

# Lecture - 11 FP67Qd.

FP67Qd

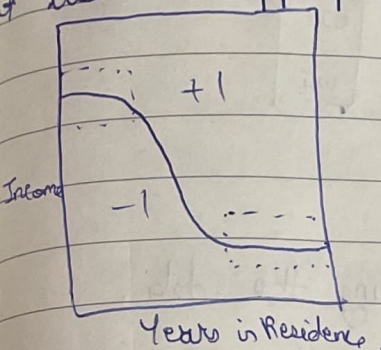
Recap: Linear model for 3 learning problem.

$$h(n) = w^T n \rightarrow \text{linear eq.}$$

\* Linear Model has limitations:-

Linearly not separable

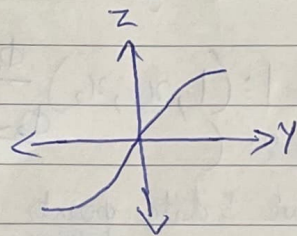
\* Use the appropriate feature.



$Y \gg 3$  years, no additional effect beyond  $Y=3$ .  
 $Y \ll 0.3$  years, no additional effect below  $Y=0.3$ .

\* Change the feature using a transform.

$$Y \xrightarrow{\Phi} Z$$

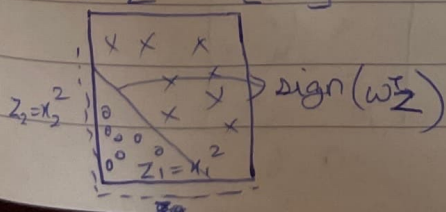


\* Mechanics of Non-linear Feature transforms.



$(x-c_1)^2 + (y-c_2)^2 = r^2$ , since this is not linear. Let's perform feature transform.

$$\Phi \downarrow \begin{matrix} x = \begin{bmatrix} 1 \\ x_1 \\ x_2 \end{bmatrix} \xrightarrow[\text{transform}]{\Phi} z = \begin{bmatrix} 1 \\ z_1 \\ z_2 \end{bmatrix} = \begin{bmatrix} 1 \\ \Phi(x_1) \\ \Phi(x_2) \end{bmatrix} = \begin{bmatrix} 1 \\ x_1^2 \\ x_2^2 \end{bmatrix}$$





Feature transforms in ~~General~~ General.

$x$ -space is  $\mathbb{R}^d$ .

$Z$  space is  $\mathbb{R}^{\tilde{d}}$

$$x = \begin{bmatrix} 1 \\ x_1 \\ \vdots \\ x_d \end{bmatrix}$$

$$z = \Phi(x) = \begin{bmatrix} 1 \\ \Phi_1(x) \\ \vdots \\ \Phi_d(x) \end{bmatrix} = \begin{bmatrix} 1 \\ z_1 \\ \vdots \\ z_{\tilde{d}} \end{bmatrix}$$

$$(x_1, y_1), \dots, (x_N, y_N)$$

$$(z_1, y_1), \dots, (z_N, y_N)$$

$$g(x) = \text{sign}(\tilde{w}^T \Phi(x))$$

↑  
non linear eq<sup>n</sup>.

$$\tilde{g}(z) = \text{sign}(\tilde{w}^T z)$$

↑  
linear eq<sup>n</sup>.

$$\tilde{w} = \begin{bmatrix} w_0 \\ w_1 \\ w_2 \\ \vdots \\ w_{\tilde{d}} \end{bmatrix}$$

★ Do not pick  $\Phi$  (feature transform) after seeing the data.  
pick  $\Phi$  before seeing the data.

★ Polynomial feature transform:-

Degree 1:  $(1, x_1, x_2) \xrightarrow{\Phi_1} (1, x_1, x_2)$

Degree 2:  $(1, x_1, x_2) \xrightarrow{\Phi_2} (1, x_1, x_2, x_1^2, x_1 x_2, x_2^2)$

$$\tilde{d}_{vc} = 3$$

$$\tilde{d}_{vc} = 6$$

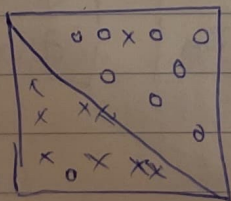
If we have 5 data points use 4<sup>th</sup> degree polynomial function.

$$x = \begin{bmatrix} 1 \\ x_1 \\ x_2 \end{bmatrix} \xrightarrow[\text{degree 2}]{\Phi_2} \Phi_2(x) = \begin{bmatrix} 1 \\ \Phi_1(x) \\ \Phi_2(x) \\ \vdots \\ \Phi_5(x) \end{bmatrix} = \begin{bmatrix} 1 \\ x_1 \\ x_2 \\ x_1^2 \\ x_1 x_2 \\ x_2^2 \end{bmatrix}$$

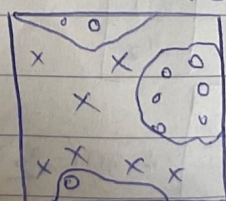
If we have higher order polynomial we will have less misclassified data points.

overfitting.

Take away:- Use simpler order function when we have small dataset



$$Q = 1$$



$$Q = 4$$