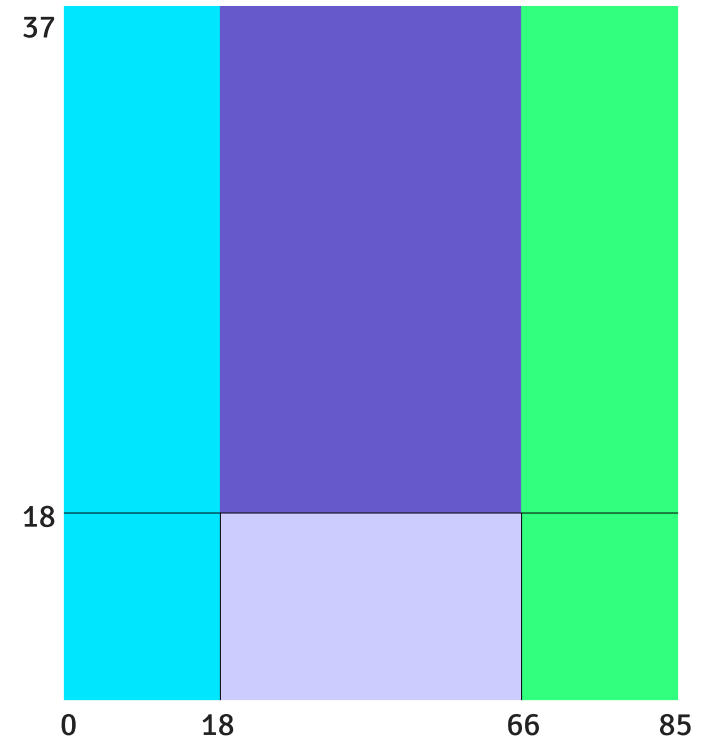
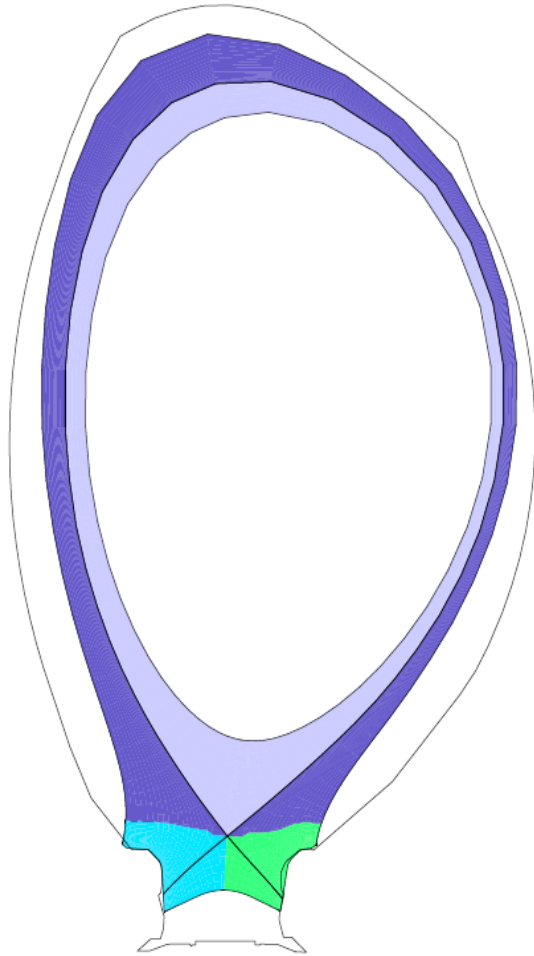
States that “a feed-forward network with finite hidden layers each consisting of finite number of nodes can approximate continuous functions on compact subsets of \mathbb{R}^n ”.

- Kurt Hornik, Maxwell Stinchcombe, and Halbert White. Multilayer feedforward networks are universal approximators. *Neural Networks*, 2(5):359 – 366, 1989.
- G. Cybenko. Approximation by superpositions of a sigmoidal function. *Mathematics of Control, Signals and Systems*, 2(4):303–314, Dec 1989.

Scrape Off Layer Plasma Simulator



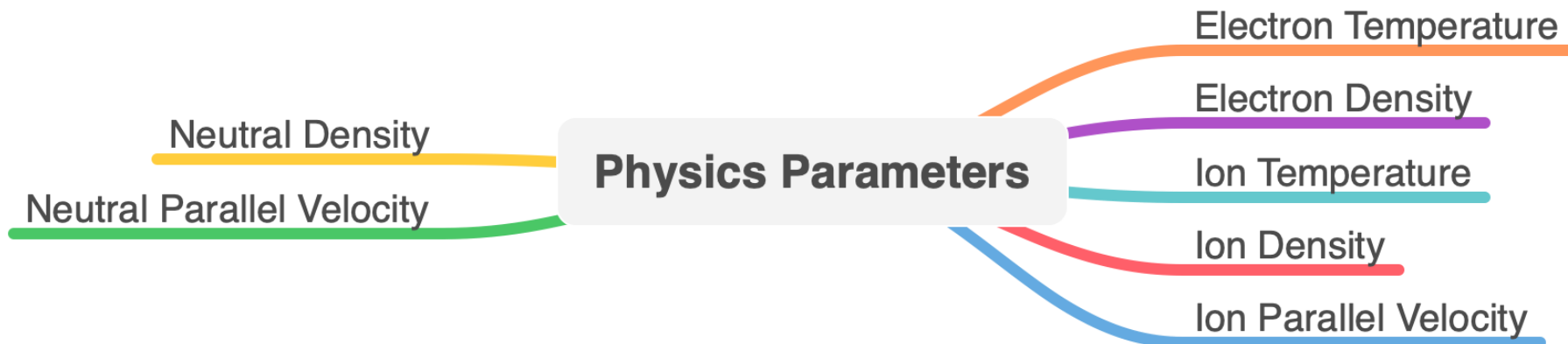
Grid Representation



M. Stanojevic X. Bonnin D.P Coster, A. Kukushkin
et al. Solps manual.

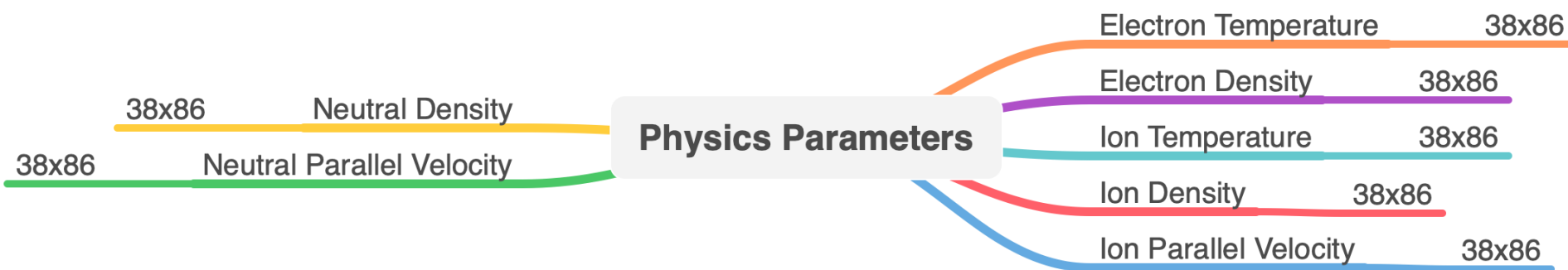
Parameters under Study

Training Data Gathered from previous SOLPS simulations



Parameters under Study

Training Data Gathered from previous SOLPS simulations



7 x (38x86) grids characterising Plasma Behaviour across the quadrangular representation of the Poloidal Cross-Section.

