

ME:4140 Modern Robotics & Automation

Homework #4

Due: see ICON

Make sure to upload any supporting documents, e.g., hand work, codes, sketches, etc.

Instructions (READ THESE FIRST!)

- To complete this homework, you can use an **Adobe** pdf reader or **Google Chrome** (after completing make sure to download with changes).
- Answer all questions by typing or selecting radio buttons in this document.
- Upload your completed document and any supporting documents, code, sketches, etc., to ICON.
- Round all values to 3 decimal places.

Example #1: what is the value of Pi? Answer: 3.142

Example #2: what is $100/3$? Answer: 33.333

Name:

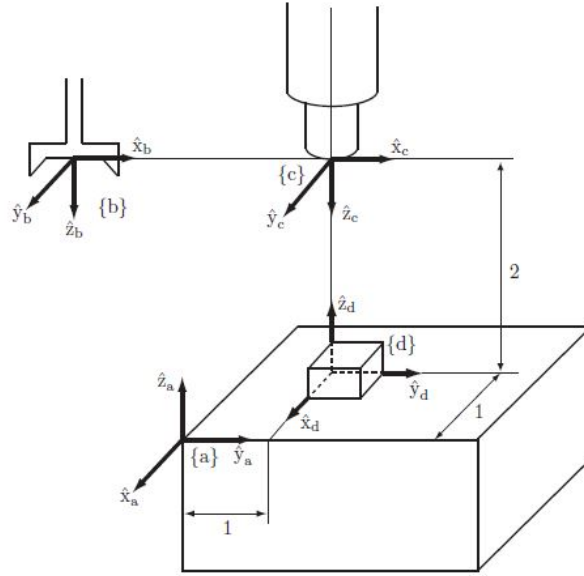
First

Last

Student ID

1. What is the screw axis \mathcal{S} if $q = (1, 3, 6)$, $s = (3, 2, 1)$ and $h = 4$? (5)

2. A robot has a workspace which contains four reference frames: fixed frame $\{a\}$, end-effector frame $\{b\}$, camera frame $\{c\}$ and workpiece frame $\{d\}$ as shown in the figure below. (20)



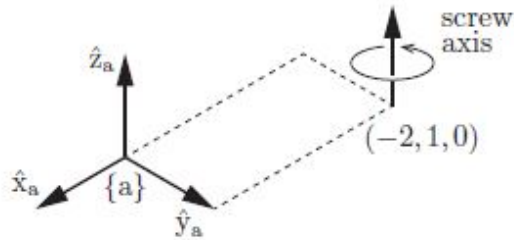
Determine the following:

- (a) T_{ab} given that

$$T_{bc} = \begin{bmatrix} 1 & 0 & 0 & 5 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

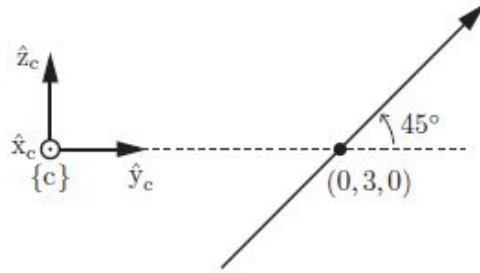
- (b) If the twist in $\{b\}$ is $\mathcal{V}_b = (1, 2, 2, 0, 0, 0)$, what is the twist in $\{c\}$?

3. The zero-pitch screw axis shown in the image below, aligned with \hat{z}_a , passes through the point $(-2, 1, 0)$ in the $\{a\}$ frame. (15)



What is the twist \mathcal{V}_a if we rotate about the screw axis at a speed of $\dot{\theta} = 7$ rad/s?

4. The figure below shows a screw axis in the (\hat{y}_c, \hat{z}_c) plane, at a 45 degree angle with respect to the \hat{y}_c -axis. The \hat{x}_c -axis is aligned such that it points out of the page. The screw axis passes through the point $(0, 3, 0)$. (10)



Determine the following:

- (a) If the pitch of the screw is $h = 5$ linear units per radian, what is the screw axis \mathcal{S}_c ?

- (b) If the speed of rotation about the screw axis is $\dot{\theta} = 2$ rad/s, what is the twist \mathcal{V}_c ?