

Algorithm Techniques

Constraints Satisfaction Problem
and Backtracking

Xian Su

Recommended Reference Material:

- Github Open Source Project: [Hello Algo](#)
- Github Repo: [krahets/hello-algo](#)
- Animated Illustrations
- Support More than 10 Programming Languages
- Programming, Data Structure, Algorithm, and Algorithm Techniques

👁 Watch 569 ▾

🔗 Fork 13.3k ▾

★ Starred 106k ▾

1. Constraint Satisfaction Problems

Understand the definition and characteristics of constraint satisfaction problems (**CSPs**)

2. Backtracking

Grasp how backtracking serves as a fundamental approach for CSPs

3. Learn how to enhance backtracking with techniques like constraint propagation

4. Complexity Analysis

Analyze **time** and **space complexity** through sample code or pseudo-code.

5. Be able to apply these ideas to classic **puzzles** like **Sudoku**, **N-Queens**, **Eight Numbers in Cross-shape boards**, etc.

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.

2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

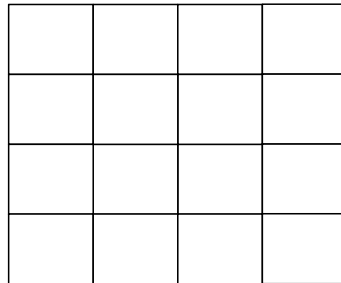
1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.

Example: Given 4 queens 

How to model this question to CSP?

and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

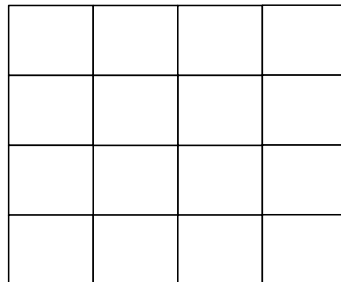
1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.

Example: Given 4 queens 

How to model this question to CSP?

and one 4*4 board



constraints -> "no threaten to each other"

Place all Queens on the board, and
no two queens threaten each other.

2 - N-Queens Problem

What is Constraint Satisfaction Problem?

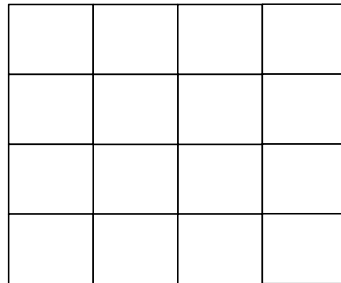
A CSP is typically defined by:

1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.

Example: Given 4 queens 

and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

How to model this question to CSP?

constraints -> "no threaten to each other"

variables -> four queens: q_1, q_2, q_3, q_4

2 - N-Queens Problem

What is Constraint Satisfaction Problem?

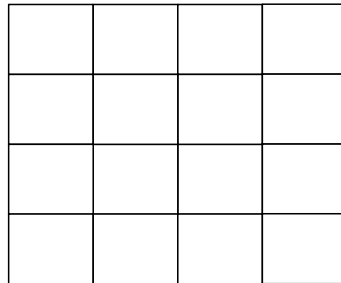
A CSP is typically defined by:

1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.

Example: Given 4 queens 

and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

How to model this question to CSP?

constraints -> "no threaten to each other"

variables -> four queens: q_1, q_2, q_3, q_4

domains -> ???

2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

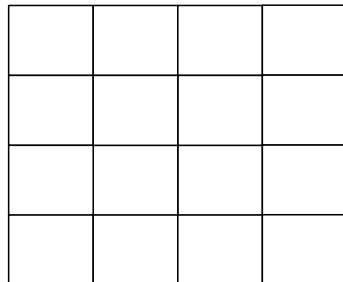
1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.

Example: Given 4 queens

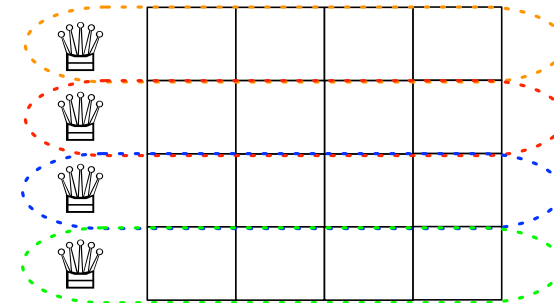


and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

How to model this question to CSP?



each row could be one container

-> `board[0], board[1], ...`

-> `board[q1], board[q2], ...`

2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

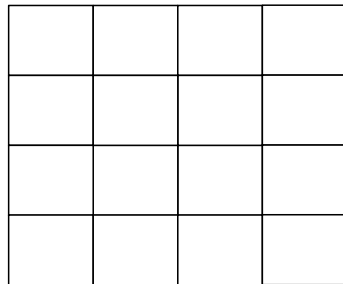
1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.

Example: Given 4 queens

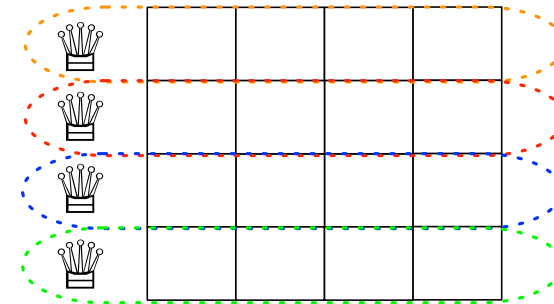


and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

How to model this question to CSP?



$\text{board}[q_1], \text{board}[q_2], \dots$

what is domain in this setup?

2 - N-Queens Problem

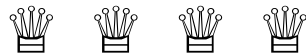
What is Constraint Satisfaction Problem?

A CSP is typically defined by:

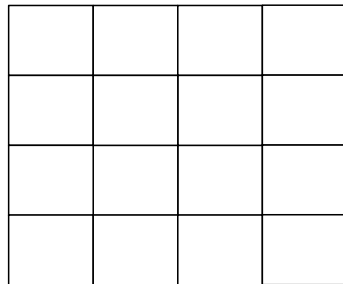
1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.

Example: Given 4 queens

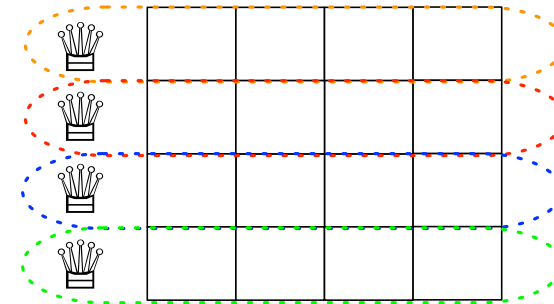


and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

How to model this question to CSP?



$\text{board}[q_1], \text{board}[q_2], \dots$

what is domain in this setup?

The positions in each row.

2 - N-Queens Problem

What is Constraint Satisfaction Problem?

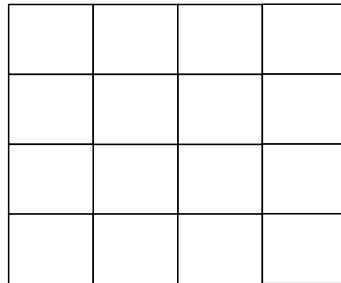
A CSP is typically defined by:

1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.

Example: Given 4 queens 

and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

How to model this question to CSP?

constraints -> "no threaten to each other"

variables -> four queens: q_1, q_2, q_3, q_4

domains -> the index of columns in each row.

2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

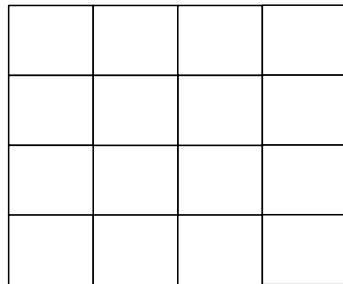
1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.

Example: Given 4 queens

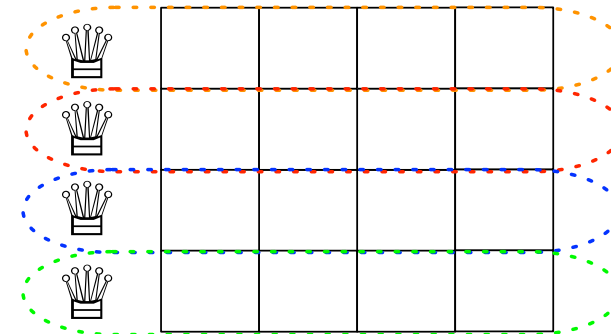


and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

What's the brute-force/naive solution?



Initialize a board

2 - N-Queens Problem

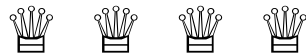
What is Constraint Satisfaction Problem?

A CSP is typically defined by:

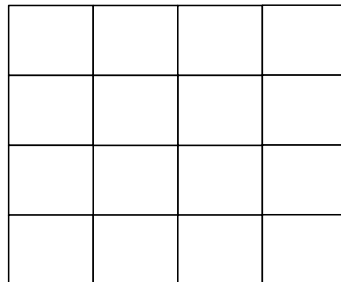
1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.

Example: Given 4 queens

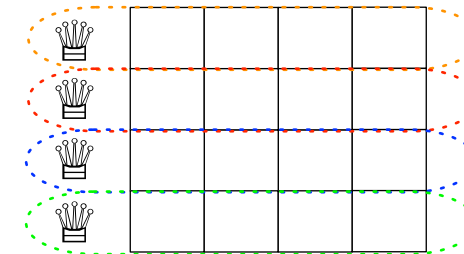


and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

What's the brute-force/naive solution?



board = [0, 0, 0, 0]

Any issues?

2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

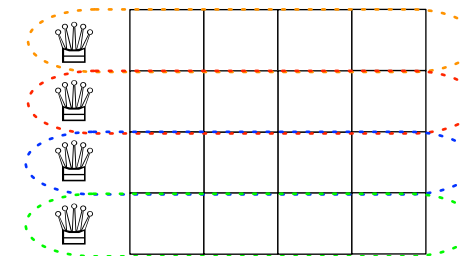
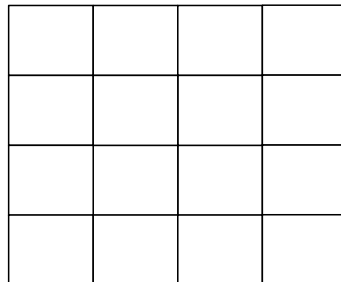
1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.

Example: Given 4 queens 

What's the brute-force/naive solution?

and one 4*4 board



board = [-1, -1, -1, -1]

Place all Queens on the board, and
no two queens threaten each other.

2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

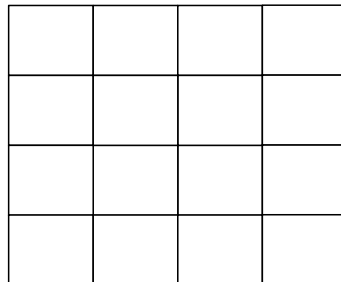
1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.

Example: Given 4 queens 

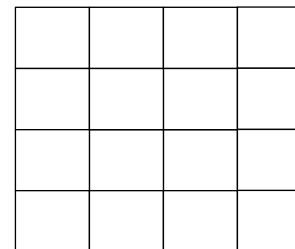
What's the brute-force/naive solution?

and one 4*4 board

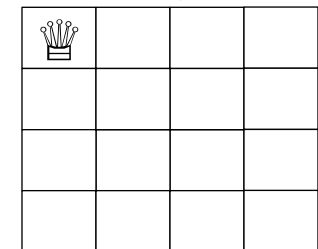


Place all Queens on the board, and
no two queens threaten each other.

initial state



step 1



2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

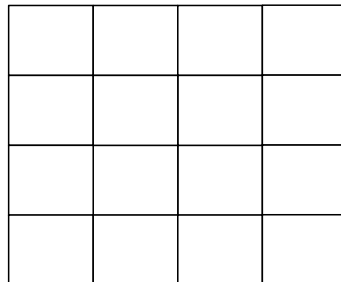
1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.

Example: Given 4 queens

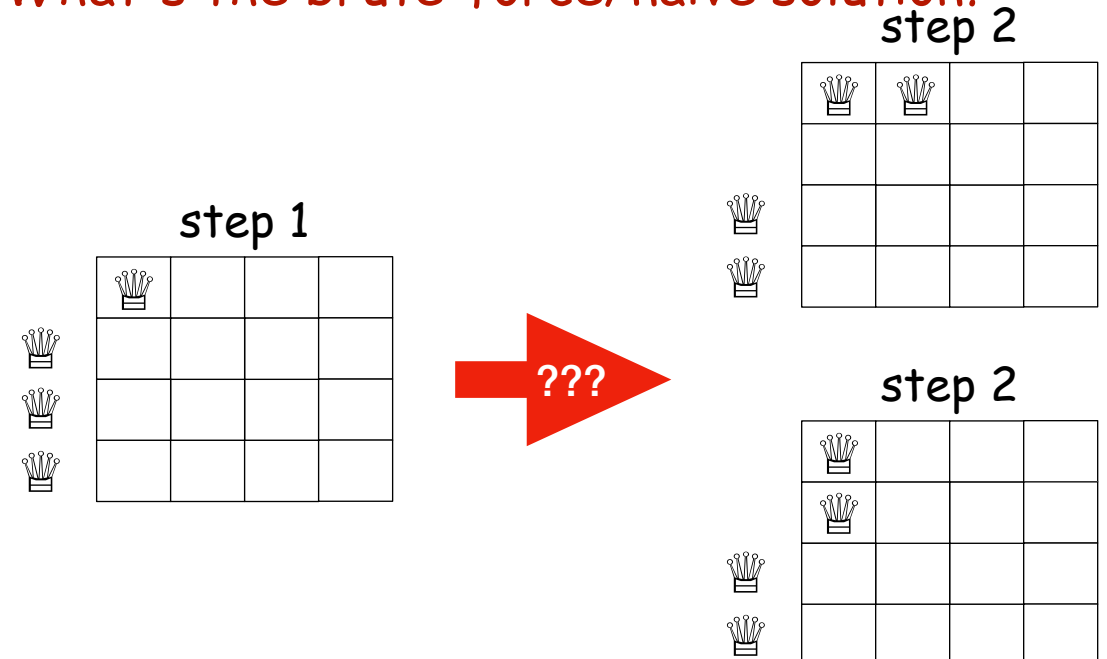


and one 4*4 board



Place all Queens on the board, and no two queens threaten each other.

What's the brute-force/naive solution?



2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

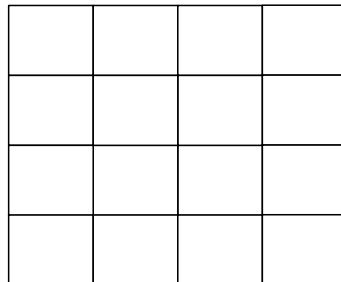
1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.

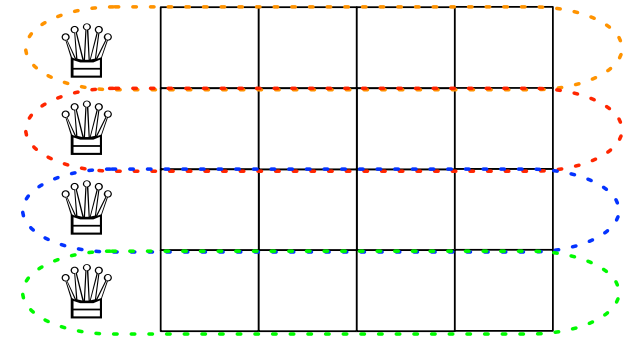
Example: Given 4 queens



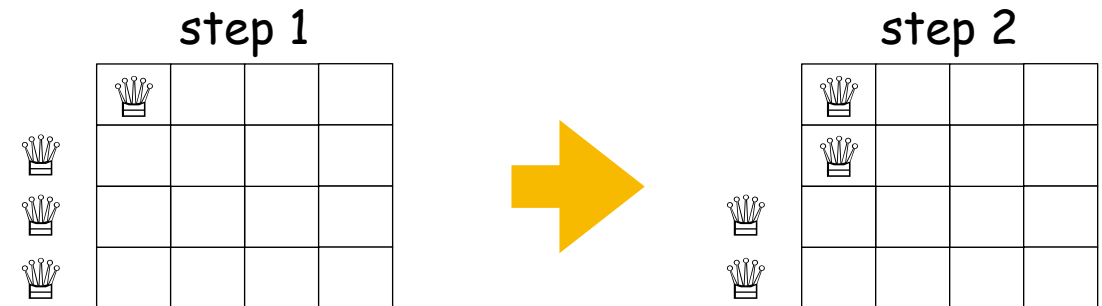
and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.



What's the brute-force/naive solution?



2 - N-Queens Problem

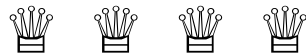
What is Constraint Satisfaction Problem?

A CSP is typically defined by:

1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

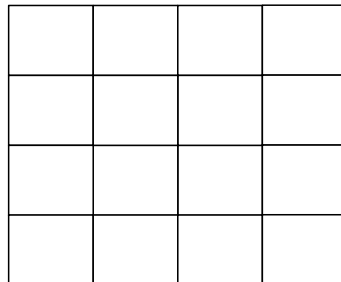
The goal is to **assign values to each variable** so that **all constraints are satisfied**.