Phase I: Perturb the steady state by changing one or more of the modelling parameters

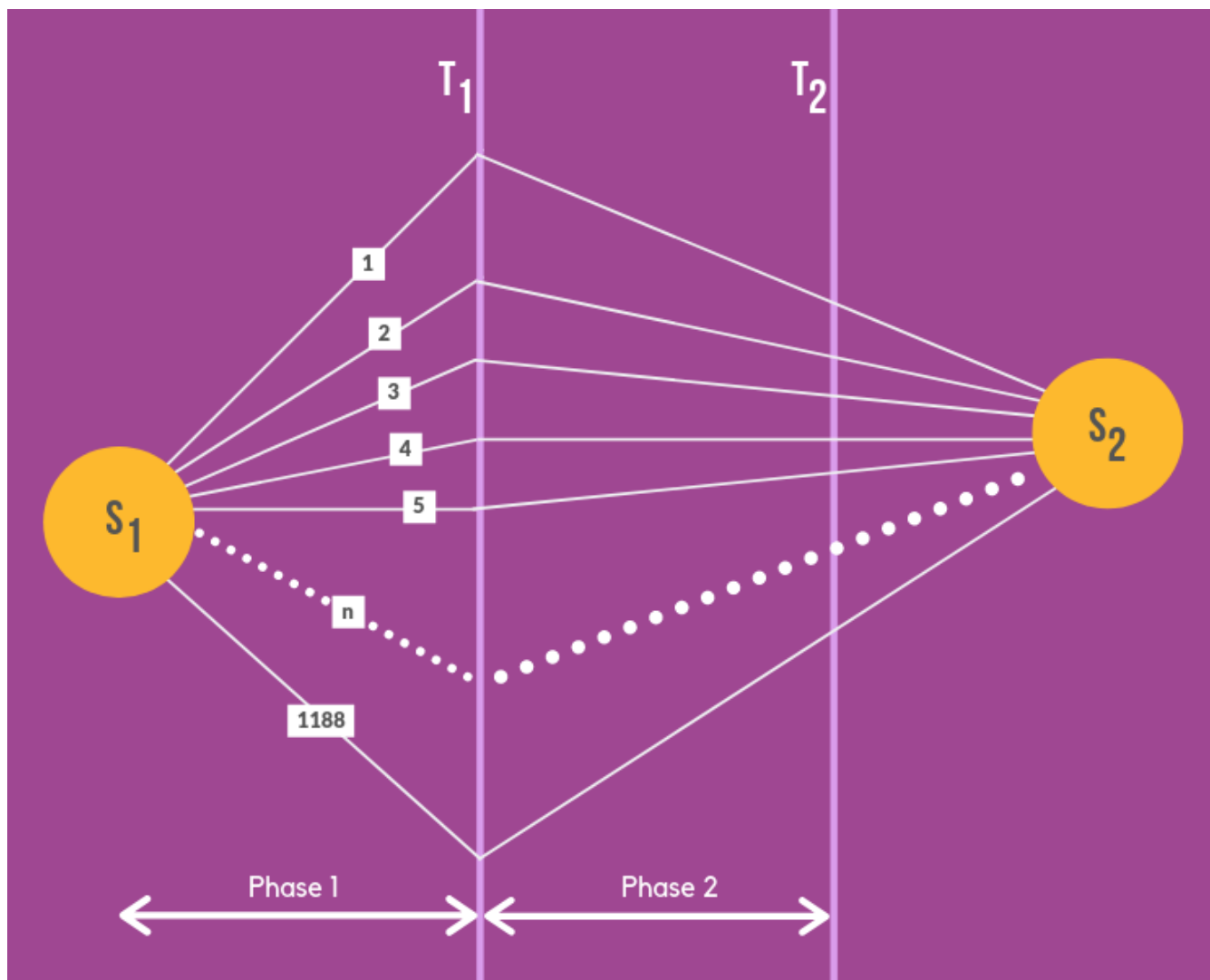
- Heating Power
- Puffing Rate
- Pump Intensity

Phase I simulations will help create the input datasets characterising the initial state of the edge.

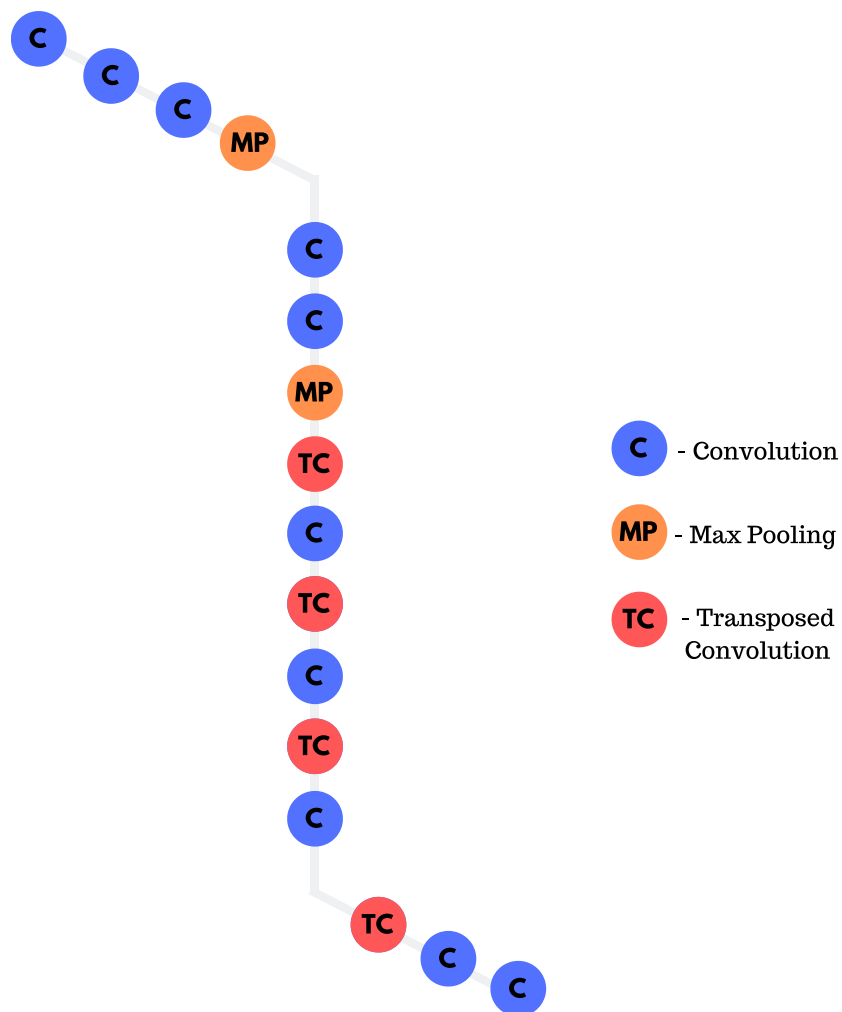
Phase II: The outputs of the Phase I simulations are run with a fixed value of the three modelling parameters to run back to steady state.

Phase II simulations will help create the output datasets characterising the final state of the edge.

