Format

- The purpose of the quals is to ensure that you have a breadth of knowledge across all the major topics in machine learning and its mathematical foundations.
- You should take your quals in your second year if you already have machine learning experience prior to starting your Ph.D. and your third year if you're new to machine learning.
- You should understand the basic idea behind each of the topics well enough to teach/explain the topic to a new CS Ph.D. student.
- The oral exam is 1.5 hours long. Three professors will each ask two questions, for a total of six questions.
- Each question will be based on the following types:
 - o For some topic X:
 - Give a brief one minute tutorial answer to "What is X?"
 - Write the formal definition on the board, and perform some basic derivations.
 - Give concrete examples of its use.
 - Explain its significance.
 - Compare and contrast two or more topics (e.g., compare SVMs and neural networks).
- Some follow up questions might include
 - When would you use this approach in practice?
 - When would you use one approach over another?
 - What are the strengths/weaknesses of an approach?
 - Let's specialize to this particular example. What are the implications?
- Things that you're not responsible for
 - Detailed proofs.
 - Knowing the constants on bounds.
 - Solving pset-style problems.

Tips

- Start studying early.
- Practice answering questions and explaining topics on the whiteboard to a friend.
 Especially if you're unfamiliar with oral exam, your ability to communicate your knowledge and answer follow-up questions is at least as important as you knowing the material.

Topics

- Supervised learning
 - Logistic regression

- Support vector machines
- Neural networks
- Boosting (AdaBoost)
 - Rob Schapire's lecture <u>notes</u> on AdaBoost (the proof of Theorem, starting from the middle of page 4, is optional)
 - Alternatively, <u>coordinate-descent interpretation</u>
 - Some broader views (optional)
- Decision trees
- Random forests

Kernels

- Definition of kernel function
- Types of kernels (linear, polynomial, RBF)
- Reproducing Kernel Hilbert Space (RKHS)
- Deep learning
 - Convolutional neural networks
 - Autoregressive models
 - Recurrent neural networks
 - Attention, transformers
 - Generative adversarial networks
- Unsupervised learning
 - K-means
 - Expectation Maximization
 - PCA
 - Matrix factorization
 - Variational autoencoders
- Reinforcement learning
 - Markov decision process
 - Value iteration
 - Model-based RL
 - SARSA
 - Q learning
 - o TD learning
 - Policy gradient
- Probability and statistics
 - Distributions
 - Gaussian
 - Poisson
 - Gamma
 - Dirichlet
 - Multinomial
 - Exponential family
 - Sufficient statistics
 - Maximum likelihood

- Asymptotic normality of M estimators
- Fisher information
- Information theory [Cover and Thomas, Elements of Information Theory, Chapter 2],
 - Entropy, conditional entropy
 - Mutual information
 - KL divergence
- Bias-variance tradeoff (for squared loss)
- Jensen's inequality
- Hypothesis testing
 - p-value, power
 - t-test
 - Bootstrap
 - Multiple hypothesis testing
- Optimization [see below, but appropriate references covering everything are Boyd and Vandenberghe's <u>Convex Optimization</u> and Duchi's <u>Introductory Lectures on Convex Optimization</u>, chapters 2--3]
 - Algorithms (including convergence rates for convex and strongly convex cases)
 - Gradient descent
 - Newton's method
 - Stochastic gradient method
 - Types of programs
 - Linear programming
 - Quadratic programming
 - Semidefinite programming
 - Lagrangian duality
 - Weak versus strong duality
 - Complementary slackness
 - KKT conditions
- Online learning [Hazan's <u>Introduction to Online Convex Optimization</u>, chapters 1--3, 6.1--6.4]
 - Regret setting
 - Online gradient descent
 - Exponentiated gradient
 - Multi-armed bandits
- Bayesian methods
 - o Prior, likelihood, posterior
 - Basic posterior computations for conjugate priors (Gaussian, Dirichlet)
 - Marginal likelihood, model selection
 - Hypothesis testing
 - Bayesian mixture model
 - Latent Dirichlet Allocation
 - Approximate inference

- Variational Bayes
- Gibbs sampling
- Graphical models
 - Bayesian networks
 - Explaining away
 - d-separation
 - Parameter estimation
 - Markov networks
 - Partition function
 - Parameter estimation
 - Inference
 - Exact inference in trees via dynamic programming
 - Loopy belief propagation, Bethe free energy
 - Mean-field variational inference
 - Sampling
 - Monte Carlo integration
 - Importance sampling
 - Gibbs sampling
 - Metropolis-Hastings
 - Detailed balance (definition)
 - Sequential Monte Carlo / particle filtering
 - Structure learning
 - Chow-Liu trees
- Differential privacy [at the level of Chapters 1, 2, and 3.1--3.5.0 (i.e. pages 1-43) of Dwork and Roth's Algorithmic Foundations of Differential Privacy]
 - Basic mechanisms (e.g. randomized response, Laplace mechanism, sensitivity)
 - Composition of privacy (not advanced composition)
- Causality
 - Potential outcomes framework
 - Average treatment effect
 - Counterfactual inference / off policy batch RL (we can restrict to 1 time step if we want)
 - Propensity score matching / importance sampling
- Learning theory
 - PAC learning framework
 - Concentration inequalities
 - Hoeffding's inequality
 - Generalization bound for finite hypothesis class
 - Measures of complexity (definitions and basic examples)
 - VC dimension
 - Rademacher complexity OR metric entropy

Readings

These are general references which should cover most (but not all) the topics above. You are also encouraged to read more widely.

- CS229 lecture notes: basic machine learning
- <u>CS229T lecture notes</u>: online learning, kernel methods, uniform convergence, asymptotic statistics
- <u>CS228 course notes</u>: covers most of the graphical model concepts above. For a more in-depth treatment of loopy belief propagation and Bethe free energy, see chapters 3-4 of <u>Wainwright and Jordan</u>. For sequential Monte Carlo, see <u>Doucet, de Freitas, &</u> Gordon.
- Optimization
 - Stephen Boyd's convex optimization book
 - For optimization and subgradient algorithms, Chapters 2 and 3 of Duchi's "Introductory Lectures on Convex Optimization," or the <u>subgradient method notes</u> <u>for ee364b</u> (Boyd/Duchi)
 - Optional: <u>Ryan Tibshirani's convex optimization course notes</u> for optimization algorithm descriptions and convergence rates
- <u>CS234</u> covers RL, bandits, and does batch RL which covers potential outcomes, average treatment effects, counterfactual inference and importance sampling.
- Sutton & Barto's reinforcement learning book

Classes

- CS221: artificial intelligence
- CS228: probabilistic graphical models
- CS229: machine learning
- CS229T: statistical learning theory
- EE364A, EE364B: convex optimization