Example: Given 4 queens

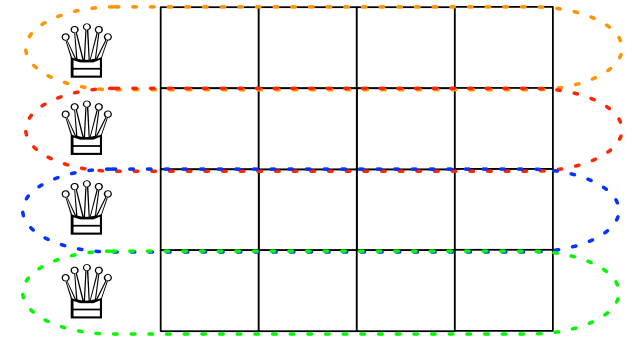


What's the brute-force/naive solution?

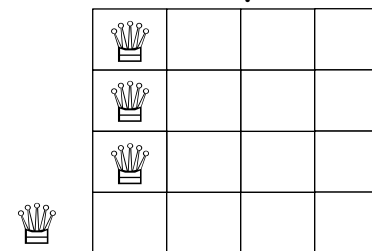
and one 4*4 board



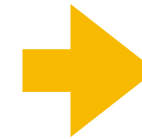
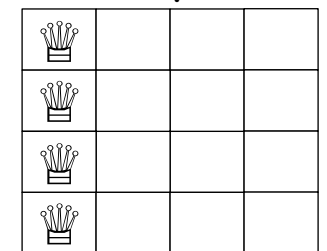
Place all Queens on the board, and
no two queens threaten each other.



step 3



step 4



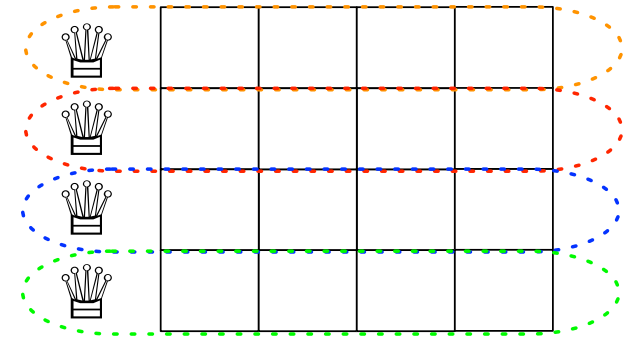
2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

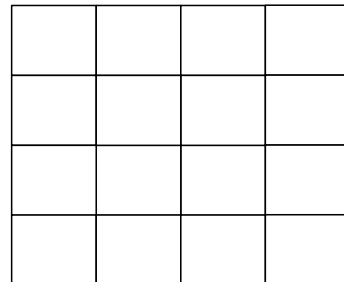
The goal is to **assign values to each variable** so that **all constraints are satisfied**.



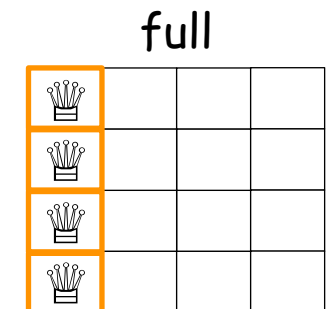
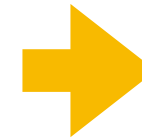
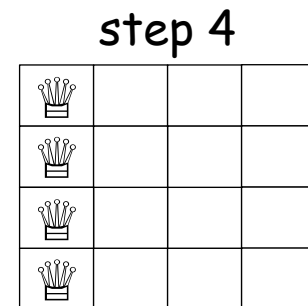
Example: Given 4 queens    

What should we do once we placed all  ?

and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.



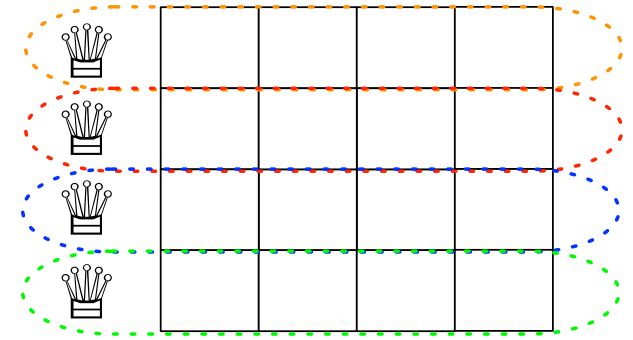
2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

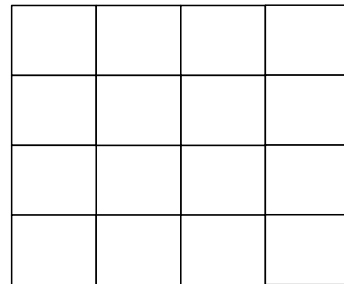
The goal is to **assign values to each variable** so that **all constraints** are satisfied.



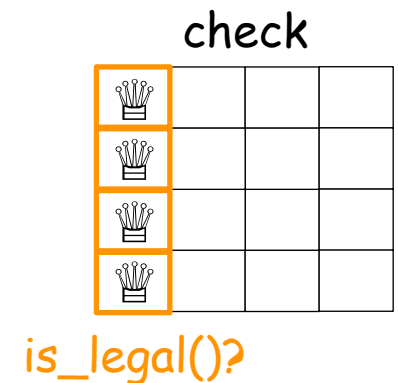
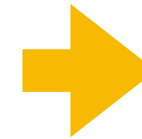
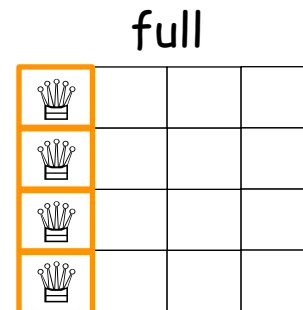
Example: Given 4 queens 

What should we do once we placed all  ?

and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.



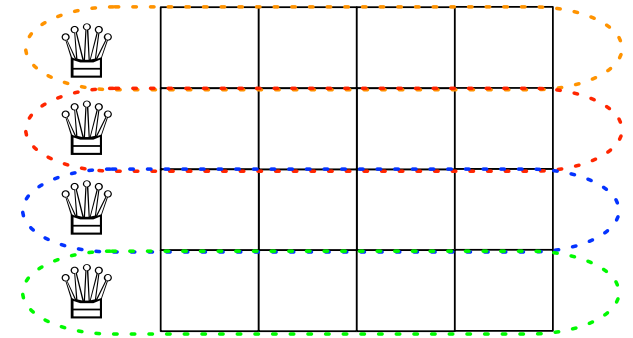
2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

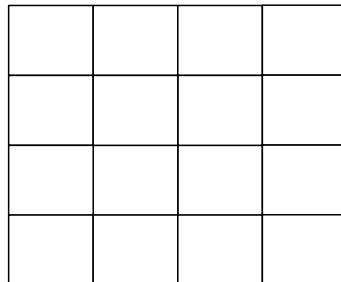
The goal is to **assign values to each variable** so that **all constraints** are satisfied.



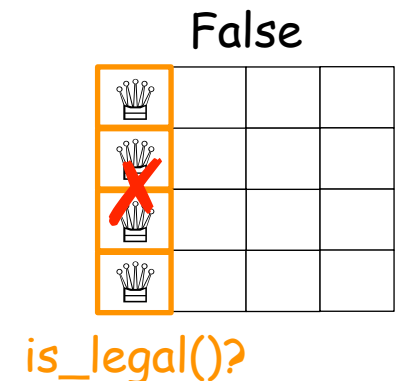
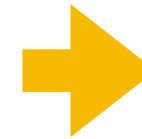
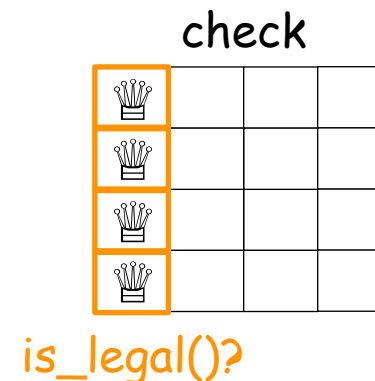
Example: Given 4 queens    

What should we do once we placed all  ?

and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.



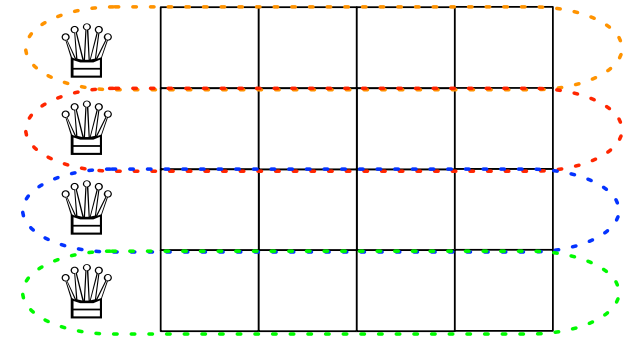
2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

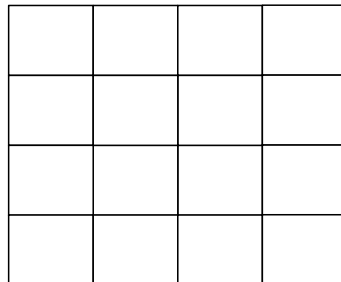
The goal is to **assign values to each variable** so that **all constraints are satisfied**.



Example: Given 4 queens

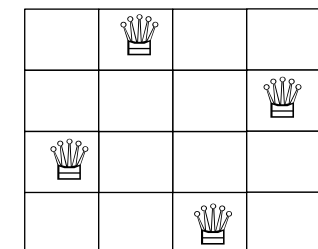
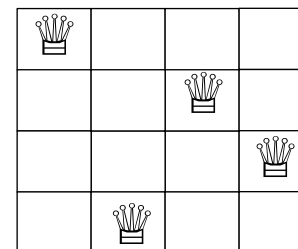
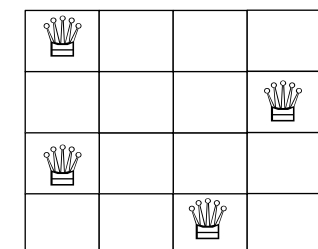
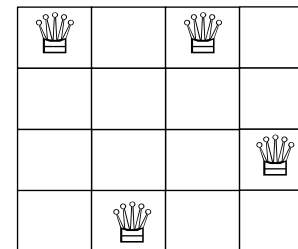


and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

How to complete `is_legal()`?



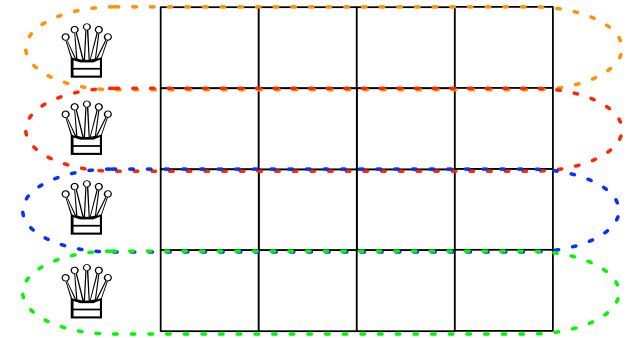
2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

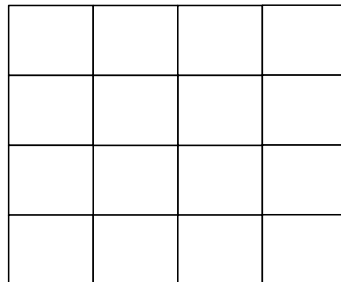
The goal is to **assign values to each variable** so that **all constraints are satisfied**.



Example: Given 4 queens

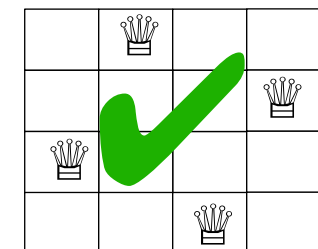
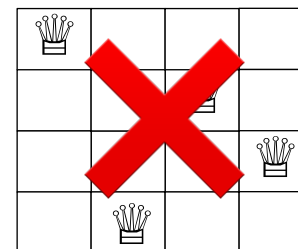
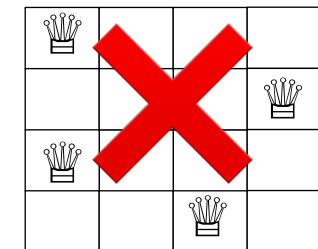
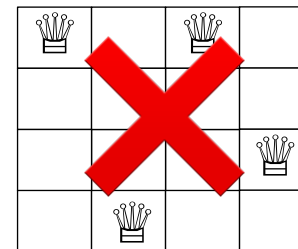


and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

How to complete `is_legal()`?



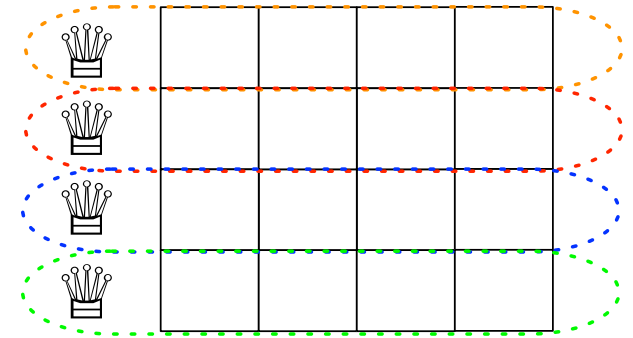
2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

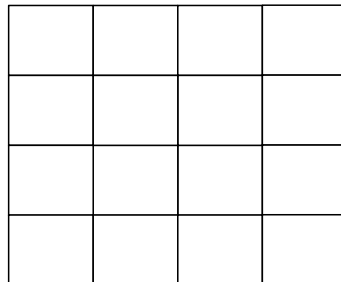
The goal is to **assign values to each variable** so that **all constraints are satisfied**.



Example: Given 4 queens

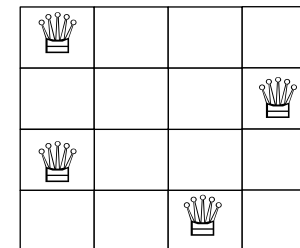


and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

How to complete `is_legal()`?



Why it's in conflict?

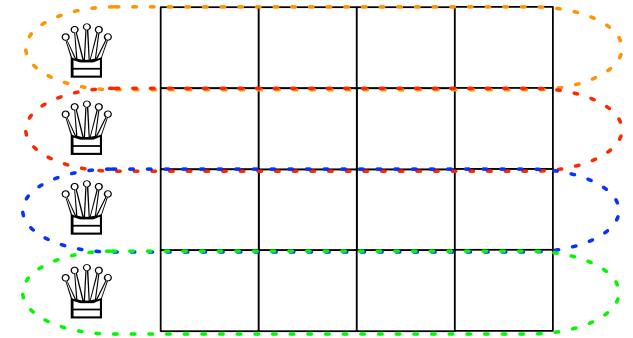
2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

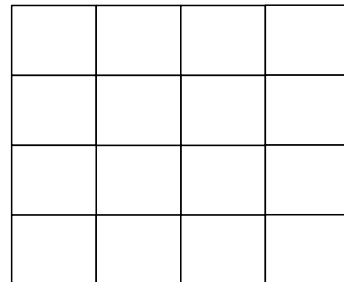
The goal is to **assign values to each variable** so that **all constraints are satisfied**.



Example: Given 4 queens

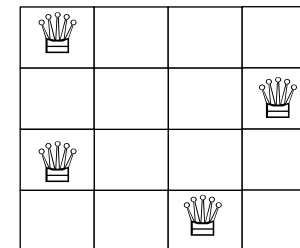


and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

How to complete `is_legal()`?



Why it's in conflict?

`board[q1] == board[q3]`

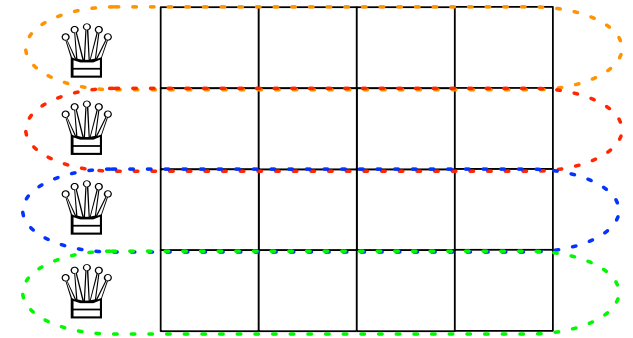
2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

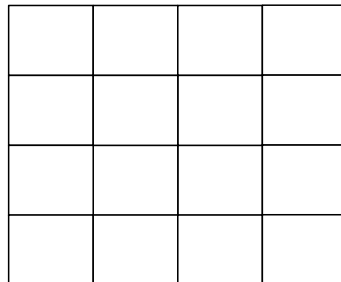
1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.