Data Generation

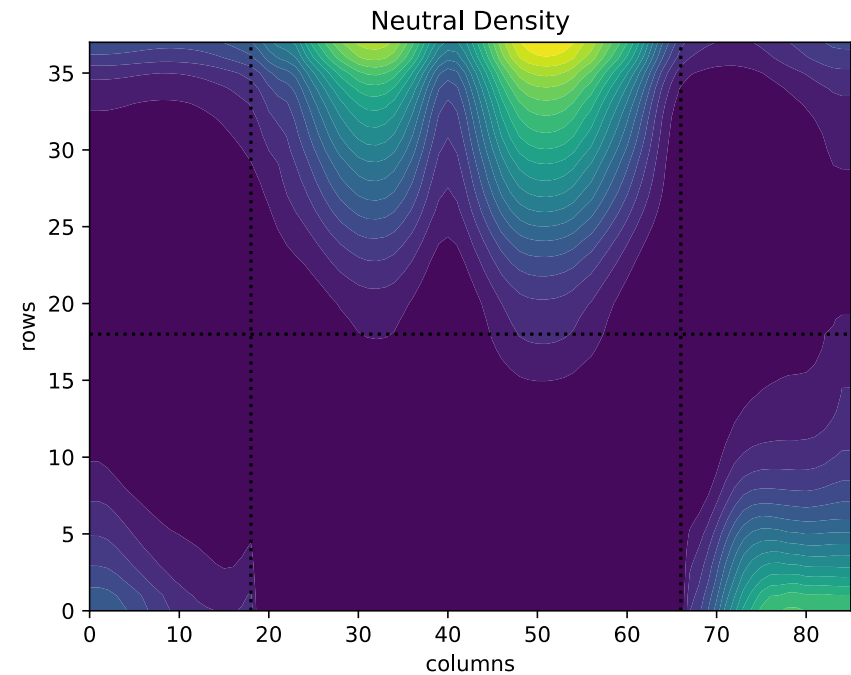
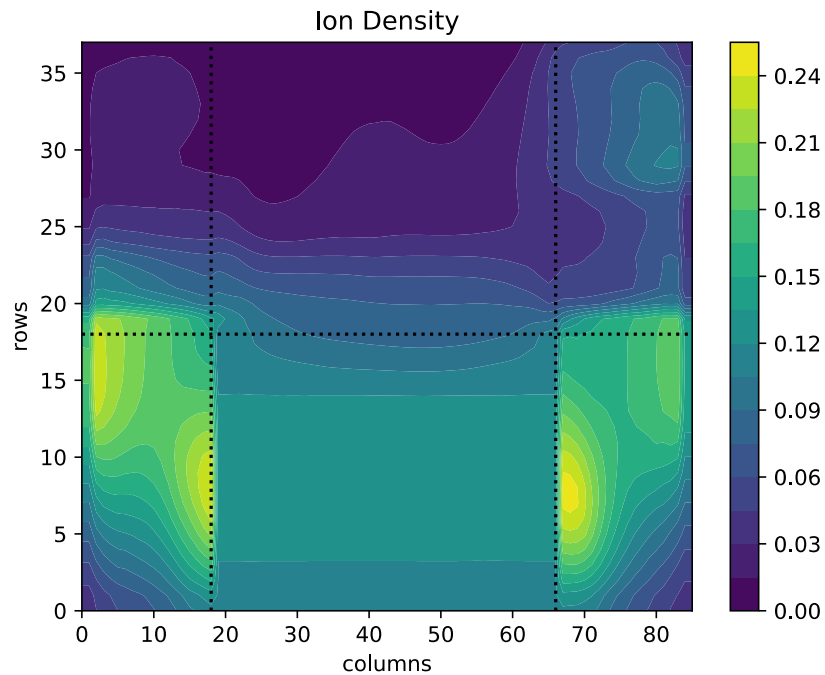


Initial Network



Results: Initial Network

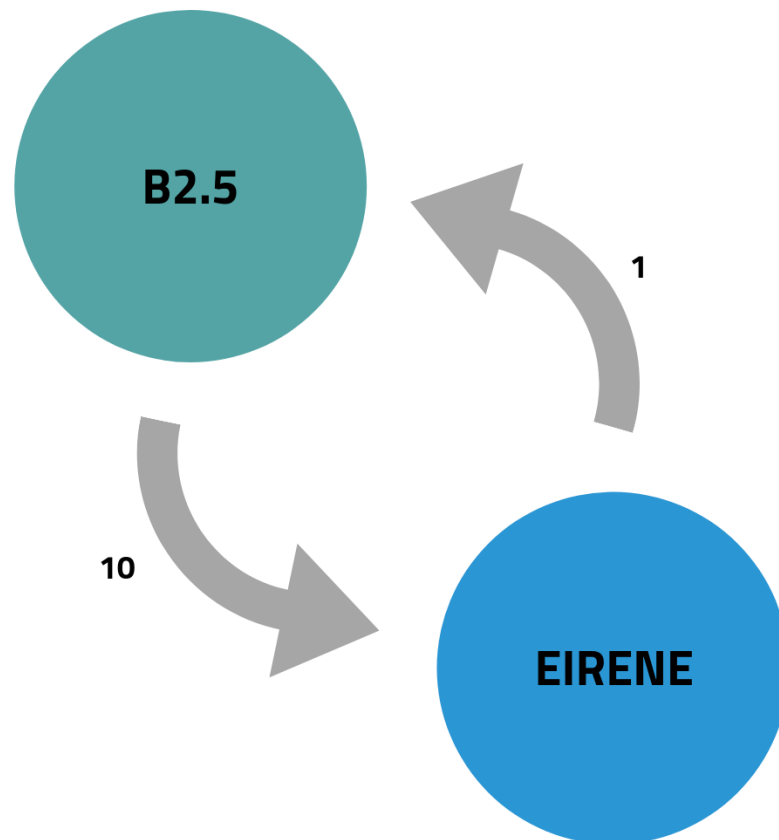
SOLPS Solution - Filled Contour Plots in Green and Blue
NN Solution – Line Contour Plots in Red and Orange



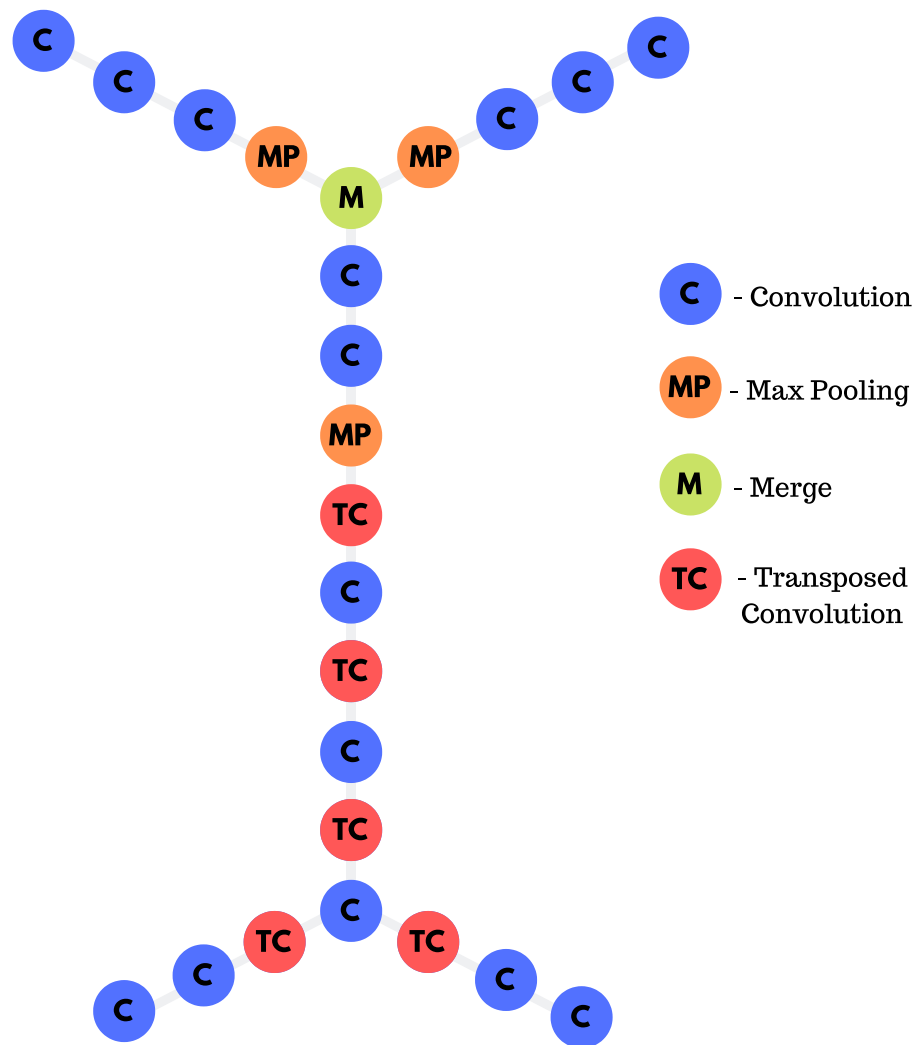
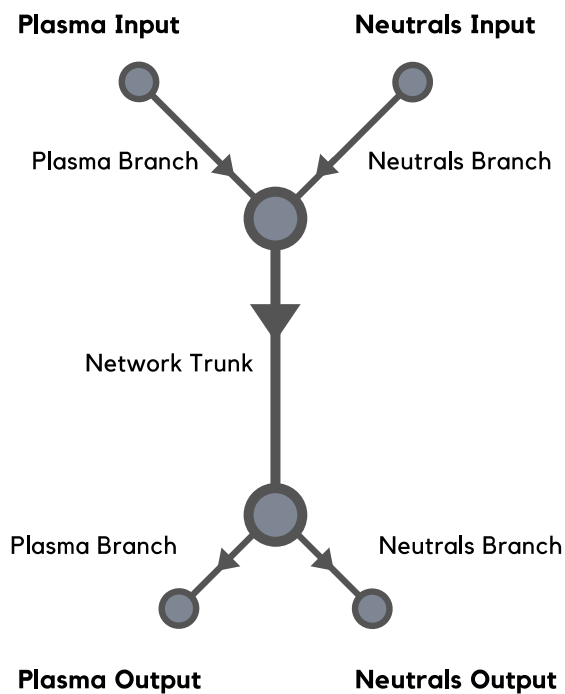
Now what could be messing up from getting a solid fit ?

