

4.8 Provide two programming examples in which multithreading does not provide better performance than a single-threaded solution.

1. Any kind of sequential program is not a good candidate to be threaded. An example of this is a program that calculates an individual tax return.

2. Another example is a "shell" program such as the C-shell or Korn shell. Such a program must closely monitor its own working space such as open files, environment variables, and current working directory.

4.9 Under what circumstances does a multithreaded solution using multiple kernel threads provide better performance than a single-threaded solution on a single-processor system?

When a kernel thread suffers a page fault, another kernel thread can be switched in to use the interleaving time in a useful manner. A single-threaded process, on the other hand, will not be capable of performing useful work when a page fault takes place.

Therefore, in scenarios where a program might suffer from frequent page faults or has to wait for other system events, a multithreaded solution would perform better even on a single-processor system.

4.10 Which of the following components of program state are shared across threads in a multithreaded process?

- a. Register values
- b. Heap memory
- c. Global variables
- d. Stack memory

The threads of a multithreaded process share heap memory and global variables. Each thread has its separate set of register values and a separate stack.

4.13 Is it possible to have concurrency but not parallelism? Explain

Yes, It is possible to have concurrency but not parallelism.

Concurrency is a condition that exists when at least two threads are making progress. A more generalized form of parallelism that can include time-slicing as a form of virtual parallelism.'

Parallelism is a condition that arises when at least two threads are executing simultaneously". It is possible for two threads to make progress, though not at the same instant.

for example, consider a single-core processor running two threads. An operating system will normally switch back and forth between the two threads very quickly, giving the appearance of parallelism. the two threads are each taking turns executing their respective instructions on the same cpu core. Though it is not possible to have parallelism without concurrency, it is possible to have concurrency but not parallelism.

4.17

Consider the following code segment:

```
pid_t pid;

pid = fork();

if (pid == 0) { /* child process */

    fork();

    thread_create( . . . );

}

fork();
```

a. How many unique processes are created?

b. How many unique threads are created?

The statement `pid = fork();` before the `if` statement creates one process. The parent process say `p` creates this process. Let it be `p1`.

The statement `fork();` in the `if` statement creates one process. The parent process `p` creates this process. Let it be `p2`.

After the `if` statement, parent process `p`, process `p1` and process `p2` will execute `fork();` creating three new processes.

One process is created by parent process `p`.

One process is created by process `p1`.

One process is created by process `p2`.

Hence, 5 unique processes (`p1`, `p2`, `p3`, `p4`, `p5`) will be created. If the parent process is also considered, then 6 unique processes (`p`, `p1`, `p2`, `p3`, `p4`, `p5`) will be created.

Thread creation is done in `if` block. Only child process `p1` is executed in the `if` block. Therefore, process `p1` will be created one thread.

In the `if` block one process `p2` is created using `fork()`. Therefore, process `p2` will also create a thread.

Hence, 2 unique threads will be created.

4.19 The program shown in Figure 4.23 uses the Pthreads API. What would be the output from the program at LINE C and LINE P?

The output is CHILD: value = 5
The child process in the thread is forked by parent process and child process each have its own memory space.
After forking, the parent process waits for the completion of child process.
New thread is created for child process and the runner() function is called which set the value of the global variable to 5.
Thus, after execution of this line, the value displayed will be 5.
The output of LINE P in the program:
The output is PARENT: value = 0
After completing the child process, the value of the global variable present in parent process remains 0.
Thus, after execution of this line, the value displayed will be 0.

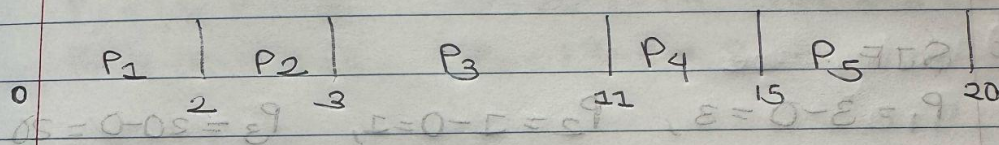
5.4

* 5.4

Process	Burst-time	Priority
P ₁	2	2
P ₂	1	1
P ₃	8	4
P ₄	4	2
P ₅	5	3

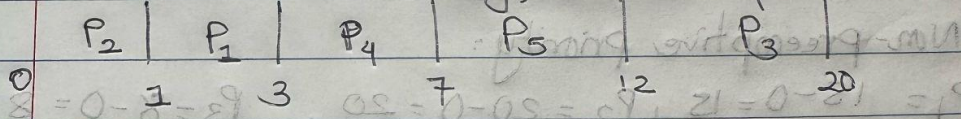
* Gantt charts for FCFS:

Here, the process comes first in the queue will be scheduled first.



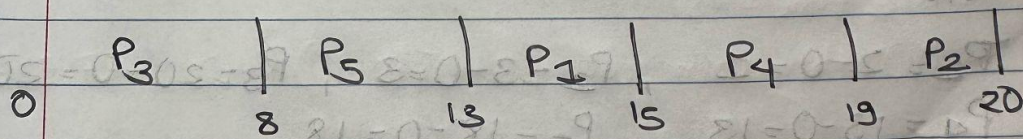
* Gantt chart for SJF Scheduling.