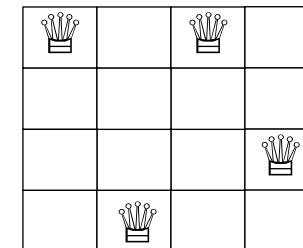
Example: Given 4 queens 

and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

How to complete `is_legal()`?



Why it's in conflict?

No need to check! Impossible.

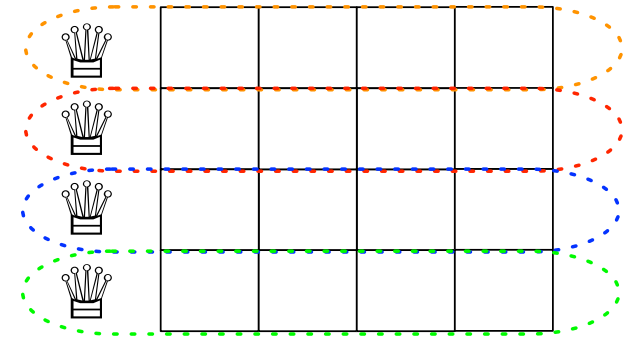
2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

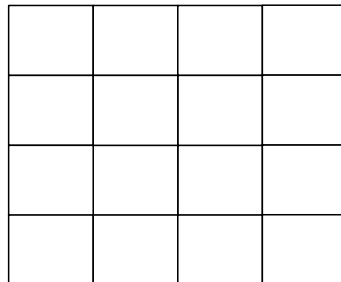
The goal is to **assign values to each variable** so that **all constraints are satisfied**.



Example: Given 4 queens

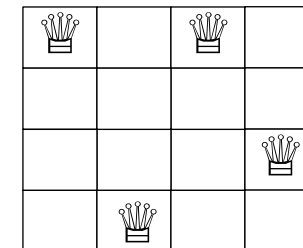


and one 4*4 board



Place all Queens on the board, and no two queens threaten each other.

How to complete `is_legal()`?



Why it's in conflict?

what will happen if we use 2D array board?

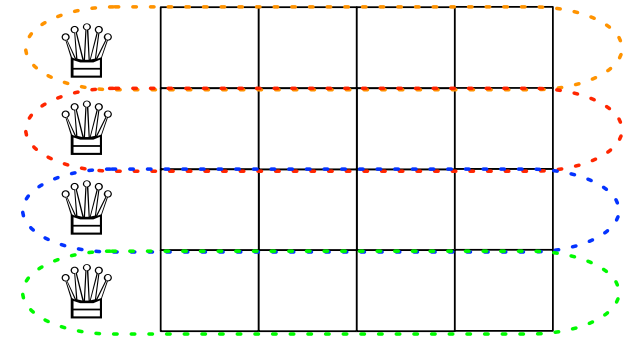
2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

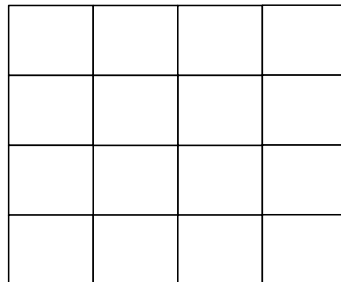
1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.



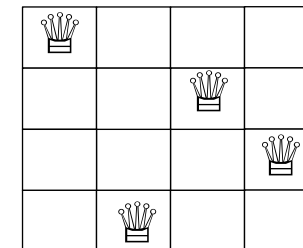
Example: Given 4 queens 

and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

How to complete `is_legal()`?



Why it's in conflict?

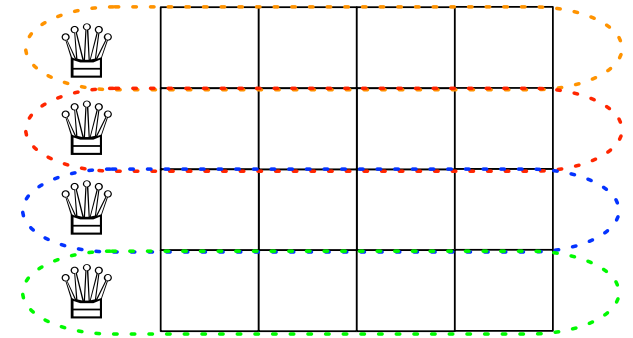
2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

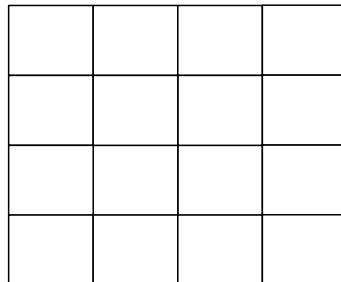
The goal is to **assign values to each variable** so that **all constraints are satisfied**.



Example: Given 4 queens

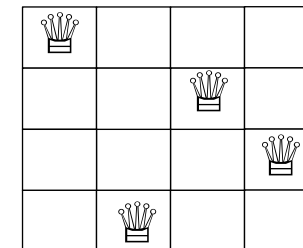


and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

How to complete `is_legal()`?



Why it's in conflict?

$$q_3 - q_2 == \text{board}[q_3] - \text{board}[q_2]$$

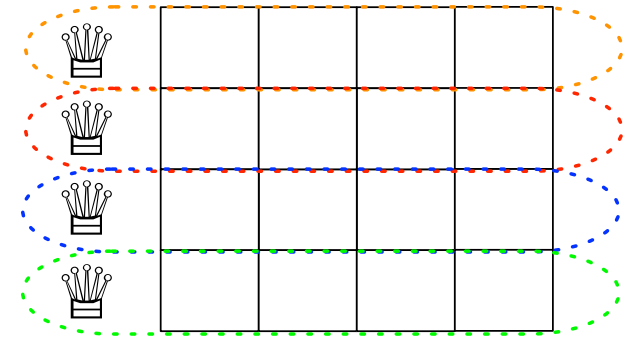
2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

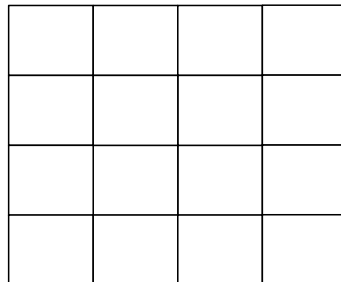
1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.



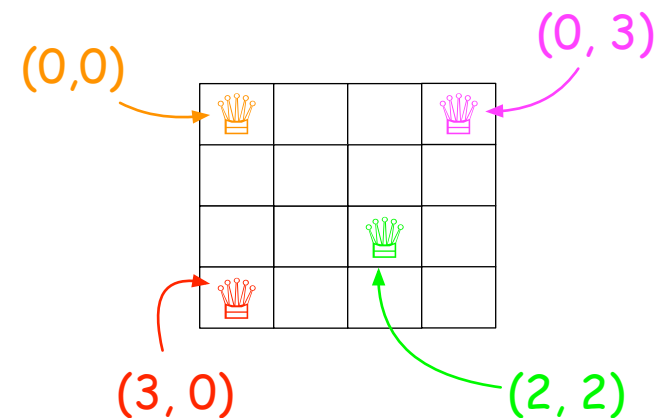
Example: Given 4 queens 

and one 4*4 board



Place all Queens on the board, and no two queens threaten each other.

How to complete `is_legal()`?



$$\text{Queen at (0,0)} - \text{Queen at (2,2)} = (-2, -2)$$

$$\text{Queen at (0,3)} - \text{Queen at (3,0)} = (-3, 3)$$

2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

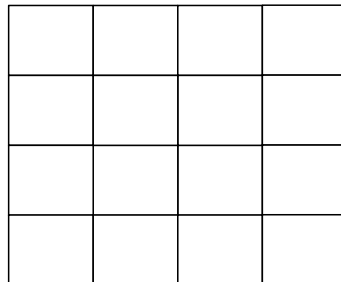
1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

The goal is to **assign values to each variable** so that **all constraints are satisfied**.

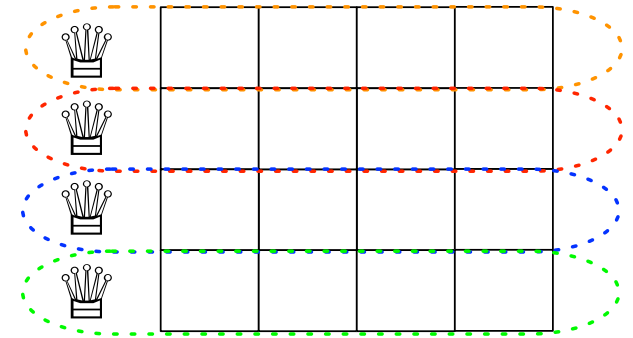
Example: Given 4 queens



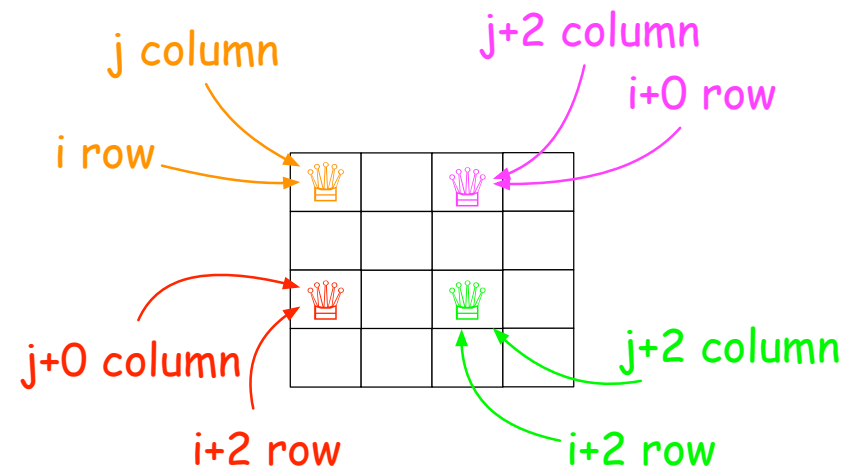
and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.



How to complete `is_legal()`?



$$\text{abs}(x_2 - x_1) == \text{abs}(\text{board}[x_2] - \text{board}[x_1])$$

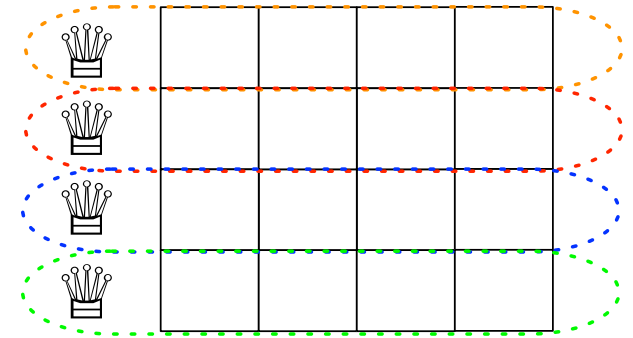
2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

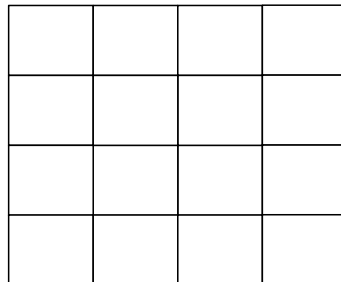
The goal is to **assign values to each variable** so that **all constraints are satisfied**.



Example: Given 4 queens



and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

How to complete `is_legal()`?

```
# Check if the current board configuration is valid.
def is_legal(board):
    # index rows one by one
    for i in range(len(board)):
        # check the remaining rows
        for j in range(i + 1, len(board)):
            # Check any two queens in the same column
            if board[i] == board[j]:
                return False
    return True
```

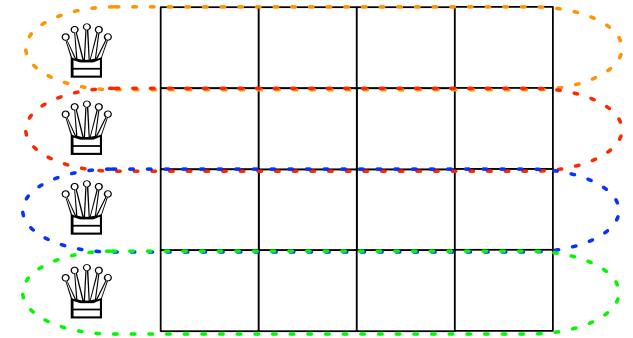

2 - N-Queens Problem

What is Constraint Satisfaction Problem?

A CSP is typically defined by:

1. A set of **variables**
2. A set of **domains** (one domain for each variable)
3. A set of **constraints** among the variables

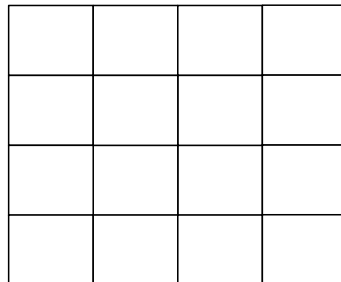
The goal is to **assign values to each variable** so that **all constraints are satisfied**.



Example: Given 4 queens 

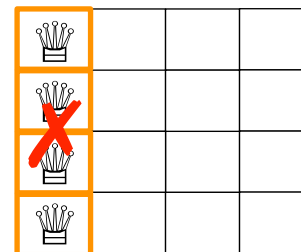
Where should we place the next  ?

and one 4*4 board

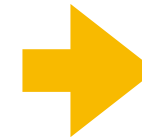


Place all Queens on the board, and
no two queens threaten each other.

False



is_legal()?



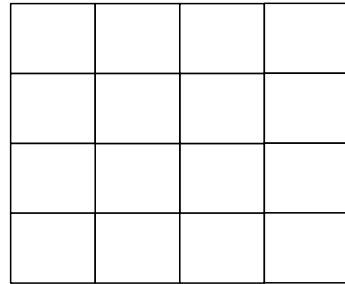
???

2 - N-Queens Problem

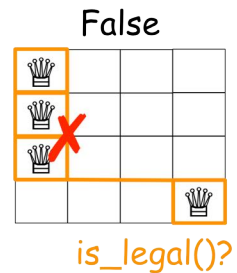
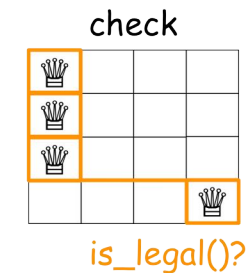
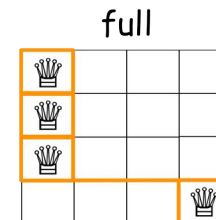
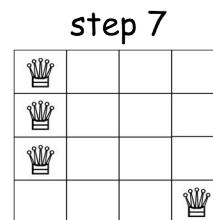
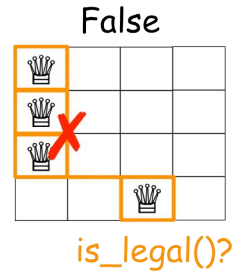
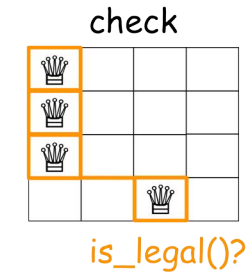
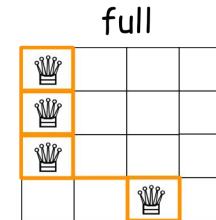
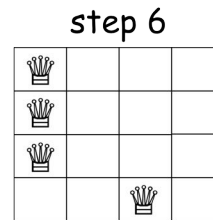
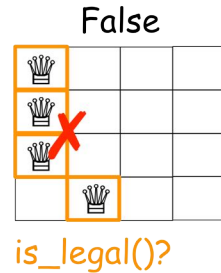
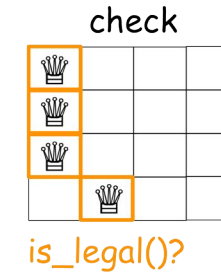
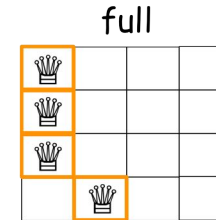
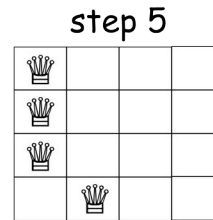
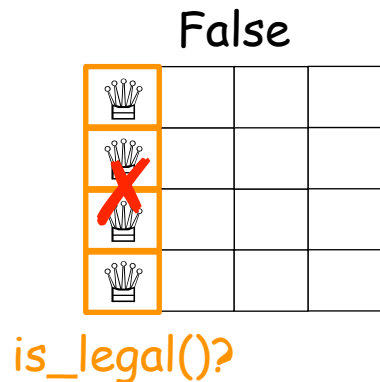
Given 4 queens



and one 4*4 board



Place all Queens on the board, and no two queens threaten each other.