- EIRENE introducing random noise ?
- Imbalanced Dataset ?
- Lack of dedicated layers to pick up differing non-linearities ?

Information Exchange within SOLPS

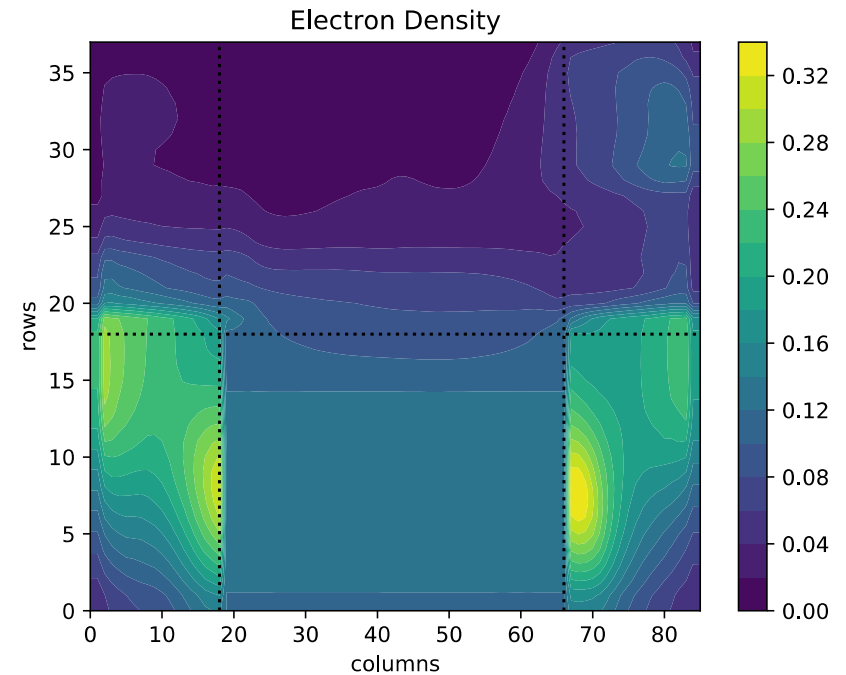
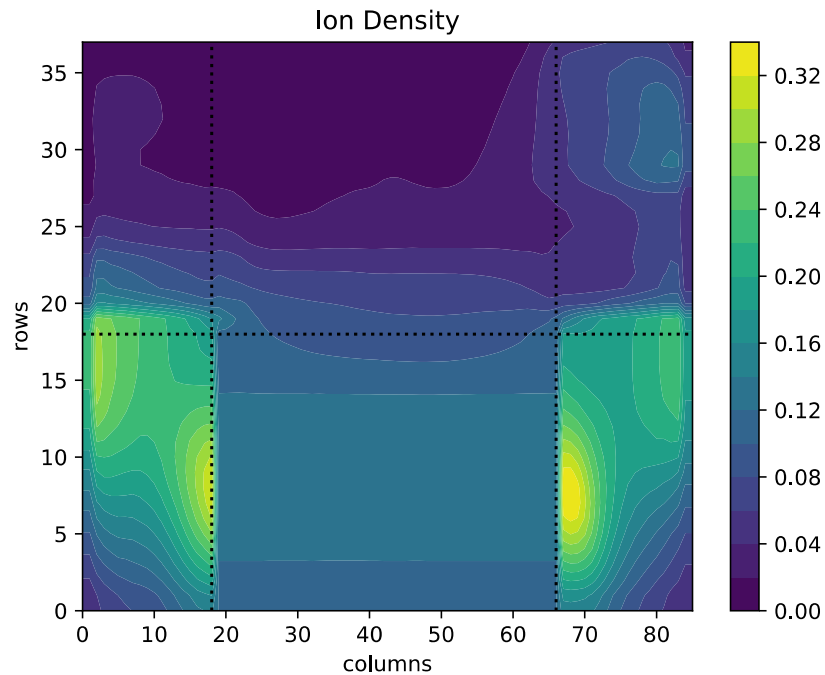


Bifurcated Network



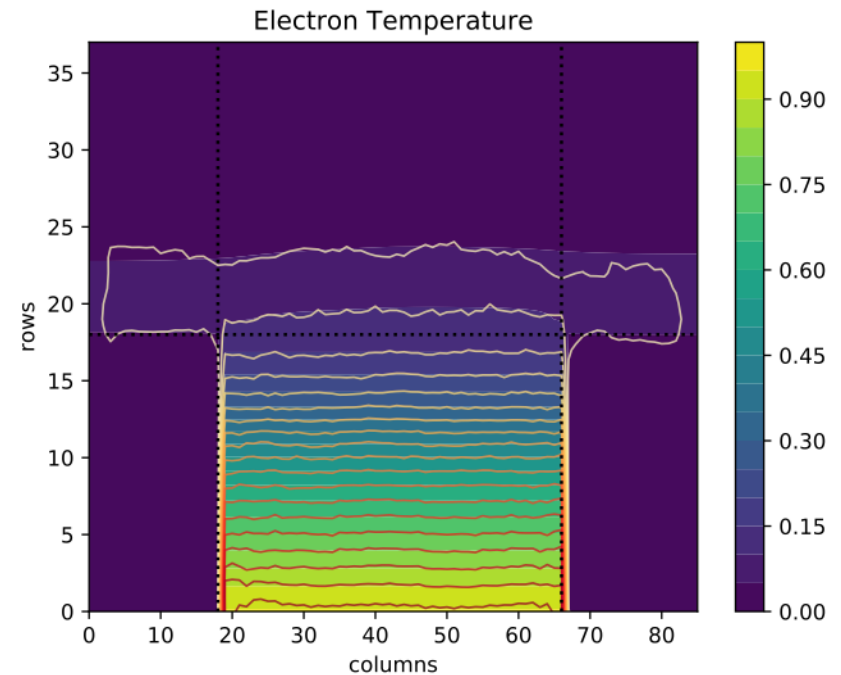
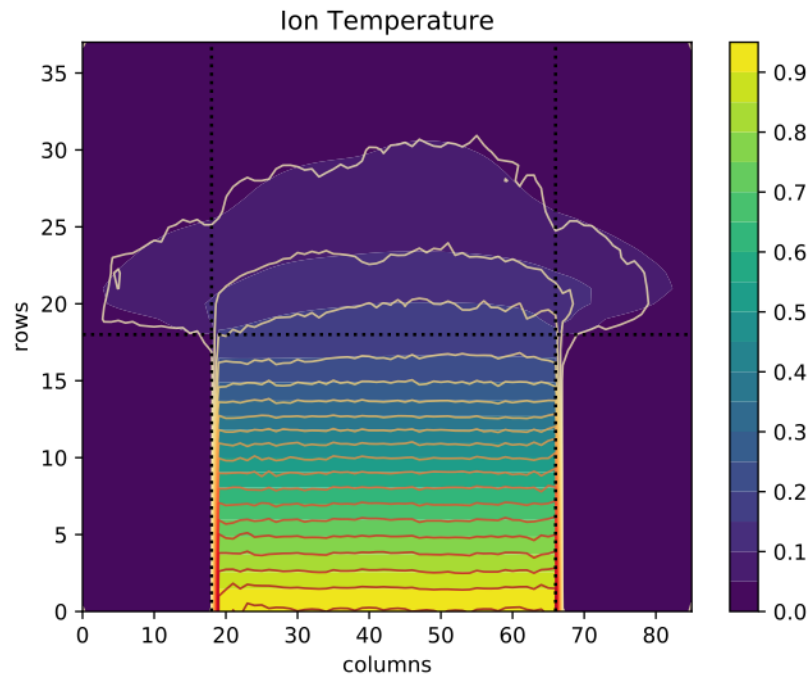
Results: Bifurcated Network