In ~~the~~ SJF Scheduling, the process of least size will be 1st

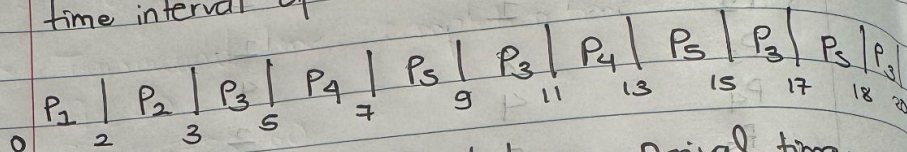


* Gantt chart for Non-preemptive priority

Here, highest priority process scheduled first.



* Gantt chart for Round Robin (Quantum = 2).
In RR scheduling each process will get the equal time interval of CPU until its completed.



b) Turn around time = Finish time - Arrival time.

* FCFS:

$$P_1 = 2 - 0 = 2, \quad P_2 = 3 - 0 = 3, \quad P_3 = 11 - 0 = 11$$

$$P_4 = 15 - 0 = 15, \quad P_5 = 20 - 0 = 20$$

* SJF:

$$P_1 = 3 - 0 = 3, \quad P_2 = 1 - 0 = 1, \quad P_3 = 20 - 0 = 20$$

$$P_4 = 7 - 0 = 7, \quad P_5 = 12 - 0 = 12$$

* Non-preemptive priority:

$$P_1 = 15 - 0 = 15, \quad P_2 = 20 - 0 = 20, \quad P_3 = 8 - 0 = 8$$

$$P_4 = 19 - 0 = 19, \quad P_5 = 13 - 0 = 13$$

* RR:-

$$P_1 = 2 - 0 = 2, \quad P_2 = 3 - 0 = 3, \quad P_3 = 20 - 0 = 20$$

$$P_4 = 13 - 0 = 13, \quad P_5 = 18 - 0 = 18$$

* Waiting time = Finish time - burst time

- FCFS

$$P_1 = 2 - 2 = 0, \quad P_2 = 3 - 1 = 2, \quad P_3 = 11 - 8 = 3$$

$$P_4 = 15 - 3 = 12, \quad P_5 = 20 - 5 = 15$$

- SJF

$$P_1 = 3 - 2 = 1, \quad P_2 = 1 - 1 = 0, \quad P_3 = 20 - 8 = 12$$

$$P_4 = 7 - 4 = 3, \quad P_5 = 12 - 5 = 7$$

- Non preemptive priority:

$$P_1 = 15 - 2 = 13, \quad P_2 = 20 - 1 = 19, \quad P_3 = 8 - 8 = 0$$

$$P_4 = 19 - 4 = 15, \quad P_5 = 13 - 5 = 8$$

- RR

$$P_1 = 2 - 2 = 0, \quad P_2 = 3 - 1 = 2, \quad P_3 = 20 - 8 = 18$$

$$P_4 = 13 - 4 = 9, \quad P_5 = 18 - 5 = 13$$

* Average time:

$$\text{FCFS} = 0 + 2 + 3 + 12 + 15 / 5 = 6.4$$

$$\text{SJF} = 1 + 0 + 12 + 3 + 7 / 5 = 4.6$$

$$\text{NPP} = 13 + 19 + 0 + 15 + 8 / 5 = 11.4$$

$$\text{RR} = 0 + 2 + 18 + 9 + 13 / 5 = 8.4$$

\therefore the least average waiting time is 4.6

So SJF is giving least waiting time

5.5

a)

P ₁	P ₁	P _{idle}	P ₂	P ₃	P ₂	P ₃	P ₄	P ₄	P ₂	P ₃	P _{idle}	P ₅	P ₆	
0	10	20	25	35	45	55	65	75	80	85	90	100	110	120

* Turnaround time = completion time - starting time.

$$P_1 = 20$$

$$P_2 = 85 - 25 = 60$$

$$P_3 = 90 - 35 = 55$$

$$P_4 = 80 - 65 = 15$$

$$P_5 = 110 - 100 = 10$$

$$P_6 = 120 - 110 = 10$$

c) Waiting time

$$P_1 = 0$$

$$P_2 = 10 + (80 - 55) = 35$$

$$P_3 = 5 + 10 + (85 - 65) = 35$$

$$P_4 = 5$$

$$P_5 = 0$$

$$P_6 = 5$$

d) CPU utilization rate

$$\text{Idle time} = 15$$

$$\text{CPU utilization rate} = \frac{(105/120) \times 100}{1} = 87.5\%$$

5.15

$$T_{n+1} = a * t_n + (1-a) * \tau_n$$

when $a=0$ and $t_0 = 100$ milliseconds, the eqⁿ is

$$T_{n+1} = 0 * t_n + (1-0) * 100 = 100 \text{ milliseconds}$$

b) $T_{n+1} = a * t_n + (1-a) * \tau_n$

when $a=0.99$ and $\tau_0 = 10$ milliseconds,

$$= 0.99 * t_n + (\cancel{0.99} - 1 - 0.99) * 10$$

$$= 0.99 t_n + 0.1$$