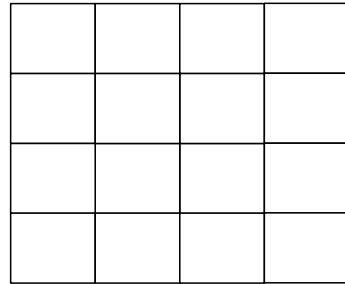


2 - N-Queens Problem

Given 4 queens

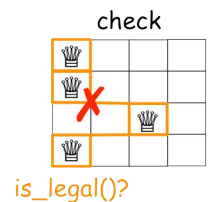
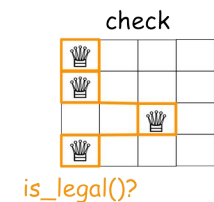
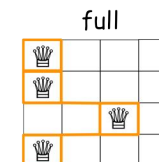
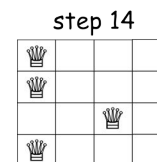
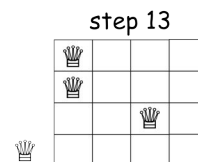
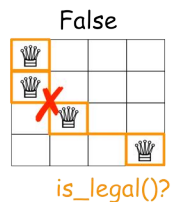
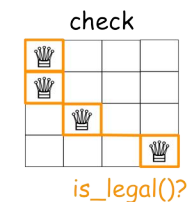
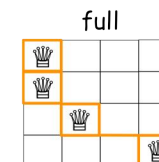
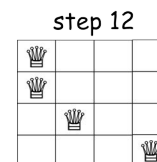
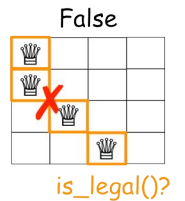
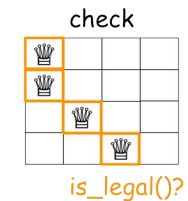
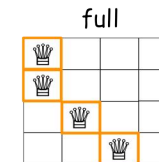
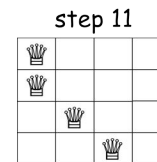
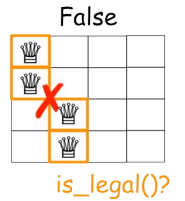
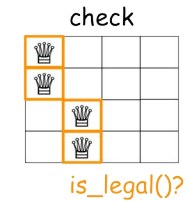
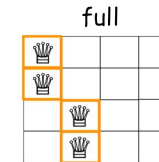
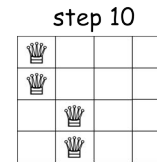
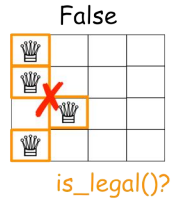
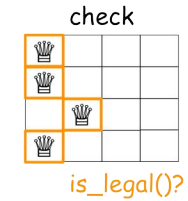
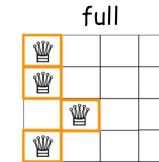
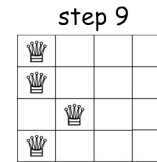
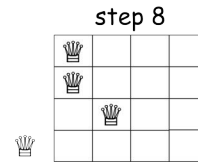
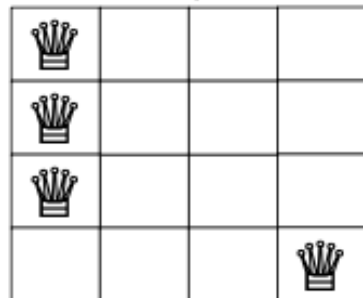


and one 4*4 board



Place all Queens on the board, and no two queens threaten each other.

step 7

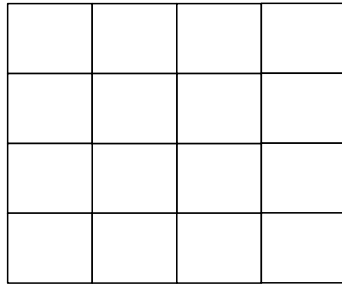


2 - N-Queens Problem

Given 4 queens

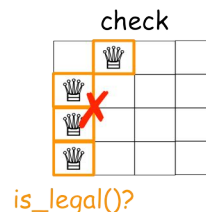
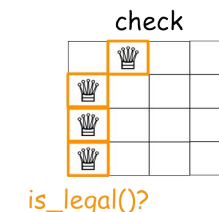
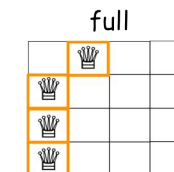
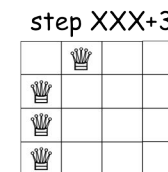
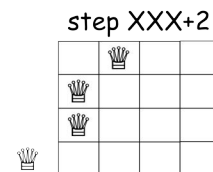
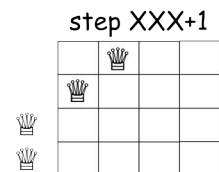
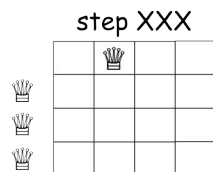
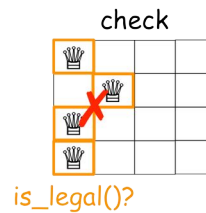
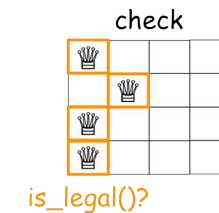
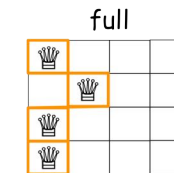
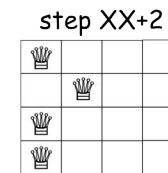
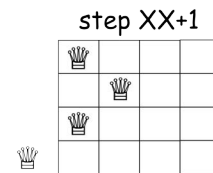
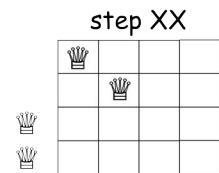
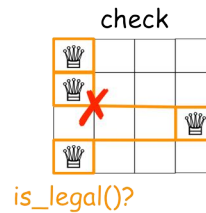
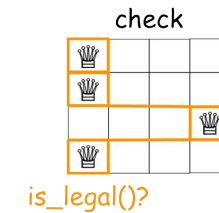
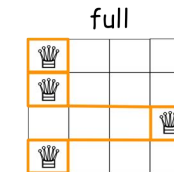
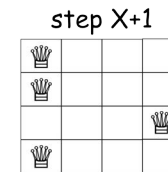
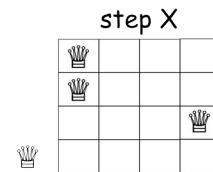


and one 4*4 board



Place all Queens on the board, and no two queens threaten each other.

What's the coding structure?

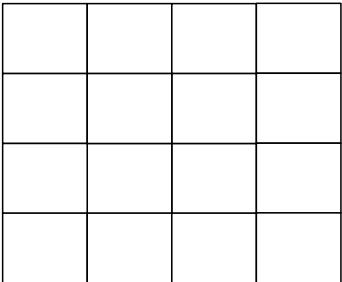


2 - N-Queens Problem

Given 4 queens



and one 4*4 board



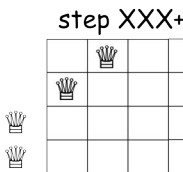
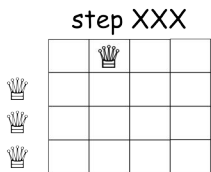
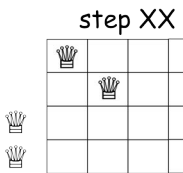
Place all Queens on the board, and no two queens threaten each other

What's the coding structure?

```

step X
for col1 in range(len(board)):
    board[0] = col1
    step X+1
    for col2 in range(len(board)):
        board[1] = col2
        full
        for col3 in range(len(board)):
            board[2] = col3
            check
            for col4 in range(len(board)):
                board[3] = col4
                check
                if is_valid(board):
                    print_board(board, counter)
                    is_legal()?

```

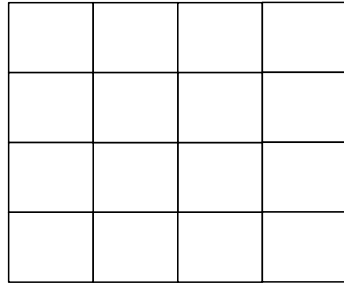


2 - N-Queens Problem

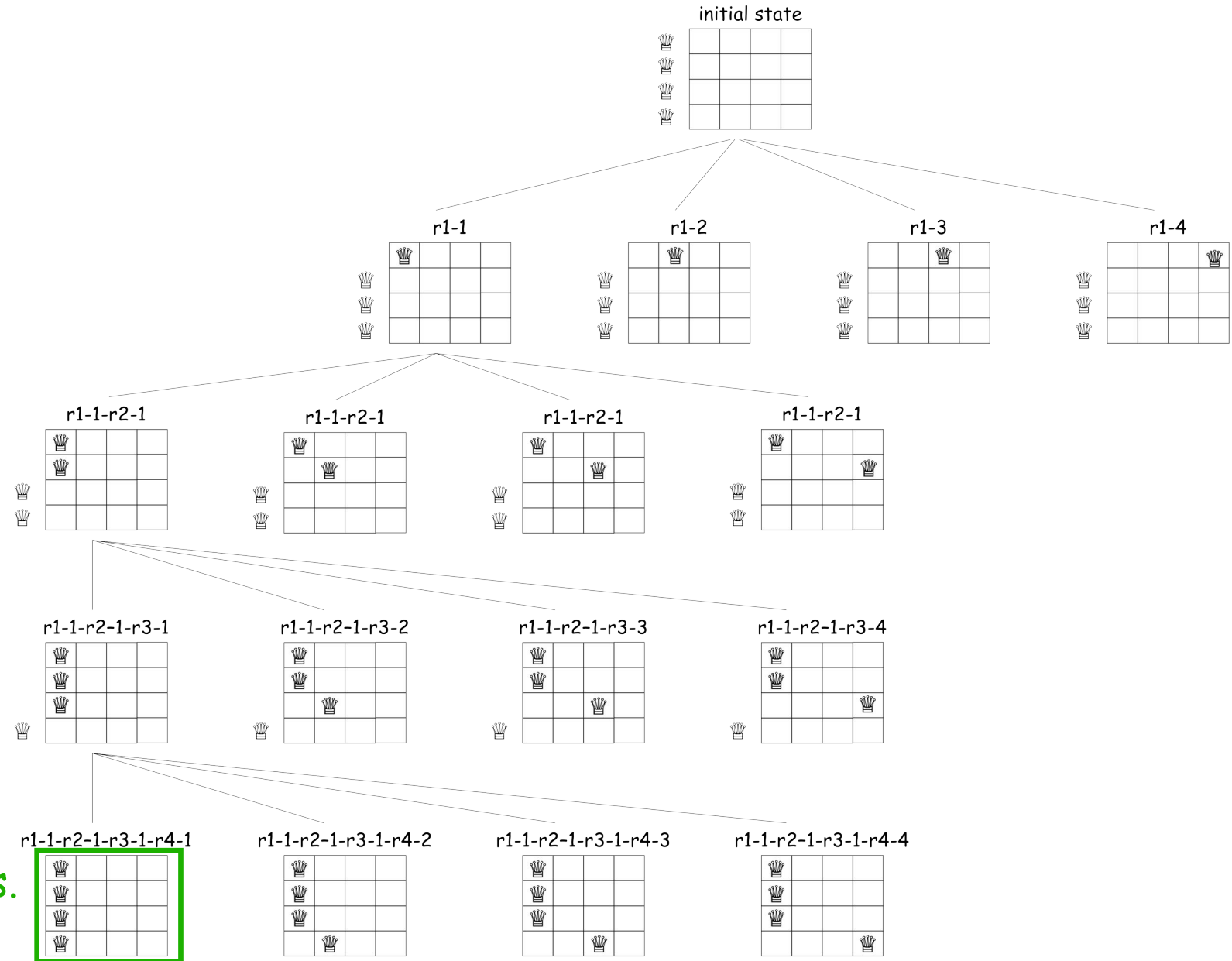
Given 4 queens



and one 4*4 board



Place all Queens on the board, and no two queens threaten each other.



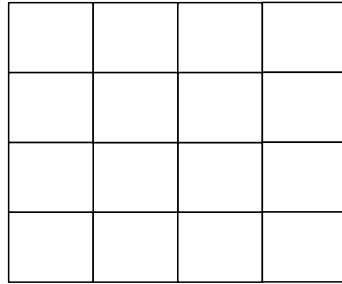
Check on leaf nodes.

2 - N-Queens Problem

Given 4 queens

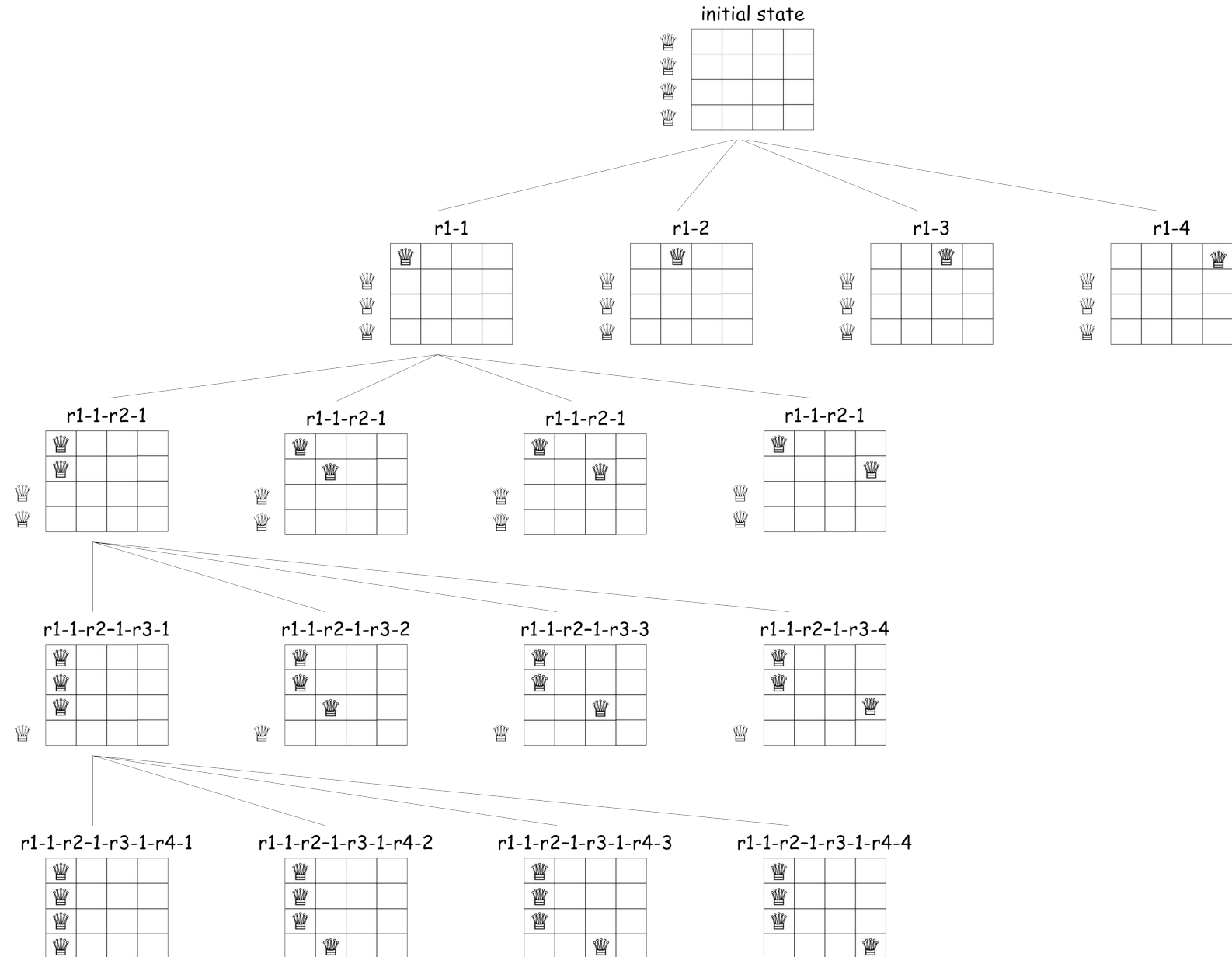


and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

How can we save runtime?
i.e., how can we prune this
search tree?