SOLPS Solution - Filled Contour Plots in Green and Blue
NN Solution – Line Contour Plots in Red and Orange

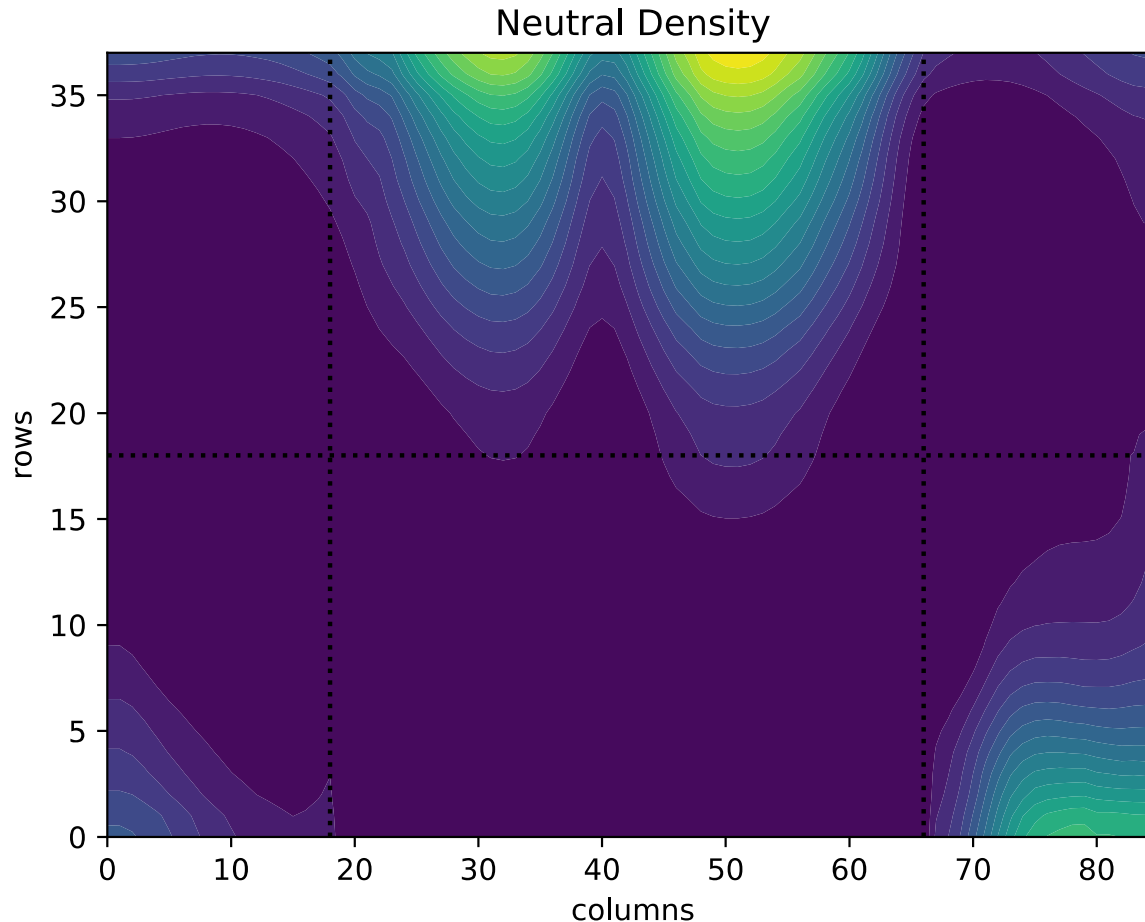


Results: Bifurcated Network

SOLPS Solution - Filled Contour Plots in Green and Blue
NN Solution – Line Contour Plots in Red and Orange



