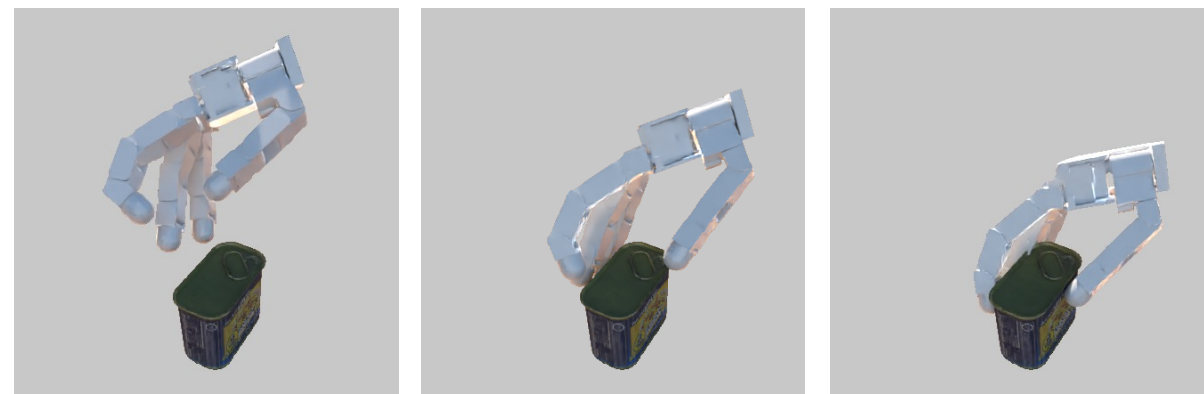




Human Demonstrations

Hand Motion
Retargeting



Robot Trajectories

Grasping Function Learning

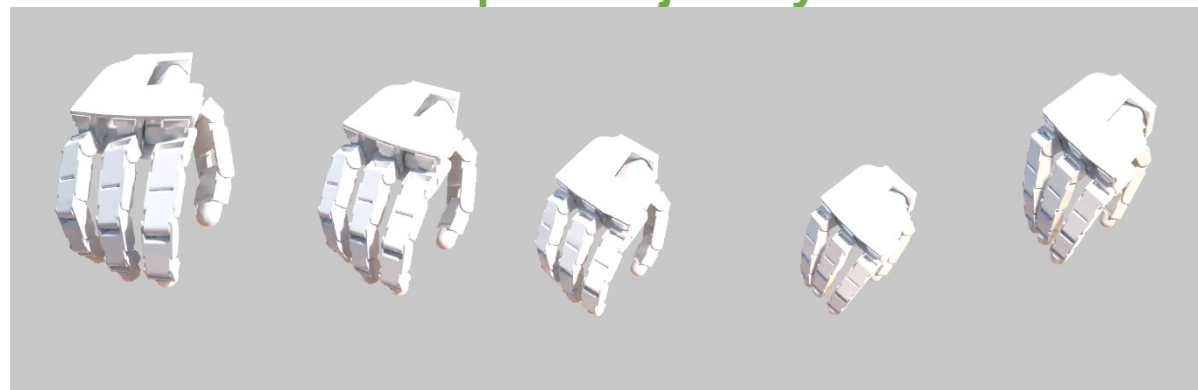


Continuous Grasping Function

Training

Test

Sampled Trajectory



Test in the
Simulation



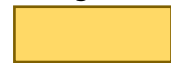
Trajectory in the Simulation



Sim-to-Real Deploy

Real Robot

object



\mathbf{z}

Continuous Grasping Function

t_0

t_1

t_2

t_3

t_4

continuous t