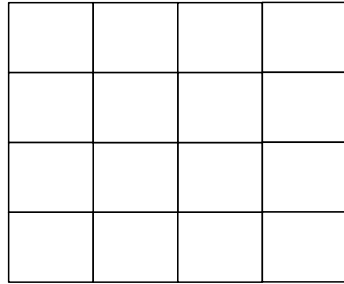


2 - N-Queens Problem

Given 4 queens

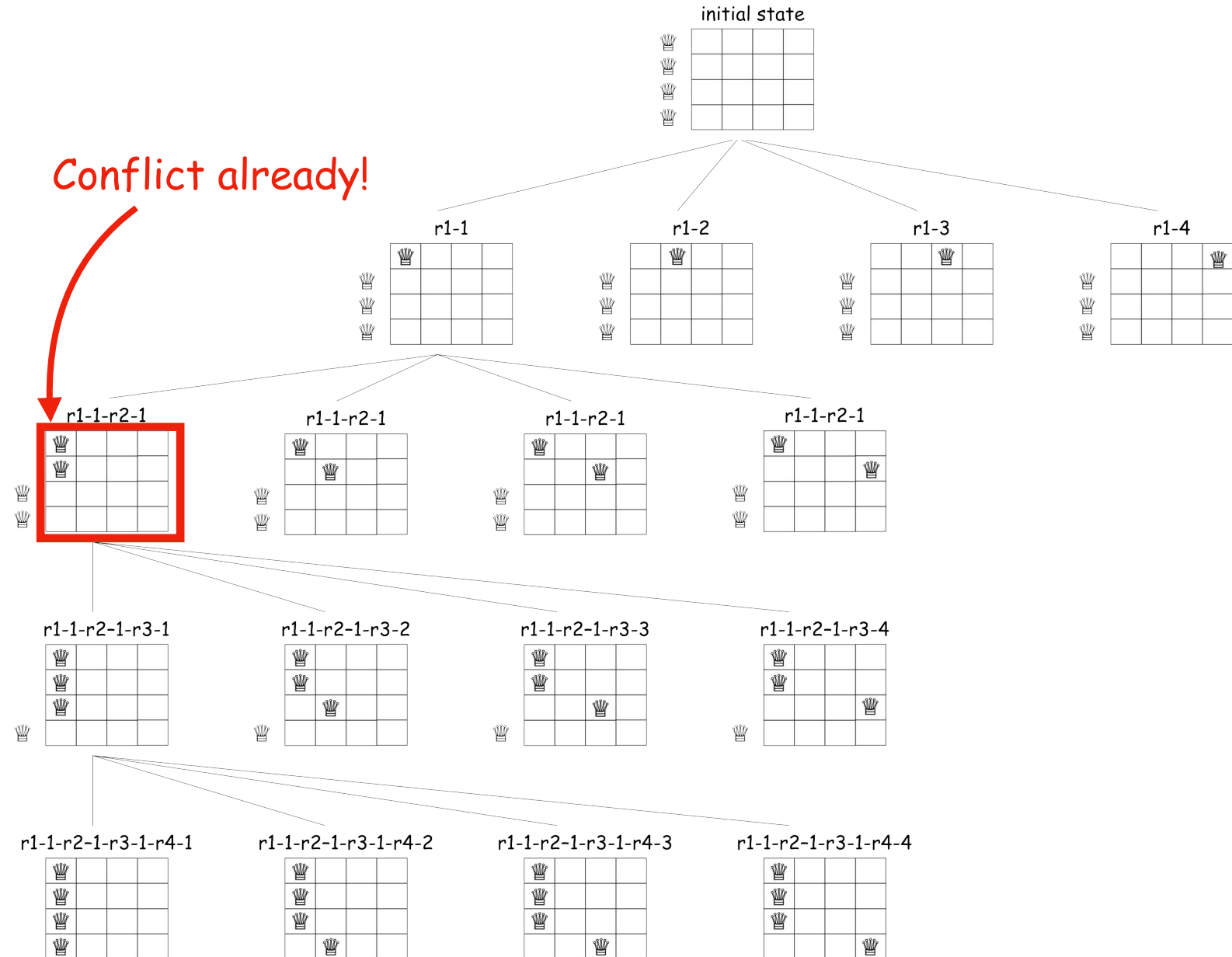


and one 4*4 board



Place all Queens on the board, and no two queens threaten each other.

How can we save runtime?
i.e., how can we prune this search tree?

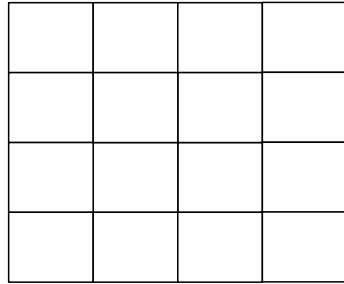


2 - N-Queens Problem

Given 4 queens

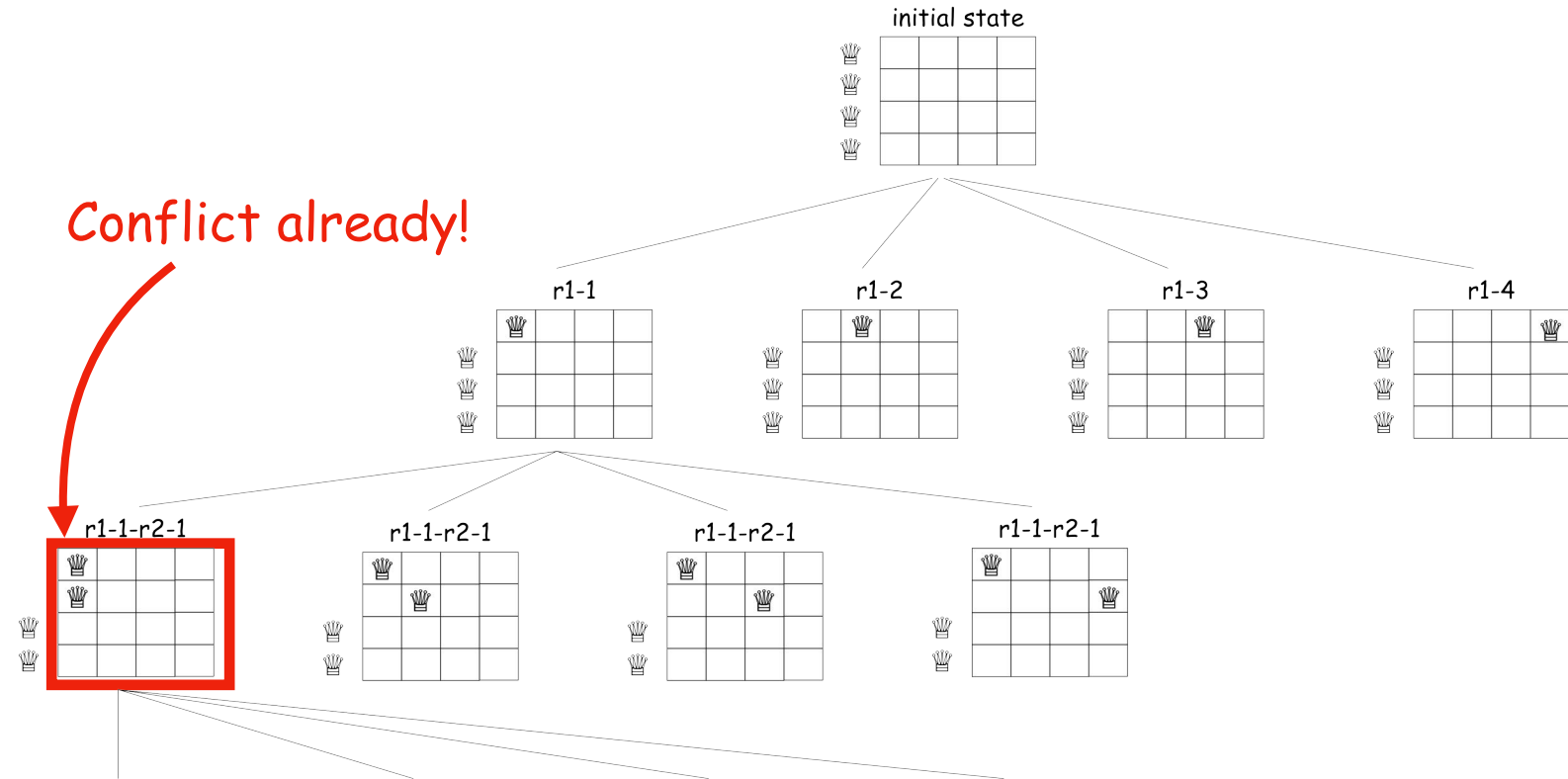


and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

How can we save runtime?
i.e., how can we prune this
search tree?



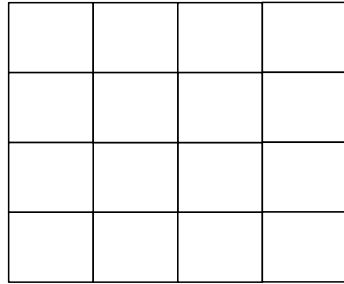
NOT Necessary

2 - N-Queens Problem

Given 4 queens

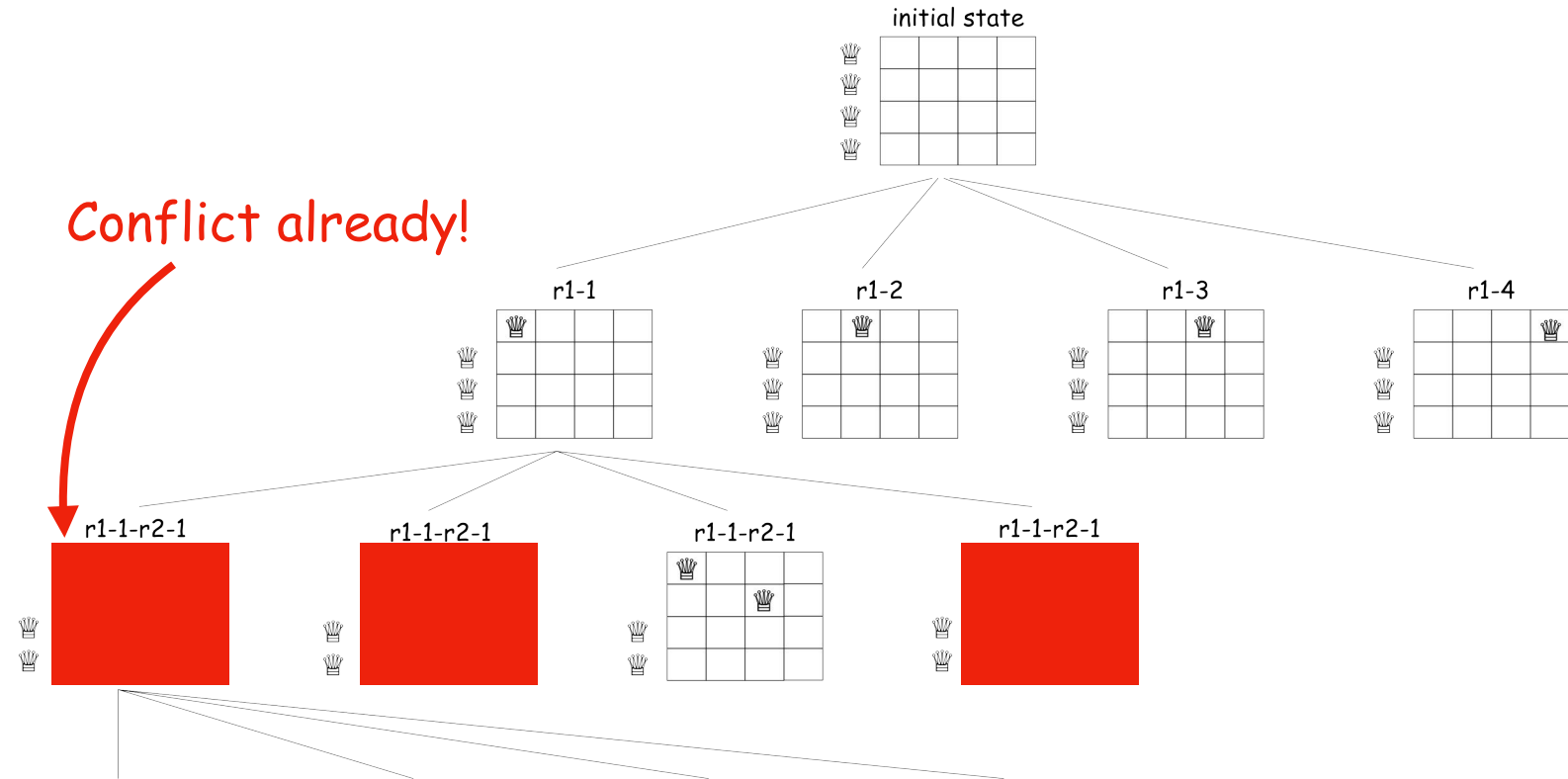


and one 4*4 board



Place all Queens on the board, and
no two queens threaten each other.

How can we save runtime?
i.e., how can we prune this
search tree?



NOT Necessary

Given an array A , where A is defined as follows:

1. How can we systematically enumerate or simulate all possible values of A ?

```
for candidate_0 in range(len(A)):  
    A[0] = candidate_0  
  
    for candidate_1 in range(len(A)):  
        A[1] = candidate_1  
  
        for candidate_2 in range(len(A)):  
            A[2] = candidate_2  
  
            for candidate_3 in range(len(A)):  
                A[3] = candidate_3  
  
                print(A)
```

2 - N-Queens Problem

Given an array A , where A is defined as follows:

2. What would be the implications if we impose the constraint that each digit can appear only once?

```
for candidate_0 in range(len(A)):
    A[0] = candidate_0

    for candidate_1 in range(len(A)):
        A[1] = candidate_1

        for candidate_2 in range(len(A)):
            A[2] = candidate_2

            for candidate_3 in range(len(A)):
                A[3] = candidate_3

                if is_valid(A):
                    print(A)
```

```
def is_valid(A):
    for i in range(len(A)):
        for j in range(i + 1, len(A)):
            if A[i] == A[j]:
                return False
    return True
```

2 - N-Queens Problem

Given an array A , where A is defined as follows:

3. How would the behavior change if we introduce the following `is_valid()` function?

```
for candidate_0 in range(len(A)):
    A[0] = candidate_0

    for candidate_1 in range(len(A)):
        A[1] = candidate_1

        for candidate_2 in range(len(A)):
            A[2] = candidate_2

            for candidate_3 in range(len(A)):
                A[3] = candidate_3

                if is_valid(A):
                    print(A)
```

```
def is_valid(A):
    for i in range(len(A)):
        for j in range(i + 1, len(A)):
            if A[i] == A[j]:
                return False
            if abs(i-j) == abs(A[i] - A[j]):
                return False
    return True
```

2 - N-Queens Problem

Given an array A , where A is defined as follows:

3. How would the behavior change if we introduce the following `is_valid()` function?

```
for candidate_0 in range(len(A)):
    A[0] = candidate_0

    for candidate_1 in range(len(A)):
        A[1] = candidate_1

        for candidate_2 in range(len(A)):
            A[2] = candidate_2

            for candidate_3 in range(len(A)):
                A[3] = candidate_3

                if is_valid(A):
                    print(A)
```

```
def is_valid(A):
    for i in range(len(A)):
        for j in range(i + 1, len(A)):
            if A[i] == A[j]:
                return False
            if abs(i-j) == abs(A[i] - A[j]):
                return False
    return True
```

It's the N-queens Problem.

Local Check!

```
for tentative_col1 in range(len(board)):
    if is_valid(board, 0, tentative_col1):
        board[0] = tentative_col1

    for tentative_col2 in range(len(board)):
        if is_valid(board, 1, tentative_col2):
            board[1] = tentative_col2

        for tentative_col3 in range(len(board)):
            if is_valid(board, 2, tentative_col3):
                board[2] = tentative_col3

            for tentative_col4 in range(len(board)):
                if is_valid(board, 3, tentative_col4):
                    board[3] = tentative_col4
            print board(board, counter)
```

Global Check!

```
for col1 in range(len(board)):
    board[0] = col1

    for col2 in range(len(board)):
        board[1] = col2

        for col3 in range(len(board)):
            board[2] = col3

            for col4 in range(len(board)):
                board[3] = col4

                if is_valid(board):
                    print_board(board, counter)
```

Local Check!

```
for tentative_col1 in range(len(board)):
    if is_valid(board, 0, tentative_col1):
        board[0] = tentative_col1

        for tentative_col2 in range(len(board)):
            if is_valid(board, 1, tentative_col2):
                board[1] = tentative_col2

                for tentative_col3 in range(len(board)):
                    if is_valid(board, 2, tentative_col3):
                        board[2] = tentative_col3

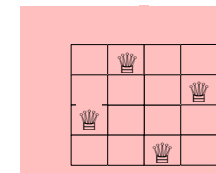
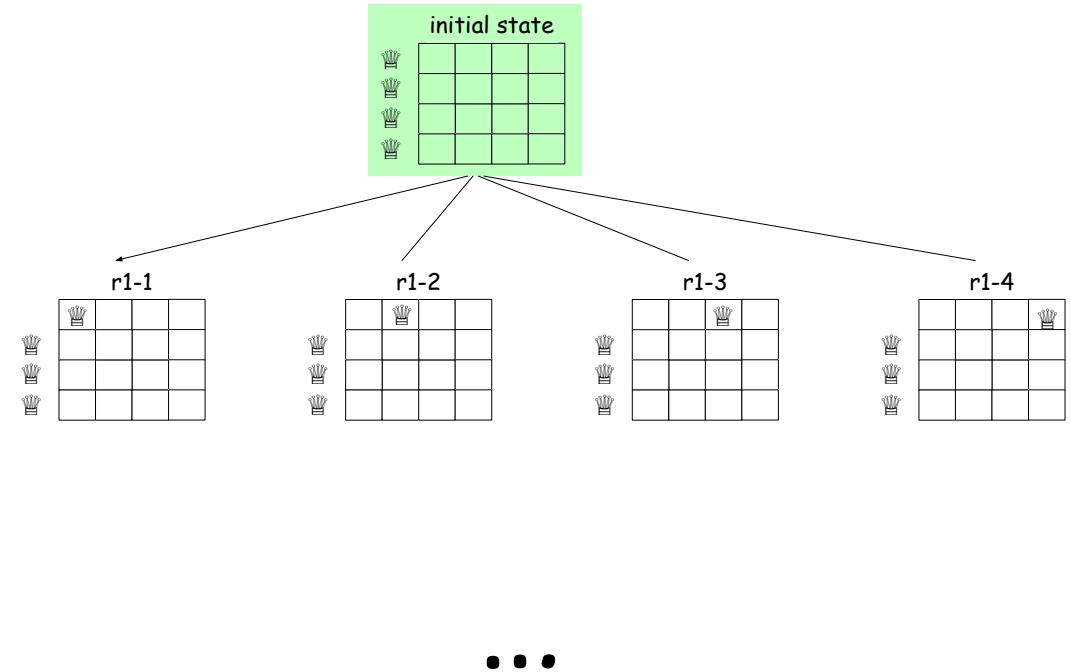
                        for tentative_col4 in range(len(board)):
                            if is_valid(board, 3, tentative_col4):
                                board[3] = tentative_col4
                                print_board(board, counter)
```

```
def solve_n_queens(n):
    solutions = []
    for perm in permutations(range(n)):
        if is_valid(perm):
            solutions.append(perm)
    return solutions
```


1 - Backtracking

What is Backtracking?