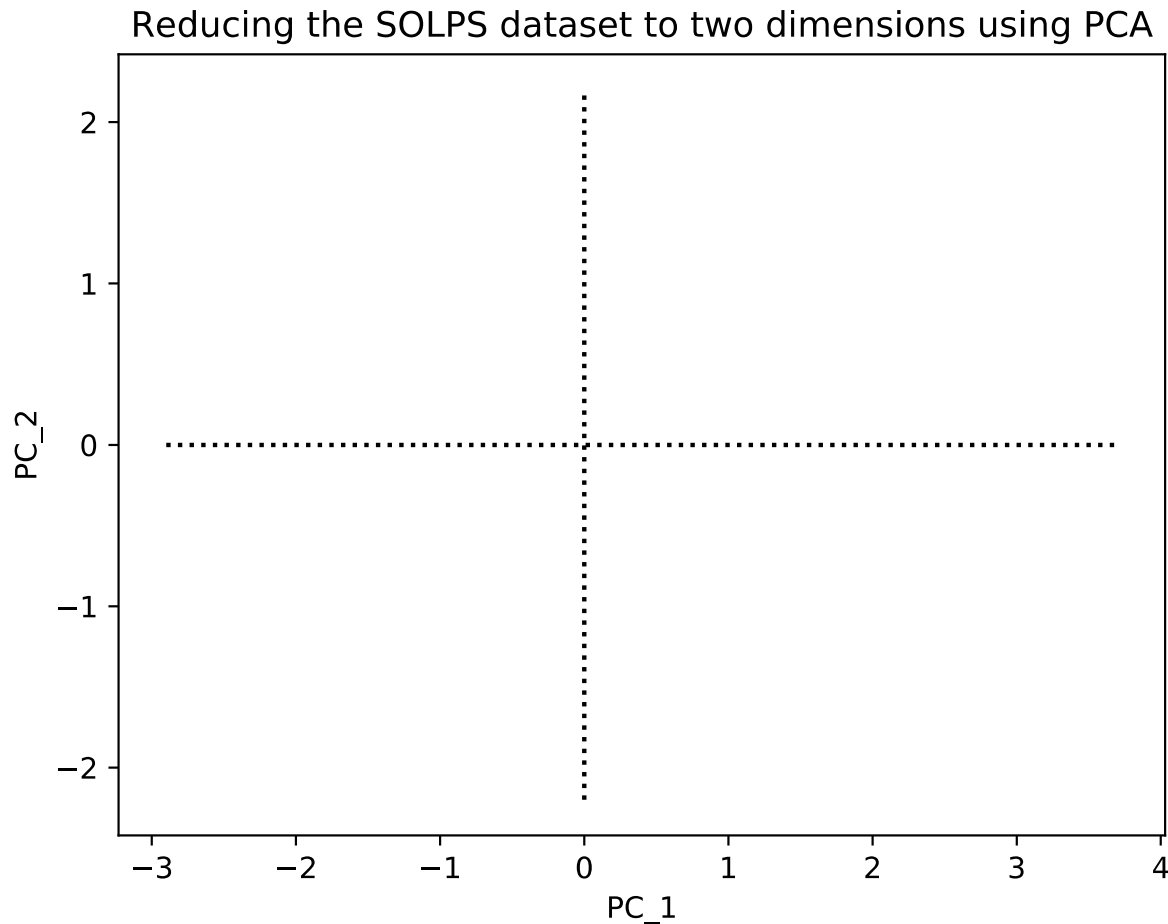
Results: Bifurcated Network

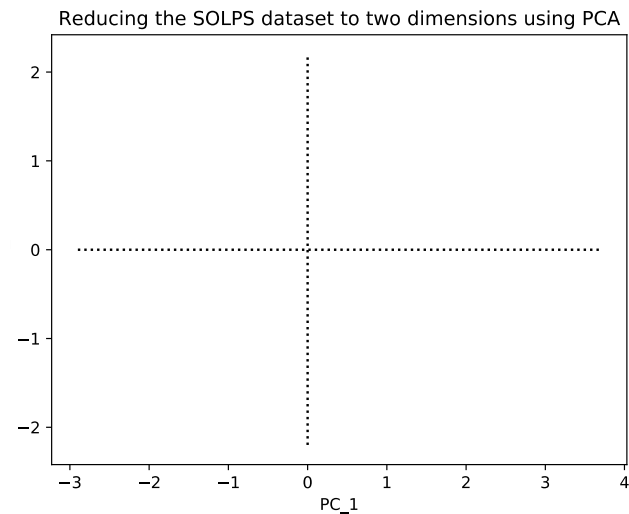
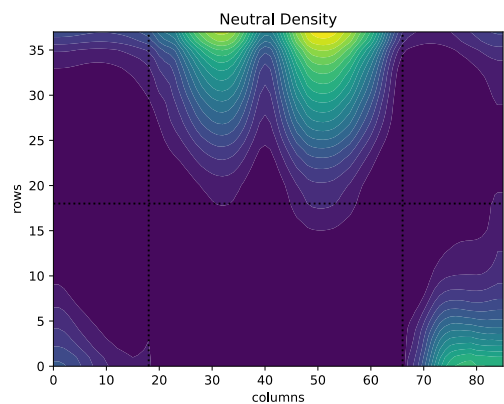
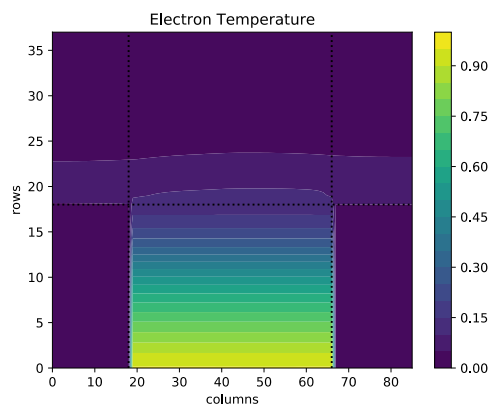
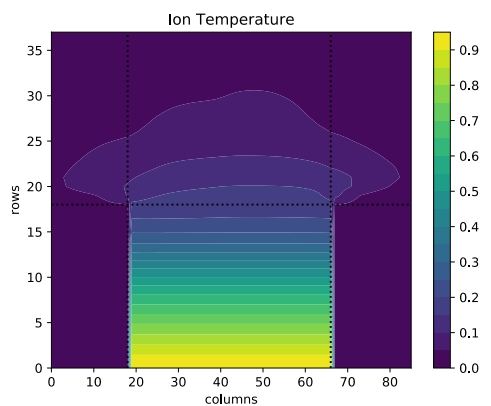
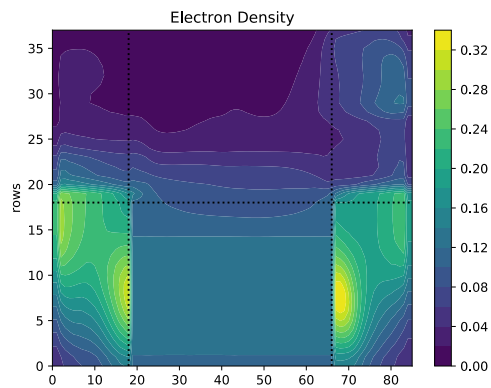
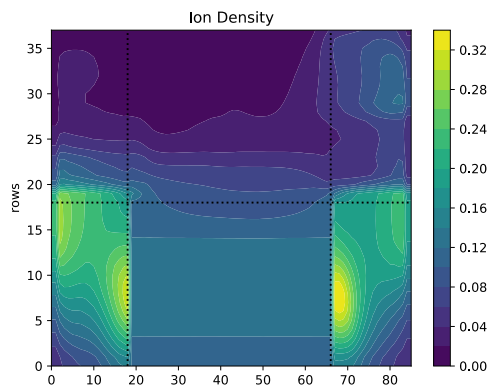


SOLPS Solution - Filled Contour Plots in Green and Blue

NN Solution – Line Contour Plots in Red and Orange

Data Diversity : Principal Component Analysis





Edge Solution	Configuration	Time Taken	Training Time
SOLPS on ITM	2 x 18 @ 2.3 GHz	2 – 3 hours	N/A
SOLPS_FCN on FREIA	1 x 16 @ 2.6 GHz	0.033 seconds	117 minutes

Time Gain of more than 5 orders of Magnitude
Without much compromise on Accuracy.

Can be employed in a Predictor-Corrector Fashion.

But still a Black Box !

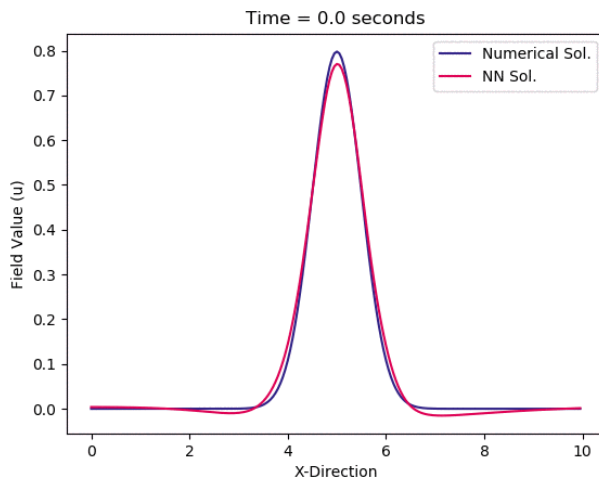
Convection-Diffusion Equation:

$$\frac{\partial u}{\partial t} + c \frac{\partial u}{\partial x} = D \frac{\partial^2 u}{\partial x^2}$$

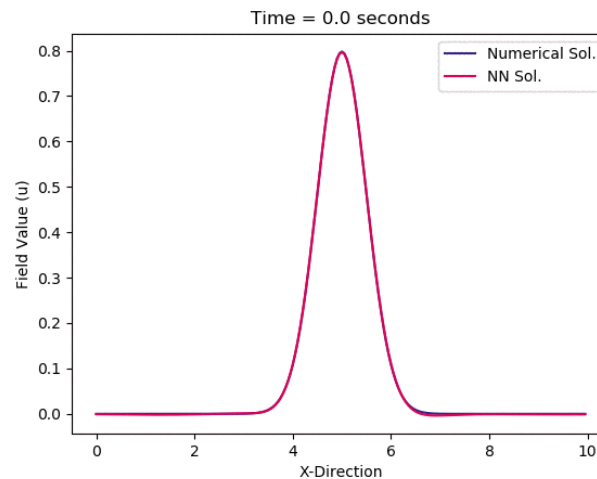
Hybrid Loss Function = Functional Loss + Reconstruction Loss

$$\text{Functional Loss} = \frac{\partial u'}{\partial t} + c \frac{\partial u'}{\partial x} - D \frac{\partial^2 u'}{\partial x^2}$$

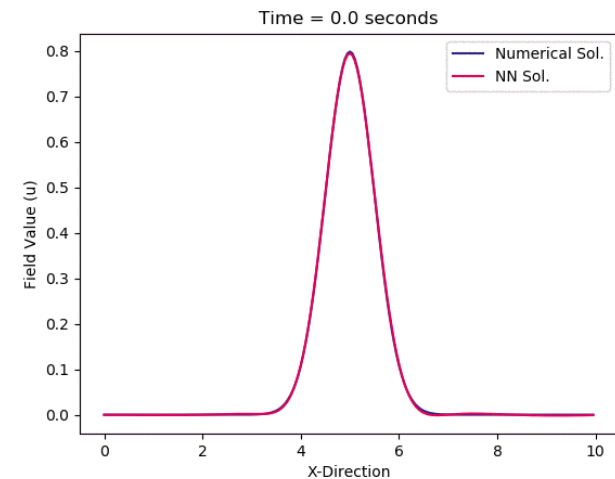
$$\text{Reconstruction Loss} = \Sigma(u - u')^2$$



Reconstruction



Functional



Hybrid

Trained up to 1 second
Tested up to 2 seconds

Operation Tokamak



Tokamak Operation

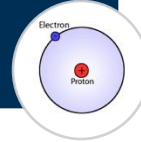
Magnetics



Heating



Fuel



Exhaust

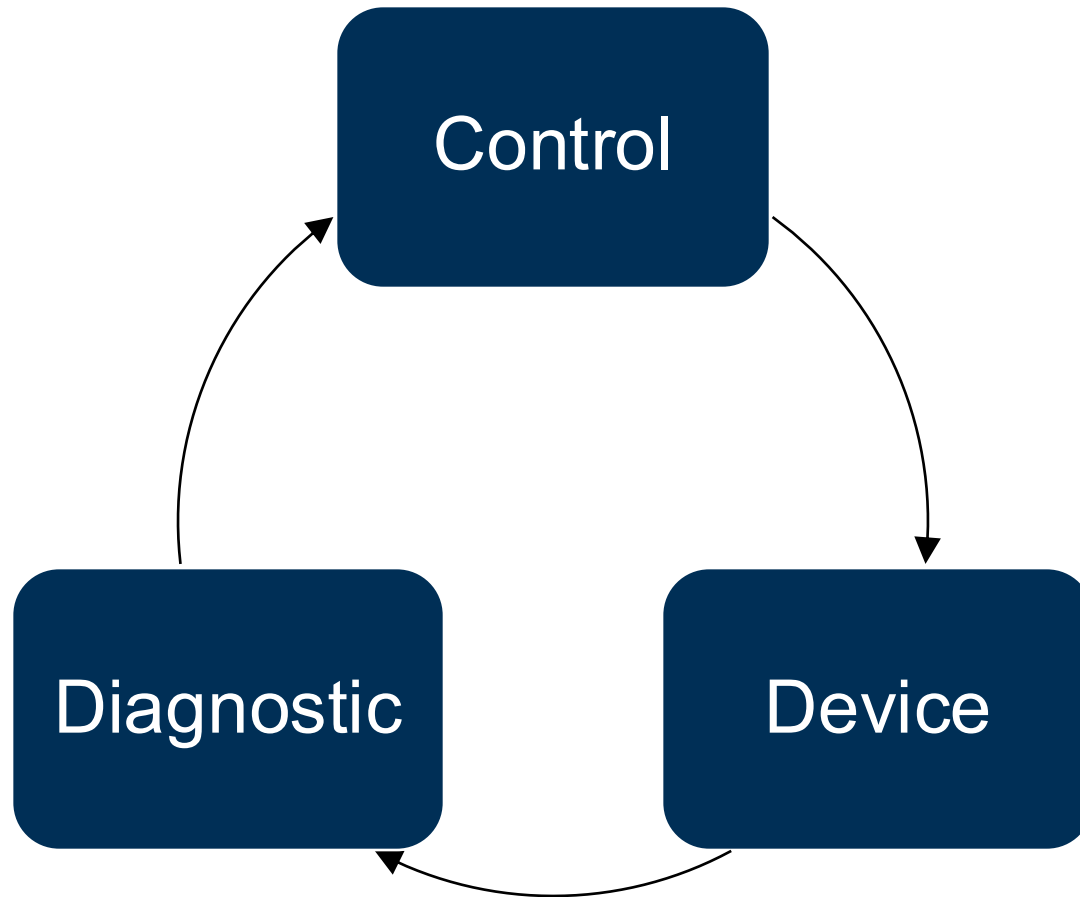


Control 1000s of parameters that influence the confinement of the plasma.

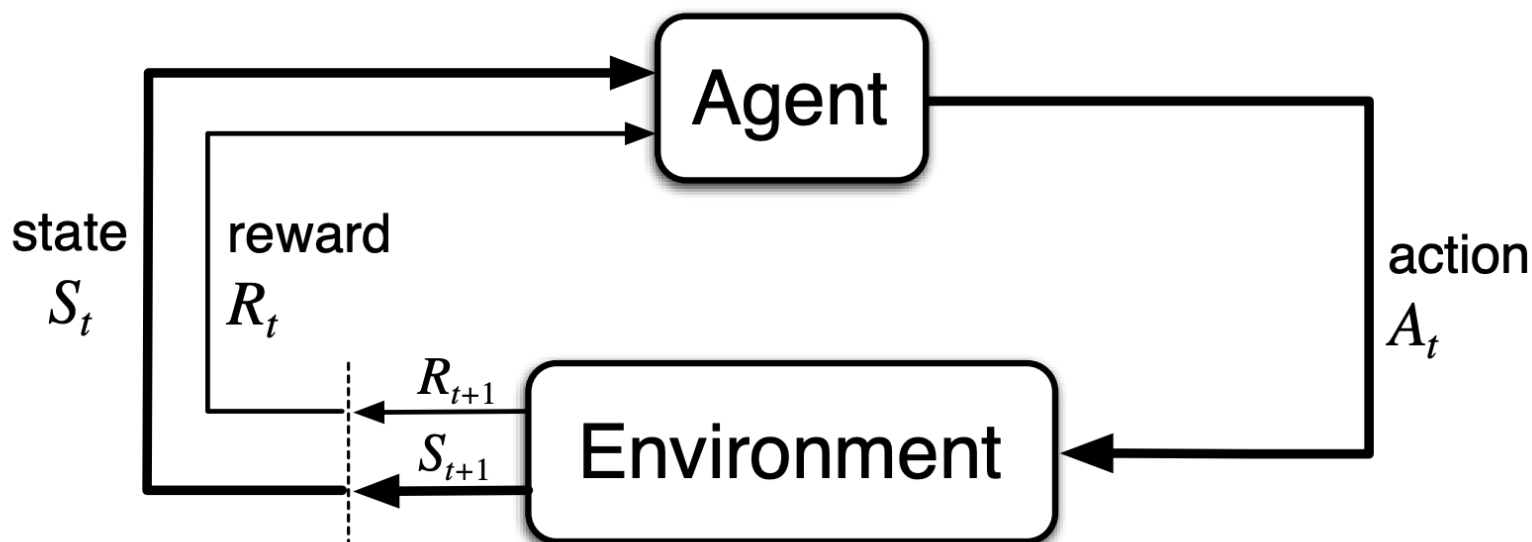
All the while dealing with instabilities and avoiding disruptions

Extended Stable Plasma control requires a prophetic knowledge of how the Plasma would evolve in time.

Operation Cycle



Exploring the Configuration Space of the operation cycle via Deep Reinforcement Learning



Source: R. Sutton – Reinforcement Learning: An Introduction

Conclusion

Barely Scratched the Surface ...

Extract the complex nonlinear nature of Fusion Plasma effectively using deterministic AI approaches. Use ML based exploratory techniques to improve our control and performance of Fusion Devices.

Vast amounts of Experimental + Simulation Data

Building a team that is currently working with :

Rutherford Appleton Laboratory
University College London
Imperial College London
University of Oxford

And looking for collaborations from ML experts within the industry.

Thanks. Questions ?