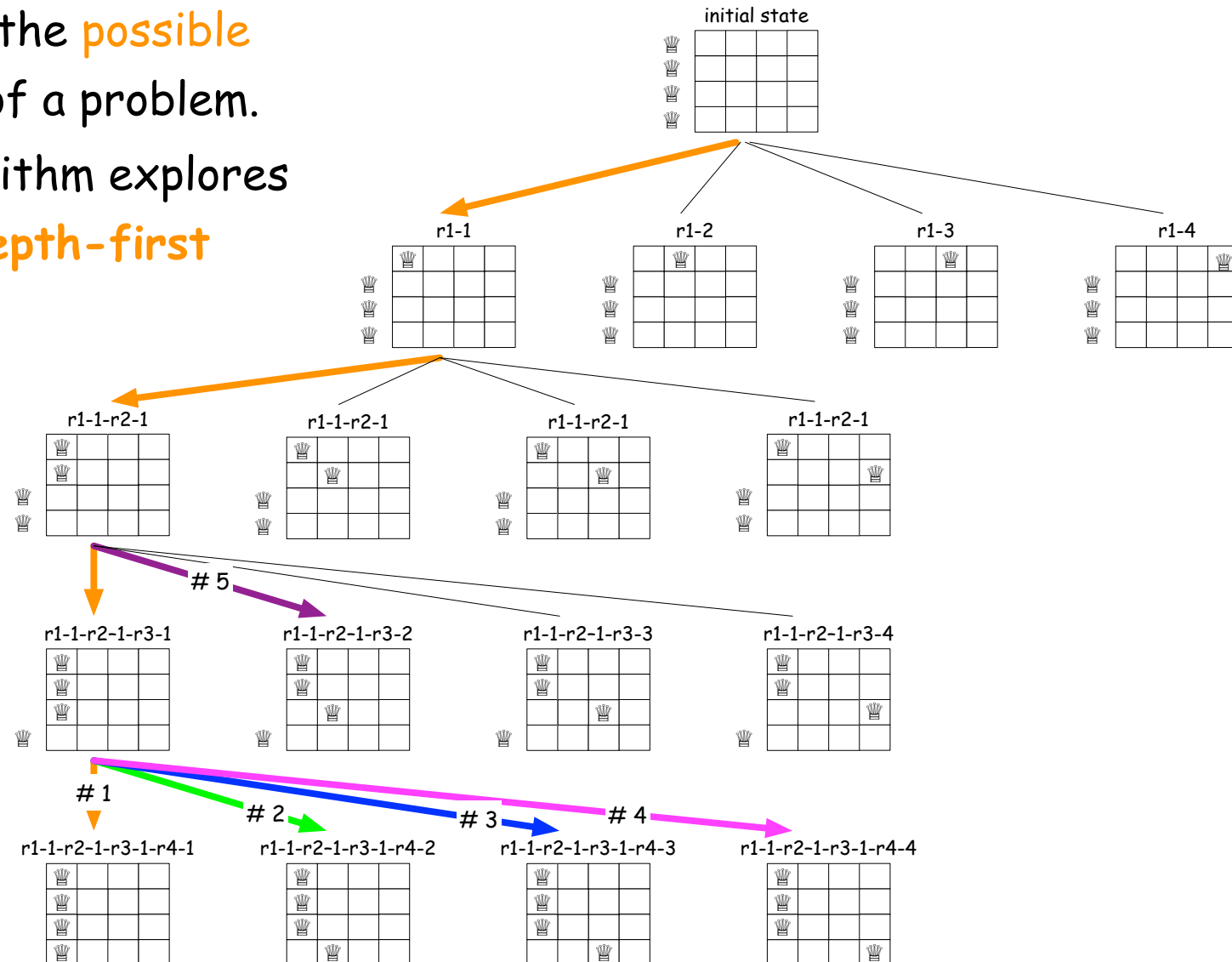
- A methodical way of **searching** through the **possible solutions** (the "solution/search space") of a problem.



1 - Backtracking

What is Backtracking?

- A methodical way of **searching** through the **possible solutions** (the "solution/search space") of a problem.
- Starting from an **initial state**, the algorithm explores possible decisions or assignments in a **depth-first** manner.

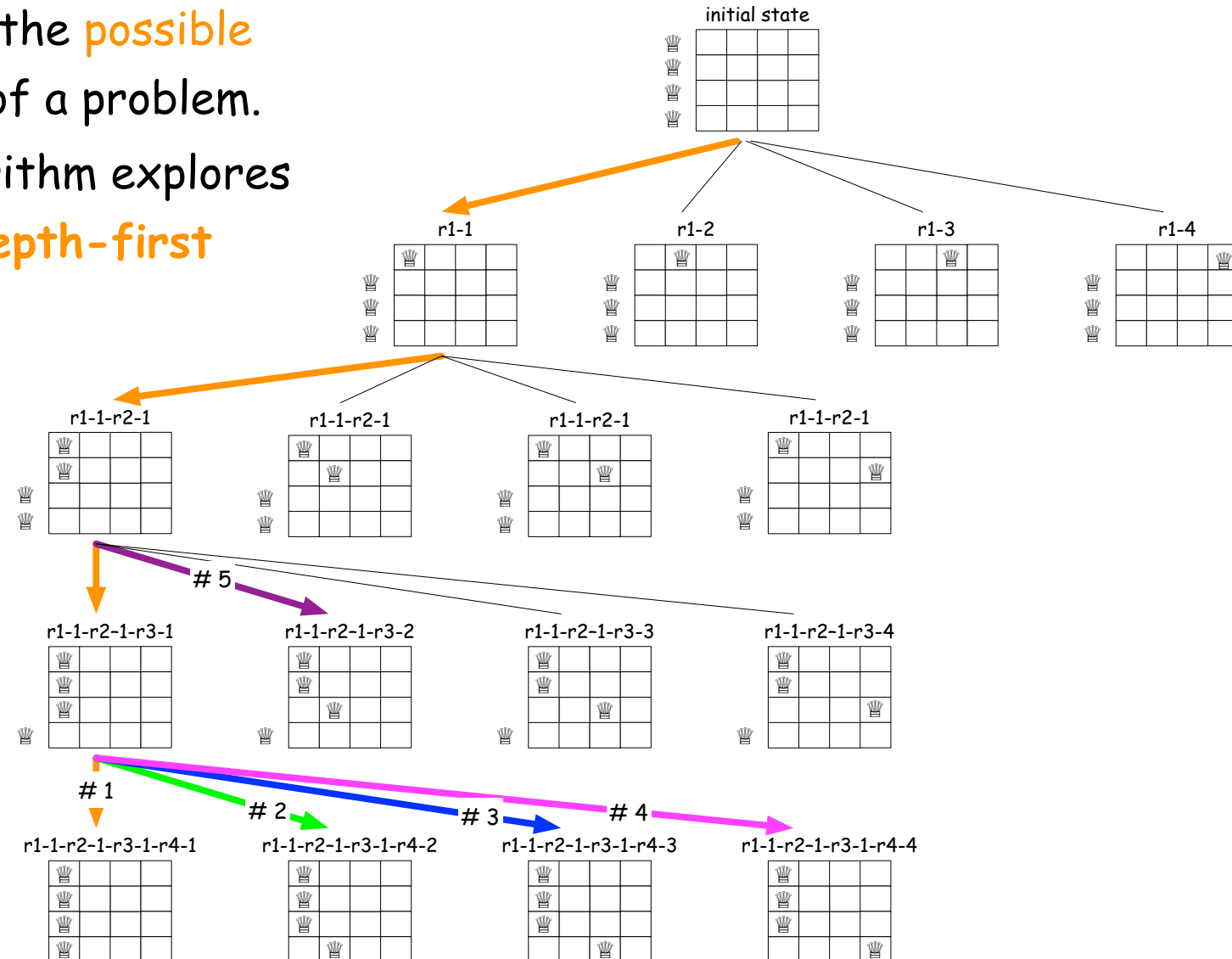


1 - Backtracking

What is Backtracking?

- A methodical way of **searching** through the **possible solutions** (the "solution/search space") of a problem.
- Starting from an **initial state**, the algorithm explores possible decisions or assignments in a **depth-first** manner.

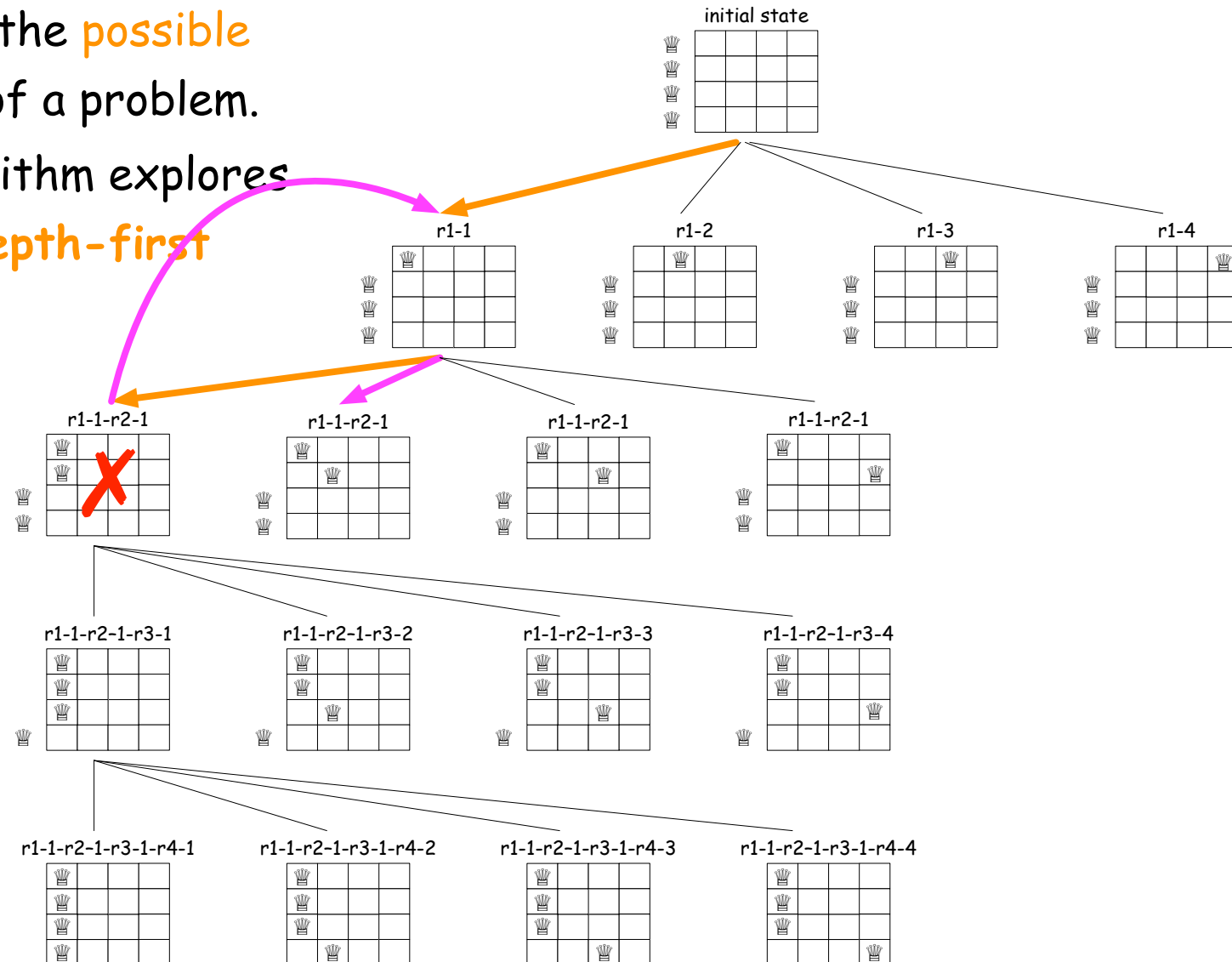
Core idea 1: Branch by branch



1 - Backtracking

What is Backtracking?

- A methodical way of **searching** through the **possible solutions** (the "solution/search space") of a problem.
- Starting from an **initial state**, the algorithm explores possible decisions or assignments in a **depth-first** manner.
- Whenever it becomes clear that a particular path cannot lead to a valid or optimal solution, the algorithm **backtracks**—i.e., it undoes the last decision and tries a different option instead.

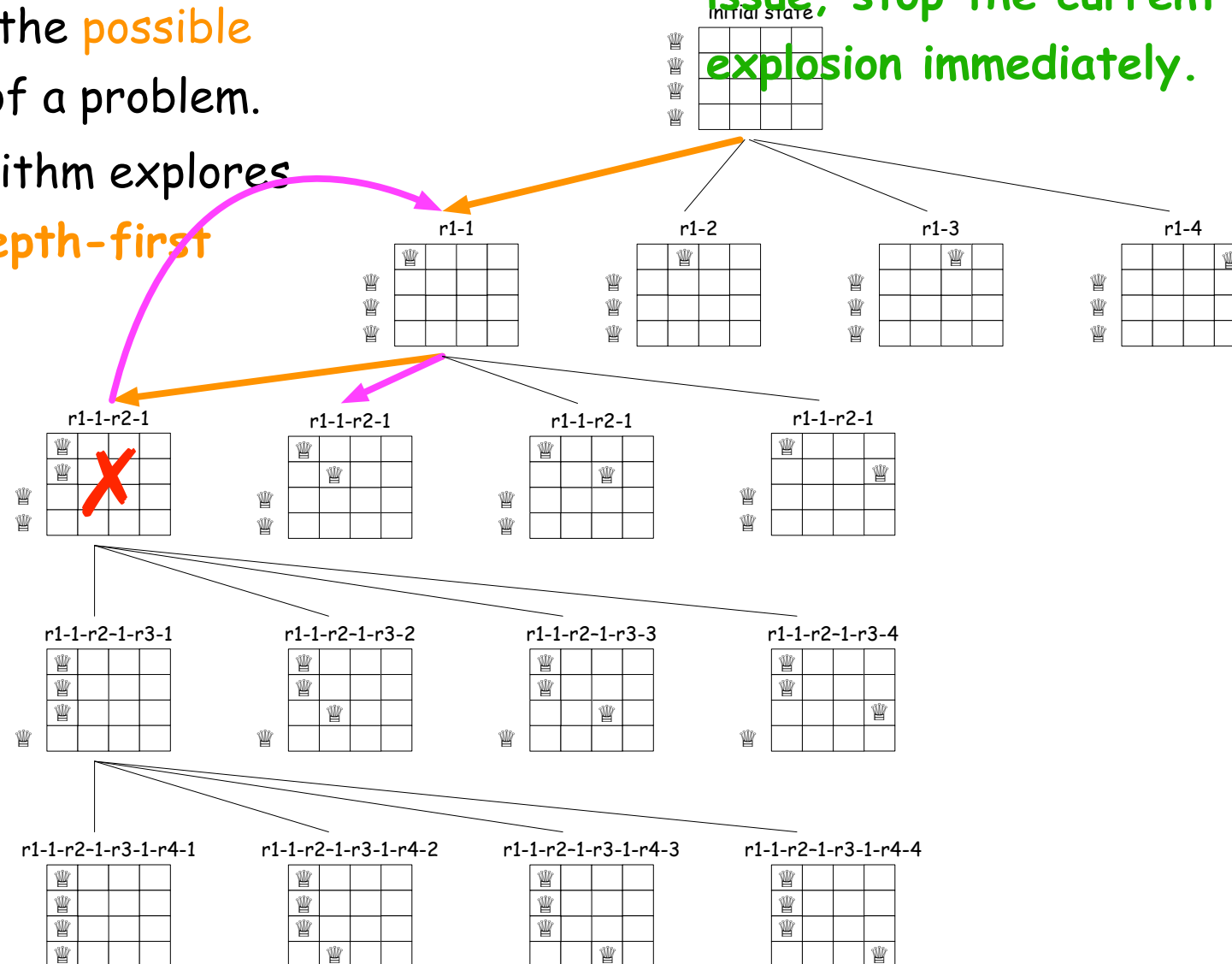


1 - Backtracking

What is Backtracking?