Vignesh Gopakumar
Fusion Specific Machine Learning Engineer



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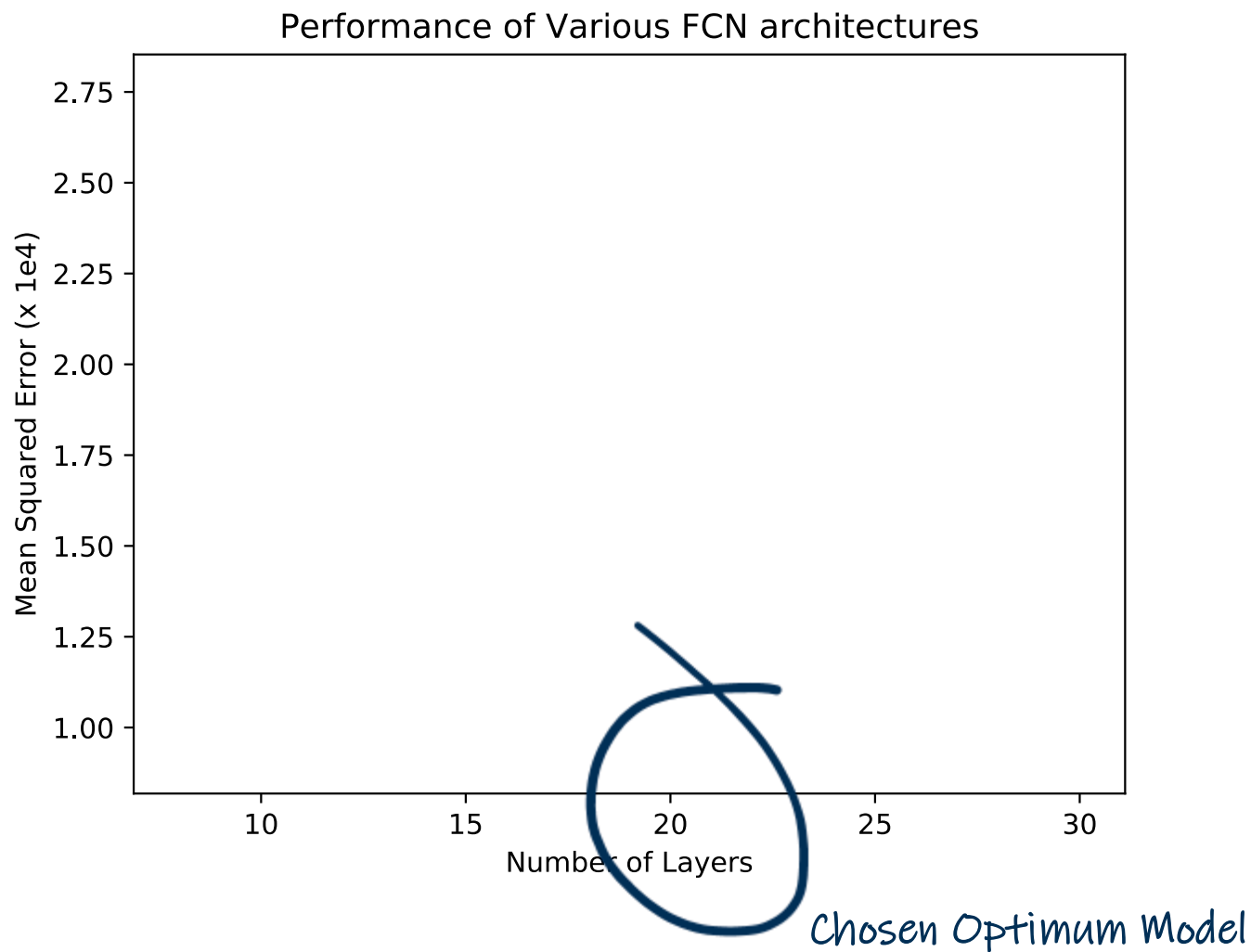
@littlevgkumar



[linkedin.com/in/vignesh-gopakumar](https://www.linkedin.com/in/vignesh-gopakumar)

Appendix Slides

Depth Variation



Phase I :

Initial Steady State Config :

Heating Power	4.080 MW
Puffing Rate	10^{21} s^{-1}
Pump Intensity	94 %

Parameter Scan :

Parameter	Min.	Max.	Step	Number
Heating Power	3.0 MW	8.5 MW	+ 0.5 MW	12
Puffing Rate	10^{17} s^{-1}	10^{21} s^{-1}	x 5.0	9
Pump Intensity	48 %	98 %	+ 5 %	11

Total Number of Simulations : $12 \times 9 \times 11 = 1188$

Phase II :

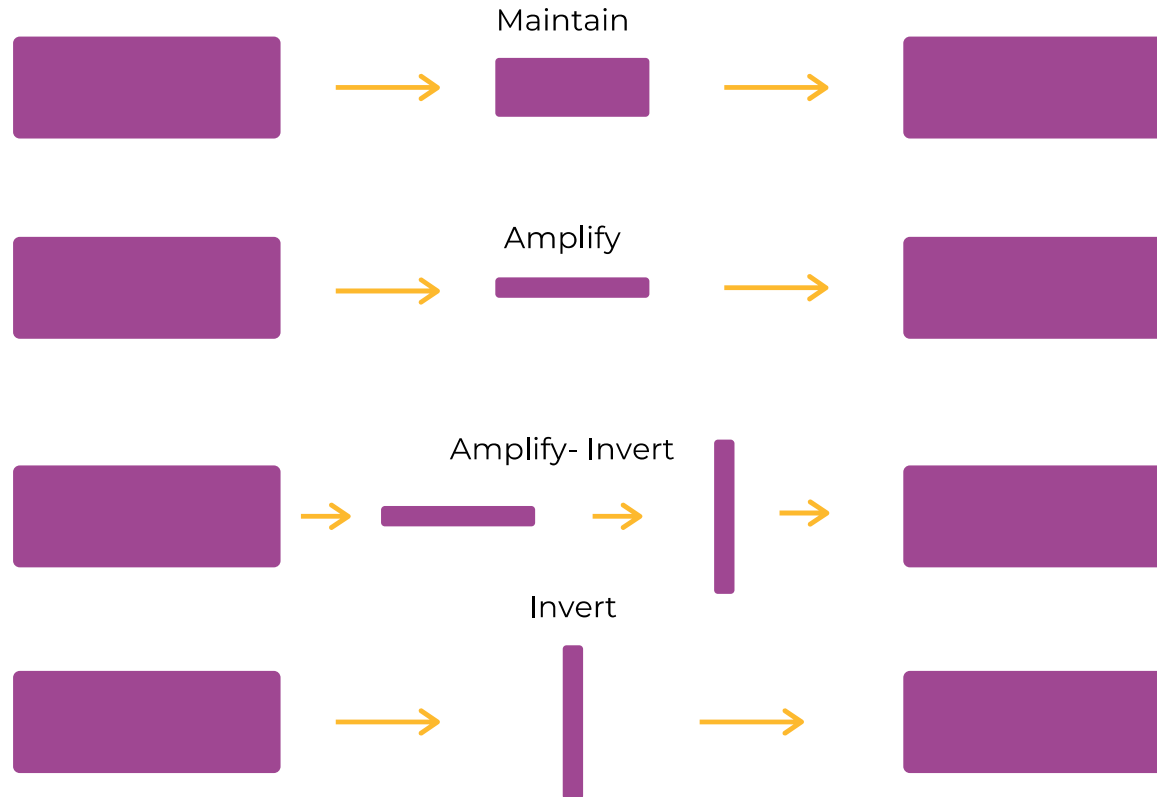
Final push towards Steady State Config :

Heating Power	3.0 MW
Puffing Rate	10^{18} s^{-1}
Pump Intensity	94 %

Output of Phase I → Input Data
Output of Phase II → Output Data

Labelled, Matching Dataset

Convolutional Strategies



Convolutional Strategies

Performance of Convolutional Strategies