- A methodical way of **searching** through the **possible solutions** (the "**solution/search space**") of a problem.
- Starting from an **initial state**, the algorithm explores possible decisions or assignments in a **depth-first** manner.
- Whenever it becomes clear that a particular path cannot lead to a valid or optimal solution, the algorithm **backtracks**—i.e., it undoes the last decision and tries a different option instead.

Core idea 2: if arising issue, stop the current explosion immediately.

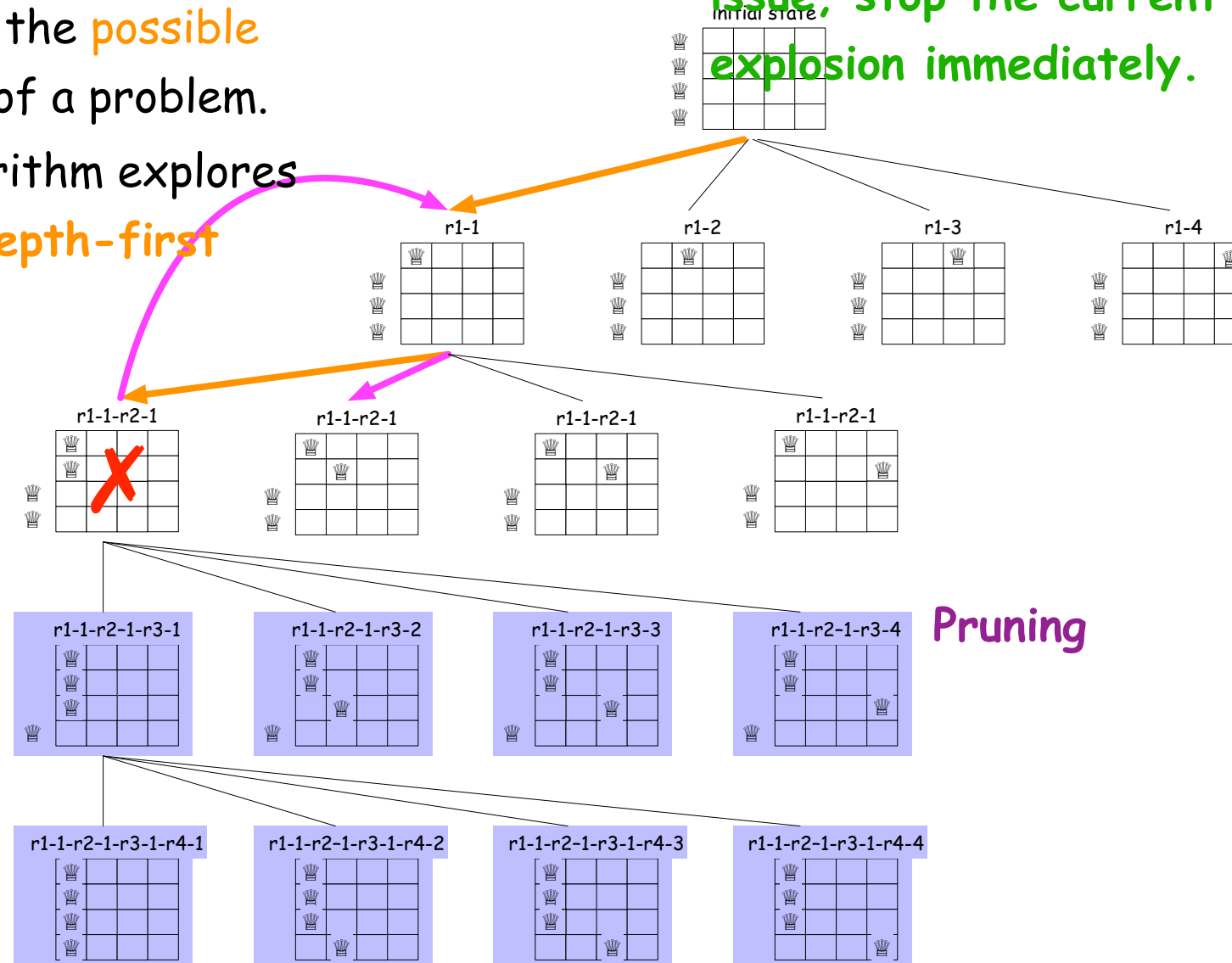


1 - Backtracking

What is Backtracking?

- A methodical way of **searching** through the **possible solutions** (the "**solution/search space**") of a problem.
- Starting from an **initial state**, the algorithm explores possible decisions or assignments in a **depth-first** manner.
- Whenever it becomes clear that a particular path cannot lead to a valid or optimal solution, the algorithm **backtracks**—i.e., it undoes the last decision and tries a different option instead.

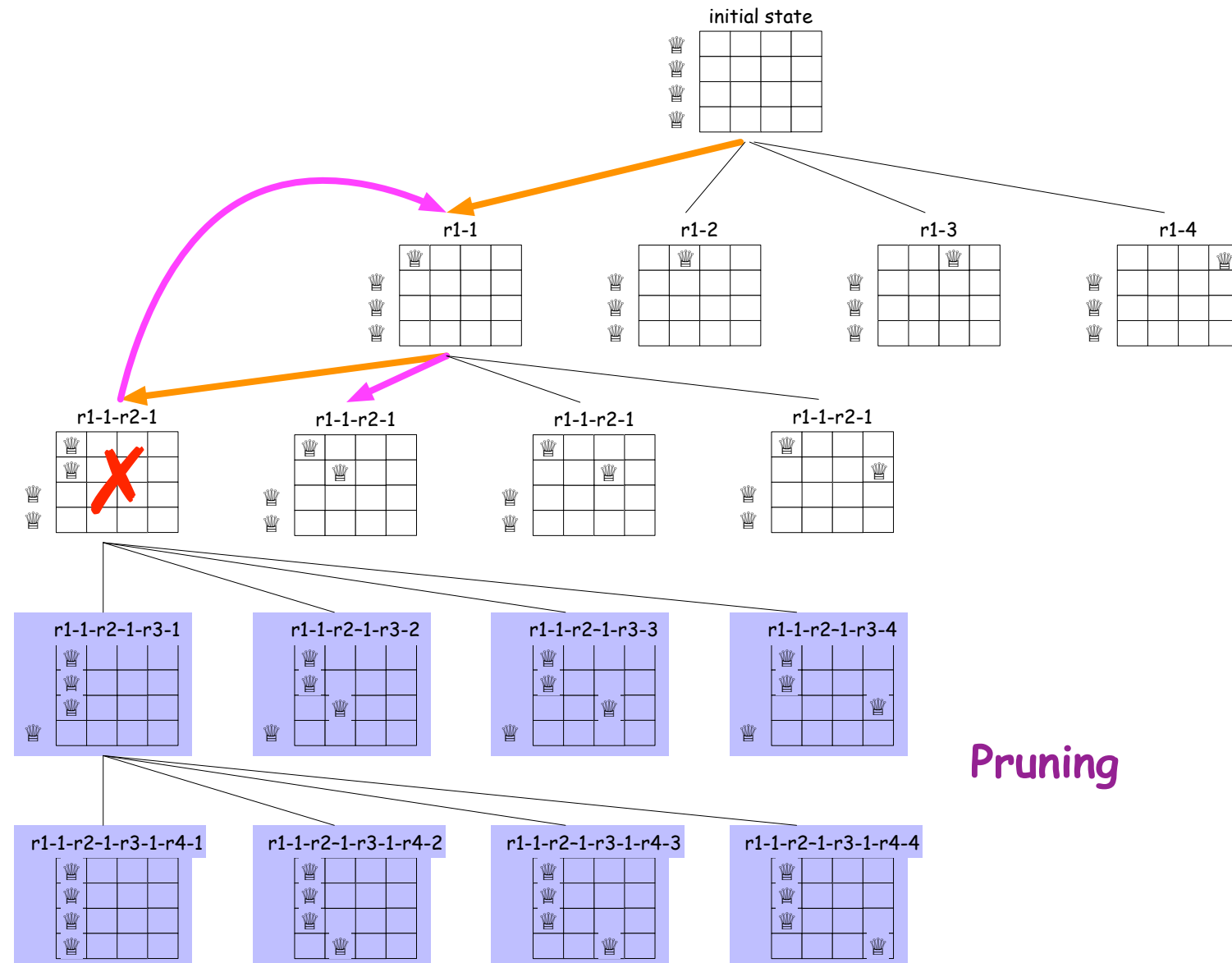
Core idea 2: if arising **issue**, stop the current **explosion** immediately.



1 - Backtracking

What is Backtracking?

- Representing your problem as a tree structure allows you to identify redundant branches, pruning opportunities, and optimization strategies.
- This is a best practice in algorithm design, particularly for backtracking, recursion, and search problems, as it helps minimize unnecessary computations and improve efficiency.



1 - General Backtracking Framework

Generic Pseudo-code - Recursion Style

```
function BACKTRACKING(current_state, current_solution):  
    if current_state reaches the required depth or number of steps:  
        if objective(current_solution):  
            # option 1: record  
            # option 2: output current_solution  
        return  
  
    # Enumerate all possible options for current_state  
    for tentative_option in feasible_option_set:  
        if not is_valid(current_solution, tentative_option):  
            continue # Prune the peach space immediately  
  
        # Just do it. (local option is legal)  
        current_solution[current_state] = tentative_option  
  
        # Recurse  
        BACKTRACKING(current_state + 1, current_solution)  
  
    # Undo the decision (backtrack)  
    current_solution[current_state] = None
```


1 - General Backtracking Framework

Generic Pseudo-code - Recursion Style

```
function BACKTRACKING(current_state, current_solution):
    if current_state reaches the required depth or number of steps:
        if objective(current_solution):
            # option 1: record
            # option 2: output current_solution
        return

    # Enumerate all possible options for current_state
    for tentative_option in feasible_option_set:
        if not is_valid(current_solution, tentative_option):
            continue # Prune the peach space immediately

        # Just do it. (local option is legal)
        current_solution[current_state] = tentative_option

        # Recurse
        BACKTRACKING(current_state + 1, current_solution)

    # Undo the decision (backtrack)
    current_solution[current_state] = None
```

Key Steps:

1. state/decision index
2. options set
3. constraints check
4. how to move to next state
5. backtracking

Sudoku is a logic-based puzzle on a 9×9 grid:

1. Each row must contain the digits 1-9 without repetition.
2. Each column must contain the digits 1-9 without repetition.
3. Each of the nine 3×3 sub-grids (boxes) must contain digits 1-9 without repetition.

The puzzle starts with some cells filled in, and the solver must fill in the rest via logical deduction.

5					9			
	1		6					
	9				2		1	
6		7						
				3				6
						2		
	4		8				5	
					6		2	
			3					7

2 - Apply Backtracking Framework

```
function BACKTRACKING(current_state, current_solution):
    if current_state reaches goal or boundary:
        if objective(current_solution):
            # option 1: record
            # option 2: output current_solution
            # option 3: just return True
        return

    # Enumerate all possible options for current_state
    for tentative_option in feasible_option_set:
        if not is_valid(current_solution, tentative_option):
            continue # Prune the peach space immediately

        # Just do it.(local option is legal)
        current_solution[current_state] = tentative_option

        # Recurse
        BACKTRACKING(current_state + 1, current_solution)

        # Undo the decision (backtrack)
        current_solution[current_state] = None
```

5					9			
	1		6					
	9				2		1	
6		7						
				3				6
						2		
	4		8				5	
					6		2	
			3					7

2 - Apply Backtracking Framework

```
function BACKTRACKING(current_state, current_solution):
    if current_state reaches goal or boundary:
        if objective(current_solution):
            # option 1: record
            # option 2: output current_solution
            # option 3: just return True
        return

    # Enumerate all possible options for current_state
    for tentative_option in feasible_option_set:
        if not is_valid(current_solution, tentative_option):
            continue # Prune the peach space immediately

        # Just do it.(local option is legal)
        current_solution[current_state] = tentative_option

        # Recurse
        BACKTRACKING(current_state + 1, current_solution)

        # Undo the decision (backtrack)
        current_solution[current_state] = None
```

5					9			
	1		6					
	9				2		1	
6		7						
				3				6
						2		
	4		8				5	
					6		2	
			3					7

2 - Apply Backtracking Framework

```
function sudoku_solver(current_state, board):  
    if all cells are filled:  
        return true  
  
    # Enumerate all possible options for current_state  
    for tentative_option in feasible_option_set:  
        if not is_valid(board, tentative_option):  
            continue # Prune the peach space immediately  
  
        # Just do it. (local option is legal)  
        board[current_state] = tentative_option  
  
        # Recurse  
        sudoku_solver(current_state + 1, board)  
  
        # Undo the decision (backtrack)  
        board[current_state] = None
```

5					9			
	1		6					
	9				2		1	
6		7						
				3				6
						2		
	4		8				5	
					6		2	
			3					7

2 - Apply Backtracking Framework

```
function sudoku_solver(current_state, board):  
    if all cells are filled:  
        return true  
  
    # Enumerate all possible options for current_state  
    for tentative_option in feasible_option_set:  
        if not is_valid(board, tentative_option):  
            continue # Prune the peach space immediately  
  
        # Just do it. (local option is legal)  
        board[current_state] = tentative_option  
  
        # Recurse  
        sudoku_solver(current_state + 1, board)  
  
        # Undo the decision (backtrack)  
        board[current_state] = None
```

5					9			
	1		6					
	9				2		1	
6		7						
				3				6
						2		
	4		8				5	
					6		2	
			3					7

2 - Apply Backtracking Framework

```
function sudoku_solver(current_state, board):
    if all cells are filled:
        return true

    FIND the next empty (row, col):
    for num in [1:9]:
        if not is_valid(board, tentative_option):
            continue # Prune the peach space
    immediately

    # Just do it. (local option is legal)
    board[current_state] = tentative_option

    # Recurse
    sudoku_solver(current_state + 1, board)

    # Undo the decision (backtrack)
    board[current_state] = None
```

5					9			
	1		6					
	9				2		1	
6		7						
				3				6
						2		
	4		8				5	
					6		2	
			3					7

2 - Apply Backtracking Framework

```
function sudoku_solver(current_state, board):  
    if all cells are filled:  
        return true  
  
    FIND the next empty (row, col):  
    for num in [1:9]:  
        if not is_valid(board, tentative_option):  
            continue # Prune the peach space  
        immediately  
  
        # Just do it. (local option is legal)  
        board[current_state] = tentative_option  
  
        # Recurse  
        sudoku_solver(current_state + 1, board)  
  
        # Undo the decision (backtrack)  
        board[current_state] = None
```

5					9			
	1		6					
	9				2		1	
6		7						
				3				6
						2		
	4		8				5	
					6		2	
			3					7

2 - Apply Backtracking Framework

```
function sudoku_solver(current_state, board):  
    if all cells are filled:  
        return true  
  
    FIND the next empty (row, col):  
    for num in [1:9]:  
        if isValid(board, row, col, num):  
            board[row][col] = num  
            # Recurse  
            sudoku_solver(current_state + 1, board)  
            # Undo the decision (backtrack)  
            board[current_state] = None
```

5					9			
	1		6					
	9				2		1	
6		7						
				3				6
						2		
	4		8				5	
					6		2	
			3					7

2 - Apply Backtracking Framework

```
function sudoku_solver(current_state, board):  
    if all cells are filled:  
        return true  
  
    FIND the next empty (row, col):  
    for num in [1:9]:  
        if isValid(board, row, col, num):  
            board[row][col] = num  
  
            sudoku_solver(current_state + 1, board)  
  
            board[current_state] = None
```

5					9			
	1		6					
	9				2		1	
6		7						
				3				6
						2		
	4		8				5	
					6		2	
			3					7

2 - Apply Backtracking Framework

```
function sudoku_solver(board):  
    if all cells are filled:  
        return true  
  
    FIND the next empty (row, col):  
    for num in [1:9]:  
        if isValid(board, row, col, num):  
            board[row][col] = num  
  
            sudoku_solver(board)  
  
            board[row][col] = None
```

5					9			
	1		6					
	9				2		1	
6		7						
				3				6
						2		
	4		8				5	
					6		2	
			3					7

2 - Apply Backtracking Framework

```
function sudoku_solver(board):  
    if all cells are filled:  
        return true  
  
    FIND the next empty (row, col):  
    for num in [1:9]:  
        if isValid(board, row, col, num):  
            board[row][col] = num  
  
            sudoku_solver(board)  
  
            board[row][col] = None  
  
    ???
```

5					9			
	1		6					
	9				2		1	
6		7						
				3				6
						2		
	4		8				5	
					6		2	
			3					7

2 - Apply Backtracking Framework

```
function sudoku_solver(board):  
    if all cells are filled:  
        return true  
  
    FIND the next empty (row, col):  
    for num in [1:9]:  
        if isValid(board, row, col, num):  
            board[row][col] = num  
  
            sudoku_solver(board)  
  
            board[row][col] = 0  
    return false
```

5					9			
	1		6					
	9				2		1	
6		7						
				3				6
						2		
	4		8				5	
					6		2	
			3					7

2 - Apply Backtracking Framework

```
function sudoku_solver(board):  
    if all cells are filled:  
        return true  
  
    FIND the next empty (row, col):  
    for num in [1:9]:  
        if isValid(board, row, col, num):  
            board[row][col] = num  
  
            sudoku_solver(board)  
  
            board[row][col] = 0  
    return false
```

5					9			
	1		6					
	9				2		1	
6		7						
				3				6
						2		
	4		8				5	
					6		2	
			3					7

2 - Apply Backtracking Framework

```
function sudoku_solver(board):  
    if all cells are filled:  
        return true  
  
    FIND the next empty (row, col):  
    for num in [1:9]:  
        if isValid(board, row, col, num):  
            board[row][col] = num  
  
            if sudoku_solver(board):  
                return true  
  
            board[row][col] = 0  
    return false
```

5					9			
	1		6					
	9				2		1	
6		7						
				3				6
						2		
	4		8				5	
					6		2	
			3					7

2 - Apply Backtracking Framework

```
function sudoku_solver(board):  
    if all cells are filled:  
        return true  
  
    FIND the next empty (row, col):  
    for num in [1:9]:  
        if isValid(board, row, col, num):  
            board[row][col] = num  
  
            if sudoku_solver(board):  
                return true  
  
            board[row][col] = 0  
    return false
```

5					9			
	1		6					
	9				2		1	
6		7						
				3				6
						2		
	4		8				5	
					6		2	
			3					7

2 - Apply Backtracking Framework

```
function is_valid(board, row, col, num):  
    for col_in_row in range(9):  
        if board[row][col_in_row] == num:  
            return False  
  
    for row_in_col in range(9):  
        if board[row_in_col][col] == num:  
            return False  
  
    box_row_start = (row // 3) * 3  
    box_col_start = (col // 3) * 3  
    for r in range(box_row_start, box_row_start + 3):  
        for c in range(box_col_start, box_col_start +  
3):  
            if board[r][c] == num:  
                return False  
  
    return True
```

5					9			
	1		6					
	9				2		1	
6		7						
				3				6
						2		
	4		8				5	
					6		2	
			3					7

2 - Apply Backtracking Framework

```
function is_valid(board, row, col, num):  
    for col_in_row in range(9):  
        if board[row][col_in_row] == num:  
            return False  
  
    for row_in_col in range(9):  
        if board[row_in_col][col] == num:  
            return False  
  
    box_row_start = (row // 3) * 3  
    box_col_start = (col // 3) * 3  
    for r in range(box_row_start, box_row_start + 3):  
        for c in range(box_col_start, box_col_start +  
3):  
            if board[r][c] == num:  
                return False  
  
    return True
```

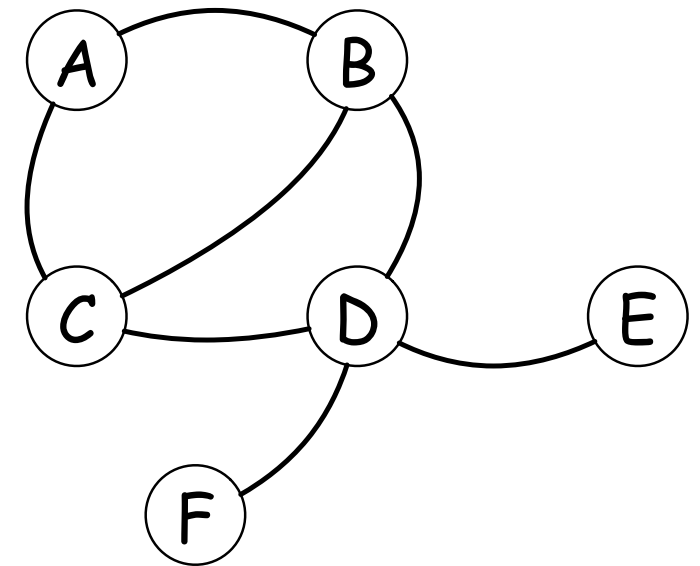
5					9			
	1		6					
	9				2		1	
6		7						
				3				6
						2		
	4		8				5	
					6		2	
			3					7

3-Graph Coloring Problem

Objective: Given an undirected graph $G = (V, E)$ and a total of K available colors, assign each vertex a color from $\{1, 2, \dots, K\}$ such that for every edge (u, v) , the vertices u and v do not share the same color.

If successful, we obtain a valid K -coloring of the graph; if not, we conclude the graph cannot be colored with K colors without violating adjacency constraints.

```
function COLOR_GRAPH(G, K):  
    # 0 means uncolored  
    colors = array of size |V|, initialized with 0  
    if assignColor(??? ) == true:  
        return colors  
    else:  
        return "No valid K-coloring found"
```

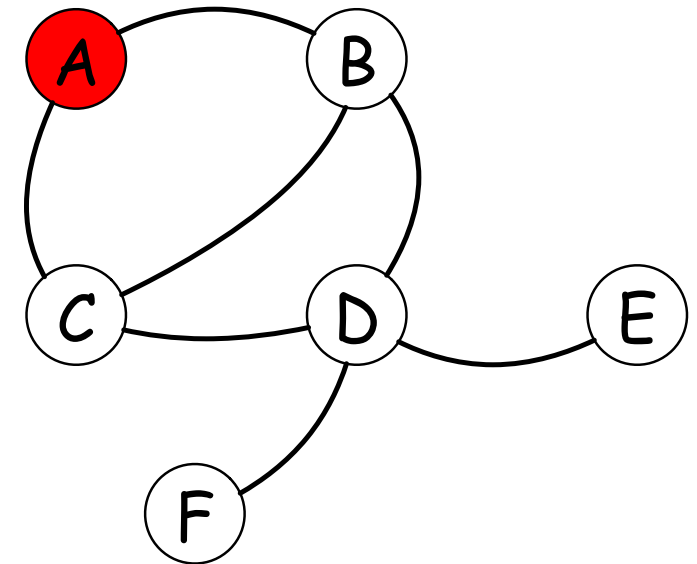


3-Graph Coloring Problem

Objective: Given an undirected graph $G = (V, E)$ and a total of K available colors, assign each vertex a color from $\{1, 2, \dots, K\}$ such that for every edge (u, v) , the vertices u and v do not share the same color.

If successful, we obtain a valid K -coloring of the graph; if not, we conclude the graph cannot be colored with K colors without violating adjacency constraints.

```
function COLOR_GRAPH(G, K):  
    # 0 means uncolored  
    colors = array of size |V|, initialized with 0  
    if assignColor(G, 1, K, colors) == true:  
        return colors  
    else:  
        return "No valid K-coloring found"
```

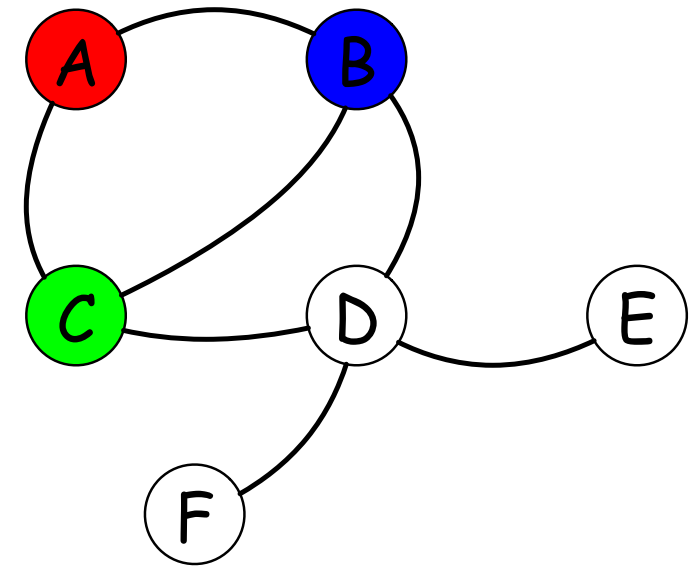


3-Graph Coloring Problem

Objective: Given an undirected graph $G = (V, E)$ and a total of K available colors, assign each vertex a color from $\{1, 2, \dots, K\}$ such that for every edge (u, v) , the vertices u and v do not share the same color.

If successful, we obtain a valid K -coloring of the graph; if not, we conclude the graph cannot be colored with K colors without violating adjacency constraints.

```
function assignColor(G, v, K, colors):  
    if v > |V|:  
        return true  
  
    for c in 1 to K:  
        if isSafe(G, v, c, colors) == true:  
            colors[v] = c  
            if assignColor(G, v+1, K, colors) == true:  
                return true  
            colors[v] = 0  
  
    return false
```



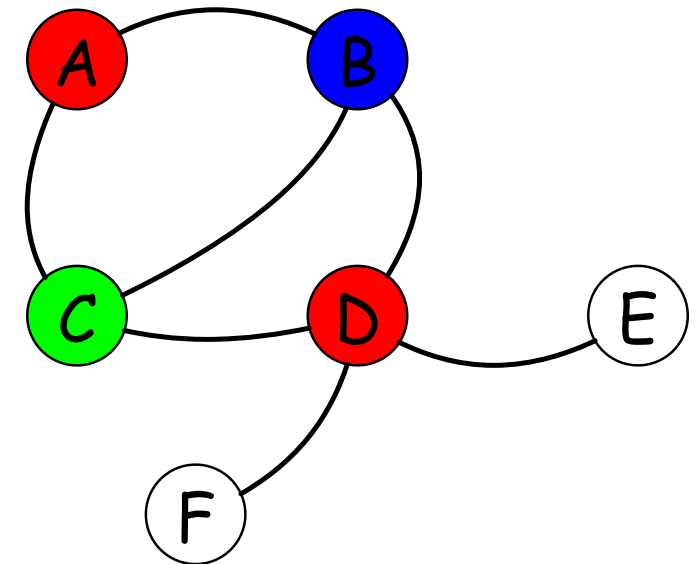
```
function isSafe(G, v, color, colors):  
    for each neighbor u of v in G:  
        if colors[u] == color:  
            return false  
    return true
```

3-Graph Coloring Problem

Objective: Given an undirected graph $G = (V, E)$ and a total of K available colors, assign each vertex a color from $\{1, 2, \dots, K\}$ such that for every edge (u, v) , the vertices u and v do not share the same color.

If successful, we obtain a valid K -coloring of the graph; if not, we conclude the graph cannot be colored with K colors without violating adjacency constraints.

```
function assignColor(G, v, K, colors):  
    if v > |V|:  
        return true  
  
    for c in 1 to K:  
        if isSafe(G, v, c, colors) == true:  
            colors[v] = c  
            if assignColor(G, v+1, K, colors) == true:  
                return true  
            colors[v] = 0  
  
    return false
```



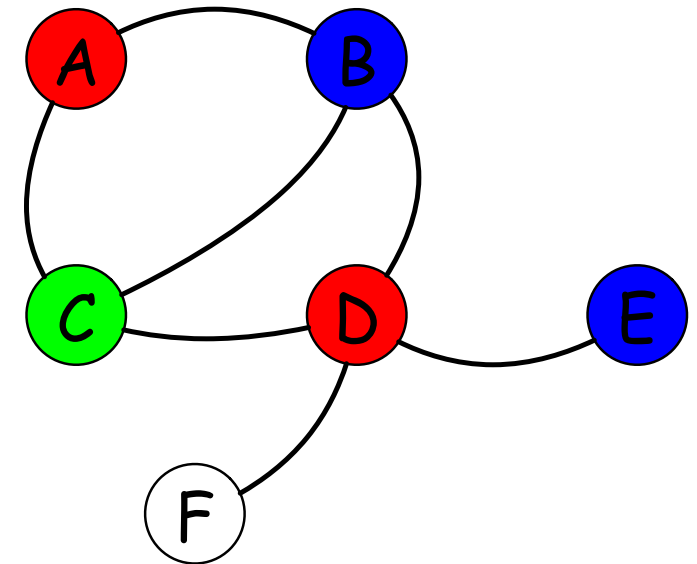
```
function isSafe(G, v, color, colors):  
    for each neighbor u of v in G:  
        if colors[u] == color:  
            return false  
    return true
```

3-Graph Coloring Problem

Objective: Given an undirected graph $G = (V, E)$ and a total of K available colors, assign each vertex a color from $\{1, 2, \dots, K\}$ such that for every edge (u, v) , the vertices u and v do not share the same color.

If successful, we obtain a valid K -coloring of the graph; if not, we conclude the graph cannot be colored with K colors without violating adjacency constraints.

```
function assignColor(G, v, K, colors):  
    if v > |V|:  
        return true  
  
    for c in 1 to K:  
        if isSafe(G, v, c, colors) == true:  
            colors[v] = c  
            if assignColor(G, v+1, K, colors) == true:  
                return true  
            colors[v] = 0  
  
    return false
```



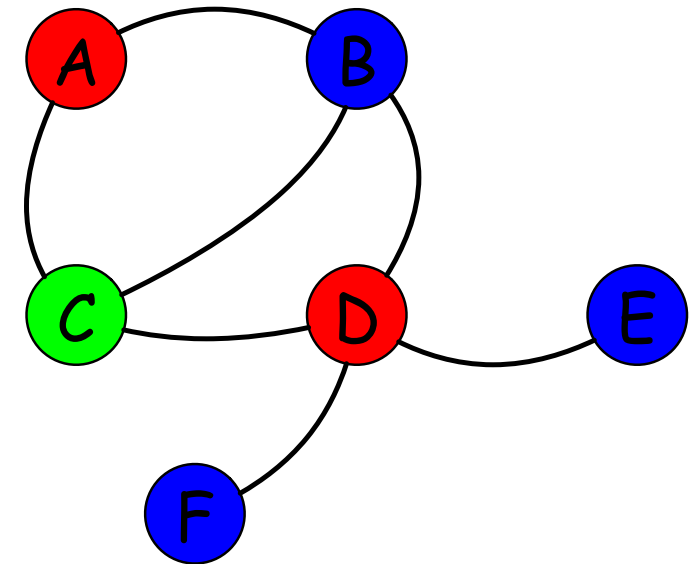
```
function isSafe(G, v, color, colors):  
    for each neighbor u of v in G:  
        if colors[u] == color:  
            return false  
    return true
```

3-Graph Coloring Problem

Objective: Given an undirected graph $G = (V, E)$ and a total of K available colors, assign each vertex a color from $\{1, 2, \dots, K\}$ such that for every edge (u, v) , the vertices u and v do not share the same color.

If successful, we obtain a valid K -coloring of the graph; if not, we conclude the graph cannot be colored with K colors without violating adjacency constraints.

```
function assignColor(G, v, K, colors):  
    if v > |V|:  
        return true  
  
    for c in 1 to K:  
        if isSafe(G, v, c, colors) == true:  
            colors[v] = c  
            if assignColor(G, v+1, K, colors) == true:  
                return true  
            colors[v] = 0  
  
    return false
```



```
function isSafe(G, v, color, colors):  
    for each neighbor u of v in G:  
        if colors[u] == color:  
            return false  
    return true
```


3-Graph Coloring Problem

Objective: Given an undirected graph $G = (V, E)$ and a total of K available colors, assign each vertex a color from $\{1, 2, \dots, K\}$ such that for every edge (u, v) , the vertices u and v do not share the same color.

If successful, we obtain a valid K -coloring of the graph; if not, we conclude the graph cannot be colored with K colors without violating adjacency constraints.

```
function assignColor(G, v, K, colors):  
    if v > |V|:  
        return true  
  
    for c in 1 to K:  
        if isSafe(G, v, c, colors) == true:  
            colors[v] = c  
            if assignColor(G, v+1, K, colors) == true:  
                return true  
            colors[v] = 0  
  
    return false
```

Try all schemes one by one!??
How can we optimize it?



3-Graph Coloring Problem

Objective: Given an undirected graph $G = (V, E)$ and a total of K available colors, assign each vertex a color from $\{1, 2, \dots, K\}$ such that for every edge (u, v) , the vertices u and v do not share the same color.

If successful, we obtain a valid K -coloring of the graph; if not, we conclude the graph cannot be colored with K colors without violating adjacency constraints.

```
function assignColor(G, v, K, colors):  
    if v > |V|:  
        return true  
  
    for c in 1 to K:  
        if isSafe(G, v, c, colors) == true:  
            colors[v] = c  
            if assignColor(G, v+1, K, colors) == true:  
                return true  
            colors[v] = 0  
  
    return false
```

Try all schemes one by one!??
How can we optimize it?



Combine with **heuristics** (vertex ordering, forward checking) for better performance.

4-Summary

1. What is CSP?
2. What is Pruning?
3. What is Backtracking?
4. How to implement backtracking?
5. Exponential Complexity - worst case

